

Unsupervised Learning: Clustering

K-means, Density-based

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All material in these lecture notes is based on our textbook: Aurélien Géron, *Hands-On Machine Learning with Scikit-Learn and TensorFlow*, 3rd ed., O'Reilly, 2022

Clustering

- Clustering is one of the most common tasks of unsupervised learning, where data is unlabelled
- Most available data is unlabelled! The process of labelling the data is an option (e.g. by using human experts) but it is:
 - Time-consuming
 - Costly
 - Error-prone
 - and needs to be repeated every time the dataset changes
- Like in classification, instances need to be assigned to clusters but these are not known a priori

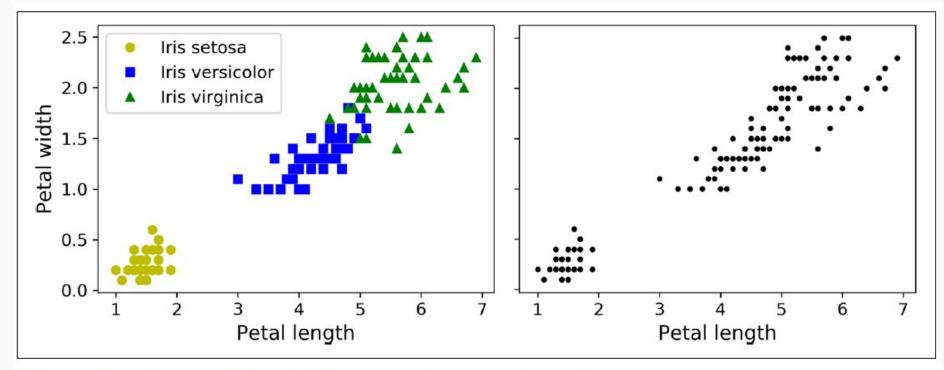


Figure 9-1. Classification (left) versus clustering (right)

Using only the two features, petal width and length, it is not clear that there are three clusters

k-means

k-means

on a random 5-blob dataset

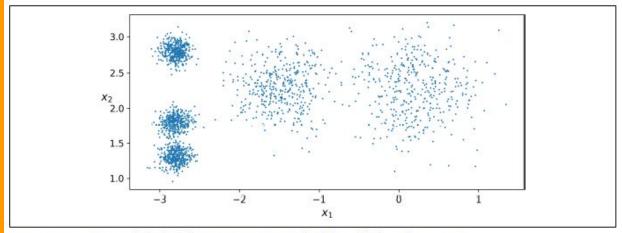


Figure 9-2. An unlabeled dataset composed of five blobs of instances

[-2.80037642, 1.30082566]])

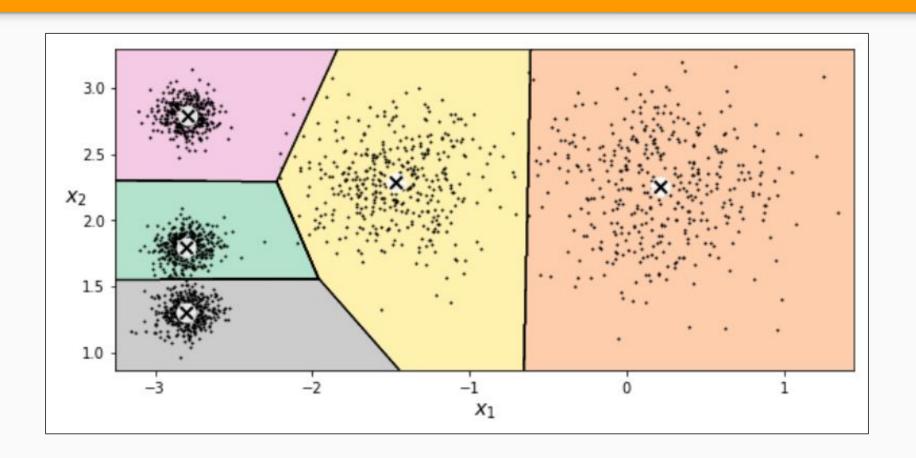
k-means

- Specify the number of clusters k
 - Not always easy to identify k...
- The goal of k-means is to find the centroids of the k clusters
- After the centroids have been identified, any new instance is predicted to belong to the cluster whose centroid is closest to the instance
 - The predicted label of the algorithm is the index of the cluster that it is assigned to

```
y_pred
array([4, 0, 1, ..., 2, 1, 0], dtype=int32)
```

k-means Decision Boundaries

Voronoi tessellation (diagram)



K-means

How are the centroids identified?

init="random"

k-means is one of the simplest and fastest clustering algorithms

- First initialise k centroids randomly: e.g., k distinct instances are chosen randomly from the dataset and the centroids are placed at their locations
- Repeat until convergence (i.e., until the centroids stop moving):
 - Assign each instance to the closest centroid
 - Update the centroids to be the mean of the instances that are assigned to them

The algorithm is guaranteed to converge in a finite number of steps

k-means

Limitation of Random Centroid initialisation

- Depending on the initial (random) centroid initialisation, k-means may converge in a sub-optimal solution (local optimum)
- Two popular solutions:
 - o **n** random initialisations
 - *k*-means++

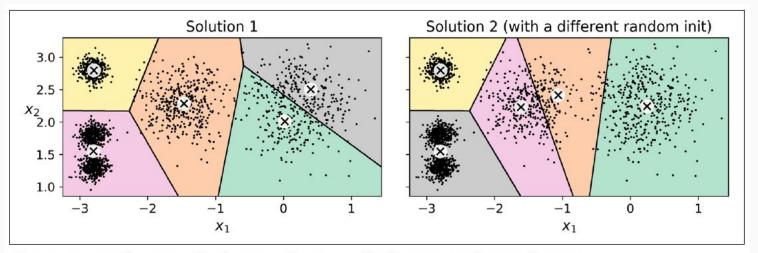


Figure 9-5. Suboptimal solutions due to unlucky centroid initializations

k-means centroid initialisation

n random initialisations

- Run the algorithm n times with n different random initialisations and keep the best one
- Controlled by the n_init hyperparameter

k-means centroid initialisation

Inertia

kmeans_rnd_10_inits.inertia_ 211.5985372581684

- To know which of the n is best, you need a performance measure: inertia
 - the mean squared distance between each instance and its closest centroid
- The best is the one with the lowest inertia

k-means centroid initialisation

k-means++

- Smarter random initialization
- Selects centroids that are distant from one another
- Scikit's KMeans class uses this as the default initialisation method —just do not define the init parameter

k-means

Finding the optimal number of clusters

- Finding k, in most cases, is not easy
- Inertia is not a good measure when trying to choose k
 - It becomes smaller as k increases
 - Because the distance of the instances from the closest centroids will get smaller as clusters increase
- A simple rule-of-thumb to adapt k:
 - If single clusters contain different entities, increase k
 - \circ If entities spread across clusters, decrease $m{k}$
- But there are techniques that can be used to help you

k-means Finding the optimal number of clusters

Inertia as a function of k — the elbow

- Computationally cheap but not necessarily accurate
- Not enough on its own

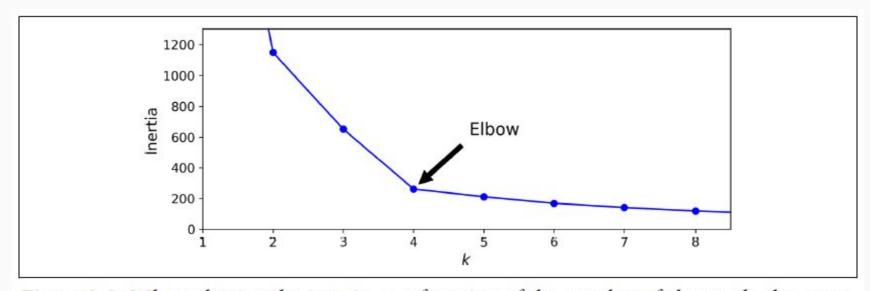


Figure 9-8. When plotting the inertia as a function of the number of clusters k, the curve often contains an inflexion point called the "elbow"

k-means Finding the optimal number of clusters

The silhouette score

- More precise, but
- Computationally more expensive
- The silhouette score is the mean silhouette coefficient over all the instances
- An instance's silhouette coefficient is in the range
 [-1, 1]
 - **~1**: instance is well inside its cluster
 - ~0: instance is close to cluster's boundary
 - ~-1: instance may have been assigned to a wrong cluster

Comparison of silhouette scores for various **k**

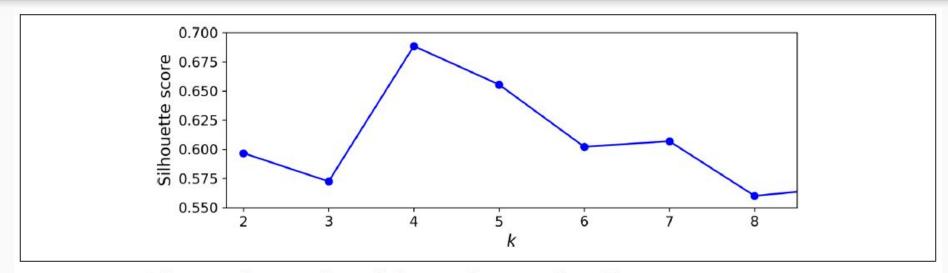
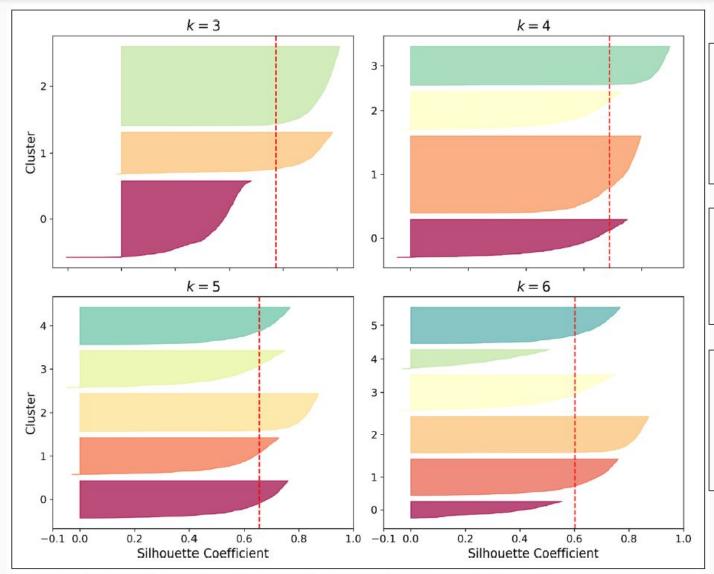


Figure 9-9. Selecting the number of clusters k using the silhouette score

- k=4 still appears to be the most promising
- But now k=5 looks more promising than demonstrated by the inertia
- We can further explore by plotting a silhouette diagram

Silhouette diagram for various **k**



The vertical dashed lines represent the silhouette score for each number of clusters

k=3 and **k**=6 are clearly bad because clusters fall short of the silhouette score

Analysing the diagram we can identify k=5 as better than k=4 because clusters have more similar sizes

Figure 9-10. Analyzing the silhouette diagrams for various values of k

k-means

Limitations

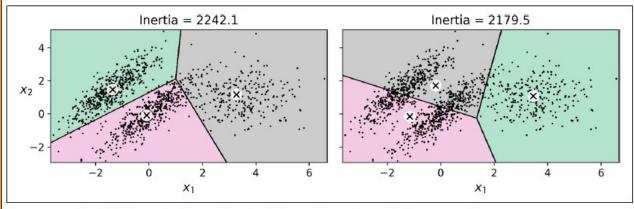


Figure 9-11. K-Means fails to cluster these ellipsoidal blobs properly

- Even after you go through the hassle of identifying the best k
 and running several times to avoid suboptimal solutions,
 k-means will not do a good job when the clusters are:
 - of varying sizes
 - of varying densities
 - non-spherical in shape
- For non-spherical clusters:
 - Try scaling the features (still does not guarantee a spherical form)
 - Or prefer Gaussian mixture models (outside the scope of this module)

DBSCAN

E and min_samples are the only
two hyperparameters of DBSCAN

Density-Based Spatial Clustering of Applications with Noise

- DBSCAN defines clusters as continuous regions of high density
- For each instance, count how many instances are located within a small distance ε (epsilon) from it
 ⇒ instance's ε-neighborhood
- If an instance has at least min_samples instances in its ε-neighborhood (including itself)
 - ⇒ core instance (i.e., located in dense regions)

DBSCAN

Density-Based Spatial Clustering of Applications with Noise (cont'd)

- All instances in the neighborhood of a core instance belong to the same cluster
- A core instance's neighborhood may include other core instances
 - ⇒ a sequence of neighboring core instances forms a single cluster
- Any instance that is not a core instance and does not have one in its neighborhood is considered an anomaly

```
from sklearn.cluster import DBSCAN
from sklearn.datasets import make_moons
```

DBSCAN

on the moons dataset

To get the identified labels of the (first 10) instances: (-1 denotes the instance is identified as an anomaly)

X, y = make moons(n samples=1000, noise=0.05, random state=42)

```
dbscan.labels_[:10]
array([0, 0, 0, 0, 1, 0, 0, 0, 0, 1])
```

dbscan = DBSCAN(eps=0.05, min samples=5)

dbscan.fit(X)

To get the core samples and their labels:

```
dbscan.core_sample_indices_[:10]
array([ 0,  4,  5,  6,  7,  8,  10,  11,  12,  13])
```

Regularisation of DBSCAN using ε

With €=0.05 DBSCAN identifies 7 clusters (identified by the different colours).

The crossed instances are identified as anomalies.

With ε =0.2 DBSCAN identifies 2 clusters that make sense.

Not bad!!

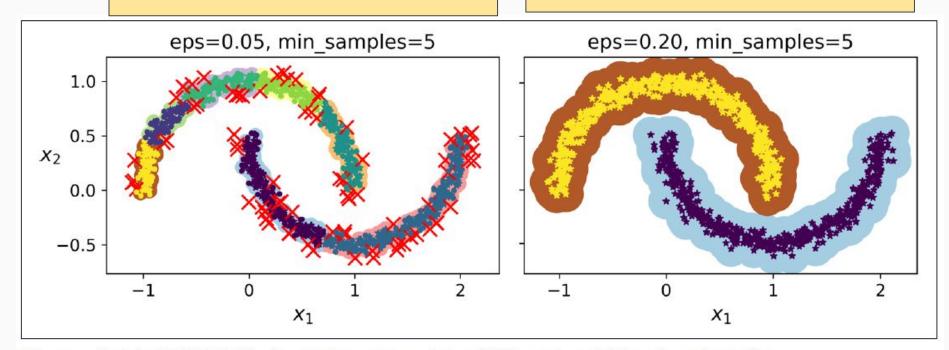


Figure 9-14. DBSCAN clustering using two different neighborhood radiuses

DBSCAN performs Clustering, not Classification!

- DBSCAN is a clustering, not a classification algorithm, which means:
- it does not predict the class of new instances!
 - Does not have a predict() method
- The rationale is that, after the clusters have been identified by DBSCAN, different classification algorithms can be used, depending on the task

Combining DBSCAN with KNN for Classification

- You may use a k-nearest neighbor (KNN) classifier to predict the class
- You can train the KNN classifier:
 - Only on the core instances that DBSCAN identifies
 - OR on the entire training set
 - OR on the entire training set excluding the anomalies
- KNN is supervised learning classifier which uses proximity to make classifications
- k in KNN defines the number of neighbours to be identified for any new instance

k-Nearest Neighbors

for Classification and Regression

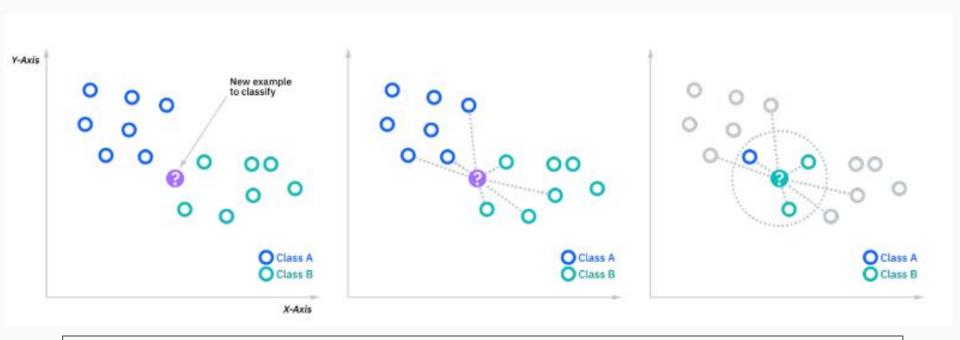
Classification

- It predicts the class of the new instance by a majority vote
 - If there are overall two classes, the one with >50% wins
 - If there are overall four classes, the one with >25% wins, etc.
- A plurality vote may also be used
 - select the class with the more votes

Regression

 The concept is the same but the target value is determined as the average of the values of the k-nearest neighbors

k-Nearest Neighbors



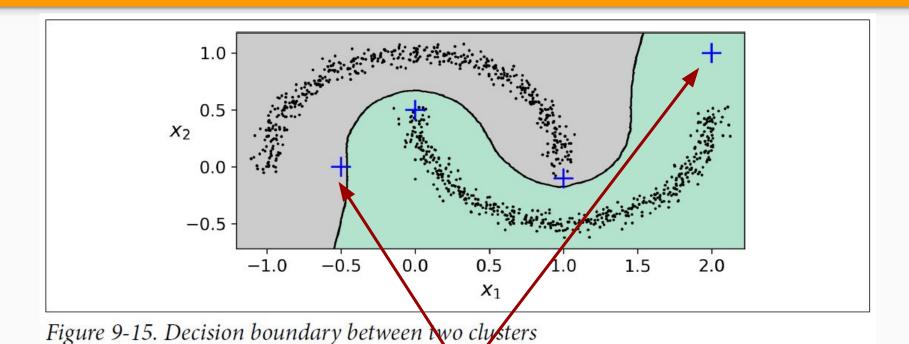
- Various **Distance Metrics** can be used:
 - Euclidean distance, Manhattan distance, etc.
- In case of a tie, reduce k until tie is broken

DBSCAN combined with KNN

```
from sklearn.neighbors import KNeighborsClassifier
knn = KNeighborsClassifier(n_neighbors=50)
knn.fit(dbscan.components_, dbscan.labels_[dbscan.core_sample_indices_])
```

for Classification on the moons dataset

Result of combining BDSCAN with KNN



- These two new instances will be assigned to the closest class
 - Unless you define a maximum distance for instances to belong to the class
- If the distance is exceeded, the instance will be classified as an anomaly

DBSCAN

Limitations

- DBSCAN will underperform, when:
 - Density varies significantly across clusters
 - There is no sufficiently low-density region around the clusters
 - ⇒ in such cases, use hierarchical DBSCAN
- Computationally complex so it does not scale well to large datasets

That's all, Folks!

Thank you!