Inicialização do objeto RadarSImulator

radobj = RadarSimulator;

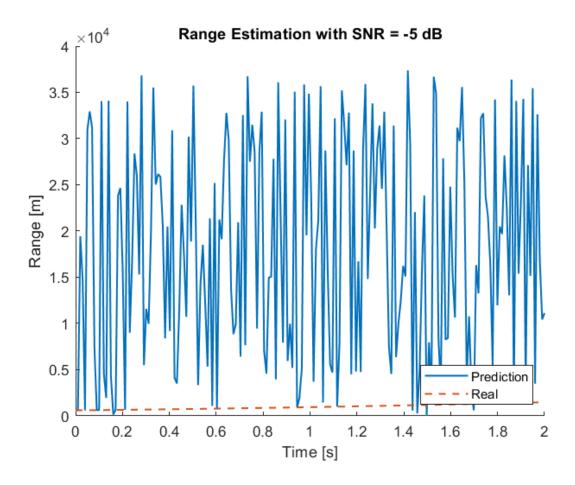
```
ans =
  RadarSimulator with properties:
               antenna rpm: 12
             beam_aperture: 3
                         c: 300000000
                    dcycle: 0.0040
                      dSNR: 20
                      dvdt: 0
                        fp: 100000000
                        Gt: 1
                        Gr: 1
                        L: 6
                     Nofig: 0
                        Pt: 100000
                        R: 600
                     Sigma: 1
               SimDuration: 2
                       Tp: 1.0000e-06
                       V 0: 100
              acceleration: 30
    npulses per prediction: 100
                rangegates: [1×1250 double]
                 range_res: 30
                        fs: 5000000
                        gd: 4
                      hant: [1x1 phased.IsotropicAntennaElement]
                      hcol: [1x1 phased.Collector]
                      hmf: [1x1 phased.MatchedFilter]
                      hrad: [1x1 phased.Radiator]
                      hrec: [1x1 phased.ReceiverPreamp]
                    hspace: [1x1 phased.FreeSpace]
                      htgt: [1x1 phased.RadarTarget]
                  htgtplat: [1x1 phased.Platform]
                       htx: [1x1 phased.Transmitter]
                   htxplat: [1x1 phased.Platform]
                      hwav: [1x1 phased.RectangularWaveform]
                      lamb: 3
                 max_range: 37500
                 max_speed: 3000
                        No: 8.7904e-12
                    Notemp: 6.3668e+05
                    npulse: []
             n predictions: []
                       PRF: 4000
                       PRI: 2.5000e-04
                     rxsig: [1250×100×0 double]
                    sigrad: []
                     sigtx: [1250×1 double]
                    sigwav: [1250×1 double]
                 speed_res: 60
                    tgtpos: [3×1 double]
                    tgtvel: [3×1 double]
                    tgtang: [2×1 double]
                     txpos: [3×1 double]
```

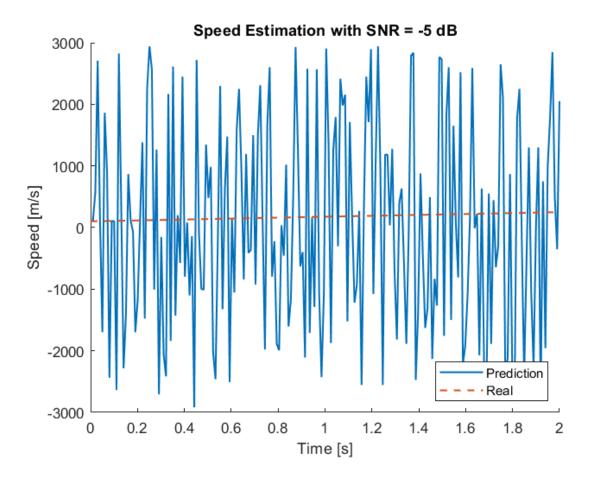
txstatus: [1250×1 logical]
 txvel: [3×1 double]

sim_duration = 5; % time in seconds to simulate.

SNR = -5 dB.

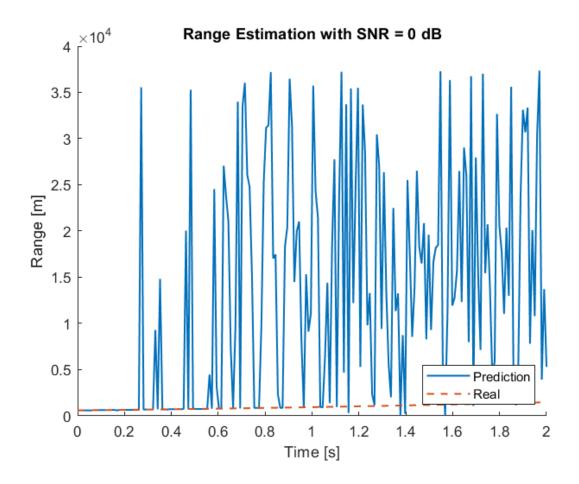
```
radobj.dSNR = -5; % dB
radobj = update_parameters(radobj);
result_struct_0 = runSim(radobj, sim_duration);
RadarSimulator.plot_range_speed_pred(result_struct_0, radobj)
```

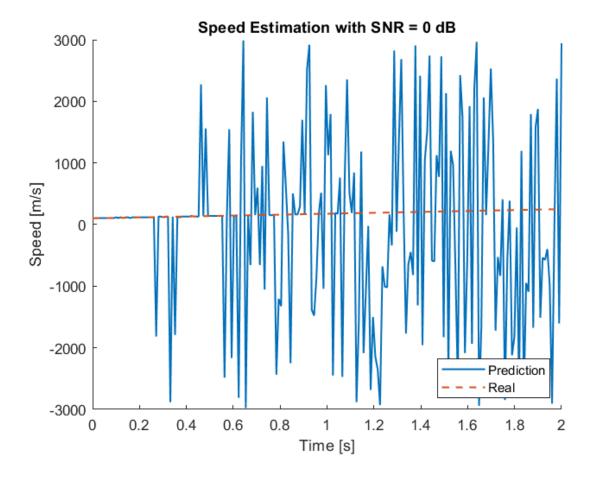




SNR = 0 dB.

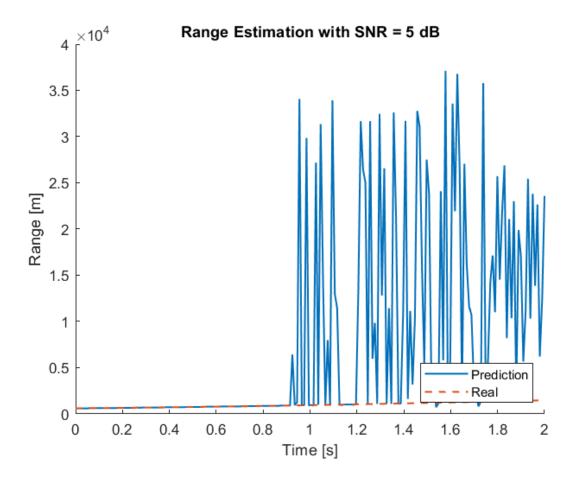
```
radobj.dSNR = 0; % dB
radobj = update_parameters(radobj);
result_struct_1 = runSim(radobj, sim_duration);
RadarSimulator.plot_range_speed_pred(result_struct_1, radobj)
```

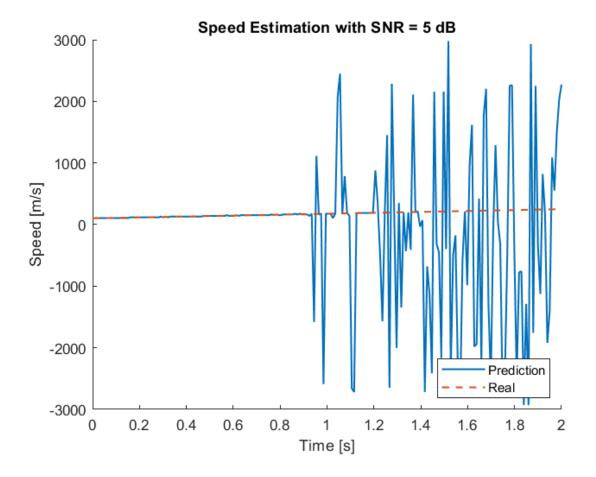




SNR = 5 dB.

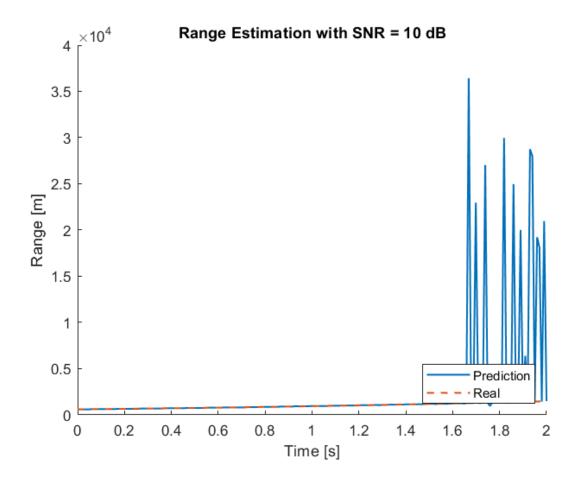
```
radobj.dSNR = 5; % dB
radobj = update_parameters(radobj);
result_struct_2 = runSim(radobj, sim_duration);
RadarSimulator.plot_range_speed_pred(result_struct_2, radobj)
```

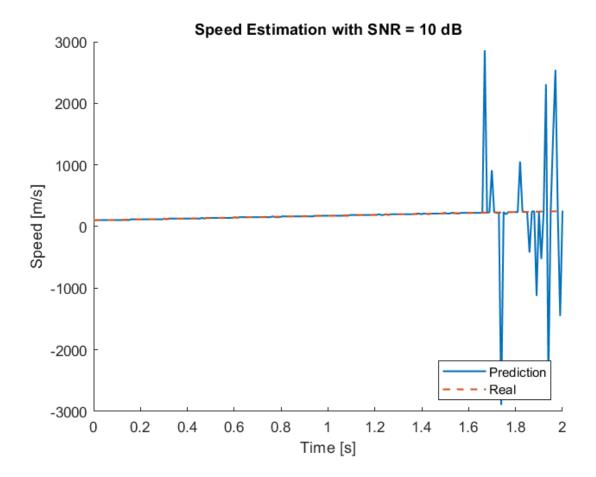




SNR = 10 dB.

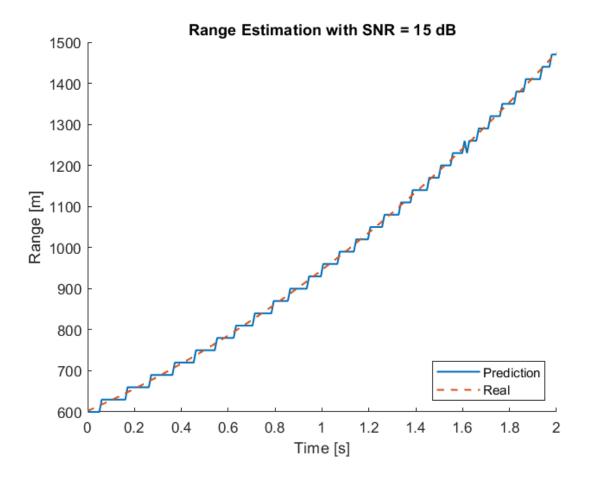
```
radobj.dSNR = 10; % dB
radobj = update_parameters(radobj);
result_struct_3 = runSim(radobj, sim_duration);
RadarSimulator.plot_range_speed_pred(result_struct_3, radobj)
```

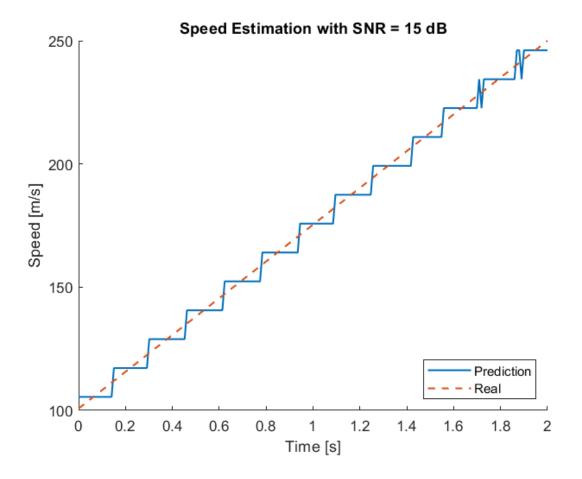




SNR = 15 dB.

```
radobj.dSNR = 15; % dB
radobj = update_parameters(radobj);
result_struct_4 = runSim(radobj, sim_duration);
RadarSimulator.plot_range_speed_pred(result_struct_4, radobj)
```





SNR = 20 dB.

```
radobj.dSNR = 20; % dB
radobj = update_parameters(radobj);
result_struct_5 = runSim(radobj, sim_duration);
RadarSimulator.plot_range_speed_pred(result_struct_5, radobj)
```

