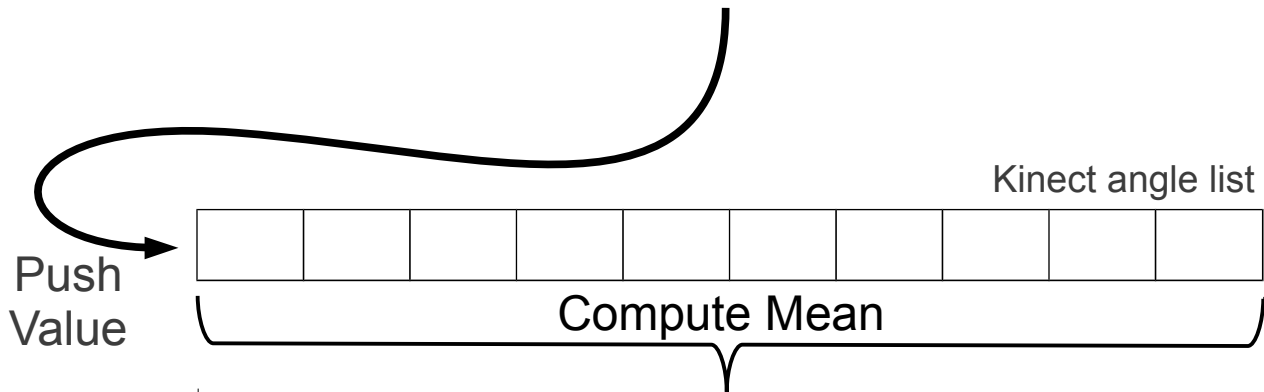
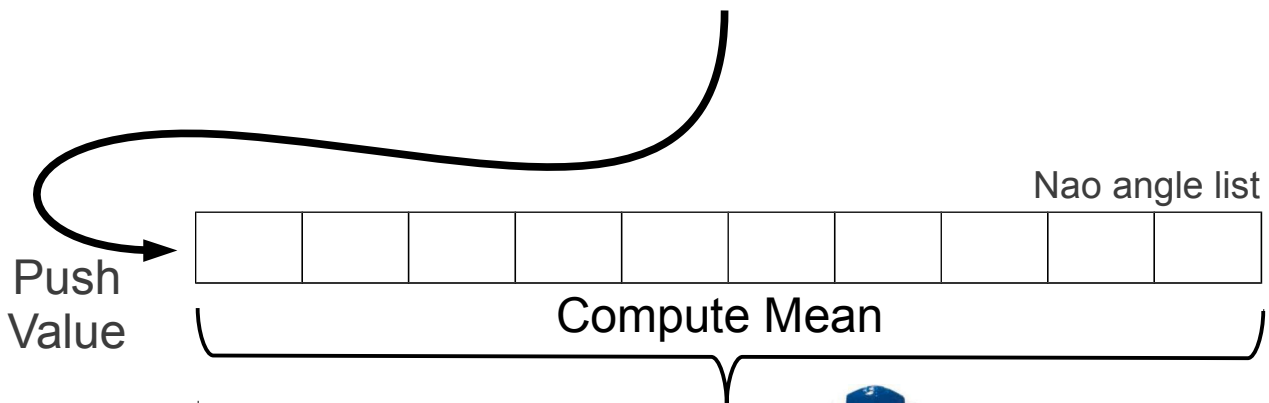


Compute angle from 3D Kinect data



Transform Kinect angle to Nao angle



Push value to the robot

