

Time Deep Gradient Flow Method for Option Pricing in rough Diffusion Models

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joint work with Antonis Papapantoleon

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Price of a derivative with pay-off $\Phi(S_T)$

$$u(t, \mathbf{x}) = \mathbb{E} \left[e^{-r(T-t)} \Phi(S_T) | S_t \right]$$

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Feynman-Kac formula:

$$\frac{\partial u}{\partial t} - \sum_{i,j=0}^n a^{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} - \sum_{i=0}^n b^i \frac{\partial u}{\partial x_i} + ru = 0$$
$$u(0, \mathbf{x}) = \Phi(\mathbf{x})$$

Rough Heston

- Not Markovian \implies no PDE

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- Lifted Heston: Markovian, but multiple dimensions

$$dS_t = rS_t dt + \sqrt{V_t^n} S_t dW_t \quad S_0 > 0$$

$$V_t^n = g^n(t) + \sum_{i=1}^n c_i^n V_t^{n,i}$$

$$dV_t^{n,i} = -\left(\gamma_i^n V_t^{n,i} + \lambda V_t^n\right) dt + \eta \sqrt{V_t^n} dB_t \quad V_0^{n,i} = 0$$

$$g^n(t) = V_0 + \lambda \theta \sum_{i=1}^n c_i^n \int_0^t e^{-\gamma_i^n(t-s)} ds$$

Deep Galerkin Method

$$\frac{\partial u}{\partial t} - \sum_{i,j=0}^n a^{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} - \sum_{i=0}^n b^i \frac{\partial u}{\partial x_i} + ru = 0$$
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Minimize

$$\left\| \frac{\partial u}{\partial t} - \sum_{i,j=0}^n a^{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} - \sum_{i=0}^n b^i \frac{\partial u}{\partial x_i} + ru \right\|_{[0,T] \times \Omega}^2 + \|u(0, \mathbf{x}) - \Phi(\mathbf{x})\|_{\Omega}^2$$

Deep Galerkin Method

$$\frac{\partial u}{\partial t} - \sum_{i,j=0}^n a^{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} - \sum_{i=0}^n b^i \frac{\partial u}{\partial x_i} + ru = 0$$
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Issue: Taking second derivative makes training in high dimensions slow

Rewrite PDE as energy minimization problem

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- Only first order derivative
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Split in symmetric and non-symmetric part

Splitting method

$$\frac{\partial u}{\partial t} = \sum_{i,j=0}^n a^{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} + \sum_{i=0}^n b^i \frac{\partial u}{\partial x_i} - ru$$

Splitting method

$$\begin{aligned}\frac{\partial u}{\partial t} &= \sum_{i,j=0}^n a^{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} + \sum_{i=0}^n b^i \frac{\partial u}{\partial x_i} - ru \\ &= \sum_{i,j=0}^n \frac{\partial}{\partial x_j} \left(a^{ij} \frac{\partial u}{\partial x_i} \right) - \sum_{i,j=0}^n \frac{\partial a^{ij}}{\partial x_j} \frac{\partial u}{\partial x_i} + \sum_{i=0}^n b^i \frac{\partial u}{\partial x_i} - ru\end{aligned}$$

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$$\begin{aligned}\frac{\partial u}{\partial t} &= \sum_{i,j=0}^n a^{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} + \sum_{i=0}^n b^i \frac{\partial u}{\partial x_i} - ru \\&= \sum_{i,j=0}^n \frac{\partial}{\partial x_j} \left(a^{ij} \frac{\partial u}{\partial x_i} \right) - \sum_{i,j=0}^n \frac{\partial a^{ij}}{\partial x_j} \frac{\partial u}{\partial x_i} + \sum_{i=0}^n b^i \frac{\partial u}{\partial x_i} - ru \\&= \sum_{i,j=0}^n \frac{\partial}{\partial x_j} \left(a^{ij} \frac{\partial u}{\partial x_i} \right) - \sum_{i=0}^n \left(\sum_{j=0}^n \frac{\partial a^{ij}}{\partial x_j} - b^i \right) \frac{\partial u}{\partial x_i} - ru \\&= \nabla \cdot (A \nabla u) - ru - F(u)\end{aligned}$$

$$F(u) = \mathbf{b} \cdot \nabla u$$

Example, $n = 1$

$$\begin{aligned}dS_t &= rS_t dt + \sqrt{V_t} S_t dW_t \\dV_t &= -\lambda V_t dt + \eta \sqrt{V_t} dB_t\end{aligned}$$

Example, $n = 1$

$$dS_t = rS_t dt + \sqrt{V_t} S_t dW_t$$

$$dV_t = -\lambda V_t dt + \eta \sqrt{V_t} dB_t$$

$$\frac{\partial u}{\partial t} = rS \frac{\partial u}{\partial S} - \lambda V \frac{\partial u}{\partial V} + \frac{1}{2} S^2 V \frac{\partial^2 u}{\partial S^2} + \frac{1}{2} \eta^2 V \frac{\partial^2 u}{\partial V^2} + \rho \eta S V \frac{\partial^2 u}{\partial S \partial V} - ru$$

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Example: $n = 1$

$$\begin{aligned}
 \frac{\partial u}{\partial t} &= rS \frac{\partial u}{\partial S} - \lambda V \frac{\partial u}{\partial V} + \frac{1}{2} S^2 V \frac{\partial^2 u}{\partial S^2} + \frac{1}{2} \eta^2 V \frac{\partial^2 u}{\partial V^2} + \rho \eta S V \frac{\partial^2 u}{\partial S \partial V} - ru \\
 &= rS \frac{\partial u}{\partial S} - \lambda V \frac{\partial u}{\partial V} + \frac{\partial}{\partial S} \left(\frac{1}{2} S^2 V \frac{\partial u}{\partial S} \right) - S V \frac{\partial u}{\partial S} \\
 &\quad + \frac{\partial}{\partial V} \left(\frac{1}{2} \eta^2 V \frac{\partial u}{\partial V} \right) - \frac{1}{2} \eta^2 \frac{\partial u}{\partial V} + \frac{\partial}{\partial S} \left(\frac{1}{2} \rho \eta S V \frac{\partial u}{\partial V} \right) - \frac{1}{2} \rho \eta V \frac{\partial u}{\partial V} \\
 &\quad + \frac{\partial}{\partial V} \left(\frac{1}{2} \rho \eta S V \frac{\partial u}{\partial S} \right) - \frac{1}{2} \rho \eta S \frac{\partial u}{\partial S} - ru \\
 &= \nabla \cdot \left(\frac{1}{2} \begin{bmatrix} S^2 V & \rho \eta S V \\ \rho \eta S V & \eta^2 V \end{bmatrix} \nabla u \right) - \left[\begin{matrix} S V + \frac{1}{2} \rho \eta S - r S \\ \frac{1}{2} \eta^2 + \frac{1}{2} \rho \eta V + \lambda V \end{matrix} \right] \cdot \nabla u - ru
 \end{aligned}$$

Time Deep Gradient Flow

$$\begin{cases} u_t - \nabla \cdot (A \nabla u) + ru + F(u) = 0 & (t, \mathbf{x}) \in [0, T] \times \Omega \\ u(0, \mathbf{x}) = \Phi(\mathbf{x}) & \mathbf{x} \in \Omega \end{cases}$$

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- Divide $[0, T]$ in intervals $(t_{k-1}, t_k]$ with $h = t_k - t_{k-1}$

$$\frac{U^k - U^{k-1}}{h} - \nabla \cdot (A \nabla U^k) + rU^k + F(U^{k-1}) = 0$$

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$$0 = \int_{\Omega} \left((U^k - U^{k-1}) + h \left(-\nabla \cdot (A \nabla U^k) + rU^k + F(U^{k-1}) \right) \right) v d\mathbf{x}$$

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$$i^k(\tau) = I^k(U^k + \tau v)$$

Time Deep Gradient Flow

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$$i^k(\tau) = I^k(U^k + \tau v)$$

$$I^k(u) = \frac{1}{2} \|u - U^{k-1}\|^2 + h \int_{\Omega} \frac{1}{2} \left((\nabla u)^T A \nabla u + ru^2 \right) + F(U^{k-1}) u dx$$

$$U^k = \arg \min_{u \in H^1(\Omega)} I^k(u)$$

Time **Deep** Gradient Flow

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$$U^k = \arg \min_{u \in H^1(\Omega)} I^k(u)$$

$$f^k(\mathbf{x}; \theta) = \arg \min_{u \in \mathcal{C}(\theta)} I^k(u)$$

$\mathcal{C}(\theta)$ = space of neural networks with parameters θ

Algorithm

- 1: **for** each time step $k = 1, \dots, K$ **do**
- 2: Initialize $\theta_0^k = \theta^{k-1}$

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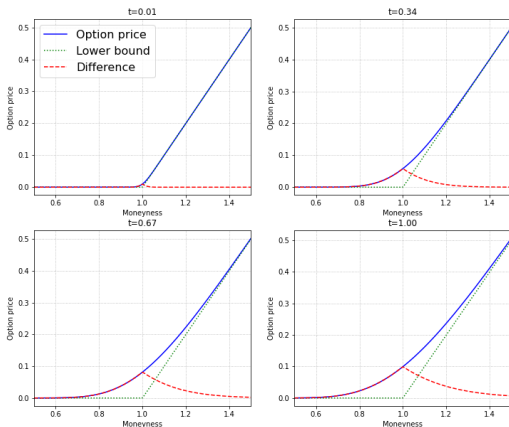
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Algorithm

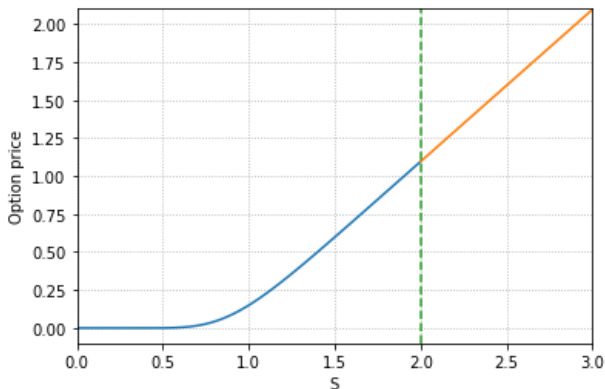
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3:   for each sampling stage  $n$  do
4:     Generate random points  $\mathbf{x}^i$  for training
5:     Calculate the cost functional  $I^k(f(\mathbf{x}^i; \theta_n^k))$ 
6:     Take a descent step  $\theta_{n+1}^k = \theta_n^k - \alpha_n \nabla_{\theta} I^k(f(\mathbf{x}^i; \theta_n^k))$ 
7:   end for
8: end for
```

No-arbitrage bound: $u(t, S) \geq S - Ke^{-rt}$



Linearization

$$f(x_p + y; \theta) = f(x_p; \theta) + y, \quad y > 0.$$



Architecture

$$S^1 = \sigma_1 (W^1 \mathbf{x} + b^1)$$

$$Z^l = \sigma_1 \left(U^{z,l} \mathbf{x} + W^{z,l} S^l + b^{z,l} \right) \quad l = 1, \dots, L$$

$$G^l = \sigma_1 \left(U^{g,l} \mathbf{x} + W^{g,l} S^l + b^{g,l} \right) \quad l = 1, \dots, L$$

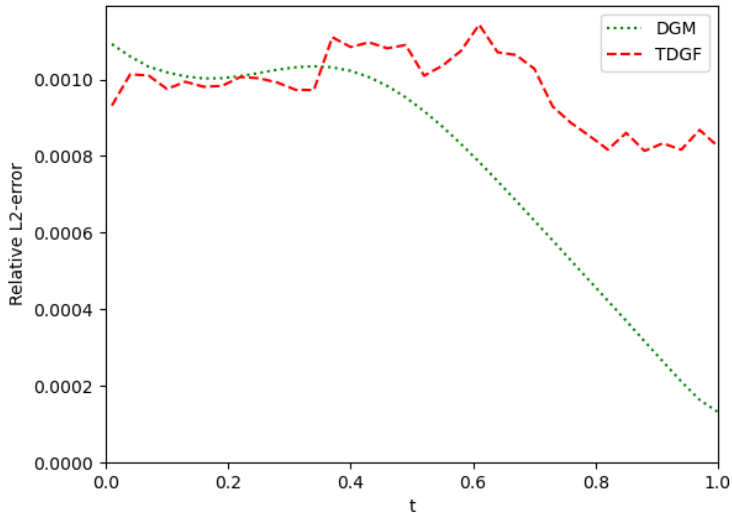
$$R^l = \sigma_1 \left(U^{r,l} \mathbf{x} + W^{r,l} S^l + b^{r,l} \right) \quad l = 1, \dots, L$$

$$H^l = \sigma_1 \left(U^{h,l} \mathbf{x} + W^{h,l} (S^l \odot R^l) + b^{h,l} \right) \quad l = 1, \dots, L$$

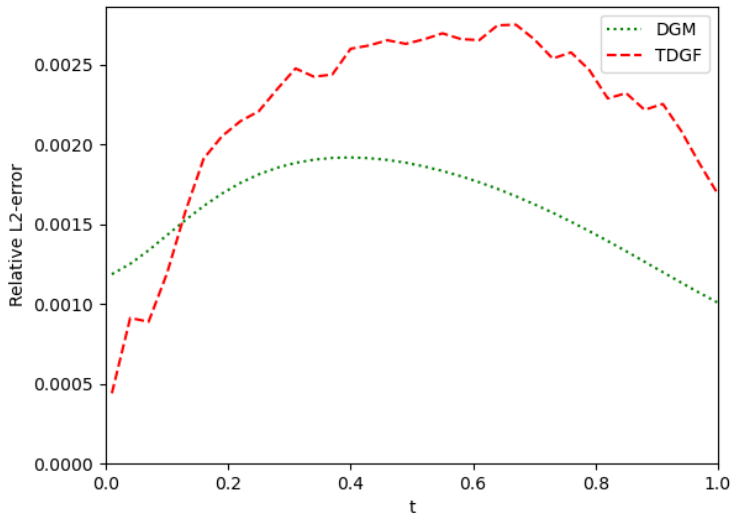
$$S^{l+1} = (1 - G^l) \odot H^l + Z^l \odot S^l \quad l = 1, \dots, L$$

$$f(\mathbf{x}; \theta) = \text{base} + \sigma_2 \left(WS^{L+1} + b \right) \quad \sigma_2 > 0$$

Lifted Heston, $n = 1$



Lifted Heston, $n = 20$



Running times

Model	LH, n=1	LH, n=20
DGM	12.5×10^3	54.3×10^3
TDGF	5.9×10^3	7.4×10^3

Table: Training time

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DGM	12.5×10^3	54.3×10^3
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Table: Training time

Model	LH, n=1	LH, n=20
COS	9.1	10.0
DGM	0.0043	0.0015
TDGF	0.0019	0.0018

Table: Computing time

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