

Juan G. Victores

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1. David Estevez, Juan G. Victores, Raul Fernandez-Fernandez, and Carlos Balaguer. Enabling Garment-Agnostic Laundry Tasks For A Robot Household Companion. *Robotics and Autonomous Systems*, 123: 103330, jan 2020. ISSN 0921-8890. doi: 10.1016/j.robot.2019.103330. URL <https://doi.org/10.1016/j.robot.2019.103330> (Q2)
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13. Juan G. Victores, Santiago Morante, Alberto Jardón, and Carlos Balaguer. An Accessible Interface For Programming An Assistive Robot. *Journal of Accessibility and Design for All (JACCES)*, 4(3):161–176, 2014a. ISSN 2013-7087. doi: 10.17411/jacces.v4i3.49. URL <http://dx.doi.org/10.17411/jacces.v4i3.49>
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Patents (2)

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1. Raul Fernandez-Fernandez, Juan G. Victores, and Carlos Balaguer. New Trends and Challenges in the Automatic Generation of New Tasks for Humanoid Robots. In *Robocity16: Open Conference on Future Trends in Robotics*, pages 169–176. CSIC, Madrid, may 2016. ISBN 978-84-608-8452-1. URL <http://www.robocity2030.org/events/event/evento-esp-2-2/>
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1. Jennifer J. Gago, Valentina Vasco, Bartek Łukawski, Ugo Pattacini, Vadim Tikhanoff, Juan G. Victores, and Carlos Balaguer. Sequence-to-Sequence Natural Language to Humanoid Robot Sign Language. In *EUROSIM 2019*, page 44, Logroño, jul 2019b. ISBN 978-3-901608-92-6. doi: 10.11128/arep.58. URL <https://www.doi.org/10.11128/arep.58>
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Jan. 2019 Estancia de 3 meses destinado a la investigación del uso de Deep Learning para el estudio de conceptos abstractos con el robot iCub (Manchester, UK).
- Sept. 2011 – **Istituto Italiano di Tecnologia.** Department of Robotics, Brain and Cognitive Sciences.
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