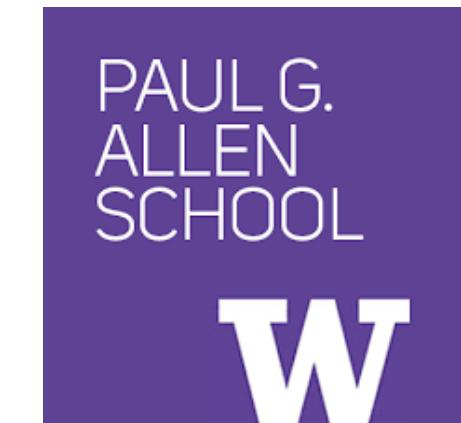


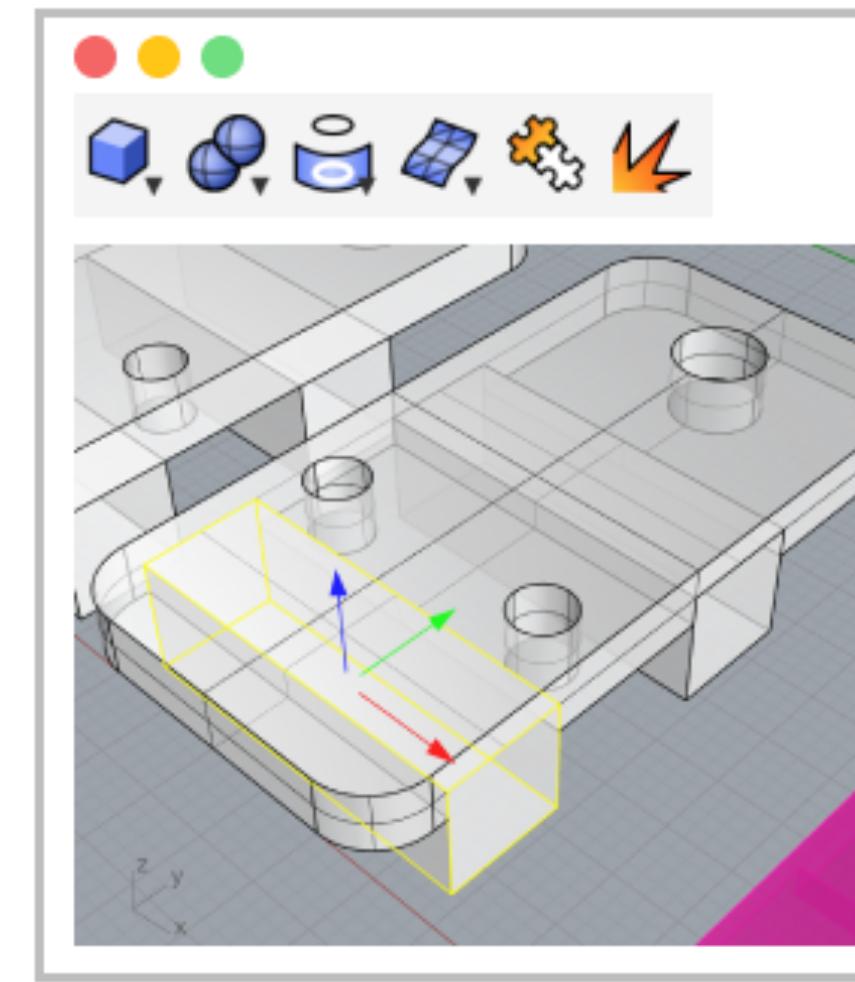
Towards Fabrication-as-Programming

SCF 2022

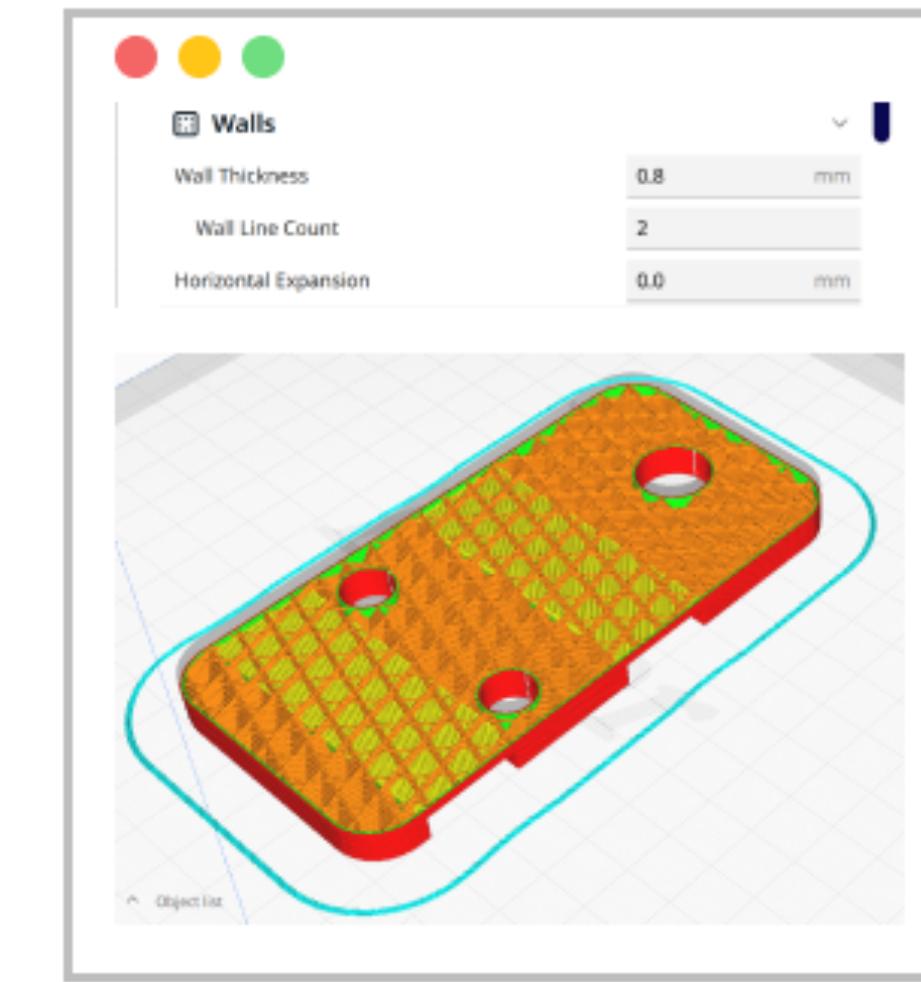
Jasper Tran O'Leary, Eunice Jun, Nadya Peek
University of Washington



CAD



CAM



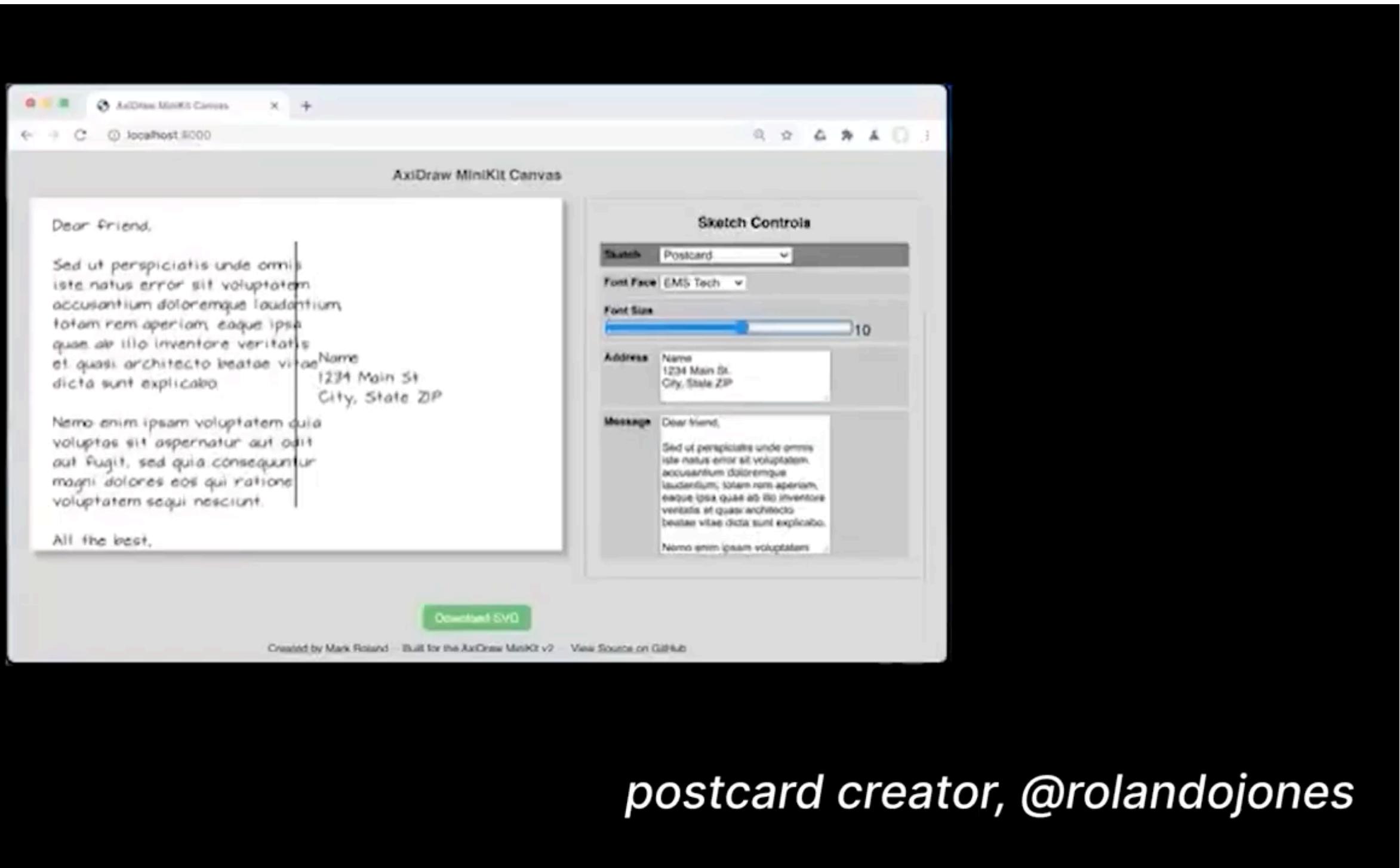
Post-Processing (sometimes)



Machine Control

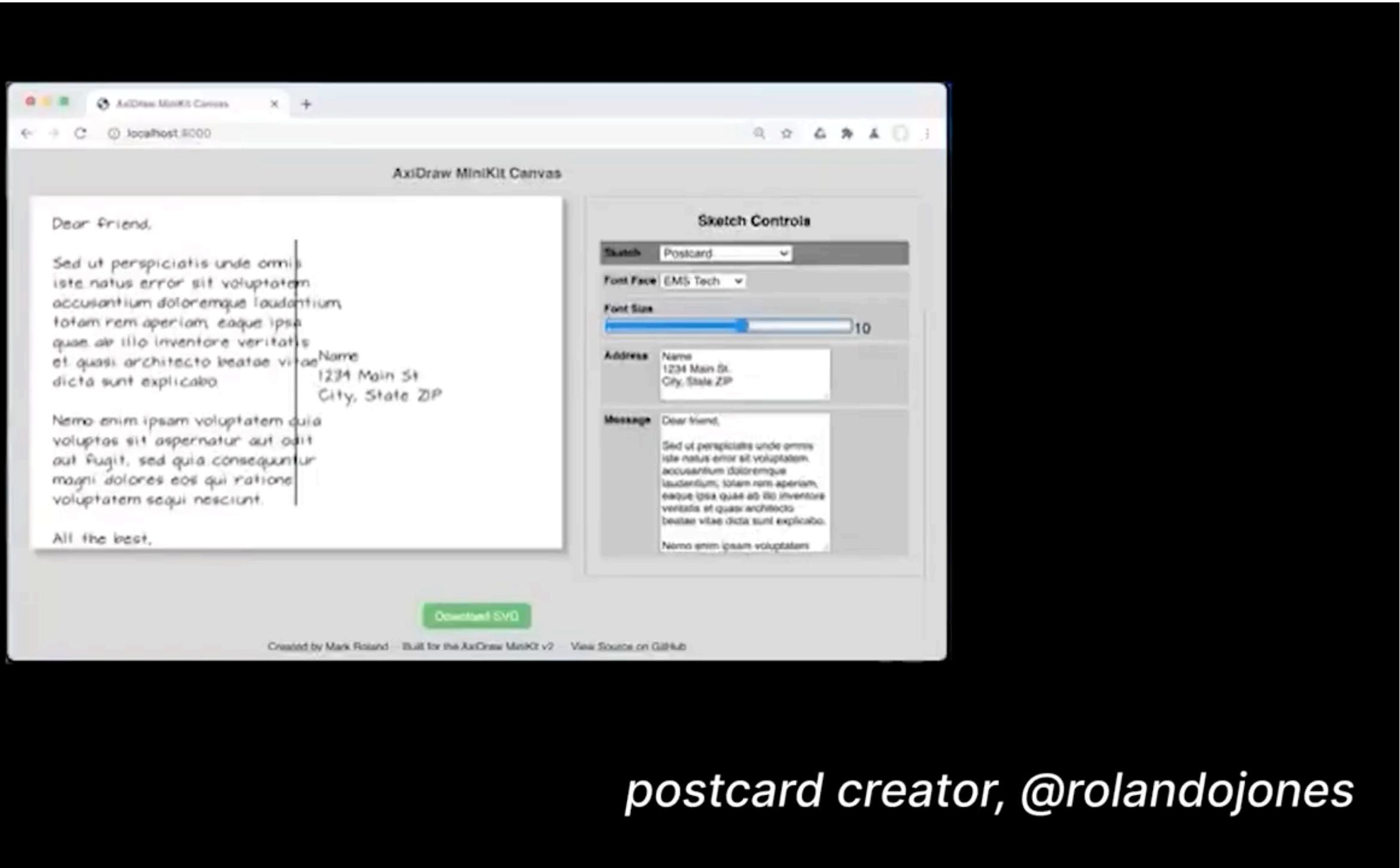
Exploratory digital fabrication

Exploratory digital fabrication



postcard creator, @rolandojones

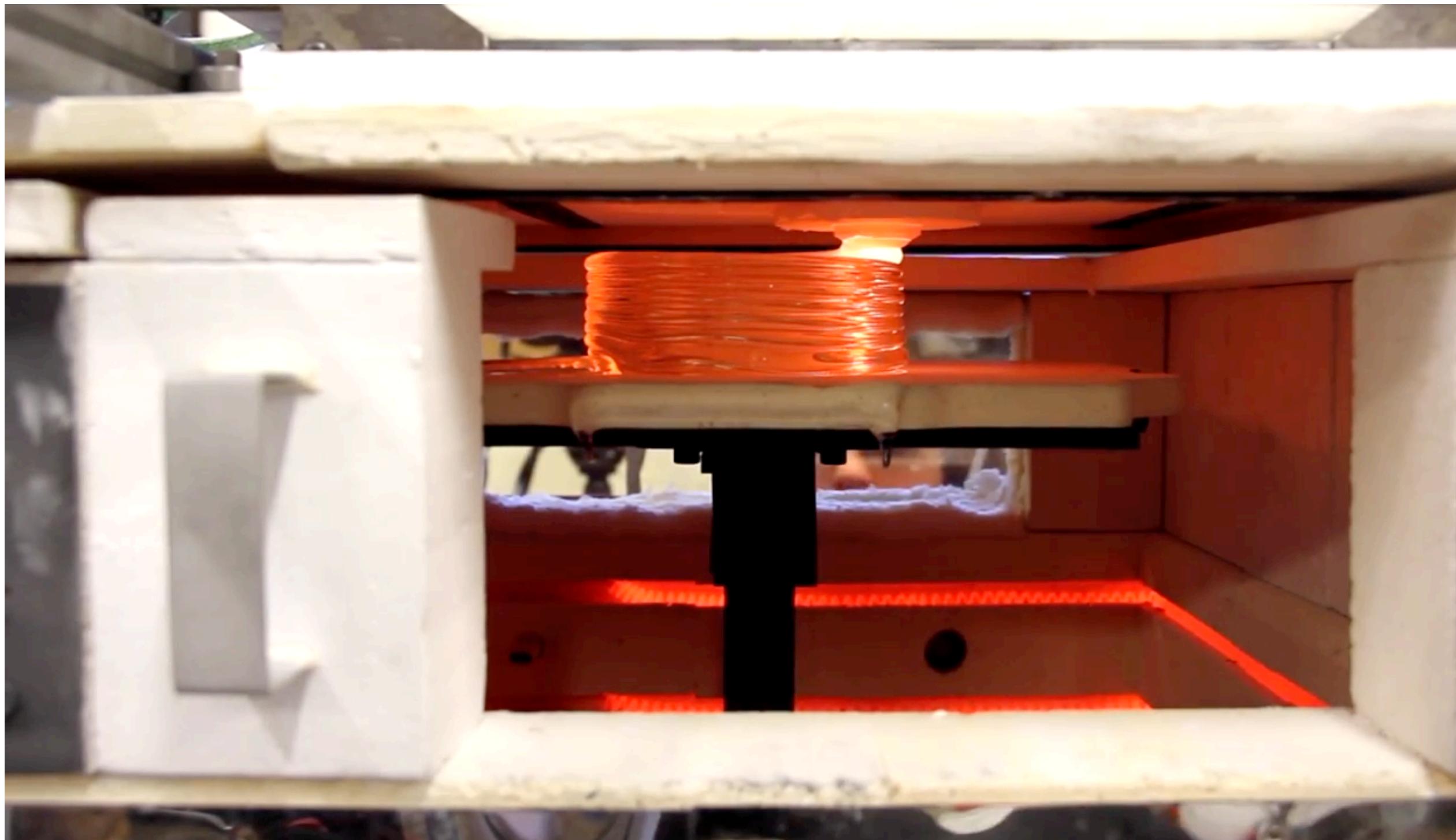
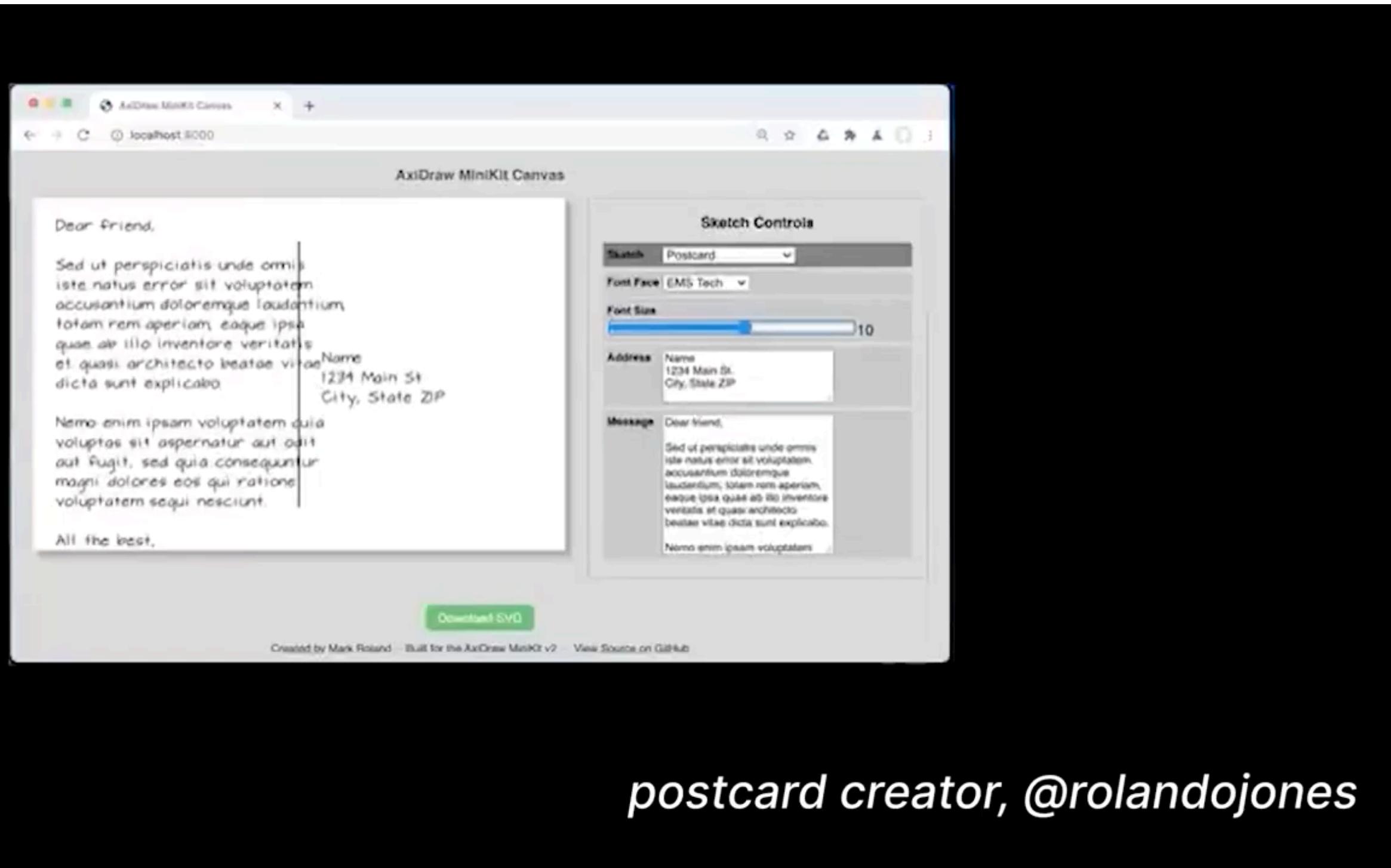
Exploratory digital fabrication



postcard creator, @rolandojones

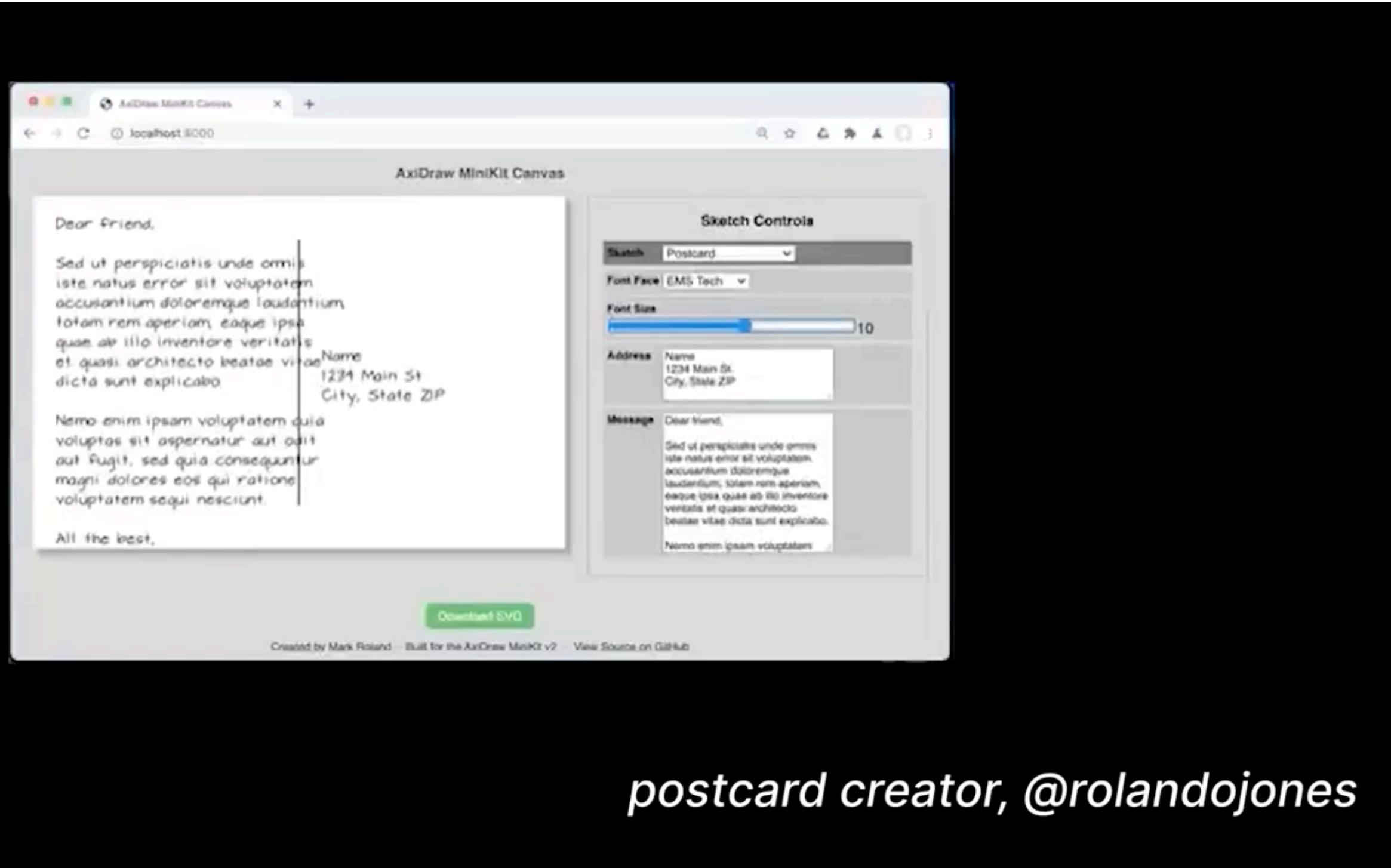
Twigg-Smith et al. Tools, Tricks, and Hacks. Investigating Novel Digital Fabrication Workflows on #PlotterTwitter. 2021.

Exploratory digital fabrication

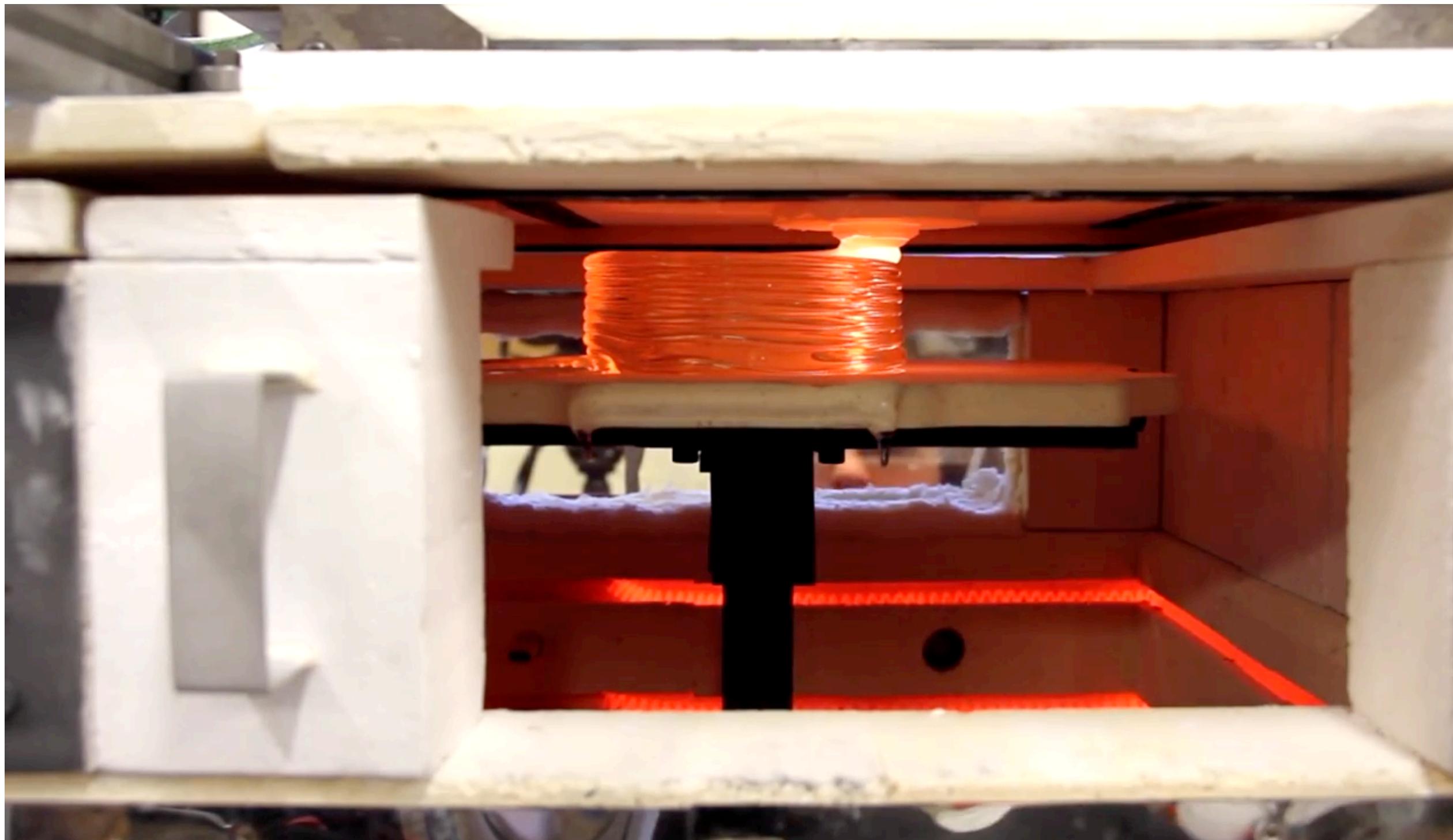


Twigg-Smith et al. Tools, Tricks, and Hacks. Investigating Novel Digital Fabrication Workflows on #PlotterTwitter. 2021.

Exploratory digital fabrication



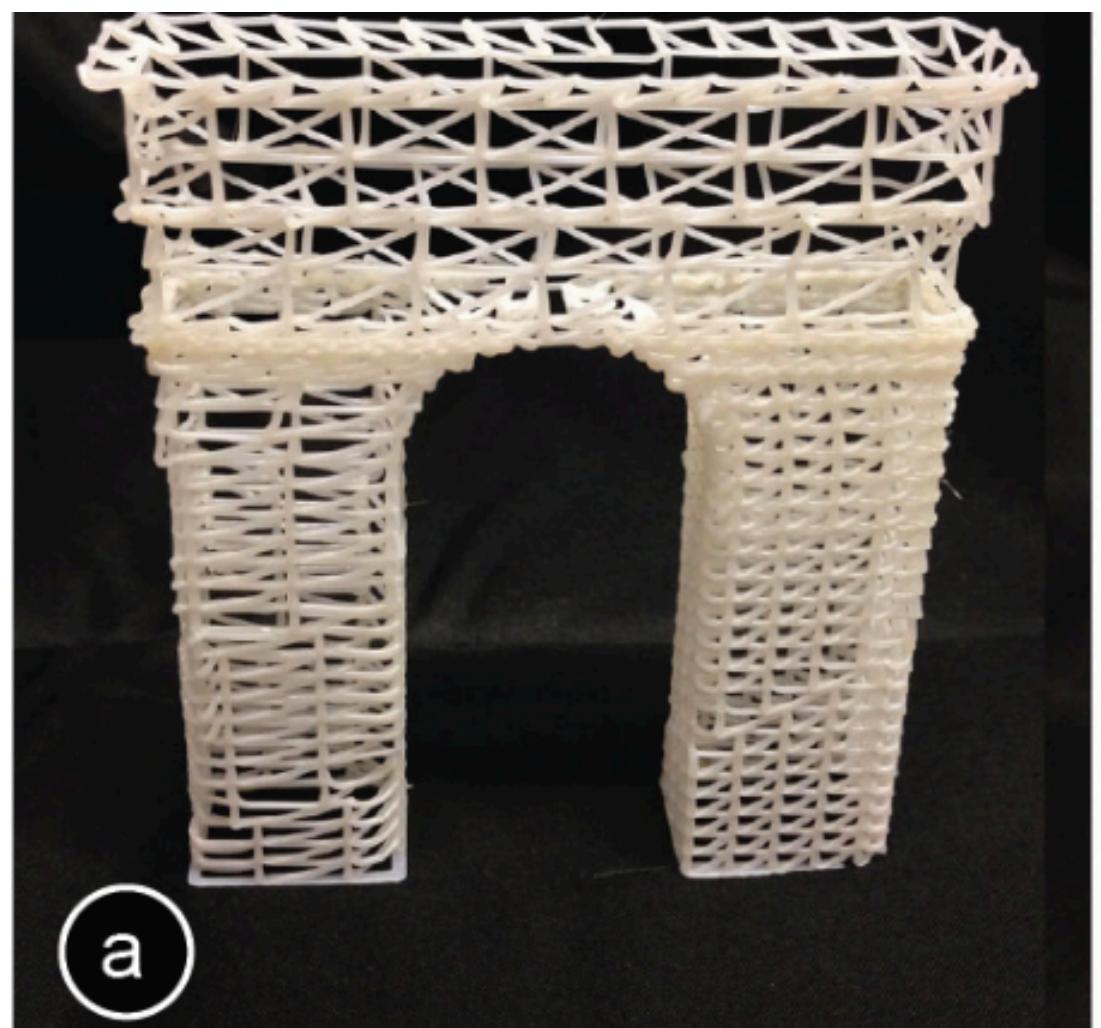
Twigg-Smith et al. *Tools, Tricks, and Hacks. Investigating Novel Digital Fabrication Workflows on #PlotterTwitter*. 2021.



Klein et al. *Additive Manufacturing of Optically Transparent Glass*. 2015.

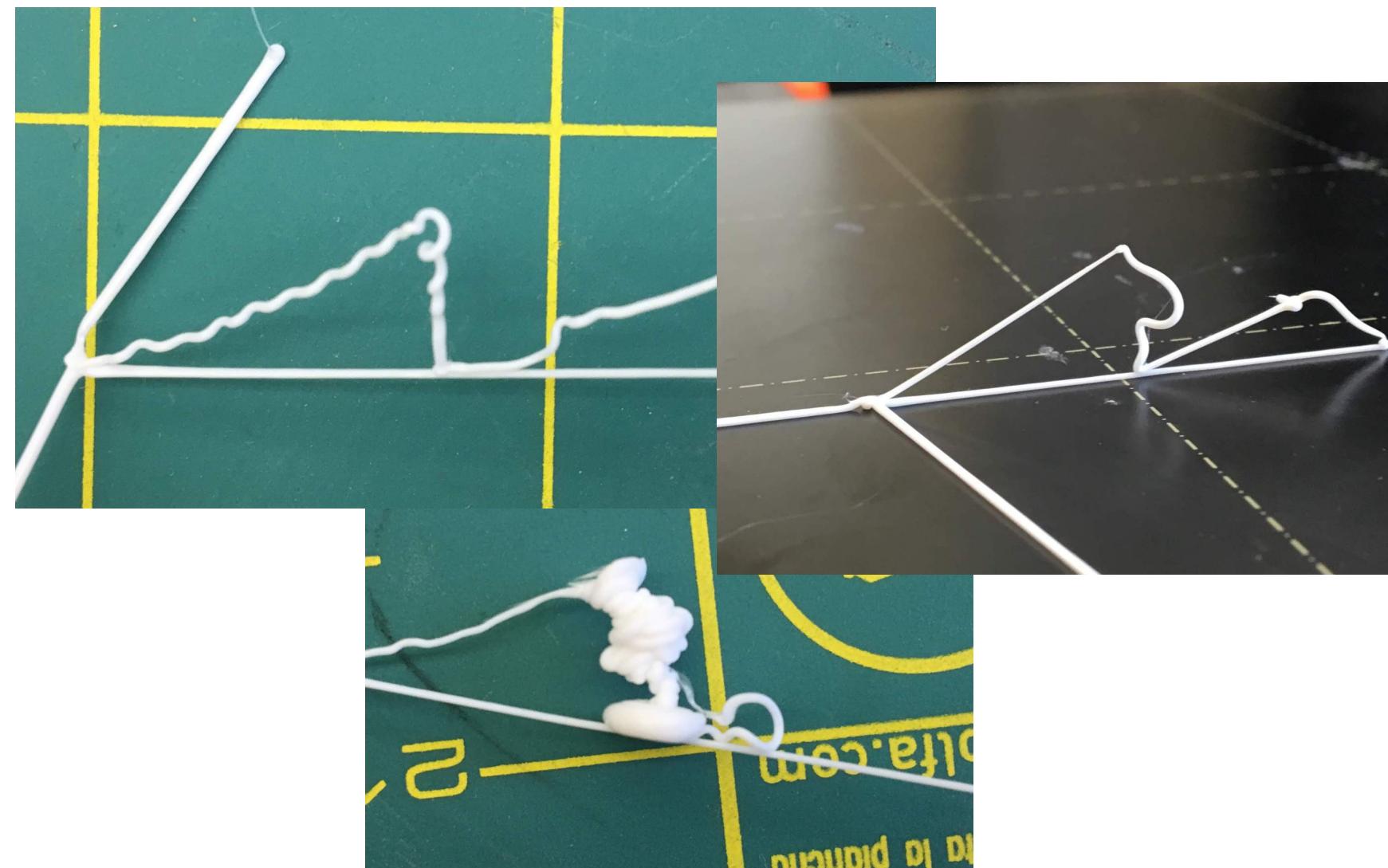
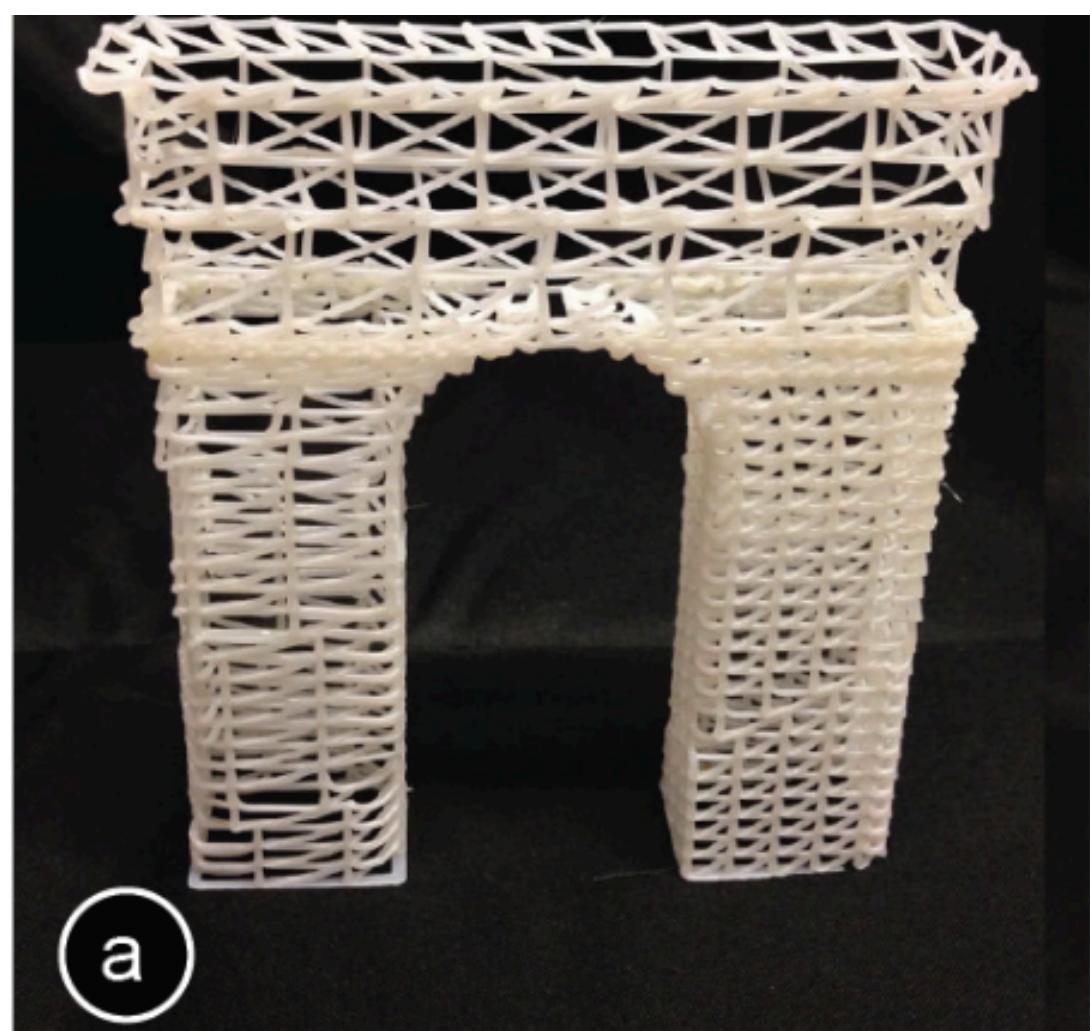
Programming for Exploratory Fab is Painful with Current Tools

Programming for Exploratory Fab is Painful with Current Tools



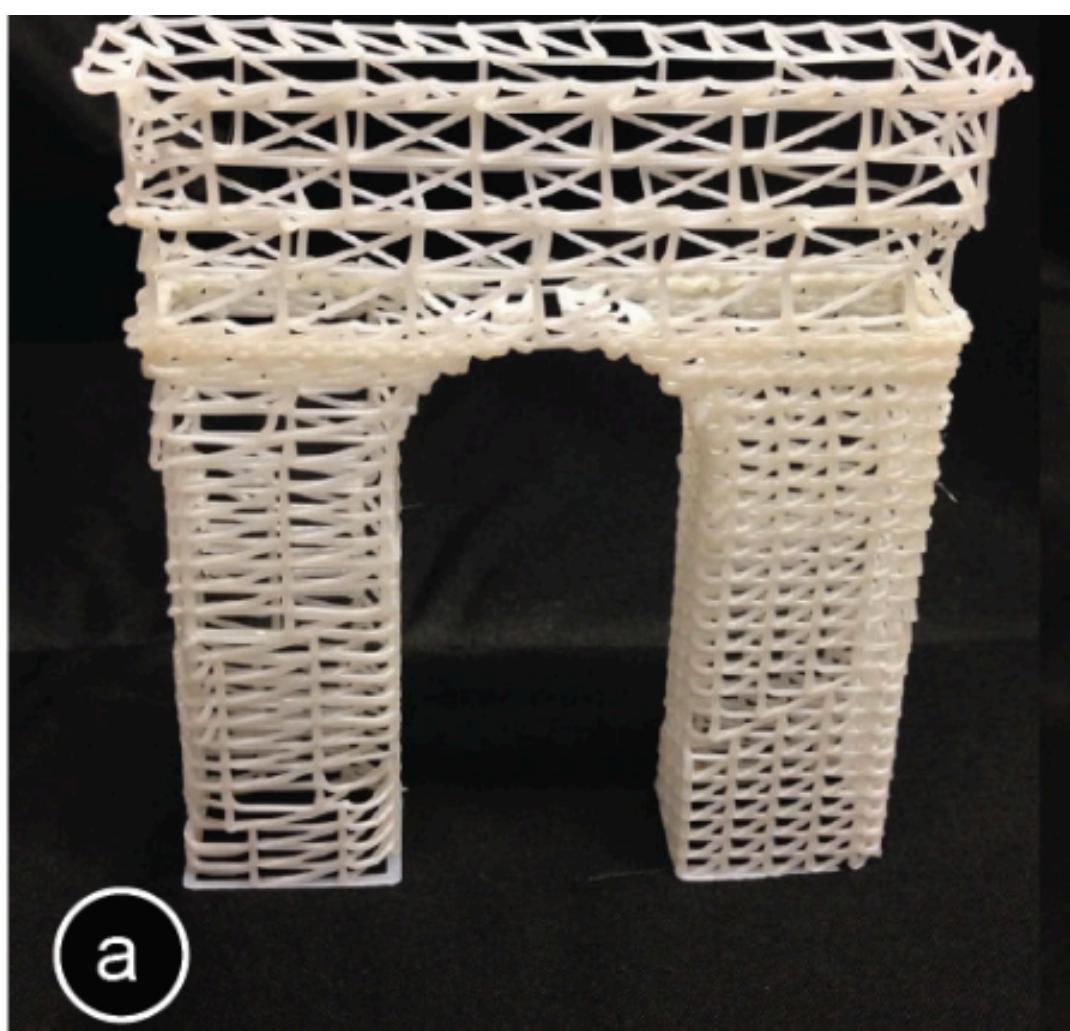
Mueller et al. Wireprint. 2014.

Programming for Exploratory Fab is Painful with Current Tools

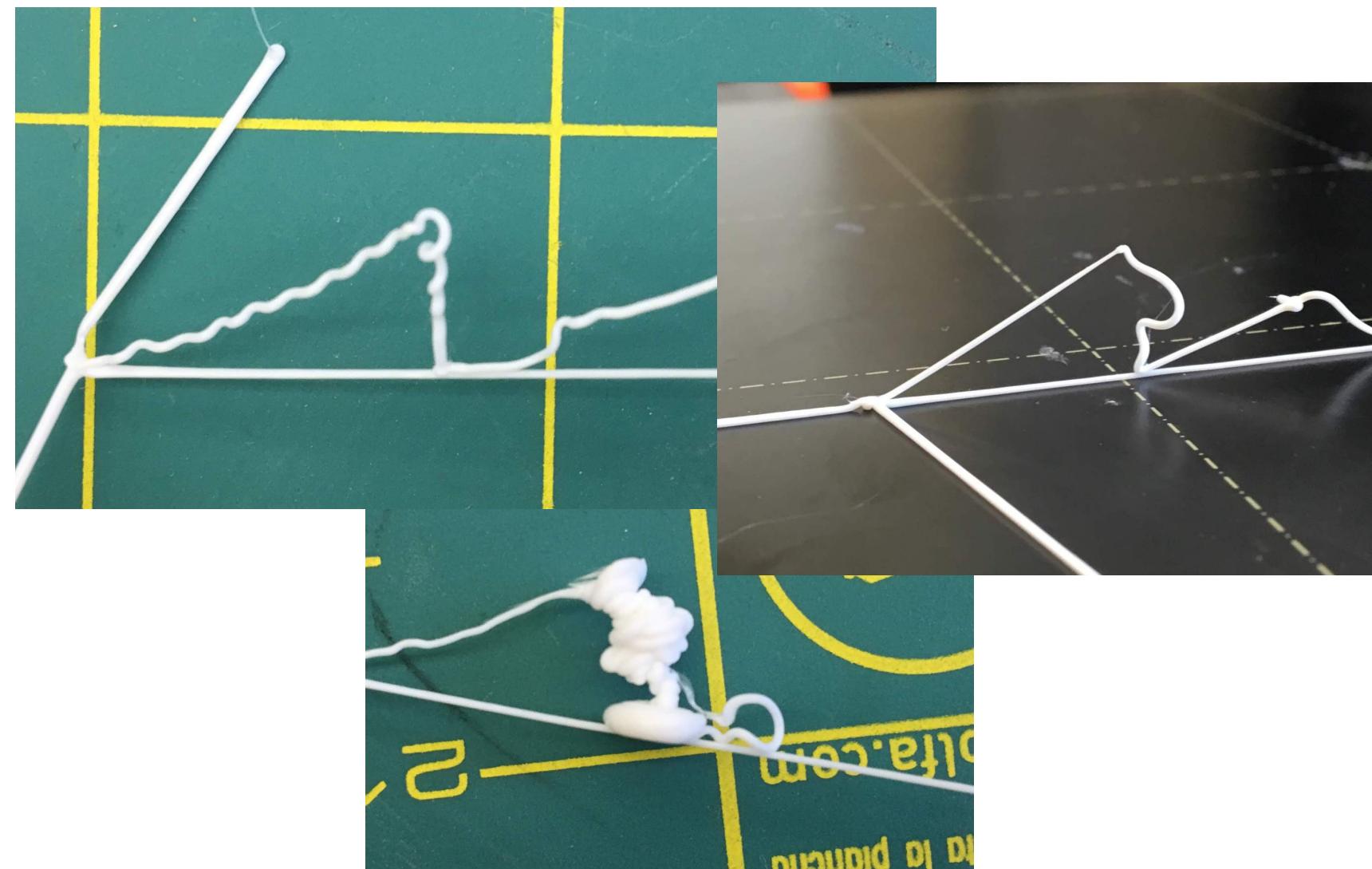


Mueller et al. Wireprint. 2014.

Programming for Exploratory Fab is Painful with Current Tools



Mueller et al. Wireprint. 2014.



Max length vertical with rate

```
G1 Z20 E4.00 F50
```

Single fin v1

```
G1 X100 Y100 Z0 F2000  
G1 X130 Y100 Z0 E4 F500 ; base  
G1 Z20 E4.00 F50 ; vertical side  
G1 X100 Y100 Z0 E4 F50 ; hypotenuse
```

Too big, try smaller fin

```
G1 X100 Y100 Z0 F2000  
G1 X120 Y100 Z0 E2 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 X100 Y100 Z0 E0.5 F50 ; hypotenuse
```

This is doing well, but try to make hypotenuse thicker without buckling

```
G1 X100 Y100 Z0.2 F2000  
G1 X120 Y100 Z0.2 E2.5 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 E0.2 F500 ; preemptive extrude before hypotenuse  
G1 X100 Y100 Z0.2 E2. F50 ; hypotenuse
```

Above worked okay at 205. Need to think about how to get hypotenuse less wiggly.

“While both GUIs and languages ... [make] it easy to say common things, a language empowers users to say uncommon things too.”

—Chasins et al. “PL and HCI: better together.” Comm. ACM ’21.

We need more programming power than raw G-Code

Max length vertical with rate

```
G1 Z20 E4.00 F50
```

Single fin v1

```
G1 X100 Y100 Z0 F2000  
G1 X130 Y100 Z0 E4 F500 ; base  
G1 Z20 E4.00 F50 ; vertical side  
G1 X100 Y100 Z0 E4 F50 ; hypotenuse
```

Too big, try smaller fin

```
G1 X100 Y100 Z0 F2000  
G1 X120 Y100 Z0 E2 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 X100 Y100 Z0 E0.5 F50 ; hypotenuse
```

This is doing well, but try to make hypotenuse thicker without buckling

```
G1 X100 Y100 Z0.2 F2000  
G1 X120 Y100 Z0.2 E2.5 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 E0.2 F500 ; preemptive extrude before hypotenuse  
G1 X100 Y100 Z0.2 E2. F50 ; hypotenuse
```

Above worked okay at 205. Need to think about how to get hypotenuse less wiggly.

We need more programming power than raw G-Code

Max length vertical with rate

```
G1 Z20 E4.00 F50
```

Functions?

Single fin v1

```
G1 X100 Y100 Z0 F2000  
G1 X130 Y100 Z0 E4 F500 ; base  
G1 Z20 E4.00 F50 ; vertical side  
G1 X100 Y100 Z0 E4 F50 ; hypotenuse
```

Too big, try smaller fin

```
G1 X100 Y100 Z0 F2000  
G1 X120 Y100 Z0 E2 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 X100 Y100 Z0 E0.5 F50 ; hypotenuse
```

This is doing well, but try to make hypotenuse thicker without buckling

```
G1 X100 Y100 Z0.2 F2000  
G1 X120 Y100 Z0.2 E2.5 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 E0.2 F500 ; preemptive extrude before hypotenuse  
G1 X100 Y100 Z0.2 E2. F50 ; hypotenuse
```

Above worked okay at 205. Need to think about how to get hypotenuse less wiggly.

We need more programming power than raw G-Code

Max length vertical with rate

```
G1 Z20 E4.00 F50
```

Functions?

Single fin v1

```
G1 X100 Y100 Z0 F2000  
G1 X130 Y100 Z0 E4 F500 ; ba  
G1 Z20 E4.00 F50 ; vertical side  
G1 X100 Y100 Z0 E4 F50 ; hypotenuse
```

Visualization?

Too big, try smaller fin

```
G1 X100 Y100 Z0 F2000  
G1 X120 Y100 Z0 E2 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 X100 Y100 Z0 E0.5 F50 ; hypotenuse
```

This is doing well, but try to make hypotenuse thicker without buckling

```
G1 X100 Y100 Z0.2 F2000  
G1 X120 Y100 Z0.2 E2.5 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 E0.2 F500 ; preemptive extrude before hypotenuse  
G1 X100 Y100 Z0.2 E2. F50 ; hypotenuse
```

Above worked okay at 205. Need to think about how to get hypotenuse less wiggly.

We need more programming power than raw G-Code

Max length vertical with rate

```
G1 Z20 E4.00 F50
```

Single fin v1

```
G1 X100 Y100 Z0 F2000  
G1 X130 Y100 Z0 E4 F500 ; ba  
G1 Z20 E4.00 F50 ; vertical  
G1 X100 Y100 Z0 E4 F50 ; hyp
```

Functions?

Visualization?

Testing?

Too big, try smaller fin

```
G1 X100 Y100 Z0 F2000  
G1 X120 Y100 Z0 E2 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 X100 Y100 Z0 E0.5 F50 ; hypotenuse
```

This is doing well, but try to make hypotenuse thicker without buckling

```
G1 X100 Y100 Z0.2 F2000  
G1 X120 Y100 Z0.2 E2.5 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 E0.2 F500 ; preemptive extrude before hypotenuse  
G1 X100 Y100 Z0.2 E2. F50 ; hypotenuse
```

Above worked okay at 205. Need to think about how to get hypotenuse less wiggly.

We need more programming power than raw G-Code

Max length vertical with rate

```
G1 Z20 E4.00 F50
```

Functions?

Single fin v1

```
G1 X100 Y100 Z0 F2000  
G1 X130 Y100 Z0 E4 F500 ; ba  
G1 Z20 E4.00 F50 ; vertical  
G1 X100 Y100 Z0 E4 F50 ; hyp
```

Visualization?

Too big, try smaller fin

```
G1 X100 Y100 Z0 F2000  
G1 X120 Y100 Z0 E2 F500 ;  
G1 Z10 E2.00 F50 ; vertic  
G1 X100 Y100 Z0 E0.5 F50 ; hypotenuse
```

Testing?

This is doing well, but try to make hypotenuse thicker without buckling

```
G1 X100 Y100 Z0.2 F2000  
G1 X120 Y100 Z0.2 E2.5 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 E0.2 F500 ; preemptive extrude before hypotenuse  
G1 X100 Y100 Z0.2 E2. F50 ; hypotenuse
```

Above worked okay at 205. Need to think about how to get hypotenuse less wiggly.

We need more programming power than raw G-Code

Max length vertical with rate

```
G1 Z20 E4.00 F50
```

Single fin v1

```
G1 X100 Y100 Z0 F2000  
G1 X130 Y100 Z0 E4 F500 ; base  
G1 Z20 E4.00 F50 ; vertical side  
G1 X100 Y100 Z0 E4 F50 ; hypotenuse
```

Functions?

Visualization?

Testing?

Too big, try smaller fin

```
G1 X100 Y100 Z0 F2000  
G1 X120 Y100 Z0 E2 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 X100 Y100 Z0 E0.5 F50 ; hypotenuse
```

Previewing in-situ?

This is doing well, but try:

Interoperating with outside libraries?

```
G1 X100 Y100 Z0.2 F2000  
G1 X120 Y100 Z0.2 E2.5 F500 ; base  
G1 Z10 E2.00 F50 ; vertical side  
G1 E0.2 F500 ; preemptive extrude before hypotenuse  
G1 X100 Y100 Z0.2 E2. F50 ; hypotenuse
```

Above worked okay at 205. Need to think about how to get hypotenuse less wiggly.

We need more programming power than raw G-Code

Max length vertical with rate

```
G1 Z20 E4.00 F50
```

Single fin v1

```
G1 X100 Y100 Z0 F2000  
G1 X130 Y100 Z0 E4 F500 ; base  
G1 Z20 E4.00 F50 ; vertical  
G1 X100 Y100 Z0 E4 F50 ; hypotenuse
```

Functions?

Visualization?

Testing?

Too big, try smaller fin

```
G1 X100 Y100 Z0 F2000  
G1 X120 Y100 Z0 E2 F500 ; base  
G1 Z10 E2.00 F50 ; vertical  
G1 X100 Y100 Z0 E0.5 F50 ; hypotenuse
```

Previewing in-situ?

This is doing well, but try:

```
G1 X100 Y100 Z0.2 F2000  
G1 X120 Y100 Z0.2 E2.5 F500 ; base  
G1 Z10 E2.00 F50 ; vertical  
G1 E0.2 F500 ; preemptive  
G1 X100 Y100 Z0.2 E2. F500
```

Interoperating with outside libraries?

Adapting to different machines?

Above worked okay at 205. Need to think about how to get hypotenuse less wiggly.

We need more programming power than raw G-Code

Max length vertical with rate

```
G1 Z20 E4.00 F50
```

Single fin v1

```
G1 X100 Y100 Z0 F2000  
G1 X130 Y100 Z0 E4 F500 ; ba  
G1 Z20 E4.00 F50 ; vertical  
G1 X100 Y100 Z0 E4 F50 ; hyp
```

Too big, try smaller fin

```
G1 X100 Y100 Z0 F2000  
G1 X120 Y100 Z0 E2 F500 ;  
G1 Z10 E2.00 F50 ; vertical  
G1 X100 Y100 Z0 E0.5 F50 ; hypotenuse
```

This is doing well, but try to

```
G1 X100 Y100 Z0.2 F20  
G1 X120 Y100 Z0.2 E2.5 F500 ; base  
G1 Z10 E2.00 F50 ; vertical  
G1 E0.2 F500 ; preemptive  
G1 X100 Y100 Z0.2 E2. F500
```

Functions?

Visualization?

Testing?

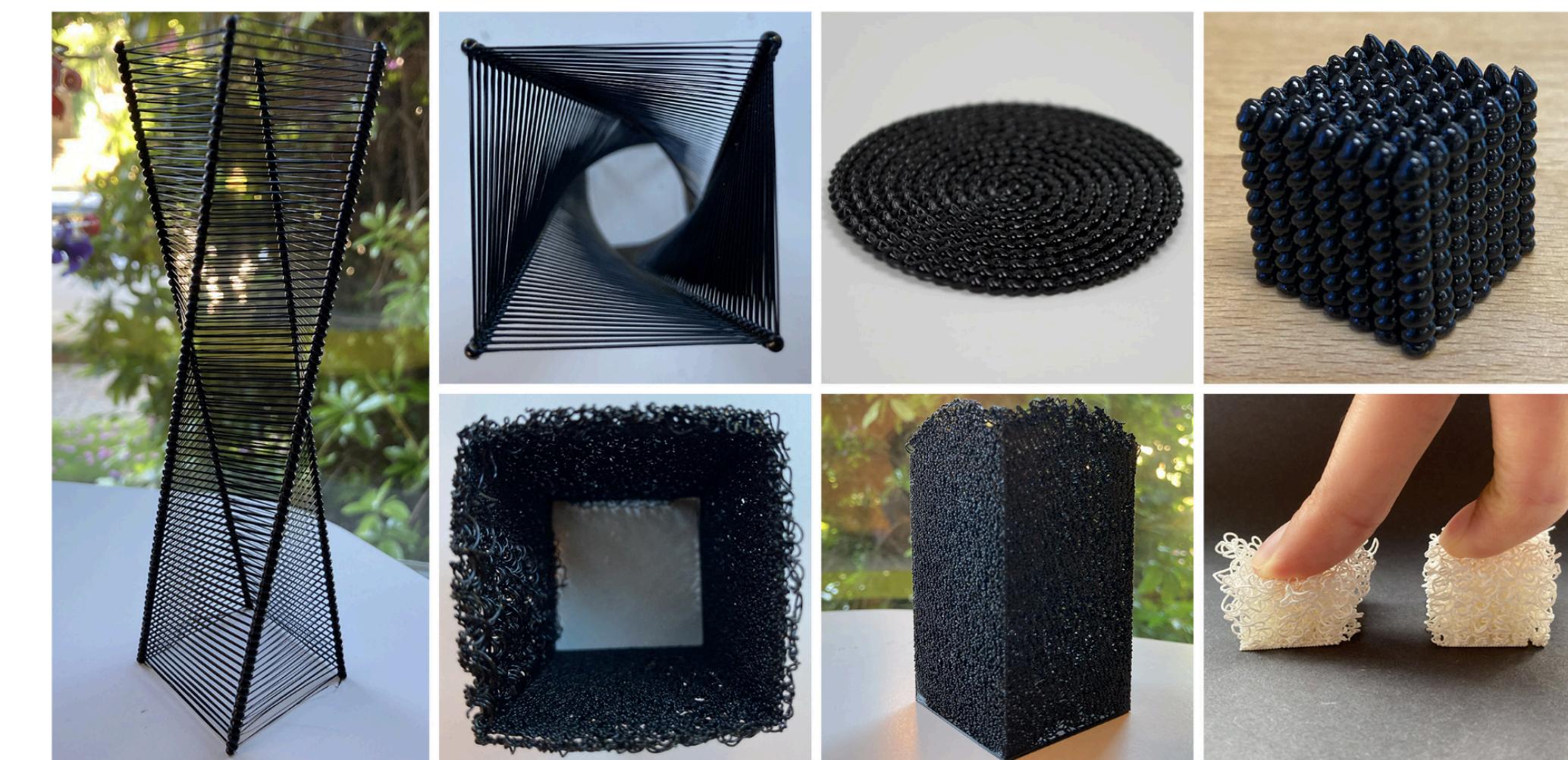
Previewing in-situ?

Interoperating with outside libraries?

Adapting to different machines?

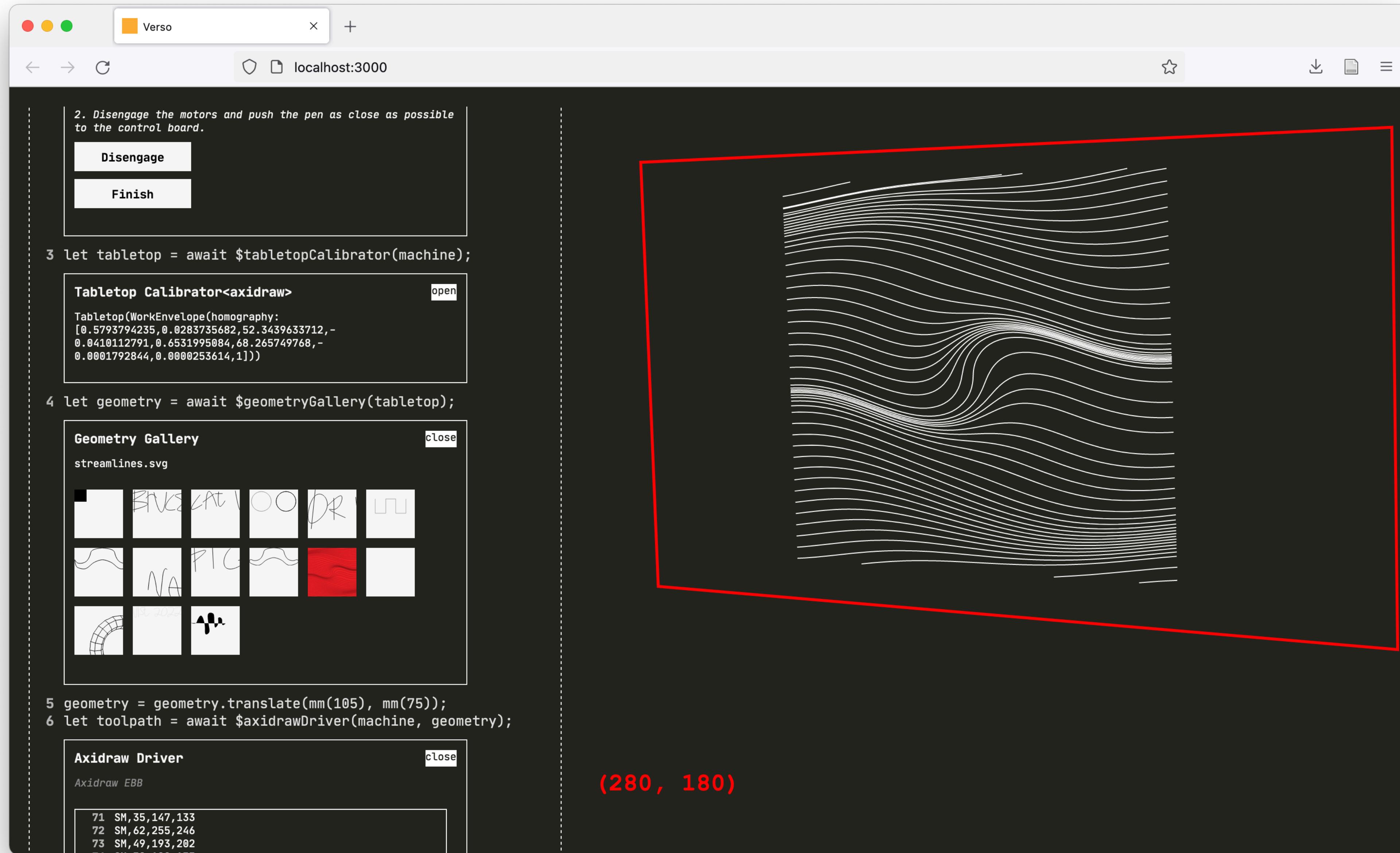
Above worked okay at 205. Need to think about how to get hypotenuse less wiggly.

```
fab.moveExtrude(  
    fab.maxX / 2 + x,  
    fab.maxY / 2 + y,  
    z  
)
```



Subbaraman and Peek. p5.fab. 2022.

Verso is a tool for *fabrication-as-programming*.



Verso is a tool for *fabrication-as-programming*.

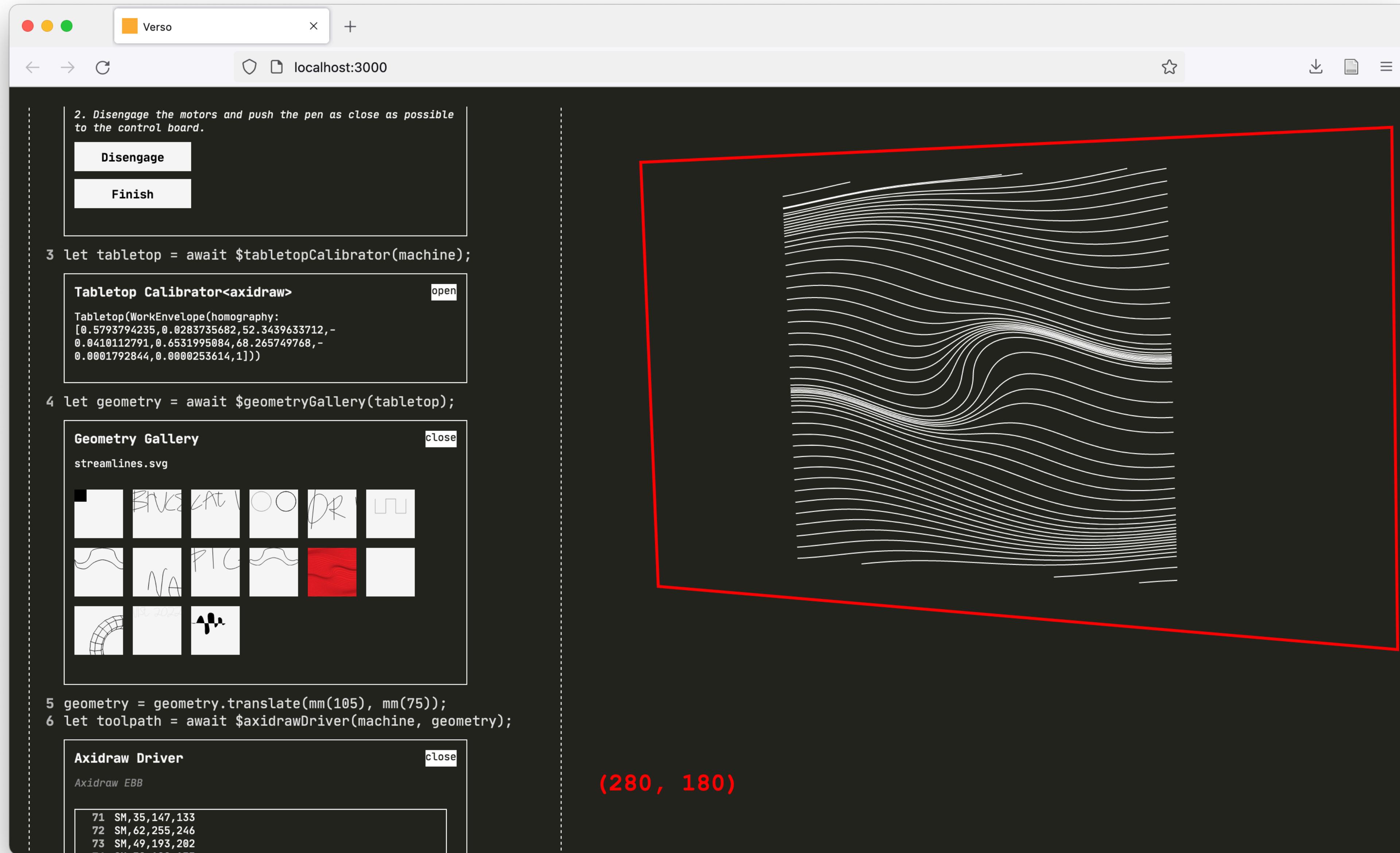
Code Editor

The screenshot shows the Verso software interface. On the left, a "Code Editor" window displays a sequence of numbered steps:

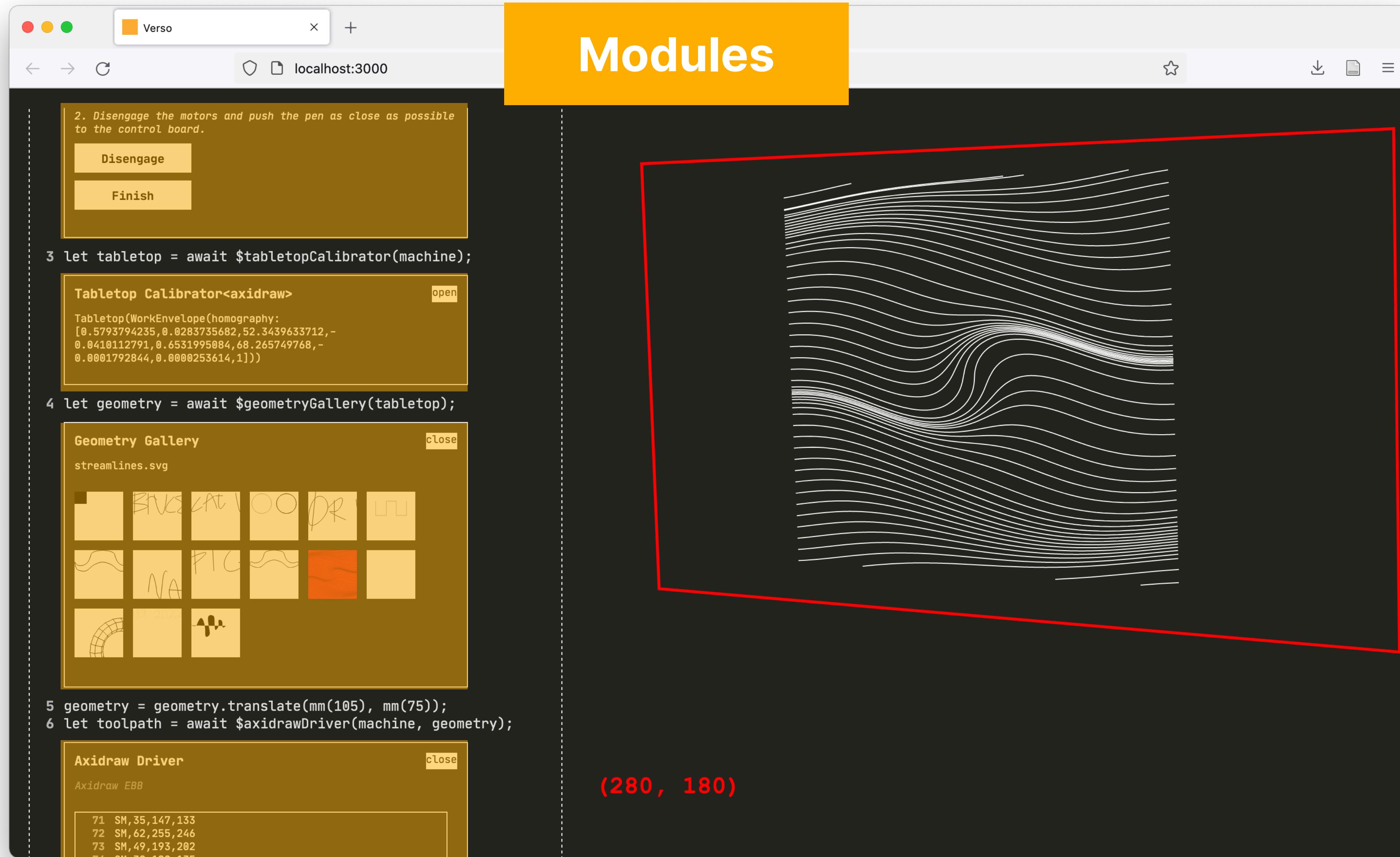
2. Disengage the motors and push the pen as close as possible to the control board.
 - Disengage
 - Finish
- 3 let tabletop = await \$tabletopCalibrator(machine);
 - Tabletop Calibrator<xidraw> open
 - Tabletop(WorkEnvelope(homography:
[0.5793794235, 0.0283735682, 52.3439633712, -
0.0410112791, 0.6531995084, 68.265749768, -
0.0001792844, 0.0000253614, 1]))
- 4 let geometry = await \$geometryGallery(tabletop);
 - Geometry Gallery close
 - streamlines.svg
 - grid
 - BNK
 - CAT
 - OO
 - DR
 - LW
 - wave
 - NA
 - PIC
 - wave
 - red
 - grid
 - BNK
 - wave
- 5 geometry = geometry.translate(mm(105), mm(75));
- 6 let toolpath = await \$xidrawDriver(machine, geometry);
 - Axidraw Driver close
 - Axidraw EBB
 - 71 SM,35,147,133
 - 72 SM,62,255,246
 - 73 SM,49,193,202
 - 74 SM,70,160,175

The right side of the interface shows a preview area with a red border containing a complex white line drawing on a black background. In the bottom left corner of the preview area, the coordinates "(280, 180)" are displayed in red text.

Verso is a tool for *fabrication-as-programming*.

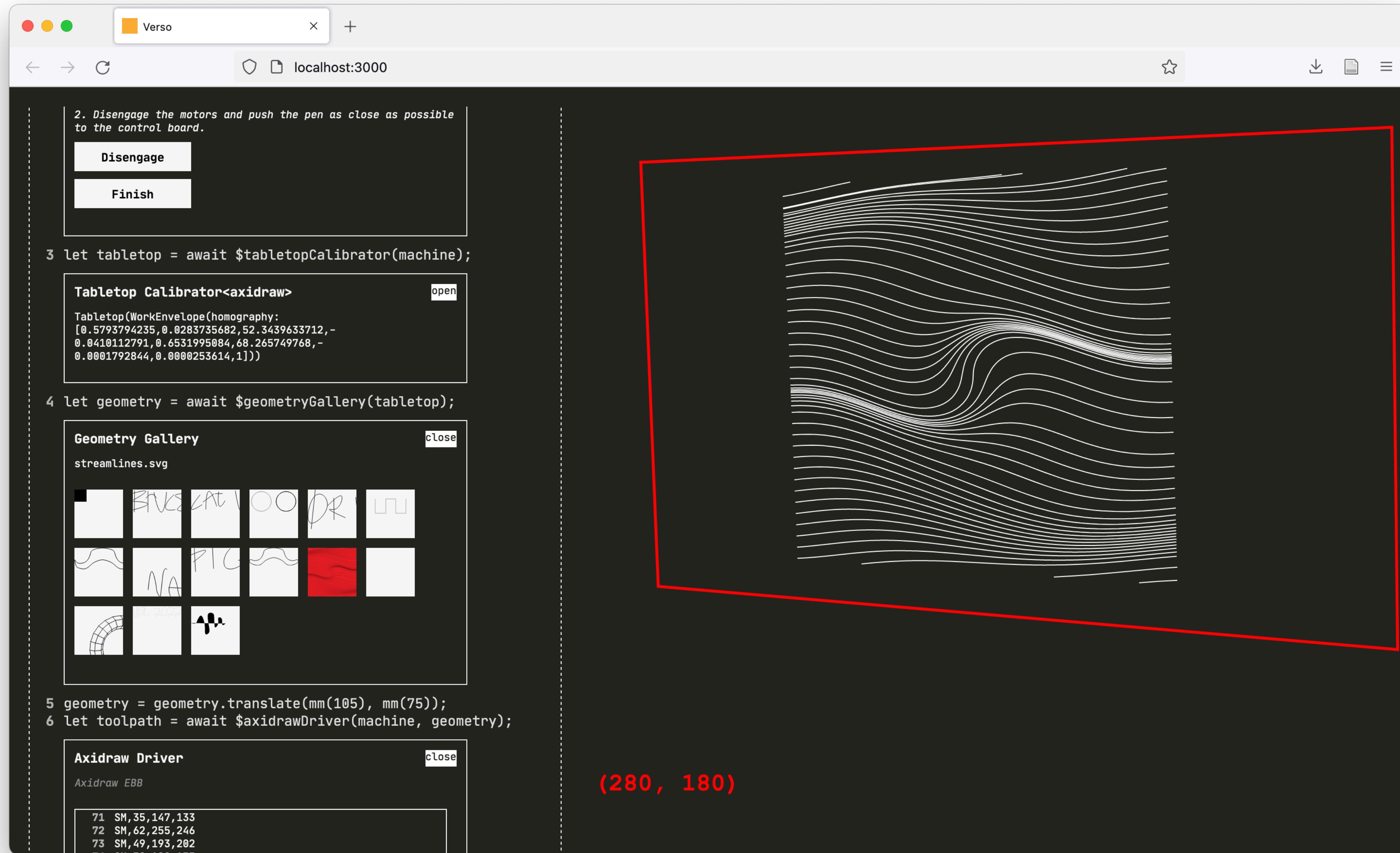


Verso is a tool for *fabrication-as-programming*.



(280, 180)

Verso is a tool for *fabrication-as-programming*.



Verso is a tool for *fabrication-as-programming*.

The screenshot shows the Verso application interface running in a web browser (localhost:3000). The interface is divided into several sections:

- Code Editor:** Displays a sequence of numbered steps:
 2. Disengage the motors and push the pen as close as possible to the control board.
 - Disengage
 - Finish
 - 3 let tabletop = await \$tabletopCalibrator(machine);
 - Tabletop Calibrator<axidraw>
 - open
 - Tabletop(WorkEnvelope(homography:
[0.5793794235, 0.0283735682, 52.3439633712, -0.0410112791, 0.6531995084, 68.265749768, -0.0001792844, 0.0000253614, 1]))
 - 4 let geometry = await \$geometryGallery(tabletop);
 - Geometry Gallery
 - close
 - streamlines.svg
 - grid of preview images (e.g., BNK, CAT, 100, DR, etc.)
 - 5 geometry = geometry.translate(mm(105), mm(75));
 - 6 let toolpath = await \$axidrawDriver(machine, geometry);
 - Axidraw Driver
 - close
 - Axidraw EBB
 - list of coordinates:
 - 71 SM,35,147,133
 - 72 SM,62,255,246
 - 73 SM,49,193,202
 - 74 SM,70,166,175
- Tool Dialogs:** Three floating windows provide details for each step: "Tabletop Calibrator", "Geometry Gallery", and "Axidraw Driver".
- Visualization Area:** A large red-bordered area on the right contains a complex streamline pattern (white lines on black background) representing the toolpath.
- Text Labels:** Red text "(280, 180)" is located at the bottom left of the visualization area. A yellow box on the right contains the text "Visualization to be Projected".

Fabrication-as-programming brings to digital fabrication:

Fabrication-as-programming brings to digital fabrication:

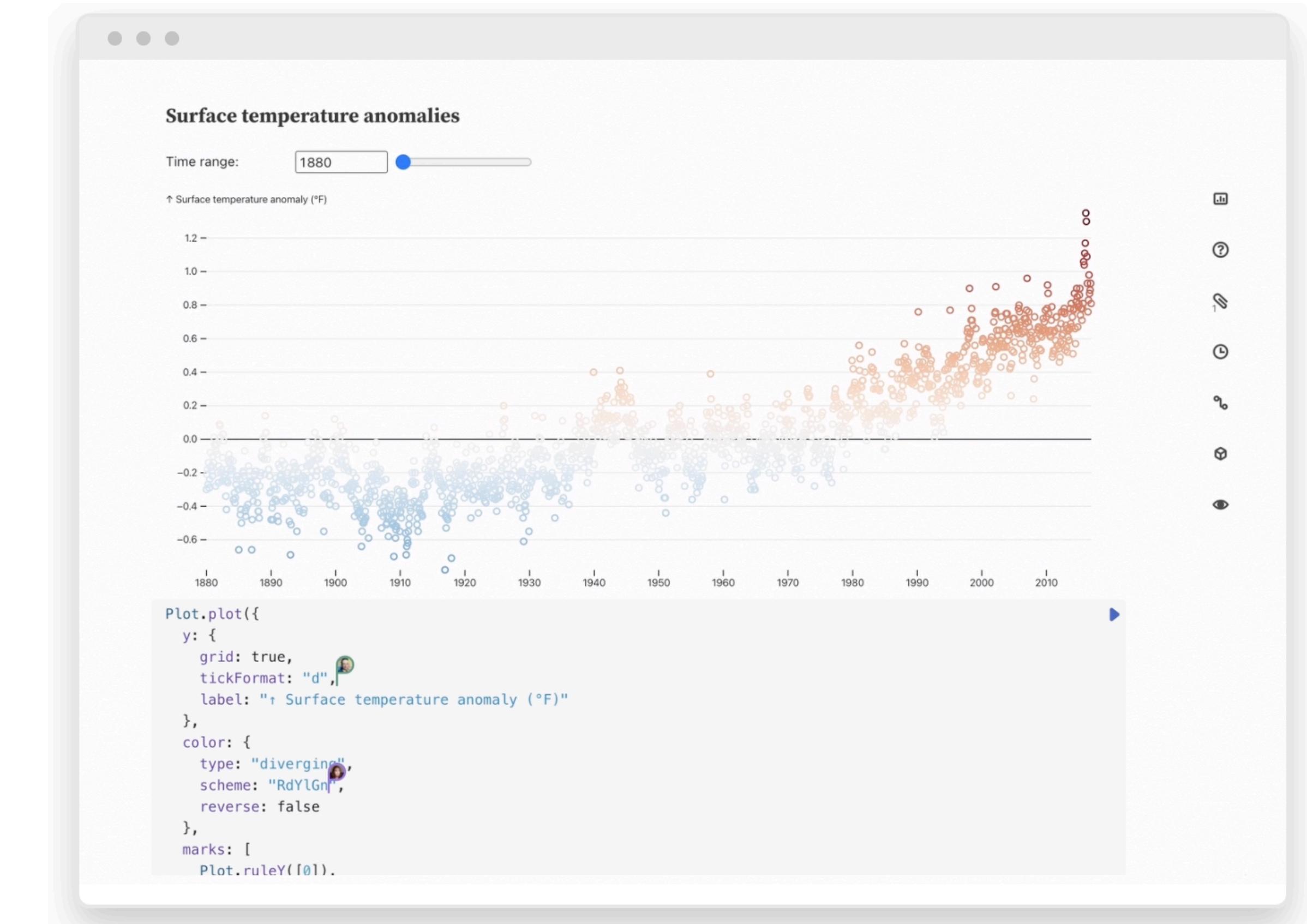
```
let q1_max = 36. in
let grades =
  $dataframe
    = |q1_max| +. 24. +. $fslider 0. 40. — 0 —
      + "A1" "A2" "A3" "Midterm" "Final"
      + "Andrew" 80. 92. 83.5 95. 88.
      + "Cyrus" 61. 64. 98. 70. 85.
      + "David" 75. 81. 73. 82. 79.
      +
in
let averages = compute_weighted_averages grades weights in
let cutoffs =
  $grade_cutoffs averages
    + 1 2 4 4 4
    + 45 55 65 75 85 95
    + D C B A
    + 0 10 20 30 40 50 60 70 80 90 100
in
format_for_university (assign_grades averages cutoffs)
```

Filling Typed Holes with Live GUIs. Omar et al. 2019.

Multimodal Programming

Fabrication-as-programming brings to digital fabrication:

```
let q1_max = 36. in
let grades =
  $dataframe
    = |q1_max| +. 24. +. $fslider 0. 40.
      +-----+
      |
      +-----+
      "A1" "A2" "A3" "Midterm" "Final"
      "Andrew" 80. 92. 83.5 95. 88.
      "Cyrus" 61. 64. 98. 70. 85.
      "David" 75. 81. 73. 82. 79.
      +
in
let averages = compute_weighted_averages grades weights in
let cutoffs =
  $grade_cutoffs averages
  +-----+
  | 2 4 4 4 4
  D C B A
  0 10 20 30 40 50 60 70 80 90 100
in
format_for_university (assign_grades averages cutoffs)
```



Filling Typed Holes with Live GUIs. Omar et al. 2019.

Multimodal Programming

D3.js and Observable Notebook.

Data visualization

Multimodal Programming

Modules: inline GUIs that accept and return values.

Multimodal Programming

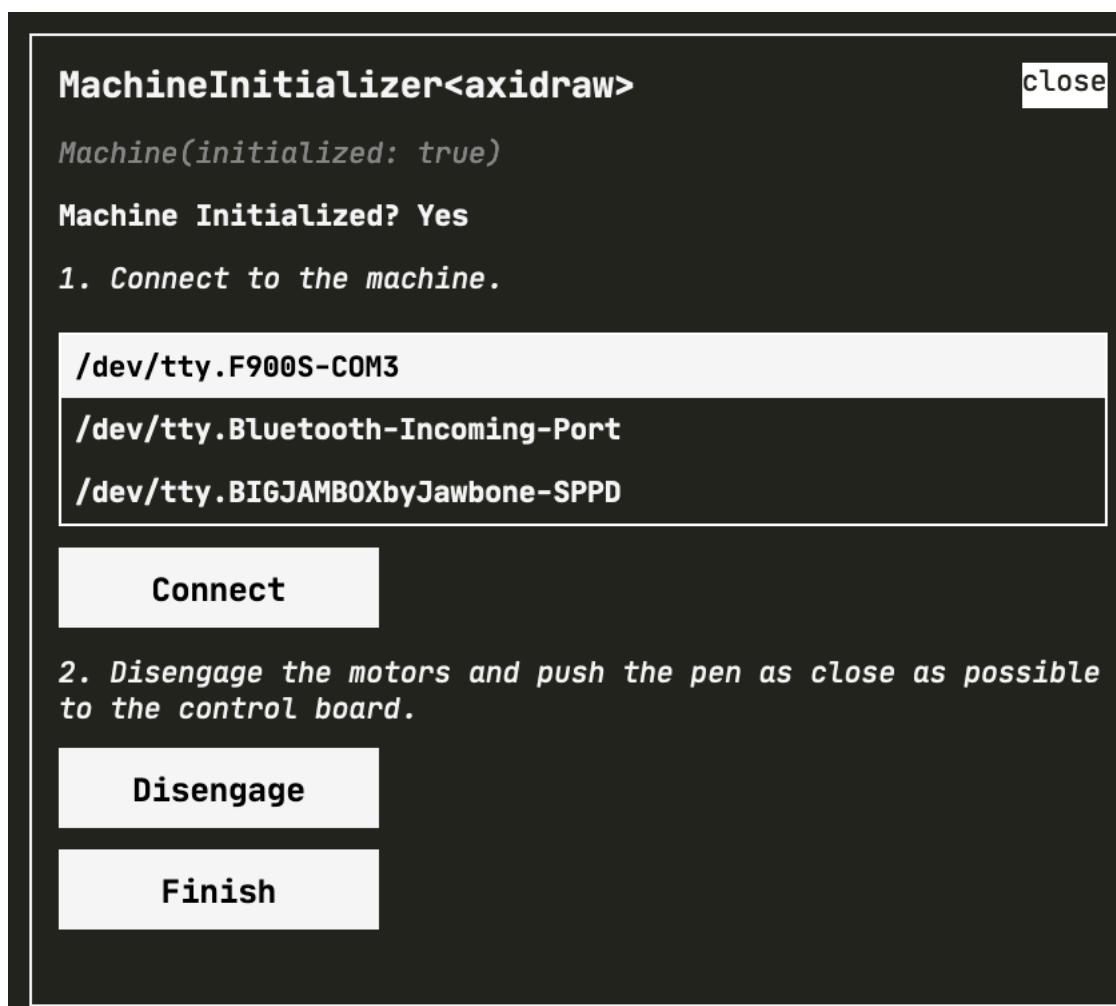
Modules: inline GUIs that accept and return values.

```
$machineInitializer(myAxidraw)
```

Multimodal Programming

Modules: inline GUIs that accept and return values.

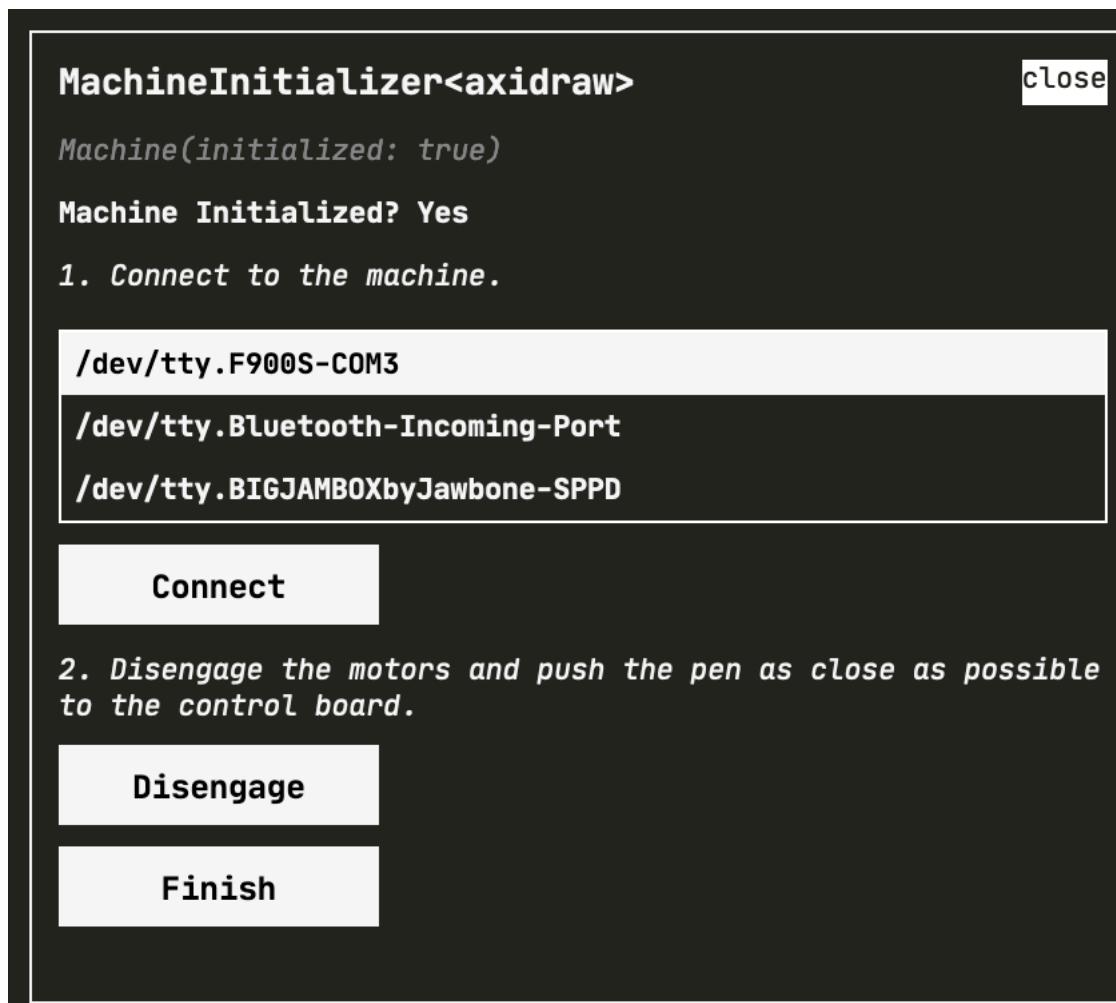
\$machineInitializer(myAxidraw)



Multimodal Programming

Modules: inline GUIs that accept and return values.

```
Machine {  
    type: "axidraw", → $machineInitializer(myAxidraw)  
    initialized: false  
}
```

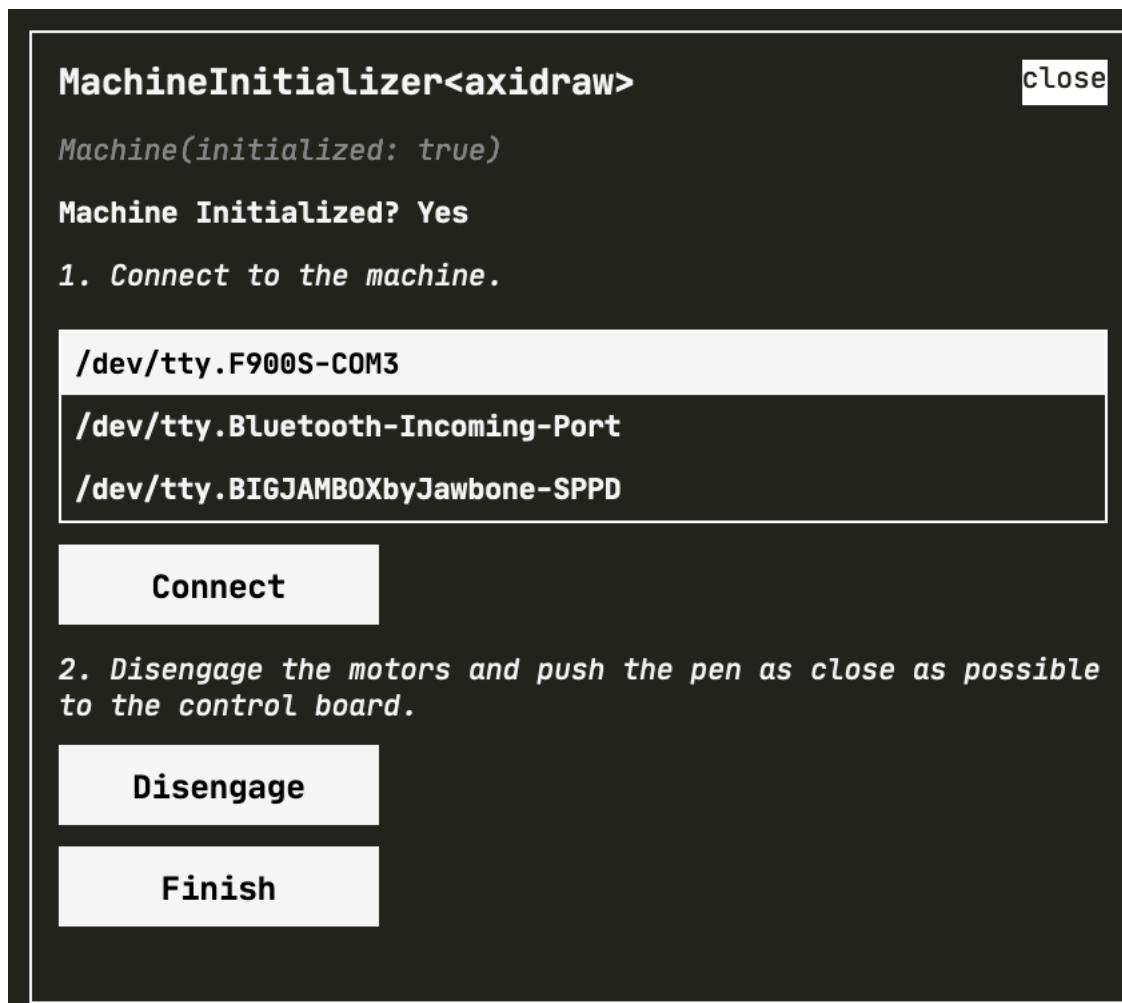


Multimodal Programming

Modules: inline GUIs that accept and return values.

```
Machine {  
  type: "axidraw", → $machineInitializer(myAxidraw)  
  initialized: false  
}
```

```
Machine {  
  type: "axidraw",  
  initialized: true  
}
```

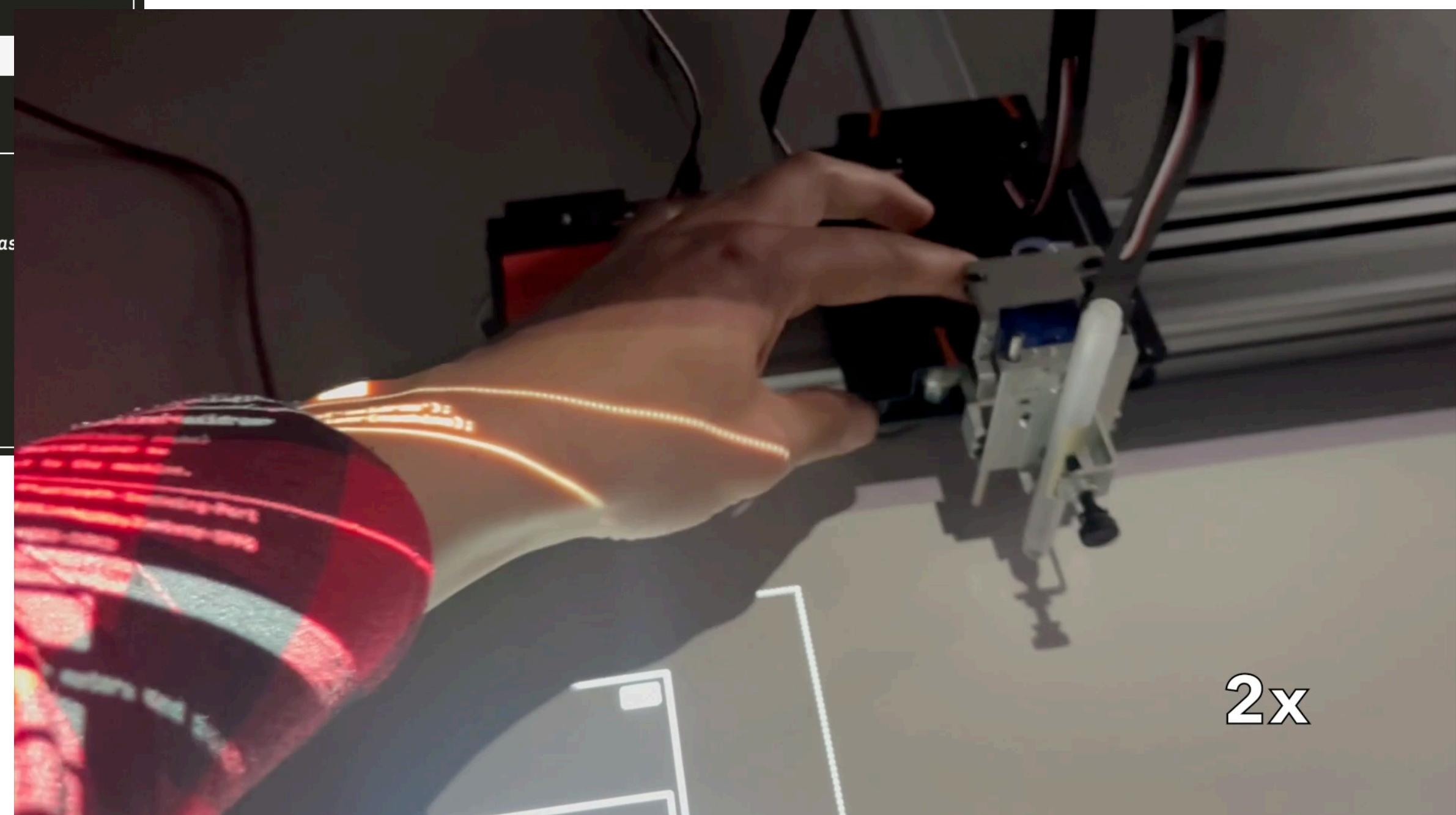
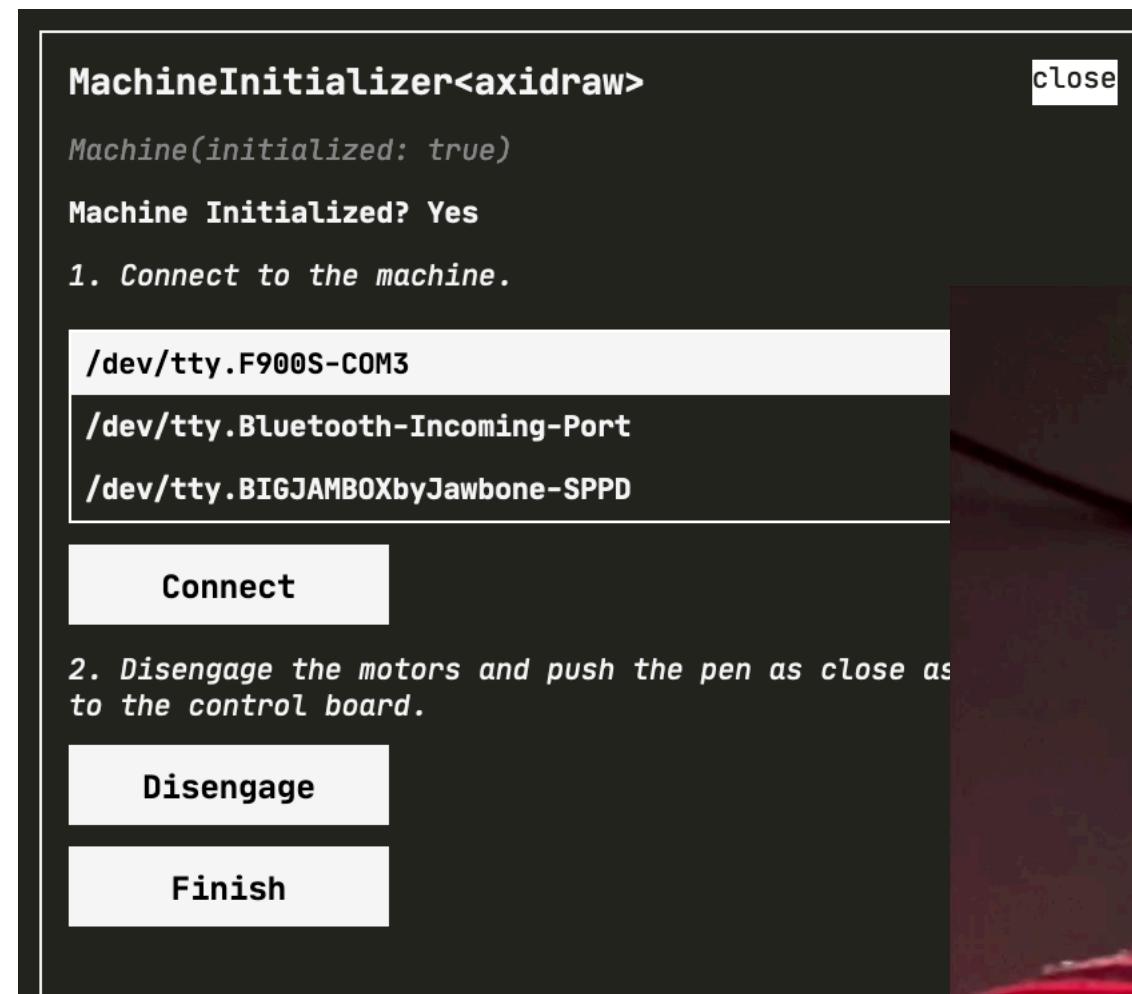


Multimodal Programming

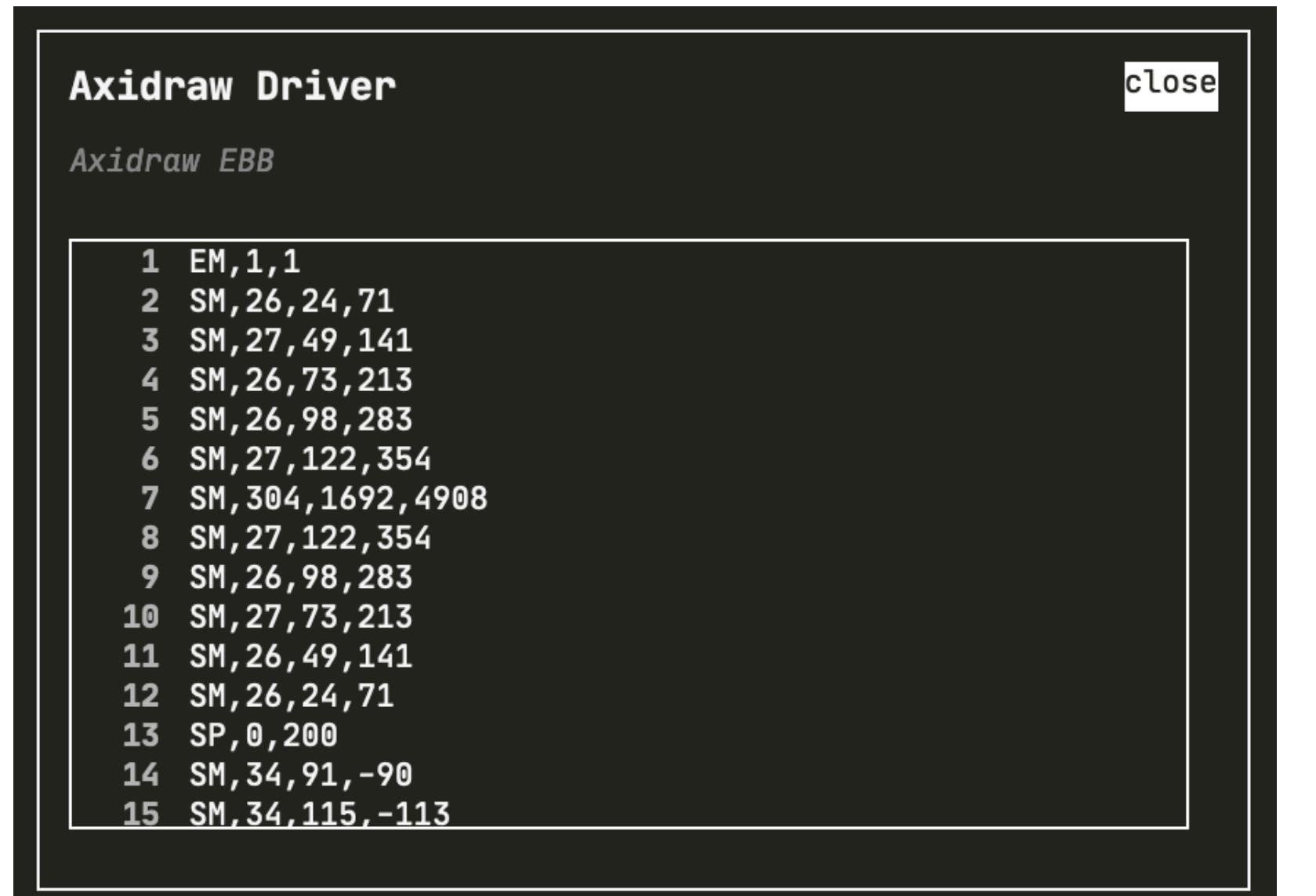
Modules: inline GUIs that accept and return values.

```
Machine {  
  type: "axidraw", → $machineInitializer(myAxidraw)  
  initialized: false  
}
```

```
Machine {  
  type: "axidraw", →  
  initialized: true  
}
```



Interoperate with existing tools



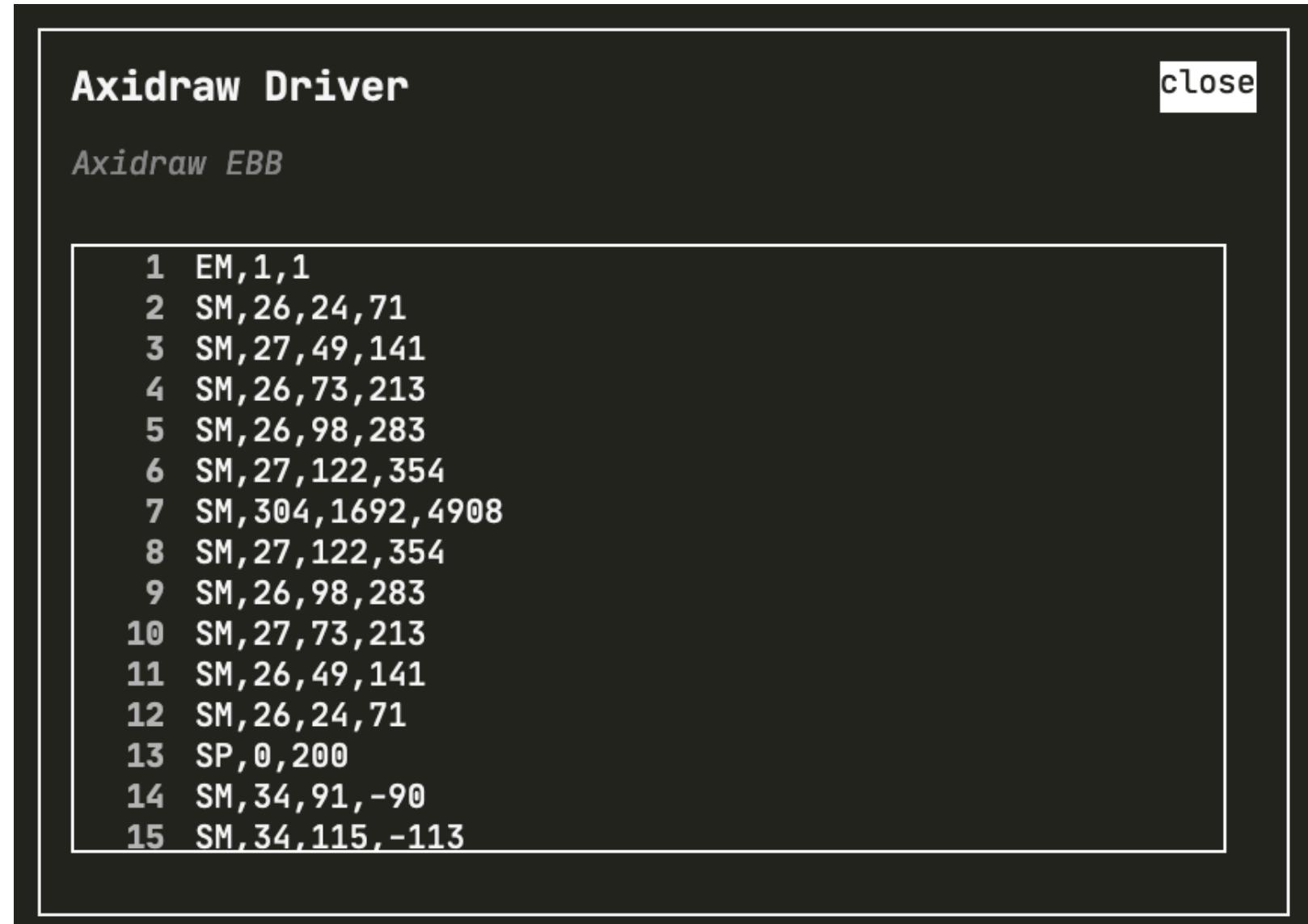
Axidraw Driver

Axidraw EBB

close

```
1 EM,1,1
2 SM,26,24,71
3 SM,27,49,141
4 SM,26,73,213
5 SM,26,98,283
6 SM,27,122,354
7 SM,304,1692,4908
8 SM,27,122,354
9 SM,26,98,283
10 SM,27,73,213
11 SM,26,49,141
12 SM,26,24,71
13 SP,0,200
14 SM,34,91,-90
15 SM,34,115,-113
```

Interoperate with existing tools



Axidraw Driver

Axidraw EBB

```
1 EM,1,1
2 SM,26,24,71
3 SM,27,49,141
4 SM,26,73,213
5 SM,26,98,283
6 SM,27,122,354
7 SM,304,1692,4908
8 SM,27,122,354
9 SM,26,98,283
10 SM,27,73,213
11 SM,26,49,141
12 SM,26,24,71
13 SP,0,200
14 SM,34,91,-90
15 SM,34,115,-113
```

Selectively deploy parts of a toolpath



Interoperate with existing tools

Axidraw Driver

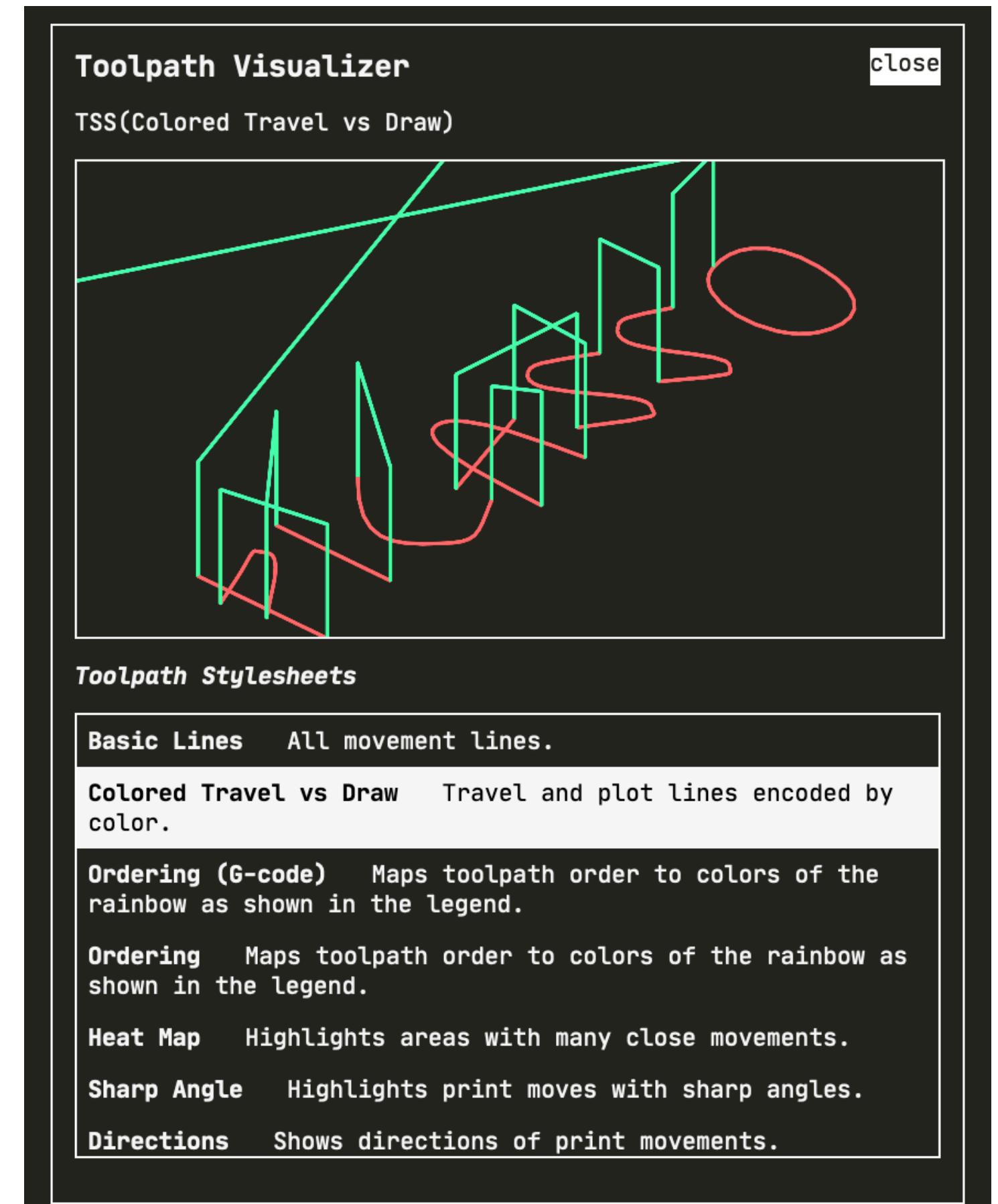
Axidraw EBB

```
1 EM,1,1
2 SM,26,24,71
3 SM,27,49,141
4 SM,26,73,213
5 SM,26,98,283
6 SM,27,122,354
7 SM,304,1692,4908
8 SM,27,122,354
9 SM,26,98,283
10 SM,27,73,213
11 SM,26,49,141
12 SM,26,24,71
13 SP,0,200
14 SM,34,91,-90
15 SM,34,115,-113
```

Selectively deploy parts of a toolpath



Visualize machine behavior



Data Visualization

Toolpath stylesheets (TSS): generate task-specific views of a given toolpath.

Data Visualization

Toolpath stylesheets (TSS): generate task-specific views of a given toolpath.



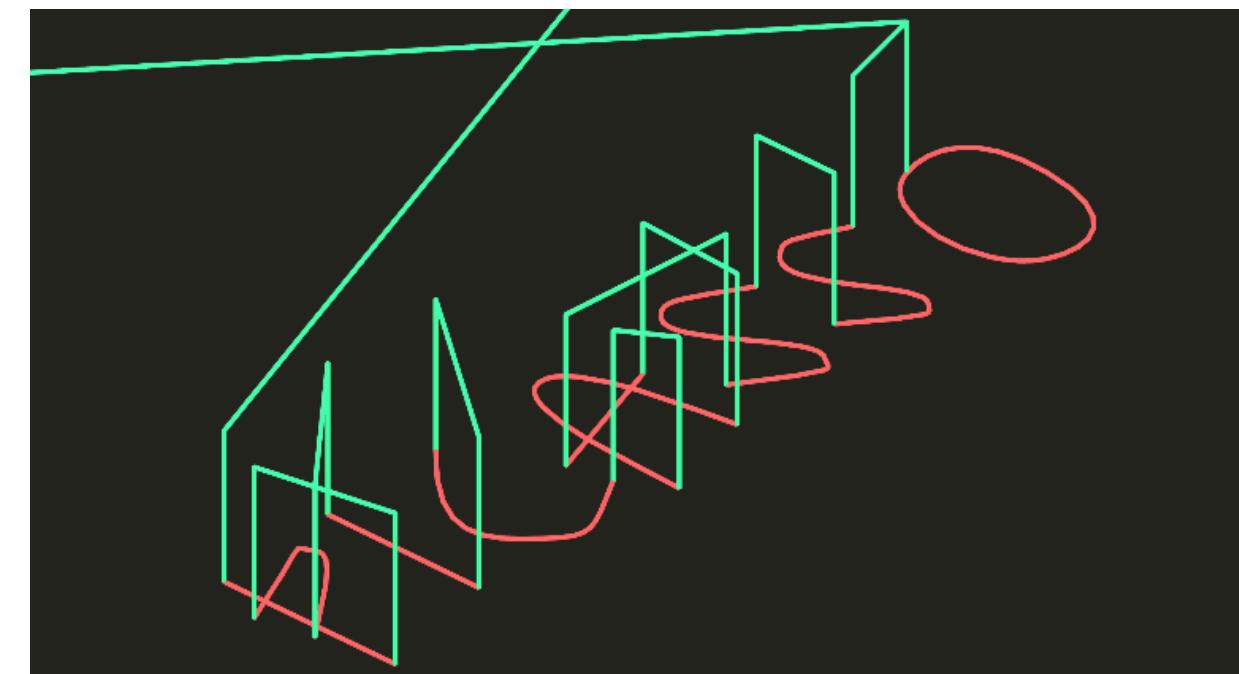
Pen markings

Data Visualization

Toolpath stylesheets (TSS): generate task-specific views of a given toolpath.



Pen markings



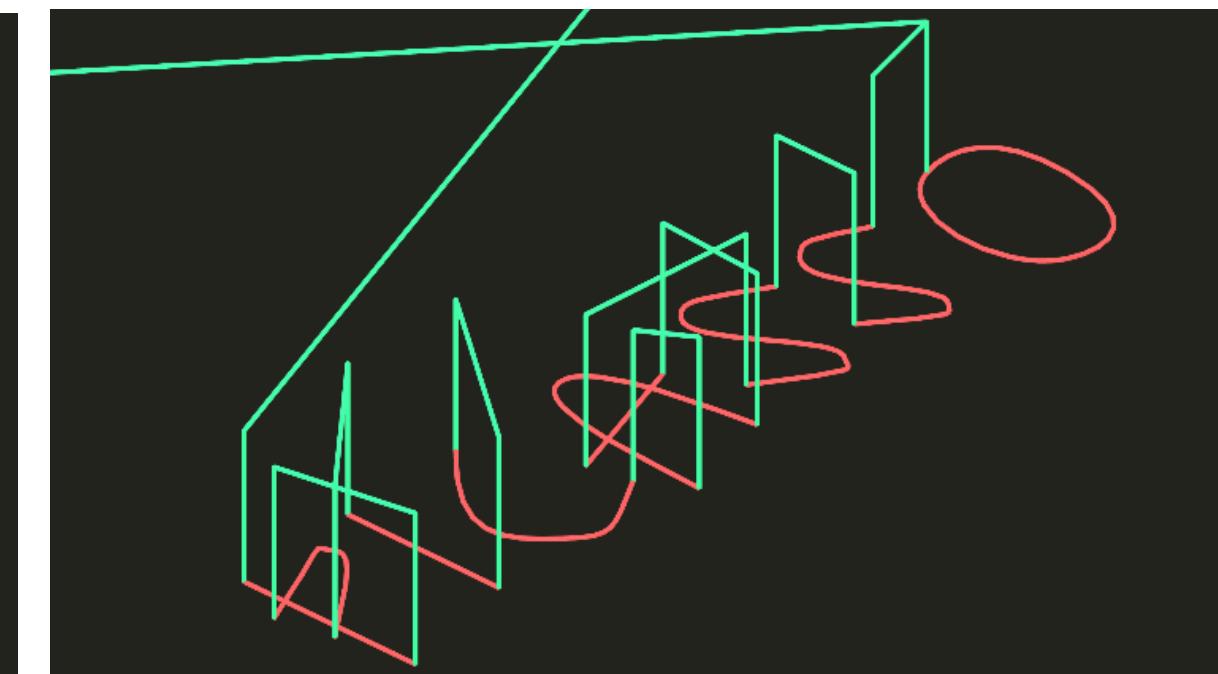
Markings vs. travel

Data Visualization

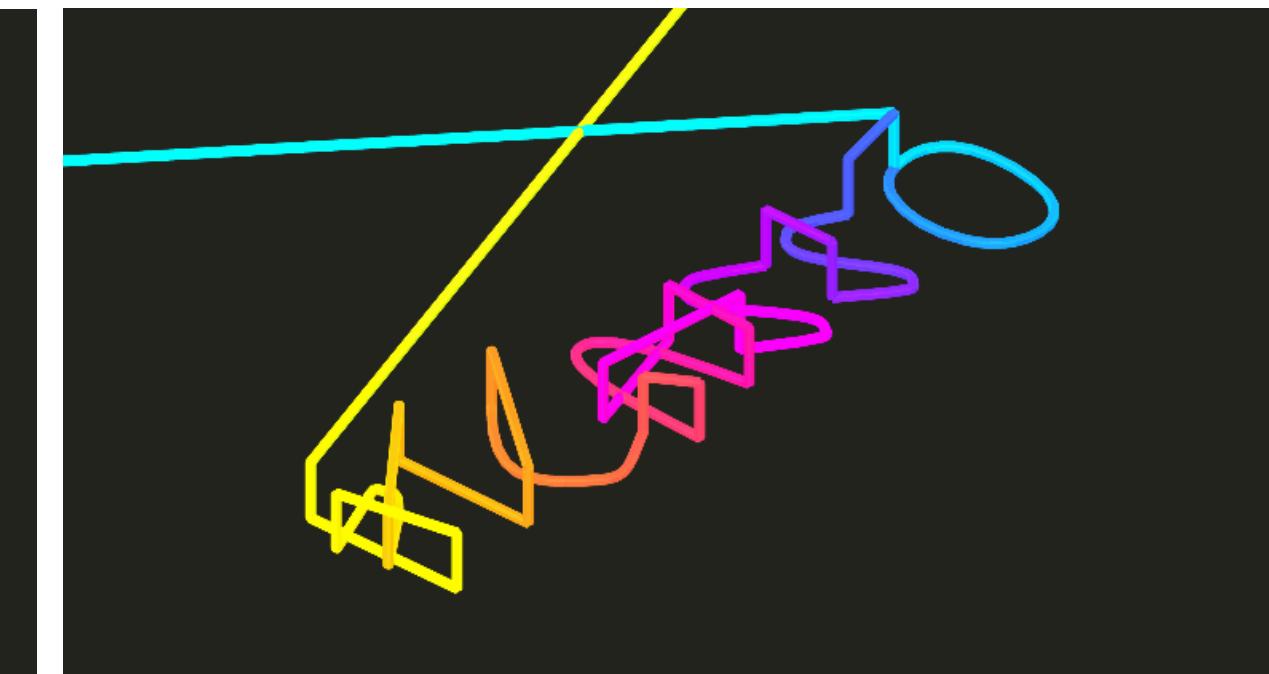
Toolpath stylesheets (TSS): generate task-specific views of a given toolpath.



Pen markings



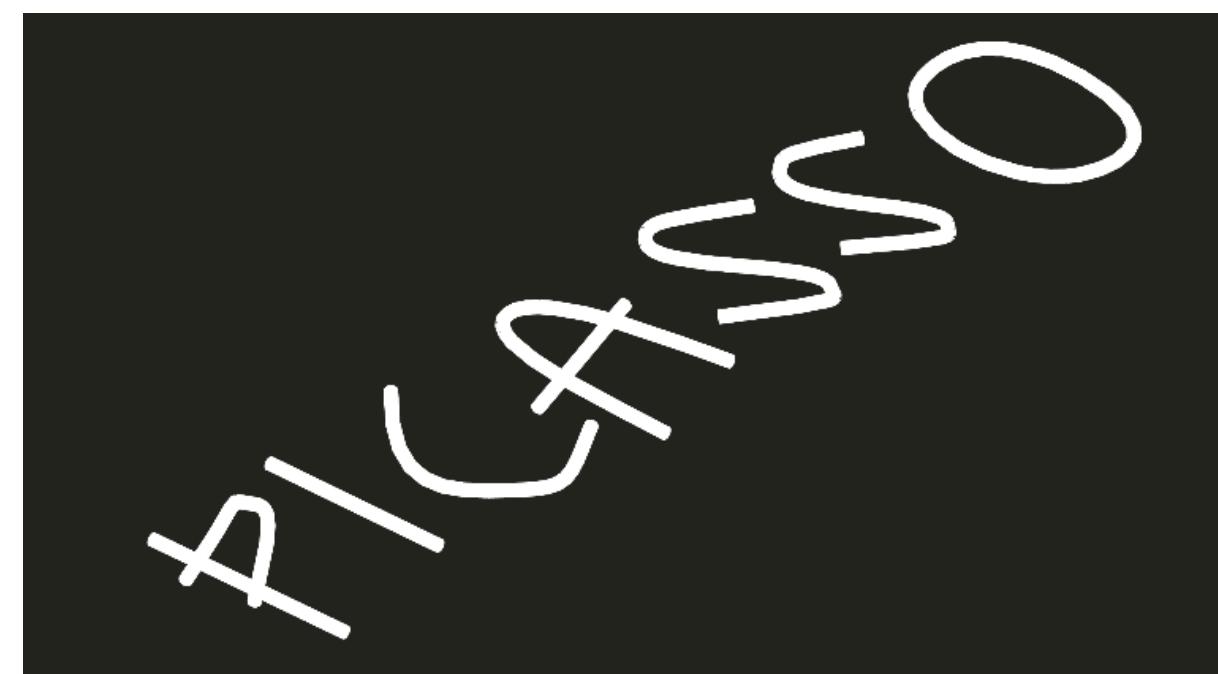
Markings vs. travel



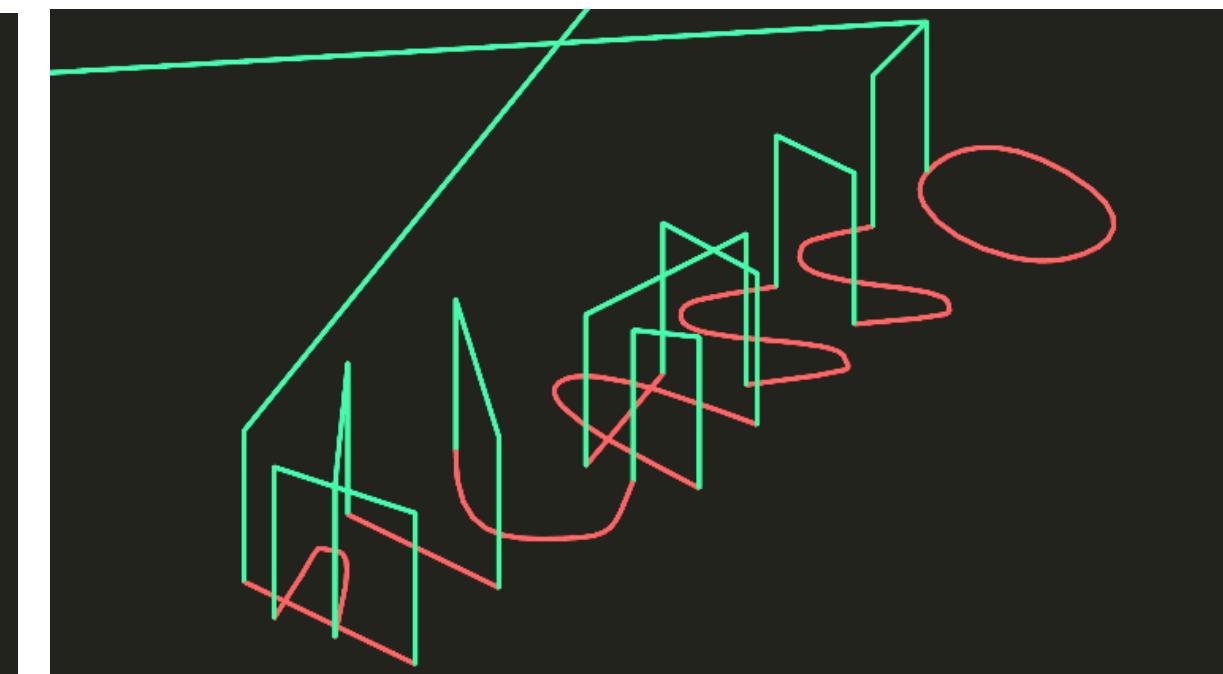
Move order

Data Visualization

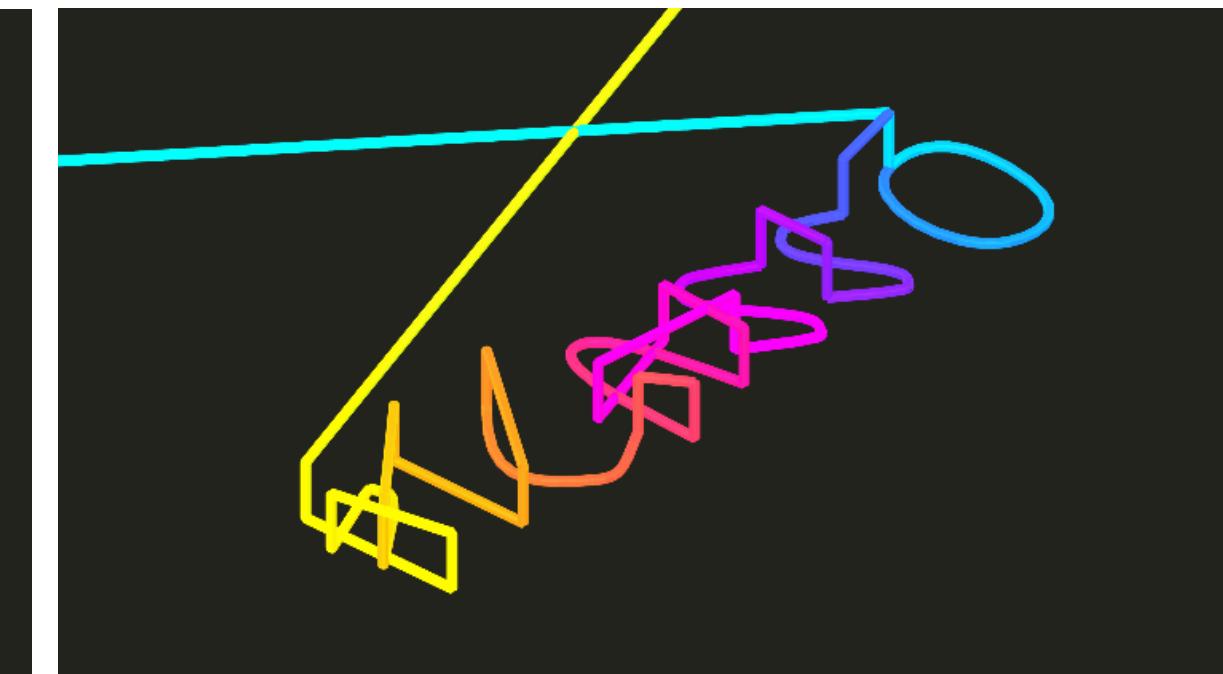
Toolpath stylesheets (TSS): generate task-specific views of a given toolpath.



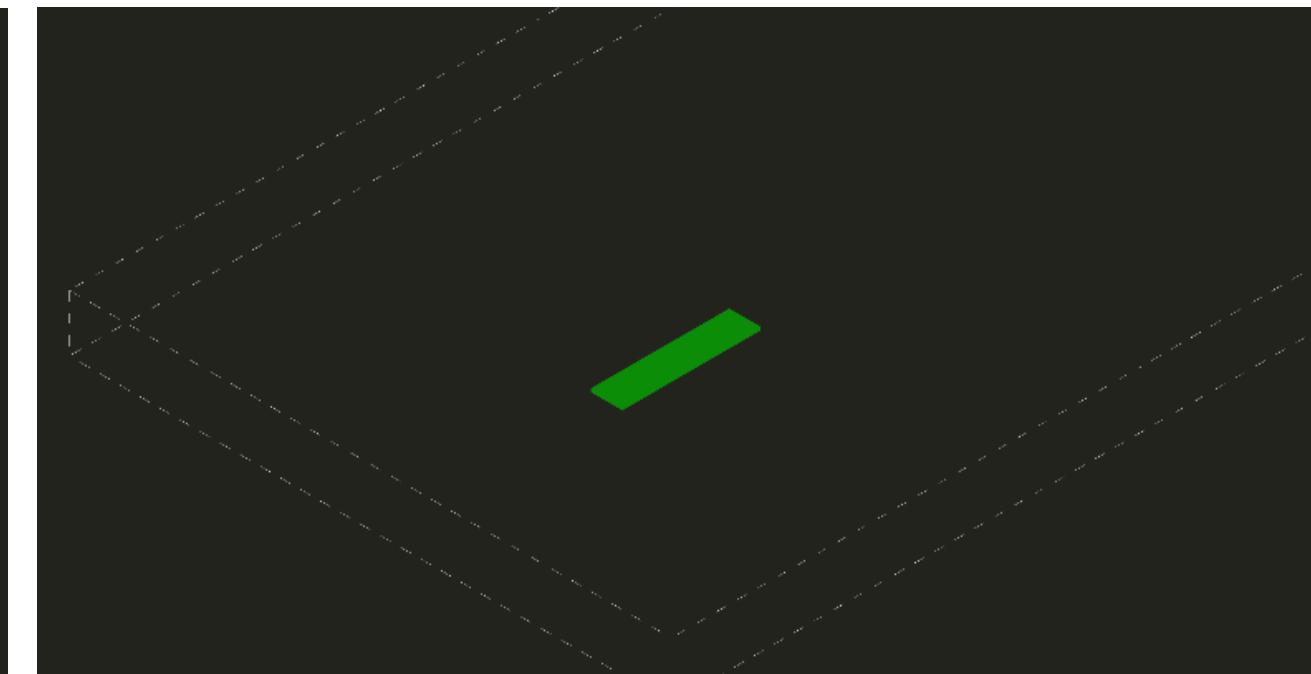
Pen markings



Markings vs. travel



Move order



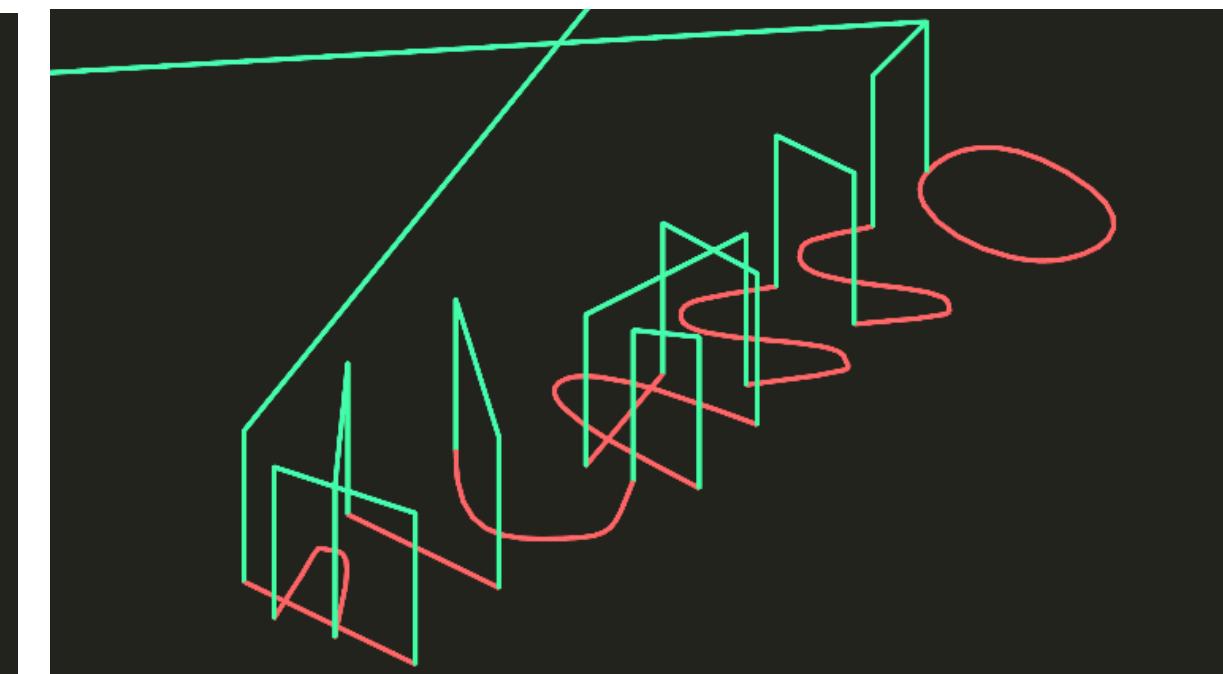
Scale w.r.t. work envelope

Data Visualization

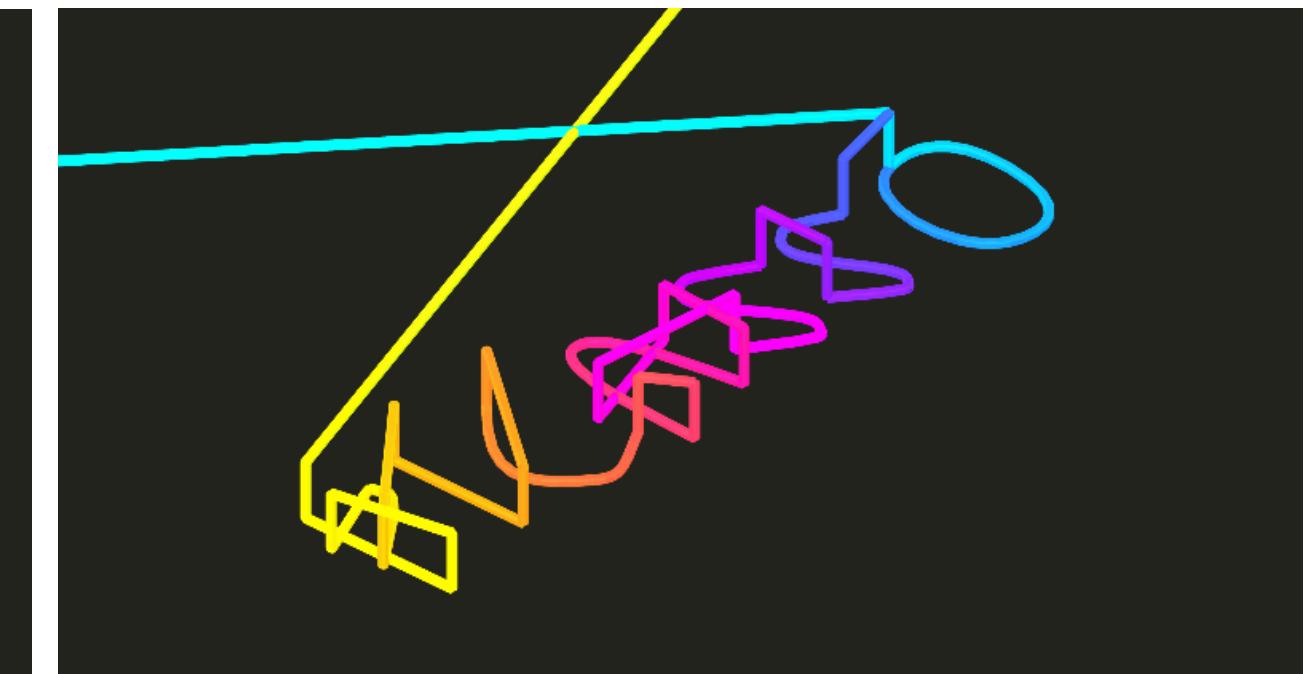
Toolpath stylesheets (TSS): generate task-specific views of a given toolpath.



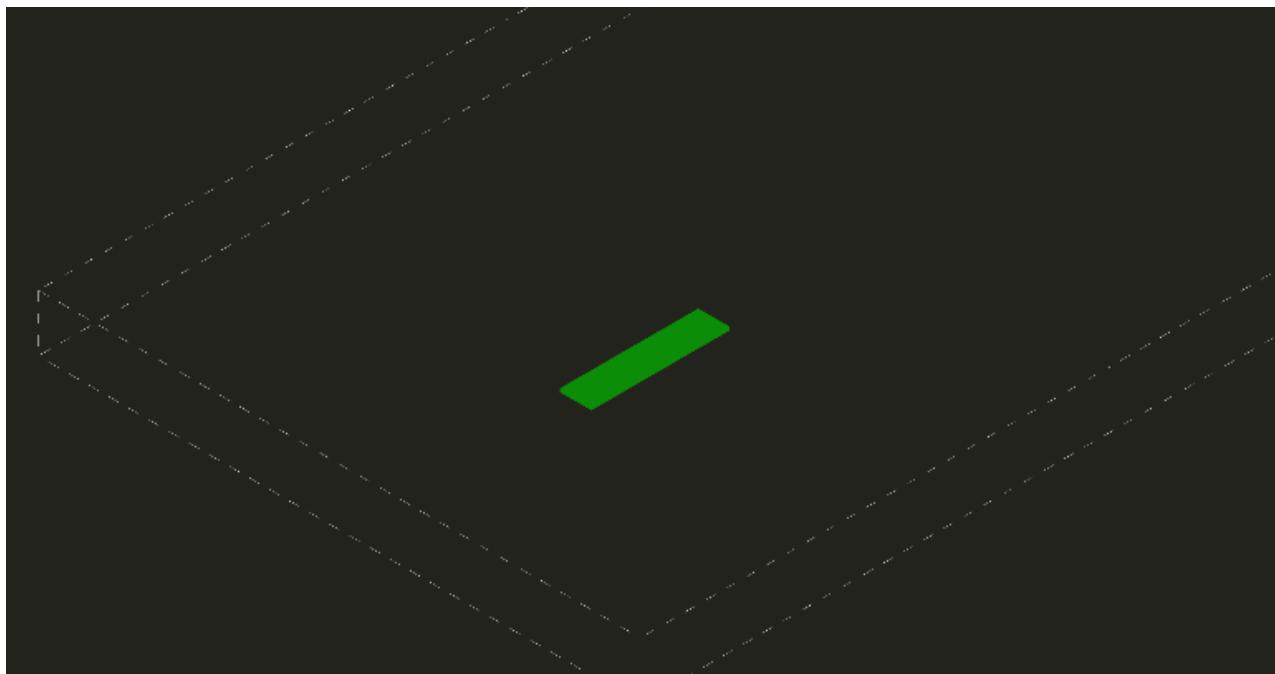
Pen markings



Markings vs. travel



Move order



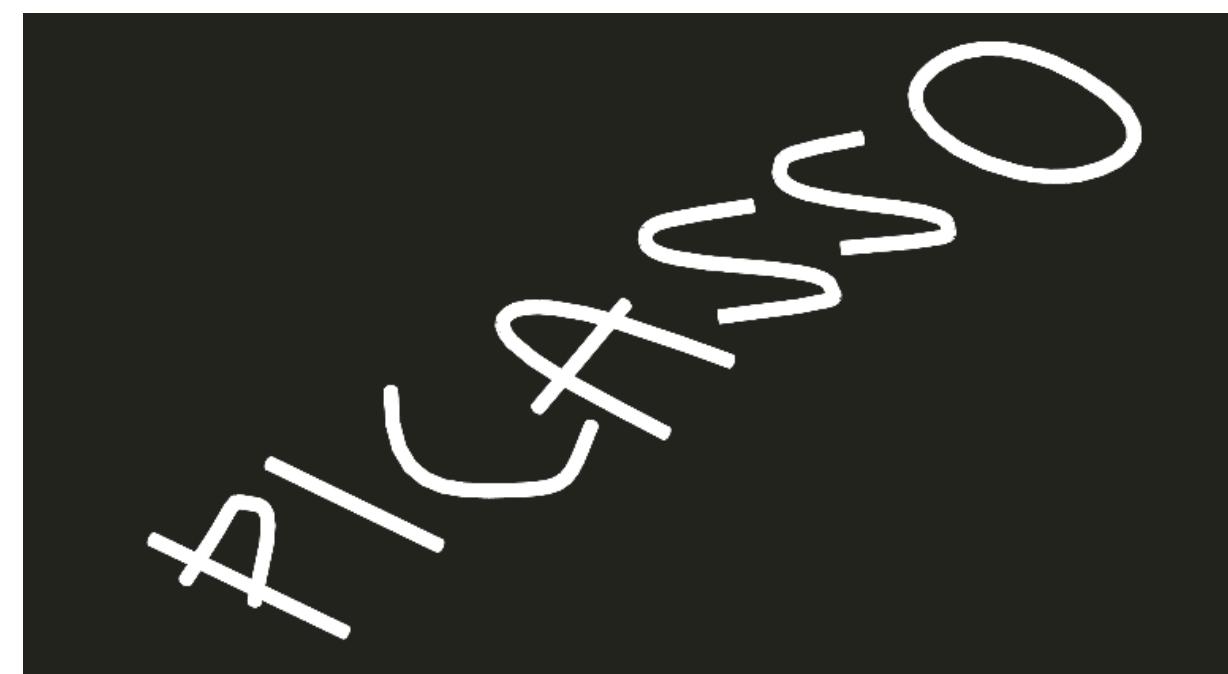
Scale w.r.t. work envelope



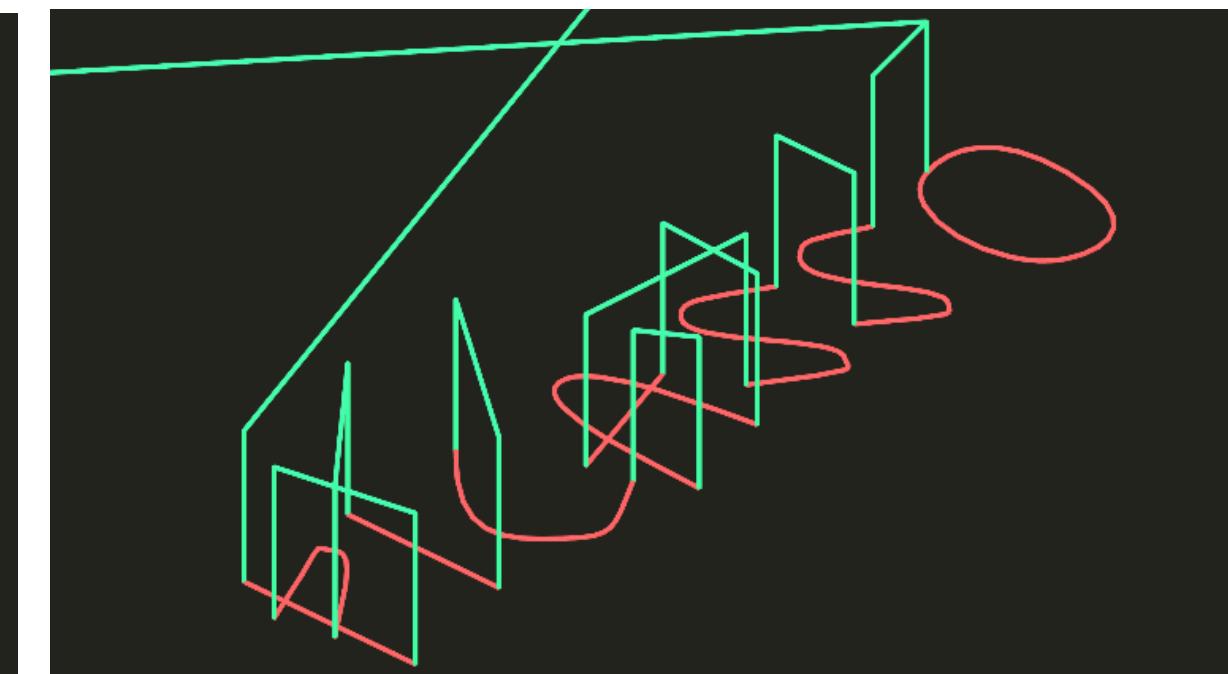
Vinyl cutter sharp angles

Data Visualization

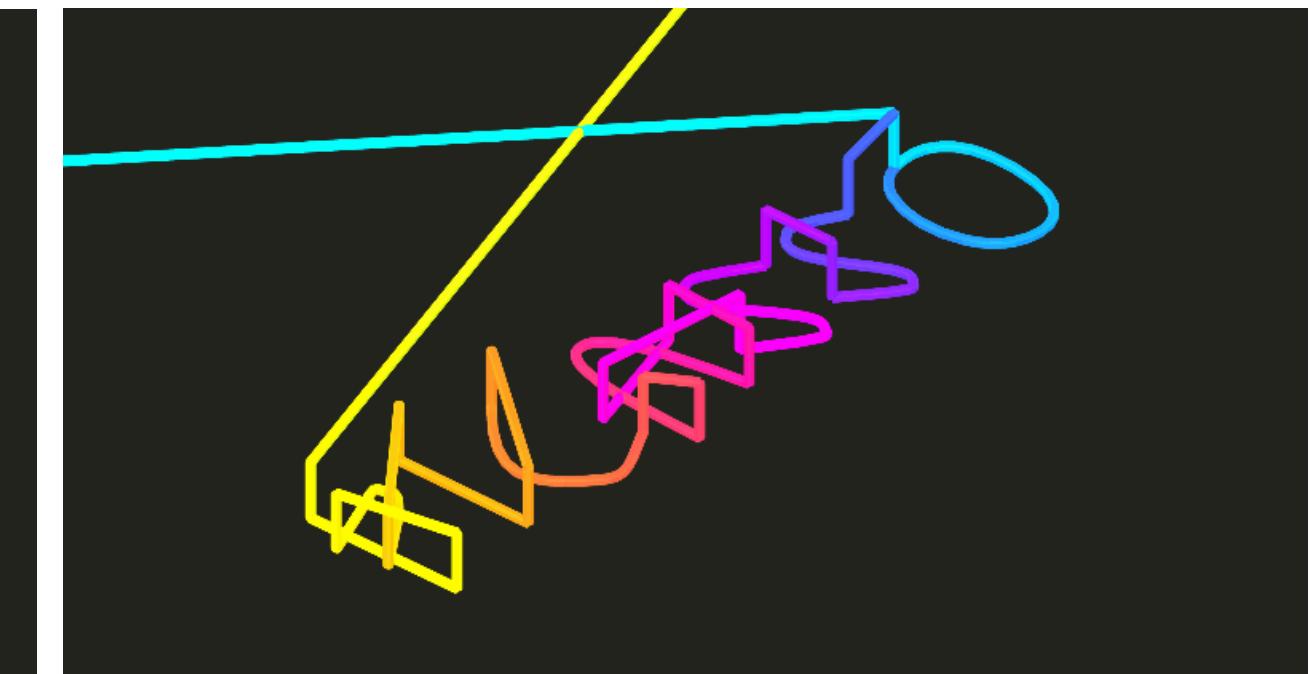
Toolpath stylesheets (TSS): generate task-specific views of a given toolpath.



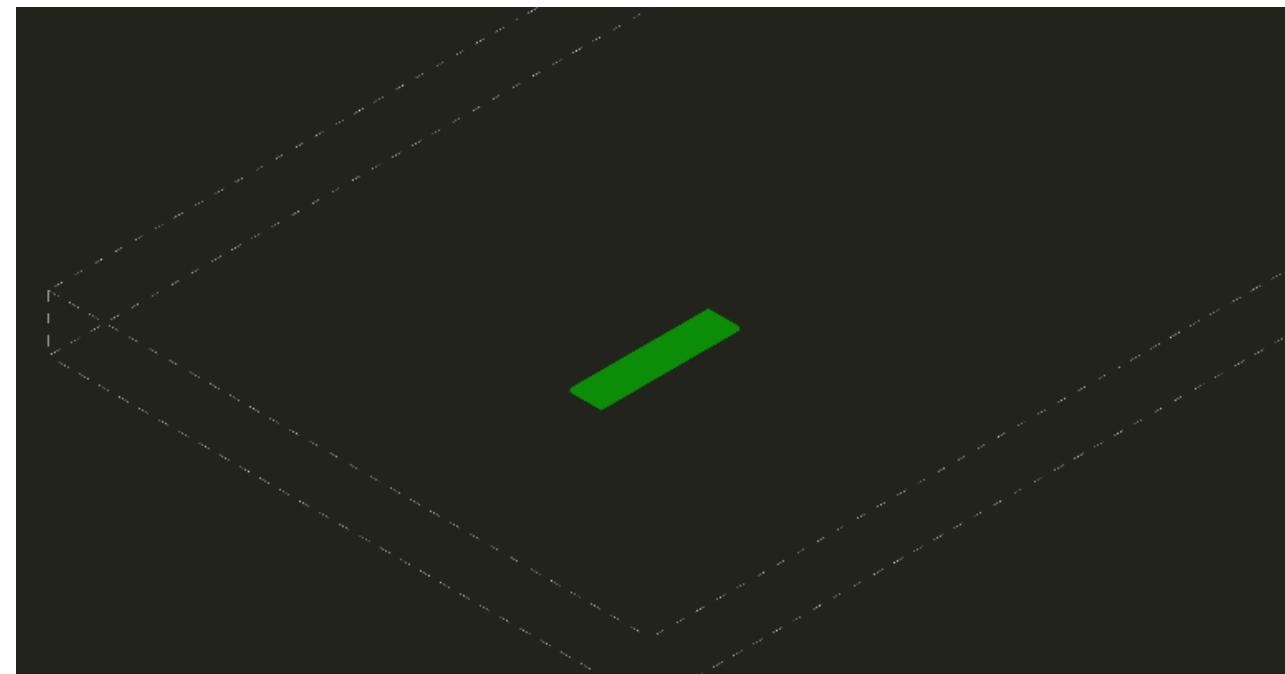
Pen markings



Markings vs. travel



Move order



Scale w.r.t. work envelope



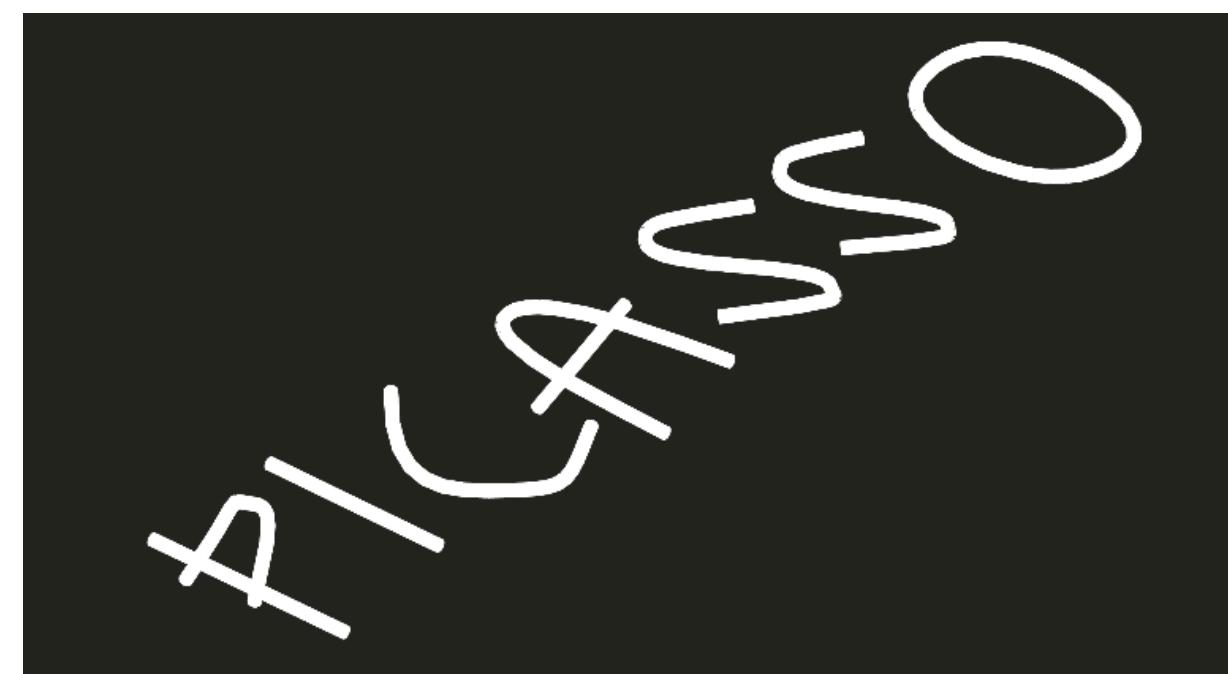
Vinyl cutter sharp angles



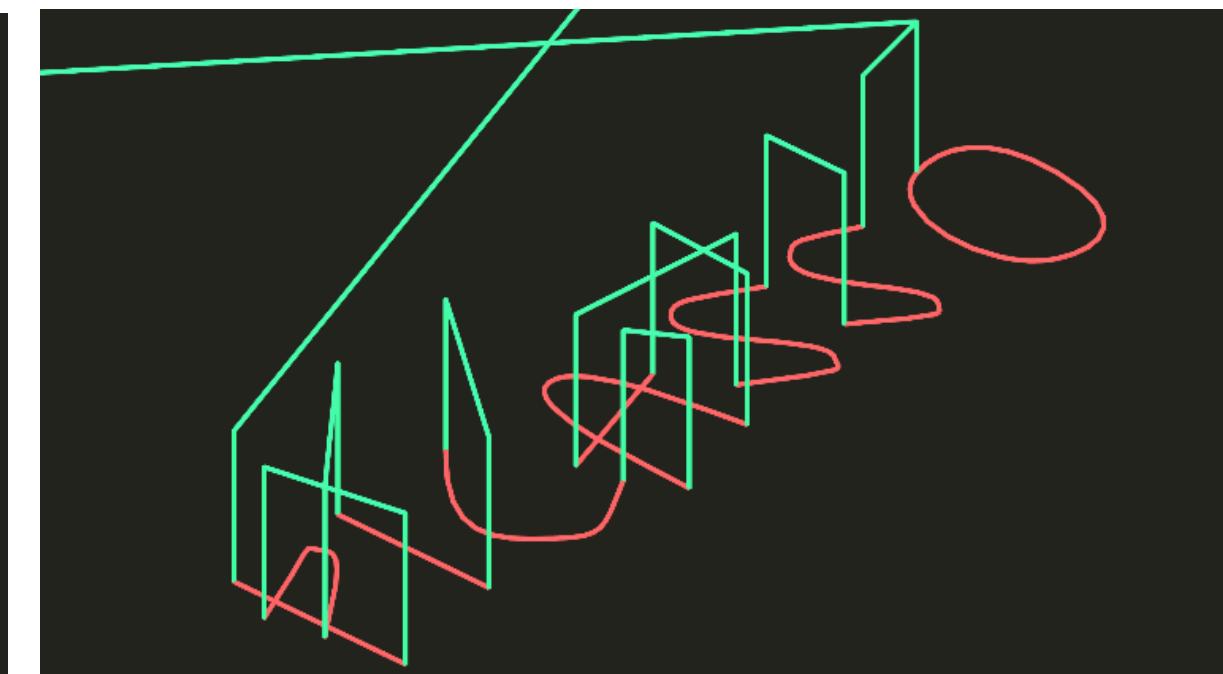
Laser cut geometries

Data Visualization

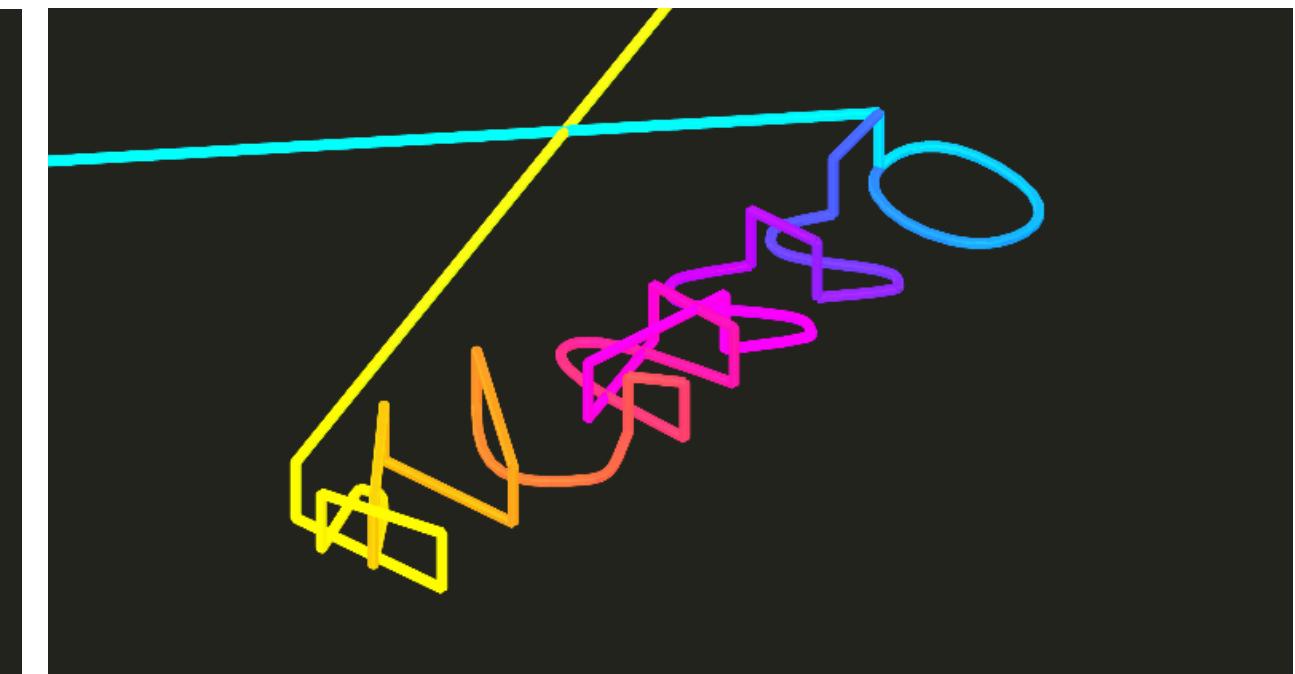
Toolpath stylesheets (TSS): generate task-specific views of a given toolpath.



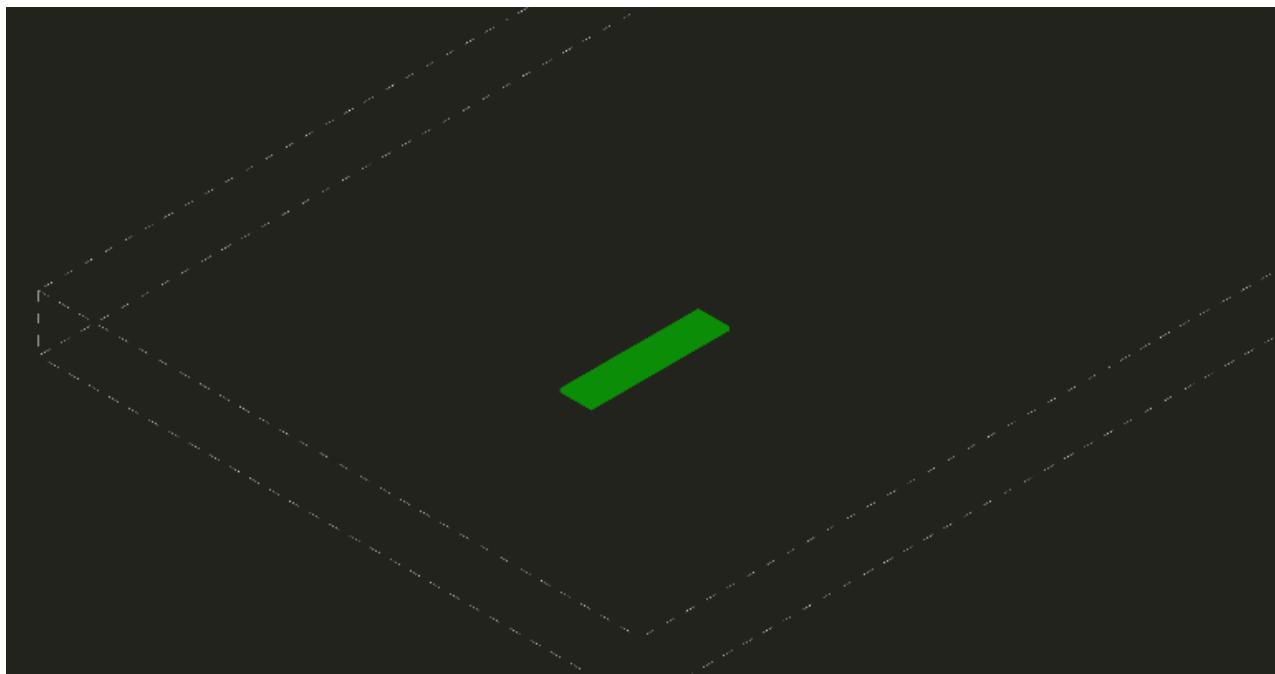
Pen markings



Markings vs. travel



Move order



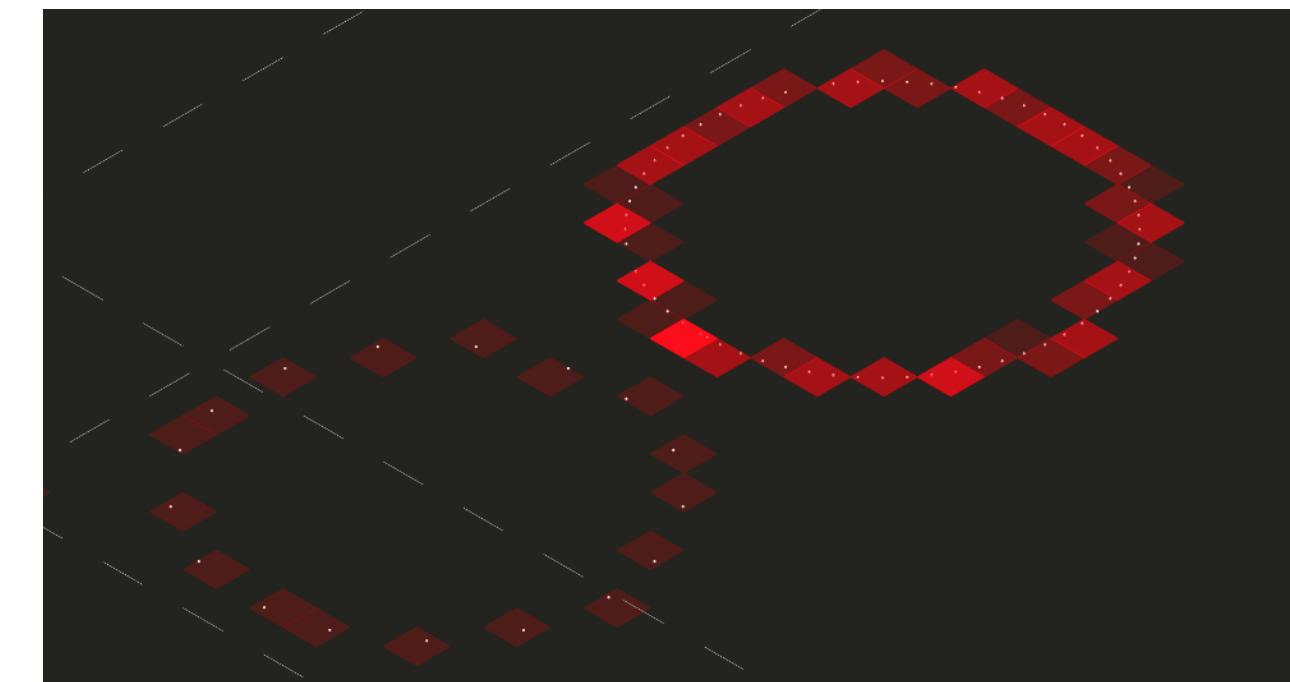
Scale w.r.t. work envelope



Vinyl cutter sharp angles



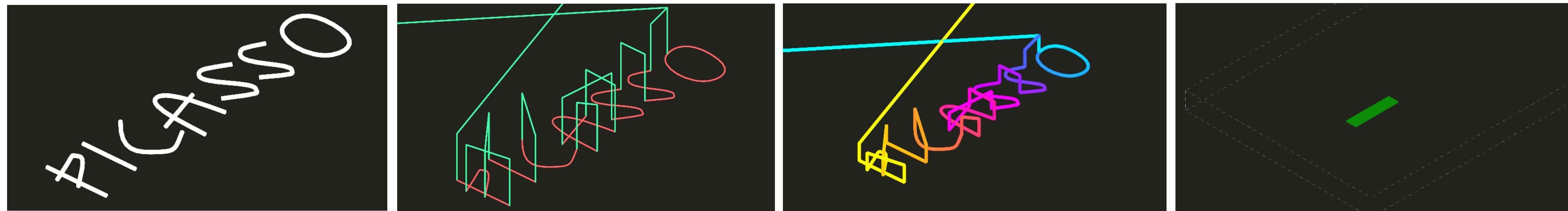
Laser cut geometries



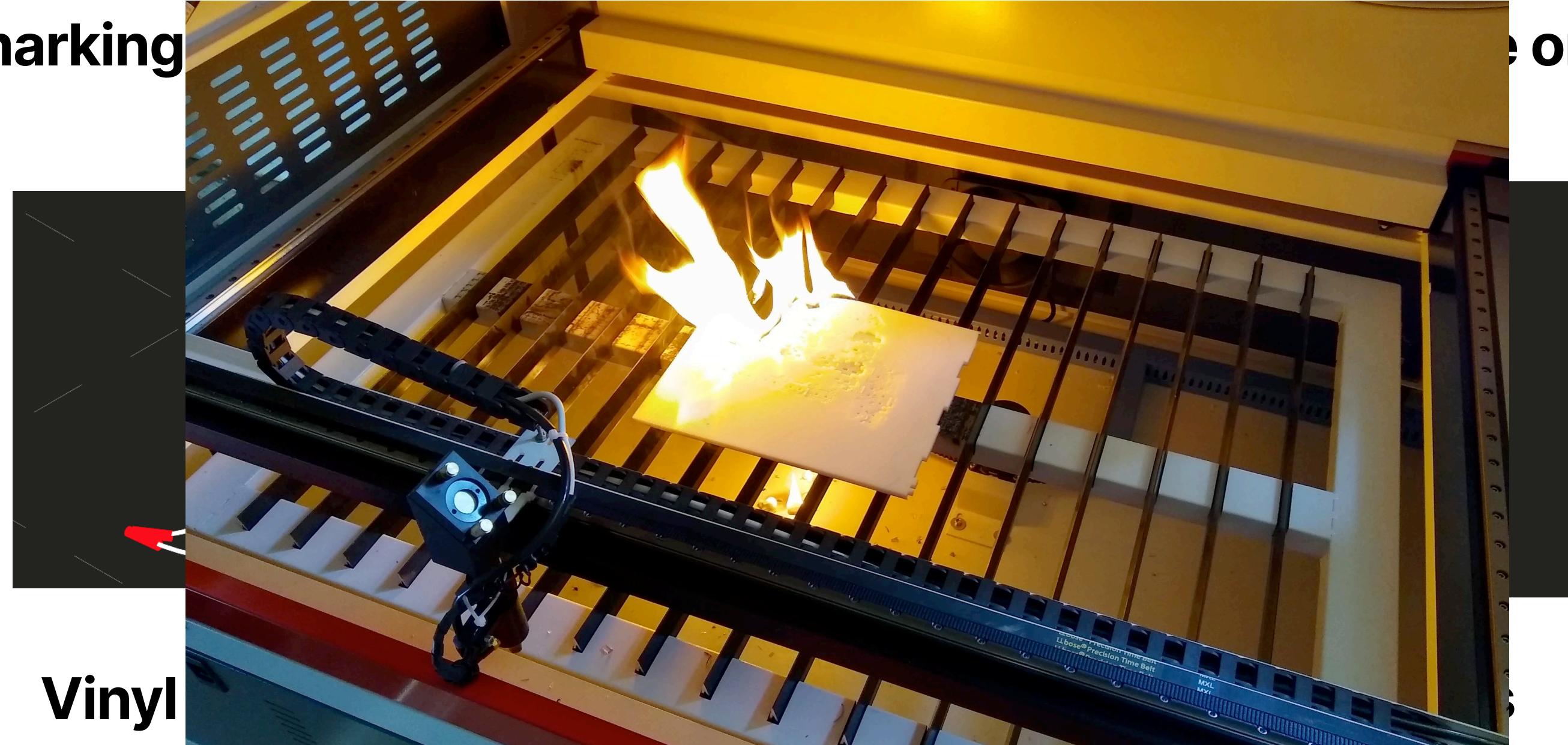
Laser heat map

Data Visualization

Toolpath stylesheets (TSS): generate task-specific views of a given toolpath.

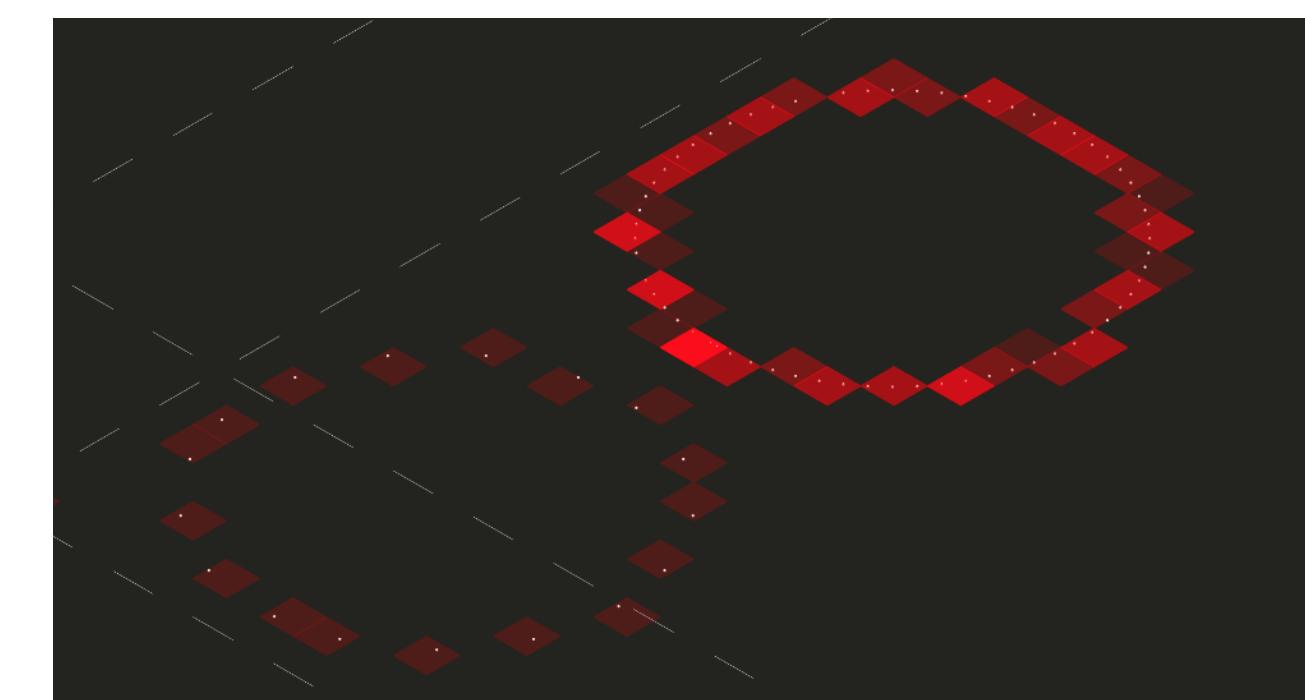


Pen marking



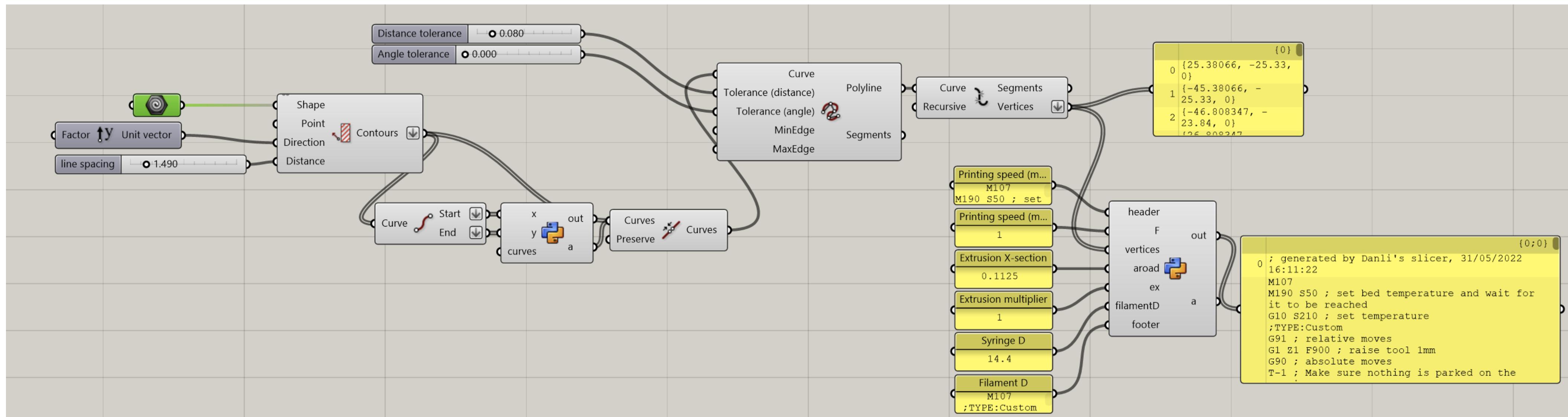
order

Scale w.r.t. work envelope

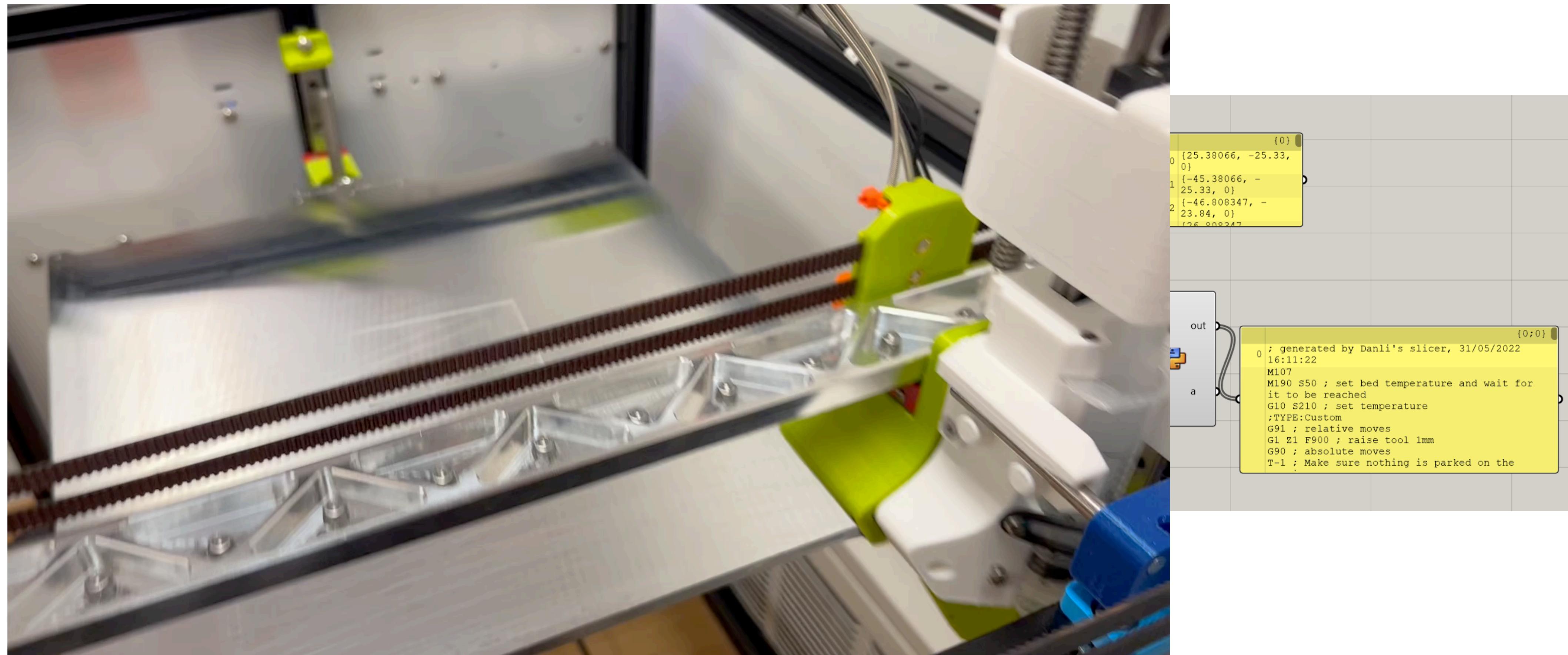


Knowing exactly where the toolpath will go in physical space is crucial in many EDF applications.

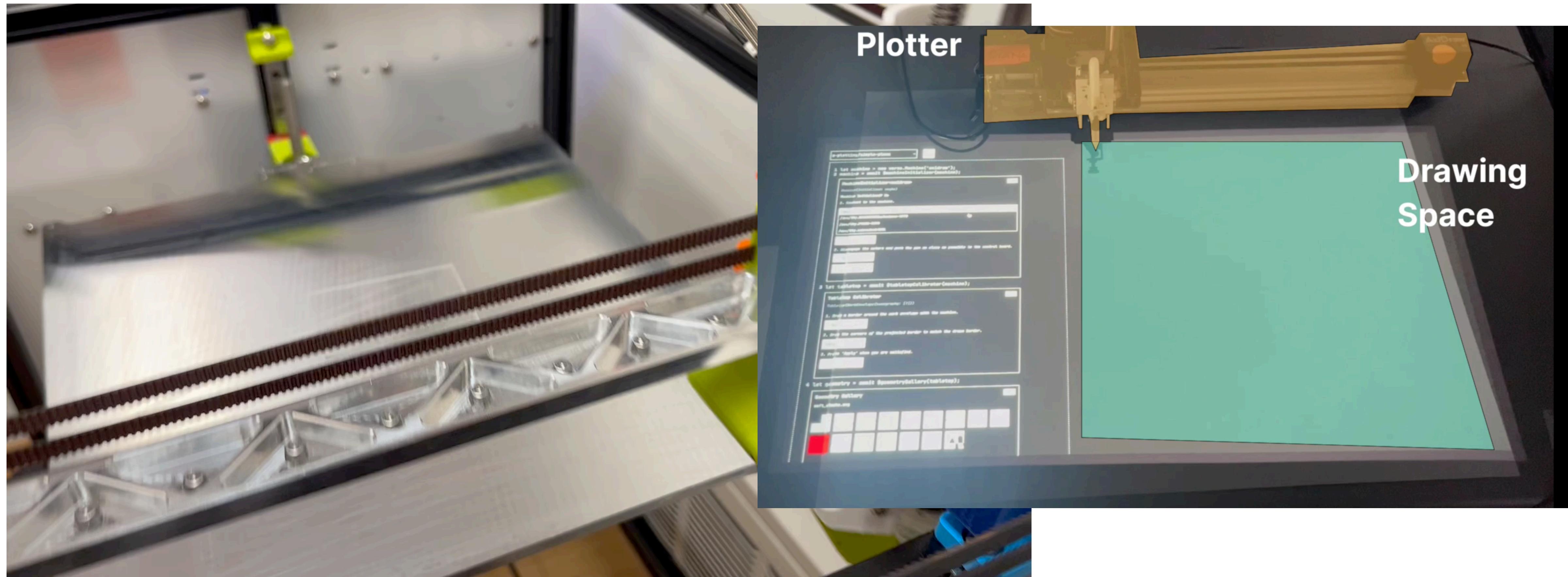
Knowing exactly where the toolpath will go in physical space is crucial in many EDF applications.



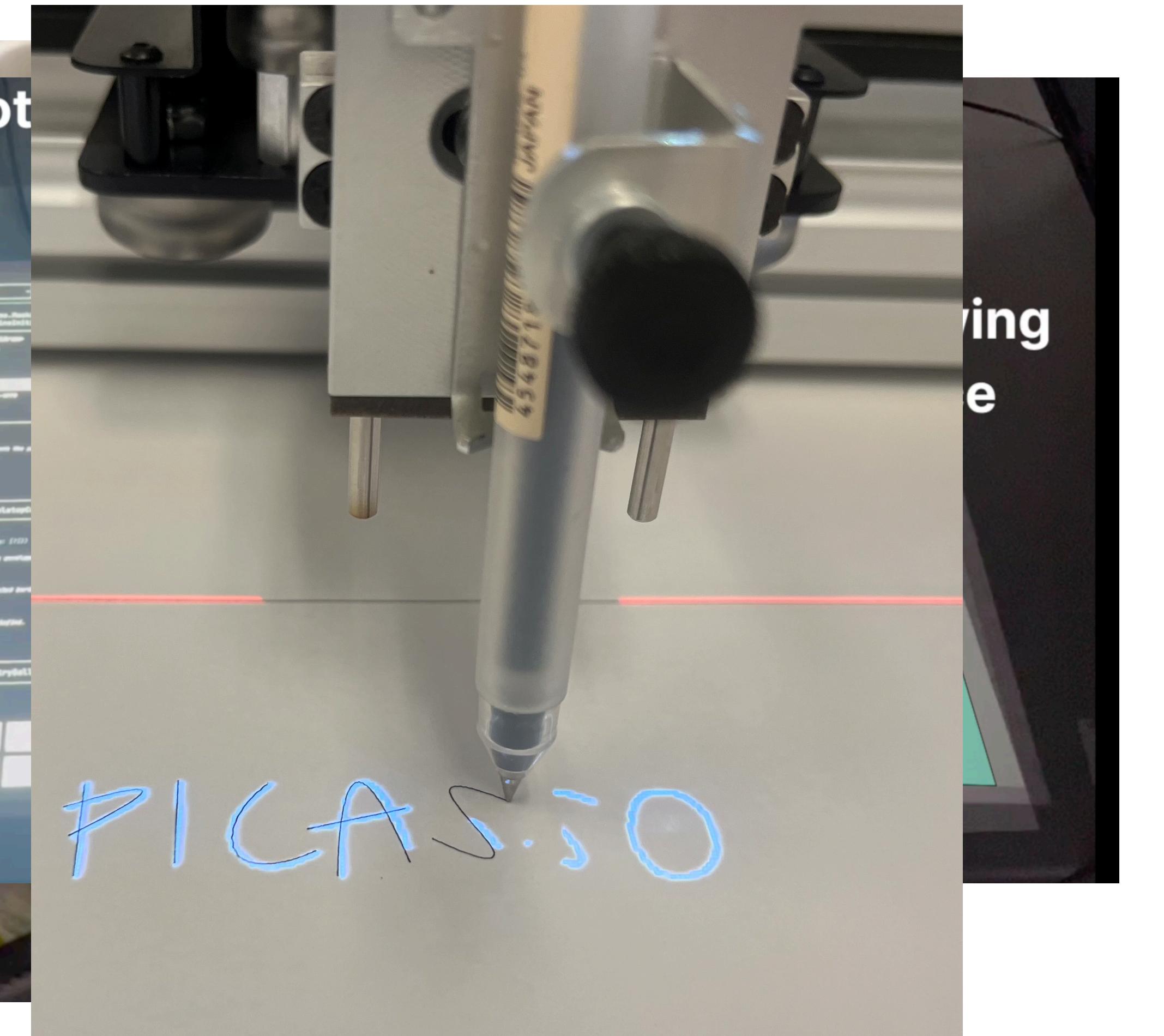
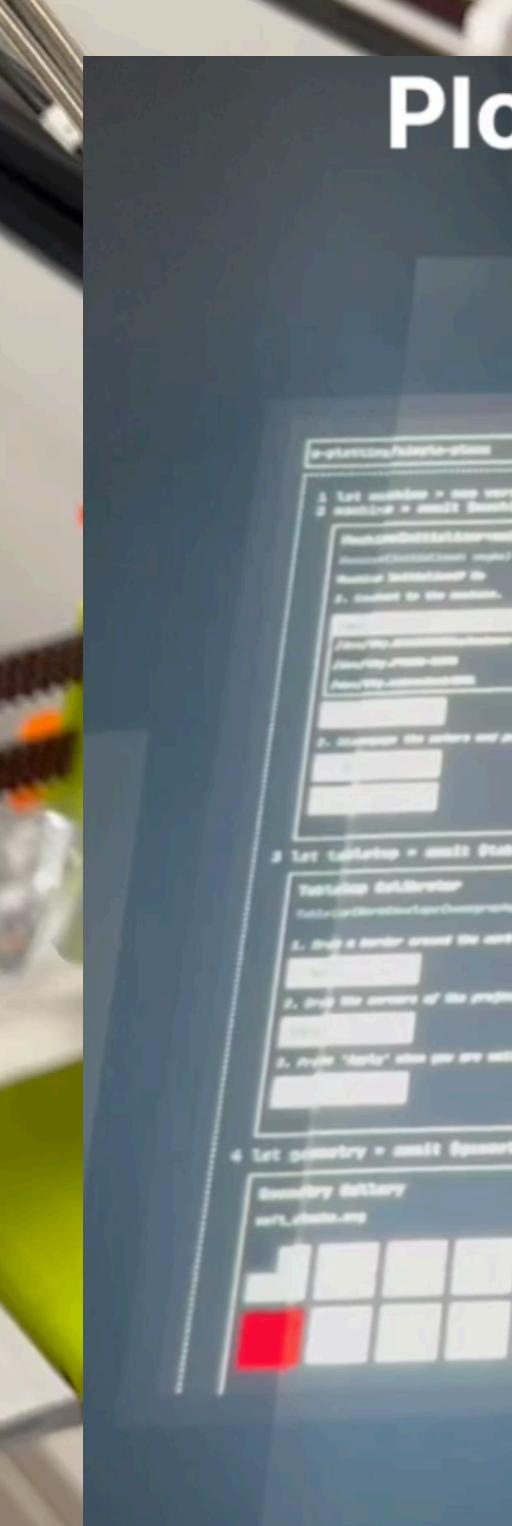
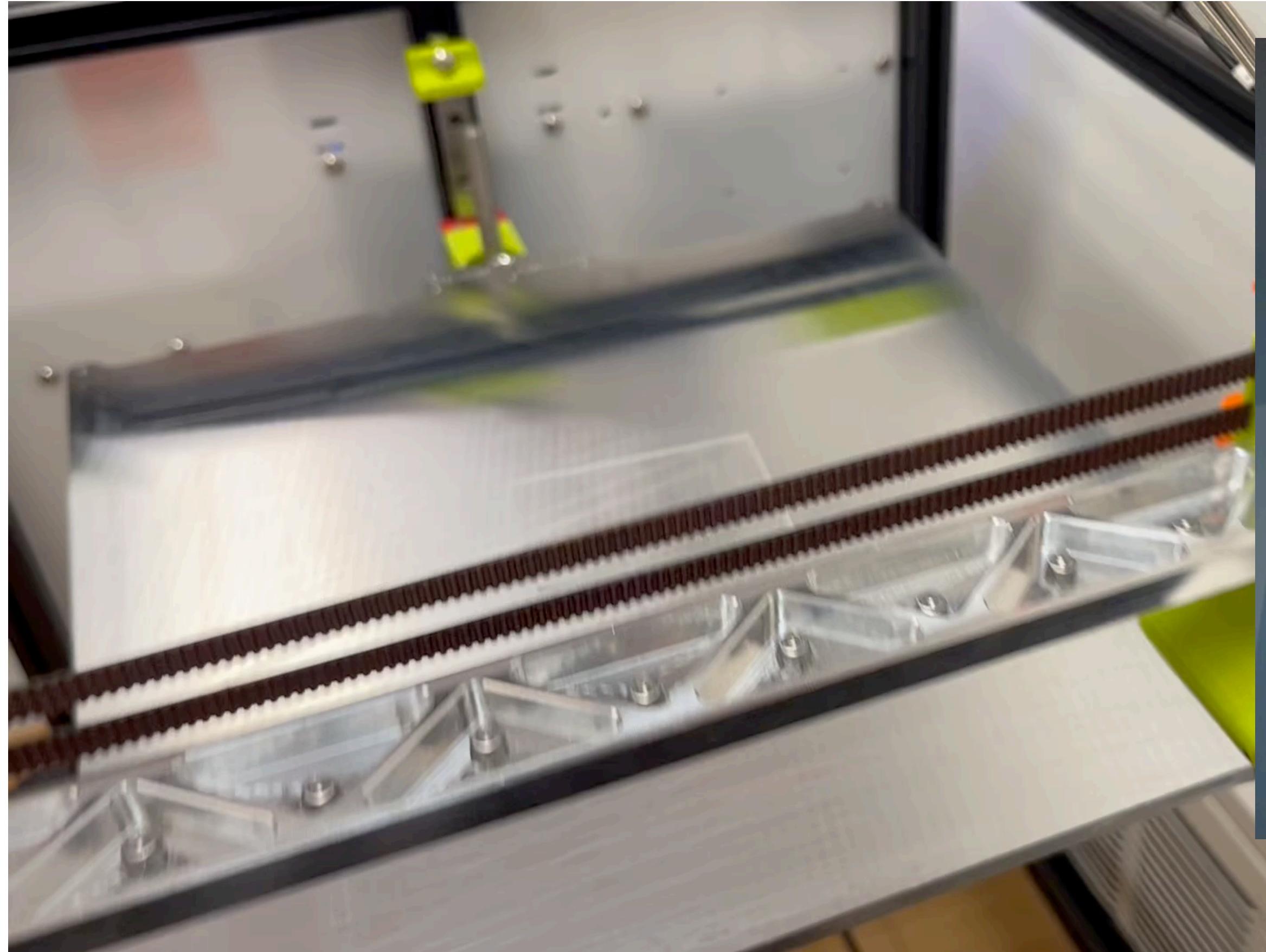
Knowing exactly where the toolpath will go in physical space is crucial in many EDF applications.

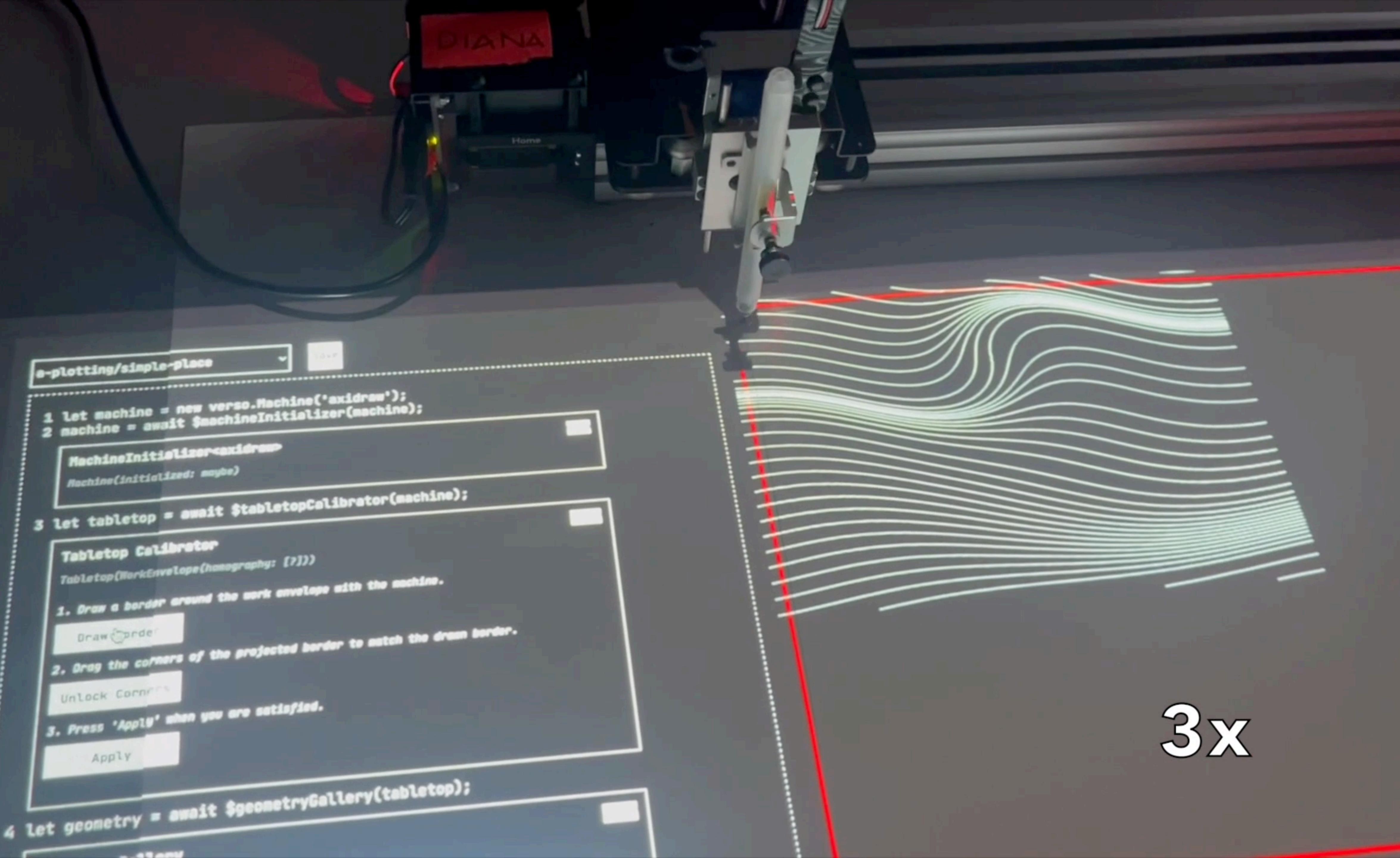


Knowing exactly where the toolpath will go in physical space is crucial in many EDF applications.



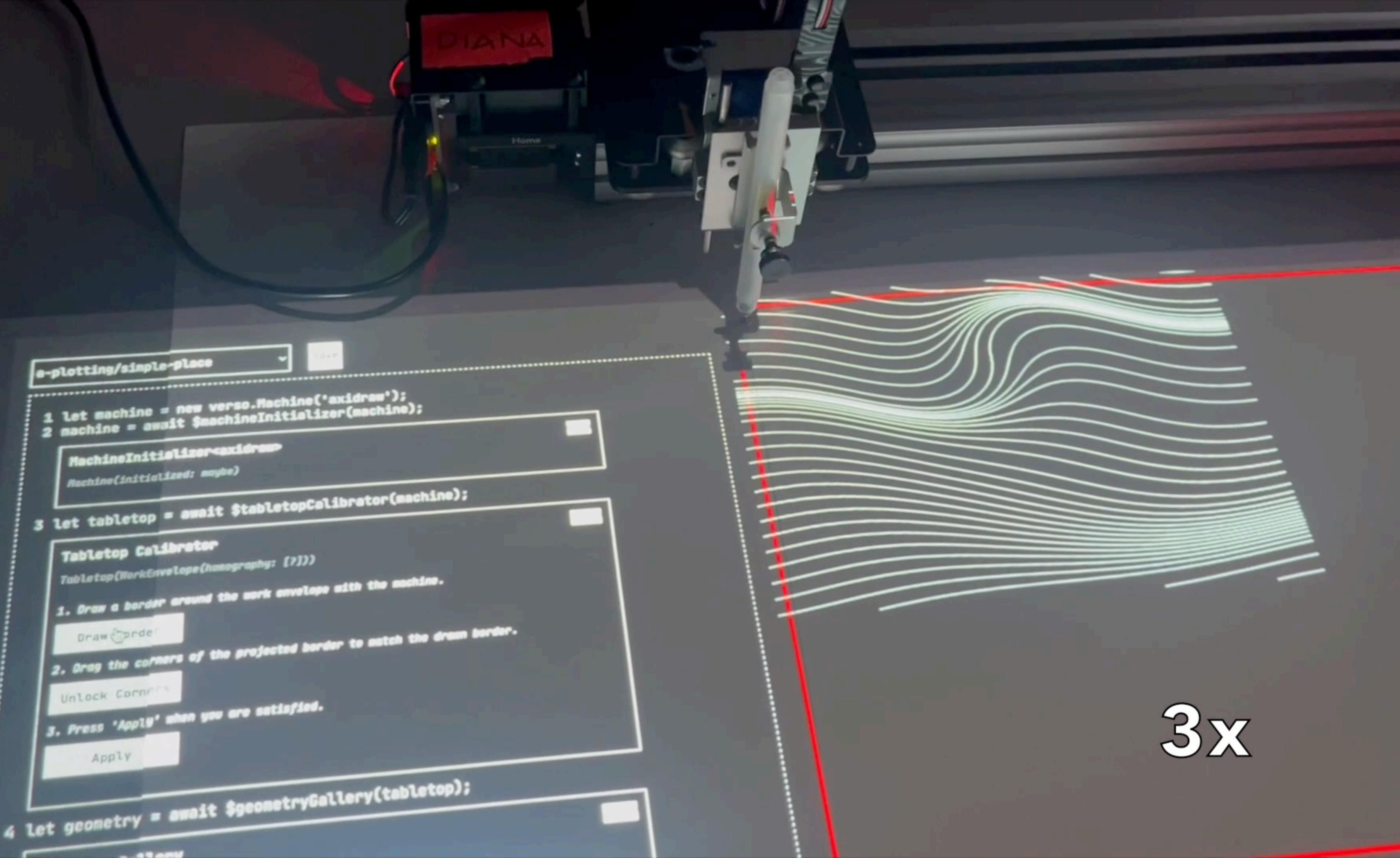
Knowing exactly where the toolpath will go in physical space is crucial in many EDF applications.





3x

```
1 let machine = new verso.Machine('axisdraw');
2 machine = await $machineInitializer(machine);
  MachineInitializer<axisdraw>
    MachineInitialized: maybe
3 let tabletop = await $tabletopCalibrator(machine);
  Tabletop Calibrator
    Tabletop(WorkEnvelope(homography: [?]))
  1. Draw a border around the work envelope with the machine.
    Draw Border
  2. Drag the corners of the projected border to match the drawn border.
    Unlock Corners
  3. Press 'Apply' when you are satisfied.
    Apply
4 let geometry = await $geometryGallery(tabletop);
```



3x

```
1 let machine = new verso.Machine('axisdraw');
2 machine = await $machineInitializer(machine);
  MachineInitializer<axisdraw>
    MachineInitialized: maybe
3 let tabletop = await $tabletopCalibrator(machine);
  Tabletop Calibrator
    Tabletop(WorkEnvelope(homography: [?]))
  1. Draw a border around the work envelope with the machine.
    Draw Border
  2. Drag the corners of the projected border to match the drawn border.
    Unlock Corners
  3. Press 'Apply' when you are satisfied.
    Apply
4 let geometry = await $geometryGallery(tabletop);
```

```
9 await $dispatcher(machine, toolpath);
```

Dispatcher

Machine(initialized: maybe)

Machine status: free

; Enter G-code to adjust the tool prior to dispatch.

Send Snippet

Toolpath 0

Dispatch

Pause

```
9 await $dispatcher(machine, toolpath);
```

Dispatcher

Machine(initialized: maybe)

Machine status: free

; Enter G-code to adjust the tool prior to dispatch.

Send Snippet

Toolpath 0

Dispatch

Pause

Next steps for fabrication-as-programming

Next steps for fabrication-as-programming

More visualizations with toolpath stylesheets

Next steps for fabrication-as-programming

More visualizations with toolpath stylesheets

More modules for emerging human-machine interactions

Next steps for fabrication-as-programming

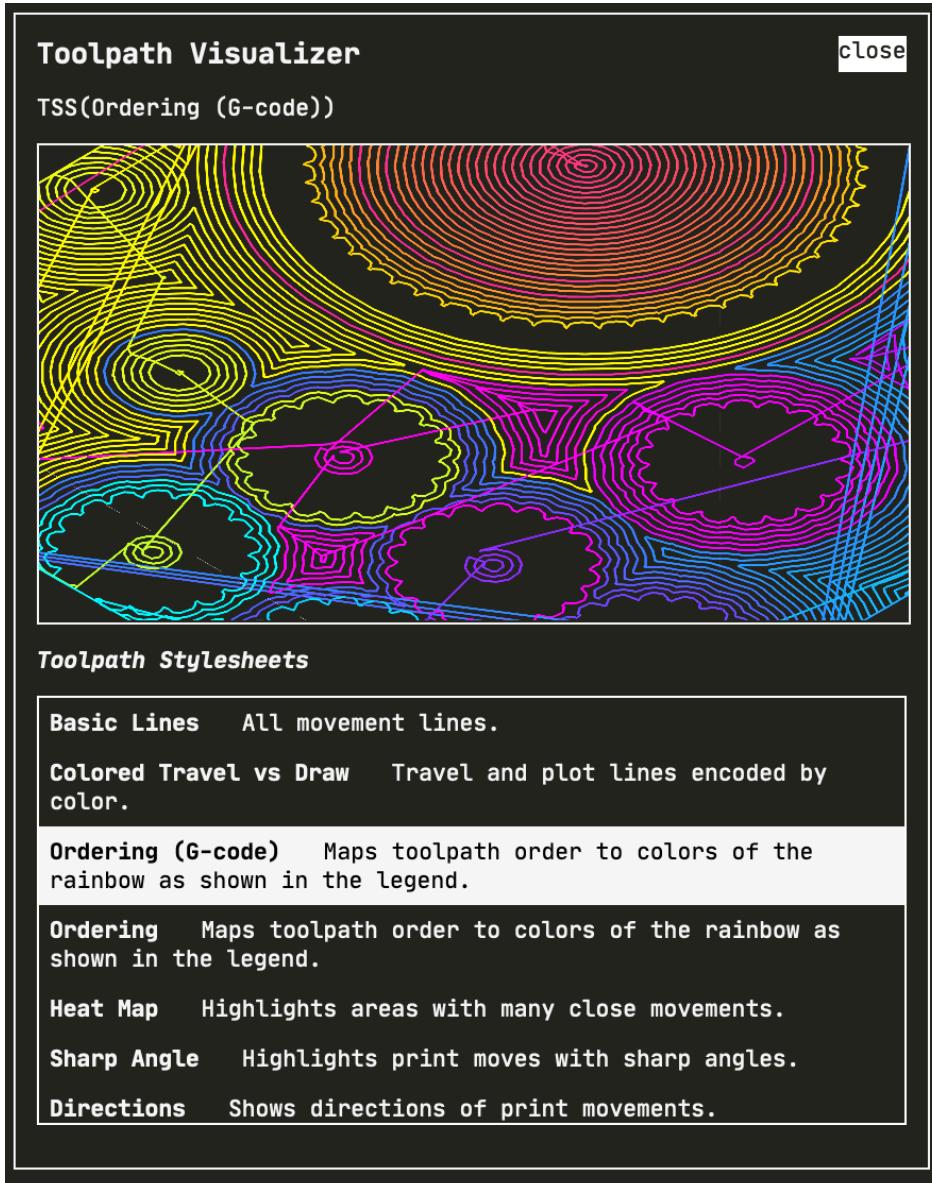
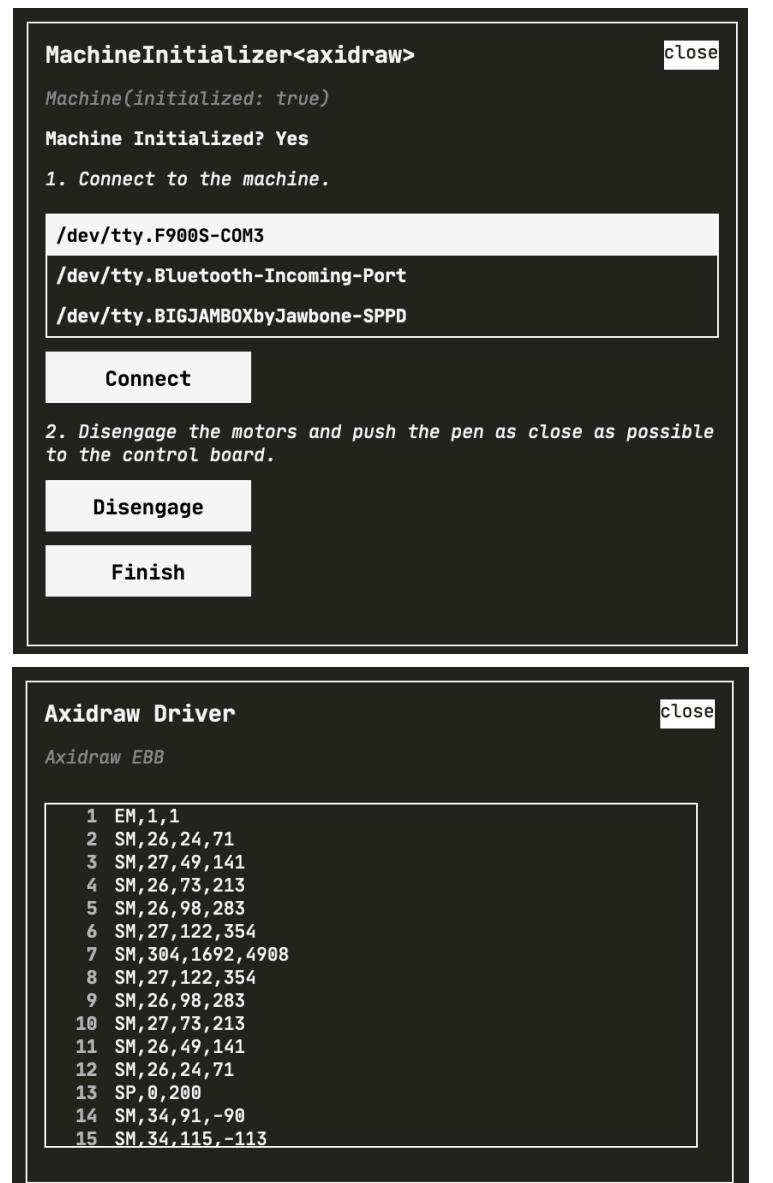
More visualizations with toolpath stylesheets

More modules for emerging human-machine interactions

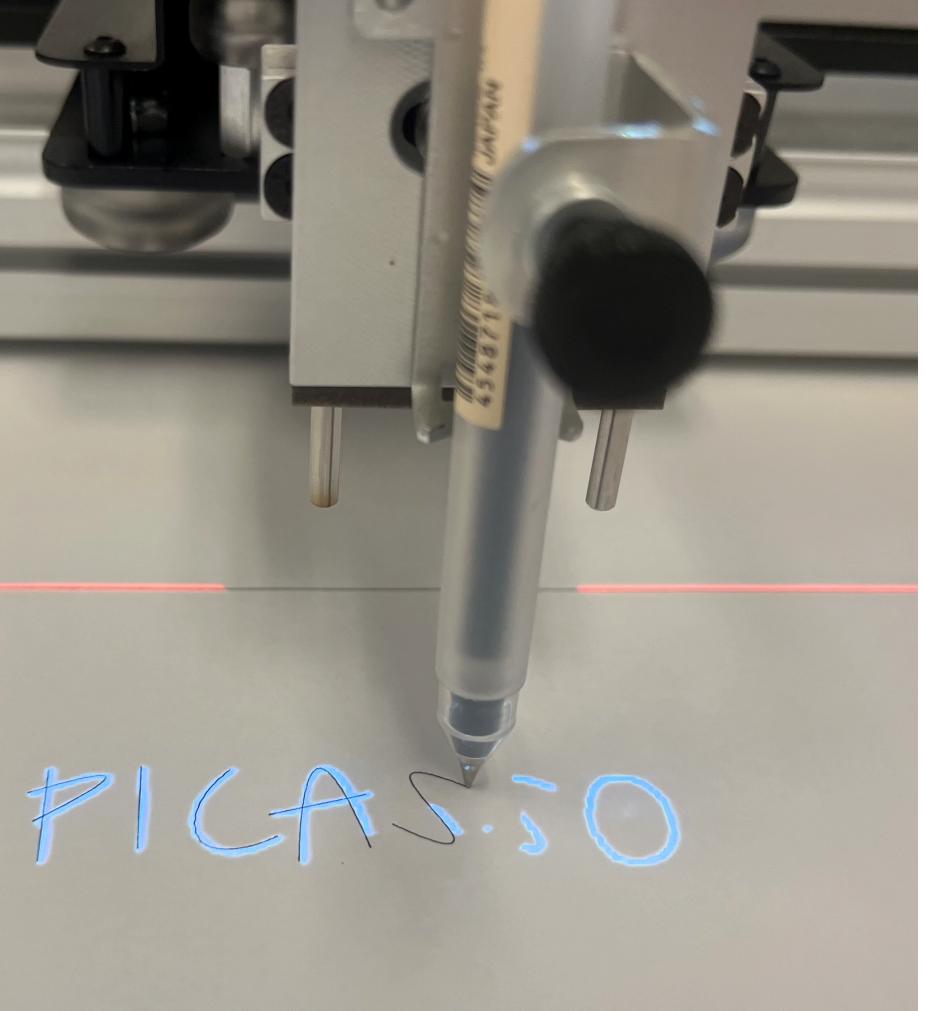
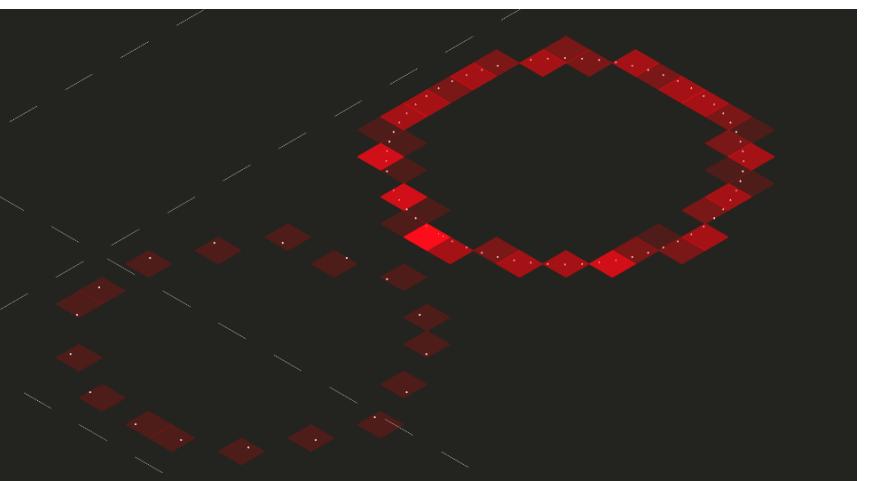
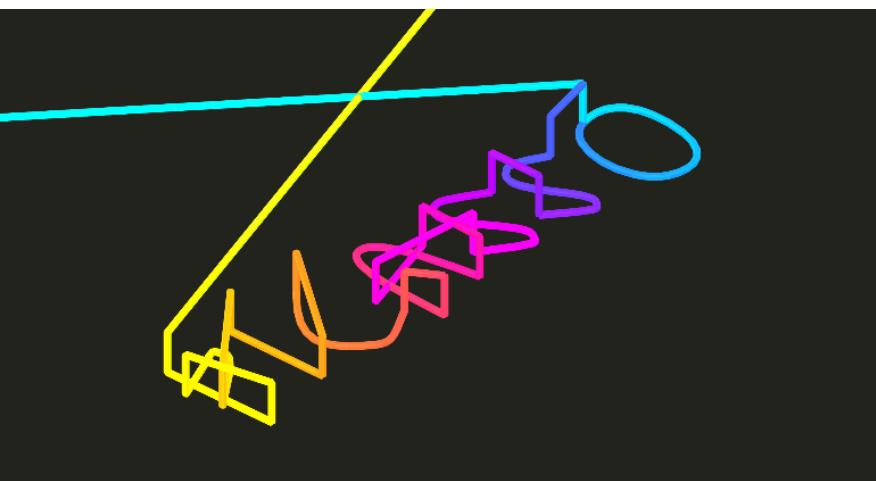
More sharing of exploratory workflows

Verso: Towards Fabrication-as-Programming

Multimodal Programming



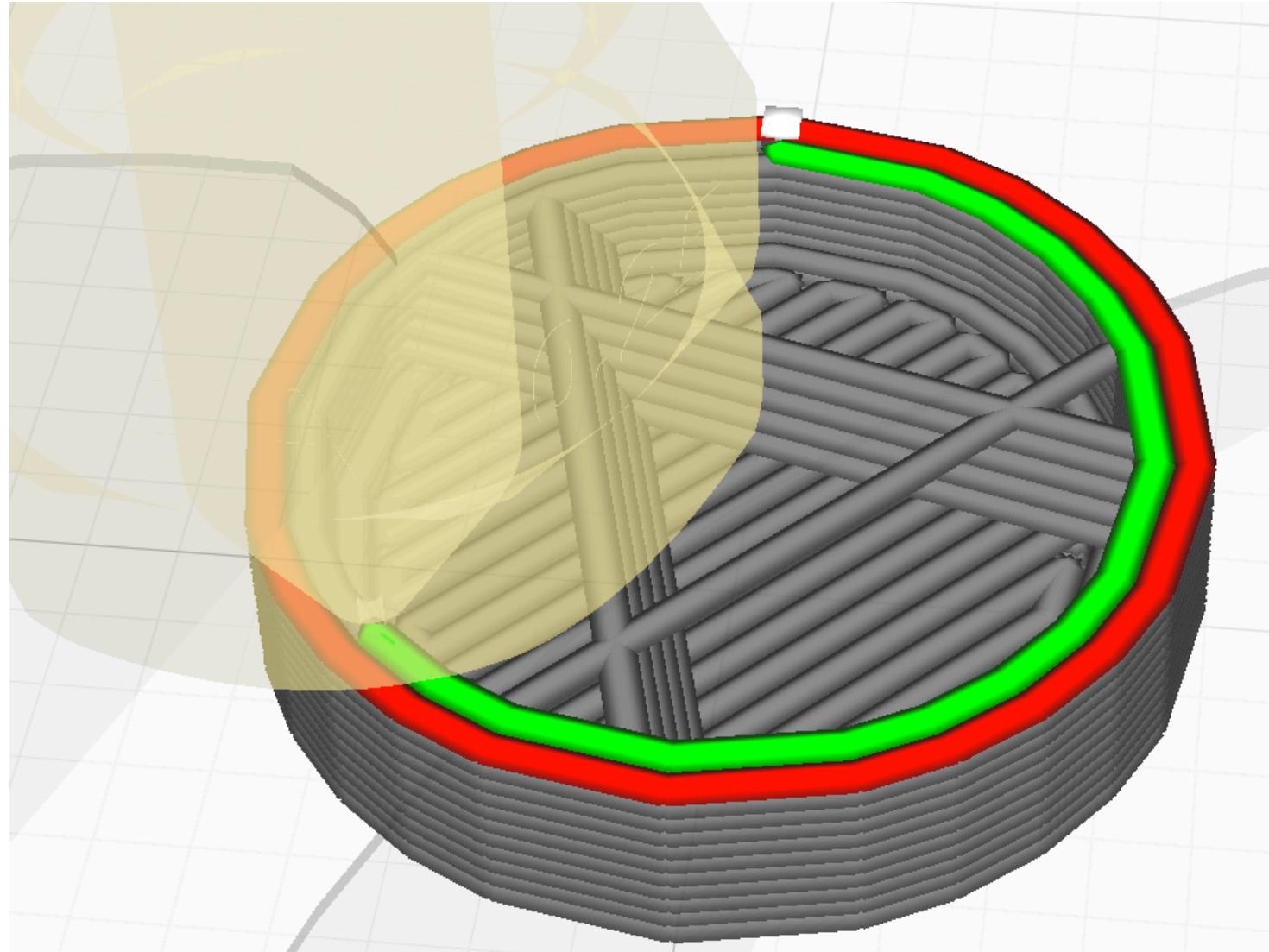
Toolpath Stylesheets



Jasper Tran O'Leary, Eunice Jun, Nadya Peek
University of Washington

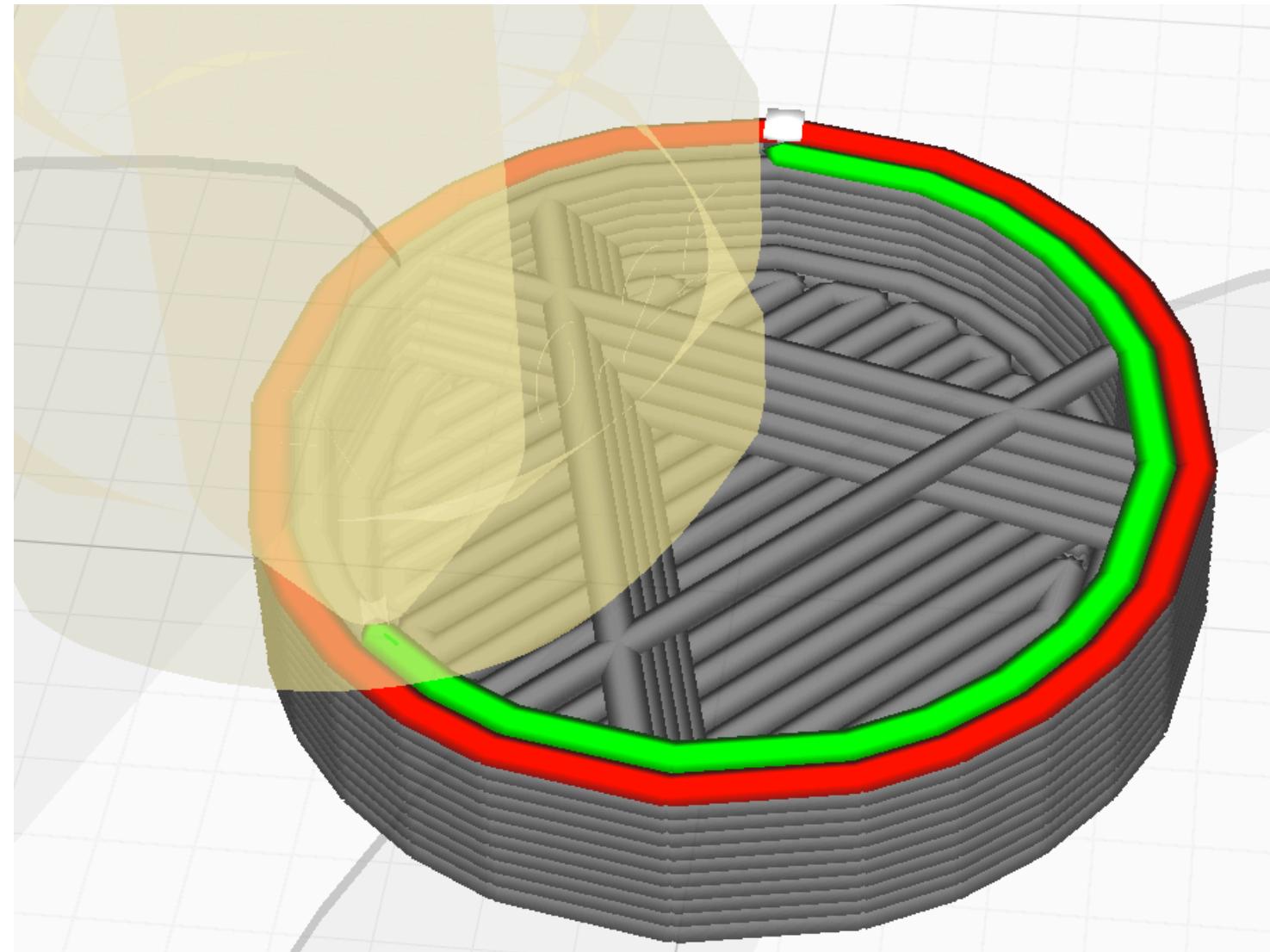


“Can’t Cura/Fusion360/etc... already visualize toolpaths?”



Yes, and they typically provide great common-case visualization.

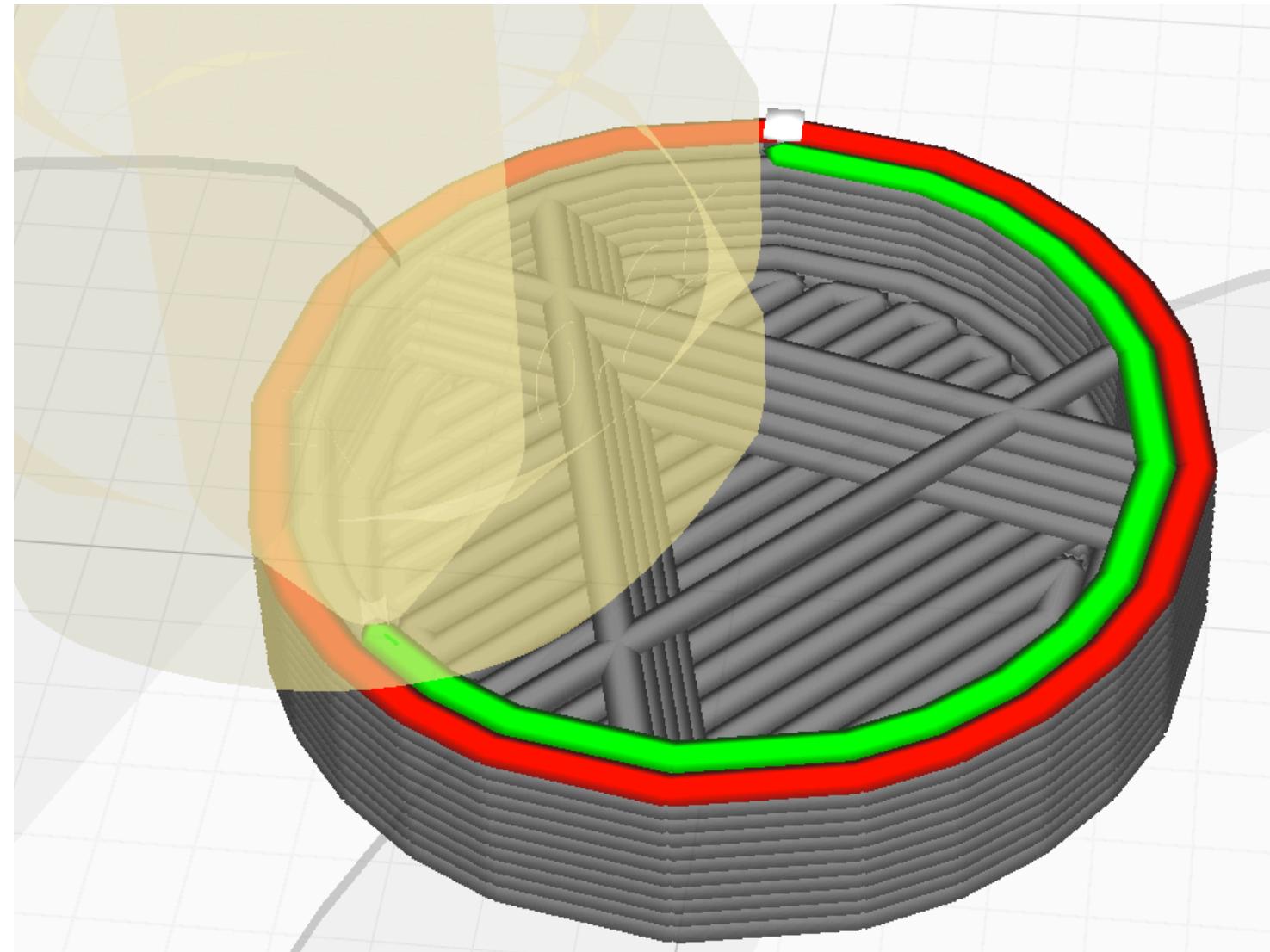
“Can’t Cura/Fusion360/etc... already visualize toolpaths?”



Yes, and they typically provide great common-case visualization.

However we’re focused on uncommon tasks which may require specialized visualizations.

“Can’t Cura/Fusion360/etc... already visualize toolpaths?”



Yes, and they typically provide great common-case visualization.

However we’re focused on uncommon tasks which may require specialized visualizations.

TSS are extensible.

A TSS is an interpreter that provides a ***visual semantics*** for a given set of instructions.

G55

M8

G0 X73.332 Y62.712

G0 Z15.

G0 Z5.

G0 Z-3.498

G1 Z-4.498 F400.

G1 X73.331 Y62.704 Z-4.618

G1 X73.325 Y62.683 Z-4.737

G1 X73.316 Y62.649 Z-4.852

G1 X73.304 Y62.601 Z-4.962

G1 X73.288 Y62.54 Z-5.066

G1 X73.144 Y61.975 Z-5.469

G1 X73.114 Y61.86 Z-5.49

G1 X73.084 Y61.743 Z-5.498

G3 X72.693 Y59.021 R12.765

G1 Y58.871 F800.

Algorithm 1 Ordering TSS (G-Code Instruction Set)

Require: *instructions*

points \leftarrow []

for *instruction* in *instructions* **do**

opcode \leftarrow *parseOpcode(instruction)*

match *opcode* **do**

case “G0” **or** “G1”

X, Y, Z, F, E \leftarrow *parseArgs(instruction)*

push(points, Vector3(X, Y, Z))

--

--

--

--

--

--

--

--

--

--

--

G55	
M8	
G0	X73.332 Y62.712
G0	Z15.
G0	Z5.
G0	Z-3.498
G1	Z-4.498 F400.
G1	X73.331 Y62.704 Z-4.618
G1	X73.325 Y62.683 Z-4.737
G1	X73.316 Y62.649 Z-4.852
G1	X73.304 Y62.601 Z-4.962
G1	X73.288 Y62.54 Z-5.066
G1	X73.144 Y61.975 Z-5.469
G1	X73.114 Y61.86 Z-5.49
G1	X73.084 Y61.743 Z-5.498
G3	X72.693 Y59.021 R12.765
G1	Y58.871 F800.

Algorithm 1 Ordering TSS (G-Code Instruction Set)

Require: *instructions*

```

points ← [ ]
for instruction in instructions do
    opcode ← parseOpcode(instruction)
    match opcode do
        case "G0" or "G1"
            X,Y,Z,F,E ← parseArgs(instruction)
            push(points, Vector3(X, Y, Z))

```

Algorithm 1 Ordering TSS (G-Code Instruction Set)

Require: *instructions*

points $\leftarrow []$

for *instruction* **in** *instructions* **do**

opcode $\leftarrow \text{parseOpcode}(\text{instruction})$

match *opcode* **do**

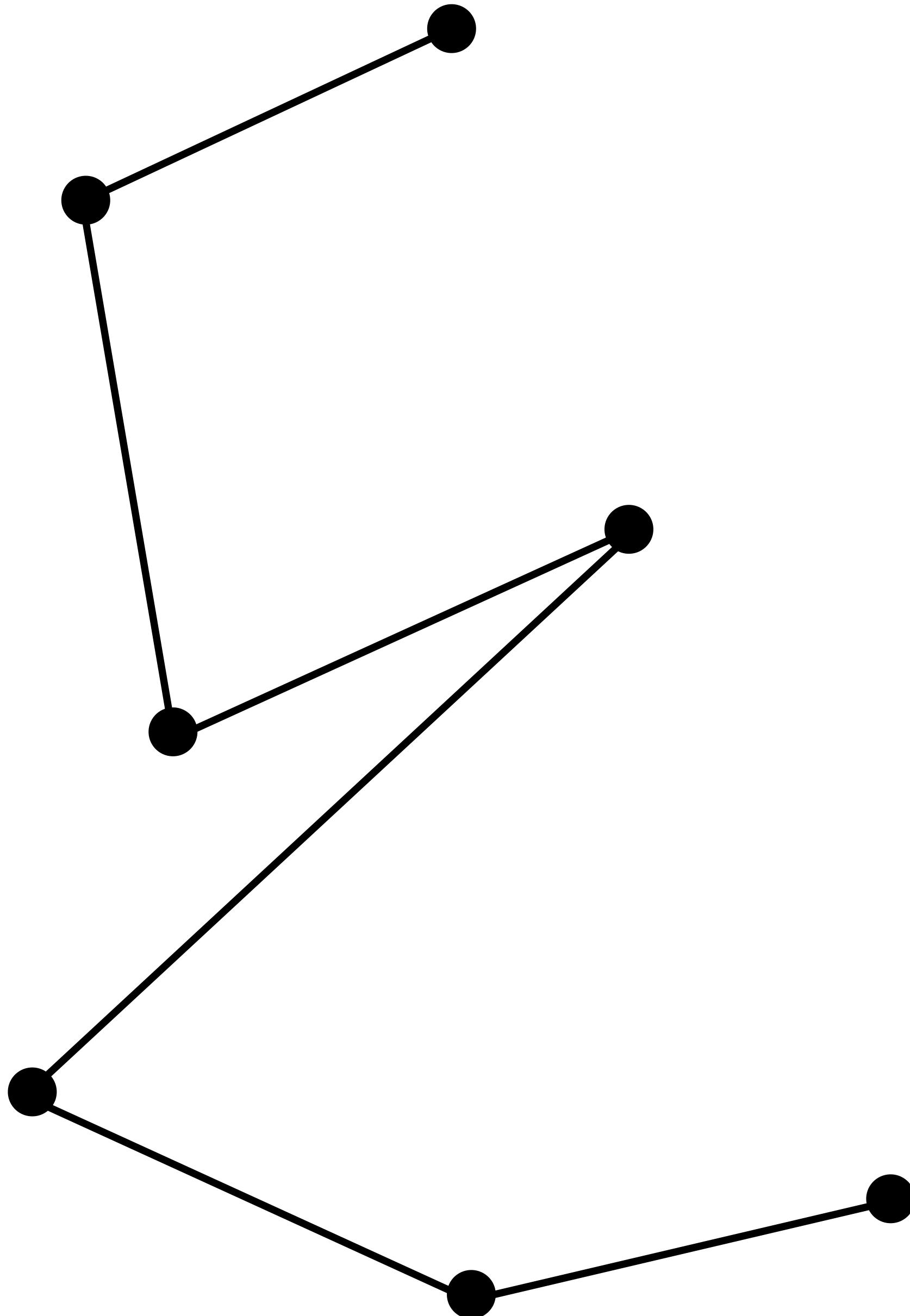
case "G0" **or** "G1"

X, Y, Z, F, E $\leftarrow \text{parseArgs}(\text{instruction})$

push(points, Vector3(X, Y, Z))

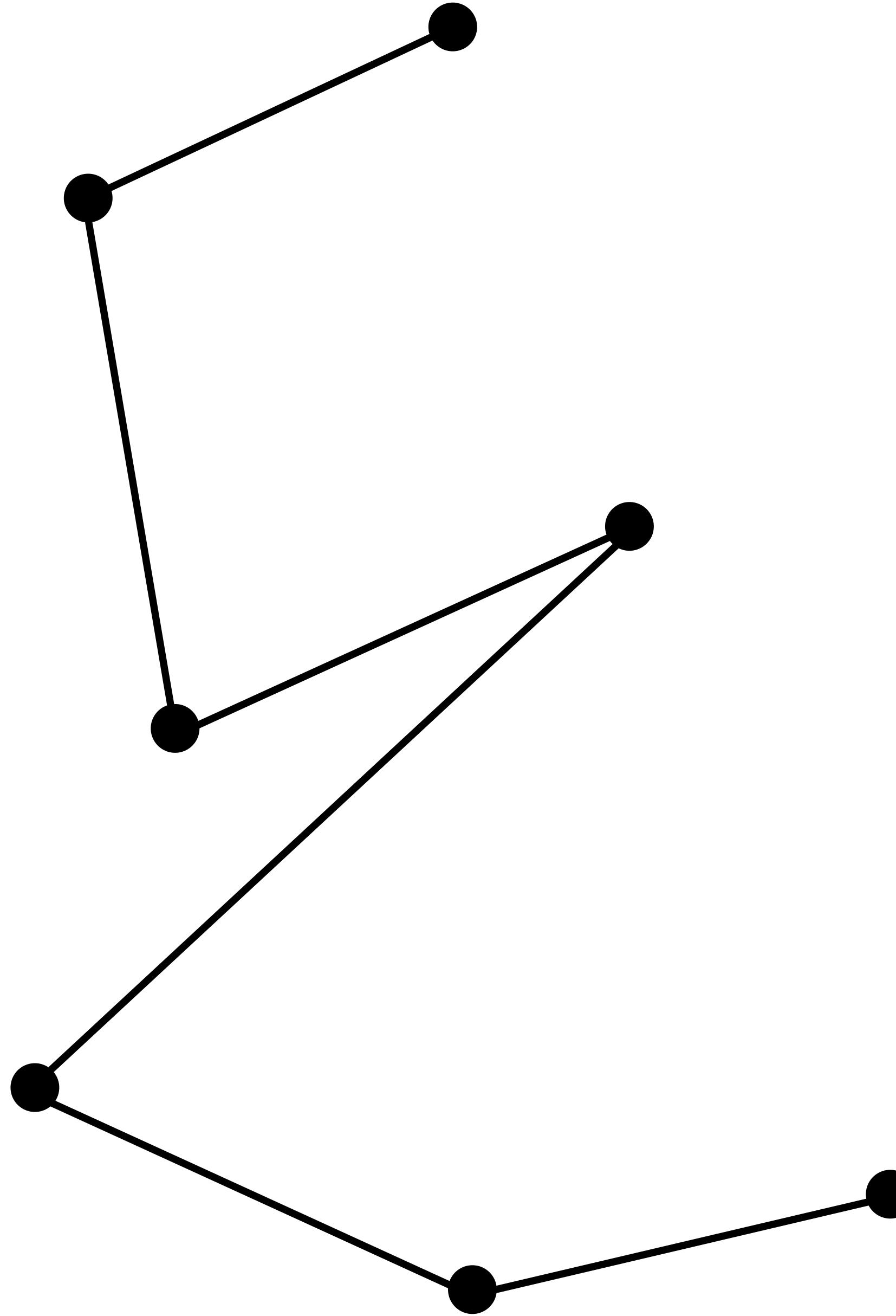
end for

curve $\leftarrow \text{interpolate}(\text{points})$

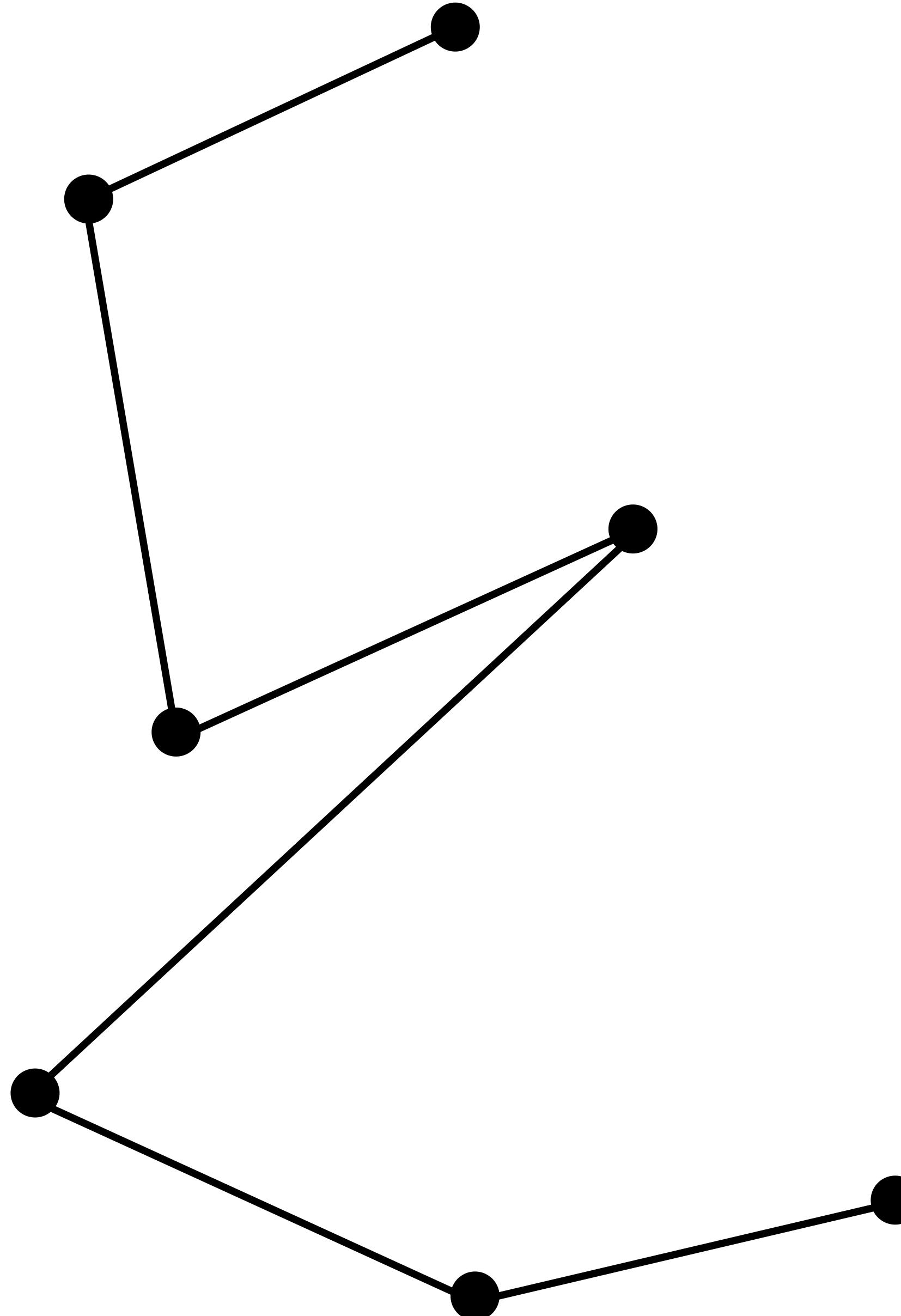


Algorithm 1 Ordering TSS (G-Code Instruction Set)

Require: *instructions*
points $\leftarrow []$
for *instruction* in *instructions* **do**
 opcode $\leftarrow \text{parseOpcode}(\text{instruction})$
 match *opcode* **do**
 case "G0" **or** "G1"
 X, Y, Z, F, E $\leftarrow \text{parseArgs}(\text{instruction})$
 push(*points*, *Vector3*(*X, Y, Z*))
 end for
curve $\leftarrow \text{interpolate}(\text{points})$



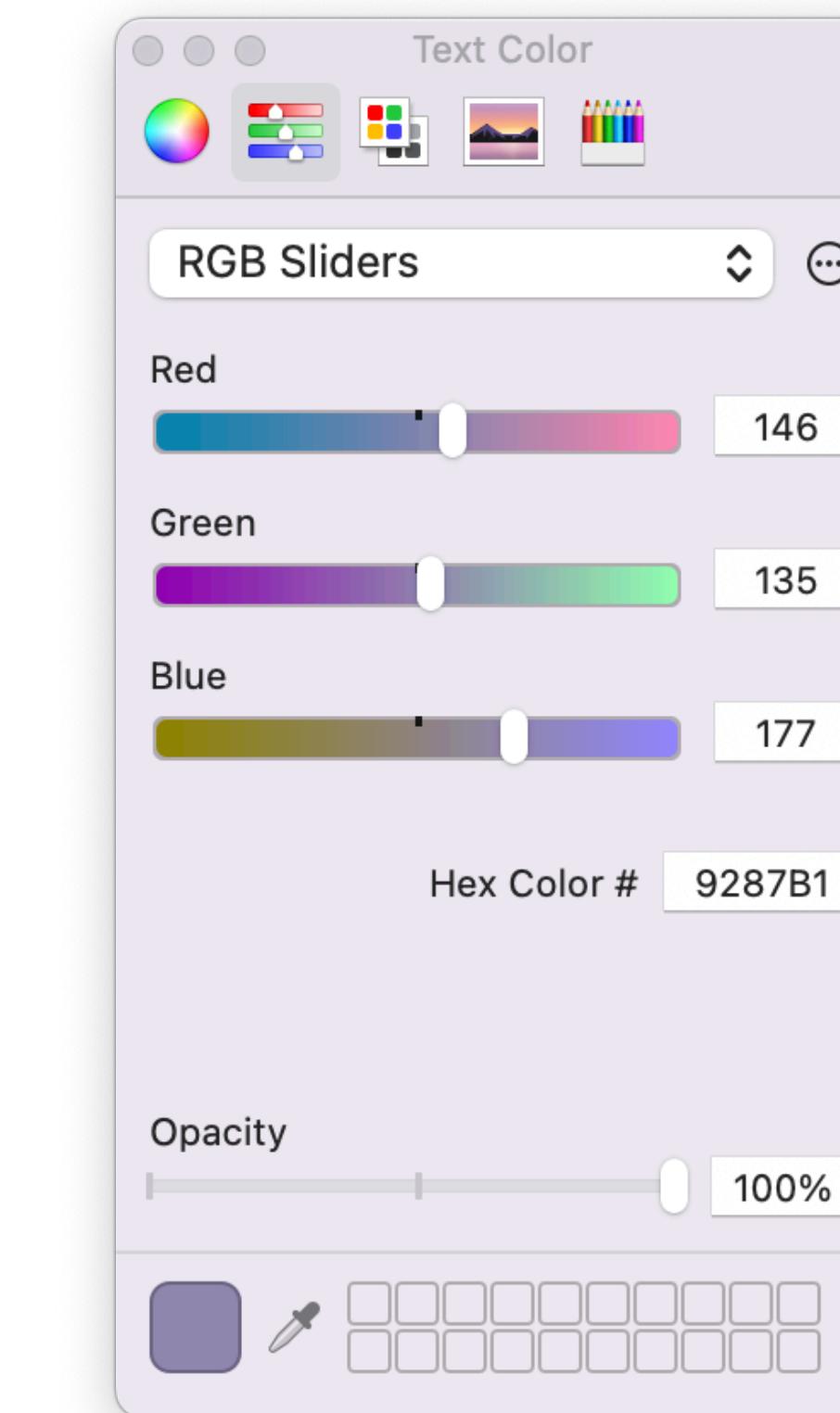
```
colors ← [ ]  
 $f \leftarrow \dots$            ▷ Choose a constant frequency for cycling colors.  
 $\phi_r, \phi_g, \phi_b \leftarrow \dots$     ▷ Choose a constant phase offset per channel.  
for  $(\_, index)$  in curve do  
    red  $\leftarrow \sin(f \times index + \phi_r)$   
    green  $\leftarrow \sin(f \times index + \phi_g)$   
    blue  $\leftarrow \sin(f \times index + \phi_b)$   
    push(colors, Color(red, blue, green))  
end for
```

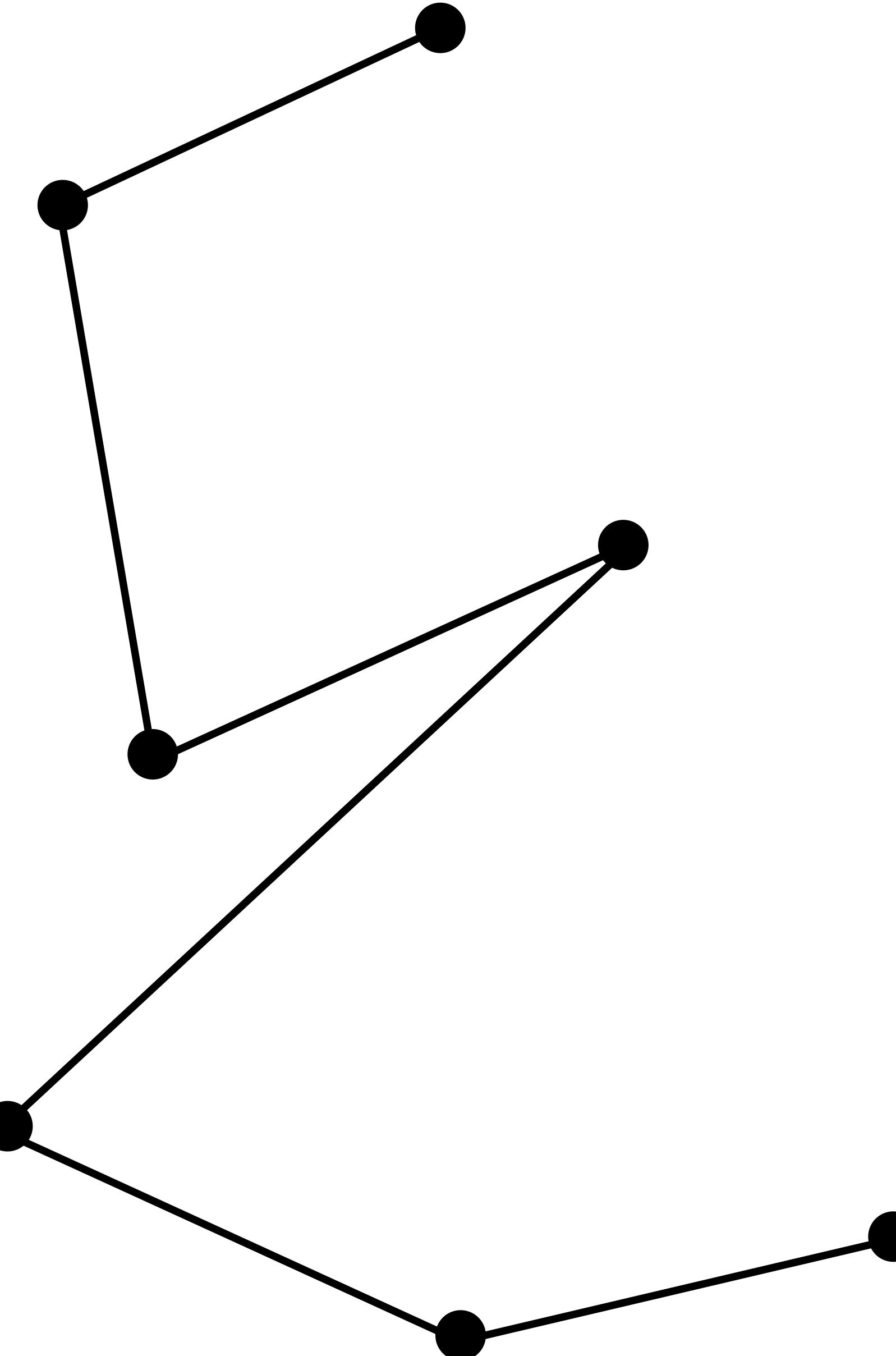


```

colors ← [ ]
f ← ...           ▷ Choose a constant frequency for cycling colors.
ϕr, ϕg, ϕb ← ...    ▷ Choose a constant phase offset per channel.
for _, index) in curve do
    red ← sin(f × index + ϕr)
    green ← sin(f × index + ϕg)
    blue ← sin(f × index + ϕb)
    push(colors, Color(red, blue, green))
end for

```

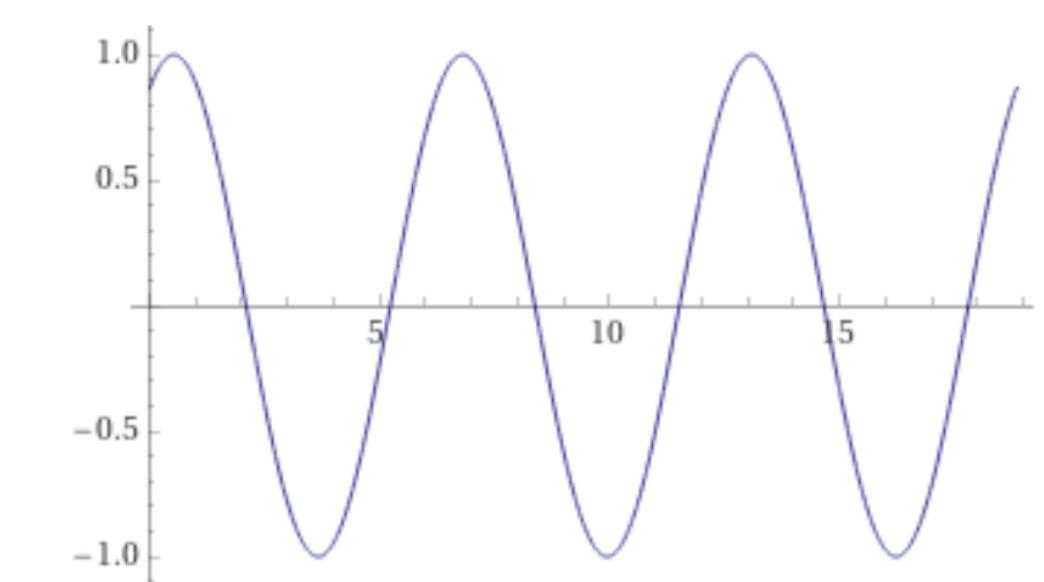
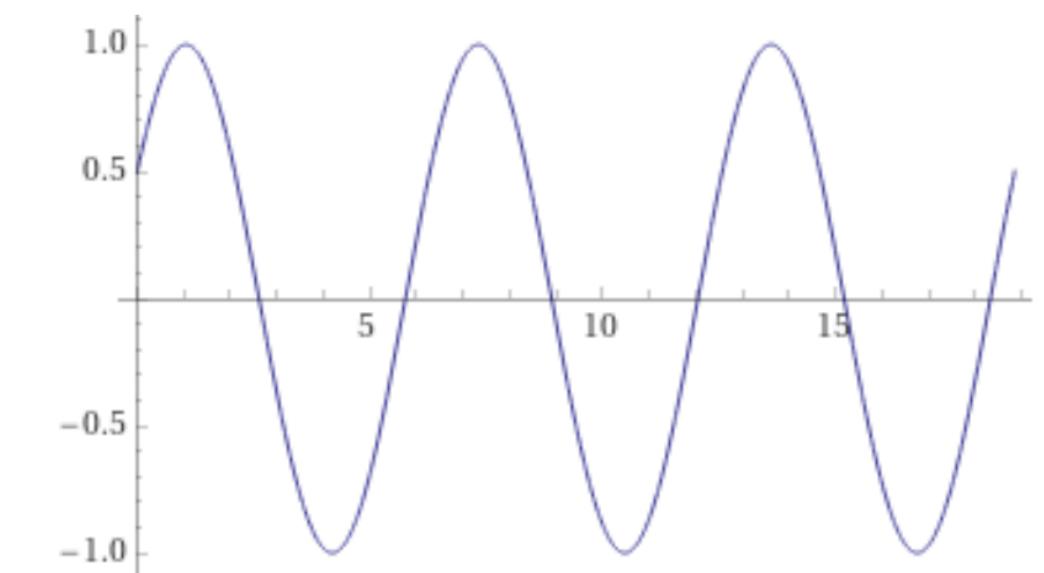
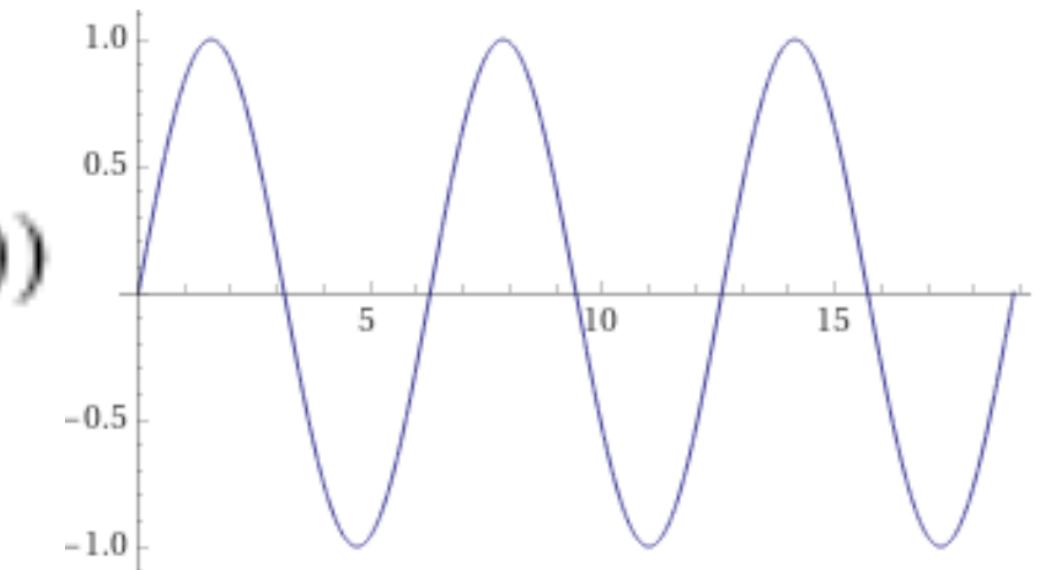
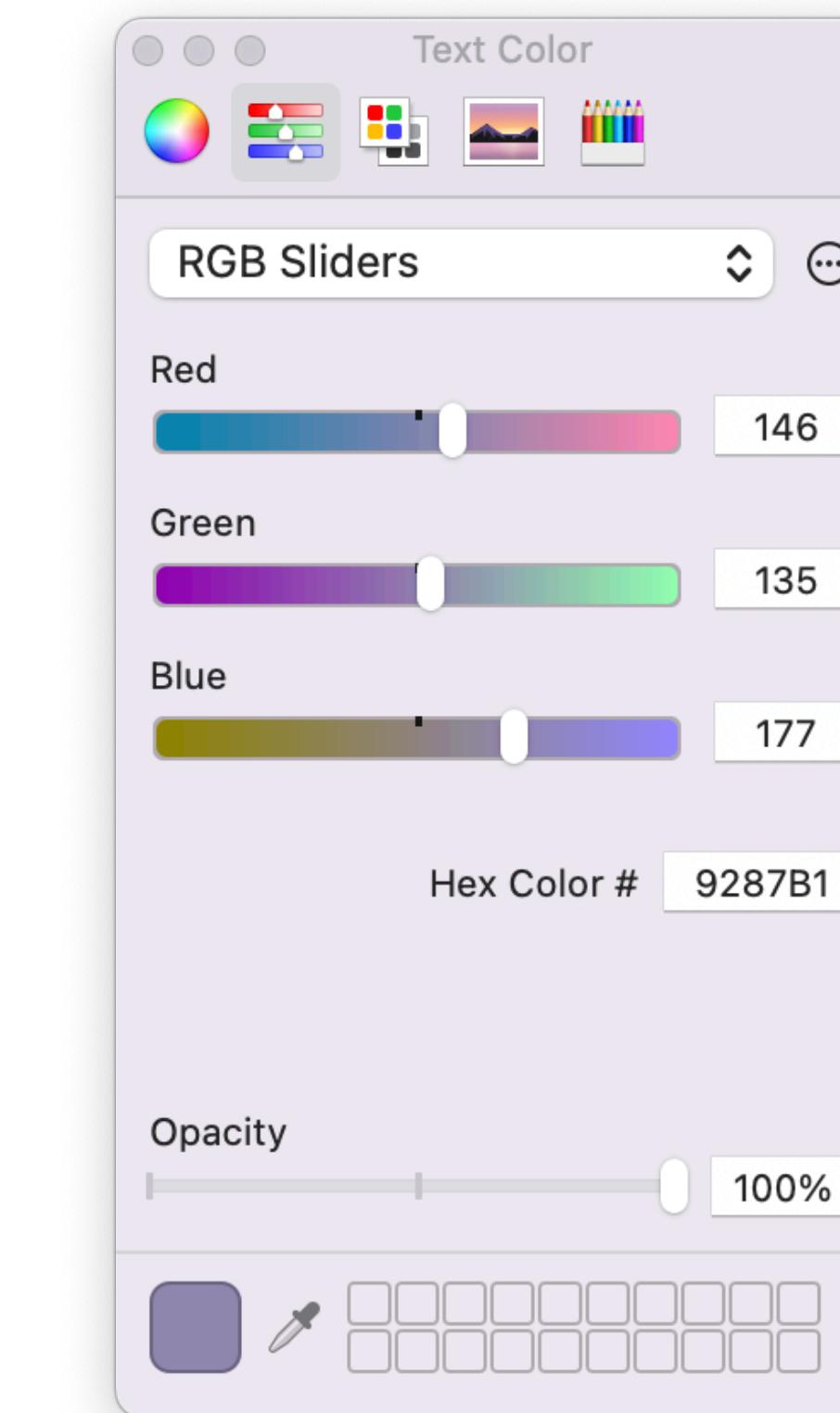


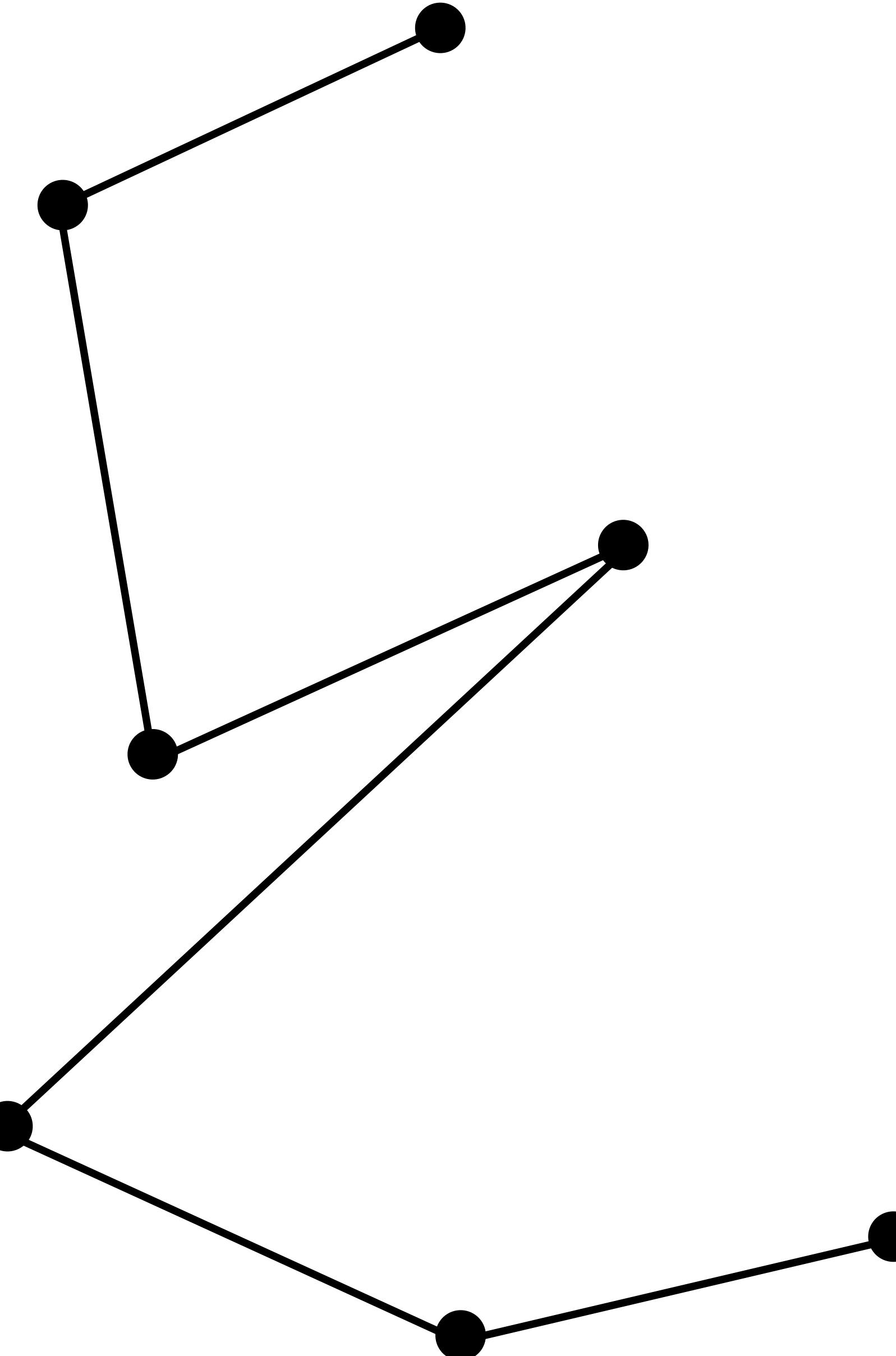


```

colors ← [ ]
f ← ...           ▷ Choose a constant frequency for cycling colors.
ϕr, ϕg, ϕb ← ...    ▷ Choose a constant phase offset per channel.
for _, index) in curve do
    red ← sin(f × index + ϕr)
    green ← sin(f × index + ϕg)
    blue ← sin(f × index + ϕb)
    push(colors, Color(red, blue, green))
end for

```

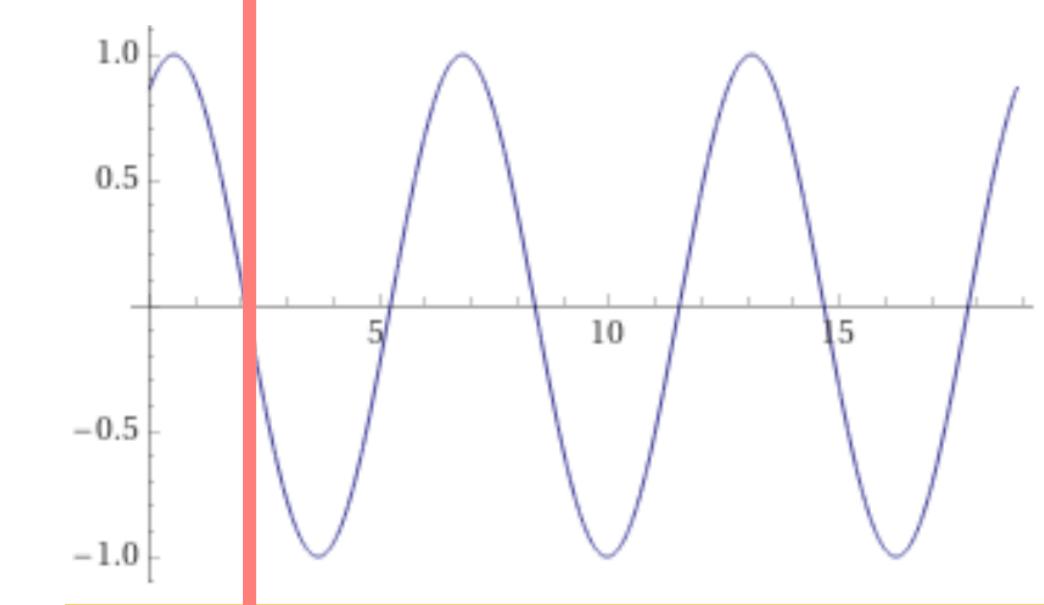
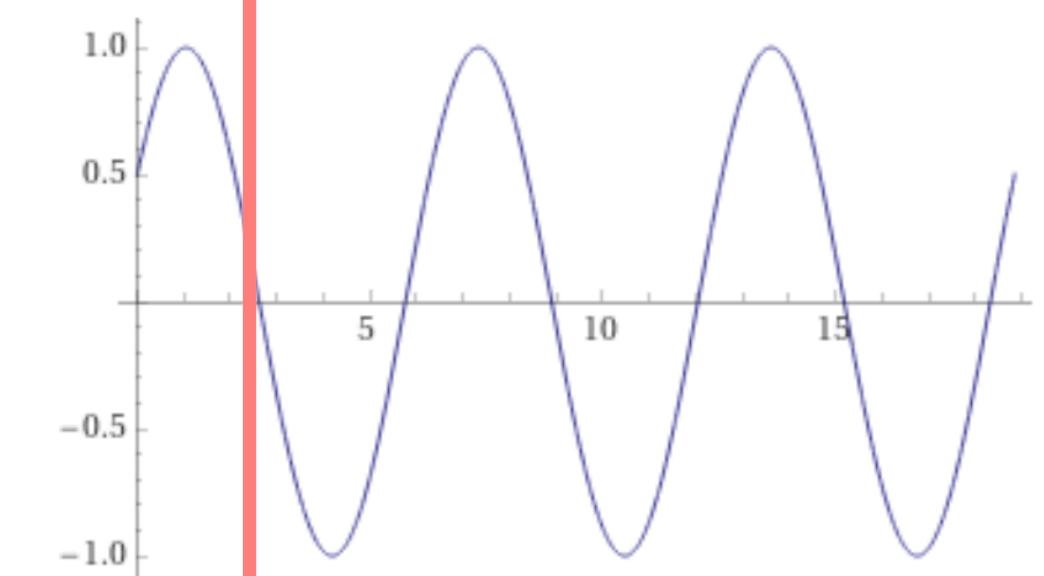
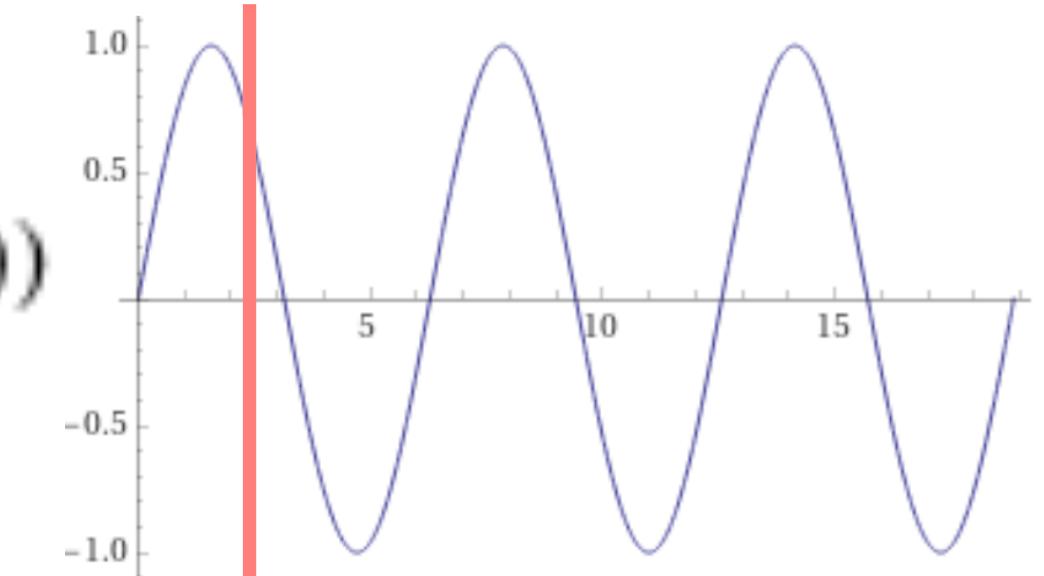
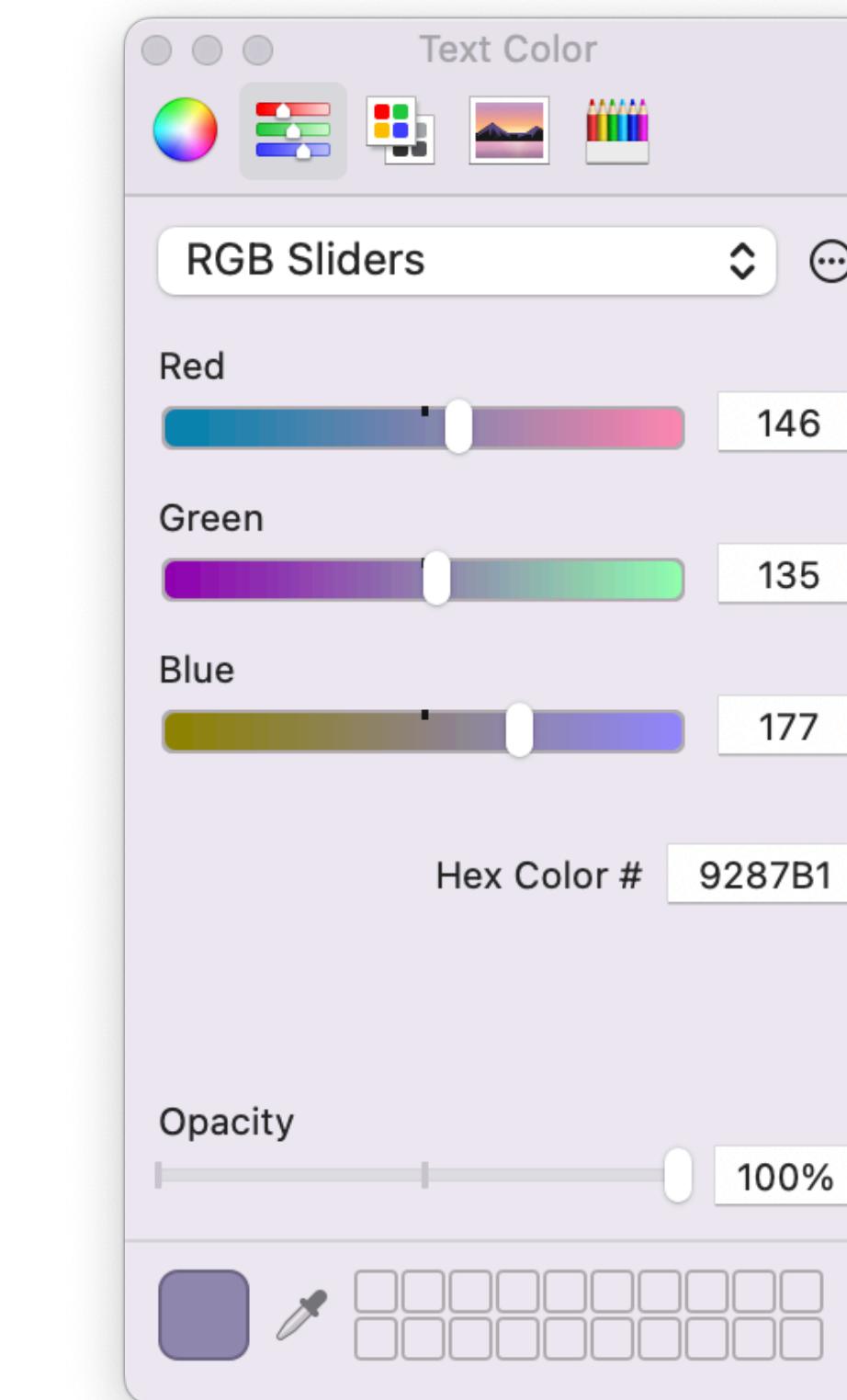


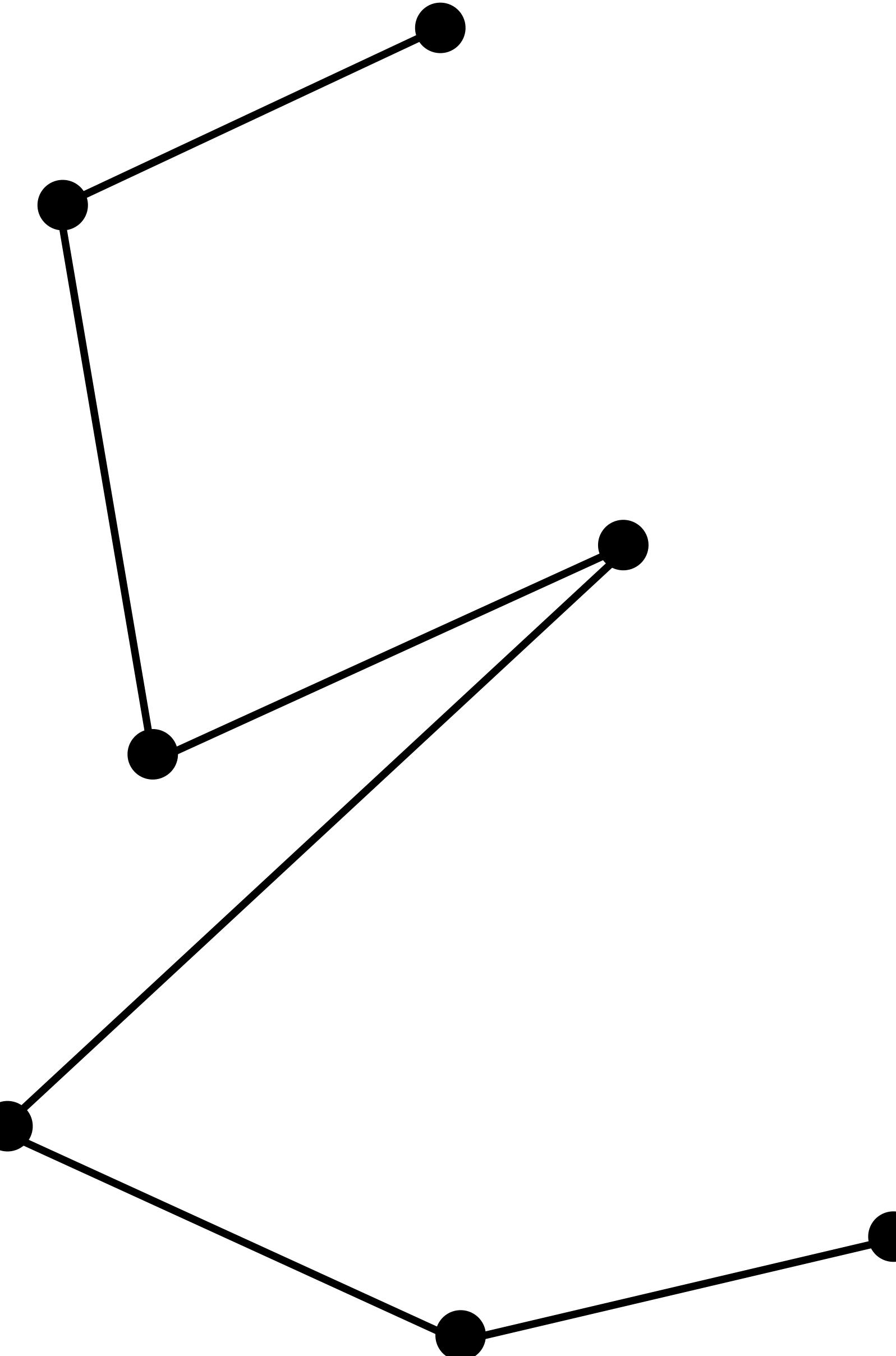


```

colors ← [ ]
f ← ...           ▷ Choose a constant frequency for cycling colors.
ϕr, ϕg, ϕb ← ...    ▷ Choose a constant phase offset per channel.
for _, index) in curve do
    red ← sin(f × index + ϕr)
    green ← sin(f × index + ϕg)
    blue ← sin(f × index + ϕb)
    push(colors, Color(red, blue, green))
end for

```

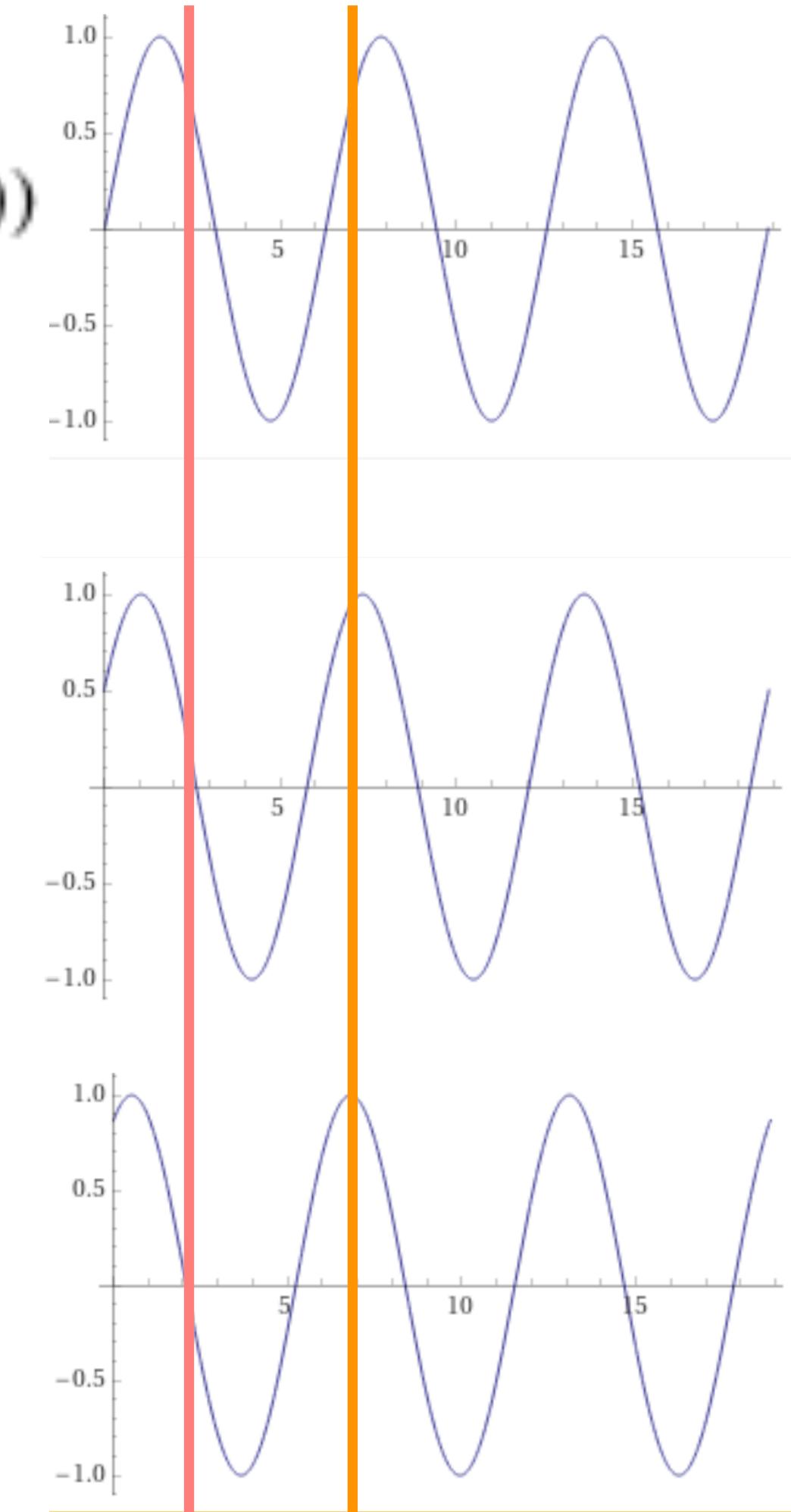
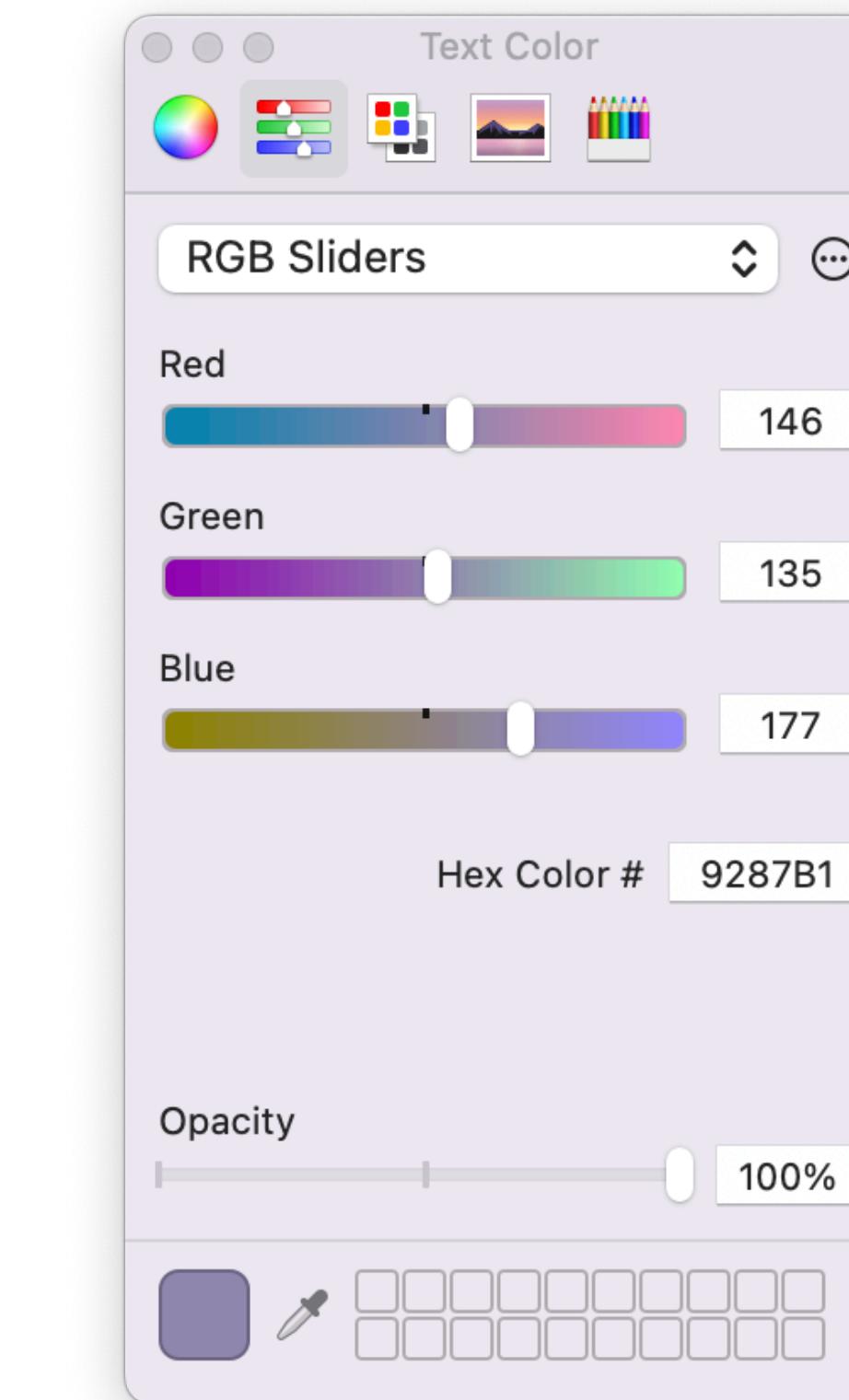


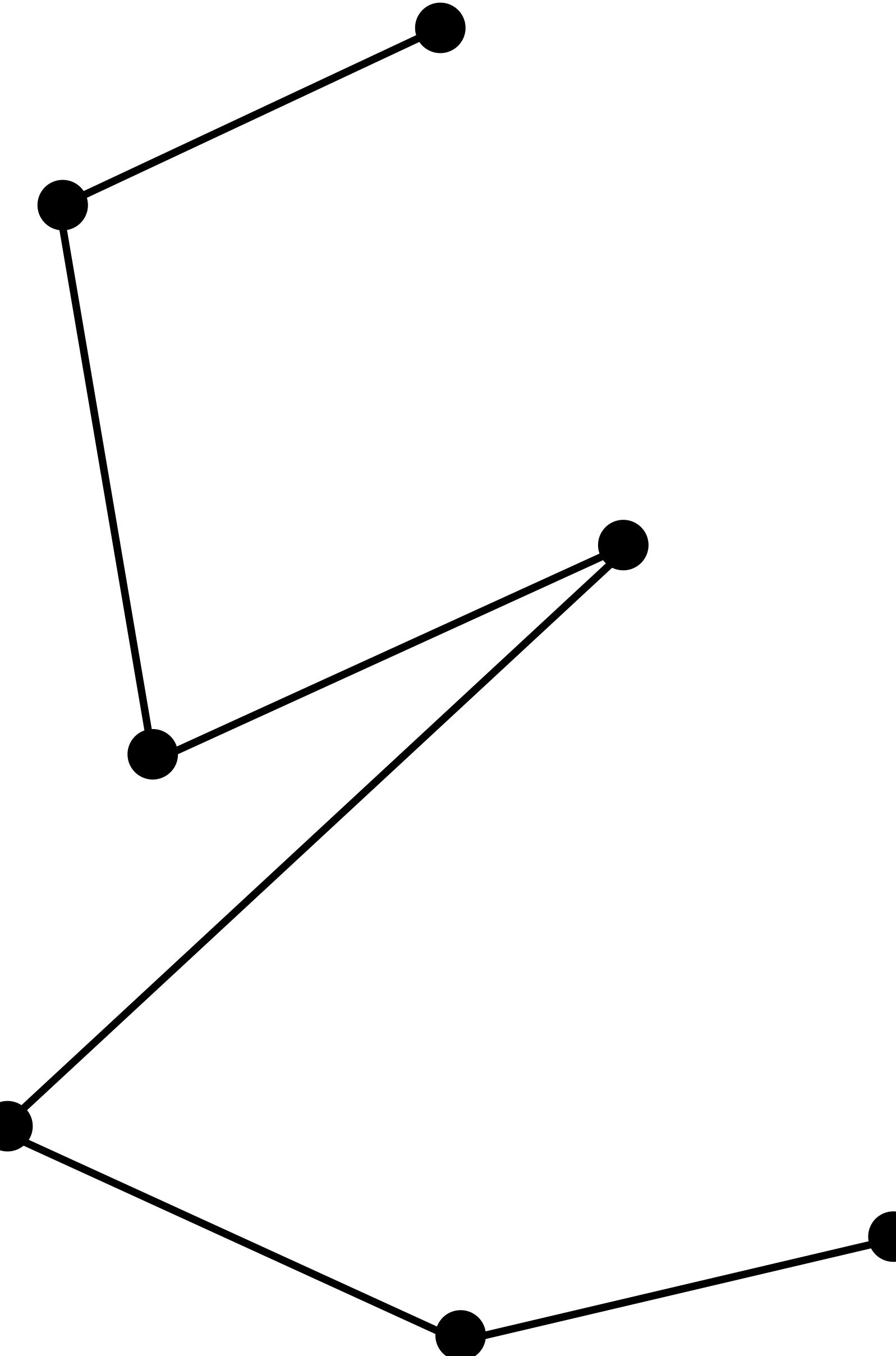


```

colors ← [ ]
f ← ...           ▶ Choose a constant frequency for cycling colors.
ϕr, ϕg, ϕb ← ...   ▶ Choose a constant phase offset per channel.
for _, index) in curve do
    red ← sin(f × index + ϕr)
    green ← sin(f × index + ϕg)
    blue ← sin(f × index + ϕb)
    push(colors, Color(red, blue, green))
end for

```

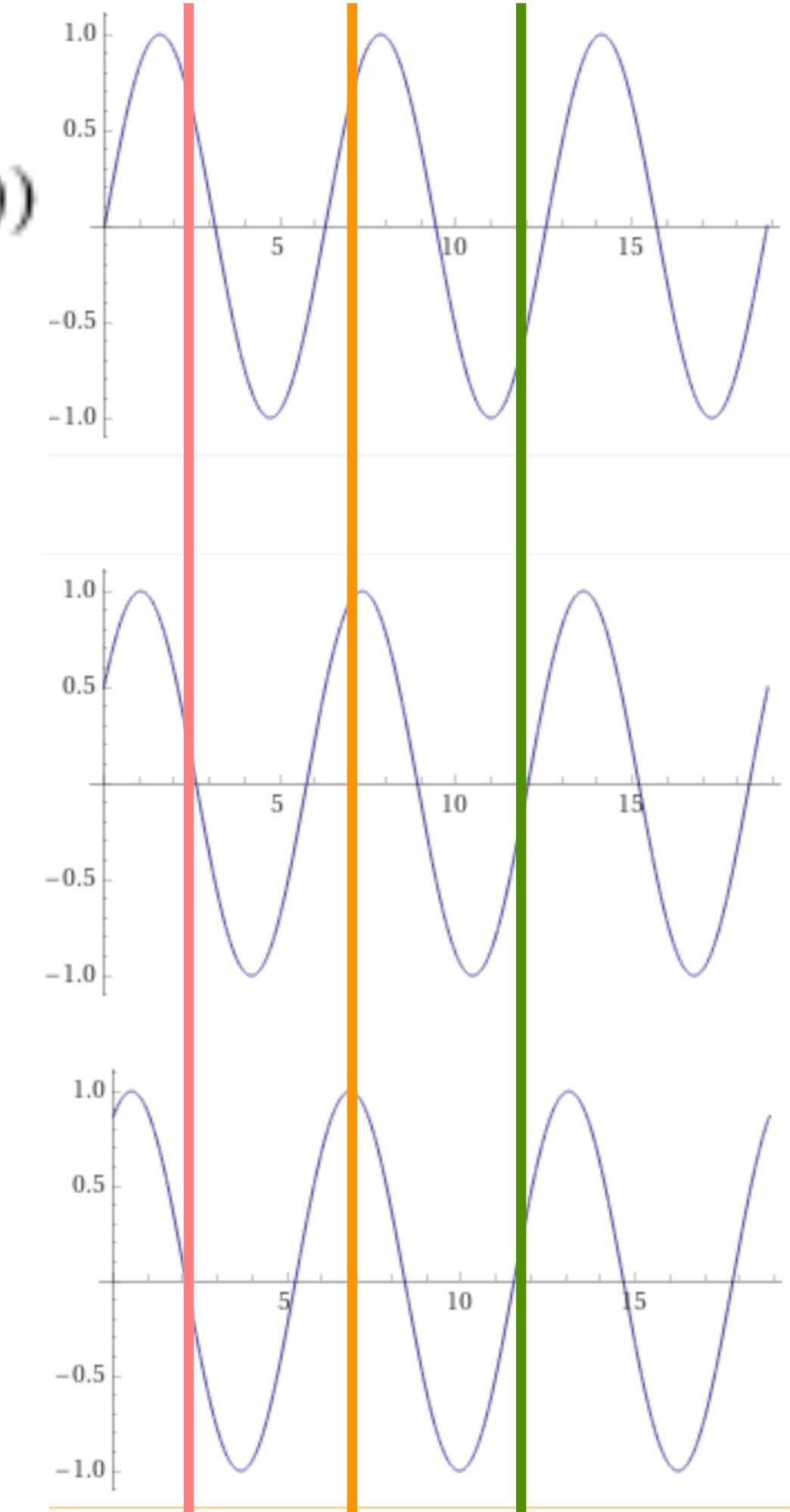
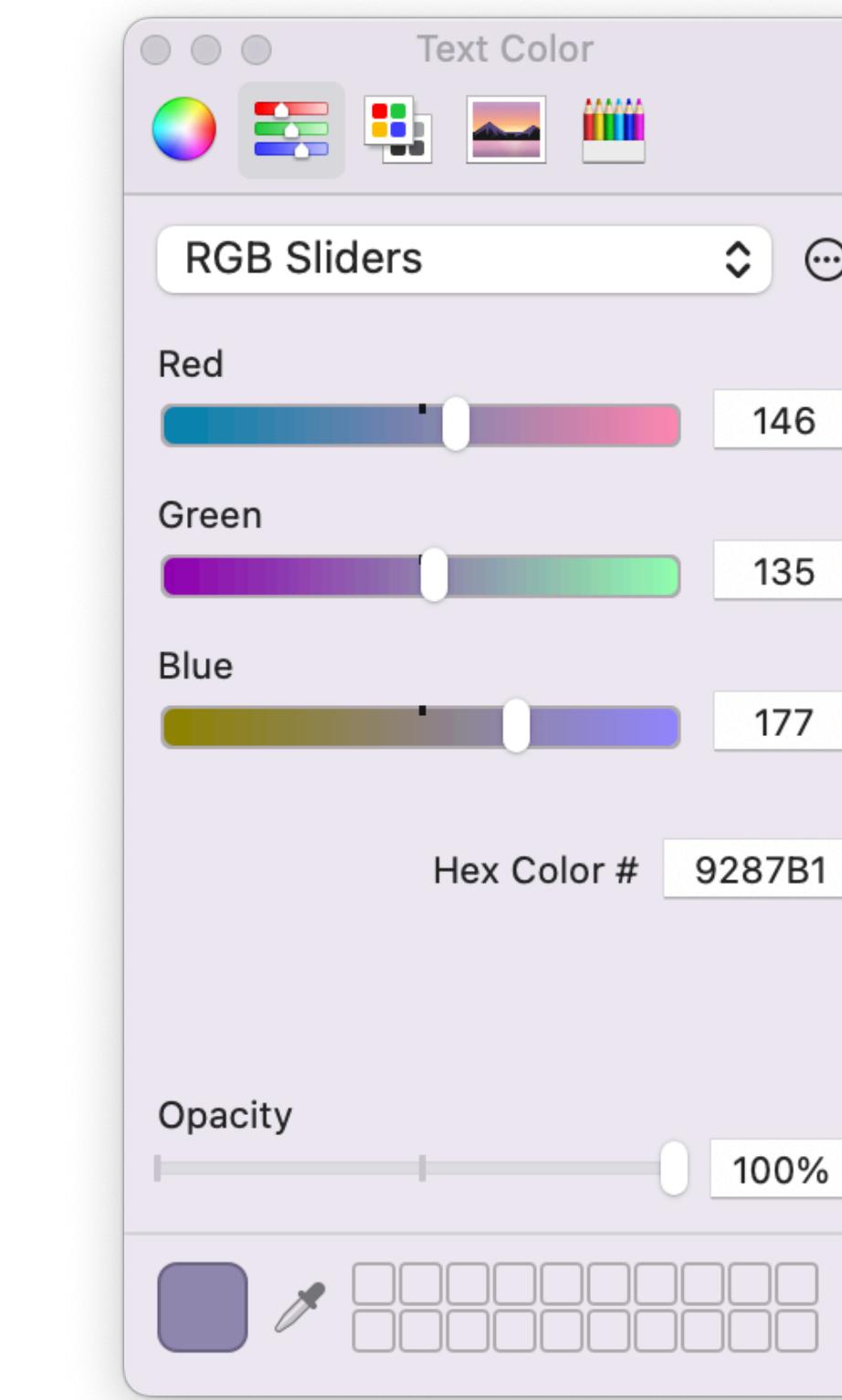


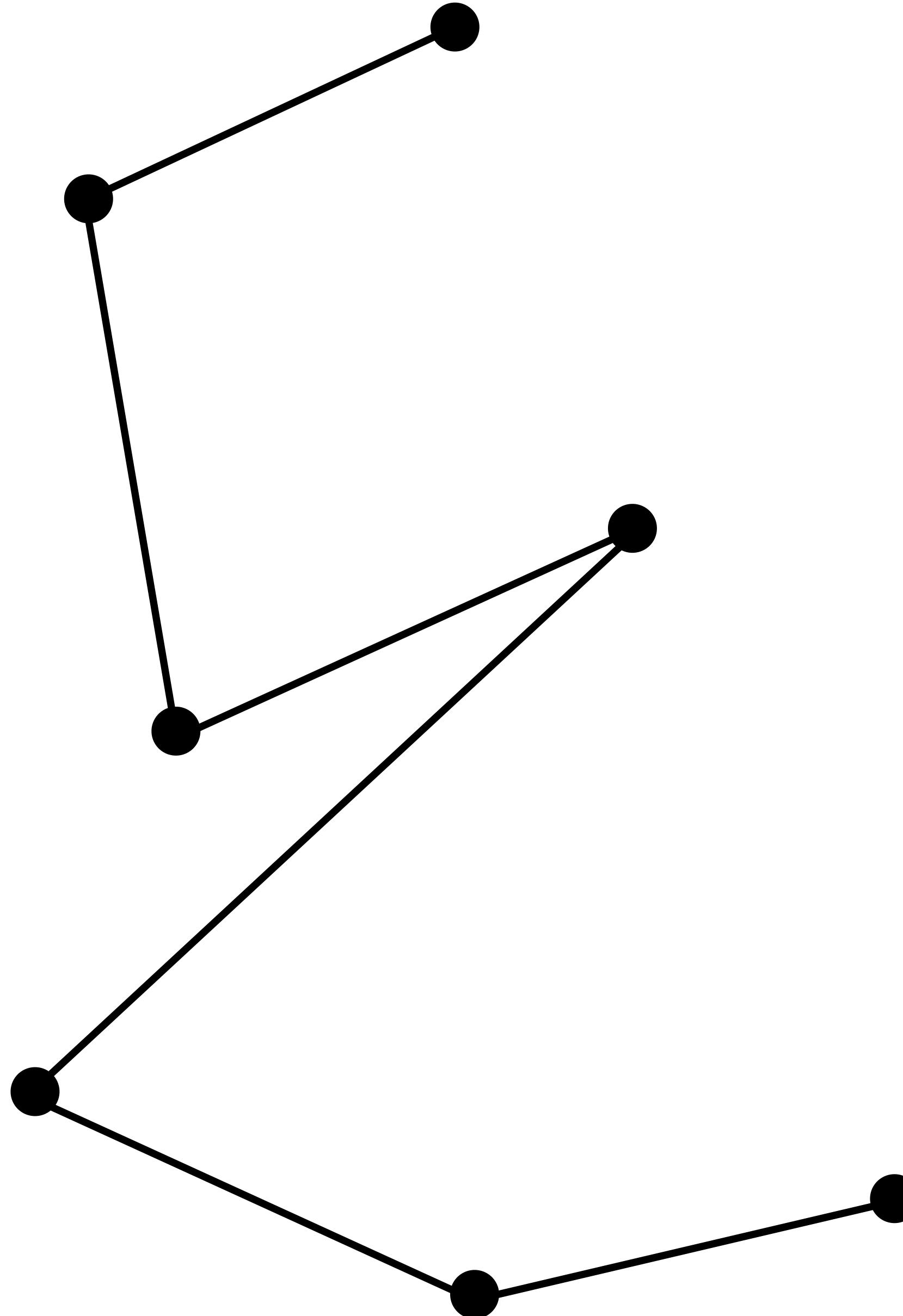


```

colors ← [ ]
f ← ...           ▶ Choose a constant frequency for cycling colors.
ϕr, ϕg, ϕb ← ...   ▶ Choose a constant phase offset per channel.
for _, index) in curve do
    red ← sin(f × index + ϕr)
    green ← sin(f × index + ϕg)
    blue ← sin(f × index + ϕb)
    push(colors, Color(red, blue, green))
end for

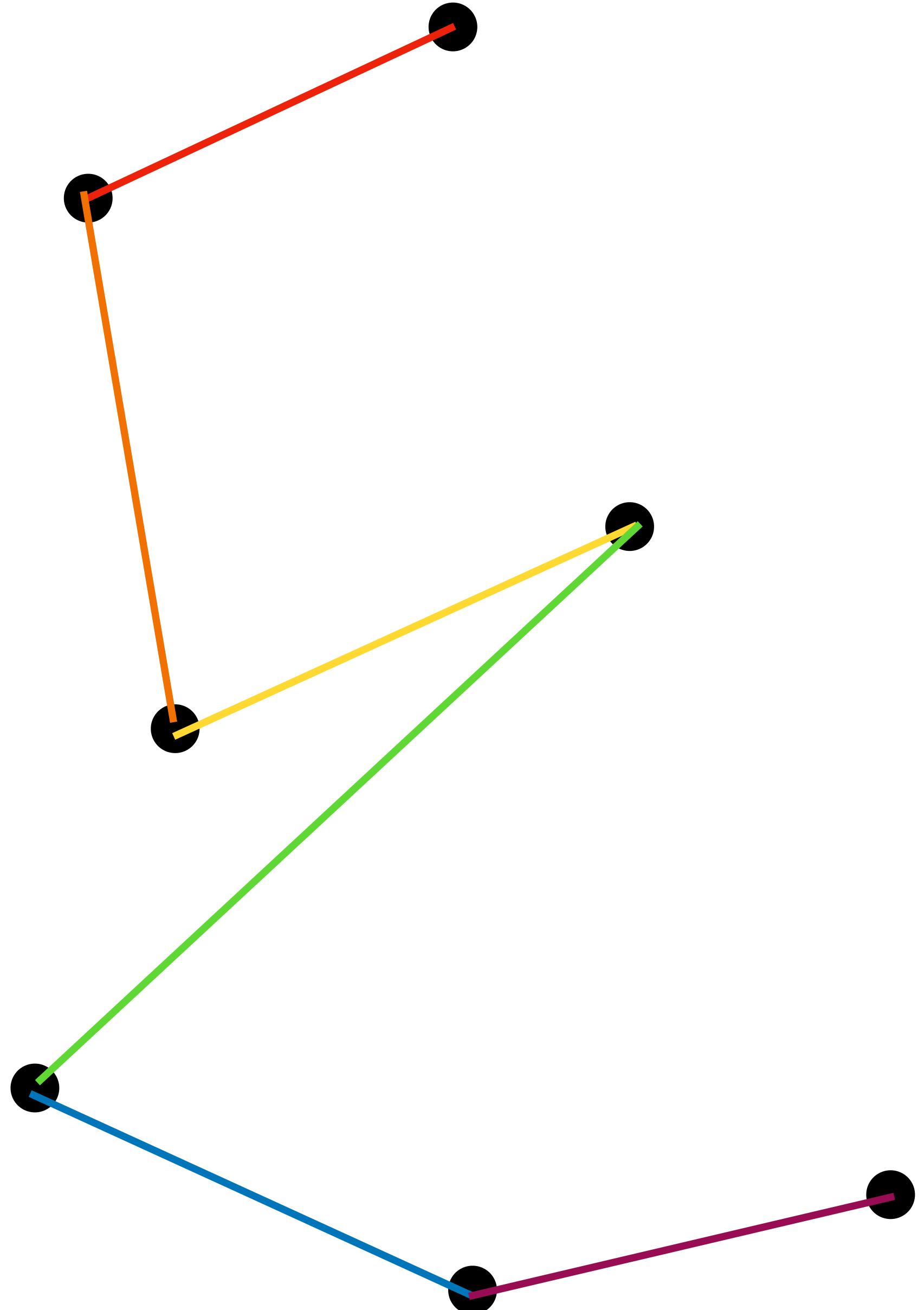
```





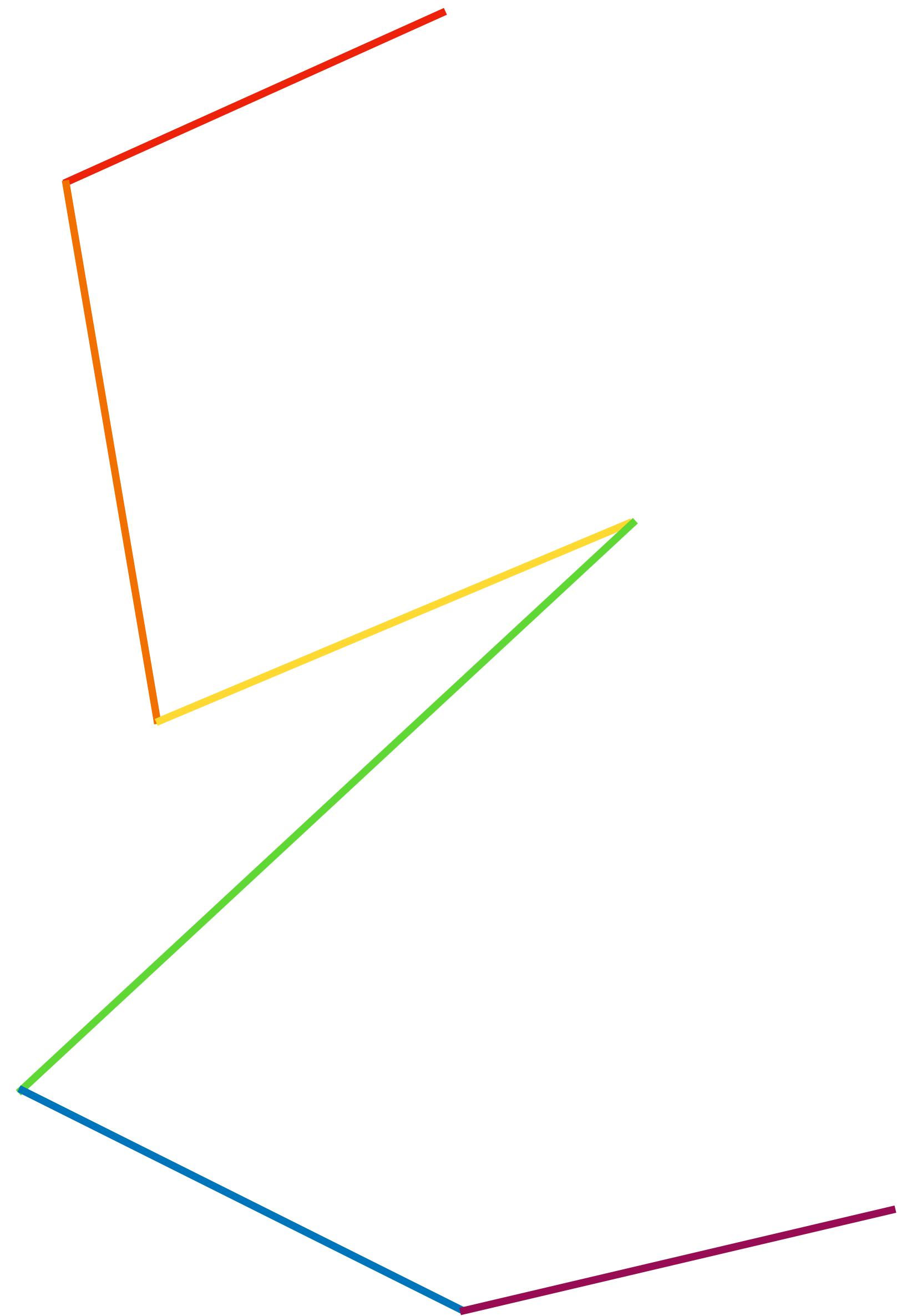
```
colors ← [ ]  
 $f \leftarrow \dots$            ▷ Choose a constant frequency for cycling colors.  
 $\phi_r, \phi_g, \phi_b \leftarrow \dots$     ▷ Choose a constant phase offset per channel.  
for  $(\_, index)$  in curve do  
    red  $\leftarrow \sin(f \times index + \phi_r)$   
    green  $\leftarrow \sin(f \times index + \phi_g)$   
    blue  $\leftarrow \sin(f \times index + \phi_b)$   
    push(colors, Color(red, blue, green))  
end for
```





```
meshes ← [ ]
for (segment, index) in curves do
    color ← colors[index]
    mesh ← Mesh(curve, color)
    push(meshes, mesh)
end for
return meshes
```





```
meshes ← [ ]
for (segment, index) in curves do
    color ← colors[index]
    mesh ← Mesh(curve, color)
    push(meshes, mesh)
end for
return meshes
```

