General information

In this kernel I work with a dataset for the Food Recognition Challenge conducted on Alcrowd hosted here: https://www.aicrowd.com/challenges/food-recognition-challenge.

This is a novel dataset of food images collected through the MyFoodRepo app where numerous volunteer Swiss users provide images of their daily food intake in the context of a digital cohort called Food & You. This growing data set has been annotated - or automatic annotations have been verified - with respect to segmentation, classification (mapping the individual food items onto an ontology of Swiss Food items), and weight / volume estimation.

This is an evolving dataset, where we will release more data as the dataset grows over time.

In this kernel I'll show how to set up environment for this challenge, provide EDA and possible in future show baseline modelling.

The code is based on this notebook by organizers:

https://colab.research.google.com/drive/1A5p9GX5X3n6OMtLjfhnH6Oeq13tWNtFO#scrollTo=lkjrKJfIVCM3

Setting up environment

There are several steps which need to be done:

- install certain versions of numpy, tensorflow, keras
- clone the Mask_RCNN repo
- install requirements and the repo itself
- the utils reqires json with annotations to be called annotation.json, but we have annotations.json; so I copy the whole data and copy this file with a new name

```
!rm -rf images assets
!pip install numpy==1.17.0
!pip install tensorflow==1.15.2
!pip install keras==2.1.0
Collecting numpy==1.17.0
  Downloading numpy-1.17.0-cp36-cp36m-manylinux1 x86 64.whl (20.4 MB)
ERROR: mizani 0.6.0 has requirement matplotlib>=3.1.1, but you'll have
matplotlib 3.0.3 which is incompatible.
ERROR: kmeans-smote 0.1.2 has requirement imbalanced-
learn<0.5,>=0.4.0, but you'll have imbalanced-learn 0.6.2 which is
incompatible.
ERROR: kmeans-smote 0.1.2 has requirement numpy<1.16,>=1.13, but
you'll have numpy 1.17.0 which is incompatible.
ERROR: kmeans-smote 0.1.2 has requirement scikit-learn<0.21,>=0.19.0,
but you'll have scikit-learn 0.22.2.post1 which is incompatible.
ERROR: hypertools 0.6.2 has requirement scikit-learn<0.22,>=0.19.1,
but you'll have scikit-learn 0.22.2.post1 which is incompatible.
ERROR: hyperopt 0.2.3 has requirement networkx==2.2, but you'll have
networkx 2.4 which is incompatible.
ERROR: dask-ml 1.2.0 has requirement numpy>=1.17.3, but you'll have
numpy 1.17.0 which is incompatible.
ERROR: allennlp 0.9.0 has requirement spacy<2.2,>=2.1.0, but you'll
have spacy 2.2.3 which is incompatible.
ру
 Attempting uninstall: numpy
    Found existing installation: numpy 1.18.1
    Uninstalling numpy-1.18.1:
      Successfully uninstalled numpy-1.18.1
Successfully installed numpy-1.17.0
Collecting tensorflow==1.15.2
  Downloading tensorflow-1.15.2-cp36-cp36m-manylinux2010 x86 64.whl
(110.5 MB)
ent already satisfied: google-pasta>=0.1.6 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(0.1.8)
Collecting tensorboard<1.16.0,>=1.15.0
  Downloading tensorboard-1.15.0-py3-none-any.whl (3.8 MB)
ent already satisfied: keras-preprocessing>=1.0.5 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(1.1.0)
Requirement already satisfied: gast==0.2.2 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(0.2.2)
Requirement already satisfied: wrapt>=1.11.1 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(1.11.2)
Collecting tensorflow-estimator==1.15.1
  Downloading tensorflow estimator-1.15.1-py2.py3-none-any.whl (503)
kB)
```

```
ent already satisfied: six>=1.10.0 in /opt/conda/lib/python3.6/site-
packages (from tensorflow==1.15.2) (1.14.0)
Requirement already satisfied: astor>=0.6.0 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(0.8.1)
Requirement already satisfied: keras-applications>=1.0.8 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(1.0.8)
Requirement already satisfied: protobuf>=3.6.1 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(3.11.3)
Requirement already satisfied: opt-einsum>=2.3.2 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
Requirement already satisfied: wheel>=0.26; python version >= "3"
in /opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
Requirement already satisfied: numpy<2.0,>=1.16.0 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(1.17.0)
Requirement already satisfied: termcolor>=1.1.0 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(1.1.0)
Requirement already satisfied: absl-py>=0.7.0 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(0.9.0)
Requirement already satisfied: grpcio>=1.8.6 in
/opt/conda/lib/python3.6/site-packages (from tensorflow==1.15.2)
(1.27.2)
Requirement already satisfied: setuptools>=41.0.0 in
/opt/conda/lib/python3.6/site-packages (from
tensorboard<1.16.0,>=1.15.0->tensorflow==1.15.2) (45.2.0.post20200210)
Requirement already satisfied: markdown>=2.6.8 in
/opt/conda/lib/python3.6/site-packages (from
tensorboard<1.16.0,>=1.15.0->tensorflow==1.15.2) (3.2.1)
Requirement already satisfied: werkzeug>=0.11.15 in
/opt/conda/lib/python3.6/site-packages (from
tensorboard<1.16.0,>=1.15.0->tensorflow==1.15.2) (1.0.0)
Requirement already satisfied: h5py in /opt/conda/lib/python3.6/site-
packages (from keras-applications>=1.0.8->tensorflow==1.15.2) (2.10.0)
Installing collected packages: tensorboard, tensorflow-estimator,
tensorflow
  Attempting uninstall: tensorboard
    Found existing installation: tensorboard 2.1.1
    Uninstalling tensorboard-2.1.1:
      Successfully uninstalled tensorboard-2.1.1
 Attempting uninstall: tensorflow-estimator
```

```
Found existing installation: tensorflow-estimator 2.1.0
    Uninstalling tensorflow-estimator-2.1.0:
      Successfully uninstalled tensorflow-estimator-2.1.0
  Attempting uninstall: tensorflow
    Found existing installation: tensorflow 2.1.0
    Uninstalling tensorflow-2.1.0:
      Successfully uninstalled tensorflow-2.1.0
Successfully installed tensorboard-1.15.0 tensorflow-1.15.2
tensorflow-estimator-1.15.1
Collecting keras==2.1.0
  Downloading Keras-2.1.0-py2.py3-none-any.whl (302 kB)
ent already satisfied: scipy>=0.14 in /opt/conda/lib/python3.6/site-
packages (from keras=2.1.0) (1.4.1)
Requirement already satisfied: six>=1.9.0 in
/opt/conda/lib/python3.6/site-packages (from keras==2.1.0) (1.14.0)
Requirement already satisfied: numpy>=1.9.1 in
/opt/conda/lib/python3.6/site-packages (from keras==2.1.0) (1.17.0)
Requirement already satisfied: pyyaml in
/opt/conda/lib/python3.6/site-packages (from keras==2.1.0) (5.3)
ERROR: keras-resnet 0.2.0 has requirement keras>=2.2.4, but you'll
have keras 2.1.0 which is incompatible.
ERROR: conx 3.7.10 has requirement keras>=2.1.3, but you'll have keras
2.1.0 which is incompatible.
Installing collected packages: keras
  Attempting uninstall: keras
    Found existing installation: Keras 2.3.1
    Uninstalling Keras-2.3.1:
      Successfully uninstalled Keras-2.3.1
Successfully installed keras-2.1.0
import os
DATA DIR = '/kaggle/working/food-recognition-challenge'
# Directory to save logs and trained model
ROOT DIR = ''
!git clone https://www.github.com/matterport/Mask RCNN.git
os.chdir('Mask RCNN')
!pip install -q -r requirements.txt
!python setup.py -q install
Cloning into 'Mask RCNN'...
remote: Enumerating objects: 956, done.ote: Total 956 (delta 0),
reused 0 (delta 0), pack-reused 956
!pip uninstall pycocotools -y
!pip install -q
qit+https://github.com/waleedka/coco.git#subdirectory=PythonAPI
WARNING: Skipping pycocotools as it is not installed.
```

import libraries

```
import sys
sys.path.append(os.path.join('.', 'Mask_RCNN')) # To find local
version of the library
sys.path.append(ROOT DIR)
import sys
import re
import random
import pandas as pd
import os
import numpy as np
import mrcnn.model as modellib
import matplotlib.pyplot as plt
import matplotlib.patches as patches
import matplotlib.lines as lines
import matplotlib
import math
import logging
import json
import itertools
import glob
import cv2
from tgdm import tgdm
from pycocotools.cocoeval import COCOeval
from pycocotools.coco import COCO
from pycocotools import mask as maskUtils
from mrcnn.model import log
from mrcnn.config import Config
from mrcnn import visualize
from mrcnn import utils
from matplotlib.patches import Polygon
from imgaug import augmenters as iaa
from collections import defaultdict, Counter
from collections import OrderedDict
ROOT DIR = os.path.abspath(".")
Using TensorFlow backend.
```

Defining dataset class and config

```
or if only a small subset of the same
should be loaded into memory
        self.load small = load small
        if self.load small:
            annotation path = os.path.join(dataset dir, "annotation-
small.json")
        else:
            annotation path = os.path.join(dataset dir,
"annotations.json")
        image dir = os.path.join(dataset dir, "images")
        print("Annotation Path ", annotation path)
        print("Image Dir ", image dir)
        assert os.path.exists(annotation path) and
os.path.exists(image dir)
        self.coco = COCO(annotation path)
        self.image dir = image dir
        # Load all classes (Only Building in this version)
        classIds = self.coco.getCatIds()
        # Load all images
        image ids = list(self.coco.imgs.keys())
        # register classes
        for _class id in classIds:
            self.add class("crowdai-food-challenge", class id,
self.coco.loadCats( class id)[0]["name"])
        # Register Images
        for img id in image ids:
            assert(os.path.exists(os.path.join(image dir,
self.coco.imgs[_img_id]['file_name'])))
            self.add image(
                "crowdai-food-challenge", image id= img id,
                path=os.path.join(image dir, self.coco.imgs[ img id]
['file name']),
                width=self.coco.imgs[ img id]["width"],
                height=self.coco.imgs[ img id]["height"],
                annotations=self.coco.loadAnns(self.coco.getAnnIds(
                                            imgIds=[ img id],
                                            catIds=classIds,
                                            iscrowd=None)))
        if return coco:
            return self.coco
    def load mask(self, image id):
```

```
""" Loads instance mask for a given image
              This function converts mask from the coco format to a
              a bitmap [height, width, instance]
            Params:
                - image id : reference id for a given image
            Returns:
                masks : A bool array of shape [height, width,
instances | with
                    one mask per instance
                class_ids : a 1D array of classIds of the
corresponding instance masks
                    (In this version of the challenge it will be of
shape [instances] and always be filled with the class-id of the
"Building" class.)
        image info = self.image info[image id]
        assert image info["source"] == "crowdai-food-challenge"
        instance masks = []
        class ids = []
        annotations = self.image info[image id]["annotations"]
        # Build mask of shape [height, width, instance_count] and list
        # of class IDs that correspond to each channel of the mask.
        for annotation in annotations:
            class id = self.map source class id(
                "crowdai-food-challenge.
{}".format(annotation['category id']))
            if class id:
                m = self.annToMask(annotation,
                                                image info["height"],
                                                image info["width"])
                # Some objects are so small that they re less than 1
pixel area
                # and end up rounded out. Skip those objects.
                if m.max() < 1:
                    continue
                # Ignore the notion of "is crowd" as specified in the
coco format
                # as we donot have the said annotation in the current
version of the dataset
                instance masks.append(m)
                class ids.append(class id)
        # Pack instance masks into an array
        if class ids:
            mask = np.stack(instance masks, axis=2)
            class ids = np.array(class ids, dtype=np.int32)
            return mask, class ids
```

```
else:
            # Call super class to return an empty mask
            return super(FoodChallengeDataset,
self).load mask(image id)
    def image reference(self, image id):
        """Return a reference for a particular image
            Ideally you this function is supposed to return a URL
            but in this case, we will simply return the image_id
        return "crowdai-food-challenge::{}".format(image id)
    # The following two functions are from pycocotools with a few
changes.
    def annToRLE(self, ann, height, width):
        Convert annotation which can be polygons, uncompressed RLE to
RLE.
        :return: binary mask (numpy 2D array)
        segm = ann['segmentation']
        if isinstance(segm, list):
            # polygon -- a single object might consist of multiple
parts
            # we merge all parts into one mask rle code
            rles = maskUtils.frPyObjects(segm, height, width)
            rle = maskUtils.merge(rles)
        elif isinstance(segm['counts'], list):
            # uncompressed RLE
            rle = maskUtils.frPyObjects(segm, height, width)
        else:
            rle = ann['segmentation']
        return rle
    def annToMask(self, ann, height, width):
        Convert annotation which can be polygons, uncompressed RLE, or
RLE to binary mask.
        :return: binary mask (numpy 2D array)
        rle = self.annToRLE(ann, height, width)
        m = maskUtils.decode(rle)
        return m
```

Warning

Please, notice that in config values of STEPS_PER_EPOCH and VALIDATION_STEPS are quite low. I decreased them so that model would train fast, but the quality will be low. When you train the model, increase the values up to 50-200.

```
from mrcnn.config import Config
class FoodChallengeConfig(Config):
    """Configuration for training on data in MS COCO format.
    Derives from the base Config class and overrides values specific
    to the COCO dataset.
    # Give the configuration a recognizable name
    NAME = "crowdai-food-challenge"
    # We use a GPU with 12GB memory, which can fit two images.
    # Adjust down if you use a smaller GPU.
    IMAGES PER GPU = 2
    # Uncomment to train on 8 GPUs (default is 1)
    GPU COUNT = 1
    BACKBONE = 'resnet50'
    # Number of classes (including background)
    NUM CLASSES = 62 # 1 Background + 61 classes
    STEPS PER EPOCH=10
    VALIDATION_STEPS=10
    LEARNING RATE=0.001
    IMAGE MAX DIM=256
    IMAGE MIN DIM=256
config = FoodChallengeConfig()
config.display()
Configurations:
BACKBONE
                                resnet50
BACKBONE STRIDES
                                [4, 8, 16, 32, 64]
BATCH SIZE
BBOX STD DEV
                                [0.1 \ 0.1 \ 0.2 \ 0.2]
COMPUTE BACKBONE SHAPE
                                None
DETECTION MAX INSTANCES
                                100
DETECTION MIN CONFIDENCE
                                0.7
DETECTION NMS THRESHOLD
                                0.3
FPN CLASSIF FC LAYERS SIZE
                                1024
GPU COUNT
                                1
GRADIENT CLIP NORM
                                5.0
IMAGES PER GPU
                                2
IMAGE CHANNEL COUNT
                                3
IMAGE MAX DIM
                                256
```

```
IMAGE META SIZE
                                74
                                256
IMAGE MIN DIM
IMAGE MIN SCALE
                                0
IMAGE RESIZE MODE
                                square
IMAGE SHAPE
                                [256 256 3]
LEARNING MOMENTUM
                                0.9
LEARNING RATE
                                0.001
LOSS WEIGHTS
                                {'rpn class loss': 1.0,
'rpn bbox loss': 1.0, 'mrcnn class loss': 1.0, 'mrcnn bbox loss': 1.0,
'mrcnn mask loss': 1.0}
MASK POOL SIZE
                                14
MASK SHAPE
                                [28, 28]
MAX GT INSTANCES
                                100
MEAN PIXEL
                                [123.7 116.8 103.9]
MINI MASK SHAPE
                                (56, 56)
NAME
                                crowdai-food-challenge
NUM CLASSES
                                62
POOL SIZE
                                7
POST NMS ROIS INFERENCE
                                1000
POST_NMS_ROIS_TRAINING
                                2000
PRE NMS LIMIT
                                6000
ROI POSITIVE RATIO
                                0.33
RPN ANCHOR RATIOS
                                [0.5, 1, 2]
RPN ANCHOR SCALES
                                (32, 64, 128, 256, 512)
RPN ANCHOR STRIDE
RPN BBOX STD DEV
                                [0.1 \ 0.1 \ 0.2 \ 0.2]
RPN NMS THRESHOLD
                                0.7
RPN TRAIN ANCHORS PER IMAGE
                                256
STEPS PER EPOCH
                                10
TOP DOWN PYRAMID SIZE
                                256
TRAIN BN
                                False
TRAIN ROIS PER IMAGE
                                200
USE MINI MASK
                                True
USE RPN ROIS
                                True
VALIDATION STEPS
                                10
WEIGHT DECAY
                                0.0001
%cd ..
!cp /kaggle/input/food-recognition-challenge /kaggle/working -r
!rm -rf images assets # to prevent displaying images at the bottom of
a kernel
/kaggle/working
!cp /kaggle/working/food-recognition-
challenge/train/train/annotations.json /kaggle/working/food-
recognition-challenge/train/train/annotation.json
```

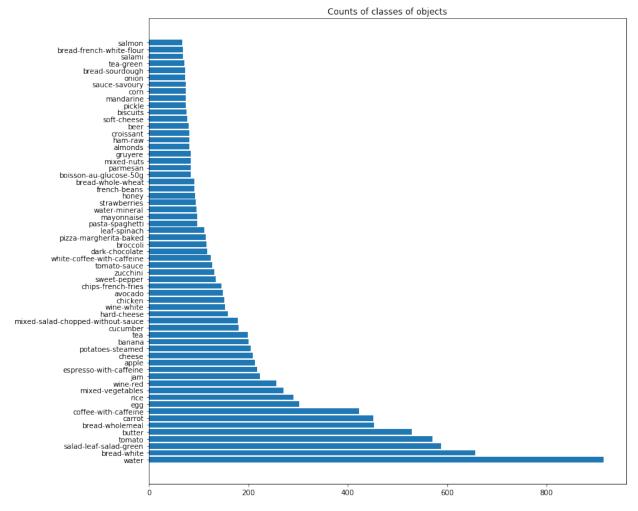
```
#from mrcnn.dataset import FoodChallengeDataset
dataset_train = FoodChallengeDataset()
dataset_train.load_dataset(dataset_dir=os.path.join("/kaggle/working/
food-recognition-challenge/train", "train"), load_small=False)
#dataset_train.load_dataset(dataset_dir="train", load_small=False)
dataset_train.prepare()
dataset = dataset_train

Annotation Path
/kaggle/working/food-recognition-challenge/train/train/annotations.jso
n
Image Dir
/kaggle/working/food-recognition-challenge/train/train/images
loading annotations into memory...
Done (t=0.94s)
creating index...
index created!
```

Data exploration

```
from collections import Counter
class_counts = Counter()
for img_info in dataset_train.image_info:
    ann = img_info['annotations']
    for i in ann:
        class_counts[i['category_id']] += 1
class_mapping = {i['id']: i['name'] for i in dataset_train.class_info}

class_counts = pd.DataFrame(class_counts.most_common(),
    columns=['class_name', 'count'])
    class_counts['class_name'] = class_counts['class_name'].apply(lambda
    x: class_mapping[x])
    plt.figure(figsize=(12, 12))
    plt.barh(class_counts['class_name'], class_counts['count'])
    plt.title('Counts of classes of objects');
```



```
print(f'We have {class_counts.shape[0]} classes!')
We have 61 classes!
```

The most common is water - I suppose it is a background. Some vegetables and white bread are the most common.

Now let's use a function from the repo to see information about one random image

```
# Load random image and mask.
image_id = random.choice(dataset.image_ids)
image = dataset.load_image(image_id)
mask, class_ids = dataset.load_mask(image_id)
# Compute Bounding box
bbox = utils.extract_bboxes(mask)

# Display image and additional stats
print("image_id ", image_id, dataset.image_reference(image_id))
log("image", image)
log("mask", mask)
```

```
log("class_ids", class_ids)
log("bbox", bbox)
# Display image and instances
visualize.display instances(image, bbox, mask, class ids,
dataset.class_names, figsize=(12, 12))
image_id 1158 crowdai-food-challenge::1158
                         shape: (391, 392, 3)
image
                                                       min:
                                                               0.00000
max: 255.00000
                 uint8
                         shape: (391, 392, 1)
                                                       min:
                                                               0.00000
mask
        1.00000
                 uint8
max:
class_ids
                         shape: (1,)
                                                       min:
                                                               9.00000
        9.00000
                 int32
max:
bbox
                         shape: (1, 4)
                                                       min:
                                                               2.00000
      285.00000
                 int32
max:
```



Let's see what information we have about images:

```
'category_id': 2578,
'segmentation': [[235.0,
 337.5,
 190.0,
 333.5,
 180.5,
 328.0,
 174.5,
 315.0,
 157.5,
 231.0,
 148.5,
 158.0,
 138.5,
 112.0,
 138.5,
 79.0,
 145.5,
 60.00000000000001,
 151.0,
 57.5,
 180.0,
 57.5,
 207.0,
 62.50000000000001,
 245.00000000000003,
 55.5,
 280.0,
 57.5,
 292.5,
 67.0,
 308.5,
 91.0,
 311.5,
 110.0,
 310.5,
 137.0,
 303.5,
 182.0,
 297.5,
 261.0,
 288.5,
 306.0,
 283.5,
 318.0,
 271.0,
 331.5,
 261.0,
 335.5]],
```

```
'area': 40035.0,
'bbox': [57.5, 138.5, 280.0, 173.0],
'iscrowd': 0}]}
```

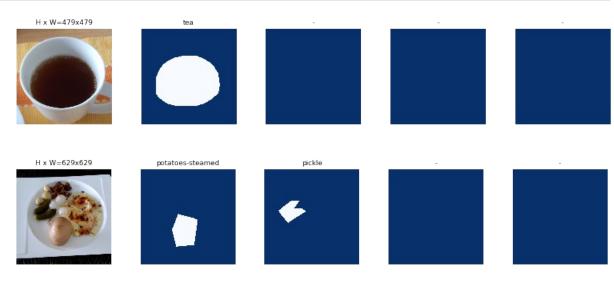
- There is some meta information: path, height, width
- for each object we have annotations: class, segmentation mask, total area, bbox coordinates.

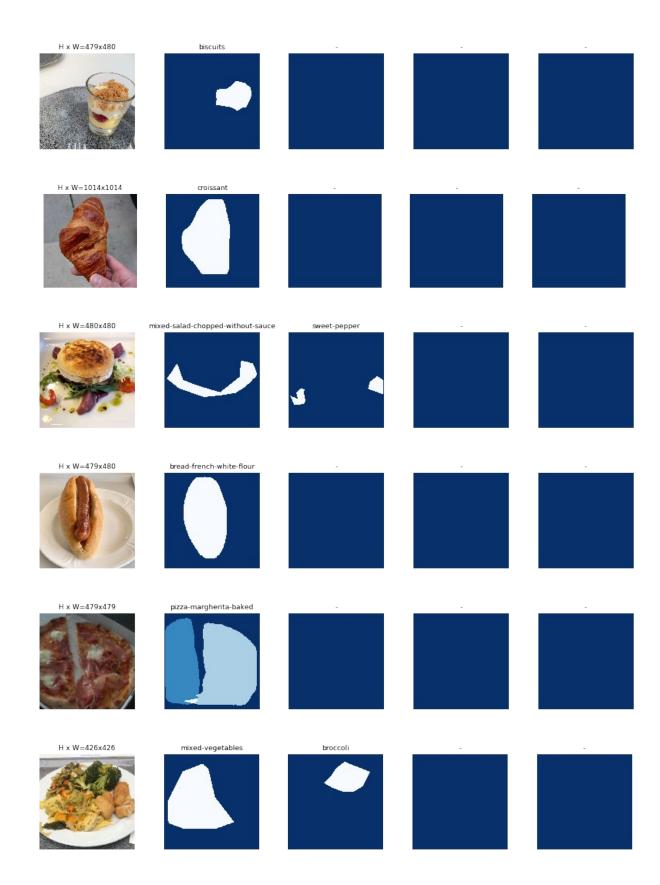
Masks

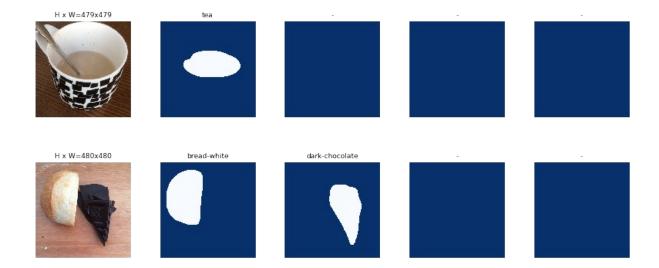
We can see masks and boxes for different classes. Let's take 10 random classes

```
class_images = defaultdict(list)
for ind, img_info in enumerate(dataset_train.image_info):
    ann = img_info['annotations']
    for i in ann:
        class_images[i['category_id']].append(ind)

image_ids = np.random.choice(dataset.image_ids, 4)
for class_id in np.random.choice(list(class_images.keys()), 10):
    image_id = np.random.choice(class_images[class_id], 1)[0]
    image = dataset.load_image(image_id)
    mask, class_ids = dataset.load_mask(image_id)
    visualize.display_top_masks(image, mask, class_ids,
dataset.class_names)
```



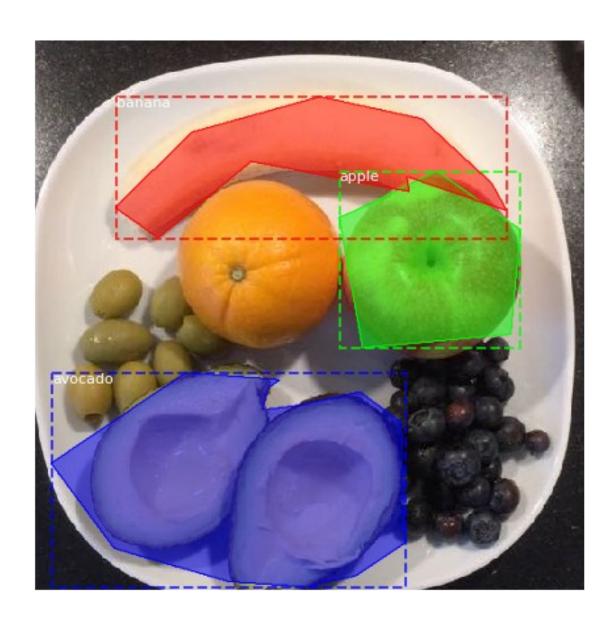


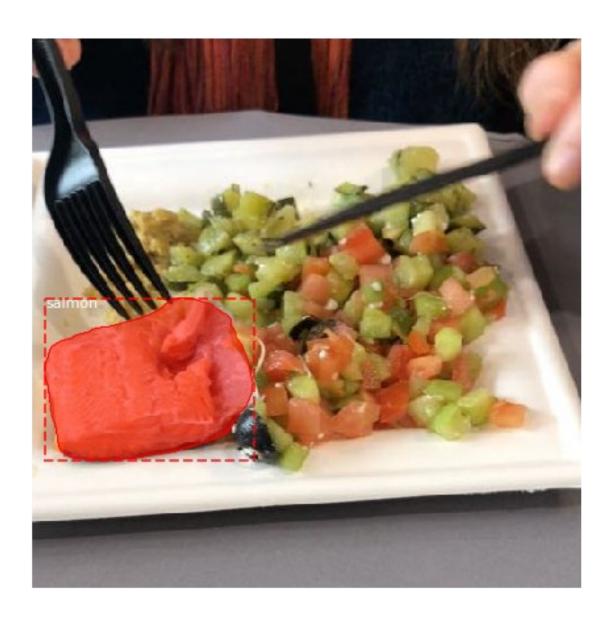


We can see that some masks are big, some are small. Some have a single area, some have multiple areas.

Bounding Boxes

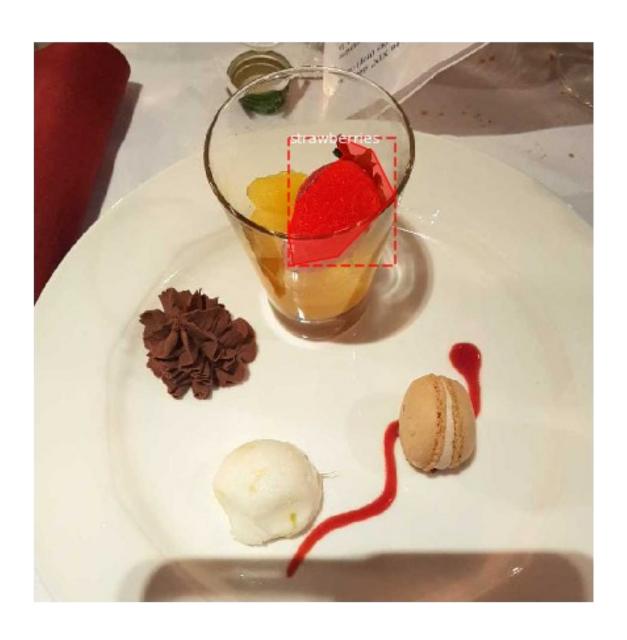
```
for idx, class_id in
enumerate(np.random.choice(list(class_images.keys()), 10)):
    image_id = np.random.choice(class_images[class_id], 1)[0]
    image = dataset.load_image(image_id)
    mask, class_ids = dataset.load_mask(image_id)
    # Compute Bounding box
    bbox = utils.extract_bboxes(mask)
    visualize.display_instances(image, bbox, mask, class_ids, dataset.class_names, figsize=(8, 8))
```







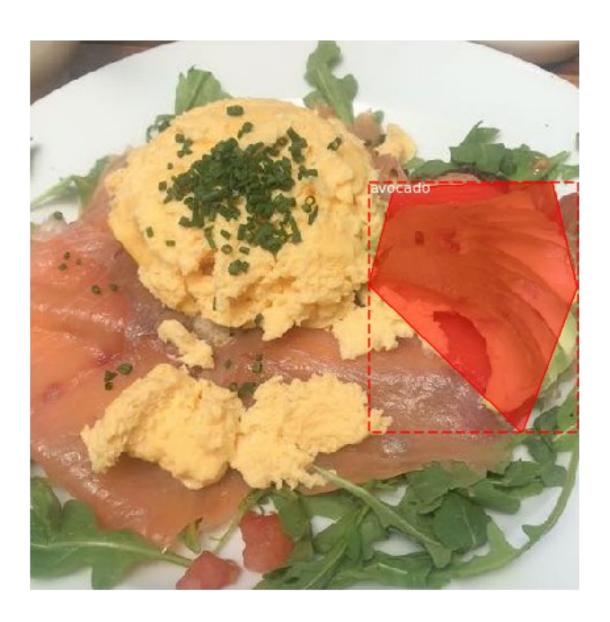


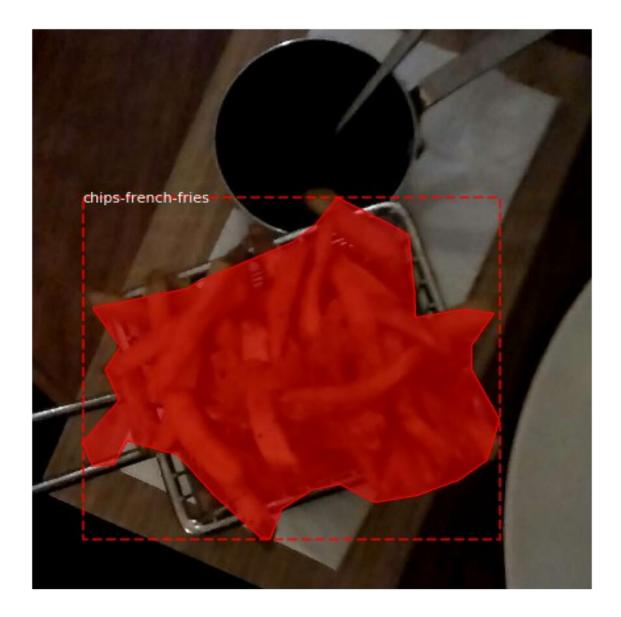












Obviously bounding boxed have masks inside them. And if an object has several masks, then the bounding box will contain all the masks.

Anchors

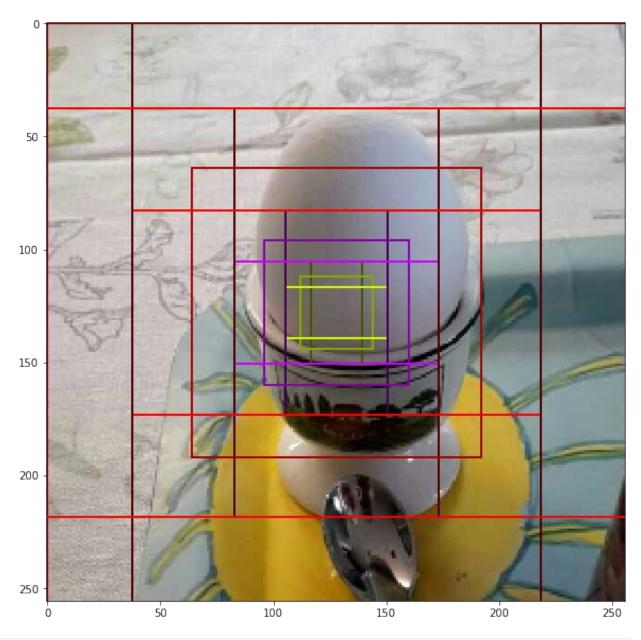
One more important type of annotation is anchor. Anchors are a set of boxes with predefined locations and scales relative to images. These boxes are defined to capture the scale and aspect ratio of specific object classes you want to detect and are typically chosen based on object sizes in your training datasets.

Generate Anchors

backbone_shapes = modellib.compute_backbone_shapes(config,

```
config.IMAGE SHAPE)
anchors = utils.generate pyramid anchors(config.RPN ANCHOR SCALES,
                                             config.RPN ANCHOR RATIOS,
                                             backbone shapes,
                                             config.BACKBONE STRIDES,
                                             config.RPN ANCHOR STRIDE)
# Print summary of anchors
num levels = len(backbone shapes)
anchors per cell = len(config.RPN ANCHOR RATIOS)
print("Count: ", anchors.shape[0])
print("Scales: ", config.RPN_ANCHOR_SCALES)
print("ratios: ", config.RPN_ANCHOR_RATIOS)
print("Anchors per Cell: ", anchors per cell)
print("Levels: ", num levels)
anchors per level = []
for l in range(num levels):
    num cells = backbone shapes[l][0] * backbone shapes[l][1]
    anchors_per_level.append(anchors_per_cell * num_cells //
config.RPN ANCHOR STRIDE**2)
    print("Anchors in Level {}: {}".format(l, anchors per level[l]))
Count: 16368
Scales: (32, 64, 128, 256, 512)
ratios: [0.5, 1, 2]
Anchors per Cell: 3
Levels:
Anchors in Level 0: 12288
Anchors in Level 1: 3072
Anchors in Level 2: 768
Anchors in Level 3: 192
Anchors in Level 4: 48
## Visualize anchors of one cell at the center of the feature map of a
specific level
# Load and draw random image
image_id = np.random.choice(dataset.image_ids, 1)[0]
image, image_meta, _, _, _ = modellib.load_image_gt(dataset, config,
image id)
fig, ax = plt.subplots(1, figsize=(10, 10))
ax.imshow(image)
levels = len(backbone shapes)
for level in range(levels):
    colors = visualize.random colors(levels)
    # Compute the index of the anchors at the center of the image
    level_start = sum(anchors_per_level[:level]) # sum of anchors of
previous levels
    level anchors =
```

```
anchors[level start:level start+anchors per level[level]]
    print("Level {}. Anchors: {:6} Feature map Shape:
{}".format(level, level anchors.shape[0],
backbone shapes[level]))
    center cell = backbone shapes[level] // 2
    center_cell_index = (center_cell[0] * backbone_shapes[level][1] +
center cell[1])
    level_center = center_cell_index * anchors_per_cell
    center_anchor = anchors_per_cell * (
        (center cell[0] * backbone shapes[level][1] /
config.RPN ANCHOR STRIDE**2) \
        + center cell[1] / config.RPN ANCHOR STRIDE)
    level_center = int(center anchor)
    # Draw anchors. Brightness show the order in the array, dark to
bright.
    for i, rect in
enumerate(level anchors[level center:level center+anchors per cell]):
        y1, x1, y2, x2 = rect
        p = patches.Rectangle((x1, y1), x2-x1, y2-y1, linewidth=2,
facecolor='none',
                              edgecolor=(i+1)*np.array(colors[level])
/ anchors per cell)
        ax.add patch(p)
Level 0. Anchors:
                  12288
                          Feature map Shape: [64 64]
Level 1. Anchors:
                    3072
                          Feature map Shape: [32 32]
                   768
Level 2. Anchors:
                          Feature map Shape: [16 16]
Level 3. Anchors:
                     192
                          Feature map Shape: [8 8]
Level 4. Anchors:
                     48
                          Feature map Shape: [4 4]
```



```
# Create data generator
random_rois = 2000
g = modellib.data_generator(
    dataset, config, shuffle=True, random_rois=random_rois,
    batch_size=4,
    detection_targets=True)
# Get Next Image
if random_rois:
    [normalized_images, image_meta, rpn_match, rpn_bbox, gt_class_ids,
gt_boxes, gt_masks, rpn_rois, rois], \
    [mrcnn_class_ids, mrcnn_bbox, mrcnn_mask] = next(g)
else:
```

```
[normalized images, image meta, rpn match, rpn bbox, gt boxes,
gt masks], = next(g)
image id = modellib.parse image meta(image meta)["image id"][0]
# Remove the last dim in mrcnn class ids. It's only added
# to satisfy Keras restriction on target shape.
mrcnn class ids = mrcnn class ids[:,:,0]
b = 0
# Restore original image (reverse normalization)
sample image = modellib.unmold image(normalized images[b], config)
# Compute anchor shifts.
indices = np.where(rpn match[b] == 1)[0]
refined anchors = utils.apply box deltas(anchors[indices], rpn bbox[b,
:len(indices)] * config.RPN_BBOX_STD_DEV)
# Get list of positive anchors
positive anchor ids = np.where(rpn match[b] == 1)[0]
negative anchor ids = np.where(rpn match[b] == -1)[0]
neutral anchor ids = np.where(rpn match[b] == 0)[0]
# ROI breakdown by class
for c, n in zip(dataset.class names,
np.bincount(mrcnn class ids[b].flatten())):
    if n:
        print("{:23}: {}".format(c[:20], n))
# Show positive anchors
visualize.draw boxes(sample image, boxes=anchors[positive anchor ids],
                     refined boxes=refined anchors)
BG
                       : 134
mixed-vegetables
                       : 66
```



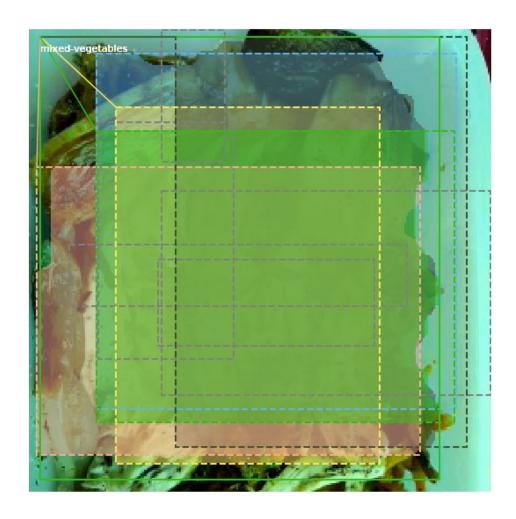
ROI

Region of interest pooling (also known as RoI pooling) is an operation widely used in object detection tasks using convolutional neural networks. For example, to detect multiple fruits and vegetables in a single image. Its purpose is to perform max pooling on inputs of nonuniform sizes to obtain fixed-size feature maps (e.g. 7×7).

The result is that from a list of rectangles with different sizes we can quickly get a list of corresponding feature maps with a fixed size. Note that the dimension of the RoI pooling output doesn't actually depend on the size of the input feature map nor on the size of the region proposals. It's determined solely by the number of sections we divide the proposal into. What's the benefit of RoI pooling? One of them is processing speed. If there are multiple object proposals on the frame (and usually there'll be a lot of them), we can still use the same input

feature map for all of them. Since computing the convolutions at early stages of processing is very expensive, this approach can save us a lot of time.

```
if random rois:
    # Class aware bboxes
    bbox specific = mrcnn bbox[b, np.arange(mrcnn bbox.shape[1]),
mrcnn class ids[b], :]
    # Refined ROIs
    refined rois = utils.apply box deltas(rois[b].astype(np.float32),
bbox specific[:,:4] * config.BBOX STD DEV)
    # Class aware masks
    mask specific = mrcnn mask[b,
np.arange(mrcnn_mask.shape[1]), :, :, mrcnn_class_ids[b]]
    visualize.draw rois(sample image, rois[b], refined rois,
mask specific, mrcnn class ids[b], dataset.class names)
    # Any repeated ROIs?
    rows = np.ascontiguousarray(rois[b]).view(np.dtype((np.void,
rois.dtype.itemsize * rois.shape[-1])))
    _, idx = np.unique(rows, return_index=True)
    print("Unique ROIs: {} out of {}".format(len(idx), rois.shape[1]))
Positive ROIs: 66
Negative ROIs: 134
Positive Ratio: 0.33
Unique ROIs: 200 out of 200
```



Modelling with Mask-RCNN

The code is based on the baseling by organizers: https://discourse.aicrowd.com/t/new-starter-notebook-paperspace/2754/1

```
!mkdir pretrained

PRETRAINED_MODEL_PATH = os.path.join("pretrained",
    "mask_rcnn_coco.h5")
LOGS_DIRECTORY = os.path.join(ROOT_DIR, "logs")
if not os.path.exists(PRETRAINED_MODEL_PATH):
    utils.download_trained_weights(PRETRAINED_MODEL_PATH)

Downloading pretrained model to pretrained/mask_rcnn_coco.h5 ...
... done downloading pretrained model!
```

```
import keras.backend
K = keras.backend.backend()
if K=='tensorflow':
    keras.backend.common.image dim ordering()
model = modellib.MaskRCNN(mode="training", config=config,
model dir=LOGS DIRECTORY)
model path = PRETRAINED MODEL PATH
model.load weights(model path, by name=True, exclude=[
        "mrcnn_class_logits", "mrcnn_bbox fc",
        "mrcnn bbox", "mrcnn mask"])
dataset_train = FoodChallengeDataset()
dataset train.load dataset(os.path.join("/kaggle/working/food-
recognition-challenge/train", "train"), load_small=False)
dataset train.prepare()
dataset val = FoodChallengeDataset()
val coco =
dataset val.load dataset(dataset dir=os.path.join("/kaggle/working/
food-recognition-challenge/val", "val"), load small=False,
return coco=True)
dataset val.prepare()
Annotation Path
/kaggle/working/food-recognition-challenge/train/train/annotations.jso
/kaggle/working/food-recognition-challenge/train/train/images
loading annotations into memory...
Done (t=0.71s)
creating index...
index created!
Annotation Path
/kaggle/working/food-recognition-challenge/val/val/annotations.json
Image Dir /kaggle/working/food-recognition-challenge/val/val/images
loading annotations into memory...
Done (t=0.03s)
creating index...
index created!
class names = dataset train.class names
assert len(class names)==62, "Please check DatasetConfig"
print("Training network")
model.train(dataset train, dataset val,
            learning rate=config.LEARNING RATE,
            epochs=1,
            layers='heads')
Training network
```

```
Starting at epoch 0. LR=0.001
Checkpoint Path: /kaggle/working/Mask RCNN/logs/crowdai-food-
challenge20200331T0232/mask rcnn crowdai-food-challenge {epoch:04d}.h5
Selecting layers to train
fpn c5p5
                        (Conv2D)
fpn_c4p4
                        (Conv2D)
fpn c3p3
                        (Conv2D)
fpn c2p2
                        (Conv2D)
fpn p5
                        (Conv2D)
fpn p2
                        (Conv2D)
fpn p3
                        (Conv2D)
fpn p4
                        (Conv2D)
In model:
           rpn model
    rpn conv shared
                            (Conv2D)
    rpn class raw
                            (Conv2D)
    rpn bbox pred
                            (Conv2D)
                        (TimeDistributed)
mrcnn mask conv1
mrcnn mask bn1
                        (TimeDistributed)
mrcnn mask conv2
                        (TimeDistributed)
mrcnn mask bn2
                        (TimeDistributed)
mrcnn class conv1
                        (TimeDistributed)
mrcnn class bn1
                        (TimeDistributed)
mrcnn mask conv3
                        (TimeDistributed)
mrcnn mask bn3
                        (TimeDistributed)
mrcnn class conv2
                        (TimeDistributed)
mrcnn class bn2
                        (TimeDistributed)
mrcnn mask conv4
                        (TimeDistributed)
mrcnn mask bn4
                        (TimeDistributed)
mrcnn bbox fc
                        (TimeDistributed)
                        (TimeDistributed)
mrcnn mask deconv
mrcnn class logits
                        (TimeDistributed)
                        (TimeDistributed)
mrcnn mask
/opt/conda/lib/python3.6/site-packages/tensorflow core/python/
framework/indexed slices.py:424: UserWarning: Converting sparse
IndexedSlices to a dense Tensor of unknown shape. This may consume a
large amount of memory.
  "Converting sparse IndexedSlices to a dense Tensor of unknown shape.
/opt/conda/lib/python3.6/site-packages/tensorflow core/python/framewor
k/indexed slices.py:424: UserWarning: Converting sparse IndexedSlices
to a dense Tensor of unknown shape. This may consume a large amount of
memory.
  "Converting sparse IndexedSlices to a dense Tensor of unknown shape."
/opt/conda/lib/python3.6/site-packages/tensorflow core/python/framewor
k/indexed slices.py:424: UserWarning: Converting sparse IndexedSlices
to a dense Tensor of unknown shape. This may consume a large amount of
memory.
```

```
"Converting sparse IndexedSlices to a dense Tensor of unknown shape."
/opt/conda/lib/python3.6/site-packages/keras/engine/training.py:2039:
UserWarning: Using a generator with `use multiprocessing=True` and
multiple workers may duplicate your data. Please consider using
the keras.utils.Sequence class.
 UserWarning('Using a generator with `use multiprocessing=True`'
Epoch 1/1
rpn_class_loss: 0.0534 - rpn_bbox_loss: 1.1211 - mrcnn_class_loss:
2.5968 - mrcnn_bbox_loss: 0.9868 - mrcnn_mask_loss: 0.7861
/opt/conda/lib/python3.6/site-packages/keras/engine/training.py:2197:
UserWarning: Using a generator with `use multiprocessing=True` and
multiple workers may duplicate your data. Please consider using
the keras.utils.Sequence class.
 UserWarning('Using a generator with `use multiprocessing=True`'
- rpn class loss: 0.0623 - rpn bbox loss: 1.2156 - mrcnn class loss:
2.3972 - mrcnn bbox loss: 0.9984 - mrcnn mask loss: 0.7748 - val loss:
3.1090 - val rpn class loss: 0.0576 - val rpn bbox loss: 0.7176 -
val mrcnn class loss: 0.6629 - val mrcnn bbox loss: 0.9465 -
val mrcnn mask loss: 0.7244
```

Looking at the predictions

```
model path = model.find last()
model path
'/kaggle/working/Mask RCNN/logs/crowdai-food-challenge20200331T0232/
mask rcnn crowdai-food-challenge 0001.h5'
# I'll use my model trained locally
model path = '/kaggle/input/food-model/mask rcnn crowdai-food-
challenge 0010.h5'
class InferenceConfig(FoodChallengeConfig):
    GPU COUNT = 1
    IMAGES PER GPU = 1
    NUM CLASSES = 62 # 1 Background + 61 classes
    IMAGE MAX DIM=256
    IMAGE MIN DIM=256
    NAME = "food"
    DETECTION MIN CONFIDENCE=0
inference config = InferenceConfig()
inference config.display()
```

```
Configurations:
BACKBONE
                                 resnet50
BACKBONE STRIDES
                                 [4, 8, 16, 32, 64]
BATCH SIZE
                                 1
BBOX STD DEV
                                 [0.1 \ 0.1 \ 0.2 \ 0.2]
COMPUTE BACKBONE SHAPE
                                 None
DETECTION MAX INSTANCES
                                 100
DETECTION_MIN_CONFIDENCE
                                 0
DETECTION NMS THRESHOLD
                                 0.3
FPN CLASSIF FC LAYERS SIZE
                                 1024
GPU COUNT
                                 1
GRADIENT CLIP NORM
                                 5.0
IMAGES PER GPU
                                 1
IMAGE CHANNEL COUNT
                                 3
IMAGE MAX DIM
                                 256
IMAGE META SIZE
                                 74
IMAGE MIN DIM
                                 256
IMAGE MIN SCALE
                                 0
IMAGE RESIZE MODE
                                 square
IMAGE SHAPE
                                 [256 256
                                            31
LEARNING MOMENTUM
                                 0.9
LEARNING RATE
                                 0.001
LOSS WEIGHTS
                                 {'rpn class loss': 1.0,
'rpn_bbox_loss': 1.0, 'mrcnn_class_loss': 1.0, 'mrcnn_bbox_loss': 1.0,
'mrcnn mask loss': 1.0}
MASK POOL SIZE
                                 14
MASK SHAPE
                                 [28, 28]
MAX GT INSTANCES
                                 100
MEAN PIXEL
                                 [123.7 116.8 103.9]
MINI MASK SHAPE
                                 (56, 56)
NAME
                                 food
NUM CLASSES
                                 62
POOL SIZE
                                 7
POST NMS ROIS INFERENCE
                                 1000
POST NMS ROIS TRAINING
                                 2000
PRE NMS LIMIT
                                 6000
ROI POSITIVE RATIO
                                 0.33
RPN ANCHOR RATIOS
                                 [0.5, 1, 2]
                                 (32, 64, 128, 256, 512)
RPN ANCHOR SCALES
RPN ANCHOR STRIDE
                                 1
RPN BBOX STD DEV
                                 [0.1 \ 0.1 \ 0.2 \ 0.2]
RPN NMS THRESHOLD
                                 0.7
RPN TRAIN ANCHORS PER IMAGE
                                 256
STEPS PER EPOCH
                                 10
TOP DOWN PYRAMID SIZE
                                 256
TRAIN BN
                                 False
TRAIN ROIS PER IMAGE
                                 200
USE MINI MASK
                                 True
USE RPN ROIS
                                 True
```

```
VALIDATION STEPS
                                 10
WEIGHT DECAY
                                 0.0001
# Recreate the model in inference mode
model = modellib.MaskRCNN(mode='inference',
                           config=inference config,
                           model dir=R00T DIR)
# Load trained weights (fill in path to trained weights here)
assert model_path != "", "Provide path to trained weights"
print("Loading weights from ", model path)
model.load weights(model path, by name=True)
Loading weights from /kaggle/input/food-model/mask rcnn crowdai-food-
challenge 0010.h5
# Show few example of ground truth vs. predictions on the validation
dataset
dataset = dataset val
fig = plt.figure(figsize=(10, 30))
for i in range(4):
    image id = random.choice(dataset.image ids)
    original image, image meta, gt class id, gt bbox, gt mask =\
        modellib.load_image_gt(dataset_val, inference_config,
                                 image id, use mini mask=False)
    print(original image.shape)
    plt.subplot(6, 2, 2*i + 1)
    visualize.display instances(original image, gt bbox, gt mask,
gt class id,
                                  dataset.class names, ax=fig.axes[-1])
    plt.subplot(6, 2, 2*i + 2)
    results = model.detect([original image]) #, verbose=1)
    r = results[0]
    visualize.display instances(original image, r['rois'], r['masks'],
r['class ids'],
                                  dataset.class names, r['scores'],
ax=fig.axes[-1])
(256, 256, 3)
(256, 256, 3)
(256, 256, 3)
(256, 256, 3)
```

