1 Problem statement and formulation

Given a nonlinear heat conduction problem, solve for the sensitivity of the solution to different parameters which affect the thermal conductivity. The problem can be written as

$$\frac{d}{dx}\left(k(T)\frac{dT}{dx}\right) = 0\tag{1}$$

subject to

$$T(0) = T_L$$
 and $T(L) = T_R$ (2)

The thermal conductivity is represented by two piecewise linear segments:

$$k(T) = \begin{cases} k_1 \left(1 - \frac{T - T_1}{T_2 - T_1} \right) + k_2 \left(\frac{T - T_1}{T_2 - T_1} \right), T_1 \leqslant T \leqslant T_2 \\ k_2 \left(1 - \frac{T - T_2}{T_3 - T_2} \right) + k_3 \left(\frac{T - T_2}{T_3 - T_2} \right), T_2 < T \leqslant T_3 \end{cases}$$

$$(3)$$

Defining the residual as

$$\mathcal{R} = \frac{d}{dx} \left(k(T) \frac{dT}{dx} \right) \tag{4}$$

then multiplying by a weight function and integrating over an element,

$$\pi = \int_{\Omega} w \frac{d}{dx} \left(k(T) \frac{dT}{dx} \right) d\Omega \tag{5}$$

Next, we apply integration by parts,

$$\pi = \oint_{\Gamma} k(T) w \frac{dT}{dx} \hat{\mathbf{n}} d\Gamma - \int_{\Omega} k(T) \frac{dw}{dx} \frac{dT}{dx} d\Omega$$
 (6)

Now, the weight function can be written as

$$w(x) = \sum_{j} V_{j} N_{j} \tag{7}$$

where N_j represents the shape functions and V_j represents a vector of unknown coefficients. Using the same shape functions for the approximation function:

$$\widetilde{T}(x) = \sum_{i} c_i N_i \tag{8}$$

Inserting these into (6) and assuming no Neumann boundary conditions,

$$\pi = -\int_{\Omega} k(T) \left[\sum_{j} V_{j} \frac{dN_{j}}{dx} \right] \left[\sum_{i} c_{i} \frac{dN_{i}}{dx} \right] d\Omega \tag{9}$$

Now, making the functional stationary with respect to V_j and dropping the summations for clarity,

$$\frac{\partial \pi}{\partial V_i} = \left[\int_{\Omega} k(T) \frac{dN_i}{dx} \frac{dN_j}{dx} d\Omega \right] c_i = 0$$
 (10)

In this case, since the Lagrange basis is used, the coefficients represent temperatures at the nodes. Integrating over the element in the computational domain,

$$\left[\int k(T(x)) \frac{dN_i}{d\xi} \frac{dN_j}{d\xi} J d\xi \right] c_i = 0$$
 (11)

This problem can be written as

$$\mathbf{K}(\mathbf{u})\,\mathbf{u} = \mathbf{f} \tag{12}$$

where \mathbf{u} is a vector which holds all the coefficients and \mathbf{f} is full of zeros because there is no source term. Because the problem is nonlinear, the stiffness matrix is a function of the solution \mathbf{u} . Piccard iteration is used to iterative solve in the following manner:

$$\mathbf{K}(\mathbf{u}^n)\mathbf{u}^{n+1} = \mathbf{f} \tag{13}$$

2 Derivation of SACVM

If we want to calculate the sensitivities of the solution, \mathbf{u} , with respect to some parameters, \mathbf{x} , we can do so using the following

$$\mathbf{K}\frac{\partial \mathbf{u}}{\partial \mathbf{x}} + \frac{\partial \mathbf{K}}{\partial \mathbf{x}} \mathbf{u} = \frac{\partial \mathbf{f}}{\partial \mathbf{x}}$$
 (14)

We may then solve for the sensitivity as

$$\frac{\partial \mathbf{u}}{\partial \mathbf{x}} = \mathbf{K}^{-1} \left(\frac{\partial \mathbf{f}}{\partial \mathbf{x}} - \frac{\partial \mathbf{K}}{\partial \mathbf{x}} \mathbf{u} \right) \tag{15}$$

Writing the derivatives using the Piccard iteration and dropping the load vector due to zero source terms,

$$\left(\frac{\partial \bar{\mathbf{u}}}{\partial \mathbf{x}}\right)^{n+1} = -\mathbf{K}(\bar{\mathbf{u}})^{-1} \left(\frac{\partial \mathbf{K}(\bar{\mathbf{u}})}{\partial \mathbf{x}}\right)^{n} \bar{\mathbf{u}}$$
(16)

where the overbar denotes the solution to the original nonlinear problem. We must now find a way to compute the gradient of the stiffness matrix with respect to the parameters. The complex variable method for approximating derivatives can be written as

$$\frac{df}{dx} = \frac{\operatorname{Im}[f(x+ih)]}{h} + \mathcal{O}[h^2]$$

Now, applying the complex variable method to the derivative of the stiffness matrix,

$$\left(\frac{\partial \mathbf{K}(\bar{\mathbf{u}})}{\partial \mathbf{x}}\right)^{n} = \underbrace{\frac{\operatorname{Im}\left[\mathbf{K}(\bar{\mathbf{u}} + i\mathbf{h}_{\mathbf{u}})\right]}{\mathbf{h}_{\mathbf{u}}}}_{\mathbf{\partial u}} \left(\frac{\partial \mathbf{u}}{\partial \mathbf{x}}\right)^{n} \tag{17}$$

This $\mathbf{h_u}$ is the perturbation in temperature due to the perturbation in the thermal conductivity. Given a perturbation in thermal conductivity, we must solve for the corresponding perturbation in the temperature field.

Another way to look at it:

$$[\Delta \mathbf{u}]^{n+1} = -\mathbf{K}(\bar{\mathbf{u}})^{-1} [\Delta \mathbf{K}(\bar{\mathbf{u}})]^n \bar{\mathbf{u}}$$
$$[\Delta \mathbf{u}]^{n+1} = -\mathbf{K}(\bar{\mathbf{u}})^{-1} \operatorname{Im} [\mathbf{K}(\bar{\mathbf{u}} + i[\Delta \mathbf{u}]^n)] \bar{\mathbf{u}}$$