

Control Group Selection in High Dimensions: A Narrow Replication Using Panel Data Approach and Difference-in-Differences¹

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Abstract

I use the forward difference-in-differences method of Li (2024) and Stata's regression control method by Yan and Chen (2022) to narrowly replicate Shi and Huang (2023), who use a panel data approach to study the impact of China's Anti-Corruption Campaign on luxury watch imports.

Key Words: Synthetic Control Method, Causal Inference, Greedy Algorithm.

1 Introduction

Control group selection has become a topic of interest for causal methodologists, where some pre-processing of the control units is done before treatment effects are estimated for a treated unit. For example, clustering approaches are sometimes invoked. Bayani (2021) employs functional PCA and a k-means clustering approach to choose control units for the Robust PCA-Synthetic Control Method. Dynamic time warping has also been used (Biazoli et al., 2024). Also for synthetic controls, Yu et al. (2022) experiment with a simple variance minimization method.

Hsiao et al. (2012) develop the *panel data approach* which rests on least-squares estimations. The method exploits pre-intervention correlations between the treated and control units, updating the selected controls based on R-squared or likelihood values. Finally, it uses OLS to construct counterfactuals. Shi and Huang (2023) (henceforth SH) develop the forward-selected panel data approach (fsPDA), extending the original formulation to when there are very many controls relative to pre-treatment periods. Empirically, SH exploit China’s January 2013 Anti-Corruption Campaign (ACC) as the treatment. Since luxury watches are a bribe good (Lan & Li, 2018), SH construct a counterfactual for the monthly growth rate of China’s import of luxury watches absent the ACC. Their data have 35 pre-intervention periods and 87 candidate control units. Extending SH, Li (2024) proposes forward difference-in-differences (fDID). Li (2024) also uses forward selection to choose the control group for a treated unit. However instead of OLS, Li’s forward selection method uses a series of difference-in-differences (DID) regressions to select the control group. fDID was recently developed for Stata by Greathouse et al. (2024). fsPDA also has an existing Stata implementation via the *Regression Control Method* (RCM). Yan and Chen (2022) explicitly cite SH’s fsPDA as one of the available models the RCM can implement, in addition to Hsiao et al. (2012).

Organization The task of this paper is to use Stata’s fDID and RCM to replicate the empirical findings presented in SH. fDID replicates SH fairly successfully, both in terms of the average treatment effect on the treated (ATT) and the standard error. The Stata

RCM does not replicate, however. I first detail the control group selection algorithms and subsequent estimation for both approaches. Then, I discuss how the replication was conducted and present the results.

2 Estimation

Notations I first develop common notations for both methods. Let “ $:=$ ” be a definition. A scalar is an italicized lowercase letter, y . A vector is a bold lowercase letter \mathbf{y} . Let a matrix be a bold uppercase letter \mathbf{Y} . Let the cardinality of a discrete set be $|\cdot|$, say $S = |S|$. Indexed by j , we observe $\mathcal{N} := \{1, 2, \dots, N\}$ units where the set \mathcal{N} has cardinality $N = |\mathcal{N}|$. $j = 1$ is the treated unit with the controls being $\mathcal{N}_0 := \mathcal{N} \setminus \{1\}$ whose cardinality is $N_0 = |\mathcal{N}_0|$. Let $\widehat{U} \subset \mathcal{N}_0$ be a subset of controls, with cardinality $U = |\widehat{U}|$. Time periods are indexed by t . Let $\mathcal{T}_1 := \{1, 2, \dots, T_0\}$ represent the pre-intervention periods, where T_0 is the final pre-intervention period, and $\mathcal{T}_2 := \{T_0 + 1, \dots, T\}$ represents the post-intervention periods. Both of these sets have cardinalities $T_1 = |\mathcal{T}_1|$ and $T_2 = |\mathcal{T}_2|$. Let $\mathcal{T} := \mathcal{T}_1 \cup \mathcal{T}_2$ represent the full time series, with cardinality $T = |\mathcal{T}|$. Let $\mathbf{y}_j := [y_{jt}, \dots, y_{jT}]^\top \in \mathbb{R}^T$ denote the generic vector of outcomes for unit $j \in \mathcal{N}$, where y_{jt} represents the outcome for unit j at time $t \in \mathcal{T}$. Furthermore, denote $\mathbf{y}_1 := (y_{1t})_{t \in \mathcal{T}}$ as the $T \times 1$ column vector of outcomes for the treated unit and $\mathbf{Y}_{\mathcal{N}_0} := (\mathbf{y}_j)_{j \in \mathcal{N}_0}$ as the $T \times N_0$ matrix of control unit outcomes. Denote $\mathbf{Y}_U := (\mathbf{y}_j)_{j \in \widehat{U}}$ as the $T \times U$ submatrix of selected controls. Let $d_{jt} \in \{0, 1\}$ be a treatment indicator, where $d_{jt} = 1$ for treated units in the post-intervention period, $t \in \{T_0 + 1, \dots, T\}$, and $d_{jt} = 0$ otherwise. Our goal is to estimate the counterfactual outcome for the treated unit, y_{1t}^0 , in order to estimate the treatment effect. We observe $y_{jt} = y_{jt}^1 d_{jt} + (1 - d_{jt}) y_{jt}^0$, where y_{jt}^1 is the potential outcome if unit j is treated, and y_{jt}^0 is the potential outcome if unit j is not treated.¹ Let the treatment effect be $\widehat{\Delta}_{\widehat{U}t} := y_{1t} - \widehat{y}_{1t}^0(\widehat{U})$, where $\widehat{y}_{1t}^0(\widehat{U})$ is the estimated counterfactual based on the control set \widehat{U} . The causal estimand of interest is the ATT, defined as $\widehat{ATT}_{\widehat{U}} = T_2^{-1} \sum_{t \in \mathcal{T}_2} \widehat{\Delta}_{\widehat{U}t}$.

¹Going forward we suppress the superscript 1 for simplicity.

2.1 Forward-Selected Panel Data Approach

fsPDA begins with an empty set of control units. In the first iteration, we run a linear regression, using pre-intervention data only, of \mathbf{y}_1 upon the outcomes for each $i \in \mathcal{N}_0$

$$\mathbf{y}_1 = \mathbf{Y}'_{\widehat{U} \cup \{i\}} \boldsymbol{\beta}_{\widehat{U} \cup \{i\}} + \boldsymbol{\beta}_0, \forall t \in \mathcal{T}_1 \quad (1)$$

This produces N_0 submodels, each with an associated R-squared statistic. We find the control unit which maximizes the R-squared statistic $i_1^* = \arg \max_{i \in \mathcal{N}_0} R^2_{\widehat{U} \cup \{i\}}$. We then add i_1^* to the set \widehat{U} such that $\widehat{U} = \{i_1^*\}$, and remove it from \mathcal{N}_0 . In the second iteration, we repeat Equation 1 with the remaining $N_0 - 1$ control units, except now each model now includes two control units: i_1^* and one from the remaining set. The control unit which maximizes the R-squared statistic in this iteration is selected as $i_2^* = \arg \max_{i \in \mathcal{N}_0} R^2_{\widehat{U} \cup \{i\}}$, and added to \widehat{U} , forming the updated candidate control group $\widehat{U} = \{i_1^*, i_2^*\}$. The algorithm continues selecting control units until the modified Bayesian Information Criterion stops the selection process (Wang et al., 2009). After, fsPDA uses OLS to predict

$$\hat{\mathbf{y}}_1^0(\widehat{U}) = \mathbf{Y}'_{\widehat{U}} \hat{\boldsymbol{\beta}}_{\widehat{U}} + \hat{\boldsymbol{\beta}}_0 \forall t \in \mathcal{T} \quad (2)$$

where $\hat{\mathbf{y}}_1^0(\widehat{U})$ corresponds to our predictions, $\hat{\boldsymbol{\beta}}_{\widehat{U}}$ corresponds to the coefficients, and $\hat{\boldsymbol{\beta}}_0$ is the intercept. In our case, we are most interested in the out-of-sample predictions.

Algorithm 1 fsPDA Method

```

1:  $\widehat{U} \leftarrow \emptyset$ 
2: while mBIC not satisfied do
3:   for each  $i \in \mathcal{N}_0 \setminus \widehat{U}$  do
4:     Estimate Equation 1
5:     Compute  $R^2_{\widehat{U} \cup \{i\}}$ 
6:   end for
7:   Select  $i^* = \arg \max_{i \in \mathcal{N}_0} R^2_{\widehat{U} \cup \{i\}}$ 
8:    $\widehat{U} \leftarrow \widehat{U} \cup \{i^*\}$ 
9: end while
10: Return:  $\widehat{U}$ 

```

To conduct inference, SH use a heteroskedasticity and autocorrelation consistent esti-

mator of the long run variance via $\hat{\rho}_{\tau\hat{U}}^2 = T_2^{-1} \sum_{ts \in T_2} (\hat{\Delta}_{\hat{U}t} - \bar{\Delta}_{\hat{U}})(\hat{\Delta}_{Us} - \bar{\Delta}_U) \cdot \mathbf{1}\{|t-s| \leq \tau\}$ where τ is the number of lags and $\bar{\Delta}_{\hat{U}}$ is the variance of the estimated treatment effect. The formula for the t-statistic is $t_{\hat{U}} = \frac{\sqrt{T_2} \cdot \bar{\Delta}_{\hat{U}}}{\hat{\rho}_{\tau\hat{U}}}$.

2.2 Forward Difference-in-Differences

Next, I describe fDID. The procedure iterates over k total candidate iterations, starting with an empty set of controls. Let $\mathcal{U} := \{\hat{U}_1, \hat{U}_2, \dots, \hat{U}_{N_0}\}$ represent the set of candidate control groups. Following Greathouse et al. (2024), DID is estimated via least-squares

$$\mathbf{y}_1 = \mathbf{Y}'_{\hat{U}_{k-1} \cup \{i\}} \hat{\beta}_{\hat{U}_{k-1} \cup \{i\}} + \hat{\beta}_0 \quad \text{s.t.} \quad \hat{\beta}_{\hat{U}_{k-1} \cup \{i\}} = \frac{1}{U_{k-1} \cup \{i\}}, \quad \forall i \in \mathcal{T}_1 \quad (3)$$

For $k = 1$, we estimate a one-control DID model $\forall i \in \mathcal{N}_0$. The control unit which maximizes the pre-treatment R-squared, R_i^2 , is selected as $i_1^* = \arg \max_{i \in \mathcal{N}_0} R_i^2$, forming the first candidate control group, $\hat{U}_1 = \{i_1^*\}$. The set \mathcal{U} is updated accordingly, $\mathcal{U} \cup \hat{U}_1 = \{\hat{U}_1\}$. For $k = 2$, a DID model is estimated for each remaining control $i \in \mathcal{N}_0 \setminus \{i_1^*\}$, where each model includes i_1^* and one additional control. The control which maximizes R^2 when combined with i_1^* is selected as $i_2^* = \arg \max_{i \in \mathcal{N}_0 \setminus \{i_1^*\}} R_{\{i_1^*, i\}}^2$, forming the next candidate control group, $\hat{U}_2 = \{i_1^*, i_2^*\}$. \mathcal{U} is updated accordingly $\mathcal{U} \cup \hat{U}_2 = \{\hat{U}_1, \hat{U}_2\}$. At each iteration k , a DID model is estimated for each remaining control $i \in \mathcal{N}_0 \setminus \hat{U}_{k-1}$, combining the previously selected controls \hat{U}_{k-1} with one additional unit. The process continues until $k = N_0$, with \mathcal{U} being updated at each step, $\mathcal{U} \cup \hat{U}_k$. The final control group returned by fDID is the one which maximizes the R-squared statistic across all candidate sets: $\hat{U} := \arg \max_{\hat{U}_k \in \mathcal{U}} R^2(\hat{U}_k)$.

The fDID predictions take the following form

$$\hat{\mathbf{y}}_1^0(\hat{U}) = \mathbf{Y}'_{\hat{U}} \hat{\beta}_{\hat{U}} + \hat{\beta}_0 \quad \text{s.t.} \quad \hat{\beta}_{\hat{U}} = \frac{1}{U}, \quad (4)$$

where we estimate DID except only using the selected control group \hat{U} . Here is the

Algorithm 2 Forward Difference-in-Differences (fDID)

```
1: Initialize:  $\hat{U}_0 \leftarrow \emptyset$ 
2: for  $k = 1$  to  $N_0$  do
3:   for each  $i \in \mathcal{N}_0 \setminus \hat{U}_{k-1}$  do
4:     Estimate: Equation 3
5:     Compute:  $R_k^2(\hat{U}_{k-1} \cup \{i\})$ 
6:   end for
7:   Update  $\mathcal{U} \cup \hat{U}_k \leftarrow \mathcal{U} \cup \left( \hat{U}_{k-1} \cup \left\{ \operatorname{argmax}_{i \in \mathcal{N}_0 \setminus \hat{U}_{k-1}} R_k^2(\hat{U}_{k-1} \cup \{i\}) \right\} \right)$ 
8: end for
9: Return:  $\hat{U} := \operatorname{argmax}_{\hat{U}_k \in \mathcal{U}} R^2(\hat{U}_k)$ 
```

formula for fDID's standard error:

$$\hat{\Omega} = \left[\left(\frac{T_2}{T_1} \right) \cdot T_1^{-1} \sum_{t \in \mathcal{T}_1} \hat{v}_{1t}^2 \right]^{0.5}, \quad \hat{v}_{1t} = \mathbf{y}_1 - \hat{\mathbf{y}}_1^0(\hat{U}) \quad (5)$$

which is then used to construct confidence intervals and t-statistics.

A few comments are in order: firstly as Li (2024) notes, fsPDA may possibly overfit the pre-intervention data if fsPDA selects too many controls [see the San Diego or Atlanta examples from Li (2024)]. In contrast, fDID cannot overfit since it only estimates $\hat{\beta}_0$. Additionally, fDID constrains $\hat{\beta}_{\hat{U}}$ to be proportional, whereas fsPDA's coefficients are unconstrained. Practically, this means it is likely the case the fsPDA method may, on average, have better in-sample fit compared to fDID, making it a more flexible estimator compared to fDID when its parallel pre-intervention trends assumption does not hold.

3 Replication Process

R Workflow I first downloaded the fsPDA package for R from Zhentao Shi's GitHub. This package contains the dataset as well as the corresponding R function. The outcome data were originally in dollars, coming from the United Nations COMTRADE database. As described in SH, the dollar amount is transformed to (what appears to be since SH do not specify) the month over month growth rate of the import value for each of the 88 goods. I then used the provided R code in the fsPDA vignette to estimate the effect of the ACC on the growth rate of the import of luxury watches. I then concatenated

the treatment vector and the control group matrix together in R into a single dataframe. I exported this dataframe as a comma separated value file so it could be used for analysis in Stata. This concluded the work in R.²

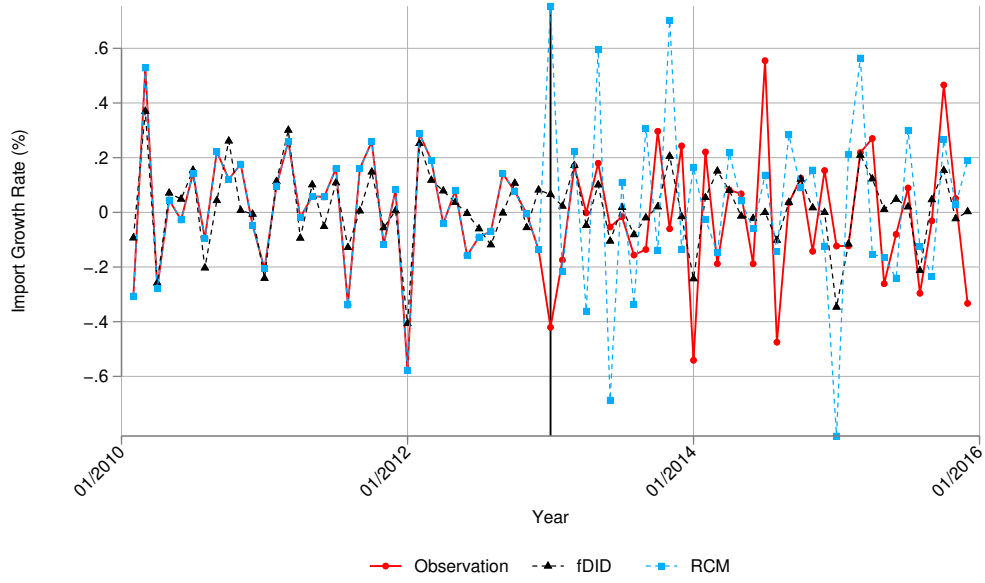
Stata Workflow In Stata 17, I installed the `fdid` package as well as `rcm` as described, respectively, in Greathouse et al. (2024) and Yan and Chen (2022). I then imported the wide-form dataset (the one exported from R) into Stata. I then generated a time variable from $t = \{1, 2, \dots, 71\}$, which would represent the time periods of interest (February 2010 to December of 2015). I then reshaped this dataset to long format, so each import good had one row per time period. Treatment begins January of 2013, where $t = 36$, giving us 35 pre-intervention periods and 36 post-intervention periods. I estimated `fdid` with the default settings, `fdid import, tr(treat) unitnames(unit)`. For RCM, the specification was `rcm import, trperiod(36) trunit(1) method(forward) criterion(mbic)`.

4 Results of Replication

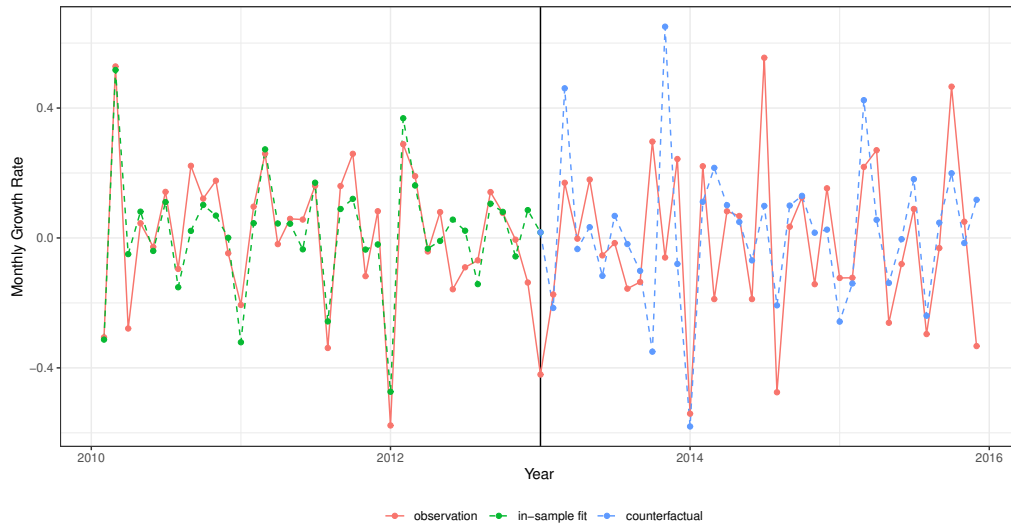
Point Estimates and Uncertainty In panels 1a and 1b respectively of Figure 1, I present the results of the `fdid`, `RCM` and `fsPDA` methods. The solid light red line corresponds to the observation, and the connected dashed lines correspond to the predictions. The returned ATT using the `fdid` method is -0.0252 .

Multiplying by 100, this corresponds to a 2.52% decrease in the monthly import of luxury watches in the post-intervention period, which extends from January 2013 to December of 2015. For `fsPDA`, the ATT is -0.0308 , or roughly a 3.1% decrease in the import of luxury watches across the post-intervention period. For `RCM`, the ATT was -0.0501 , or a 5% decrease. Now we turn to the uncertainty estimates. The standard error for `fdid` is 0.0265. For `fsPDA`, the standard error is 0.0274, virtually identical to `fdid`. Unfortunately, `RCM` reports neither a standard error for the ATT or a corresponding t-statistic. Both `fdid` and `fsPDA` have similar ATTs and very similar standard errors.

²See the exact replication code at the author's GitHub.



(a) Stata: fDID and RCMs



(b) R: fsPDA

Figure 1: Comparison of Methods

The Selected Controls Now I discuss the selected control units. Since the point of both algorithms is to choose a relevant control group among a pool of many irrelevant units, listing the selected controls allows us to get a sense of how both methods compare to one another. The fsPDA method chooses control units with the numeric ids 60, 45, and 25. The RCM selects, for some reason, 33 controls, almost as many controls as we have pre-treatment time periods. fDID selects 14 controls, specifically: Control 60, Control 82, Control 26, Control 58, Control 45, Control 50, Control 15, Control 19, Control 21,

Control 54, Control 81, Control 31, Control 85, and Control 51. The pre-intervention R-squared from fsPDA is 0.777, and the analogous metric for fDID is 0.707, or a difference of around 7 percentage points. This suggests the pre-intervention parallel trend assumption seems to hold for the fDID method. The difference of R-squared statistics, regarding fDID and fsPDA, is to be expected since the unconstrained regression fsPDA is based on tends to obtain better in-sample fit (Gardeazabal & Vega-Bayo, 2017). Overall though, the differences between fDID and fsPDA are marginal: both methods select two of the same control units and have good in-sample fit and produce similar out-of-sample predictions. For RCM, the model overfits drastically with a pre-intervention R-squared of 100%.

There are a few caveats to this replication, however: the most concerning of them is the results of RCM do not come close to matching fDID’s results or the results of SH. The in-sample predictions overfit substantially. It is not apparent why this would be, as Yan and Chen (2022) note their package allows for use of the modified Bayesian criterion and forward selection, the same one used by SH. More puzzlingly, when we use forward-selection and the AICc for RCM,³ we get 14 control units selected and the exact same ATT as fsPDA. However, the stopping rule for SH is specifically the modified Bayesian Information Criterion, so I report the RCM specification that matches closest to SH’s method.

SH list “knitted or crocheted fabric”, “cork and articles of cork”, and “salt, sulfur, earth, stone, plaster, lime and cement” as the selected controls. However, the actual names of the control units are not named in the R data. Otherwise, it would be interesting to see which specific controls were selected by fDID. SH also write in the published paper “the t-statistic is -2.457, with a p-value 1.40%”. However, when the code is ran (as of October 5th 2024), we get the t-statistic I list above. It is not obvious why this discrepancy exists, especially since a t-statistic of 2.457 would reject the null hypothesis of 0 ATT at the 5% size. This aside, the results between fsPDA and fDID are mostly similar.

³The Stata code is `rcm import, trperiod(36) trunit(1) method(forward) frame(fsframe)`.

5 Conclusion

Excluding the RCM, I succeeded in replicating the empirical findings from Shi and Huang (2023). In terms of future research, it would be interesting to more formally compare both fDID and fsPDA’s control group selection methods to synthetic control methods. The idea would be to theoretically explain why the algorithms select the control units they do. A corollary to this would be to use finely tuned and realistic synthetic studies to measure the degree to which each method selects the proper set of control units.

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