#### Lecture XII

# Approximating the Invariant Distribution

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# SS Equilibrium in the Aiyagari model

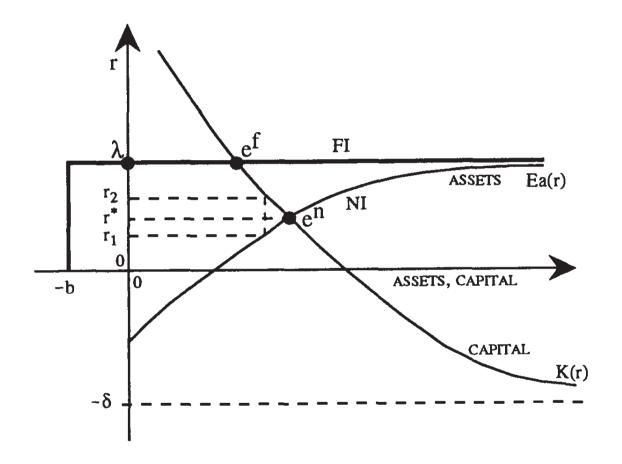


FIGURE IIb
Steady-State Determination

### SS Equilibrium of the Aiyagari model

Fixed point algorithm over the interest rate (or K).

- 1. Fix an initial guess for the interest rate  $r^0 \in \left(-\delta, \frac{1}{\beta} 1\right)$ .  $r^0$  is our first candidate for the equilibrium (the superscript denotes the iteration number).
- 2. Given  $r^0$ , solve the dynamic programming problem of the agent to obtain  $a' = g(a, y; r^0)$ . We described several solution methods.
- 3. Given the decision rule for assets next period  $g(a,y;r^0)$  and the Markov transition over productivity shocks  $\Gamma(y',y)$ , we can construct the transition function  $Q(r^0)$  and, by successive iterations, we obtain the fixed point distribution  $\Lambda(r^0)$ , conditional on the candidate interest rate  $r^0$ .

### SS Equilibrium of the Aiyagari model

4. Compute the aggregate demand of capital  $K\left(r^{0}\right)$  from the optimal choice of the firm who takes  $r^{0}$  as given, i.e.

$$K(r^0) = F_k^{-1}(r^0 + \delta)$$

5. Compute the integral:

$$A(r^{0}) = \int_{A \times Y} g(a, y; r^{0}) d\Lambda(a, y; r^{0})$$

which gives the aggregate supply of assets. This can be easily done by using the invariant distribution obtained in step 3.

## SS Equilibrium of the Aiyagari model

- 6. Compare  $K\left(r^{0}\right)$  with  $A\left(r^{0}\right)$  to verify whether the asset market clearing condition holds.
- 7. Use a nonlinear equation solver in your outer loop to update from  $r^0$  to  $r^1$  and go back to step 1.
- 8. Keep iterating until you reach convergence of the interest rate, i.e., until, at iteration n:

$$|r^{n+1} - r^n| < \varepsilon$$

### Calculating the invariant distribution

- Continuum of households makes the wealth distribution a continuous function and therefore an infinite-dimensional object in the state space. Need approximation.
- Small errors in computing the invariant distribution, particularly in models with aggregate shocks, can accumulate and lead to significant errors in the equilibrium values of aggregate variables.
- Five approaches:
  - 1. piecewise linear approximation of invariant distribution function
  - 2. discretization of the invariant density function
  - 3. eigenvector method
  - 4. simulation of an artificial panel
  - 5. approximating the cdf by an exponential function [not today]

#### **Preliminaries**

- Let  $\mathcal{Y}$  be the grid of y and  $\Gamma$  be its J-state Markov chain with  $\Gamma_{ij} = \Pr\{y' = y_j | y = y_i\}$
- We think of separate asset distributions conditional on each value of  $y \in \mathcal{Y}$ , i.e.

$$\Lambda(a^*, y^*) = \Pr\{a \le a^*, y = y^*\}$$

• The invariant distribution function satisfies the law of motion:

$$\Lambda\left(a',y'\right) = \sum_{y \in \mathcal{Y}} \Gamma\left(y',y\right) \Lambda\left(g^{-1}\left(a',y\right),y\right) \quad \text{ for all } \left(a',y'\right)$$

where  $g^{-1}(a',y)$  is the inverse of the saving decision rule with respect to its first argument a. Clearly, we are using the monotonicity of g.

- This method involves approximating  $\Lambda$  by a weighted sum of piecewise-linear functions and iterating on the law of motion above
- The approximation of  $\Lambda$  must be shape-preserving since it would not make sense if  $\Lambda$  decreased over some range of a. This makes piecewise linear basis functions a better choice than say Chebyshev polynomials or cubic splines.
- Other approximations that preserve shape, such as shape-preserving splines could potentially also be appropriate
- First we need a grid  $\mathcal{A}$  of interpolation nodes in the interval  $[\underline{a}, \overline{a}]$ . This grid needs to be a lot finer than the grid used for computing the decision rule. Does not have to be an evenly spaced grid. Let N be the size of this grid.

• Choose an initial distribution  $\Lambda^0$  over the grid  $\mathcal{A} \times \mathcal{Y}$ . One choice is, for example, for every pair  $(a_k, y_j) \in \mathcal{A} \times \mathcal{Y}$ 

$$\Lambda^{0}(a_{k}, y_{j}) = \frac{a_{k} - \underline{a}}{\overline{a} - \underline{a}} \Gamma_{j}^{*}$$

as if the two variables were independent and the distribution over assets a were uniform.

• Update the distribution on grid points as follows. For every pair  $(a_k, y_j) \in \mathcal{A} \times \mathcal{Y}$ 

$$\Lambda^{1}\left(a_{k}, y_{j}\right) = \sum_{y_{i} \in \mathcal{Y}} \Gamma_{ij} \Lambda^{0}\left(g^{-1}\left(a_{k}, y_{i}\right), y_{i}\right)$$

Note: (i) need to compute  $g^{-1}$  and (ii)  $g^{-1}$  not on  $\mathcal{A}$ 

• How do we solve for  $a = g^{-1}(a_k, y_i)$ ? Recall: you also have the consumption decision rule on the original grid used for policy functions (obtained residually from the budget constraint). Then, since  $a_k = g(a, y_i)$ 

$$c\left(a, y_i\right) + a_k = Ra + y_i$$

and we can calculate a through a nonlinear solver given a piece-wise linear representation of  $c\left(a,y_{i}\right)$ .

• Given  $a = g^{-1}(a_k, y_i)$ , we need a linear interpolation of  $\Lambda^0$  since  $\Lambda^0$  is only defined on the grid.

• For an  $a \in [a_n, a_{n+1}]$ , we define:

$$\Lambda^{0}(a, y_{i}) = \Lambda^{0}(a_{n}, y_{i}) + \frac{\Lambda^{0}(a_{n+1}, y_{i}) - \Lambda^{0}(a_{n}, y_{i})}{a_{n+1} - a_{n}}(a - a_{n})$$

• Compare  $\Lambda^{1}\left(a_{k},y_{j}\right)$  to  $\Lambda^{0}\left(a_{k},y_{j}\right)$ , for example with the supnorm

$$\max_{j,k} |\Lambda^{1}(a_{k}, y_{j}) - \Lambda^{0}(a_{k}, y_{j})| < \varepsilon$$

and stop when your tolerance level  $\varepsilon$  is reached

How do we compute the aggregate supply of capital

$$A = \sum_{y_i \in \mathcal{Y}} \int_A a d\Lambda(a, y_i)$$

• We assume the distribution of assets is uniform within the element  $[a_n, a_{n+1}]$  and therefore

$$\int_{a_{n}}^{a_{n+1}} ad\Lambda(a, y_{i}) = \int_{a_{n}}^{a_{n+1}} a \left[ \frac{\Lambda(a_{n+1}, y_{i}) - \Lambda(a_{n}, y_{i})}{a_{n+1} - a_{n}} \right] da$$

$$= \frac{\Lambda(a_{n+1}, y_{i}) - \Lambda(a_{n}, y_{i})}{a_{n+1} - a_{n}} \left[ \frac{a^{2}}{2} \right]_{a_{n}}^{a_{n+1}}$$

$$= \frac{\Lambda(a_{n+1}, y_{i}) - \Lambda(a_{n}, y_{i})}{2} (a_{n+1} + a_{n})$$

• Then:

$$A = \sum_{y_i \in \mathcal{Y}} \sum_{n=1}^{N-1} \frac{\Lambda(a_{n+1}, y_i) - \Lambda(a_n, y_i)}{2} (a_{n+1} + a_n) + \Lambda(\underline{a}, y_i) \underline{a}$$

where we account for the fact that there may be a mass point at the borrowing constraint.

### Discretization of the invariant density function

- A simpler approach involves finding an approximation to the invariant density function  $\lambda\left(a,y\right)$
- We will approximate the density by a probability distribution function defined over a discretized version of the state space.
   Once again the grid should be finer than the one used to compute the optimal savings rule.
- Choose initial density functions  $\lambda^0\left(a_k,y_i\right)$  . For example

$$\lambda^{0}\left(a_{k},y_{i}\right)=\left\{\begin{array}{ll}0&\text{if }k>1\text{ and }i>1\\1&\text{if }k=1\text{ and }i=1\end{array}\right.$$

i.e., all the mass is at the borrowing limit and at the lowest realization of the income shock

### Discretization of the invariant density function

• For every  $(a_k, y_j)$  on the grid:

$$\lambda^{1}\left(a_{k}, y_{j}\right) = \sum_{y_{i} \in \mathcal{Y}} \Gamma_{ij} \sum_{m \in \mathcal{M}_{i}} \frac{a_{k+1} - g\left(a_{m}, y_{i}\right)}{a_{k+1} - a_{k}} \lambda^{0}\left(a_{m}, y_{i}\right)$$

$$\lambda^{1}\left(a_{k+1}, y_{j}\right) = \sum_{y_{i} \in \mathcal{Y}} \Gamma_{ij} \sum_{m \in \mathcal{M}_{i}} \frac{g\left(a_{m}, y_{i}\right) - a_{k}}{a_{k+1} - a_{k}} \lambda^{0}\left(a_{m}, y_{i}\right)$$

where

$$\mathcal{M}_i = \{ m = 1, ..., N | a_k \le g(a_m, y_i) \le a_{k+1} \}$$

### Discretization of the invariant density function

 We can think of this way of handling the discrete approximation to the density function as forcing the agents in the economy to play a lottery.

- Lottery: with the probability of going to  $a_k$  given that your optimal policy is to save  $a' = g\left(a_m, y_i\right) \in [a_k, a_{k+1}]$  is given by  $\frac{a_{k+1} g(a_m, y_i)}{a_{k+1} a_k} \text{ and with probability } 1 \frac{a_{k+1} g(a_m, y_i)}{a_{k+1} a_k} \text{ you go to } a_{k+1}.$
- Then, once you have found  $\lambda$ , the aggregate supply of capital is computed as:

$$A = \sum_{y_i \in \mathcal{Y}} \sum_{a_k \in \mathcal{A}} a_k \lambda \left( a_k, y_j \right)$$

### Eigenvector method

• Let A be a square matrix. If there is a vector  $v \neq 0$  in  $\mathbb{R}^n$  such that:

$$vA = ev$$

for some scalar e, then e is called the eigenvalue of A with corresponding (left) eigenvector v.

• Recall that the definition of invariant pdf for a Markov transition matrix Q is  $\lambda^*$  that satisfies:

$$\lambda^* Q = \lambda^*$$

thus an invariant distribution is the eigenvector of the matrix Q associated to eigenvalue 1.

 How do we guarantee this eigenvector is unique and how do we find it in that case?

#### Eigenvector method

- Perron-Frobenius Theorem: Let Q be a transition matrix of an homogeneous ergodic Markov chain. Then Q has a unique dominant eigenvalue e=1 such that:
  - its associated eigenvector has all positive entries
  - ightharpoonup all other eigenvalues are smaller than e in absolute value
  - ightharpoonup Q has no other eigenvector with all non-negative entries
- This eigenvector (renormalized so that it sums to one) is the unique invariant distribution

### Eigenvector methods

- How do we construct Q?
- Let Q(a', y'; a, y) be the  $JN \times JN$  transition matrix from state (a, y) into (a', y'). Since the evolution of y' is independent of a:

$$Q(a', y'; a, y) = Q_a(a'; a, y) \otimes \Gamma(y', y)$$

where, if a' = g(a, y) is such that  $a_{k+1} \le a' < a_k$ , then we define:

$$Q_{a}(a_{k}; a, y) = \frac{a_{k+1} - g(a, y)}{a_{k+1} - a_{k}}$$

$$Q_{a}(a_{k+1}; a, y) = \frac{g(a, y) - a_{k}}{a_{k+1} - a_{k}}$$

... same lottery we used before for the density

### Eigenvector methods

- In practice: the Q function is very large and very sparse and there are many eigenvalues very close to one
- The corresponding eigenvectors generally have negative components that are inappropriate for the density function.
- Idea: perturb the zero entries of Q by adding a perturbation constant  $\eta$  and renormalizing the rows of Q.
- Then find the unique non-negative eigenvector associated with the unit root of the matrix. The stationary density can be obtained by normalizing this eigenvector to add to one.
- How do we select  $\eta$ ? Authors suggest

$$\eta \leq \frac{\min Q}{2N}$$
 or even smaller

#### Monte-Carlo simulation

- One must generate a large sample of households and track them over time.
- Monte Carlo simulation is memory and time consuming: not recommended for low dimensional problems.
- Valuable method however when the dimension of the problem is large since it is not subject to the curse of dimensionality that plagues all other methods.
- Choose a sample size I. Typically,  $I \ge 10,000$
- At t=0, initialize states by (i) draws from  $\Gamma^*$  and (ii) some value for  $a_i^0=a^*$ , for all agents, e.g., steady-state capital of the representative agent (divided by I)

#### Monte-Carlo simulation

 Update asset holdings each individual i in the sample by using the decision rule:

$$a_i^1 = g\left(a_i^0, y_i^1\right)$$

where  $y_i^1$  is drawn from  $\Gamma\left(y_i^1,y_i^0\right)$  .

• Use a random number generator for the uniform distribution in [0,1]. Suppose the draw from the uniform is u. Then  $y_i^1=y_{j^*}$  where  $j^*$  is the smallest index for gridpoints on  $\mathcal Y$  such that:

$$u \le \sum_{j=1}^{j^*} \Gamma\left(y_j, y_i^0\right)$$

• Because of randomness, the fraction of households with income values y will never be exactly equal to  $\Gamma^*(y)$ .

#### Monte-Carlo simulation

• Correction: you can make an adjustment where you (i) check for which values of y you have an excess relative to the stationary share  $\Gamma^*(y)$  and reassign the status of individuals with other realizations of y (for which you have less than the stationary share) appropriately.

- At every t compute the vector  $M^t$  of statistics of the wealth distribution (e.g., mean, variance, IQR, etc...).
- Stop if  $M^t$  and  $M^{t-1}$  are close enough.
- Then A is just the mean of wealth holding in the final sample.

### Speed vs stability of the algorithm

- Two tricks that make the algorithm a lot more stable, albeit slower
  - 1. Don't use gradient methods to solve for  $r^*$  in the outer loop. Use bisection. Given  $r^0$ , to obtain the new candidate  $r^1$  bisect between  $r^0$  and  $\left[F_K(A\left(r^0\right))-\delta\right]$

$$r^{1} = \frac{1}{2} \left\{ r^{0} + \left[ F_{K}(A(r^{0})) - \delta \right] \right\}$$

which are, by construction, on opposite sides of the steady-state interest rate  $r^*$ . Even better, use "dampening" in updating:

$$r^{1} = \omega r^{0} + (1 - \omega) \left[ F_{K}(A(r^{0})) - \delta \right]$$

with weight  $\omega = 0.8 - 0.9$  for example.

### Speed vs stability of the algorithm

2. When you resolve the household problem for a new value of the interest rate  $r^{n+1}$ , do not initialize the decision rule from the one corresponding to  $r^n$  obtained in the previous loop. Always start from the same guess to avoid propagation error in wealth distribution. Slower, but safer.