

Juan G. Victores

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1. Raul Fernandez-Fernandez, Juan G. Victores, David Estevez, and Carlos Balaguer. Real Evaluations Tractability using Continuous Goal-Directed Actions in Smart City Applications. *Sensors*, 18(11):3818, nov 2018a. ISSN 1424-8220. doi: 10.3390/s18113818. URL <https://doi.org/10.3390/s18113818> (Q1)
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5. Konstantinos Loupos, Anastasios D Doulamis, Christos Stentoumis, Eftychios Protopapadakis, Konstantinos Makantasis, Nikolaos D Doulamis, Angelos Amditis, Philippe Chrobocinski, Juan G. Victores, Roberto Montero, Elisabeth Menendez, Carlos Balaguer, Rafa Lopez, Miquel Cantero, Roman Navarro, Alberto Roncaglia, Luca Belsito, Stephanos Camarinopoulos, Nikolaos Komodakis, and Praveer Singh. Autonomous robotic system for tunnel structural inspection and assessment. *International Journal of Intelligent Robotics and Applications*, pages 1–24, 2017. ISSN 2366-598X. doi: 10.1007/s41315-017-0031-9. URL <https://doi.org/10.1007/s41315-017-0031-9>
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3. Elisabeth Menendez, Juan G. Victores, and Carlos Balaguer. Sistema robótico para la inspección y análisis estructural de túneles. In *Jornadas Nacionales de Robótica*, 2017a. URL <http://jnr2017.ai2.upv.es/wp-content/uploads/2016/11/Programa-JNR2017.pdf>
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15. Konstantinos Loupos, Angelos Amditis, Christos Stentoumis, Juan G. Victores, Philippe Chrobocinski, Alberto Roncaglia, Stephanos Camarinopoulos, Nikos Komodakis, and Rafael Lopez. Robotic System with Intelligent Vision for Tunnel Structural Assessment - System Architecture – The ROBO-SPECT EC project. In *Third conference on smart monitoring, assessment and rehabilitation of civil structures (SMAR)*, 2015
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Conference Videos (2)

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Research Stays (2)

- Oct. 2018 – **The University of Manchester**. Cognitive Robotics Lab.
Jan. 2019 Estancia de 3 meses destinado a la investigación del uso de Deep Learning para el estudio de conceptos abstractos con el robot iCub (Manchester, UK).
- Sept. 2011 – **Istituto Italiano di Tecnologia**. Department of Robotics, Brain and Cognitive Sciences.
Dic. 2011 Estancia de 3 meses destinado a la investigación del uso de Support Vector Machines y Gaussianas mixtas para el control en fuerza del robot iCub (Génova, Italia).

Workshop Organizer (2)

1. Juan G. Victores, Lorenzo Natale, Eiichi Yoshida. Towards Humanoid Robots OS. HUMANOIDS. Cancun, Mexico. Nov 15. 2016. <https://roboticslab-uc3m.github.io/workshop-humanoids2016/>
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