

# Russell H. Taylor

## PERSONAL DATA

**Current Positions** John C. Malone Professor of Computer Science  
with joint appointments in Radiology, Mechanical Engineering and Surgery  
Director, Laboratory for Computational Sensing and Robotics  
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## EDUCATION

**1970 The Johns Hopkins University B.E.S. (Interdepartmental)**

Interdepartmental major with concentration in Operations Research & Computer Science

**1976 Stanford University Ph.D. (Computer Science)**

Dissertation research, *The Synthesis of Manipulator Control Programs from Task-Level Specifications*, developed methods for automatic programming of sensor-based robot programs for mechanical assembly tasks.

## WORK HISTORY

2013-now	Johns Hopkins University	Director, Laboratory for Computational Sensing and Technology (LCSR)
1998-now	Johns Hopkins University	Director, Engineering Research Center for Computer-Integrated Surgical Systems and Technology (CISST ERC)
1995-now	Johns Hopkins University	John C. Malone Professor of Computer Science with joint appointments in Radiology, Mechanical Engineering, and Surgery
1990-95	IBM Research	Manager of Computer Assisted Surgery
1989-90	IBM Research	Research Staff Member
1987-89	IBM Research	Manager of Automation Technology
1982-87	IBM Research	Manager of Robot Systems and Technology
1982	IBM Research	Visiting Scientist at MIT AI Lab
1980-82	IBM Research	Research Staff Member
1978-79	IBM Boca Raton	Advisory Engineer
1976-77	IBM Research	Research Staff Member
1970-76	Stanford University	Research Assistant

Note: Fuller summaries of experience appear below.

## AWARDS and HONORS

1. The **Honda Prize** “for his tremendous contributions in the development of medical robots, technological evolution in this field, and producing highly skilled technical personnel” (2015)
2. **IEEE Engineering in Medicine and Biology Society Technical Field Award** “for contributions and leadership in the field of surgical robotics and computer-integrated interventional systems” (2015)
3. **Member of the National Academy of Inventors** (2015)
4. **John C. Malone Professorship** in the Johns Hopkins University Whiting School of Engineering in recognition of leadership and accomplishment in multidisciplinary research (2011).
5. **Medical Image Computing and Computer Assisted Surgery (MICCAI) Society Enduring Impact Award** (2010)
6. **Medical Image Computing and Computer Assisted Surgery (MICCAI) Society Fellow** (2009)
7. **Fellow of the Engineering School of the University of Tokyo** (2009)
8. **IEEE Robotics and Automation Society Pioneer Award** "for pioneering work in medical robotics and in the theory and practice of programmable automation systems" (2008)
9. **Maurice E. Mueller Award for Excellence in Computer Assisted Surgery** (2000)
10. **IEEE Third Millenium Medal** (2000)
11. **IEEE Fellow** (elected 1994) for technical contributions and leadership in the theory and implementation of programmable sensor-based robot systems and their application to surgery and manufacturing.
12. **AIBME Fellow** (elected 1998)
13. **IBM Outstanding Technical Achievement Award** (1993) and **IBM Group Achievement Award** (1991) for "Robodoc" system for Hip Replacement Surgery.
14. **IBM Outstanding Technical Achievement Award** (1984) and two **Outstanding Contribution Awards** (1982,1987) for development and transfer into productive use of AML language.
15. **IBM Invention Awards** (1983, 1991, 1992, 1994)

## PROFESSIONAL ACTIVITIES

### Editorial boards

1. *IEEE Trans. on Robotics and Automation* (1985-now, Editor in Chief: 1988-1994; Editor in Chief Emeritus 1995-now)
2. *International Journal of Robotics Research* (1986-2009)
3. *Computer Aided Surgery* (1995-2005)
4. *Medical Image Analysis* (1996-2009)
5. *IEEE Transactions on Medical Imaging* (2011-now)
6. *Biosystems & Biorobotics*, Springer Book Series (2012-now)

### Selected conference and workshop committees

1. *Medical Robotics and Computer Assisted Surgery* (**Program chair**, 1994; **general chair** 1995; Organizing committee 1997)
2. *Medical Image Computing & Computer-Assisted Interventions (MICCAI)* – **Organizing/Steering Committee** (1998-2002)
3. *NSF Workshop on Computer-Assisted Surgery* (co-organizer and program chair, Mar 1993)
4. *MediMech 92* (Program chair, Oct. 1992)
5. *IEEE Int. Conference on Robotics and Automation* (1987-1994; 2001-2004; ... )

6. *Int. Workshop on Deformable Modeling and Soft Tissue Simulation* (2001)
7. *Computer-Assisted Radiology & Surgery (CARS)* 2002
8. *Computer Assisted Surgery for the Head (CAS-H)*, Conference Advisory Board, Bern, Switzerland, 2004
9. **Conference Review Committee Member**, *IEEE International Conference on Robotic Systems (IROS)*
10. **Organizer**, *Winter School on Medical Robotics and Computer-Integrated Interventional Systems*, Johns Hopkins University, Jan 12-16, 2009.
11. **Program committee member**, *Medical Image Computing and Computer-Assisted interventions (MICCAI)*, London; PC Meeting 5/17-18, 2009; Conference 9/21-23/2009.
12. **Organizer**, *Tutorial on Medical Robotics*; MICCAI, London, 9/20/2009.
13. **Executive Committee Member**, *Information Processing in Computer-Assisted Intervention (IPCAI)*; 2010-now.
14. **Program chair**, *Information Processing in Computer-Assisted Intervention (IPCAI)*; Berlin, June, 2011.
15. **Program committee member**, *Medical Image Computing and Computer-Assisted interventions (MICCAI)*, Toronto, PC Meeting May 2011, Conference 9/19-23.
16. **Program committee member**, *Hamlyn Symposium on Medical Robotics*, London, June 2011.
17. **Program committee member**, *Information Processing in Computer-Assisted Intervention (IPCAI)*, Pisa, June, 2012.
18. **Program committee member**, *Hamlyn Symposium on Medical Robotics*, London, July 2012.
19. **Program committee member**, *Medical Image Computing and Computer-Assisted interventions (MICCAI)*, Nice, September 2012.
20. **Program committee member**, *Information Processing in Computer-Assisted Intervention (IPCAI)*, Heidelberg, Germany, June 2013.
21. **Program committee member**, *Hamlyn Symposium on Medical Robotics*, London, July 2013.
22. **Program committee member**, *Medical Image Computing and Computer-Assisted interventions (MICCAI)*, Nagoya, September, 2013.
23. **Program committee member**, *Hamlyn Symposium on Medical Robotics*, London, June 2014.
24. **Program Committee member**, *International Conference on Robotics and Automation*, Hong Kong, 2014.
25. **Program Committee member**, *Information Processing in Computer-Assisted Intervention (IPCAI)*, Fukuota, Japan, June 2014.
26. **Steering Committee member**, *Hamlyn Robotics Challenge*, London, 2015

## Selected other committees and advisory boards

1. Advisory Committee, NSF Div. of Information, Robotics and Intelligent Systems (1988-1991)
2. Administrative Committee, IEEE Robotics and Automation Society (1987-1994)
3. National Research Council; Japan Society for Promotion of Science Panel on Bilateral Exchange on Approaches to Robotics in the United States and Japan (1989)
4. Advisory Panel, NSF Robotics and Human Augmentation (2001-2003)
5. Advisory Board, Ontario Consortium for Image-Guided Therapy and Surgery (2001-2003)
6. Medical Image Computing and Computer-Aided Interventions Society, Founding Member of Society Board, 2003-2004
7. Computer-Assisted Orthopaedic Surgery, Standards Committee Member, 2004
8. **External Advisory Board**, Mechanical Engineering Department, Columbia University (2009-now)
9. **External Advisory Board**, Center for Image-Guided Innovation and Therapeutic Intervention at Toronto Children's Hospital (2012-now)
10. **External Advisory Board**, Institut de Chirurgie Mini-Invasive Guidée par L'Image, IHU Strasbourg (2012-now)
11. **External Advisory Board**, Computer Assisted Surgery Laboratory of Excellence in Grenoble (2012-now)
12. **President's Advisory Board**, Daegu Gyeongbuk Institute of Science and Technology, Daegu, Korea (2012-now)
13. **Standing Committee of External Evaluators for Robotics**, Italian Institute of Technology (2012-now)
14. **Ad hoc Strategic Advisory Board Member**, Boston Children's Hospital (2013)
15. (Numerous other committees and advisory boards over the past 20 years)

# PUBLICATIONS

## Books

1. Taylor, R.H., S. Lavallee, G. Burdea, and R. Mosges, eds. *Computer-Integrated Surgery*, 1996, MIT Press: Cambridge, Mass.

## Book Chapters & Sections

1. Lozano-Perez, T. and R. Taylor, "Geometric Issues in Planning Robot Tasks", in *Robotics Science*, M. Brady, Editor. 1989, MIT Press.
2. Cutting, C.B., F.L. Bookstein, and R.H. Taylor, "Applications of Simulation, Morphometrics and Robotics in Craniofacial Surgery", in *Computer-Integrated Surgery*, R.H. Taylor, et al., Editors. 1996, MIT Press: Cambridge, Mass. p. 641-662.
3. R. H. Taylor, "Safety". in *Computer-Integrated Surgery*, R. H. Taylor, S. Lavallee, G. Burdea, and R. Mosges, Eds. Cambridge, Mass.: MIT Press, 1996, pp. 283-286.
4. Taylor, R. H. (1999). "Medical Robotics". *Handbook of Industrial Robotics*, Second Edition. S. Y. Nof. New York, Wiley: 1213-1230.
5. Taylor, R. H., "Robotics in Orthopaedic Surgery", *Computer-Assisted Orthopaedic Surgery*, Nolte & Ganz, eds. Seattle, Hogrefe & Huber, pp 35-41.
6. Taylor, R. H. and L. Joskowicz, "Computer-Integrated Surgery and Medical Robotics", in *Standard Handbook of Biomedical Engineering and Design*, M. Kutz, Editor. 2002, McGraw Hill.
7. R. H. Taylor, "Robotic Systems for Orthopaedic Surgery," in *Computer and Robotic Assisted Knee and Hip Surgery*, A. DiGioia, B. Jaramaz, F. Picard, and L. P. Nolte, Eds., Oxford Press, 2004, pp. 67-78.
8. R. H. Taylor, "Medical Robotics," in *Computer and Robotic Assisted Knee and Hip Surgery*, A. DiGioia, B. Jaramaz, F. Picard, and L. P. Nolte, Eds., Oxford Press, 2004, pp. 54-59.
9. N. Simaan, R. Taylor, A. Hillel, and P. Flint, "Minimally Invasive Surgery of the Upper Airways: Addressing the Challenges of Dexterity Enhancement in Confined Spaces," in *Surgical Robotics – History, Present and Future Applications*, R. Faust, Ed.: Nova Science Publishing, 2007, pp. 223-242.
10. Li, M., A. Kapoor, R.H. Taylor. "Telerobot Control by Virtual Fixtures for Surgical Applications." Chapter in: *Advances in Telerobotics Human Interfaces, Bilateral Control and Applications*. Manuel Ferre, Martin Buss, Rafael Aracil, Claudio Melchiorri and Carlos Balaguer (Eds.) Springer Verlag, 2007, pp 381-401.
11. Taylor, R.H., P. Kazanzides. "Medical Robotics and Computer-Integrated Interventional Medicine." In *Biomedical Information Technology*. Academic Press, 2007, pp. 393-416.
12. R. Taylor, A. Menciassi, G. Fichtinger, and P. Dario, "Medical Robotics and Systems", *Handbook on Robotics: Springer*, 2008, pp. 1199-1222.
13. R. H. Taylor and P. Kazanzides, "Medical Robotics and Computer-Integrated Interventional Medicine," in *Advances in Computers*. vol. 73, M. Zelkowitz, Ed.: Elsevier, 2008, pp. 217-258.

## Published Refereed Reviews

1. Taylor, R.H., "Review of 'MH-1: a Computer Operated Mechanical Hand:', by H.A. Ernst", in *Robotics Reviews*, O. Khatib, Editor. 1989, MIT Press: Cambridge.
2. Taylor, R.H., "Review of 'Robots in Service', by J. Engleberger", in *Robotics Reviews II*, O. Khatib, Editor. 1991, MIT Press: Cambridge

## Refereed Journal Articles

1. Grossman, D.D. and R.H. Taylor, "The Interactive Generation of Object Models with a Manipulator." *IEEE Trans. on Systems, Man, and Cybernetics*, 1978, SMC-8 (9): p. 667-679.
2. Taylor, R.H., "The Planning and Execution of Straight Line Manipulator Trajectories." *IBM Journal of Research and Development*, 1979, 23(4): p. 424-436.

3. Taylor, R.H., P.D. Summers, and J.M. Meyer, "AML, A Manufacturing Language." *Int. Journal. of Robotics Research*, 1982, 1(3): p. 19-41.
4. Taylor, R.H. and D.D. Grossman, "An Integrated Robot Systems Architecture." *IEEE Proceedings*, 1983, 71(7): p. 842-857.
5. Lozano-Perez, T., M.T. Mason, and R.H. Taylor, "Automatic Synthesis of Fine-Motion Strategies for Robots" *Int. J. Robotics Res*, 1984, 3(1): p. 3-24.
6. Nackman, L.R. and R.H. Taylor, "An Hierarchical Exception Handler Binding Mechanism." *Software Practice and Experience*, 1984, 14(10): p. 999-1003.
7. Taylor, R.H., R.L. Hollis, and M.A. Lavin, "Precise Manipulation with Endpoint Sensing." *IBM Journal of Research and Development*, 1985, 29(5): p. 363-377.
8. Funda, J., R.H. Taylor, and R.P. Paul, "On Homogeneous Transforms, Quaternions, and Computational Efficiency." *IEEE Transactions on Robotics and Automation*, 1990, 6(3 (June)): p. 382-387.
9. Taylor, R.H., R.P. Paul, B.D. Mittelstadt, et al, "An Image-Based Robotic System for Hip Replacement Surgery," *J. Robotics Society of Japan*, 1990, 8(5): p. 111-116.
10. H. Paul, W. Bargar, B. Mittelstadt, B. Musits, R. Taylor, P. Kazanzides, and e. al., "Development of a Surgical Robot for Cementless Total Hip Arthroplasty", *Clinical Orthopaedics and Related Research*, vol. 285-, pp. 57-66, Dec 1992
11. Taylor, R.H., H.A. Paul, C.B. Cutting, B. Mittelstadt, W. Hanson, P. Kazanzides, B. Musits, Y.-Y. Kim, A. Kalvin, B. Haddad, D. Khoramabadi, and D. Larose, "Augmentation of Human Precision in Computer-Integrated Surgery." *Innovation et Technologie en Biologie et Medicine*, 1992, 13(4 (special issue on computer assisted surgery)): p. 450-468.
12. Taylor, R.H., H.A. Paul, P. Kazanzides, B.D. Mittelstadt, W. Hanson, J.F. Zuhars, B. Williamson, B.L. Musits, E. Glassman, and W.L. Bargar, "An Image-directed Robotic System for Precise Orthopaedic Surgery." *IEEE Transactions on Robotics and Automation*, 1994, 10(3): p. 261-275.
13. Taylor, R.H., J. Funda, B. Eldridge, K. Gruben, D. LaRose, S. Gomory, M. Talamini MD, L. Kavoussi MD, and J. Anderson, "A Telerobotic Assistant for Laparoscopic Surgery." *IEEE EMBS Magazine*, 1995, 14(3): p. 279-291.
14. J. Anderson, R. Taylor, S. Schreiner, M. Choti, E. Fishman, and G. Anderson, "Image-Guided Percutaneous Robotic Assisted Therapy", *Annals of Biomedical Engineering*, vol. 24- Supp 1, pp. S-71, October 1996
15. Eldridge, B., K. Gruben, D. LaRose, J. Funda, S. Gomory, J. Karidis, G. McVicker, R. Taylor, and J. Anderson, "A Remote Center of Motion Robotic Arm for Computer Assisted Surgery." *Robotica*, 1996, 14(1): p. 103-109.
16. Kalvin, A.D. and R.H. Taylor, "Superfaces: Polygonal Mesh Simplification with Bounded Error." *IEEE Computer Graphics and Applications*, 1996, 16(3): p. 64-77.
17. Joskowicz, L. and R.H. Taylor, "Interference-Free Insertion of a Solid Body into a Cavity: An Algorithm and a Medical Application." *Int Journal of Robotics Research*, 1996, 15(3): p. 211-229.
18. Taylor, R.H., J. Funda, L. Joskowicz, A. Kalvin, S. Gomory, A. Gueziec, and L. Brown, "An Overview of Computer-Integrated Surgery Research at the IBM T. J. Watson Research Center." *IBM Journal of Research and Development*, 1996, 40(2): p.163-183.
19. Funda, J., R. Taylor, B. Eldridge, S. Gomory, and K. Gruben, "Constrained Cartesian motion control for teleoperated surgical robots." *IEEE Transactions on Robotics and Automation*, 1996, 12(3), p. 453-466.
20. Cadeddu, J.A., A. Bzostek, S. Schreiner, A. Barnes, W.W. Roberts, J.H. Anderson, R.H. Taylor, and L.R. Kavoussi, "A Robotic System for Percutaneous Renal Access." *Urology*, 1997, 158(4): p. 1589-1593.
21. Gueziec, A., P. Kazanzides, B. Williamson, and R. Taylor, "Anatomy-Based Registration of CT-Scan and Intraoperative X-Ray Images for Guiding a Surgical Robot." *IEEE Transactions on Medical Imaging*, 1998, 17(5): p. 715-728. PMID: 9874295.
22. Taylor, R.H., L. Joskowicz, B. Williamson, et al., "Computer-Integrated Revision Total Hip Replacement Surgery: Concept and Preliminary Results." *Medical Image Analysis*, 1999, 3(3): p. 301-319.
23. Poulouse, B., M. Kutka, M.M. Sagaon, et al., "Human Versus Robotic Organ Retraction During Laparoscopic Nissen Fundoplication." *Surgical Endoscopy*, 1999, 13: p. 461-465.
24. Sadegh, P., F. Mourtada, R. Taylor, and J. Anderson, "Brachytherapy Optimal Planning with application to Intravascular Radiation Therapy." *Medical Image Analysis*, 1999, 3(3): p. 223-236.
25. Taylor, R., P. Jensen, L. Whitcomb, et al., "A Steady-Hand Robotic System for Microsurgical Augmentation". *International Journal of Robotics Research*, 1999. 18(12): p. 1201-1210 (Invited Paper).

26. Taylor, R.H., G. Fichtinger, P. Jensen, and C. Riviere, "Medical Robotics and Computer-Integrated Surgery: Information-driven Systems for 21st Century Operating Rooms." *Japanese Journal of Computer-Assisted Surgery*, 2000, 2(2): p. 47-53 (Invited Paper).
27. Yao, J., R.H. Taylor, R.P. Goldberg, et al., "A c-arm fluoroscopy-guided progressive cut refinement strategy using a surgical robot." *J. Computer Aided Surgery*, 2000, 5(6): p. 373-390. PMID: 11295851,
28. Liao, R., J. Williams, L. Myers, S. Li, R.H. Taylor, C. Davatzikos, "Optimization of Multiple Isocenter Treatment Planning for Linac-Based Stereotactic Radiosurgery." *Computer Aided Surgery*, 2000, 5(4): p. 220-233.
29. Joskowicz, L. and R. Taylor, "Computers in Imaging and Guided Surgery." *Computing in Science and Engineering*, 2001, 3(5): p. 65-72.
30. K. Masamune, G.F., A. Patriciu, R. Susil, R. Taylor, L. Kavoussi, J. Anderson, I. Sakuma, T. Dohi, D. Stoianovici, "Guidance System for Robotically Assisted Percutaneous Procedures with Computed Tomography". *Computer Aided Surgery*, 2001, 6(6): p. 370-383.
31. G. Fichtinger, T. L DeWeese, A. Patriciu, A. Tanacs, D. Mazilu, J. H. Anderson, K. Masamune, R H. Taylor, and D. Stoianovici, "System For Robotically Assisted Prostate Biopsy And Therapy With Intra-Operative CT Guidance." *Journal of Academic Radiology*, 2002, 9(1): p. 60-74. PMID: 11918360.
32. Solomon S, Patriciu A, Masamune K, Whitcomb L, Taylor RH, Kavoussi L, Stoianovici D, "CT Guided Robotic Needle Biopsy: A Precise Sampling Method Minimizing Radiation Exposure", *Radiology*. 225 (2002): 277-282.
33. D. L. Rothbaum, J. Roy, P. Berkelman, G. Hager, D. Stoianovici, R. H. Taylor, L. L. Whitcomb, M. Howard Francis, and J. K. Niparko, "Robot-assisted stapedotomy: micropick fenestration of the stapes footplate," *Otolaryngology - Head and Neck Surgery*, 2002,127(5): p. 417-426.
34. R. Taylor, D. Stoianovici. "Medical Robotic Systems in Computer-Integrated Surgery". *Problems in General Surgery*, 2003, 20(2): p. 1-9.
35. R. Taylor, D. Stoianovici, "Medical Robotics in Computer-Integrated Surgery." *IEEE Transactions on Robotics and Automation*, 2003, 19(5), p. 765-781.
36. P. J. Berkelman, L. Whitcomb, R. Taylor, and P. Jensen, "A miniature microsurgical instrument tip force sensor for enhanced force feedback during robot-assisted manipulation." *IEEE Trans. Robotics and Automation*, 2003, 19(5), p. 917-922.
37. D. Rothbaum, J. Roy, G. Hager, R. Taylor, and L. Whitcomb, "Task Performance in stapedotomy: Comparison between surgeons of different experience levels," *Otolaryngology - Head and Neck Surgery*, 2003, 128(1): p. 71-77.
38. Yao, J. and R. H. Taylor, "Non-Rigid Registration and Correspondence in Medical Image Analysis Using Multiple-Layer Flexible Mesh Template Matching." *International Journal of Pattern Recognition and Artificial Intelligence (IJPRAI)*, 2003, 17(7): p. 1145-1165.
39. M. Armand, J. Lepistö, A. Merkle, K. Tallroth, X. Liu, R. Taylor, and J. Wenz, "Computer-Aided Orthopaedic Surgery with Near Real-Time Biomechanical Feedback," *APL Technical Digest*, vol. 25, pp. 242-252, 2004.
40. Cleary, K., V. Watson, D. Lindisch, D. Stoianovici, A. Patriciu, D. Mazilu, R. H. Taylor, G. Fichtinger, S. Xu, C. S. White, J. Donlon, and M. Taylor, "Precision placement of instruments for minimally invasive procedures using a "needle driver" robot." *International Journal of Medical Robotics and Computer Assisted Surgery*, 2005, 1(2): p. 1-9.
41. G. Fichtinger, A. Degeut, M. K., G. S. Fischer, E. Balogh, H. Matthieu, R. H. Taylor, S. J. Zinreich, and L. M. Fayad, "Image Overlay Guidance for Needle Insertions in CT Scanner." *IEEE Transactions on Biomedical Engineering*, 2005, 52 (8): p. 1415-1424.
42. Burschka, D., M. Li, R. Taylor, G.D. Hager, and M. Ishii, "Scale-invariant registration of monocular endoscopic images to CT-scans for Sinus." *Medical Image Analysis*, 2005, 9(1): p. 413-426. PMID: 16009593.
43. G. S. Fischer, A. Degeut, D. Schlattman, R. H. Taylor , L. Fayad, S. J. Zinreich, and G. Fichtinger, "MRI Image Overlay: Applications to Arthrography needle insertion." *Stud. Health. Technol. Inform.*, 2005, 119: p. 150-155.
44. Herman, B. C., E. Hanly, N. Schenkman, R. Taylor, M. Talamini, and M. Marohn, "Telerobotic Surgery Creates Opportunity for Augmented Reality Surgery." *Telemedicine Journal and e-Health*, 2005, 11(2): p. 203.

45. Fichtinger, G., A. Deguet, G. Fischer, I. Iordachita, E. Balogh, K. Masamune, R.H. Taylor, L.M. Fayad, M. De Oliveria, and S.J. Zinreich, "CT Image Overlay for Percutaneous Needle Insertions." *Journal of Computer Aided Surgery*, 2005, 10, p. 241-255.
46. Sadowsky, O., J. Cohen, and R.H. Taylor, "Projected Tetrahedra Revisited: A Barycentric Formulation Applied to Digital Radiograph Reconstruction Using Higher-Order Attenuation Functions." *IEEE Transactions On Visualization and Computer Graphics*, 2006: p. 231-236.
47. Xu, S., K. Cleary, et al., "Lung Deformation Estimation and Four-Dimensional CT Lung Reconstruction." *Academic Radiology*, 2006, 13(9): p. 1082-1092.
48. Taylor, R.H., "A Perspective on Medical Robotics." *IEEE Proceedings*, 2006, 94: p. 1652-1664. **(invited paper)**
49. Li, M., M. Ishii, and R.H. Taylor, "Spatial Motion Constraints in Medical Robot Using Virtual Fixtures Generated by Anatomy." *IEEE Transactions on Robotics* 2007, (23)1, pp4-19.
50. Armiger, R., Armand, M., Lepisto, J., Minhas, D., Tallroth, K., Mears, S., Waites, M., Taylor, R.H., "Evaluation of a Computerized Measurement Technique for Joint Alignment Before and During Periacetabular Osteotomy." *Computer Aided Surgery*, 2007, 12(4): p. 215-224.
51. Dimairo, S., T. Kapur, K. Cleary, S. Aylward, P. Kazanzides, K. Vosburgh, R. Ellis, J. Duncan, K. Farahani, H. Lemke, T. Peters, W.B. Lorensen, D. Gobbi, J. Haller, L.L. Clarke, S. Pizer, R. Taylor, R. Galloway Jr., G. Fichtinger, N. Hata, K. Lawson, C. Tempany, R. Kikinis, F. Jolesz, "Challenges in image-guided therapy system design." *Neuroimage*, 2007, 37 Suppl 1: p. S144-51.
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53. P. Kazanzides, G. Fichtinger, G. D. Hager, A. M. Okamura, L. L. Whitcomb, and R. H. Taylor, "Surgical and Interventional Robotics - Core Concepts, Technology, and Design [Tutorial]," *Robotics & Automation Magazine, IEEE*, vol. 15, pp. 122-130, 2008.
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56. L.-M. Su, B. P. Vagvolgyi, R. Agarwal, C. E. Reiley, R. H. Taylor, and G. D. Hager, "Augmented Reality During Robot-assisted Laparoscopic Partial Nephrectomy: Toward Real-Time 3D-CT to Stereoscopic Video Registration", *Urology*, vol. 73- 4, pp. 896-900, Apr 2009 . PMID: 1919340.
57. N. Simaan, K. Xu, A. Kapoor, W. Wei, P. Kazanzides, P. Flint, and R. Taylor, "A System for Minimally Invasive Surgery in the Throat and Upper Airways", *Int. J. Robotics Research* (special issue on medical robotics), vol. 28- 9, pp. 1134-1153, June 2009.<http://ijr.sagepub.com/cgi/content/abstract/28/9/1134> 10.1177/0278364908104278; NIH MSID 114080.
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59. L. M. Ellingsen, G. Chintalapani, R. H. Taylor, and J. L. Prince, "Robust deformable image registration using prior shape information for atlas to patient registration", *Computer Medical Imaging and Graphics*, vol. 34, pp. 79-90, 2009. <http://dx.doi.org/10.1016/j.compmedimag.2009.05.003>. PMID: 18051096
60. B. Wu, F. Ricchetti, G. Sanguineti, M. Kazhdan, P. Simari, M. Chuang, R. Taylor, R. Jacques, and T. McNutt, "Patient geometry-driven information retrieval for IMRT treatment plan quality control" *Med. Phys.*, vol. 36- 12, pp. 5497-5505, December 2009.
61. X. Liu, M. Balicki, R. H. Taylor, and J. U. Kang, "Towards Automatic Online Calibration of Fourier-Domain OCT for Robot-Assisted Vitreoretinal Surgery", *Optics Express*, vol. 18- 23, pp. 24331-24343, Nov. 8 2010. PMC3003938.
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## Invited Technical Magazine Articles and Similar Publications

1. N. Simaan, R. H. Taylor, and H. Choset, "Intelligent Surgical Robots with Situational Awareness: From Good to Great Surgeons", *ASME Dynamic Systems Magazine*, vol 3, no 3, September, 2015.
2. P. Kazanzides, A. Deguet, B. Vagvolgyi, Z. Chen, and R. H. Taylor, "Modular Interoperability in Surgical Robotics Software", *Mechanical Engineering*, vol. 137- 9, pp. S19-22, September, 2015; (Web <http://search.proquest.com/docview/1709807575?pq-origsite=gscholar>).

## Refereed Conference Papers

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27. R. Jacques, R. Taylor, J. Wong, and T. McNutt, "SU-E-T-719: Multi-Energetic, GPU-Accelerated Superposition/Convolution (abstract from AAPM 2011)", *Medical Physics*, vol. 38- 6, Published Abstract, p. 3656, 2011.
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29. X. Kang, W. P. Yau, Y. Otake, and R. H. Taylor, "A novel method in assessing tunnel positions in ACL Reconstruction", *Extended Abstract in Int. Conf. on Computer-Assisted Orthopaedic Surgery (CAOS)*, London, June 15-17, 2011.
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31. S. F. Petit, B. Wu, M. Kazhdan, A. Dekker, P. Simari, R. Kumar, R. H. Taylor, J. M. Herman, and T. McNutt, "The potential of shape-based treatment plan optimization for pancreatic IMRT treatments to spare organs at risk and allow for dose escalation to the tumor PTV.", *J. Clin. Oncol.*, vol. Suppl 4- , republished abstract from ASCO 2011, p. abstr 316, 2011.
32. K. Ramamurthi, O. Ahmad, K. Engelke, R. H. Taylor, K. Zhu, S. Gustafsson, R. L. Prince, and K. E. Wilson, "QCT and DXA hip size and strength measurements are highly correlated (Abstract)", *Abstract and Poster in International Osteoporosis Federation 2nd Asia-Pacific Osteoporosis and Bone Meeting* Queensland, Sep. 6, 2011.
33. B. Wu, T. McNutt, M. Zaburak, M. Kazhdan, P. Simari, D. Pang, R. Taylor, and G. Sanguinetti, "Fully automated IMRT treatment planning is feasible for head-and-neck (H&N) cancer: a prospective study using

- an overlap volume histogram (OVH)-guided strategy ", Abstract in proceedings and poster in ASTRO Annual Meeting, Miami, Oct 2-6, 2011. pp. S198, Poster 1087.
34. B. Wu, T. McNutt, M. Zahurak, M. Kazhdan, P. Simari, D. Pang, R. Taylor, and G. Sanguinetti, "On the Feasibility of using Overlap Volume Histogram and DVH Data of Prior IMRT Plans to Guide Smart Arc-based Volumetric Modulated Arc Therapy Treatment Planning (Abstract)", Abstract in Proceedings and Poster in ASTRO Annual Meeting, Miami, Oct 2-6, 2011. p. S827
  35. R. H. Taylor, "Medical Robotics and Computer-Integrated Interventional Medicine (Abstract)", in Proc. SPIE Medical Imaging, San Diego, Feb 5-7, 2012. pp. 8316-12.
  36. J. K. Niparko, W. W. Chien, I. Iordachita, J. U. Kang, and R. H. Taylor, "Robot-assisted, sensor-guided cochlear implant electrode insertion (Abstract in Proceedings)", in *12th International Conference on Cochlear Implants and Other Implantable Auditory Technologies*, Baltimore, MD, May 3-5, 2012.
  37. W. W. Chien, J. K. Niparko, I. Iordachita, R. H. Taylor, and J. U. Kang, "Optical coherence tomography (OCT) sensor guided cochlear implant electrode insertion (Abstract in Proceedings)", in *12th International Conference on Cochlear Implants and Other Implantable Auditory Technologies*, Baltimore, MD, May 3-5, 2012.
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  41. W. P. Liu, R. H. Taylor, S. Reaugamornrat, J. M. Sorger, J. H. Siewerdsen, and J. Richmon, "Intraoperative Image-Guided Robotic Surgery: Pre-Clinical Studies" (Abstract in Proceedings), in *20th International Federation of Oto-Rhino-Laryngological Societies (IFOS 2013)*, June 1-5, 2013.
  42. G.-W. Cheon, H.-W. Jeong, P. Chalasani, W. W. Chien, I. Iordachita, R. Taylor, J. Niparko, and J. U. Kang, "3D optical coherence tomography image registration for guiding cochlear implant insertion (abstract in proceedings)", in *SPIE 8926, Photonic Therapeutics and Diagnostics X*, San Francisco, Feb 1, 2014. p. 89261Z. 10.1117/12.2040594.
  43. A. L. Feng, K. Olds, M. Balicki, Z. Ashai, P. Lakshminarayanan, R. H. Taylor, and J. D. Richmon, "The Steady Hand Robot: Improving Microvascular Surgery", in *AAO-HNSF Annual Meeting*, Dallas, Texas, Sept 27-30, 2015.

## Significant Reports

1. Taylor, R. H., *The Synthesis of Manipulator Control Programs from Task-Level Specifications*, Ph.D. Dissertation, Stanford University, 1976. Report STAN-CS-76-560.
2. Taylor, R.H., G.B. Bekey, and J. Funda, "Proc.of NSF Workshop on Computer Assisted Surgery", 1993: Washington D.C.
3. Taylor, R.H. and S.D. Stulberg. "Medical Robotics Working Group Section Report" in *NSF Workshop on Medical Robotics and Computer-Assisted Medical Interventions (RCAMI)*. 1996. Bristol, England: Shadyside Hospital, Pittsburgh, Pa.
4. Curley, K., T Broderick, R. Marchessault, G. Moses, R. Taylor, W. Grundfest, E. Hanley, B. Miller, A. Gallagher, and M. Marohn, "Integrated Research Team Final Report: Surgical Robotics – The Next Steps September 9-10 2004," Telemedicine & Advanced Technology Research Center (TATRC); U.S. Army Medical Research and Material Command, Fort Detrick, MD, TATRC Report 04-03, January 2005.

## PATENTS

1. US Patent 4,485,453, Taylor R.H., "Device and method for determining the location and orientation of a drill hole," Filed March 29, 1982, Issued Nov 27, 1985.
2. US Patent 4,544,889, Taylor R.H., F. Hendricks, "Robot Precision Probe Positioner with Guidance Optics," Filed September 12, 1983, Issued October 1, 1985.
3. US Patent 5,086,401, Glassman, E., W. Hanson, P. Kazanzides, B. Mittelstadt, B. Musits, H. Paul, R. Taylor "Image-Directed Robotic System for Robotic Surgery Including Redundant Consistency Checking", Filed May 1990, Issued Feb 4, 1992. US, Japan.
4. US Patent 5,279,309, Taylor, R.H., Y.Y. Kim, "Signaling Device and Method for Monitoring Positions in a Surgical Operation," Filed July, 1992, Issued January 18, 1994.
5. US Patent 5,299,288, Glassman, E., W. Hanson, P. Kazanzides, B. Mittelstadt, B. Musits, H. Paul, R.H. Taylor, "Image-directed robotic system for precise robotic surgery including redundant consistency checking," Filed September 18, 1991, Issued March 29, 1994.
6. U. S. Patent 5,343,385, Joskowicz, L., R. Taylor, "Interference-Free Insertion of a Solid Body into A Cavity", Filed August 17, 1993, Issued August 30, 1994.
7. US Patent 5,397,323, Taylor R., J. Funda, D. Grossman, J. Karidis, D. LaRose, "Remote center-of-motion robot for surgery," Filed October 30, 1992, Issued March 14, 1995.
8. US Patent 5,402,801, Taylor, R., "System and method for augmentation of surgery," Filed April 28, 1994, Issued April 4, 1995.
9. US Patent 5,408,409, Glassman E., W. Hanson, P. Kazanzides, B. Musits, H. Paul, R. Taylor, "Image-directed robotic system for precise robotic surgery including redundant consistency checking," Filed December 20, 1993, Issued April 18, 1995 (US only).
10. US Patent 5,417,210, Funda, J., D. LaRose, R. Taylor, "System and Method for Augmentation of Endoscopic Surgery," Filed May 27, 1992, Issued May 23 1995; US.
11. US Patent 5,445,166, Taylor, R., "System for advising a surgeon," Filed April 6, 1994, Issued August 29, 1995; (US only).
12. US Patent 5,572,999, Funda, J., D. LaRose, R. Taylor, "Robotic System for Positioning a Surgical Instrument Relative to a Patient's Body," Filed January 26, 1995, Issued Nov 12, 1996
13. US Patent 5,630,431, R. Taylor, "System and Method for Augmentation of Surgery," Filed October 11, 1994, Issued May 20, 1997.
14. US Patent 5,695,500, Kim, Y., R. Taylor, "System for manipulating movement of surgical instrument with computer controlled brake," Filed April 6, 1994, Issued December 9, 1997.
15. US Patent 5,749,362 to Funda, J., D. LaRose, R.H. Taylor, "Method of creating an image of an anatomical feature where the feature is within a patient's body," Filed 1/26/95, Issued 5/12/98.
16. US Patent 5,887,121, Funda, J., R. Taylor, "Method of Constrained Cartesian Control of Robotic Mechanism" Filed July 17, 1997, Issued March 23, 1999.
17. US Patent 5,950,629 to Taylor et al., "System and Method of Augmentation of Surgery," Filed April 28, 1994, Issued Sept 14, 1999 (US Only).
18. US Patent 5,976,156, Taylor, R.H., Y.Y. Kim, "Stereotaxic Apparatus and Method for Moving an End Effector", Filed November 2, 1993, Issued April 27, 1999 (US Only).
19. US Patent 5,951,475, Gueziec, A., P. Kazanzides; R. Taylor, "Methods and apparatus for registering CT-scan data to multiple fluoroscopic images," Filed September 25, 1997, Issued Sept 14, 1999.
20. US Patent 6,024,695, Taylor, R., Y. Kim, "System and Method for Augmentation of Surgery", Filed May 6, 1999, Issued February 15, 2000.
21. US Patent 6,201,984, Funda, J., D. LaRose, R. Taylor; "System and Method for Augmentation of Endoscopic Surgery," Filed Jan 26, 1995, Issued March 13, 2001.
22. US Patent 6,226,566, Funda, J., R. Taylor, "Method of Constrained Cartesian Control of Robotic Mechanisms with Active and Passive Joints." Filed Feb 18, 1999, Issued May 1, 2001.
23. US Patent 6,231,526, Taylor, R. and Y. Kim, "System and Method for Augmentation of Surgery," Filed December 8, 1999, Issued May 15, 2001.
24. US Patent 6,393,340, Funda, J., R.H. Taylor, "Robotic Mechanisms with Active and Passive Joints," Filed December 28, 2000, Issued May 21, 2002.
25. US Patent 6,400,979 B1, Stoianovici, D., L. Kavoussi, L. Whitcomb, R. Taylor, J. Cadeddu, R. Demaree, S. Basile, "Friction transmission with axial loading and a radiolucent surgical needle driver", Filed February 20, 1998, Issued June 4, 2002.
26. US Patent 6,547,782, Taylor, R.H., "System and Method for Augmentation of Surgery," Filed August 11, 2000, Issued April 15, 2003.

27. US Patent 7,021,173, Stoianovici, D., L. Whitcomb, D. Mazilu, R.H. Taylor, L. Kavoussi, "Remote Center of Motion Robotic System and Method." Filed February 6, 2003, Issued April 4, 2006. US.
28. US Patent 7,225,012, Susil, R, R. Taylor, "Methods and Systems for Image-Guided Surgical Interventions." Filed September 18, 2000, Issued May 29, 2007.
29. US Patent 7,494,494 B2, D. Stoianovici, G. Fichtinger, I. Iordachita, L. Whitcomb, and R. H. Taylor, "Controllable Motorized Device for Percutaneous Needle Placement in Soft Tissue Target and Methods and Systems Related Thereto", Filed Aug. 30, 2001, Issued Feb. 24, 2009.
30. US Patent 7,901,357 B2, E. M. Boctor, M. Choti, G. Fichtinger, R. Taylor, and J. L. Prince, "Robotic 5-Dimensional Ultrasound", Filed July 21, 2004, Issued March 8, 2011.
31. US Patent 8,152,756 B2, R. J. Webster, A. M. Okamura, N. J. Cowan, and R. H. Taylor, "Active Cannulas for Bio-sensing and Surgical Intervention", Filed Nov 15, 2006, Issue date Apr 10, 2012.
32. US Patent 8,365,633, N. Simaan, R. H. Taylor, P. Flint, C. Chirikjian, and D. Stein, "Devices, Systems, and Methods form Minimally Invasive Surgery of the Throat and other Portions of the Mammalian Body", Utility, Filed May 21, 2004, Issue date Feb. 5, 2013.
33. US Patent 8,39,541 B2, S. Dimaio, C. J. Hasser, R. H. Taylor, D. Q. Larkin, P. Kazanzides, A. Deguet, and B. P. Vagvolgyi, "Interactive User Interfaces for Robotic Minimally Invasive Surgical Systems", Filed April 11, 2008, Issue date March 19, 2013.
34. US Patent 8,688,618 B2, T. R. McNutt, M. M. Kazhdan, and R. H. Taylor, "Shape Based Retrieval of Prior Patients for Automation and Quality Control of Radiation Therapy Treatment Plans", Filed 23-Jun-2009, Issue date April 1, 2014.
35. US Patent 8,715,226 B2, R. J. Webster, A. M. Okamura, N. J. Cowan, and R. H. Taylor, "Active Cannulas for Bio-sensing and Surgical Intervention", Filed Mar 9, 2012, Issue date May 6, 2014.
36. US Patent 8,886,330 B2, R. H. Taylor, W. W.-D. Chien, J. Niparko, and I. Iordachita, "Method and Apparatus for Cochlear Implant Surgery", Filed September 21, 2011, Issue date Nov 11, 2014.
37. US Patent 8,911,429 B2, K. C. Olds and R. H. Taylor, "Steady Hand Micromanipulation Robot", Filed Nov 5, 2012, Issue date December 16, 2014.
38. Several other utility patents are currently in prosecution. Numerous preliminary patents are not included in this list.

## SELECTED PRESENTATIONS (starting in 2001)

### Conferences and Workshops (excluding paper presentations)

1. "Dependable Medical/Surgical Robots", **invited talk** to the *1- IARP/IEEE-RAS Joint Workshop on Technical Challenge for Dependable Robots in Human Environment*, Seoul Korea, May 22, 2001
2. "Computer-Integrated Surgery: Coupling Information to Action in 21st Century Medicine", **plenary address** to the *IEEE International Conference on Robotics and Automation*, Seoul Korea, May 23, 2001. . Text accompanying the speech is at [http://www.icra2001.org/plenary\\_speech\\_1.pdf](http://www.icra2001.org/plenary_speech_1.pdf).
3. "Computer-Integrated Surgery: Coupling Information to Action in 21st Century Medicine", **invited address** to the *Annual Meeting of the Society of Urological Engineers*, Anaheim, Ca. June 2, 2001
4. "Medical Robotics and Computer Integrated Surgery", **invited faculty lecture** to the Advanced Science Institute 2001: "New Frontiers of Intelligent Robotics" course, Tokyo, Japan, July 23-30, 2001.
5. "The role of Medical Robotics in Computer-Integrated Surgery", **invited talk** to the German Workshop on Computer/Robot-assisted Surgery, July 19, 2001.
6. "Medical Robotics and Computer-Integrated Therapy Delivery: Coupling Information to Action in 21'st Century Surgery", **invited talk** to the *Ontario Consortium on Image-Guided Therapy and Surgery Annual Symposium*, October 18, 2001.
7. "What does the future hold for medical robotics?", **invited talk**, *Robot Industries Association Annual Meeting*, Orlando, November 8, 2001.
8. "Medical Robotics and Computer-Integrated Therapy Delivery: Coupling Information to Action in 21'st Century Surgery", **invited talk** to the *Special Symposium of the Japan Society for Promotion of Science*, December 6, 2001.
9. "Computer-Integrated Surgery: Where we are now and wither are we tending", **invited talk**, *CIMIT Symposium*, Boston, MA, February 12, 2002.
10. "Steady Hand Microsurgery/Deformable 2D-3D Registration", **invited talks** given back to back to the *Ontario Consortium for Image-Guided Therapy and Surgery*, Ontario, Canada, December 13, 2002.
11. "Steady Hand Microsurgery", **invited plenary talk** to the *NSF Annual Meeting of Engineering Research Centers*, November 3, 2002.
12. "Computer-Integrated Surgery: Coupling Information to Action in 21st Century Operating Rooms", **invited talk** at the *European Summer Institute on Medical Robotics*, Montpellier, France, September, 2003.
13. "Medical Robotics and Computer Integrated Surgery", **invited talk** to the *CSTAR/OCITS Joint Workshop*, Ontario, Canada, October 18, 2004.
14. "Advances in Robotics, CT, and Ultrasound Guided Surgery", **invited talk** to the *Orthopaedic Research Society Meeting*, Banff, Alberta, Canada, October 12, 2004.
15. "Future Research and Development: Robotic Surgical Systems Integration", **invited talk**, *Integrated Research Team on Surgical Robotics*, Marina del Rey, CA, September 9, 2004. DoD/ TATRC.
16. "Biomedical Robotics and Biomechanics: Scientific and Technical Foundations of a New Interdisciplinary Field for Research, Medical Application, and Industry", **invited talk**, *IEEE International Conference on Robotics and Automation workshop*, New Orleans, April 27, 2004.
17. "Robotics State-of-the-Art and Future Scenarios", **invited talk**, *OR of the Future*, Turf Valley, MD, March 18, 2004.
18. "Computer-Integrated Surgery: Coupling Information to Action in the 21st Century", **invited talk**, *International Symposium on Mechanical Systems Innovation*, Tokyo, Japan, March 7, 2004.
19. "Medical Robotics and Computer Integrated Surgery", **invited talk**, University of Maryland Medical Center, Department of Surgery Grand Rounds, Baltimore, MD, January 5, 2005.
20. "Computer-Integrated Surgical Systems", **invited talk**, NSF workshop *From Macro to Micro: Challenges and Opportunities in Integrative Complex Systems Engineering*, Washington, D.C., March 7, 2005.
21. "Computer-Integrated Surgery", **invited talk**, *ICRA*, Barcelona, Spain, April 19, 2005.
22. "Computer-Integrated Surgery: Coupling Information to Action in the 21st Century", **invited talk**, *Operating Rooms of the Future*, Washington, D.C., April 22, 2005.



23. "Computer-Integrated Surgery: Coupling Information to Action in the 21<sup>st</sup> Century", **invited plenary talk**, *44<sup>th</sup> Annual Conference of Japanese Society for Medical and Biological Society*, Tsukuba City, Japan, April 26, 2005.
24. "Computer-Integrated Surgery: Coupling Information to Action in the 21<sup>st</sup> Century", **invited plenary talk**, *First Asian Symposium on Computer Aided Surgery*, Tsukuba City, April 28, 2005.
25. "Computer-Integrated Surgery: Coupling Information to Action in the 21<sup>st</sup> Century", **speaker/organizer**, *I4M workshop*, School of Medicine, Baltimore, MD, February 27, 2006.
26. "Medical Robotics and Computer-Integrated Surgery", **keynote speaker**, *3rd COE workshop*, Tokyo, Japan, March 3-4, 2006.
27. **seminar speaker**, *Radiation Oncology*, Baltimore, MD, April 10, 2006.
28. "Medical Robotics and Computer-Integrated Surgery", **invited speaker**, *World Congress 2006*, Seoul, South Korea, August 27 – September 1, 2006.
29. "Medical Robotics and Computer-Integrated Surgery", **seminar speaker**, NIH, June 9, 2006.
30. "Medical Robotics and Computer-Integrated Surgery", **keynote speaker**, *Human Centered Robotic Systems*, Munich, Germany, October 6, 2006.
31. "Image Guidance for Surgical Robotics", **invited speaker**, *American College of Surgeons 92<sup>nd</sup> Annual Clinical Congress*, Chicago, IL, October 9, 2006.
32. "Medical Robotics and Computer-Integrated Surgery", **panel speaker**, *National Center for Image Guided Therapy*, Rockville, MD, October 19, 2006.
33. "Medical Robotics and Computer-Integrated Surgery", **invited speaker**, *TK60 Symposium*, Pittsburg, PA, March 9, 2007.
34. "Medical Robotics and Computer-Integrated Surgery", **keynote speaker**, *Design of Medical Devices Conference*, Minneapolis, MN, April 17, 2007.
35. "Medical Robotics and Computer-Integrated Surgery", **invited speaker**, *3<sup>rd</sup> Summer School in Surgical Robotics*, Montpellier, France, September 11, 2007.
36. "Robotics: The Future is Now", **invited speaker**, *Boston Chapter of the Johns Hopkins University Alumni Association*, Boston, MA, October 7, 2007.
37. "Medical Robotics and Computer-Integrated Surgery", *BioRob 2008*, Scottsdale, AZ. October 18, 2008. **Invited Speaker**
38. "Medical Robotics and Computer-Integrated Surgery", *Compsac 2008*, Turku, Finland. July 28, 2008. **Keynote Speaker**
39. "Perspectives on Medical Robotics and Computer-Integrated Interventional", *Medicine Medizin Innovativ 2008*, NurnbergMesse, Germany. July 10, 2008. **Invited Speaker**
40. "Ergonomics/Human Factors", *5th Annual Innovations in the Surgical Environment*, Baltimore, MD. June 27, 2008. **Panel Moderator**
41. "Future of Robotics", AAOS AICASKH. Providence, RI. May 15, 2008. **Invited Speaker**
42. "Surgical Assistance: Systems to Improve Efficiency and Outcomes", *Keck Institute Conference on New Frontiers in Medicine*, Claremont, CA. April 23, 2008. **Invited Speaker and Panelist**
43. "Medical Robotics and Computer-Integrated Interventions: where we are, wither we are tending, and how to get there", **Presidential Plenary Speaker**, *4th International Congress of the Minimally-Invasive Robotic Association*, Quebec City, Quebec, Canada, January 29, 2009.
44. "Future trends and Opportunities in Medical Robotics Research", **Invited Panelist**, *4th International Congress of the Minimally-Invasive Robotic Association*, Quebec City, Quebec, Canada, January 31, 2009.
45. "Medical Robotics and Computer-Integrated Interventional Medicine", **Invited Speaker**, Seoul Digital Forum 2009, May 28, 2009.
46. "Medical Robotics and Computer-Integrated Interventional Medicine", **Invited Speaker**, Symposium on surgical computing, imaging, sensing, and robotics – from in silico patient modeling to clinical practice, Osaka University, Osaka, Japan, June 2, 2009.
47. "Medical Robotics and Computer-Integrated Interventional Medicine", **invited speaker**, *4th Summer School in Surgical Robotics*, Montpellier, France, September 14, 2009.
48. "Medical Robotics and Computer-Integrated Interventional Medicine", **organizer & leadoff speaker**, *Tutorial on Medical Robotics* held as part of *MICCAI 2009*, September 20, 2009.
49. "Medical Robotics and Computer-Integrated Interventional Medicine", **invited speaker**, *3rd NIH and NCIGT Image-Guided Therapy Workshop*, Arlington, Va., March 9, 2010.

50. "Medical Robotics and Computer-Assisted Interventional Systems: Integrating Imaging, Intervention, and Informatics to Improve Patient Care", **invited speaker**, *Biomedical Engineering as Enabler for Research, Diagnosis and Therapy: GSISH Second Invited Symposium*, Spritzingse, Bavarian Alps, March 21, 2010.
51. "A Microsurgical Assistant for Retinal Surgery", **invited speaker**, *Stanford Medical Innovation Conference*, Stanford University, Stanford California, April 10, 2010.
52. "A Perspective on Flexible Robots for MIS", **invited speaker**, in *ICRA Workshop on Continuum and Serpentine Robots for Minimally Invasive Surgery*, Anchorage, Alaska May 3 2010.
53. "Medical Robotics and Computer-Integrated Interventional Medicine", **invited speaker**, *ICRA Workshop on Medical Cyber-Physical Systems*, Anchorage, Alaska, May 7, 2010.
54. "Medical Robotics and Computer-Integrated Interventional Medicine", **invited plenary speaker**, *American Control Conference*, Baltimore, Maryland, June 30, 2010.
55. "Medical Robotics and Computer-Integrated Interventional Medicine", **invited speaker**, *North American School on Medical Robotics*, Seattle, Washington, August 24, 2010.
56. "Medical Robotics and Computer-Integrated Interventional Medicine", **invited speaker**, *Advances in Surgical Technology*, Orlando, Florida, November 4, 2010.
57. "JHU Center for Computer-Integrated Surgical Systems and Technology (CISST ERC) - Sustainability Post-Graduation", **invited speaker**, *ERC Association Annual Meeting*, Bethesda, Maryland, December 2, 2010.
58. Medical Robots: Extending Human Capabilities in an Especially Challenging Environment, **invited speaker**, *ICRA 2011 workshop on Mechanisms for Surgical Robotics*, Shanghai, China, May 9, 2011.
59. "Medical Robotics and Computer-Integrated Interventional Medicine", **keynote speaker**, *IASTED International Conference on Imaging and Signal Processing in Healthcare and Technology*, Washington, DC, May 17, 2011.
60. "Medical Robotics and Computer-Integrated Interventional Systems", *Computer-Assisted Orthopaedic Surgery (CAOS) Workshop on Novel Technologies*, London, England, June 15, 2011.
61. "A Robotic Assistant for Trans-Oral Surgery: The Robotic Endo-Laryngeal Flexible (Robo-ELF) Scope", *Hamlyn Symposium on Medical Robotics*, London, England, June 19, 2011.
62. "Recent Work Toward a Microsurgical Assistant for Retinal Surgery", **invited lecture**, *Hamlyn Symposium on Medical Robotics*, London, England, June 20, 2011.
63. "A Multi-view Active Contour Method for Bone Cement Reconstruction from C-Arm X-Ray Images", *Information Processing in Computer-Assisted Interventions (IPCAI)*, Berlin, Germany, June 22, 2011.
64. "Academic, Clinical, and Industry Partnerships", *IPCAI-ISCAS Joint Panel Session*, Berlin, Germany, June 23, 2011.
65. "Medical Robotics and Computer-Integrated Interventional Medicine", *5th Summer School Surgical Robotics*, Montpellier, France, Sept. 12, 2011.
66. "Medical Robotics and Computer-Integrated Interventional Medicine", **invited keynote**, *SPIE Medical Imaging: Image-Guided Procedures, Robotic Interventions and Modeling*, San Diego, February 5, 2012.
67. "Medical Robotics and Computer-Integrated Interventional Medicine", **invited lecture**, *Symposium on Robotics Science and Technology*, College de France, Paris, June 12, 2012.
68. "Medical Robotics and Computer-Integrated Interventional Medicine", "A Microsurgical Assistant for Retinal Surgery", "Statistical Atlases", and other topics. Lectures given at the *EMBS Summer School on Biomedical Imaging*, Berners Island, Brittany, June 24-25, 2012.
69. "Engineering Research Center for Computer-Integrated Surgical Systems and Technology", *Laboratory for Computational Sensing and Robotics Industry Day Symposium*, July 16, 2012.
70. "Medical Robotics and Computer Integrated Interventional Medicine", *3rd North American Summer School on Medical Robotics*, London Ontario, August 13, 2012.
71. "Medical Robotics and Computer-Integrated Interventional Medicine", **keynote lecture**, *Daegu Global Innovation Festival*, Daegu, Korea, December 6, 2012.
72. "Medical Robotics and Computer-Integrated Interventional Medicine", *NCIGT Workshop*, **invited speaker**, Crystal City, March 21, 2013.
73. "3D Ultrasound-Guided Retrieval of Foreign Bodies from a Beating Heart using a Dexterous Surgical Robot", *Hamlyn Symposium on Medical Robotics*, London, June 24, 2013.
74. "Toward a sub-millimetric triaxial force sensing instrument with integrated fiber Bragg grating for vitreoretinal surgery", *Computer Assisted Radiology and Surgery Conference*, Heidelberg, June 27, 2013.
75. "Medical Robotics and Computer-Integrated Interventional Medicine", **invited speaker**, *5th Summer School Surgical Robotics*, Montpellier, France, Sept. 7, 2013.

76. "A Microsurgery Assistant System", **invited speaker**, *Mathematical Challenges in Ophthalmology Conference*, UCLA, Los Angeles, California, January 17, 2014.
77. "The Future of Medical Robotics and Computer-Assisted Interventional Systems", **invited speaker and panelist**, *MedTech Partners Conference*, Erlangen, Germany, February 19, 2014.
78. "3D Ultrasound-Guided Retrieval of Foreign Bodies from a Beating Heart using a Dexterous Surgical Robot", *IEEE International Conference on Robotics and Automation*, Hong Kong, June 4, 2014.
79. "Medical Robotics and Computer-Integrated Interventional Systems: where we are and wither we are tending", **Invited Talk** to the *Asian Conference on Computer Aided Surgery (ACCAS)*, Fukuoka, Japan, June 25, 2014.
80. "The human and the machine: Robotic Cooperative Systems in MIS", **invited talk** at the *BEST Innovation Symposium*, IRCAD Institute, Strasbourg, France, July 10, 2014.
81. "An Open-Source Software Environment for the da Vinci Research Kit and Other Medical Robotics Research", *Hamlyn Symposium Workshop*, London, July 15, 2014.
82. "Medical robotics and computer-integrated interventional medicine" **invited talk** at the *4<sup>th</sup> Biennial North American Summer School on Surgical Robotics*, Carnegie Mellon University, Pittsburgh, July 21, 2014.
83. "An Open-Source Software Environment for the da Vinci Research Kit and Other Medical Robotics Research", *4<sup>th</sup> Biennial North American Summer School on Surgical Robotics*, Carnegie Mellon University, Pittsburgh, July 22, 2014.
84. "The Future of Medical Robotics and Computer-Assisted Interventional Systems", **invited talk** at the *Johns Hopkins Symposium on Head and Neck Robotic Surgery, Adjuvant Therapy and Emerging Technologies*, Baltimore, July 25, 2014.
85. "Common Components for Medical Robotics and Computer-Integrated Surgery Research", short talk at the *IROS2014 "Medical Robotics" Workshop: Community Consensus Benchmarks for Clinical Translation of Medical Robots*, Chicago, September 18, 2014.
86. "Will Robotics Save Medicine", **invited talk**, *Techna 2014 Symposium – Robotics for Healthcare*, Toronto, October 31, 2014.
87. "Medical Robotics and Computer-Integrated Interventional Systems", **invited talk** at the *North American Spine Society Annual Meeting*, San Francisco, November 13, 2014.
88. "Medical Robotics and Computer-Integrated Interventional Systems", **invited talk** at *Surgetica 2014*, Chambéry, France, December 3, 2014.
89. "The Role of Imaging in Computer-Integrated Interventional Systems", **invited talk** at *MICCAI Workshop on Interventional Microscopy*, October 5, 2015
90. "Medical Robotics in Image-Guided Interventions", **invited talk** at *MICCAI Workshop on Advanced Robotics Assistance in Medicine: IROS meets MICCAI*, October 5, 2015.

## Invited University Colloquia, Grand Rounds Presentations, and Seminars

1. "Medical Robotics and Computer Integrated Surgery", Carnegie Mellon University, April 2001.
2. "Medical Robotics: The Key for Computer-Integrated Therapy Delivery", Boston University, April 2002.
3. "Computer-Integrated Surgery: Where We Are Now and Wither We Are Tending", Drexel University, February, 2002.
4. "Steady Hand Microsurgery/Deformable 2D-3D Registration", MERITS Seminar, Carnegie Mellon University, November 25, 2002.
5. "Computer-Integrated Surgery: Coupling Information to Action in 21<sup>st</sup> Century Operating Rooms", Yale University, March, 2004.
6. "Medical Robotics and Computer-Integrated Surgery", Columbia University, December, 2004.
7. "Medical Robotics and Computer-Integrated Surgery", University of Maryland Medical Center Grand Rounds, January 5, 2005.
8. "Medical Robotics and Computer-Integrated Surgery", University of Calgary, Calgary, Canada, October 30, 2006.
9. "Medical Robotics and Computer-Integrated Surgery", George Washington University, Washington D.C., March 24, 2006.

10. "Computer-Integrated Surgery", *Emerging Technology and Best Industry Practices Seminar*, Boston University, March 31, 2006.
11. "Medical Robotics and Computer-Integrated Surgery", McMaster School of Biomedical Engineering, McMaster University,
12. "Medical Robotics and Computer-Integrated Surgery", Surgical Grand Rounds Hospital for Sick Children, Toronto, Canada, February 9, 2007.
13. "Medical Robotics and Computer-Integrated Surgery", NIH STEPS Symposium, May 10, 2007.
14. "Medical Robotics and Computer-Integrated Surgery", USC/Intuitive, California, June 19, 2007.
15. "Medical Robotics and Computer-Integrated Surgery", Fraunhofer Institute, Munich, Germany, July 16, 2007.
16. "Medical Robotics and Computer-Integrated Surgery", UCLA. January 15, 2008.
17. "Medical Robotics and Computer-Integrated Surgery". Queen's University. March 13, 2008.
18. "Medical Robotics and Computer-Integrated Surgery". UNC/Duke/NCSU. April 07, 2008.
19. "Computer-Integrated Interventional Medicine – The vision of the CISST ERC", *JHU Winter School on Medical Robotics and Computer-Integrated Interventional Systems*, Jan 12, 2009.
20. "Medical Robotics and Computer-Integrated Interventional Medicine", Michigan State University. Jan 22, 2009.
21. "Medical Robotics and Computer-Integrated Interventional Medicine", *Cross-faculty Symposium on Medical Robotics and Computer-Assisted Interventions*, Imperial College, London, May 19, 2009.
22. "Medical Robotics and Computer-Integrated Interventional Medicine", Yonsei University, Seoul, Korea. May 29, 2009.
23. "Medical Robotics and Computer-Integrated Interventional Medicine", Shiga University, Shiga, Japan. June 1, 2009.
24. "Medical Robotics and Computer-Integrated Interventional Medicine", University of Tokyo, Tokyo, Japan. June 3, 2009.
25. "Statistics and Prior Models in Image-based Modeling and Interventions", Johns Hopkins Medical Imaging Symposium, November 11, 2009.
26. "A Microsurgical Assistant for Retinal Surgery", talk to technical staff at Intuitive Surgical, Inc., Sunnyvale, California, November 23, 2009.
27. "Medical Robotics and Computer-Assisted Interventional Systems: Integrating Imaging, Intervention, and Informatics to Improve Patient Care", Surgical Grand Rounds, Mt. St. Agnes Hospital, February 12, 2010.
28. "A Microsurgical Assistant for Retinal Surgery", Mechanical Engineering Department Seminar, The University of Maryland, May 14, 2010.
29. "Medical Robotics and Computer-Integrated Interventional Medicine", Robotics Institute Seminar, Carnegie-Mellon University, January 21, 2011.
30. "Medical Robotics and Computer-Integrated Interventional Medicine", Computer Science Department Seminar, University of Maryland, January 31, 2011.
31. "Medical Robotics and Computer-Integrated Interventional Medicine", APL Colloquium Series, Johns Hopkins Applied Physics Lab, January 13, 2011.
32. "Medical Robotics and Computer-Integrated Interventional Medicine", Biomedical Imaging Research Centre, University of Western Ontario, January 18, 2012.
33. "Medical Robotics and Computer-Integrated Interventional Medicine", Johns Hopkins Applied Physics Laboratory, Jan 13, 2012.
34. "A Microsurgical Assistant for Retinal Surgery", Computer-Assisted Medical Interventions, Canadian Surgical Technologies and Advanced Robotics (CSTAR) Centre, University of Western Ontario, January 20, 2012.
35. "A Microsurgical Assistant for Retinal Surgery", GRASP Lab Seminar, University of Pennsylvania, Philadelphia, April 20, 2012.
36. "Medical Robotics and Computer-Integrated Interventional Medicine", Siemens Corporate Research Laboratory, July 26, 2012.
37. "Medical Robotics and Computer-Integrated Interventional Medicine", Robotics and Mechatronics Center, Forschungszentrum der Bundesrepublik Deutschland für Luft- und Raumfahrt. (DLR), Munich, July 30, 2012.
38. "Medical Robotics and Computer-Integrated Interventional Medicine", Computer Science Department, Montana State University, Bozeman, Montana, October 26, 2012.

39. "A Microsurgery Assistant for Retinal Surgery", Robotics Engineering Department, Daegu Gyeongbuk Institute of Science and Technology (DGIST), December 7, 2012.
40. "Medical Robotics and Computer-Integrated Interventional Medicine", **distinguished lecture**, Stanford EE Computer Science Systems Colloquium, Stanford University, January 16, 2013.
41. "Medical Robotics and Computer-Integrated Interventional Medicine", Computer Science Colloquium at the University of Texas, Arlington, March 8, 2013.
42. "Medical Robotics and Computer-Integrated Interventional Medicine", National Robotics Engineering Center, Carnegie-Mellon University, Pittsburgh, March 6, 2013.
43. "Medical Robotics and Computer-Integrated Interventional Medicine", Computer Science Colloquium at the University of Texas, Arlington, March 8, 2013.
44. "Medical Robotics and Computer-Integrated Interventional Medicine", Mechanical Engineering Colloquium at Vanderbilt University, October 7, 2013
45. "Medical Robotics and Computer-Integrated Interventional Medicine", Invited Grand Rounds talk to Department of Surgery at Brigham and Women's Hospital, September 24, 2014.
46. "Medical Robotics and Computer-Integrated Interventional Medicine", Robotics and Mechatronics Center, Forschungszentrum der Bundesrepublik Deutschland für Luft- und Raumfahrt. (DLR), Munich, October 8, 2015.

## Other

1. "Computer-Integrated Surgery", talk to upper management, G.E. Medical Systems, Milwaukee, April 5, 2001.
2. "Medical Robotics and Computer-Integrated Therapy Delivery: Coupling Information to Action in 21<sup>st</sup> Century Surgery", **invited talk** to the University Health Consortium, Atlanta, Sept. 11, 2001.
3. "Medical Robotics and Computer-Integrated Therapy Delivery: Coupling Information to Action in 21<sup>st</sup> Century Surgery", **invited talk** to the Houston Surgical Society, Houston, September 24, 2001.
4. "Computer-Integrated Surgery", talk at IBM T. J. Watson Research Center, October 29, 2001.
5. "Computer-Integrated Surgery: Coupling Information to Action in the 21<sup>st</sup> Century", **invited talk**, Philips Research, Briarcliff, NY, May 16, 2005.
6. "Computer-Integrated Surgery", *CMU Surgery for Engineers*, Pittsburgh, PA, May 3, 2006.
7. "Medical Robotics and Computer-Integrated Surgery", *Society of Engineering Alumni, Johns Hopkins University*, Los Angeles, CA, November 5, 2006.
8. "Medical Robotics and Computer-Integrated Surgery", *Fraunhofer Workshop*, Munich Germany, November 14, 2006.
9. "Robotics: The Future is Now", NY Chapter of the Johns Hopkins Alumni. February 10, 2008.
10. "NSF Engineering Research Center for Computer-Integrated Surgical Systems and Technology", presentation to members of US Congressional Staff, February 20, 2009.
11. "Medical Robotics and CIIM", Presentation to Siemens Management, Erlangen, Germany, March 24, 2009.
12. "Registration and Visualization for Laparoscopic Surgery", Fraunhofer/JHU workshop, Munich, Germany, March 25, 2009.
13. "Information-Enhanced Interventional Medicine", Fraunhofer/JHU workshop, Munich, Germany, March 25, 2009.
14. "A Microsurgery Assistant System for Retinal Surgery", Presentation to Zeiss technical staff, Oberkochen, Germany, March 26, 2009.
15. "E-science meets radiation oncology: Using statistical shape analysis to improve the quality and efficiency of radiation therapy planning", presentation for Paul Maritz, Johns Hopkins University, April 7, 2009.
16. "Steady-hand robot and workstation for microsurgery", Poster presentation and demonstration for NSF CPS exhibition to US Senate and Congressional staffs, July 9, 2009.
17. "Overview of Medical Robotics and Computer-Integrated Intervention Research at CISST ERC", presentation to management from Hologic Corp., JHU, July 27, 2009.
18. "Overview of Medical Robotics and Computer-Integrated Intervention Research at CISST ERC", presentation to visiting delegation from NASA, JHU, September 17, 2009.
19. "Overview of Medical Robotics and Computer-Integrated Intervention Research at CISST ERC", presentation to visiting delegation from Twente University, JHU, November 11, 2009.

20. "Introduction to the CISST ERC and to our Microsurgical Assistant Project", presentation to visitors from Alcon, Inc., November 19, 2009.
21. "Overview of Medical Robotics and Computer-Integrated Intervention Research at CISST ERC", presentation to visiting delegation from New Zealand Embassy, JHU, December 14, 2009.
22. "A Microsurgical Assistant for Retinal Surgery", presentation to representatives of Auris Inc, May 13, 2010.
23. "Overview of Medical Robotics and Computer-Integrated Intervention Research at CISST ERC", presentation to Executives from Siemens AX, JHU, Baltimore, July 16, 2010.
24. "Overview of Medical Robotics and Computer-Integrated Intervention Research at CISST ERC", presentation to visitors from Johnson and Johnson, JHU, Baltimore, July 22, 2010.
25. "Overview of Medical Robotics and Computer-Integrated Intervention Research at CISST ERC", presentation to visitors from the Danish "RoboCluster" robotics research consortium, JHU, Baltimore, October 28, 2010.
26. "Overview of Medical Robotics and Computer-Integrated Intervention Research at CISST ERC", presentation to visitors from Hansen Medical, JHU, Baltimore, November 22, 2010.
27. "Overview of Medical Robotics and Computer-Integrated Intervention Research at CISST ERC", presentation to visiting US Congressional and Senate Staff members, Johns Hopkins University, June 2, 2011.
28. "The CISST ERC", *Johns Hopkins Applied Physics Laboratory Collaboration Expo*, Johns Hopkins APL Kossiakoff Center, June 9, 2011.
29. "Medical Robotics and Computer-Integrated Interventional Systems" to students in the *JHU Meyerhoff Bridge Program*, Johns Hopkins University, June 28, 2011.
30. "Medical Robotics and Computer-Assisted Microsurgery" to visitors from Cochlear Corporation, July 19, 2011.
31. "A Microsurgery Assistant for Vitreoretinal Surgery", Carl Zeiss Meditec, Oberkochen, Germany, July 30, 2012.
32. "Overview of the Laboratory for Computational Sensing and Robotics", LCSR Industry Day, Johns Hopkins University, October 18, 2013.
33. "Medical Robotics Research at JHU", LCSR Industry Day, Johns Hopkins University, October 18, 2013.
34. "Medical Robotics and Computer-Integrated Interventional Medicine", invited talk at Siemens AX, Forstheim, Germany, February 18, 2014.
35. "Medical Robotics and Computer-Integrated Interventional Medicine", invited talk at Kuka Robotics, Augsburg, Germany, February 20, 2014.
36. "The Future of Medical Robotics and Computer-Assisted Interventional Systems", Presentation to John Dineen (CEO of GE Health Care) at Johns Hopkins University, March 12, 2014.
37. "The Laboratory for Computational Sensing and Robotics", short overview for MSE Visitors Day.
38. "The Laboratory for Computational Sensing and Robotics and the CISST ERC", Presentation to Dr. Lynn Preston, Emeritus Director of the NSF Engineering Research Centers Program, May 9, 2014.
39. "Medical Robotics and Computer-Assisted Interventional Systems", Presentation to Dr. Michael Zinner (Chairman of Surgery, Brigham and Women's Hospital), Johns Hopkins University, May 22, 2014.
40. "Medical Robotics and Computer-Integrated Interventional Systems", **invited talk** at Daegu Gyeonbuk Institute of Science and Technology (DGIST), Daegu, Korea, June 23, 2014.
41. "Medical Robotics and Computer-Assisted Interventional Systems", presentation to John Dineen and other GE Health Care executives, July 8, 2014.
42. "Overview of the Laboratory for Computational Sensing and Robotics", LCSR Industry Day, Johns Hopkins University, September 8, 2014.
43. "Overview of Medical Robotics Research in LCSR", LCSR Industry Day, Johns Hopkins University, September 8, 2014.
44. "Medical Robotics and Computer-Integrated Interventional Medicine", **invited talk** at Siemens Corporate Research, Princeton, November 7, 2014.

# TEACHING

## Courses Taught or Developed at Johns Hopkins University

	Course Name & description	Year Developed	Years Taught (by me)
600.445/645	<b>Computer-Integrated Surgery (Fall Semester)</b> This course (originally titled "Quantitative Medical Computing") is a difficult, multidisciplinary course that combines an overview of emerging applications in computer-integrated surgery with instruction in a range of technical sub-disciplines ranging from image processing to modeling to registration to interventional devices. It is taken by upper level-undergraduates and graduate students	1995	1995-2014
600.446/646	<b>Advanced Computer-Integrated Surgery (Spring)</b> This course is a project-oriented seminar course, in which students work in small teams to undertake a substantial implementation effort tied to current research or development activities. Students learn project management and presentation skills as well as gaining practical experience and more in-depth knowledge in a CIS topic.	1996	1996-2014
600.145	<b>Introduction to Computer-Integrated Surgery (intersession &amp; summer)</b> This course provides a brief (1 credit) introduction to the basic technology of computer-integrated surgery systems, together with example applications. The material covered is similar in nature to that in 600.445, but in less depth and without intensive mathematics. The course is intended for lower-level undergraduates and for students wanting to learn something about CIS without investing the time required to take 600.445. The summer version of the course is also taken by high school students in special programs.	1999	1999-2006,2008
600.746	<b>Methods in Medical Image Analysis Seminar</b> This weekly seminar focuses on research issues in medical image analysis, including image segmentation, registration, statistical modeling, and applications. It will also include selected topics relating to medical image acquisition, especially where they relate to analysis. The purpose of the course is to provide the participants with a thorough background in current research in these areas, as well as to promote greater awareness and interaction between multiple research groups within the University. Topics vary from year to year. Examples include classic papers in medical imaging, ultrasound imaging, deformable registration, level-set segmentation methods, etc.	2001	2001-2014

500.410	<b>Surgery for Engineers</b> This course is a hands-on course on basic surgical technique offered to graduate students and undergraduates in computer-integrated surgery and biomedical engineering. It is taught by a faculty member in the JHU Department of Comparative Medicine. I do not teach this course, but was instrumental in developing the course concept and in getting it started.	1999-2000	
	<b>Winter School for Medical Robotics and Computer-Integrated Interventional Systems (MRCIIS)</b> This is an intensive one week short course for post-graduate and post-doctoral students on medical robotics and computer-integrated interventional medicine. The course includes tutorial lectures and research talks by internationally recognized faculty, lab tours & demonstrations in our new facilities in the Computational Sciences and Engineering Building on the Johns Hopkins Homewood Campus, and a compressed version of Johns Hopkins' unique Surgery for Engineers course. I was the principal organizer of the course, which was team taught by an international team of faculty.  The course was first taught in January 2009, with partial support from NSF and IEEE. It was taken by 38 students from around the world, 25 of whom participated in surgery for engineers. The faculty of the school consisted of 19 distinguished researchers from around the world, of whom 13 were from outside JHU.  It was subsequently taught in Summer 2010 at the University of Washington and Summer 2012 at the University of Western Ontario; I was a co-organizer.	2008	2009
500.754	<b>Seminar on Statistical Anatomic Models, Registration, and Reconstruction</b> This weekly research seminar focuses generally on statistical modeling of anatomic structures, image and model registration, 3D image reconstruction methods, and their interrelationships. We concentrate primarily, though not exclusively, on x-ray based imaging modalities (x-ray fluoroscopy, CT, cone-beam tomography, "hybrid" reconstruction methods, etc.)	2010	2010-2011

## Courses Taught or Developed Elsewhere

1. "Computer-Integrated Surgery", 1 week short course taught at Daegu Gyeonbuk Institute of Science and Technology (DGIST) in July 2013.

## Postdoctoral Fellows Advised



1. Peter Kazanzides: Developed prototype of Robodoc, the first robot for orthopaedic surgery; 1989-1990 (at IBM Research).
2. Yong-Yil Kim: Developed prototype passive manipulation aid for craniofacial osteotomies; 1989-1990 (at IBM Research).
3. Kreg Gruben: Developed prototype robots for laparoscopic surgery; 1993 (at JHU and IBM Research).
4. Steve Schreiner: X-ray guided robotic system for percutaneous therapy of liver cancer; 1994-1996 (JHU).
5. Payman Sadegh: Optimal planning for HDR brachytherapy; 1998 (JHU)
6. Peter Berkelman: Microsurgical force sensing for steady hand robot; 1999-2000 (JHU, jointly supervised with Louis Whitcomb).
7. Nabil Simaan: Developed snake-like robots for minimally-invasive surgery; 2003-2004 (JHU)
8. Ofri Sadowsky: X-ray hybrid reconstruction and applications to orthopaedic surgery 2008-2009 (JHU)
9. Yoshito Otake: X-ray reconstruction, registration, and application to orthopaedic surgery (with Jeff Siewerdsen) 2008-2010 (JHU)
10. Eric Meisner: Tool tracking, visual servoing, and experiments in retinal microsurgery (with Greg Hager) 2009 (JHU)
11. Patricio Simari: Radiation oncology "shapes" project (with Misha Kazhdan) 2009-2010 (JHU)
12. Rogerio Richa: Microsurgery Assistant Workstation (with Greg Hager) 2010-2012 (JHU)
13. Marcin Balicki: Robot and computer vision systems for retinal microsurgery and head and neck surgery 2014-2015 (JHU).

## Ph.D. Theses Advised

### As principal advisor

1. Rajesh Kumar, *An Augmented Steady Hand System for Precise Micromanipulation*, Computer Science, The Johns Hopkins University, Baltimore, 2001.
2. Jianhua Yao., *A statistical bone density atlas and deformable medical image registration*, Ph.D. Thesis, Computer Science, The Johns Hopkins University, Baltimore, January 2002.
3. Andrew Bzostek, *Computer-Integrated Needle Therapy Systems: Implementation and Analysis*, Ph.D. thesis, Computer Science, The Johns Hopkins University, Baltimore, March 2005.
4. Ming Li, *Intelligent Robotic Surgical assistance for Sinus Surgery*. Ph.D. thesis, Computer Science, The Johns Hopkins University, Baltimore, August 2005.
5. Ankur Kapoor, *Motion Constrained Control of Robots for Dexterous Surgical Tasks*, Ph.D. Thesis, Computer Science, The Johns Hopkins University, Baltimore, September 2007.
6. Ofri Sadowsky, *Image Registration and Hybrid Volume Reconstruction of Bone Anatomy Using a Statistical Shape Atlas*, Ph.D. Thesis, Computer Science, The Johns Hopkins University, September 2008.
7. Gouthami Chintalapani, *Statistical Atlases of Bone Anatomy and Applications*, Ph.D. Thesis, Computer Science, The Johns Hopkins University, October, 2010.
8. Omar Ahmad, *Volumetric DXA (VXA): A New Method to Extract 3D Information From Multiple In Vivo DXA Images*, Ph.D. Thesis, Computer Science, The Johns Hopkins University, August, 2011.
9. Blake Lucas, *Unifying Deformable Model Representations through New Geometric Data Structures*, Ph.D. Thesis, Computer Science, The Johns Hopkins University, July 2012.
10. Marcin Balicki, *Augmentation Of Human Skill In Microsurgery*, PhD thesis in Computer Science, Johns Hopkins University, Baltimore, Maryland, February 2014.
11. Paul Thienphrapa, *A Minimally Invasive Surgical System for 3D Ultrasound Guided Robotic Retrieval of Foreign Bodies from a Beating Heart*, PhD thesis in Computer Science, Johns Hopkins University, Baltimore, Maryland, March 2014.
12. Wen Liu, *Augmented Reality and Intraoperative C-Arm CBCT for Image-Guided Robotic Surgery*, PhD thesis in Computer Science, Johns Hopkins University, Baltimore, Maryland, June 2014.

### As secondary advisor or reader (incomplete list)

1. David LaRose, *X-ray/CT Registration using Accelerated Volume Rendering*, Ph.D. Thesis, Computer Science, Carnegie Mellon University, April 2001. **(Reading Committee Member)**

2. Ashraf Mohamed, *Combining Statistical and Biomechanical Models for Estimation of Anatomical Deformations*, Ph.D. Thesis, Computer Science, Johns Hopkins University, July, 2005. **(Co-advisor and Reading Committee Member)**
3. Sheng Xu, *Organ motion compensation in computer integrated surgery*, Ph.D. Thesis, Computer Science, Johns Hopkins University, July, 2005. **(Co-advisor and Reading Committee Member)**
4. Krishna Ramamurthy, *Cone-Beam Tomography Using C-Arm X-ray Projections: Complete Trajectories and Integration of PRior CT Information*, Ph.D. Thesis, Electrical and Computer Engineering, The Johns Hopkins University, Baltimore, April 2006. **(Reading Committee Member)**
5. Emad Bector, *Enabling Technologies for Ultrasound Imaging in Computer-Assisted Intervention*, Ph.D. Thesis, Computer Science, The Johns Hopkins University, Baltimore, October 2007. **(Co-advisor and Reading Committee Member)**
6. Panadda Marayong, *Motion Control Methods for Human-Machine Cooperative Systems*, Ph.D. Thesis, Mechanical Engineering, Ph.D. Thesis, Computer Science, The Johns Hopkins University, Baltimore, August 2007. **(Reading Committee Member)**
7. Ameet Jain, *Computation of 3D Implant Coordinates for Prostate Brachytherapy*, Ph.D. Thesis, Computer Science, The Johns Hopkins University, Baltimore, September 2007. **(Co-advisor and Reading Committee Member)**
8. Lotta Ellingsen, *Hybrid Deformable Image Registration - with Application to Brains, Pelvises, and Statistical Atlases*, Ph.D. Thesis, Electrical and Computer Engineering, The Johns Hopkins University, Baltimore, December 2007. **(Reading Committee Member)**
9. Robert Webster, *Design and Mechanics of Continuum Robots for Surgery*, Ph.D. Thesis, Mechanical Engineering, Ph.D. Thesis, Computer Science, The Johns Hopkins University, Baltimore, December 2007. **(Reading Committee Member)**
10. Yiqiang Zhan, *Advanced Image Analysis Methods for the Diagnosis of Prostate Cancer*, Ph.D. thesis in Computer Science, Johns Hopkins University, Baltimore, 2007. **(Reading Committee Member)**
11. Jeffrey Stoll, *Ultrasound-based Navigation for Minimally Invasive Medical Procedures*, Ph. D. thesis in Mechanical Engineering, Boston University, 2007. **(Reading Committee Member)**
12. Lawton Verner, *Sensor/Actuator Asymmetries in Telemanipulators*, Ph.D. thesis in Mechanical Engineering, Johns Hopkins University, Baltimore, 2009. **(Reading Committee Member)**
13. Nicholas Patronik, *A Miniature Mobile Robot for Precise and Stable Access to the Beating Heart*, Ph.D. thesis in Robotics, Carnegie-Mellon University, 2008. **(Reading Committee Member)**
14. Gabriel Brisson, *The Precision Freehand Sculptor: A Robotic Tool for Less Invasive Joint Replacement Surgery*, Ph.D. thesis in Robotics, Carnegie-Mellon University, 2008. **(Reading Committee Member)**
15. Gregory Fischer, *Enabling Technologies for MRI-Guided Interventional Procedures*, Ph.D. thesis in Mechanical Engineering, Johns Hopkins University, Baltimore, 2008. **(Reading Committee Member)**
16. Orcun Goksel, *Meshing and Rendering of Patient-Specific Deformation Models with Application to Needle Insertion Simulation*, Ph.D. thesis in Electrical and Computer Engineering, University of British Columbia, Vancouver, 2010. **(External Reader)**
17. Michael D. Kutzer, *Advancements in Cooperative Robotics*, Ph.D. Thesis in Mechanical Engineering, May 2012, **(Reading Committee Member)**
18. Daniel Mirota, *Video-Based Navigation with Application to Endoscopic Skull Base Surgery*, Ph.D. Thesis in Computer Science, July 2012 **(Advisory Committee Member)**.
19. Tian Xia, *Toward Model Driven Robotic Assistance in Human-Robot Collaboration Systems*, Ph. D. Thesis in Computer Science, The Johns Hopkins University, 2012 **(Reading Committee Member)**
20. Lejing Wang, *Novel Techniques for Integrating Video Augmented X-ray Imaging into Orthopedic and Trauma Surgery*, Ph.D. Thesis in Computer Science, Technical University of Munich, 2012 **(External Examiner)**
21. James Gwilliam, *Tactile Sensing and Display for Robot-Assisted Minimally Invasive Surgery: Detecting Lumps in Soft Tissue*, Ph.D. Thesis in Mechanical Engineering, May 2013 **(Reading Committee Member)**.
22. Ehsan Basafa, *Computer-Assisted Femoral Augmentation for Osteoporotic Hip Fracture Prevention*, Ph. D. Thesis in Mechanical Engineering, Johns Hopkins University, September 2013 **(Reading Committee Member)**.
23. Ioana Fleming, *Robust Displacement Estimation for Ultrasound Elastography and Thermal Imaging*, Ph. D. Thesis in Computer Science, 2014 **(Reading Committee Member)**.

24. Chunwoo Kim, *Image Guided Robots for Urology*, Ph.D. Thesis in Mechanical Engineering, March 2014 (Reading Committee Member).

## M.S. Theses Advised

### As principal advisor

1. Aaron Barnes, *A modular robotic system for precise minimally invasive surgery*, MS Thesis, Mechanical Engineering, The Johns Hopkins University, Baltimore, 1999.
2. Jonathan Lazarus, *Computer-Assisted Vertebroplasty*, MS Thesis, Computer Science, The Johns Hopkins University, Baltimore, 2000.
3. Randall Goldberg, *A Modular Robotic System for Ultrasound Image Acquisition*, M.S. Thesis, Mechanical Engineering, The Johns Hopkins University, Baltimore, 2001.
4. Adam Morris, *Bone Registration and Tracking using an optical tracking system*, M.S. Thesis, Computer Science, The Johns Hopkins University, Baltimore, 2002.
5. Joshua Leven, *A Telerobotic Surgical System with Integrated Robot-Assisted Laparoscopic Ultrasound Capability*, Computer Science, The Johns Hopkins University, Baltimore, May 2005.
6. Gregory Fischer, *Electromagnetic Tracker Characterization and Optimal Tool Design (with Application to ENT Surgery)*, Mechanical Engineering, The Johns Hopkins University, Baltimore, May 2005.
7. Barry Herman, *On the Role of Three Dimensional Visualization for Surgical Applications in Interactive Human Machine Systems*, Computer Science, The Johns Hopkins University. May 2005.
8. Gorkem Sevinc, *Integration and Evaluation of Interactive Speech Control in Robotic Surgery*, MS thesis in Computer Science, Johns Hopkins University, Baltimore, Maryland, 2010.
9. Orhan Ozguner, *Virtual Fixtures for Teleoperation*, MSE Thesis in Computer Science, Johns Hopkins University, Baltimore, Maryland, 2013.
10. Saumya Gurbani, *Submillimeter Fiber-Based Endomicroscopy using Optical Coherence Tomography for Cochlear Implant Surgery*, MS Thesis in Biomedical Engineering, 2013 (co-advisor).
11. Mehmet Gulsun, *CTA Coronary Labeling Through Efficient Geodesics Between Trees Using Anatomy Priors*, MS Thesis in Computer Science, The Johns Hopkins University, October 2014.

# Research Funding

## Current

- Title:** **NRI: Large: Collaborative Research: Complementary Situational Awareness for Human-Robot Partnerships**  
**Dates:** 10/01/2013-09/30/2018  
**Grantor:** National Science Foundation  
**Award number:** NSF IIS-1327657  
**Award amount:** \$1,175,809 for JHU part (\$561,787 awarded in FY13 and \$614,022 to be awarded in FY14)  
**Summary:** This work will advance human-robot partnerships by establishing a new concept called complementary situational awareness (CSA), which is the simultaneous perception and use of the task environment, using focusing applications in medical robotics. Our partner institutions for this award are Vanderbilt University (N. Simaan) and Carnegie Mellon University (H. Choset)  
**Role:** Principal Investigator
- Title:** **Interventional PhotoAcoustic Surgical System (i-PASS)**  
**Dates:** 4/1/2013-3/31/2015  
**Award Number:** NIH 1 R21 EB015638  
**Award Amount:** \$235,987  
**Summary:** The goal of this project is to develop a feasibility prototype of a novel system that exploits the photoacoustic effect to promote intraoperative video-to-ultrasound registration and guidance in minimally invasive interventions.  
**Role:** Principal Investigator
- Title:** **Image-Guided Workstation and Tools for the Treatment of Bone Defects**  
**Dates:** 1/1/14-11/30/17  
**Grantor:** National Institutes of Health  
**Award number:** NIH 1 R01 EB016703  
**Award amount:** \$447,949 (estimated suballocation from JHU APL for Taylor parts)  
**Summary:** The goal of this project is to develop a prototype robotically-assisted, less-invasive surgical workstation for preoperative planning, and real-time intraoperative monitoring, navigation, and updating of plans during hip revision surgery and for the treatment of osteolytic bone defects.  
**Role:** Co-Investigator (Principal Investigator is Mehran Armand)
- Title:** **Enhanced Navigation for Endoscopic Sinus Surgery Through Video Analysis**  
**Dates:** 7/1/2012-6/30/2017  
**Grantor:** National Institutes of Health  
**Award number:** R01 EB015530  
**Award amount:** \$ 1,828,944  
**Summary:** This project will provide new registration and visualization tools for sinus surgery using widely available high-definition endoscopic video. These tools will provide higher accuracy navigation to the surgeon, and will make it possible to accurately measure change as surgery progresses. The impact of these tools will be to enhance patient safety, reduce operative time, and reduce the need for intraoperative CT or cone beam imaging.  
**Role:** Co-Investigator (Principal Investigator is Greg Hager)
- Title:** **OCT-Guided Free-Hand Semi-Automated Microsurgical Tool for Enhanced Retinal Surgery Applications**  
**Dates:** 08/01/2011-07/31/2016  
**Grantor:** NIH 1 R01 EY021540 - 01  
**Award Amount:** \$2,040,444

Summary: This project addresses fundamental limitations in current vitreoretinal surgery by developing functional free-hand surgical tools that could empower micro-surgeons to achieve surgical objectives, diminish surgical risk and improve outcomes in all microsurgical fields

Role: Co-investigator (Principal Investigator is Jin Kang)

**Title:** A New robotic platform for image-guided orthopaedic surgery

Dates: 5/1/2014-12/31/2015

Grantor: Think Surgical

Award Amount: \$349,179

Summary: This work comprises several interrelated projects developing new technology and applications for a surgical robotics company.

Role: Co-investigator (Principal Investigator is Peter Kazanzides)

## Completed

**Title:** Microsurgical Assistant Workstation

Dates: 6/1/08-5/30/14

Grantor: National Institutes of Health

Award number: BRP 1 R01 EB 007969-01 A1

Award amount: \$5,795,410

Summary: This Bioengineering Research Partnership (BRP) focuses the efforts of highly qualified engineers and scientists from JHU (lead institution), Columbia and CMU, as well as surgeons from the JHU School of Medicine, to overcome human limitations in surgical practice. This project proposes to develop novel core technology and microsurgical tools with unique capability, as well as integrate computer assist systems. The effort will generate a computer assisted human user with enhanced microsurgical ability.

Role: Principal Investigator

**Title:** OCT Imaging and Assistive Systems for Cochlear Implant Surgery

Dates: 1/1/2012-1/15/2015

Grantor: Cochlear Corporation

Award amount: \$230,000

Summary: This is an exploratory project with Cochlear Corporation to develop and evaluate novel methods for assisting a surgeon in inserting a cochlear implant into the cochlea without damage to the cochlea

Role: Principal Investigator

**Title:** SBIR Phase II: Active Device for Reliable Cleaning of Feeding Tubes

Dates: 9/13/12-9/12/13

Grantor: Actuated Medical (Subcontract from NSF SBIR)

Award number: 5026-501

Award amount: \$99,785

Summary: This NSF SECO Phase II Supplement program will develop the Brain Shunt In-situ Clearing System - BASIC™ - a simple, safe, and minimally invasive device for percutaneous restoration of patency to occluded cerebrospinal fluid (CSF) shunts.

Role: Principal Investigator

**Title:** Richard A. Swirnow Computer-Integrated Surgical and Interventional Systems Mock Operating Room

Dates: 2008-2012

Grantor: Swirnow Family Foundation

Award amount: \$400,000 (\$80,000/year)

Summary: This is a charitable donation from the Swirnow Foundation to Johns Hopkins University for a computer-integrated "mock operating room" for systems-integration research and education in the Computational Sciences and Engineering Building on Johns Hopkins' Homewood Campus.  
Role: Principal Investigator

**Title:** North-American School on Medical Robotics and Computer-Integrated Interventional Systems (NAS MR/CIIS)

Dates: 10/1/2008-9/30/2011

Grantor: NSF

Award amount: \$50,000

Summary: This is a small grant from NSF to help support the Winter School in January 2009 and similar activities in the following year. The School was an intensive 1 week short course for post-graduate and post-doctoral students on medical robotics and computer-integrated interventional medicine. The course includes tutorial lectures and research talks by internationally recognized faculty, lab tours & demonstrations in our new facilities in the Computational Sciences and Engineering Building on the Johns Hopkins Homewood Campus, and a compressed version of Johns Hopkins' unique Surgery for Engineers course. For the following year the money will be used to subsidize student expenses for a similar school elsewhere.

Role: Co-principal investigator (with Ralph Etienne-Cummings)

**Title:** MRI: Development of Infrastructure for Integrated Sensing, Modeling, and Manipulation with Robotic and Human-Machine Systems

Dates: 9/1/07-8/31/2011

Grantor: National Science Foundation

Award number: CNS Major Research Instrumentation

Award amount: \$1,994,353

Summary: The focus of the grant is construction of two complementary robotics platforms for robotics research. My role is essentially consulting.

Role: Co-investigator (PI is A. Okamura)

**Title:** 3D Volumetric and Biomechanical Models of the Proximal Femur from DXA Projection Images

Dates: 10/1/05-10/1/11

Grantor: Hologic, Inc

Award amount: \$388,924

Summary: This project combines development of a statistical atlas of the proximal femur with deformable 2D-3D registration to create patient-specific "virtual CT" volumetric models based on a small number of Dual-Energy X-ray (DXA) images. One potential application of this work would be biomechanical modeling to assess fracture risk of patients undergoing DXA screening.

Role: Principal investigator

**Title:** High-Performance Cone-Beam CT Guidance of Head and Neck Surgery

Dates: 08/01/07-07/31/11

Grantor: National Institutes of Health

Award number: 1- R01-CA127444

Summary: Development of an integrated cone-beam CT guidance system for head and neck surgery. Quantitation of surgical performance improvement under various guidance modalities. Deployment in clinical research trials.

Role: Co-investigator (PI is J. Siewerdsen)

**Title:** Computer-assisted Hip Osteotomy Surgery with Real-Time Biomechanical Guidance

Dates: 10/01/07-9/30/10

Grantor: National Institutes of Health

Award number: 1 R01 EB006839-01A1

Award amount: \$212,220 (subaward)

Summary: Our goal is to develop and evaluate a real-time, intra-operative biomechanical guidance system that may improve the outcome of image-guided Periacetabular osteotomy surgery  
Role: Co-investigator (PI is M. Armand)

**Title: Image-Guided Osteoporotic Bone Augmentation**

Dates: 08/01/07-07/31/10

Grantor: National Institutes of Health

Award number: NIH 1 R21 EB007747-01

Award amount: \$448,003

Summary: The long-range goal of this project is to develop an image-guided workstation with biomechanical planning and intraoperative updates for surgical interventions applied to osteoporotic bone augmentation, when the risk of bone fracture becomes imminent. Specifically in this proposal, we demonstrate the feasibility of bone augmentation by developing a surgical system for femur augmentation

Role: Co-investigator (PI is M. Armand)

**Title: Active Multi-Spectral Illumination for Video Microscopy and Endoscopy**

Dates: 9/1/2008-6/30/2010

Grantor: Equinox Corp.

Award amount: \$149,998

Summary: This is a small project to explore active illumination schemes for endoscopy and microscopy

Role: Principal investigator

**Title: Initiative for Innovations in Interventional Medicine**

Dates: 08/01/07-07/31/10

Grantor: Johns Hopkins University / Fraunhofer Gesellschaft

Award amount: \$891,000 for JHU portion

Summary: This is a jointly funded collaborative project between Johns Hopkins University and Fraunhofer Institute to develop technology for computer-assisted endoscopic surgery. The funds for the JHU investigators come from JHU internal funds.

Role: Co-investigator (PI is E. McVeigh)

**Title: Ultrasound Guidance for a Laparoscopic Surgical Robot**

Dates: 8/15/06-7/31/2010

Grantor: National Institutes of Health

Award number: Phase II STTR 2 R42 RR019159

Award amount: \$330,075 direct spending; \$386,433 total

Summary: The goal of this Phase II STTR with Intuitive Surgical is development of a "third hand" laparoscopic ultrasound capability for the daVinci surgical robot

Role: Principal investigator

**Title: Engineering Research Center for Computer-Integrated Surgical Systems and Technology (CISST ERC).**

Dates: 9/1/97-12/31/2009

Grantor: National Science Foundation

Award Number: EEC9731478

Amount: \$30,189,932

Summary: This was the core "seed money" grant for the CISST ERC. The CISST ERC is a multi-institutional, multidisciplinary center whose focus is of basic science, computer-based technology, and engineered systems working cooperatively with surgeons to significantly change the way surgical procedures are carried out in the 21st century. Significant research focuses include modeling and analysis for treatment planning and control, robotics and human interfaces and systems for minimally-invasive, image-guided percutaneous therapy and microsurgery. Although the NSF grant is now "spent out", the Center continues.

**Role:** Principal Investigator and ERC Director. In addition to my duties as ERC Director, I also participate in a variety of ERC research in medical robotics, image registration, modeling, and systems.

**Title: Surgical Assistant Workstation for Telesurgical Robotics Research**

**Dates:** 9/1/97-12/31/2009

**Grantor:** National Science Foundation

**Award Number:** Supplement to EEC9731478

**Amount:** \$529,277 direct spending; \$691,454 total

**Summary:** This is a collaborative project between the NSF Engineering Research Center for Computer-Integrated Surgical Systems and Technology (CISST ERC) and Intuitive Surgical, Inc. (ISI) to develop an open-source software environment for medical robotics and computer-integrated surgery research.

**Role:** Principal Investigator

**Title: E-science Meets Radiation Oncology: Information-based closed loop interventional medicine**

**Dates:** 4/1/07-12/31/2009

**Grantor:** Maritz Fund

**Award amount:** \$232,540

**Summary:** This project explores the statistical relationship between anatomic shape and treatment planning in radiation oncology

**Role:** Principal investigator

**Title: Winter School on Medical Robotics and Computer-Integrated Interventional Systems (MRCIIS)**

**Dates:** 2008-2009

**Grantor:** IEEE Robotics and Automation Society

**Award amount:** \$25,000

**Summary:** This was a small grant from IEEE RAS to help support the Winter School in January 2009. This was an intensive 1 week short course for post-graduate and post-doctoral students on medical robotics and computer-integrated interventional medicine. The course includes tutorial lectures and research talks by internationally recognized faculty, lab tours & demonstrations in our new facilities in the Computational Sciences and Engineering Building on the Johns Hopkins Homewood Campus, and a compressed version of Johns Hopkins' unique Surgery for Engineers course.

**Role:** Principal investigator

**Title: Dexterous, Compact Telesurgical Robot for Throat & Airways**

**Dates:** 03/01/05-02/28/09

**Grantor:** National Institutes of Health

**Award number:** NIH 1 R21 EB0045457-01

**Award amount:** \$274,999 direct; \$440,500 total

**Summary:** The goal of this project was development and initial evaluation on phantoms of a very compact, high-dexterity telesurgical robot system suitable for minimally invasive surgery of the throat & airways.

**Role:** Principal investigator

**Title: Direct Video-CT Registration for High-Precision Surgical Navigation**

**Dates:** 04/01/06 – 03/31/09

**Grantor:** National Institutes of Health

**Award number:** 1R21EB005201 - 01A1

**Award amount:** \$125,000



Summary: The goal of this project is to demonstrate that direct registration of endoscopic video to pre-operative CT is a viable route to increasing the precision and usefulness of current surgical navigation systems. These results will set the stage for developing new approaches to high precision intra-operative navigation and visualization in anterior skull surgery

Role: Co-investigator (PI is G. Hager)

**Title:** **Modeling Synthesis and Analysis of Human Machine Collaborative Systems**  
**Dates:** 10/1/2002-9/30/2008  
**Grantor:** National Science Foundation  
**Award number:** IIS0205318 (medium ITR)  
**Award amount:** \$1,100,000  
**Summary:** Creating complete systems for different types of puncture tasks, examining and exploiting the commonalities of those tasks for single handed augmentation.  
**Role:** Co-Investigator (PI is G. Hager)

**Title:** **Prior Knowledge in 3D Reconstruction from 2D X-Rays**  
**Dates:** 08/01/04-07/31/08  
**Grantor:** NIH  
**Award number:** NIH1-R21 EB003616-01  
**Award amount:** \$375,000 direct; \$589,952 total  
**Summary:** This project will develop and validate novel algorithms for 3D CT-like reconstruction of bone images from mobile c-arm images. The novelty of the proposed methods will be their exploitation of prior knowledge in the form of prior CT scans when available and a statistical atlas when CT is not available. We use orthopaedic surgery as a focusing application.  
**Role:** Co-Investigator (PI was Jerry Prince)

**Title:** **Computer-assisted Hip Osteotomy Surgery with Real-Time Biomechanical Guidance**  
**Dates:** 10/01/03-08/31/05  
**Grantor:** National Institutes of Health  
**Award number:** 1R21EB002881-01  
**Award amount:** \$75,672 (for JHU Homewood part)  
**Summary:** The goal of this project is integration of preoperative and on-line biomechanical analysis for periacetabular osteotomies with a CT based surgical navigation system, together with a patient study of the resulting system.  
**Role:** Co-investigator

**Title:** **Ultrasound Assistant for a Laparoscopic Surgical Robot**  
**Dates:** 11/11/04-07/31/05  
**Grantor:** NIH  
**Award number:** R41 RR019159  
**Award Amount:** \$59,999  
**Summary:** The goal of the Phase I STTR project (with Intuitive Surgical Systems) is development of a "third hand" laparoscopic ultrasound capability for the daVinci surgical robot.  
**Role:** Principal investigator

**Title:** **Robot-assisted Needle Placement in Ultrasound-guided Liver Ablation**  
**Dates:** 09/30/03-09/30/04  
**Grantor:** National Institutes of Health  
**Award number:** 1R41CA103468  
**Summary:** This is a Phase I STTR with Burdette Medical Systems and JHU Medical School to develop an ultrasound-guided robotic system for percutaneous RF ablation of liver tumors.

**Title:** **Research on Applications of Localizer Technology.**  
**Dates:** 6/2002-6/2004  
**Grantor:** Northern Digital, Inc.

Amount: Approx \$150,000 total  
Summary: Industrially sponsored research aimed at characterization and novel applications of 3D navigational systems.  
Role: Principal Investigator

**Title: Scale-Invariant Skill Augmentation for Cooperative Human-Machine Micromanipulation Systems**

Dates: 7/1/2001-6/30/2004  
Grantor: National Science Foundation  
Award number: IIS0099770  
Award Amount: \$380,000  
Summary: Human-machine cooperation for skilled manipulation tasks. The research is on basic technology and techniques, using microsurgical tasks as a focus.  
Role: Co-Investigator

**Title: Cooperative Steady Hand Augmentation of Human Skill in Micromanipulation Tasks**

Dates: 8/30/1998-8/31/2003  
Grantor: National Science Foundation  
Award number: IIS 9801684  
Award amount: \$242,737  
Summary: Robotic systems and novel cooperative control methods for extending human abilities to perform extremely precise manipulation tasks, using applications in microsurgery and otology as focus. Results included demonstration of a novel "steady hand" robot system and its application in retinal vein cannulation, stapedotomy, and access to the cochlea of the inner ear. Note: This project is the predecessor to IIS099770, and is on continuation of funding to permit wrapping up of results.  
Role: Principal Investigator

**Title: Augmented Micro-Manipulation System**

Dates: 7/1/2002-12/31/2002  
Grantor: Foster Miller  
Award number: SUB100078 (on NSF SBIR to Foster-Miller, Inc.)  
Award amount: \$30,000  
Summary: The goal of this Phase I SBIR is feasibility demonstration and preliminary evaluation of the use of steady-hand robots for cell surgery  
Role: Principal Investigator for JHU component

**Title: X-ray registration for spine surgery**

Dates: Approx. April 2001-September 2001  
Grantor: Orthosoft  
Award number: N/A  
Award amount: Approx \$21,000  
Summary: This was a short-lived cooperative project with Orthosoft, Inc. to investigate new methods for x-ray registration in spine surgery.  
Role: Principal Investigator for JHU component

**Title: CISE Research Infrastructure: A Networked Computing Environment for The Manipulation and Visualization of Geometric Data**

Dates: 8/14/1997-7/31/2003  
Grantor: National Science Foundation  
Award Number: EIA-9703080  
Award Amount: \$1,226,381  
Summary: This was a shared research infrastructure grant that provided computing equipment for a variety of research projects involving several Johns Hopkins Computer Science faculty members  
Role: Co-investigator

**Title: Image Guided Percutaneous Robotic Assisted Therapy**

Dates: 7/1/1995-6/30/1998  
 Grantor: National Science Foundation  
 Award number: BES9520501  
 Award amount: \$762,425  
 Summary: Systems and technology research on robotically-assisted delivery of percutaneous therapy under CT and x-ray guidance, using liver brachytherapy as main focusing application. This project led to development of much of the infrastructure that was later incorporated into percutaneous therapy research within the ERC  
 Role: Co-Investigator

**Title: Instrumentation for Computer Science & Engineering Research in Image Segmentation, Registration, Modeling and Interactive Model-Based Task Optimization**  
 Dates: 2/15/1996-1/31/1999  
 Grantor: National Science Foundation  
 Award number: CDA-9529509  
 Award amount: \$113,207  
 Summary: Shared instrumentation grant involving 2 Johns Hopkins CS faculty members used to buy computers and other equipment for research on image processing and computer-assisted surgery  
 Role: Principal Investigator

**Title: Robotic Revision Hip Replacement Surgery**  
 Grantor: Integrated Surgical Systems/National Institute of Science and Technology  
 Dates: 10/95-4/98  
 Award number: NIST ATP Cooperative Agreement No. 94-01-0228.  
 Award amount: \$230,239  
 Summary: Development of x-ray registration and guidance methods for robotically-assisted revision hip replacement. This was the Johns Hopkins component of a \$4M NIST ATP involving IBM, Integrated Surgical Systems and (after I moved to JHU), Johns Hopkins  
 Role: Principal Investigator for JHU component; earlier was principal investigator for IBM

**Title: Workshop on Surgical Robotics**  
 Dates: 1993  
 Grantor: National Science Foundation  
 Award Number: 9222082  
 Award amount: \$30,000  
 Summary: This was the first NSF-sponsored planning workshop on medical robotics and computer-assisted surgery  
 Role: Principal investigator and workshop co-chairman (with George Bekey)

## WORK HISTORY (with summaries)

**1995-now     Johns Hopkins Univ.     Professor of Computer Science, with joint appointments in Radiology, Surgery and Mechanical Engineering**

Director of NSF Engineering Research Center on Computer-Integrated Surgical Systems and Technology. Current research interests include: computer-integrated planning and robotic delivery of optimized patterns of localized therapy; steady-hand augmentation of microsurgery and endoscopic surgery; image-guided orthopaedic surgery; medical imaging, modeling, and registration; and human-machine systems.

**1990-1995     IBM Research     Manager of Computer Assisted Surgery Group**

Technical direction and leadership for research group (5 PhD's, 1 Engineer, 1 coop student) in medical robotics and computer assisted surgery. Specific activities included orthopaedics, craniofacial surgery, image guided telerobotic systems for minimally invasive surgery, and image-based modeling and analysis. Set strategy and research agenda, contributed key technical ideas, participated/led in implementations and negotiated relations with outside organizations. Led successful effort to secure \$2M NIST ATP support for a joint IBM/Integrated Surgical Systems project to develop system for revision hip replacement surgery, and subsequently was principal investigator for IBM's part of the project..

**1989-1990      IBM Research                      Research Staff Member/Project Leader**

Developed "Robodoc" a robotic system for precise orthopaedic surgery, and transferred it to clinical collaborators at the University of California at Davis and, subsequently, to a startup company (Integrated Surgical Systems, Inc..) for commercial development. This system is now marketed in Europe and is pending FDA approval in the US. Also, established a broader research program on medical robotics and human-machine augmentation and initiated joint work on craniofacial surgery with NYU.

**1987-1988      IBM Research                      Manager of Automation Technology**

Department: Technical and administrative leadership for 22 researchers in robotics and vision; liaisons with key IBM manufacturing sites; continued technical research; and external professional activities with NSF, IEEE, etc. Department research themes included coarse-fine manipulation, endpoint sensing and control, computational architectures and programming environments for robotics and vision, massively parallel computation, model-based planning, and advanced applications.

**1982-1987      IBM Research                      Manager of Robot Systems and Technology**

Established 3-person research group in 1982 and grew it to a 15-person, three group department covering a broad spectrum of robotics research topics (see above). Activities included coarse-fine manipulation and endpoint sensing concepts, a multi-processor computational architecture for integrated sensing and control, and advanced applications for use inside IBM. Collaborated on AML/X extension to AML.

**1982              MIT AI Lab                      Visiting Scientist**

Co-developed "LMT" paradigm for automatic synthesis of manipulator fine motion strategies from analysis of configuration space. This paradigm has led to three generations of PhD theses on motion planning at several universities.

**1980-1982      IBM Research                      Research Staff Member**

Led effort that extended the RS/1 AML system to incorporate concurrent multiple arm control, vision, and a number of other features for research and advanced applications. Collaborated in development of robot for IBM clean rooms, led implementation of distributed controller architecture, and continued to advise IBM robot product group.

**1978-1979      IBM Boca Raton                      Advisory Engineer**

Product Architect for the IBM RS/1 and 7565 robot systems and product version of AML language.

**1976-1977      IBM Research                      Research Staff Member**

Principal designer and implementor of AML robot language. Other robotics research including bounded deviation straight line manipulator trajectories, application programming and sensor-based calibration techniques, and collaboration on a very sophisticated two-armed robot for testing IBM mainframes.

**1970-1976      Stanford University      Research Assistant**

Dissertation research on sensor-based fine motion synthesis; co-development of AL robot language and POINTY teaching system; extension of SAIL programming language.

**1968-1970     Johns Hopkins Univ.     Research Assistant**

Implementation of efficient codes for mathematical programming algorithms (mostly travelling salesman, multi-commodity network flow problems).