

Lecture III

Computational Basics and Numerical Differentiation

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Quantitative Macroeconomics

A number according to the computer

- Computers store **approximations** of real numbers
- Type of approximate representation is called a **format**
- Most common format is **double precision floating points**
 - ▶ **Precision**: number of bits computer number format occupies: single (32), double (64), quad (128)
 - ▶ **Floating point**: the position of “.” in the number varies
 - ▶ Binary format that occupies 64 bits (0/1) in computer memory: 1 bit for the sign of the number, 52 bits for the mantissa, and 11 bits to store the exponent (of which one is reserved to ∞)

											∞
1	2					53	54				64
sign	mantissa						exponent				

Binary floating point repres. (“IEEE 754” standard)

- A floating point number is computed as

$$(-1)^S \times \left(1 + \sum_{i=1}^N d_i \cdot 2^{-i} \right) \times 2^{(\sum_{i=1}^E d_i \cdot 2^i - 1023)}$$

► $S \in \{0, 1\}$ determines the **sign** (convention: 0 is +)

► $d_i \in \{0, 1\}$ is each digit of the **mantissa** and $N = 52$

► $E = 10$ is the **exponent**, with largest value

$$\sum_{i=1}^{10} 1 \cdot 2^i - 1023 = 1023 \text{ and lowest value } -1022 \text{ (} -1023 \text{ is 0)}$$

- **Machine infinity** (largest number can be represented): $2^{1023} \simeq 10^{308}$ and **machine zero** (smallest....): $2^{-1074} \simeq 10^{-324}$
- **Machine epsilon** (smallest number such that when added to 1 the computer can tell is no longer 1): $2^{-52} = 2.2 \times 10^{-16}$

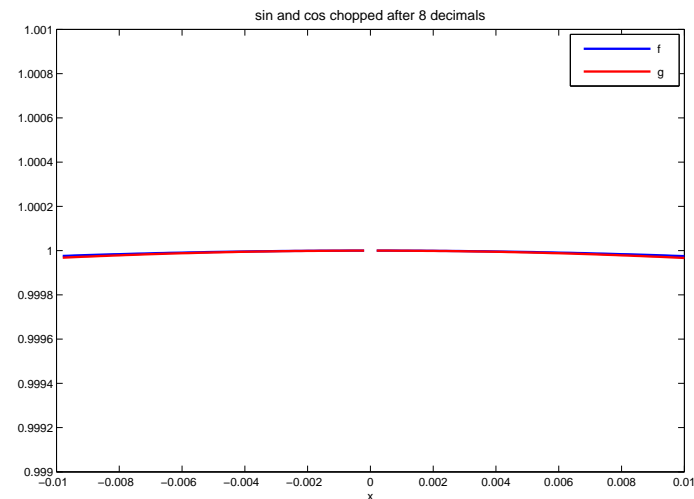
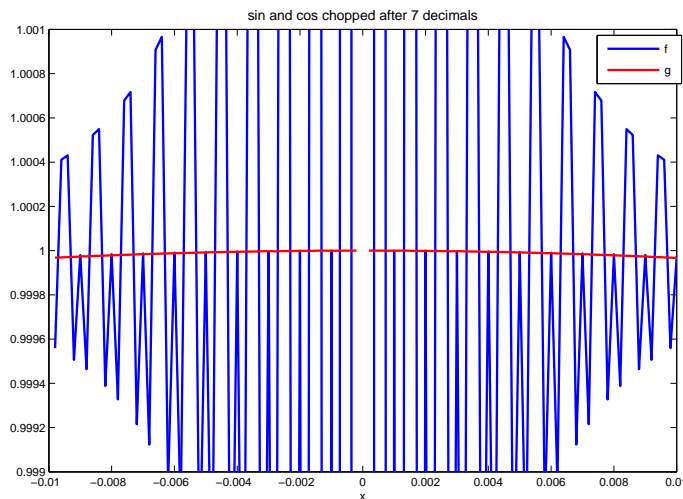
Three types of errors

1. **Rounding error**: depends on the degree of precision in which numbers are stored. A property of hardware and software.

$$10,000,000.2 - 10,000,000.1 = 0.099999996$$

- Two expressions for the same function:

$$f(x) = \frac{1 - \cos^2(x)}{x^2} \text{ and } g(x) = \frac{\sin^2(x)}{x^2}$$



Three types of errors

1. **Rounding error**: depends on the degree of precision in which numbers are stored. A property of hardware and software.
 - Avoid propagation!
 - Judd: (i) avoid subtractions of numbers of similar magnitude; (ii) when adding, add first small numbers and then add result to large numbers; (iii) avoid multiplying very large with very small numbers (both poorly approximated)
2. **Approximation error**: operations involving an infinite or long finite series which must be approximated by truncating the sequence

$$\log(x) = \sum_{i=1}^{\infty} \frac{1}{n} \left(\frac{x-1}{x} \right)^n \simeq \sum_{i=1}^N \frac{1}{n} \left(\frac{x-1}{x} \right)^n$$

3. **Human error**: the most common

Ill-conditioned problems

- When small changes in the input lead to large changes in the output: unstable algorithms!
- Example: I need to evaluate $f(x) = x/(1 - x)$ at x_0 but I have an approximate solution for x_0
 - ▶ Near 1, ill-conditioned problem: $f(0.95) = 18, f(0.96) = 24$
 - ▶ Near -1, well-cond.: $f(-0.95) = -0.487, f(-0.96) = -0.490$
- Relative error in f = conditioning number \times relative error in x_0
- Perturb input from x_0 to $x_0 + \varepsilon$. By mean-value theorem:

$$\frac{f(x_0 + \varepsilon) - f(x_0)}{f(x_0)} = \varepsilon \frac{f'(x^*)}{f(x_0)} \simeq \left[\frac{x_0 f'(x_0)}{f(x_0)} \right] \left(\frac{\varepsilon}{x_0} \right) = \frac{1}{1 - x_0} \left(\frac{\varepsilon}{x_0} \right)$$

Numerical Differentiation

- Definition of derivative:

$$f'(x_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

- Replace it with a **finite difference** (one-sided derivative):

$$f'(x_0) \simeq \frac{f(x_0 + h) - f(x_0)}{h}$$

- Another way to numerically approximate it (two-sided derivative):

$$f'(x_0) \simeq \frac{f(x_0 + h) - f(x_0 - h)}{2h}$$

1. Which one is better?
2. How small must h be?

Two-sided vs one-sided: which one is better?

- Approximate $f(x)$ around x_0 and evaluate it at $x_0 + h$

$$f(x_0 + h) = f(x_0) + f'(x_0)h + \frac{1}{2}f''(x_0)h^2 + \frac{1}{6}f'''(x_0)h^3 + O_4(h)$$

- One sided derivative:

$$\frac{f(x_0 + h) - f(x_0)}{h} = f'(x_0) + \frac{1}{2}f''(x_0)h + \frac{1}{6}f'''(x_0)h^2 + \frac{O_4(h)}{h}$$

- Two sided derivative

$$\frac{f(x_0 + h) - f(x_0 - h)}{2h} = f'(x_0) + \frac{1}{6}f'''(x_0)h^2 + \frac{O_4(x_0 + h) - O_4(x_0 - h)}{2h}$$

T-S derivative closer to $f'(x_0)$ as long as the fourth-order residual terms on both sides of x_0 are of similar magnitude.

Size of h (Miranda-Fackler)

- In practice, compute the derivative as:

$$f'(x_0) \simeq \frac{f(x_0 + h) - f(x_0 - h)}{(x_0 + h) - (x_0 - h)}$$

so you represent the arguments exactly in the same way in numerator and denominator

- According to MF, as **rule of thumb** for TSD, h should be set to:

$$h = \max(|x_0|, 1) \sqrt[3]{\varepsilon} \simeq \max(|x_0|, 1) \times 6 \times 10^{-6}$$

where ε is the machine epsilon

- h too large: **approximation error** in computing derivative
- h too small: **rounding error**

Approximation of a gradient

- Straightforward extension of what we saw already:
- **Bivariate case:**

$$\begin{aligned}\nabla f(x_1, x_2) |_{(x_1^0, x_2^0)} &= \left[f_1(x_1, x_2) |_{(x_1^0, x_2^0)}, f_2(x_1, x_2) |_{(x_1^0, x_2^0)} \right] \\ &\simeq \left[\frac{f(x_1^0 + h, x_2^0) - f(x_1^0 - h, x_2^0)}{(x_1^0 + h) - (x_1^0 - h)}, \frac{f(x_1^0, x_2^0 + h) - f(x_1^0, x_2^0 - h)}{(x_2^0 + h) - (x_2^0 - h)} \right]\end{aligned}$$

- To wrap up: write your own finite difference routine, experiment with h ... turns out MF's suggestion is pretty good in most contexts