

# Juan G. Victores

## Journal Articles (20)

1. Raul Fernandez-Fernandez, Juan G Victores, Jennifer J Gago, David Estevez, and Carlos Balaguer. Neural policy style transfer. *Cognitive Systems Research*, 72:23–32, 3 2022. ISSN 1389-0417. doi: 10.1016/j.cogsys.2021.11.003. URL <https://doi.org/10.1016/j.cogsys.2021.11.003> [robot] [xg-nitive: cgda] (Q2)
2. Andrea Gil Ruiz, Juan G Victores, Bartek Łukawski, and Carlos Balaguer. Design of an active vision system for high-level isolation units through q-learning. *Applied Sciences*, 10:5927, 8 2020. ISSN 2076-3417. doi: 10.3390/app10175927. URL <https://doi.org/10.3390/app10175927> [robot] [textiles: horus] (Q2)
3. David Estevez, Juan G. Victores, Raul Fernandez-Fernandez, and Carlos Balaguer. Enabling garment-agnostic laundry tasks for a robot household companion. *Robotics and Autonomous Systems*, 123: 103330, 1 2020. ISSN 0921-8890. doi: 10.1016/j.robot.2019.103330. URL <https://doi.org/10.1016/j.robot.2019.103330> [robot] [textiles: folding] [textiles: ironing] (Q2)
4. Alice Stazio, Juan G. Victores, David Estevez, and Carlos Balaguer. A study on machine vision techniques for the inspection of health personnels’ protective suits for the treatment of patients in extreme isolation. *Electronics*, 8:743, 6 2019. doi: 10.3390/electronics8070743. URL <https://doi.org/10.3390/electronics8070743> [robot] [textiles: horus] (Q2)
5. Jennifer J. Gago, Juan G. Victores, and Carlos Balaguer. Sign language representation by teo humanoid robot: End-user interest, comprehension and satisfaction. *Electronics*, 8:57, 1 2019a. ISSN 2079-9292. doi: 10.3390/electronics8010057. URL <https://doi.org/10.3390/electronics8010057> [robot] [sign-language] (Q2)
6. Raul Fernandez-Fernandez, Juan G. Victores, David Estevez, and Carlos Balaguer. Real evaluations tractability using continuous goal-directed actions in smart city applications. *Sensors*, 18:3818, 11 2018a. ISSN 1424-8220. doi: 10.3390/s18113818. URL <https://doi.org/10.3390/s18113818> [robot] [xgnitive: cgda] (Q1)
7. Santiago Martinez, Juan Miguel Garcia-Haro, Juan G. Victores, Alberto Jardon, and Carlos Balaguer. Experimental robot model adjustments based on force-torque sensor information. *Sensors*, 18:836, 3 2018. ISSN 14248220. doi: 10.3390/s18030836. URL <https://doi.org/10.3390/s18030836> [robot] [humanoid] (Q1)
8. Elisabeth Menendez, Juan G. Victores, Roberto Montero, Santiago Martínez, and Carlos Balaguer. Tunnel structural inspection and assessment using an autonomous robotic system. *Automation in Construction*, 87:117–126, 3 2018. ISSN 09265805. doi: 10.1016/j.autcon.2017.12.001. URL <https://doi.org/10.1016/j.autcon.2017.12.001> [robot] [construction] (Q1)
9. Eugenio Marinetto, Juan G. Victores, Mónica García-Sevilla, Mercedes Muñoz, Felipe Ángel Calvo, Carlos Balaguer, Manuel Desco, and Javier Pascau. Technical note: Mobile accelerator guidance using an optical tracker during docking in ioert procedures. *Medical Physics*, 44:5061–5069, 2017. ISSN 2473-4209. doi: 10.1002/mp.12482. URL <http://dx.doi.org/10.1002/mp.12482> [robot] [medical] (Q1)
10. Konstantinos Loupos, Anastasios D Doulamis, Christos Stentoumis, Eftychios Protopapadakis, Konstantinos Makantasis, Nikolaos D Doulamis, Angelos Amditis, Philippe Chrobocinski, Juan G. Victores, Roberto Montero, Elisabeth Menendez, Carlos Balaguer, Rafa Lopez, Miquel Cantero, Roman

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11. David Estevez, Juan G. Victores, Santiago Morante, and Carlos Balaguer. Robot devastation: Using diy low-cost platforms for multiplayer interaction in an augmented reality game. *EAI Endorsed Transactions on Collaborative Computing*, 15:1–5, 2015a. doi: 10.4108/icst.intetain.2015.259753. URL <http://dx.doi.org/10.4108/icst.intetain.2015.259753> [robot] [video-game]
  12. Santiago Morante, Juan G. Victores, and Carlos Balaguer. Cryptobotics: Why robots need cyber safety. *Frontiers in Robotics and AI*, 2:1–4, 2015a. doi: 10.3389/frobt.2015.00023. URL <http://dx.doi.org/10.3389/frobt.2015.00023> [robot] [cryptography]
  13. Roberto Montero, Juan G. Victores, Santiago Martínez, Alberto Jardón, and Carlos Balaguer. Past, present and future of robotic tunnel inspection. *Automation in Construction*, 59:99–112, 2015a. doi: 10.1016/j.autcon.2015.02.003. URL <http://dx.doi.org/10.1016/j.autcon.2015.02.003> [robot] [construction] (Q1)
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  15. Juan G. Victores, Santiago Morante, Alberto Jardón, and Carlos Balaguer. An accessible interface for programming an assistive robot. *Journal of Accessibility and Design for All (JACCES)*, 4:161–176, 2014a. ISSN 2013-7087. doi: 10.17411/jacces.v4i3.49. URL <http://dx.doi.org/10.17411/jacces.v4i3.49> [robot] [assistive]
  16. Jonathan Crespo, Ramon Barber, Juan G. Victores, and Alberto Jardón. Algorithm for graph visibility obtainment from a map of non-convex polygons. *Journal of Mechanical Engineering and Robotics Research*, 3:150–170, 2014. ISSN 2278-0149. URL [http://www.ijmerr.com/v3n2/ijmerr\\_v3n2\\_19.pdf](http://www.ijmerr.com/v3n2/ijmerr_v3n2_19.pdf) [robot] [planning]
  17. Santiago Martínez, Alberto Jardón, Juan G. Victores, and Carlos Balaguer. Flexible field factory for construction industry. *Assembly Automation*, 33:175–183, 2013. doi: 10.1108/01445151311306708. URL <http://dx.doi.org/10.1108/01445151311306708> [robot] [construction] (Q4)
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  19. Alberto Jardón, Juan G. Victores, Santiago Martínez, Antonio Giménez, and Carlos Balaguer. Personal autonomy rehabilitation in home environments by a portable assistive robot. *IEEE Trans. on Systems, Man, and Cybernetics, Part C: Applications and Reviews*, 42:561–570, 2011a. doi: 10.1109/TSMCC.2011.2159201. URL <http://dx.doi.org/10.1109/TSMCC.2011.2159201> [robot] [assistive] (Q1)
  20. Juan G. Victores, Santiago Martinez, Alberto Jardón, and Carlos Balaguer. Robot-aided tunnel inspection and maintenance system by vision and proximity sensor integration. *Automation in Construction*, 20:629–636, 2011a. ISSN 09265805. doi: 10.1016/j.autcon.2010.12.005. URL <http://dx.doi.org/10.1016/j.autcon.2010.12.005> [robot] [construction] (Q1)

## Patents (2)

1. Alberto Jardón Huete, Santiago Martínez, Juan G. Victores, Carlos Balaguer, Rafael Portero, and Marc Martí. Sistema y método para la verificación de la trayectoria de un tunel, 2014. URL <http://invenes.oepm.es/InvenesWeb/detalle?referencia=P201330794> [robot] [construction]
2. Juan G. Victores, Santiago Martinez, Alberto Jardón, and Carlos Balaguer. Tool and method for the automatic remote application of strips of fibre-reinforced polymer tape, comprising the dispensing of epoxy adhesive, 2011b. URL <http://www.google.im/patents/WO2011138481A1?c1=en> [robot] [construction]

## Book Chapters (8)

1. Raul Fernandez-Fernandez, Juan G. Victores, and Carlos Balaguer. New trends and challenges in the automatic generation of new tasks for humanoid robots. pages 169–176. CSIC, 5 2016. ISBN 978-84-608-8452-1. URL <http://www.robocity2030.org/events/event/evento-esp-2-2/> [xgnitive: cgda]
2. David Estevez, Juan G. Victores, and Carlos Balaguer. A new generation of entertainment robots enhanced with augmented reality. pages 129–136. CSIC, 5 2016a. URL <http://www.robocity2030.org/events/event/evento-esp-2-2/> [robot] [video-game]
3. David Estevez, Juan G. Victores, and Carlos Balaguer. Future trends in perception and manipulation for unfolding and folding garments. pages 333–340. CSIC, 5 2016b. URL <http://www.robocity2030.org/events/event/evento-esp-2-2/> [robot] [textiles: folding]
4. Roberto Montero, Juan G. Victores, Elisabeth Menéndez, and Carlos Balaguer. The robot-spect eu project: Autonomous robotic tunnel inspection. pages 91–100. 2015b. URL <http://www.robocity2030.org/events/event/13th-robocity2030-workshop/> [robot] [construction]
5. Santiago Morante, Juan G. Victores, Santiago Martínez, and Carlos Balaguer. Force-sensorless friction and gravity compensation for robots. volume 418. Springer International Publishing, 2015c. ISBN 9783319271484. doi: 10.1007/978-3-319-27149-1\_5. URL [http://doi.org/10.1007/978-3-319-27149-1\\_5](http://doi.org/10.1007/978-3-319-27149-1_5) [robot] [modelling]
6. Alberto Jardón, Félix R. Cañadillas, Juan G. Victores, Santiago Martínez, and Carlos Balaguer. A review of eight years of ceabot contest: A national wide mini humanoids competition. pages 41–52. Springer International Publishing, 2014a. ISBN 978-3-319-03652-6. doi: 10.1007/978-3-319-03653-3\_4. URL [http://dx.doi.org/10.1007/978-3-319-03653-3\\_4](http://dx.doi.org/10.1007/978-3-319-03653-3_4) [robot] [contests]
7. Juan G. Victores, Félix R. Cañadillas, Santiago Morante, Alberto Jardón, and Carlos Balaguer. Assistive robot multi-modal interaction with augmented 3d vision and dialogue. pages 209–217. Springer International Publishing, 2014b. ISBN 978-3-319-03412-6. doi: 10.1007/978-3-319-03413-3\_15. URL [http://dx.doi.org/10.1007/978-3-319-03413-3\\_15](http://dx.doi.org/10.1007/978-3-319-03413-3_15) [robot] [assistive]
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2. Jennifer J. Gago, Valentina Vasco, Bartek Łukawski, Ugo Pattacini, Vadim Tikhanoff, Juan G. Victores, and Carlos Balaguer. Sequence-to-sequence natural language to humanoid robot sign language. page 44. ARGESIM, 7 2019b. ISBN 978-3-901608-92-6. doi: 10.11128/arep.58. URL <https://www.doi.org/10.11128/arep.58> [robot] [sign-language]
3. David Estevez, Juan G. Victores, Raul Fernandez-Fernandez, and Carlos Balaguer. Towards clothes hanging via cloth simulation and deep convolutional networks. page 35. ARGESIM, 7 2019. ISBN 978-3-901608-92-6. doi: 10.11128/arep.58. URL <https://www.doi.org/10.11128/arep.58> [robot] [textiles: hanging]
4. Raul Fernandez-Fernandez, Juan G. Victores, David Estevez, and Carlos Balaguer. Quick, stat!: A statistical analysis of the quick, draw! dataset. page 27. ARGESIM, 7 2019. ISBN 978-3-901608-92-6. doi: 10.11128/arep.58. URL <https://www.doi.org/10.11128/arep.58> [robot] [xgnitive: drl]
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6. Raul Fernandez-Fernandez, Juan G. Victores, David Estevez, and Carlos Balaguer. Robot imitation through vision, kinesthetic and force features with online adaptation to changing environments. pages 6546–6551. IEEE, 2018b. ISBN 978-1-5386-8094-0. doi: IROS.2018.8593724. URL <https://doi.org/10.1109/IROS.2018.8593724> [robot] [xgnitive: cgda]
7. David Estevez, Juan G. Victores, Raul Fernandez-Fernandez, and Carlos Balaguer. Robotic ironing with 3d perception and force/torque feedback in household environments. volume 2017-Sept, pages 6484–6489. IEEE, 2017a. ISBN 9781538626818. doi: 10.1109/IROS.2017.8206556. URL <https://doi.org/10.1109/IROS.2017.8206556> [robot] [textiles: ironing]
8. Elisabeth Menendez, Juan G. Victores, and Carlos Balaguer. Sistema robótico para la inspección y análisis estructural de túneles. 2017a. URL <http://jnr2017.ai2.upv.es/wp-content/uploads/2016/11/Programa-JNR2017.pdf> [robot] [construction]
9. David Estevez, Juan G. Victores, and Carlos Balaguer. Horus: Inspección robotizada de los trajes de protección del personal sanitario de pacientes en aislamiento de alto nivel, incluido el Ébola. 2017b [robot] [horus]
10. Elisabeth Menendez, Juan G. Victores, Roberto Montero, and Carlos Balaguer. Autonomous robotic system with tunnel inspection tool positioning. pages 655–662, 2017b. URL <https://doi.org/10.22260/ISARC2017/0091> [robot] [construction]
11. Roberto Montero, Elisabeth Menendez, Juan G. Victores, and Carlos Balaguer. Intelligent robotic system for autonomous crack detection and characterization in concrete tunnels. pages 316–321. IEEE, 2017. ISBN 9781509062331. doi: 10.1109/ICARSC.2017.7964094. URL <https://doi.org/10.1109/ICARSC.2017.7964094> [robot] [construction]
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1. Juan G Victores, Santiago Morante, Alberto Jardón, and Carlos Balaguer. On using humanoid robot imagination to perform the shortened token test. page 172. IEEE, 2014c. doi: 10.1109/HUMANOIDS.2014.7041355. URL <https://youtu.be/KFHFw9dJfzA> [robot] [xgnitive: ris]
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## PhD Thesis (Author)

1. Juan G. Victores. *Robot Imagination System*. PhD thesis, 2014. URL <http://e-archivo.uc3m.es/handle/10016/19834>

## PhD Thesis (Advisor)

1. Santiago Morante. *Continuous Goal-Directed Actions: Advances in Robot Learning*. PhD thesis, Universidad Carlos III de Madrid, mar 2016. URL <http://e-archivo.uc3m.es/handle/10016/23459>

## Research Stays (2)

- |              |  |
|--------------|--|
| Oct. 2018 –  | <b>The University of Manchester.</b> Cognitive Robotics Lab.   |
| Jan. 2019    | Estancia de 3 meses destinado a la investigación del uso de Deep Learning para el estudio de conceptos abstractos con el robot iCub (Manchester, UK).              |
| Sept. 2011 – | <b>Istituto Italiano di Tecnologia.</b> Department of Robotics, Brain and Cognitive Sciences.  |
| Dic. 2011    | Estancia de 3 meses destinado a la investigación del uso de Support Vector Machines y Gaussianas mixtas para el control en fuerza del robot iCub (Génova, Italia). |

## Workshop Organizer (2)

1. Juan G. Victores, Lorenzo Natale, Eiichi Yoshida. Towards Humanoid Robots OS. HUMANOIDS. Cancun, Mexico. Nov 15. 2016. <https://roboticslab-uc3m.github.io/workshop-humanoids2016/>
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## Talks (2)

1. Juan G. Victores. XGNITIVE: Avances hacia la generalización avanzada de acciones y sistemas de imaginación en robótica. Technology Festival (Techfest). Universidad Rey Juan Carlos (URJC). 2017. <https://www.eventbrite.es/e/registro-technology-festival-urjc-2017-28838850779?aff=es2#>
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