

Chapter 1: Linear Equations in Linear Algebra

Section 1.1: Systems of Linear Equations

BGSU Math 3320

Linear Systems

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Sometimes also called “systems of *simultaneous* equations”

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Vocab: “solution”, “solution set,” “equivalent” linear systems

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It is important that you clearly understand the definition of equivalence of two linear systems.

A system with many solutions

Example: For this linear system

$$x_1 - x_2 - 2x_3 = 1$$

$$3x_1 - 3x_2 - 5x_3 = 3$$

$$2x_1 - 2x_2 - 6x_3 = 2,$$

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these are examples of “solutions”:

$$\begin{pmatrix} x_1 = 1 \\ x_2 = 0 \\ x_3 = 0 \end{pmatrix}, \quad \begin{pmatrix} x_1 = 2 \\ x_2 = 1 \\ x_3 = 0 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} x_1 = -1 \\ x_2 = -2 \\ x_3 = 0 \end{pmatrix}$$

Each is in the solution set.

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*If a system has at least one solution then it is “**consistent**.”*

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*If a system has at least one solution
then it is “**consistent.**” Otherwise, “**inconsistent.**”*

Finding Equivalent Linear Systems

Three simple things we can do without altering the solution set.

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| $x_1 - x_2 - 2x_3 = 1$ | | $3x_1 - 3x_2 - 5x_3 = 3$ |
| $3x_1 - 3x_2 - 5x_3 = 3$ | has same | $x_1 - x_2 - 2x_3 = 1$ |
| $2x_1 - 2x_2 - 6x_3 = 2$ | solution set | $2x_1 - 2x_2 - 6x_3 = 2$ |
| | as | |

(we swapped the order of the 1st and 2nd equations)

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2. We can scale one of the equations

| | | |
|--------------------------|--------------|---------------------------|
| $x_1 - x_2 - 2x_3 = 1$ | | $7x_1 - 7x_2 - 14x_3 = 7$ |
| $3x_1 - 3x_2 - 5x_3 = 3$ | has same | $3x_1 - 3x_2 - 5x_3 = 3$ |
| $2x_1 - 2x_2 - 6x_3 = 2$ | solution set | $2x_1 - 2x_2 - 6x_3 = 2$ |
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(we multiplied both sides of 1st eq'n with 7.)

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...and third,
3. We can **replace** one of the equations with a scalar multiple of another:

None of these three operations alters the solution set.

Finding Equivalent Linear Systems

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2. We can **scale** ...
...and third,
3. We can **replace** one of the equations with a scalar multiple of another:

| | | | |
|----------------------|-----|--------------------------------|------------------------------------|
| | | $4(2x_1 - 2x_2 - 6x_3) +$ | |
| $x_1 - x_2 - 2x_3$ | $=$ | 1 | $x_1 - x_2 - 2x_3 = 1 + 4 \cdot 2$ |
| $3x_1 - 3x_2 - 5x_3$ | $=$ | 3 | $3x_1 - 3x_2 - 5x_3 = 3$ |
| $2x_1 - 2x_2 - 6x_3$ | $=$ | 2 | $2x_1 - 2x_2 - 6x_3 = 2$ |
| | | has same solution set as | |

Here, we *added the same number to both sides* of the 1st equation, since

$$4 \times (\text{left side of eqn 3}) = 4 \times (\text{right side of eqn 3})$$

None of these three operations alters the solution set.

Using Elementary Operations to Finding a Solution Set

Example

Find the solution set of

$$x_1 - x_2 - 2x_3 = 1$$

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- Add (-3) times 1^{st} equation to 2^{nd} equation, thus *eliminating* x_1 and x_2 from the 2^{nd} eq:

$$x_1 - x_2 - 2x_3 = 1$$

$$x_3 = 0$$

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$$\begin{aligned}x_1 - x_2 - 2x_3 &= 1 \\ x_3 &= 0 \\ 2x_1 - 2x_2 - 6x_3 &= 2\end{aligned}$$

- Add (-2) times 1^{st} equation to 3^{rd} equation, thus *eliminating* x_1 and x_2 from the 3^{rd} eq:

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$$\begin{aligned}x_1 - x_2 - 2x_3 &= 1 \\ x_3 &= 0 \\ -2x_3 &= 0\end{aligned}$$

\therefore Solution Set: $\{(1 + x_2, x_2, 0) \mid x_2 \in \mathbb{R}\}$ “ x_2 is a free variable”

Matrix Notation for linear systems.

$$\begin{aligned}x_1 - x_2 - 2x_3 &= 1 \\ 3x_1 - 3x_2 - 5x_3 &= 3 \\ 2x_1 - 2x_2 - 6x_3 &= 2\end{aligned}$$

Augmented matrix for the system

$$\left[\begin{array}{ccc|c} 1 & -1 & -2 & 1 \\ 3 & -3 & -5 & 3 \\ 2 & -2 & -6 & 2 \end{array} \right]$$

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- Note well the difference between **augmented** matrix and the **coefficient** matrix.
- Convention about matrices: “Row,Column” or “ $m \times n$ ”.

The three types of “elementary row operations”

| Things we can do to a system of equations without changing the solution set | Things we can do to an augmented matrix without changing the solution set of the associated linear system |
|---|---|
| <p>We can swap the order of the equations</p> <p>We can scale both sides of one of the equations.</p> <p>We can add number to both sides of an equation</p> | <ol style="list-style-type: none">1. (“swap”) We can interchange any two rows2. (“scale”) We can multiply a row a scalar3. (“Replacement”) We two can replace a row with the sum of itself and any scalar multiple of another row |

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Two Fundamental Questions about a Linear System:

- 1 Is the system consistent; that is, does at least one solution exist?
- 2 If a solution exists, is it the only one; that is, is the solution unique?

Elementary Row Operations

Example

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Elementary Row Operations

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We can now read-off the solution set, as before.

Intuitively, we seek “Triangular” matrices

Let’s take a look at Example 1.1.1 (p. 5) of the text.

$$x_1 - 2x_2 + x_3 = 0$$

$$2x_2 - 8x_3 = 8$$

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So do you see the intuitive meaning of “upper triangular”?

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Do you see the advantage of putting a matrix into a triangular form?

“Triangular” augmented matrices and Consistency

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If the augmented matrix for a linear system is upper-triangular, then we can easily determine whether that linear system is consistent or not, by interpreting the rows of the augmented matrix. (HW.)

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If the augmented matrix for a linear system is upper-triangular, then we can easily determine whether that linear system is consistent or not, by interpreting the rows of the augmented matrix. (HW.)

So we’re going to be using row operations to put matrices into upper triangular form.

True/False questions from the book

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- 1 Two matrices are “row-equivalent” if they have the same number of rows.

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False. They are “row-equivalent” if one can be obtained from the other via a sequence of “elementary row operations”.
- ② Elementary Row operations on an augmented matrix never change the solution set of the associated linear system.

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- 2 Elementary Row operations on an augmented matrix never change the solution set of the associated linear system.
True.

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True. If a system is consistent, then it has 1 solution or an infinitude of solutions.

Problem 1.1.2

Solve the linear system $\begin{cases} 2x_1 + 4x_2 = -4 \\ 5x_1 + 7x_2 = 11 \end{cases}$ by using elementary row operations on the augmented matrix. Follow the systematic elimination procedure described in this section.

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We can also present the solution as $(x_1, x_2) = (12, -7)$.

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To see why, interpret the last row of the triangular matrix as an equation ...