

HW 3 - João Lazzaro

In this code, I compute a version of the HW 3 without the government. It is a simple Ayiagari with endogenous labor choice. First, Define some Parameters:

```
In [8]: using LinearAlgebra, Plots
include("functions.jl") #In the file functions, I defined the functions for VF
I and finding the distribution

#Defining Parameters:
β = 0.98 #Discount rate
μ = 1.5 #Elasticity of intertemporal substitution
η = 1 #Utility parameter
τy = 0.0 #Income tax
ρ = 0.6 #autocorrelation
σ = 0.3 #Variance
δ = 0.075 #Depreciation rate
θ = 0.3 #Capital Share
T=0 #tax rate, to be added
Z=1 #productivity level (not used)

b = -0 #Debt limit
amax=0.1 #capital limit

nE = 5 #Number of states for e
nA = 500 #states for assets
```

Out[8]: 500

Initial Guess for interest:

```
In [9]: r0= (1/β - 1)*rand() #initial guess for r liens in the interval (-δ, 1/β-1)
K = ((r0+δ)/(Z*θ))^(1/(θ-1)) #K for the nitial guess of r
w0= (1-θ)*K^θ #Initial wage given r0
```

Out[9]: 1.1822524385888202

Get the grid for E and assets. Note that in this code, I only use grids. No interpolation, therefore it is inefficient and slow, but I fully understand what is going on. I'll make it better once I understand the full algorithm.

```
In [10]: #Defining grids
pdfE,E = Tauchen(p,σ,nE) #E comes from Tauchen method
A = range(b,stop = amax, length = nA) #Assets
```

Out[10]: 0.0:0.0002004008016032064:0.1

Get the policy functions and distribution, see the file functions.jl where I defined the aiyagari function:

```
In [11]: @time λ,r,w, policy_a, policy_c, policy_l = aiyagari(A,E,r0,w0)

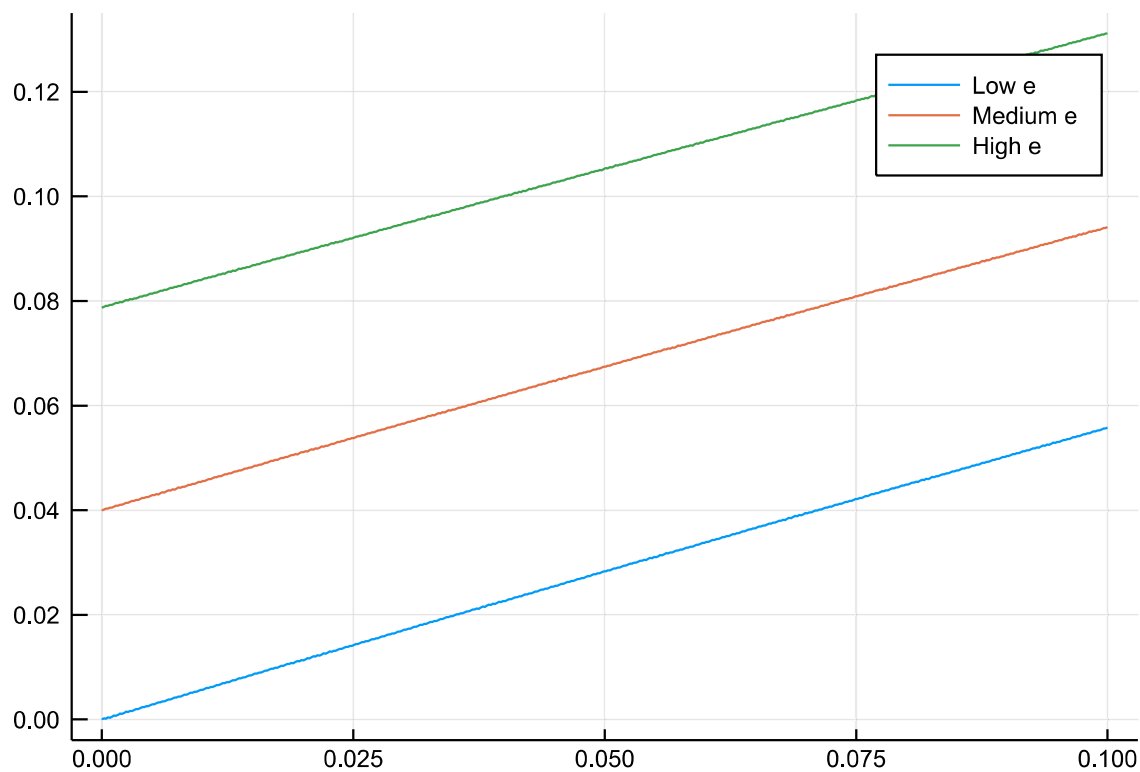
Iteration: 1 , r distance is: 0.03477533080014417
Iteration: 2 , r distance is: 0.017180917731642868
Iteration: 3 , r distance is: 0.008419506640375503
Iteration: 4 , r distance is: 0.004116731393197834
Iteration: 5 , r distance is: 0.0020061780931023634
Iteration: 6 , r distance is: 0.0009768144509964063
Iteration: 7 , r distance is: 0.0004739778374897516
Iteration: 8 , r distance is: 0.00023149238822364054
Iteration: 9 , r distance is: 0.0001116913951787965
Iteration: 10 , r distance is: 5.43965823850065e-5
Iteration: 11 , r distance is: 2.67634567219302e-5
Iteration: 12 , r distance is: 1.309181308896401e-5
Iteration: 13 , r distance is: 6.545906544482005e-6
Iteration: 14 , r distance is: 3.272953272244472e-6
Iteration: 15 , r distance is: 1.6364766361187666e-6
Iteration: 16 , r distance is: 6.732729937175552e-7
r converged to -0.0550857093428804
1453.662580 seconds (60.13 G allocations: 1.001 TiB, 4.56% gc time)

Out[11]: ([6.50672e-16 2.85692e-17 ... 0.0 0.0], -0.0550857093428804, 2.238361412098928
6, [1 1 ... 133 271; 1 1 ... 133 271; ... ; 195 194 ... 334 480; 196 194 ... 334 481],
[-1.99883e-9 -9.99414e-10 ... 0.0399438 0.0786852; 0.000189358 0.000189361 ... 0.
0401332 0.0788746; ... ; 0.0554243 0.0556247 ... 0.0939653 0.131103; 0.0554133 0.
0558141 ... 0.0941547 0.131092], [1.0 1.0 ... 3.32456e-16 3.02815e-16; 1.0 1.0 ...
3.32456e-16 2.87259e-16; ... ; 1.0 1.0 ... 4.1727e-16 3.32456e-16; 1.0 1.0 ... 3.32
456e-16 3.32456e-16])
```

The consumption policy function is plotted below:

```
In [22]: plot(A,[policy_c[:,2] policy_c[:,4] policy_c[:,5]], labels = ["Low e" "Medium e" "High e"])
```

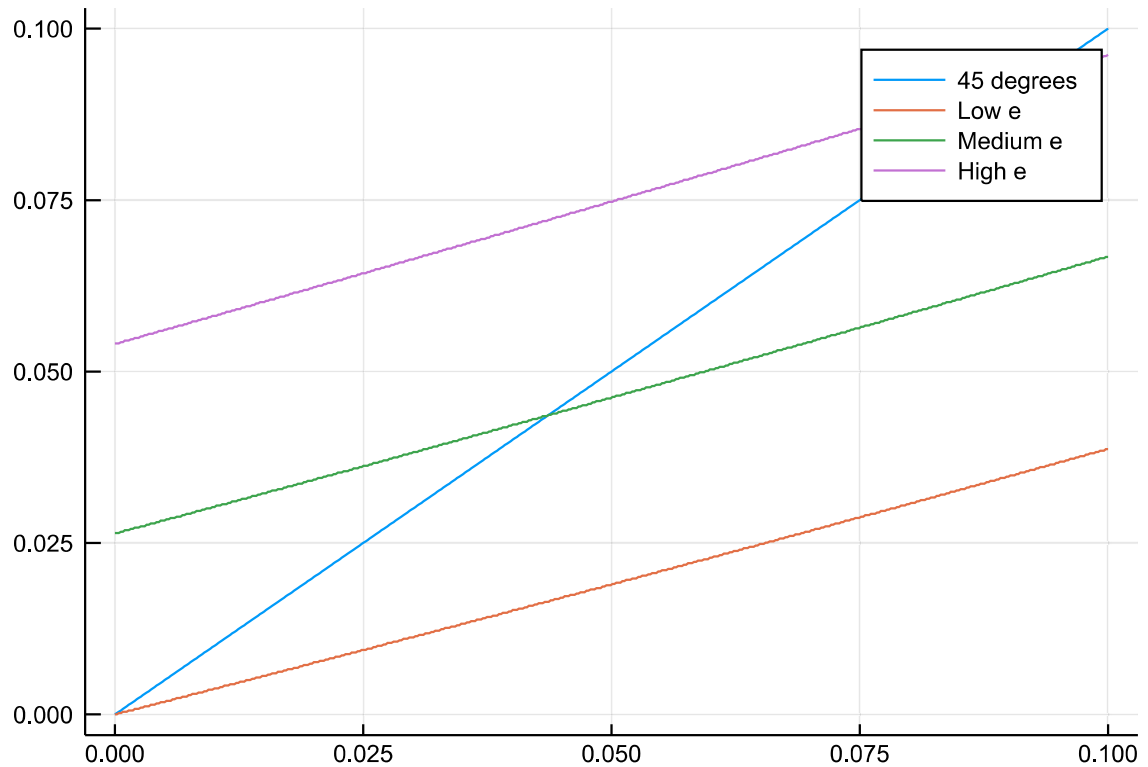
Out[22]:



The assets policy function is plotted below:

```
In [21]: plot(A,[A,A[policy_a[:,2]],A[policy_a[:,4]],A[policy_a[:,5]]], labels = ["45 d  
egrees" "Low e" "Medium e" "High e"])
```

Out[21]:



The assets distribution is below:

```
In [29]: #reshaping  $\lambda$  so it gets in a format easier to plot  
 $\lambda_1$  = ones(nA,nE)  
i=0  
for a=1:nA  
    global i  
    for e=1:nE  
        i+=1  
         $\lambda_1[a,e] = \lambda[i]$   
    end  
end  
  
plot(A, sum( $\lambda_1$ ,dims=2) , label = "\\lambda")
```

Out[29]:

