

Juan G. Victores

Journal Articles (15)

1. Raul Fernandez-Fernandez, Juan G. Victores, David Estevez, and Carlos Balaguer. Real Evaluations Tractability using Continuous Goal-Directed Actions in Smart City Applications. *Sensors*, 18(11):3818, nov 2018a. ISSN 1424-8220. doi: 10.3390/s18113818. URL <https://doi.org/10.3390/s18113818> (Q1)
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4. Eugenio Marinetto, Juan G. Victores, Mónica García-Sevilla, Mercedes Muñoz, Felipe Ángel Calvo, Carlos Balaguer, Manuel Desco, and Javier Pascau. Technical Note: Mobile accelerator guidance using an optical tracker during docking in IOERT procedures. *Medical Physics*, 44(10):5061–5069, 2017. ISSN 2473-4209. doi: 10.1002/mp.12482. URL <http://dx.doi.org/10.1002/mp.12482> (Q1)
5. Konstantinos Loupos, Anastasios D Doulamis, Christos Stentoumis, Eftychios Protopapadakis, Konstantinos Makantasis, Nikolaos D Doulamis, Angelos Amditis, Philippe Chrobocinski, Juan G. Victores, Roberto Montero, Elisabeth Menendez, Carlos Balaguer, Rafa Lopez, Miquel Cantero, Roman Navarro, Alberto Roncaglia, Luca Belsito, Stephanos Camarinopoulos, Nikolaos Komodakis, and Praveer Singh. Autonomous robotic system for tunnel structural inspection and assessment. *International Journal of Intelligent Robotics and Applications*, pages 1–24, 2017. ISSN 2366-598X. doi: 10.1007/s41315-017-0031-9. URL <https://doi.org/10.1007/s41315-017-0031-9>
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Patents (2)

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7. Juan G. Victores, Félix R. Cañadillas, Santiago Morante, Alberto Jardón, and Carlos Balaguer. Assistive Robot Multi-modal Interaction with Augmented 3D Vision and Dialogue. In Manuel A. Armada, Alberto Sanfeliu, and Manuel Ferre, editors, *ROBOT2013: First Iberian Robotics Conference*, pages 209–217. Springer International Publishing, Madrid, 2014b. ISBN 978-3-319-03412-6. doi: 10.1007/978-3-319-03413-3-15. URL <http://dx.doi.org/10.1007/978-3-319-03413-3-15>
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1. Raul Fernandez-Fernandez, Juan G. Victores, David Estevez, and Carlos Balaguer. Robot Imitation through Vision, Kinesthetic and Force Features with Online Adaptation to Changing Environments. In *2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, pages 6546–6551, Madrid, 2018b. IEEE. ISBN 978-1-5386-8093-3. doi: IROS.2018.8593724. URL <https://doi.org/10.1109/IROS.2018.8593724>
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15. Konstantinos Loupos, Angelos Amditis, Christos Stentoumis, Juan G. Victores, Philippe Chrobocinski, Alberto Roncaglia, Stephanos Camarinopoulos, Nikos Komodakis, and Rafael Lopez. Robotic System with Intelligent Vision for Tunnel Structural Assessment - System Architecture – The ROBO-SPECT EC project. In *Third conference on smart monitoring, assessment and rehabilitation of civil structures (SMAR)*, 2015

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Conference Videos (2)

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2. Santiago Morante, Juan G Victores, Santiago Martinez de la casa, and Carlos Balaguer. Sensorless Friction and Gravity Compensation. In *IEEE RAS International Conference on Humanoid Robots (Humanoids 2014)*, page 265, Madrid, 2014c. IEEE. doi: 10.1109/HUMANOIDS.2014.7041370. URL <https://dx.doi.org/10.1109/HUMANOIDS.2014.7041370><https://youtu.be/-fjHQA7FhU0>

PhD Thesis (Author)

1. Juan G. Victores. *Robot Imagination System*. PhD thesis, Universidad Carlos III de Madrid, 2014. URL <http://e-archivo.uc3m.es/handle/10016/19834>

PhD Thesis (Advisor)

1. Santiago Morante. *Continuous Goal-Directed Actions: Advances in Robot Learning*. PhD thesis, Universidad Carlos III de Madrid, mar 2016. URL <http://e-archivo.uc3m.es/handle/10016/23459>

Research Stays (2)

- | | |
|--------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Oct. 2018 – | The University of Manchester. Cognitive Robotics Lab. |
| Jan. 2019 | Estancia de 3 meses destinado a la investigación del uso de Deep Learning para el estudio de conceptos abstractos con el robot iCub (Manchester, UK). |
| Sept. 2011 – | Istituto Italiano di Tecnologia. Department of Robotics, Brain and Cognitive Sciences. |
| Dic. 2011 | Estancia de 3 meses destinado a la investigación del uso de Support Vector Machines y Gaussianas mixtas para el control en fuerza del robot iCub (Génova, Italia). |

Workshop Organizer (2)

1. Juan G. Victores, Lorenzo Natale, Eiichi Yoshida. Towards Humanoid Robots OS. HUMANOIDS. Cancun, Mexico. Nov 15. 2016. <https://roboticslab-uc3m.github.io/workshop-humanoids2016/>
2. Angelos Amditis, Konstantinos Loupos, Juan G. Victores. Autonomous Robotic Systems for Inspection and Structural Assessment of Civil Underground Infrastructures. European Robotics Forum (ERF). Ljubljana, Slovenia. Mar 22. 2016. https://www.eu-robotics.net/robotics_forum/upload/digest_1-96_without_emails_250ppi1.pdf

Talks (2)

1. Juan G. Victores. XGNITIVE: Avances hacia la generalización avanzada de acciones y sistemas de imaginación en robótica. Technology Festival (Techfest). Universidad Rey Juan Carlos (URJC). 2017. <https://www.eventbrite.es/e/registro-technology-festival-urjc-2017-28838850779?aff=es2#>

2. Angelos Amditis, Juan G. Victores, Fedi Francesco. Welcome and Introduction. Autonomous Robotic Systems for Inspection and Structural Assessment of Civil Underground Infrastructures. European Robotics Forum (ERF). Ljubljana, Slovenia. Mar 22. 2016. https://www.eu-robotics.net/robotics_forum/upload/digest_1-96_without_emails_250ppi1.pdf