

Vector Spaces and Subspaces

Vector space:-

The space \mathbb{R}^n consists of all column vectors v with n components.

→ should obey 8 conditions.

Similarly, $M \Rightarrow$ The vector space of all real 2×2 matrices.

$F \Rightarrow$ The vector space of all real functions $f(x)$.

$Z \Rightarrow$ The vector space with only a zero vector.

→ No space can do without zero vector. Each space has its own zero vector, the zero matrix, the zero function..

Subspace:-

A subspace of a vector space is a set of vectors (including 0) that satisfies two requirements.

If v and w are vectors in the subspace and c is any scalar, then

i) $v + w$ is in the subspace

ii) cv is in the subspace.

→ Every subspace contains the zero vector. From rule ii) if $c=0$, then $cv=0$ should be in subspace.

→ For \mathbb{R}^3 , possible subspaces are

i) $L \rightarrow$ Any line through $(0,0,0)$

ii) $P \rightarrow$ Any plane through $(0,0,0)$

iii) $\mathbb{R}^3 \rightarrow$ The whole space

iv) $Z \rightarrow$ The single vector $(0,0,0)$

→ A subspace containing v and w must contain all linear combinations $cv + dw$.

Column space:-

It consists of all linear combinations of the columns.

The system $Ax=b$ is solvable if and only if b is in the column space of A .

$$\begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix}_{m \times n} \begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix}_{n \times 1} = \begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix}_{m \times 1}$$

Ex: $C(A)$ if $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ is the whole space \mathbb{R}^2

Is it a subspace? Yes

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$v = \begin{bmatrix} a \\ c \end{bmatrix}, \quad w = \begin{bmatrix} b \\ d \end{bmatrix}$$

$$v+w = \begin{bmatrix} a+b \\ c+d \end{bmatrix}$$

$$q(v+w) = \begin{bmatrix} qa+qb \\ qc+qd \end{bmatrix}$$

Null Space:-

The nullspace of A consists of all solutions to $Ax=0$.

Is it a subspace? Yes.

Suppose x and y are in $N(A) \Rightarrow Ax=0$ and $Ay=0$
then from rules of matrix multiplication, $A(x+y)=0$ to
also $A(cx)=c \cdot 0$. Therefore $x+y$ and cx are
also in the $N(A)$.

Ex:- $A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}$

$$Ax=0 \Rightarrow \begin{aligned} x_1 + 2x_2 &= 0 \\ 3x_1 + 6x_2 &= 0 \end{aligned} \rightarrow \begin{aligned} x_1 + 2x_2 &= 0 \\ 0 &= 0 \end{aligned}$$

$$x_1 = -2x_2 \Rightarrow \begin{bmatrix} -2 \\ 1 \end{bmatrix} \text{ special solution.}$$

$N(A)$ contains all multiples of $s = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$

Ex- $x + 2y + 3z = 0 \quad \leftarrow \quad [1 \ 2 \ 3] \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \end{bmatrix}$

for $y=1$ & $z=0 \Rightarrow x = -2$

for $z=1$ & $y=0 \Rightarrow x = -3$

$s_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \quad s_2 = \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$ two special solutions

Nullspace is span of s_1, s_2

3. Multiplication

9. Linear Independence, Basis, and Dimension:-

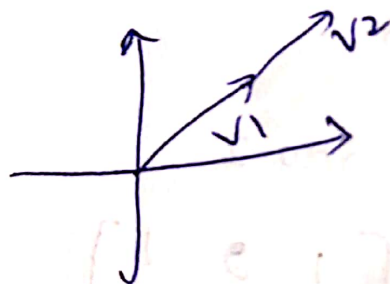
→ Suppose A is $m \times n$ with $m < n$. Then there are non-zero solutions to $AX=0$.
(more unknowns than equations)

Reason:- There will be free variables !!

Independence:- Vectors x_1, x_2, \dots, x_n are independent if no combination gives zero vector (except the zero combination \Rightarrow all $c_i = 0$)

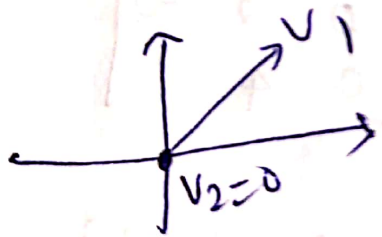
$$c_1 x_1 + c_2 x_2 + \dots + c_n x_n \neq 0$$

Ex:-



$$2v_1 - v_2 = 0$$

dependent



$$0v_1 + cv_2 = 0 \text{ independent}$$

Repeat v_1, \dots, v_n are ~~inde~~ columns of A .
They are independent if nullspace of A is $\{ \text{Zero vector} \}$. They are dependent if $Ac=0$ for some non-zero c .

Rank:- Independent $\rightarrow \text{rank} = n$ $N(A) = \{0\}$
 Dependent $\rightarrow \text{rank} < n \rightarrow$ free variables.

Span:- Vectors v_1, \dots, v_k span a space means the space consists of all combinations of those vectors.

Basis for a space is a sequence of vectors v_1, \dots, v_d with 2 properties

- 1) they are independent
- 2) they span the space.

(If given basis, then everything about the space will be understood)

Example:-

Space is \mathbb{R}^3

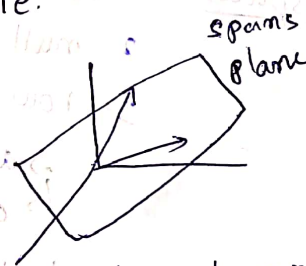
i) one basis is $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

The N (Identity matrix) is $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

ii) Another basis is $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 5 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \\ 8 \end{bmatrix}$

\rightarrow 'n' vectors give basis if the $n \times n$ matrix with those columns is invertible.

iii) $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 5 \end{bmatrix}$



* Any invertible matrix, its columns are basis for \mathbb{R}^3 [millions of basis vectors].

* Every Given a space, every basis for the space has the same number of vectors.
dimension of the space

Example:-

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix}$$

They are not independent

$$N(A) = \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix}$$

$$2 = \text{rank}(A) = \# \text{ pivot columns} = \text{dimension of ColumnSpace}(A)$$

another basis for $C(A) = \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 7 \\ 5 \\ 7 \end{bmatrix}$

$$\dim(C(A)) = \text{rank}$$

$$N(A) \text{ can be: } \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$\dim(N(A)) = \# \text{ free variables} = n - r$$

10. Four Fundamental Subspaces (for Matrix A)

$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ is the standard basis of \mathbb{R}^3

Another basis $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 5 \end{bmatrix} \begin{bmatrix} 3 \\ 3 \\ 8 \end{bmatrix}$ is said independent but not

The rows 1 & 2 are dependent & inverse won't exist.

4 Subspaces :

1. Column space $C(A)$

2. null space $N(A)$

3. row space $R(A) = C(A^T)$

→ all combinations of rows of A
↳ all combs of columns of A^T

4. Null space of $A^T = N(A^T)$

(left nullspace of A)

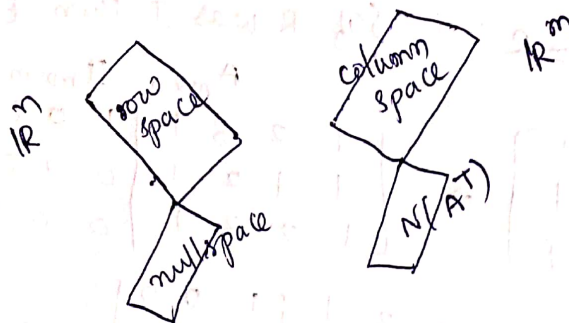
If A is $m \times n$

$$C(A) \rightarrow \mathbb{R}^m$$

$$N(A) \rightarrow \mathbb{R}^n$$

$$R(A) = C(A^T) \rightarrow \mathbb{R}^m$$

$$N(A^T) \rightarrow \mathbb{R}^n$$



basis?
Dimension?

1) $C(A) \Rightarrow$ Basis is # pivot columns
dimension is 'r'

2) $R(A) \Rightarrow$ dimension is 'r'
Basis

3) $N(A) \Rightarrow$ Basis is special solutions
dimension = $n - r$

$n - r = \text{free variables}$

4) $N(A^T) \Rightarrow$ dimension = $m - r$

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = R$$

$$C(A) \neq C(R)$$

Basis for row space is first r rows of R

From $R \rightarrow$ we can get any ^{row} vector of A

$$\text{Ex: } R_1 + R_2 = A_2$$

$$R_1 + 2R_2 = A_3$$

A^T space: $N(A^T)$

$$A^T y = 0$$

$$\begin{bmatrix} \end{bmatrix} \begin{bmatrix} \end{bmatrix} = \begin{bmatrix} \\ 0 \end{bmatrix}$$

$$y^T (A^T)^T = 0^T$$

$$[y^T] [A] = [0]$$

$$\text{ref } \begin{bmatrix} A_{m \times n} & I_{m \times m} \end{bmatrix} \rightarrow \begin{bmatrix} R_{m \times n} & E_{m \times m} \end{bmatrix}$$

Method 2

$$EA = R$$

{ If R was I then $E = A^{-1}$

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix} \rightarrow \begin{array}{c} A_{m \times n} \quad I_{m \times m} \\ \left[\begin{array}{cccc|cccc} 1 & 2 & 3 & 1 & 1 & 0 & 0 \\ 1 & 1 & 2 & 1 & 0 & 1 & 0 \\ 1 & 2 & 3 & 1 & 0 & 0 & 1 \end{array} \right] \end{array}$$

$$R_3 - R_1 \rightarrow \left[\begin{array}{cccc|cccc} 1 & 2 & 3 & 1 & 1 & 0 & 0 \\ 1 & 1 & 2 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{array} \right]$$

$$R_2 - R_1 \rightarrow \left[\begin{array}{cccc|cccc} 1 & 2 & 3 & 1 & 1 & 0 & 0 \\ 0 & -1 & -1 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{array} \right] \xrightarrow{R_1 + 2R_2} \left[\begin{array}{cccc|cccc} 1 & 0 & 1 & 1 & -1 & 2 & 0 \\ 0 & -1 & -1 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{array} \right] \Rightarrow \left[\begin{array}{cccc|cccc} 1 & 0 & 1 & 1 & -1 & 2 & 0 \\ 0 & -1 & -1 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{array} \right]$$

$$(-1)R_2 \Rightarrow \left[\begin{array}{cccc|cccc} 1 & 0 & 1 & 1 & -1 & 2 & 0 \\ 0 & 1 & 1 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{array} \right]$$

$\underbrace{\quad\quad\quad}_R \quad \underbrace{\quad\quad\quad}_E$

$$\begin{bmatrix} 1 & 2 & 0 \\ -1 & -1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$E \quad A$

$$\rightarrow N(A^T) \quad \therefore -1[1 \ 2 \ 3 \ 1] + 0[1 \ 1 \ 2 \ 1] + -1[1 \ 2 \ 3 \ 1] = 0$$