

INFO1105/1905

Data Structures

Week 10: Graphs (rest)

see textbook section 14.4, 14.5, 14.6

Professor Alan Fekete

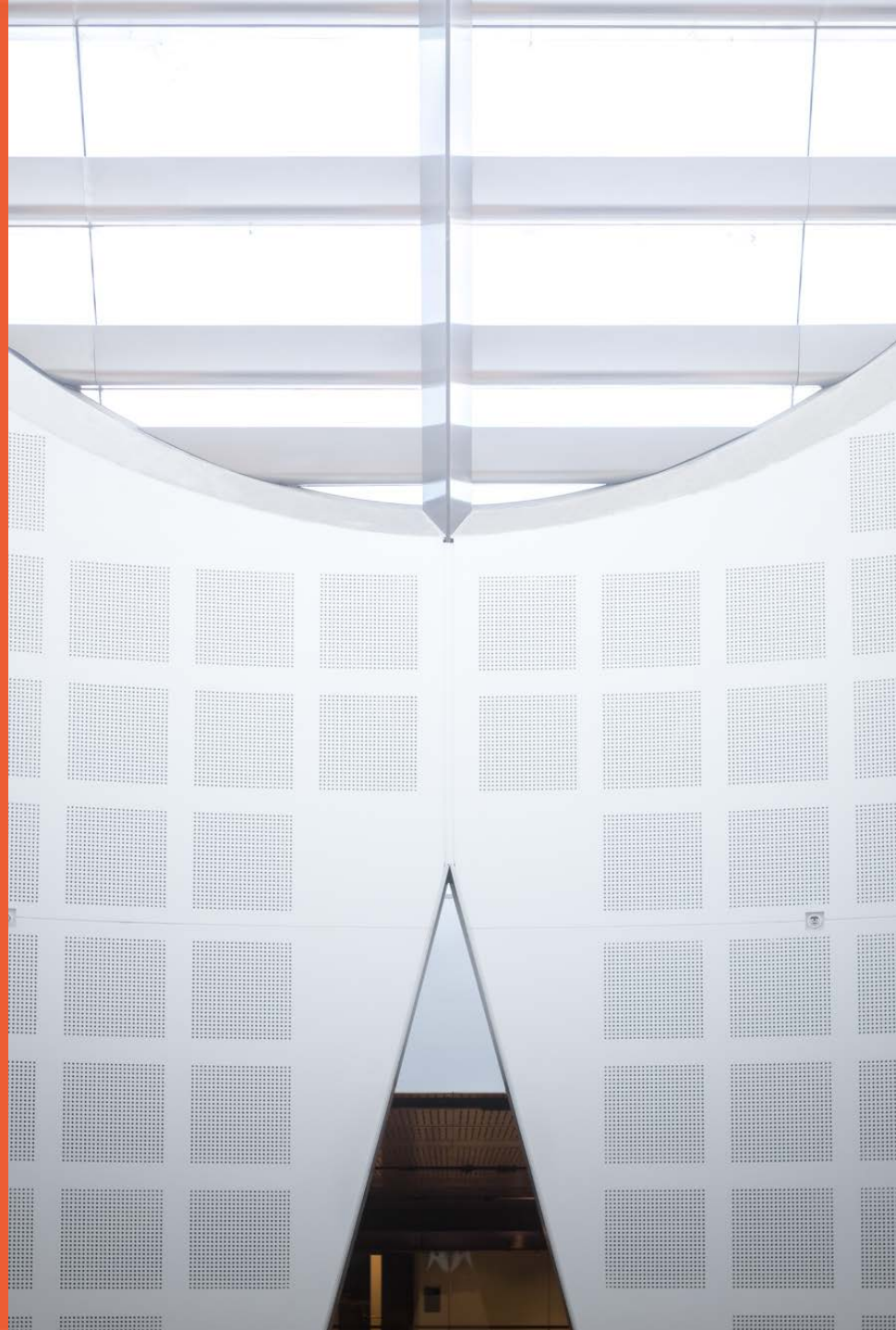
Prof Seokhee Hong

School of Information Technologies

using material from the textbook
and A/Prof Kalina Yacef, Dr Taso Viglas



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- These slides contain material from the textbook (Goodrich, Tamassia & Goldwasser)
 - Data structures and algorithms in Java (5th & 6th edition)
- With modifications and additions from the University of Sydney
- The slides are a guide or overview of some big ideas
 - Students are responsible for knowing what is in the referenced sections of the textbook, not just what is in the slides

Reminder! Quiz 4

- Quiz 4 will take place during lab in week 10
- Done online, over a 20 minutes duration,
 - during the last 30 minutes of the lab period, or as indicated by your tutor
- A few multiple choice questions,
 - covering material from weeks 7, 8, also part of week 9
 - hash tables and collision handling (including chaining and open addressing)
 - recurrence equations
 - graph definition
 - graph representations
 - However, graph traversal (BFS, DFS) will be in quiz 5!

Assignment 2

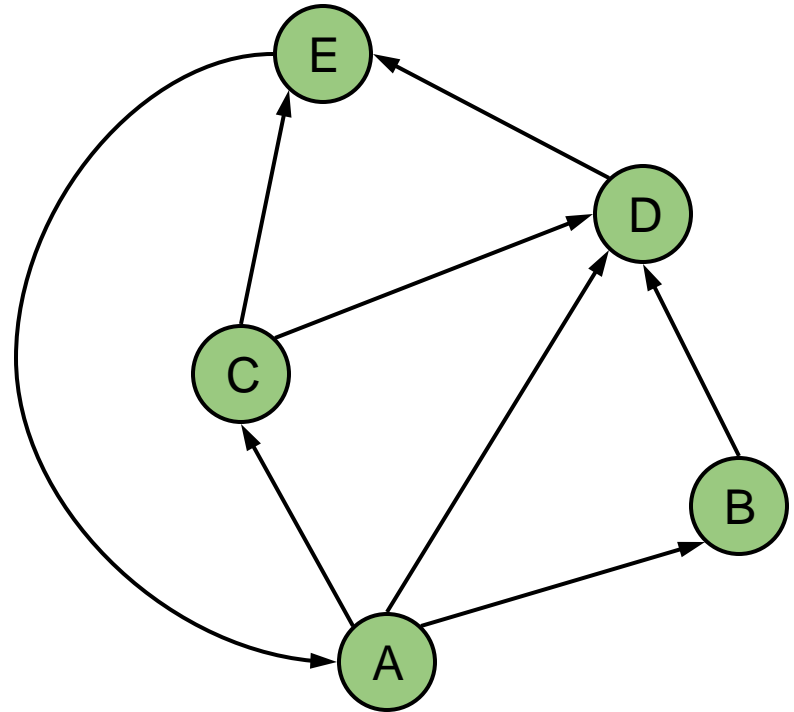
- **Due 5pm Friday October 27 (week 12)**
- Assignment specification will be released **this afternoon**
- Worth **12%** of the grade of the unit
- Submit
 - Code on Ed
 - Code on eLearning
 - Report on eLearning (Turnitin)
- Slight differences in the marking scheme, and the requirements for the report, for postgraduates (info9105) vs undergraduates (info1105/1905)
- Submit early and often!
- Warning: we use similarity detection on code and on report. Make sure you acknowledge sources properly. Make sure that you do not provide your code or report to others.

Outline

- Directed graphs
 - Directed DFS
 - 1. **Strong connectivity**
 - 2. **Transitive closure** (Floyd-Warshall algorithm)
 - 3. **Topological ordering**
- Weighted graphs
 - 1. Shortest paths (Dijkstra's algorithm)

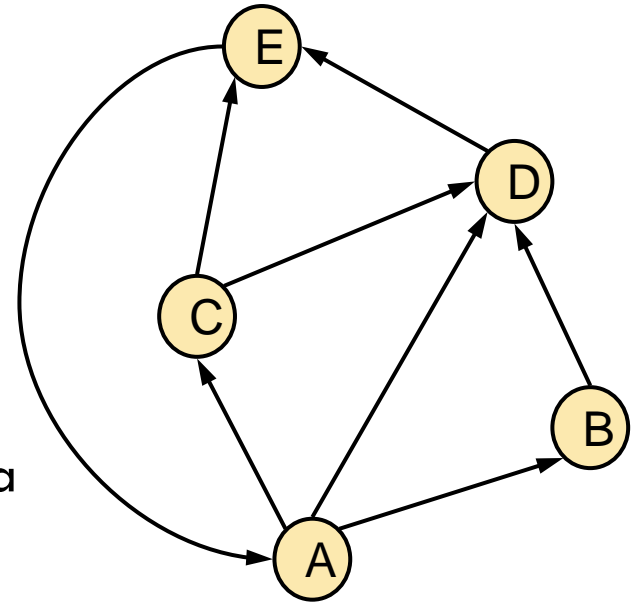
Digraphs

- A **digraph** is a graph whose edges are all directed
 - Short for “directed graph”
- Applications
 - one-way streets
 - flights
 - task scheduling



Digraph Properties

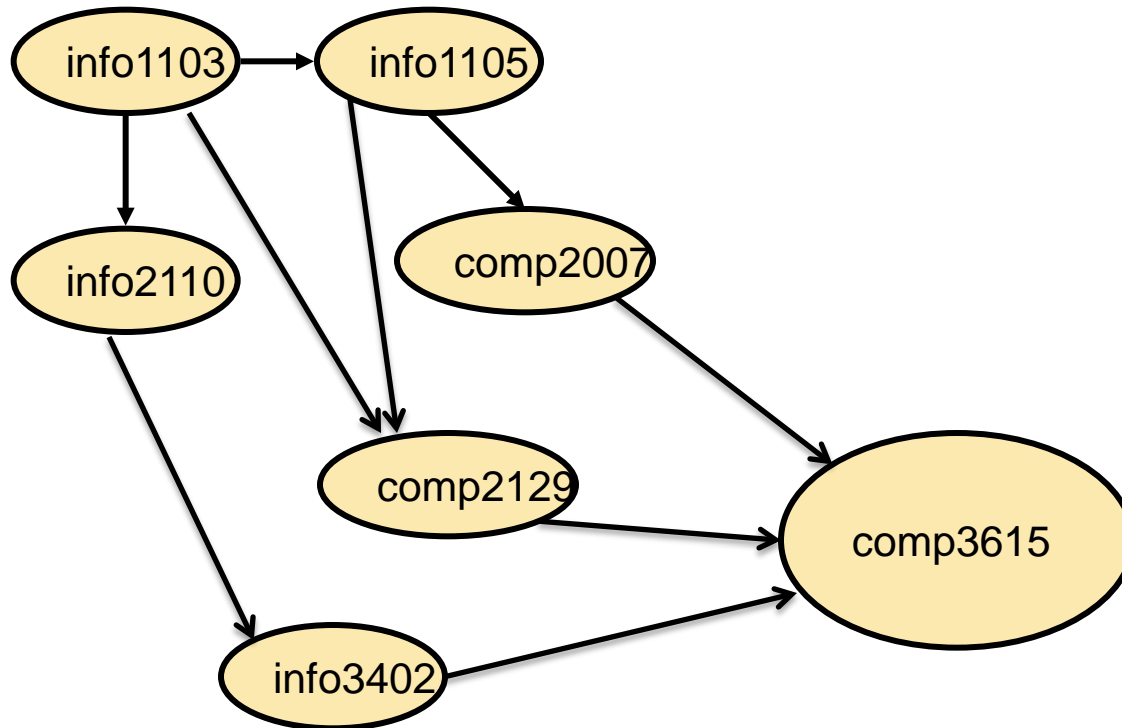
- A graph $G=(V,E)$ such that
 - Each edge goes in **one direction**:
 - Edge (a,b) goes from a to b , but not b to a
- If G is simple, $m \leq n \cdot (n - 1)$
- If we keep **in-edges** and **out-edges** in separate adjacency lists, we can perform listing of incoming edges and outgoing edges in time proportional to their size



Recall m = number of edges, n = number of nodes

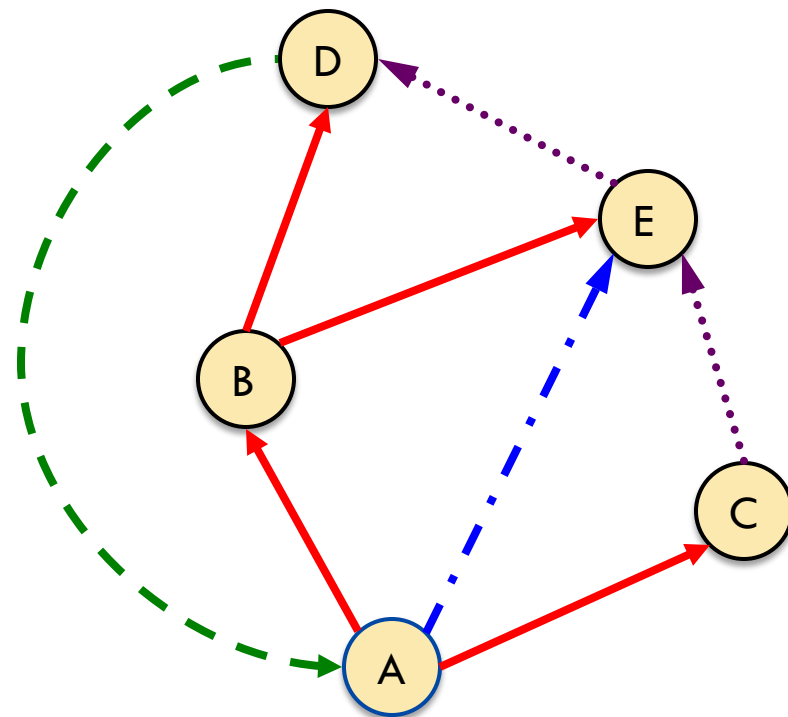
Digraph Application

- **Scheduling**: edge (a,b) means task a must be completed before b can be started



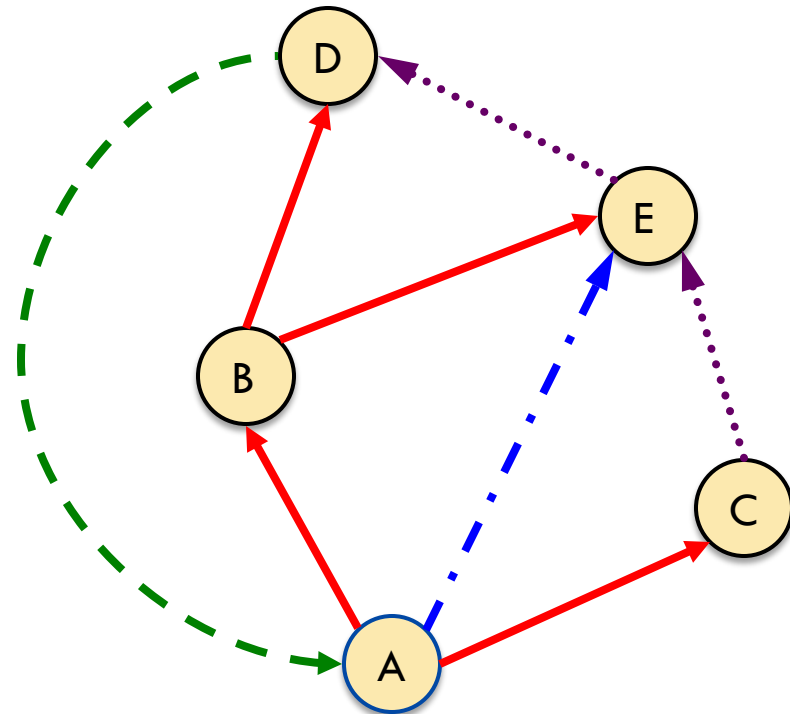
Directed DFS

- We can specialize the traversal algorithms (DFS and BFS) to digraphs by traversing edges only along their direction
- A directed DFS starting at a vertex s determines the vertices **reachable** from s



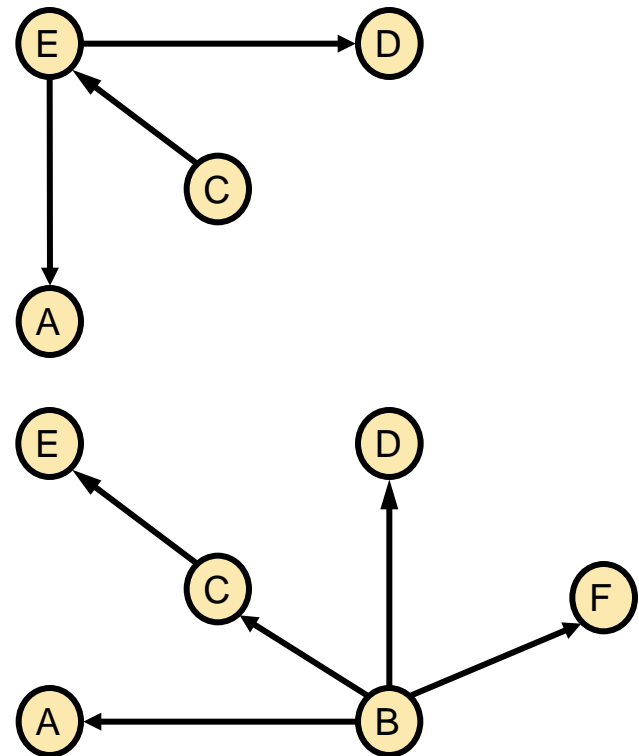
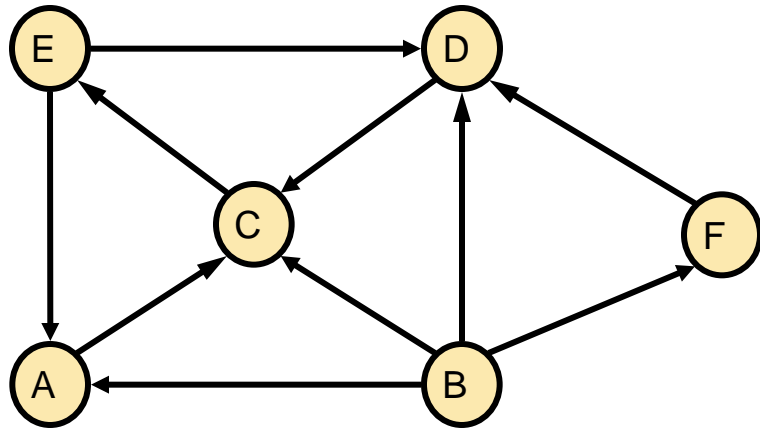
Directed DFS

- In the directed DFS algorithm, we have four types of edges
 1. discovery edges: these are the DFS tree edges
 2. back edges: connect a vertex to an ancestor in the DFS tree
 3. forward edges: connect a vertex to a descendant in the DFS tree
 4. cross edges: connect to vertex that is not an ancestor/descendant
- A directed DFS starting at a vertex s determines the vertices **reachable** from s



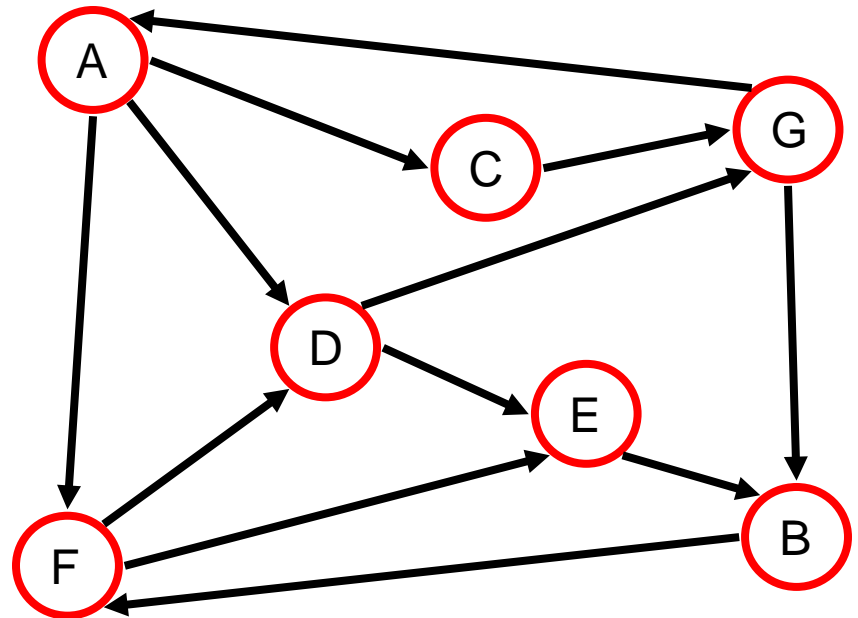
Reachability

- A reaches B if there is a directed path from A to B
- **DFS tree** rooted at v: vertices reachable from v via directed paths



1. Strong Connectivity

- **Strongly connected graph**: each vertex has a directed path to every other vertex



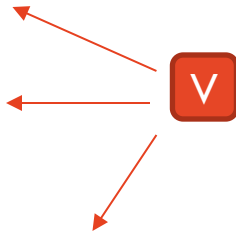
Simplistic Strong connectivity algorithm using DFS

- Simplistic approach (naïve) : Run DFS from each vertex u , and check that each vertex is reached
- Runtime?
 - n DFS runs, so $O(n \cdot (n+m))$
- There is a faster algorithm

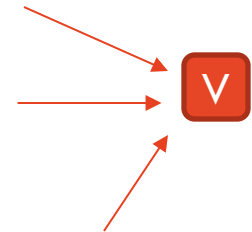
Strong Connectivity Algorithm

A better way:

DFS from v:
Testing if v can reach
everyone



Reverse edge DFS from v:
Testing if v can be reached
from everyone



If v can reach everyone and everyone can reach v then...

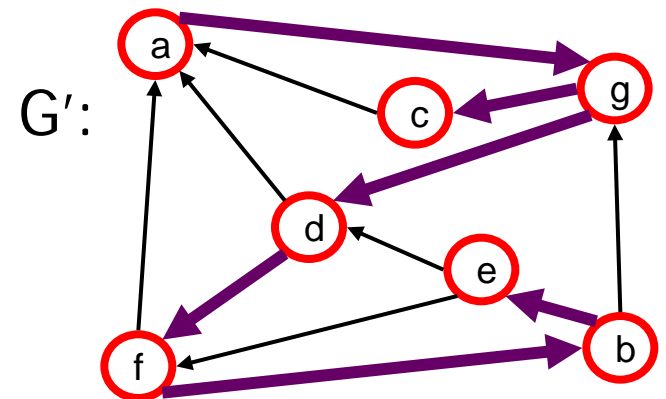
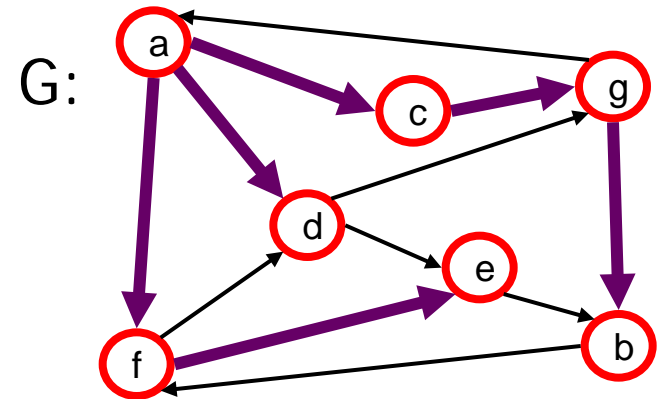
...every node x can reach any other node y.

Just go through v:
x has a path to v (since everyone can reach v)
and
v has a path to y (since v can reach everyone)

Strong Connectivity Algorithm

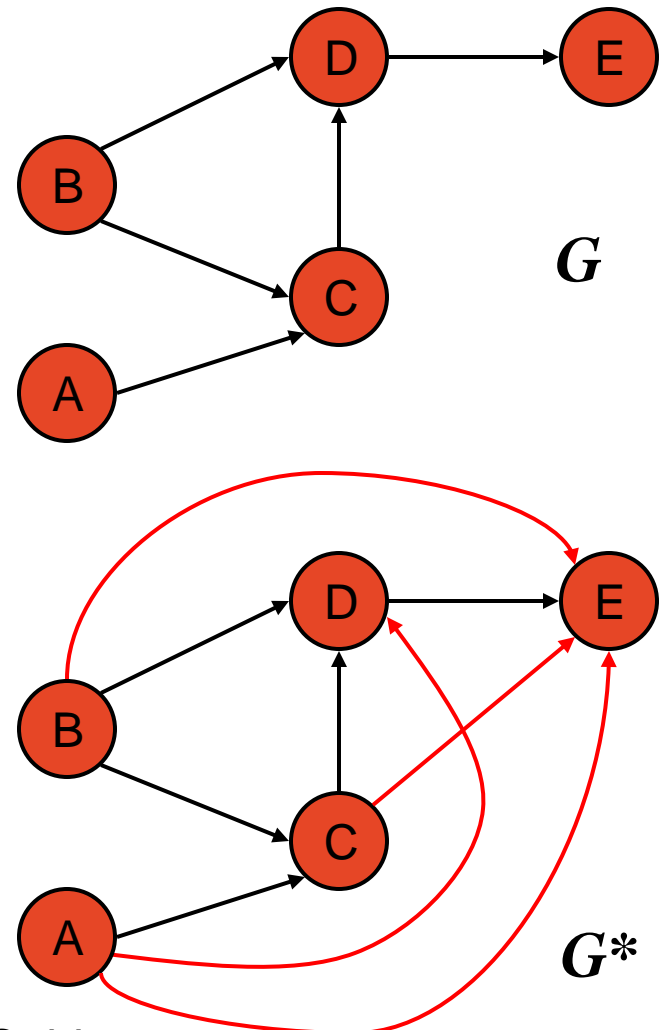
Improved algorithm (with only 2 DFS)

- Pick a vertex v in G
- Perform a DFS from v in G
 - If there's a w not visited, return “no”
- Let G' be G with edges **reversed**
- Perform a DFS from v in G'
 - If there's a w not visited, return “no”
 - Else, return “yes”
- Running time: $O(n+m)$



2. Transitive Closure

- For pre-computing all reachable vertices from each vertex
- Given a digraph G , the transitive closure of G is the digraph G^* such that
 - G^* has the same vertices as G
 - if G has a directed path from u to v ($u \neq v$), G^* has a directed edge from u to v
- The transitive closure provides reachability information about a digraph



Computing the Transitive Closure

- We can perform DFS starting at each vertex
 - $O(n(n+m))$
 - Better for **sparse graph**
 - Adjacent list/map

If there's a way to get from **A** to **B** and from **B** to **C**, then there's a way to get from **A** to **C**.



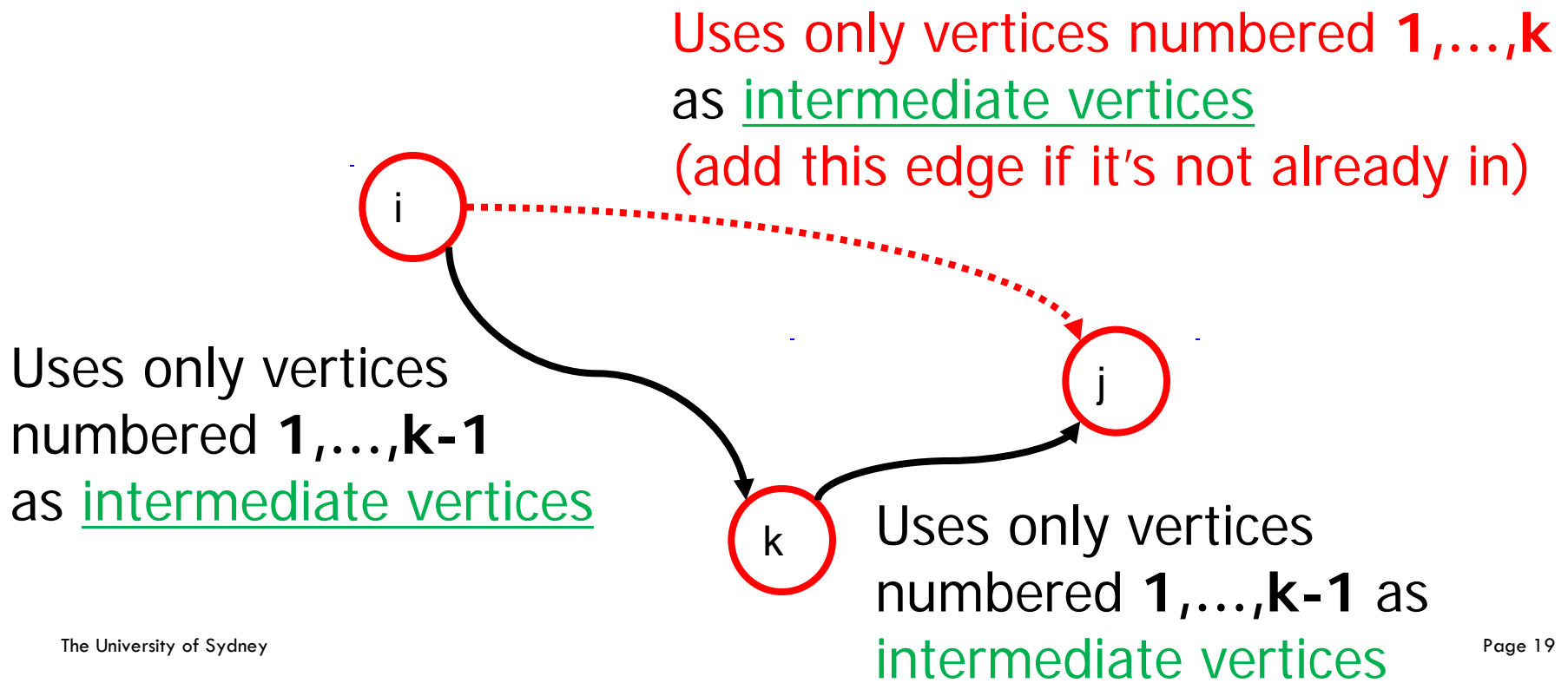
Alternatively ...

Use **dynamic programming**:
The Floyd-Warshall Algorithm

Floyd-Warshall Transitive Closure

1. Number the vertices $1, 2, \dots, n$ (arbitrarily).
2. Construct transitive closure digraph incrementally.

At round $k+1$, consider paths that use only vertices numbered $1, 2, \dots, k$, as intermediate vertices:



Floyd-Warshall's Algorithm

- Number vertices v_1, \dots, v_n
- Compute digraphs G_0, \dots, G_n
 - $G_0 = G$
 - G_k has **directed edge** (v_i, v_j) iff G has a directed path from v_i to v_j with intermediate vertices in $\{v_1, \dots, v_k\}$
- We have $G_n = G^*$
- In phase k , digraph G_k is computed from G_{k-1}
- Running time?
 - $O(n^3)$, assuming **areAdjacent** (**getEdge**) is $O(1)$: (e.g., **adjacency matrix**)
 - Easier to implement/fast in practice
 - Better for dense graph

Algorithm *FloydWarshall*(G)

Input digraph G

Output transitive closure G^* of G

$i \leftarrow 1$

for all $v \in G.vertices()$ {number the vertices}

denote v as v_i

$i \leftarrow i + 1$

$G_0 \leftarrow G$

for $k \leftarrow 1$ to n **do**

$G_k \leftarrow G_{k-1}$

for $i \leftarrow 1$ to n ($i \neq k$) **do**

for $j \leftarrow 1$ to n ($j \neq i, k$) **do**

if $G_{k-1}.areAdjacent(v_i, v_k)$ **and**

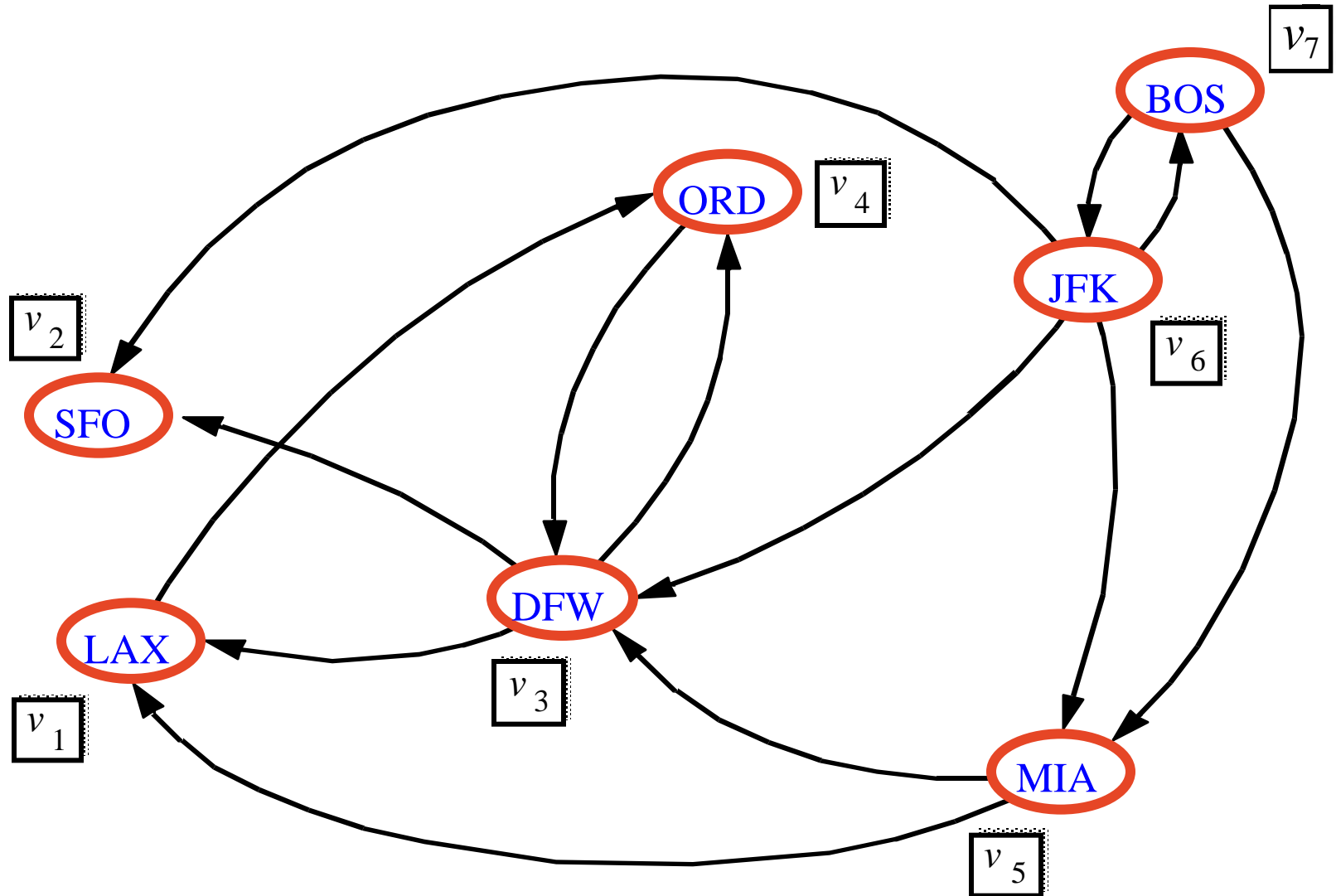
$G_{k-1}.areAdjacent(v_k, v_j)$

if not $G_k.areAdjacent(v_i, v_j)$

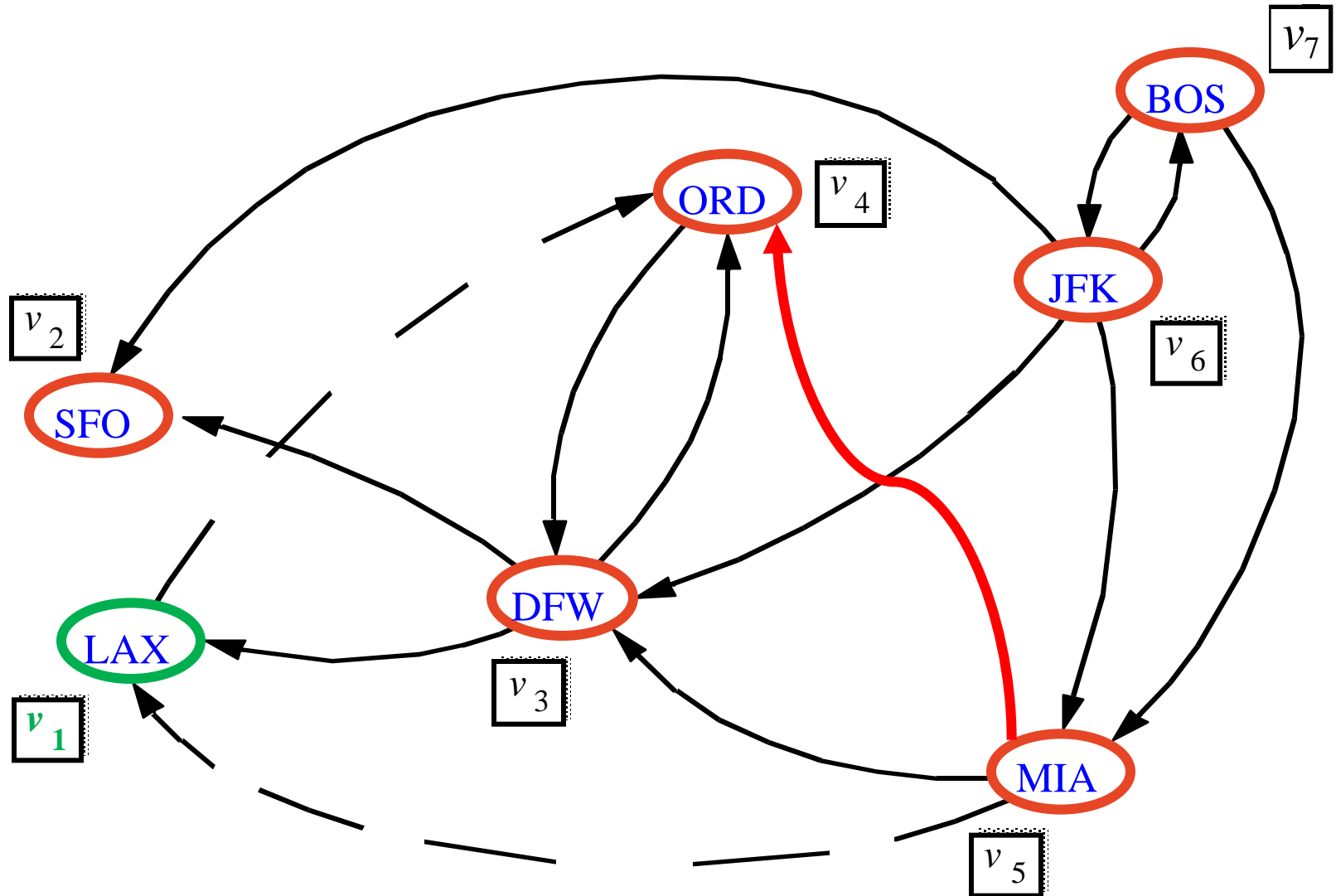
$G_k.insertDirectedEdge(v_i, v_j, k)$

return G_n

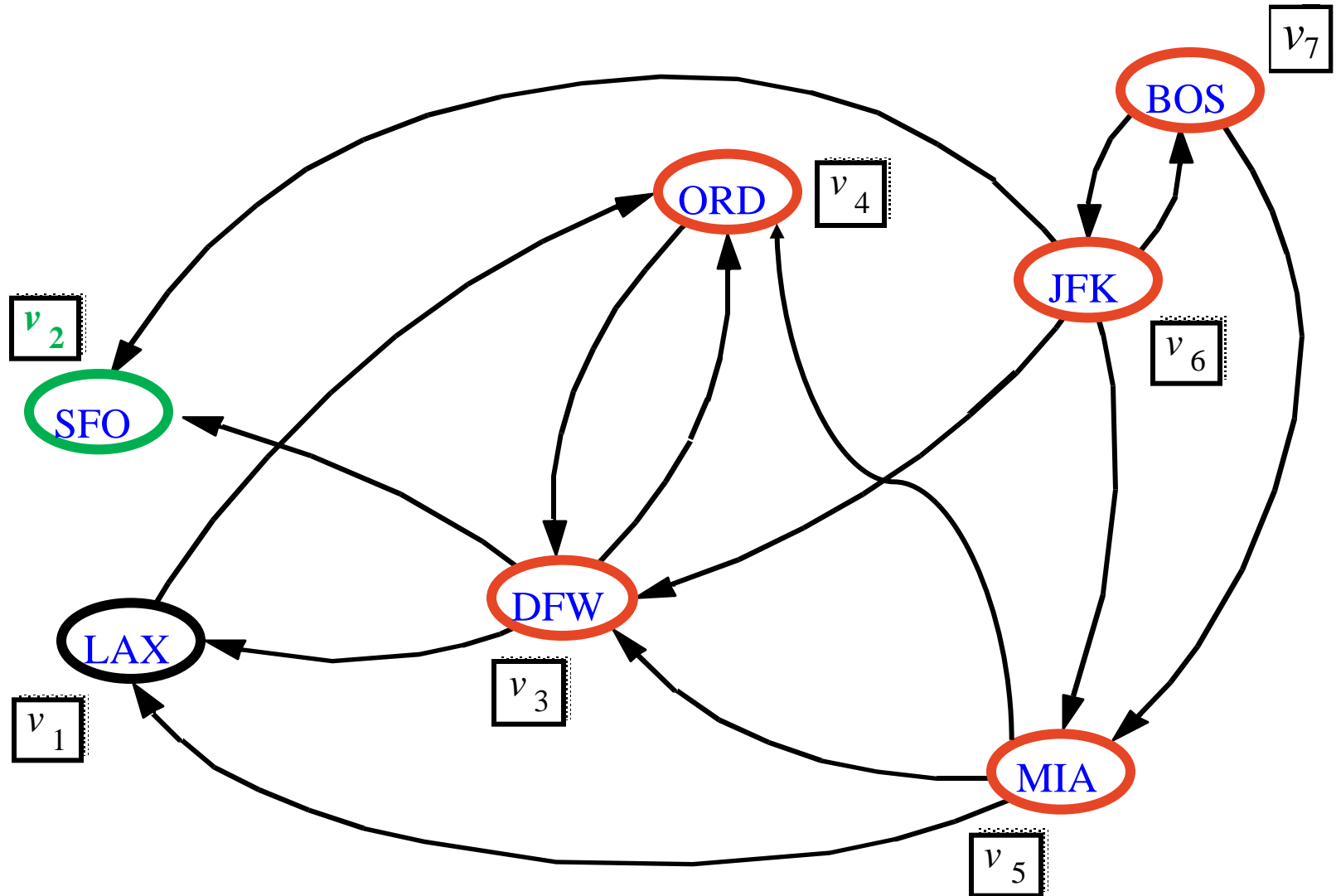
Floyd-Warshall Example: G0



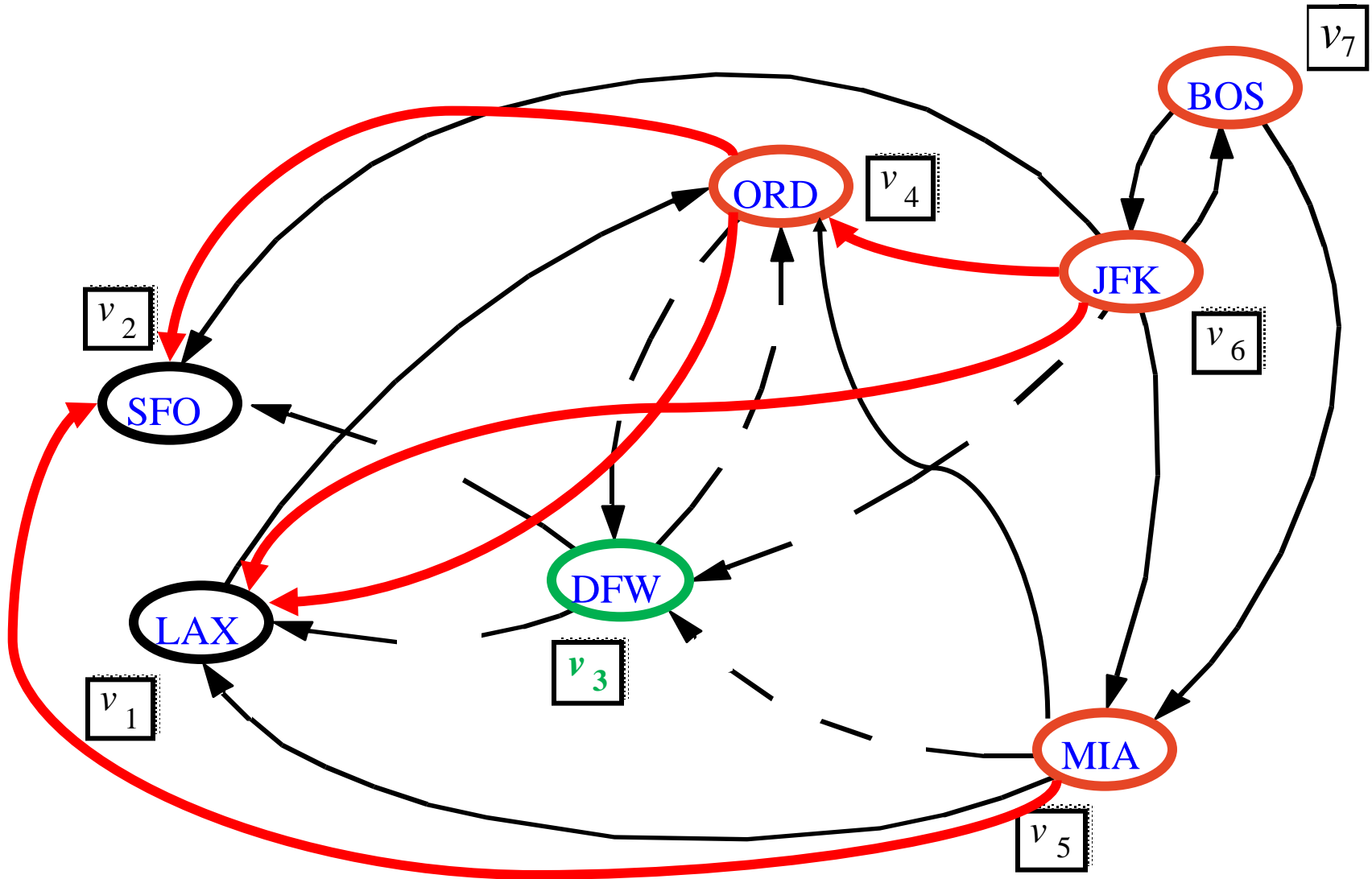
Floyd-Warshall, Iteration 1: G1



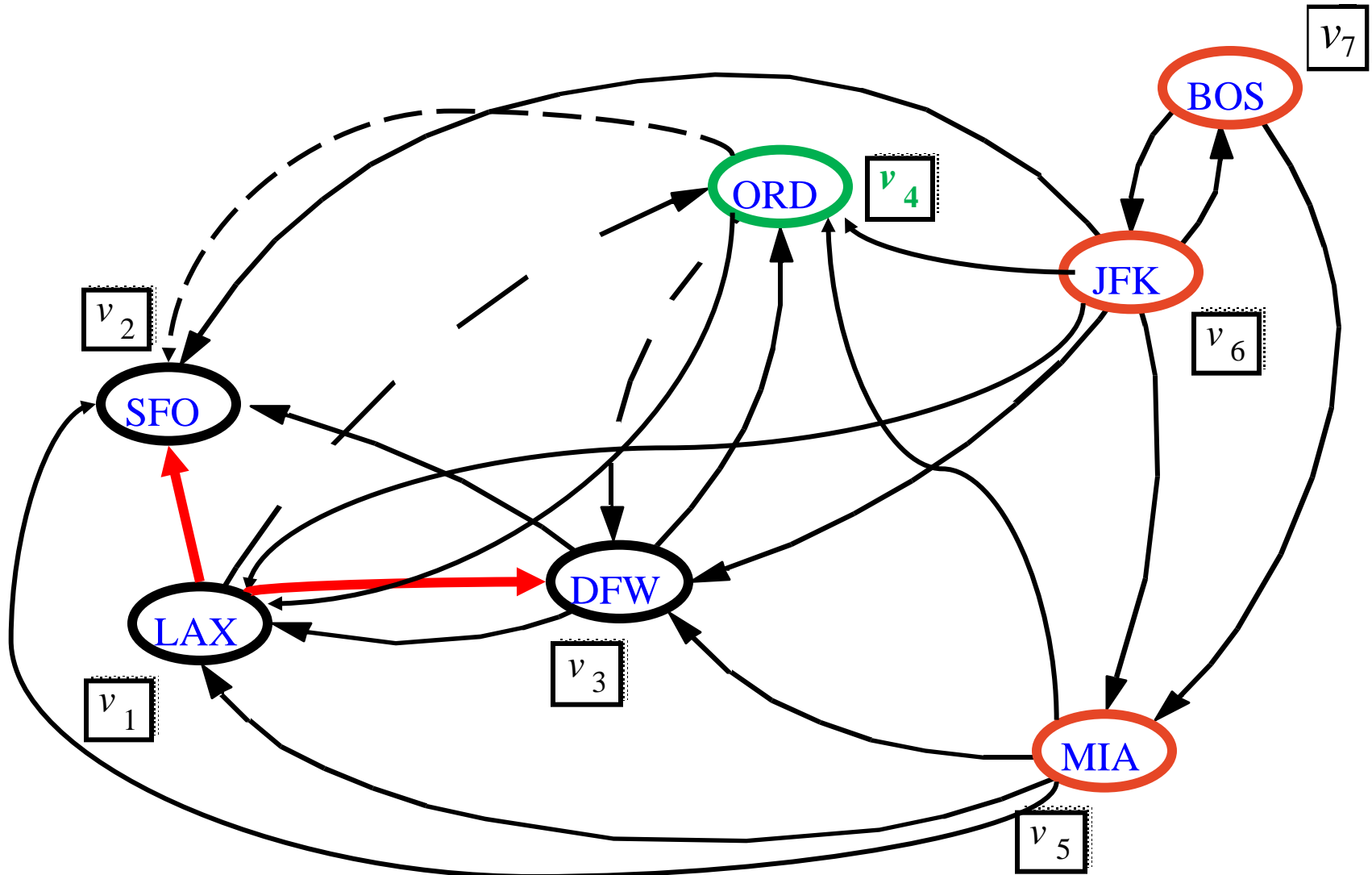
Floyd-Warshall, Iteration 2: G2



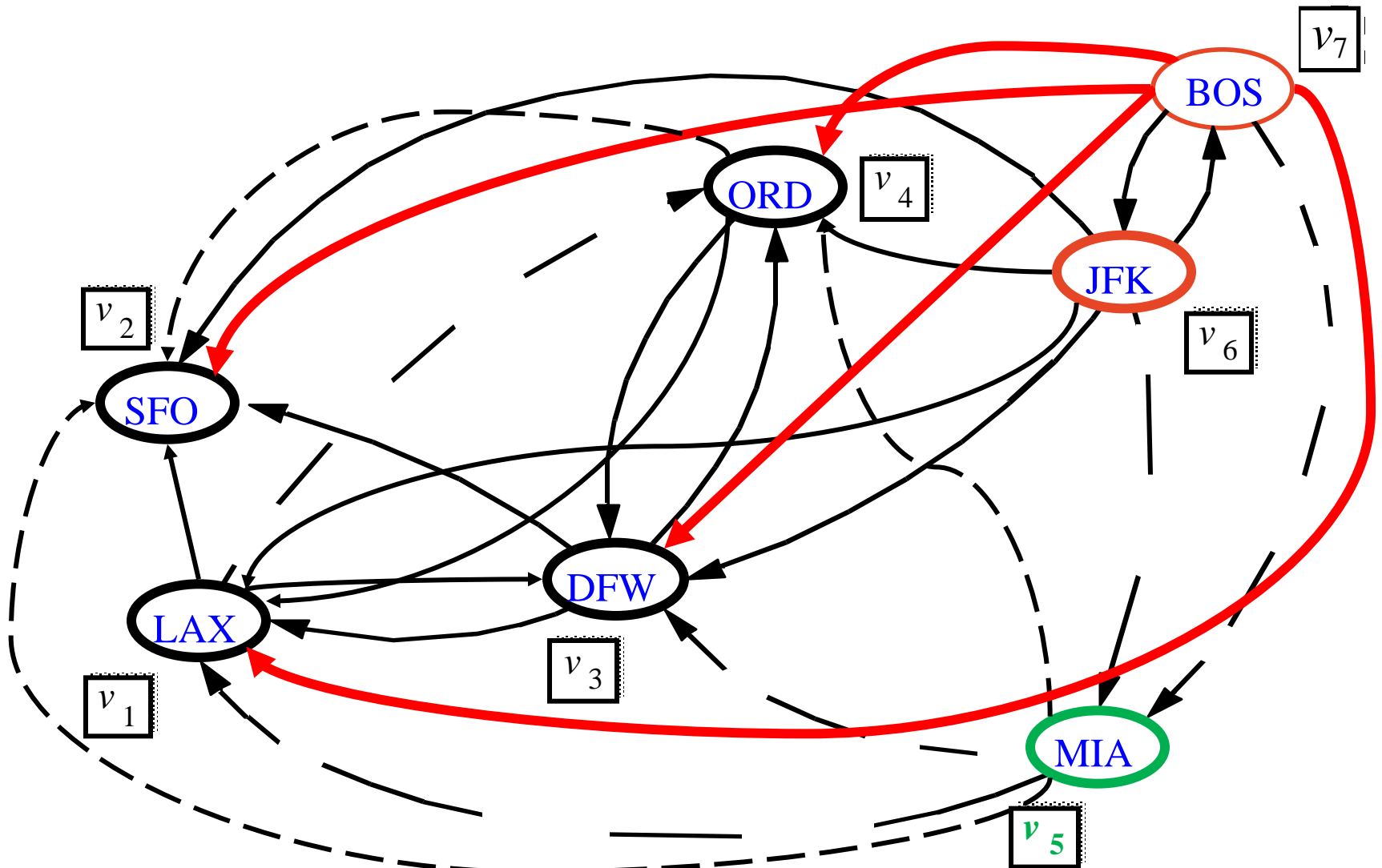
Floyd-Warshall, Iteration 3: G3



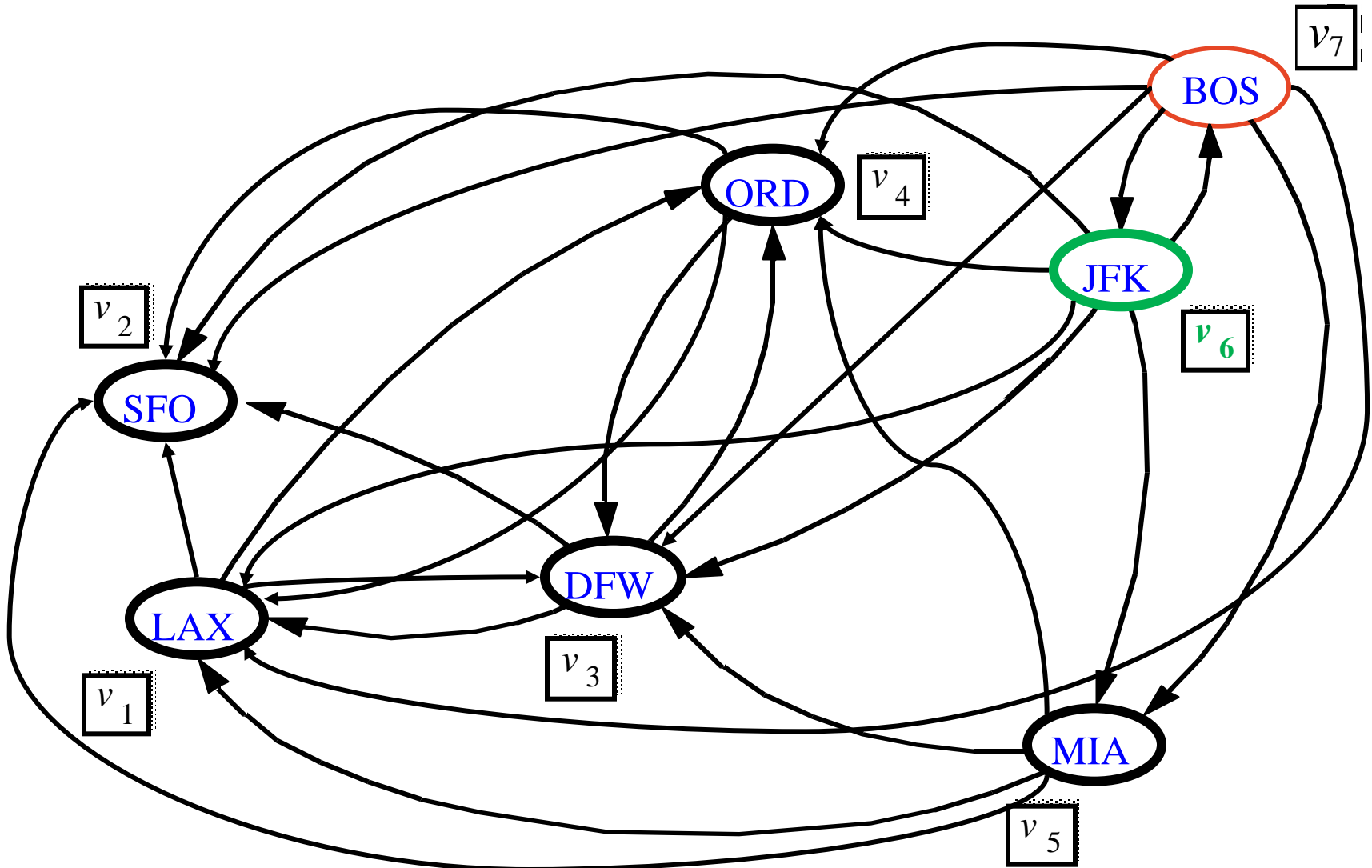
Floyd-Warshall, Iteration 4: G4



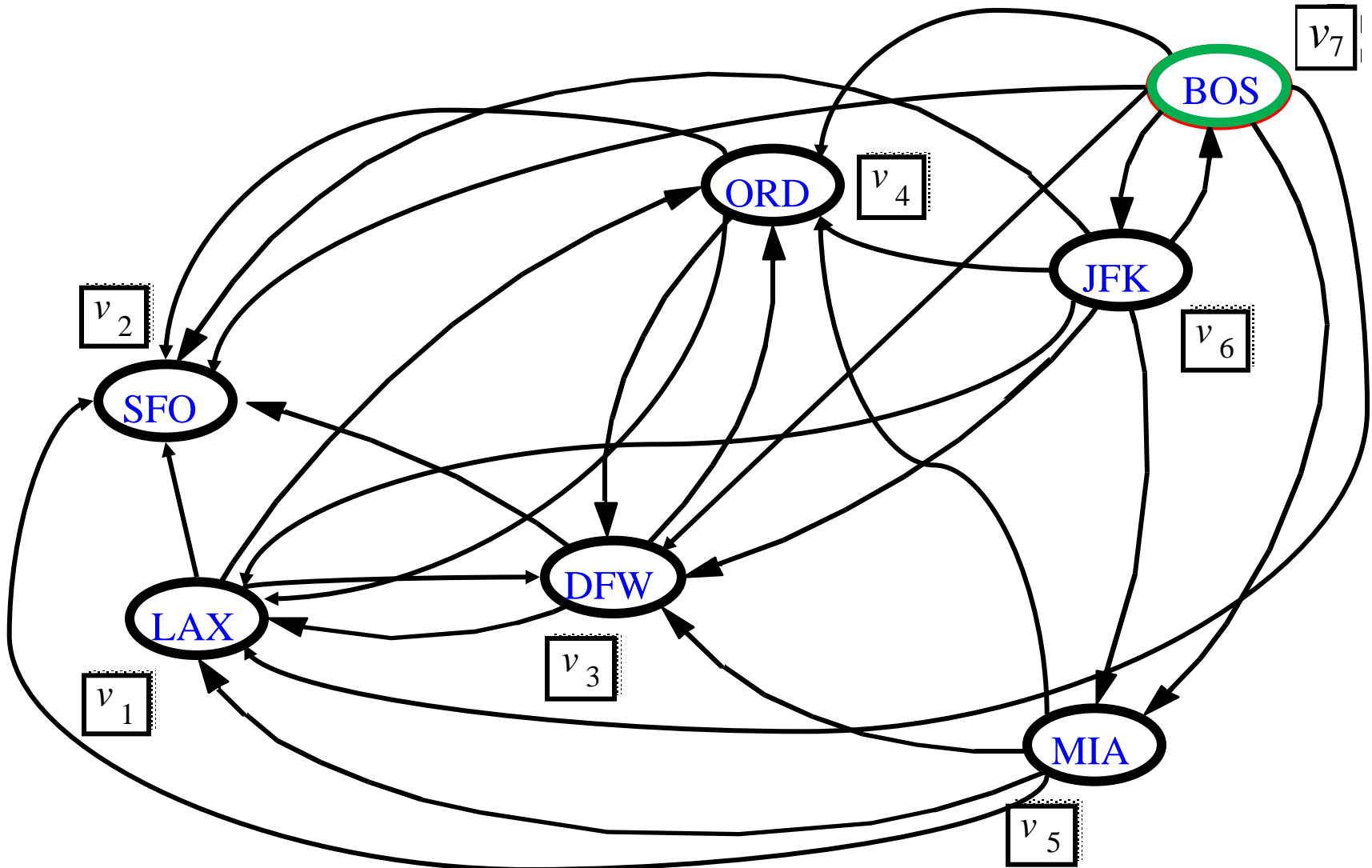
Floyd-Warshall, Iteration 5: G5



Floyd-Warshall, Iteration 6: G6 (G5=G6)



Floyd-Warshall, Conclusion: G7 (G5=G6=G7)

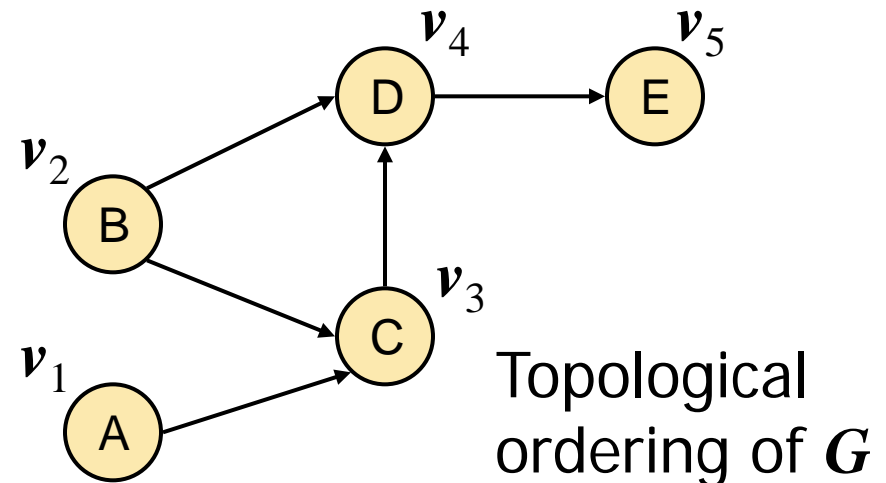
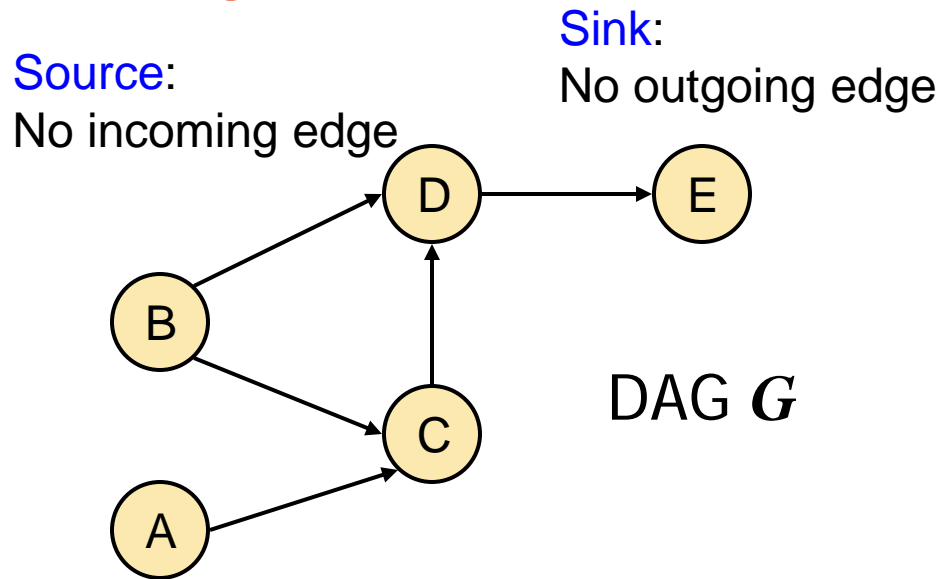


Java Implementation

```
1  /** Converts graph g into its transitive closure. */
2  public static <V,E> void transitiveClosure(Graph<V,E> g) {
3      for (Vertex<V> k : g.vertices())
4          for (Vertex<V> i : g.vertices())
5              // verify that edge (i,k) exists in the partial closure
6              if (i != k && g.getEdge(i,k) != null)
7                  for (Vertex<V> j : g.vertices())
8                      // verify that edge (k,j) exists in the partial closure
9                      if (i != j && j != k && g.getEdge(k,j) != null)
10                         // if (i,j) not yet included, add it to the closure
11                         if (g.getEdge(i,j) == null)
12                             g.insertEdge(i, j, null);
13 }
```

3. DAGs and Topological Ordering

- A **directed acyclic graph (DAG)** is a digraph that has no directed cycles
- A topological ordering of a digraph is a numbering v_1, \dots, v_n of the vertices such that for every edge (v_i, v_j) , we have $i < j$
- Example: in a task scheduling digraph, a topological ordering a task sequence that satisfies the precedence constraints
- **Theorem**
A digraph has a topological ordering if and only if it is a **DAG**

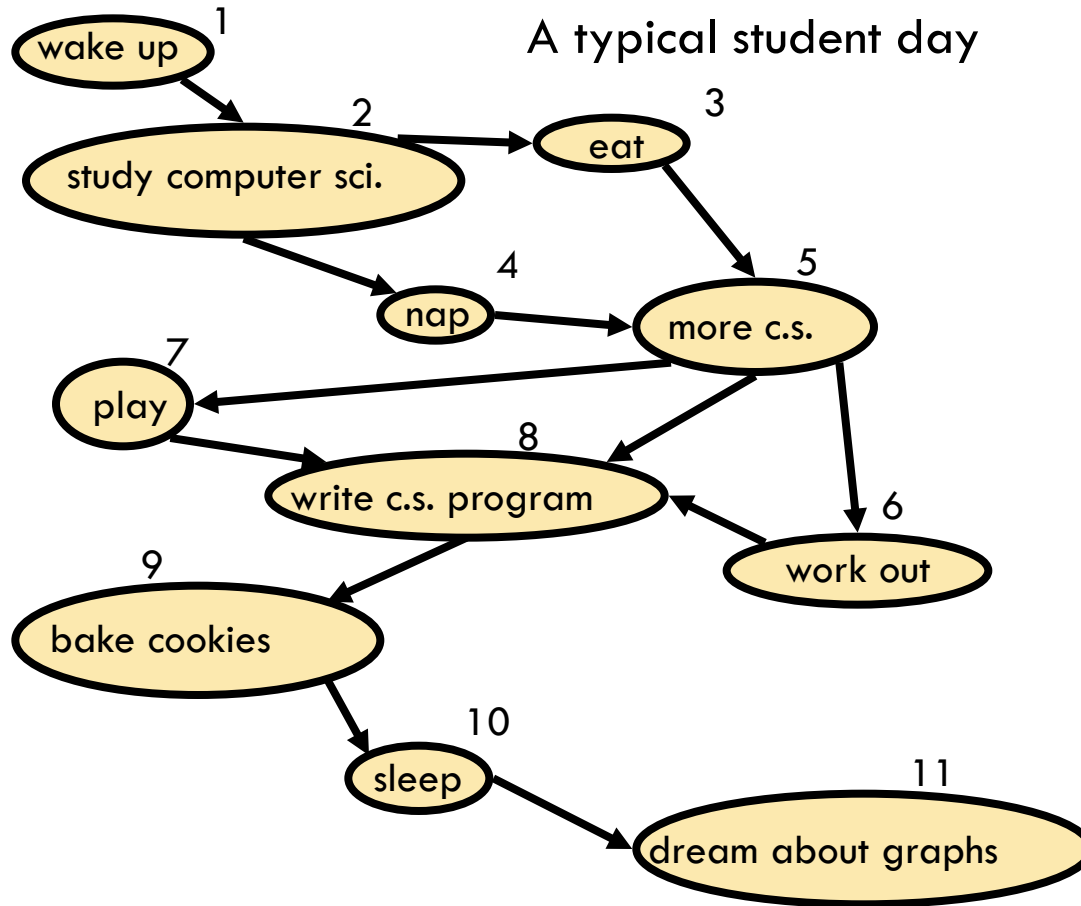


Topological Sorting

- Number vertices, so that (u,v) in E implies $u < v$

Source:

In-degree=0



Sink:

Out-degree=0

Topological sorting

Algorithm TopologicalSort(\vec{G}):

Input: A digraph \vec{G} with n vertices.

Output: A topological ordering v_1, \dots, v_n of \vec{G} .

$S \leftarrow$ an initially empty stack.

for all u in $\vec{G}.\text{vertices}()$ **do**

Let $\text{incounter}(u)$ be the in-degree of u .

if $\text{incounter}(u) = 0$ **then**

$S.\text{push}(u)$

$i \leftarrow 1$

while $!S.\text{isEmpty}()$ **do**

$u \leftarrow S.\text{pop}()$

Let u be vertex number i in the topological ordering.

$i \leftarrow i + 1$

for all outgoing edge (u, w) of u **do**

$\text{incounter}(w) \leftarrow \text{incounter}(w) - 1$

if $\text{incounter}(w) = 0$ **then**

$S.\text{push}(w)$

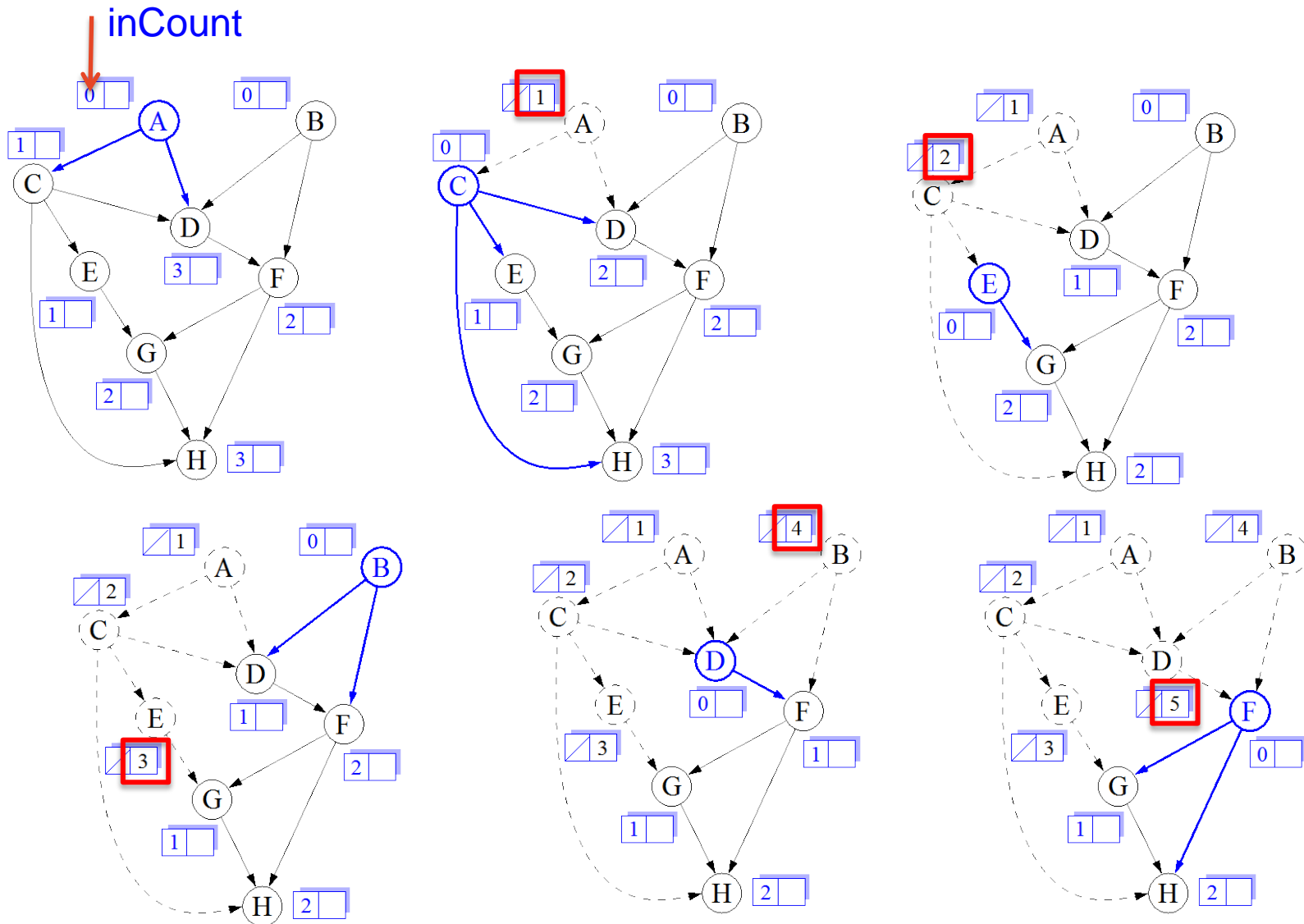
Topological sorting analysis

- Uses an auxiliary **stack** and a **map**
 - this could take $O(n)$ extra space
- Algorithm considers each vertex, and each adjacent outgoing edge (once)
 - Running time: proportional to the number of outgoing edges of visited vertices
 - $O(n+m)$: hash-based map has $O(1)$ expected time access

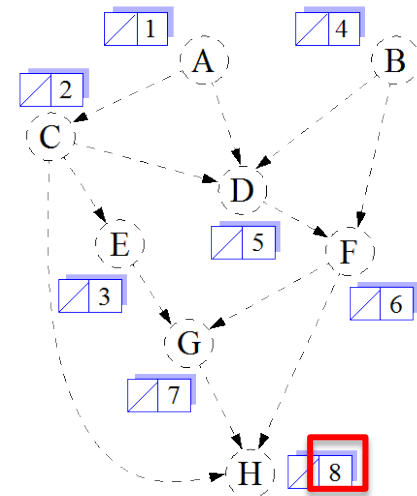
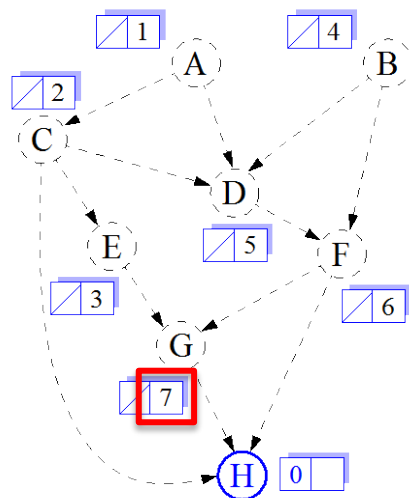
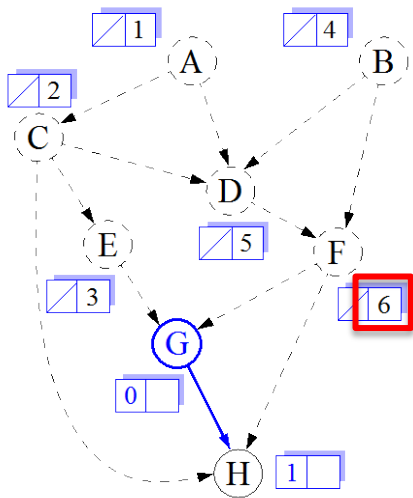
Java Implementation

```
1  /** Returns a list of vertices of directed acyclic graph g in topological order. */
2  public static <V,E> PositionalList<Vertex<V>> topologicalSort(Graph<V,E> g) {
3      // list of vertices placed in topological order
4      PositionalList<Vertex<V>> topo = new LinkedPositionalList<>();
5      // container of vertices that have no remaining constraints
6      Stack<Vertex<V>> ready = new LinkedStack<>();
7      // map keeping track of remaining in-degree for each vertex
8      Map<Vertex<V>, Integer> inCount = new ProbeHashMap<>();
9      for (Vertex<V> u : g.vertices()) {
10         inCount.put(u, g.inDegree(u));           // initialize with actual in-degree
11         if (inCount.get(u) == 0)                 // if u has no incoming edges,
12             ready.push(u);                       // it is free of constraints
13     }
14     while (!ready.isEmpty()) {
15         Vertex<V> u = ready.pop();
16         topo.addLast(u);
17         for (Edge<E> e : g.outgoingEdges(u)) { // consider all outgoing neighbors of u
18             Vertex<V> v = g.opposite(u, e);
19             inCount.put(v, inCount.get(v) - 1); // v has one less constraint without u
20             if (inCount.get(v) == 0)
21                 ready.push(v);
22         }
23     }
24     return topo;
25 }
```

Topological sorting



Topological sorting (cont)

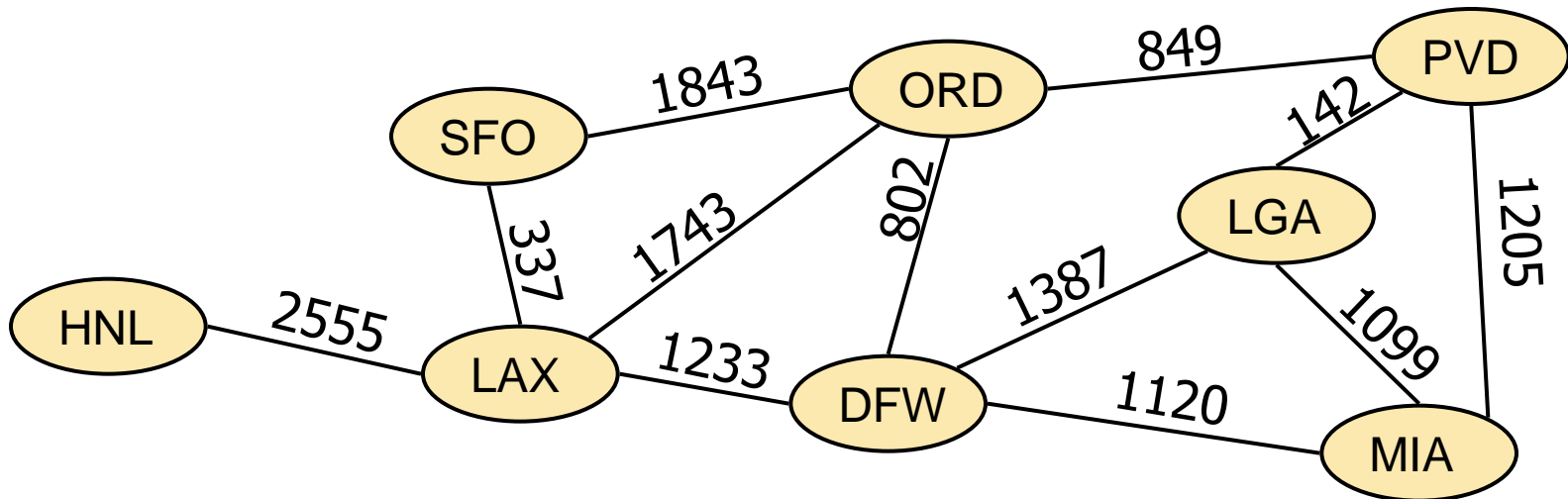


Outline

- Directed graphs
 - Directed DFS
 1. Strong connectivity
 2. Transitive closure (Floyd-Warshall algorithm)
 3. Topological ordering
- Weighted graphs
 - **Shortest paths** (Dijkstra's algorithm)

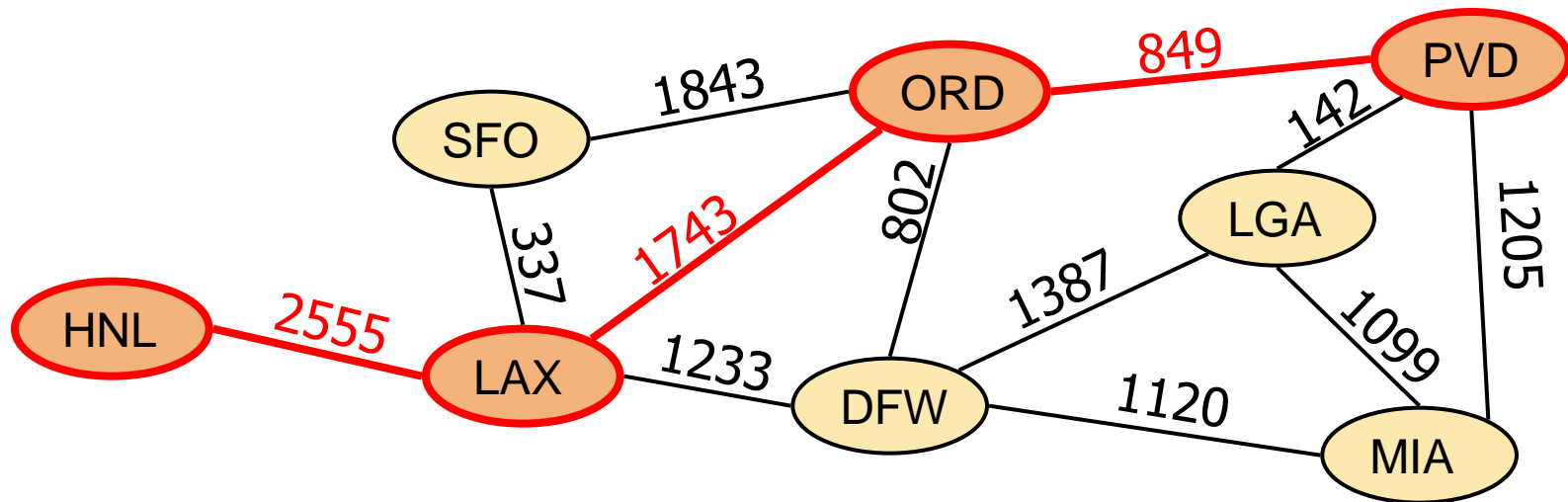
Weighted Graphs

- In a weighted graph, each edge has an associated numerical value, called the weight of the edge
- Edge weights may represent, distances, costs, etc.
- Positive or negative
- Example:
 - In a flight route graph, the weight of an edge represents the distance in miles between the endpoint airports



Shortest Paths

- Given a weighted graph and two vertices u and v , we want to find a path of minimum total weight between u and v .
 - Length of a path is the sum of the weights of its edges.
- Example:
 - Shortest path between Providence and Honolulu
- Applications
 - Internet packet routing
 - Flight reservations
 - Driving directions



Shortest Path Properties

Property 1:

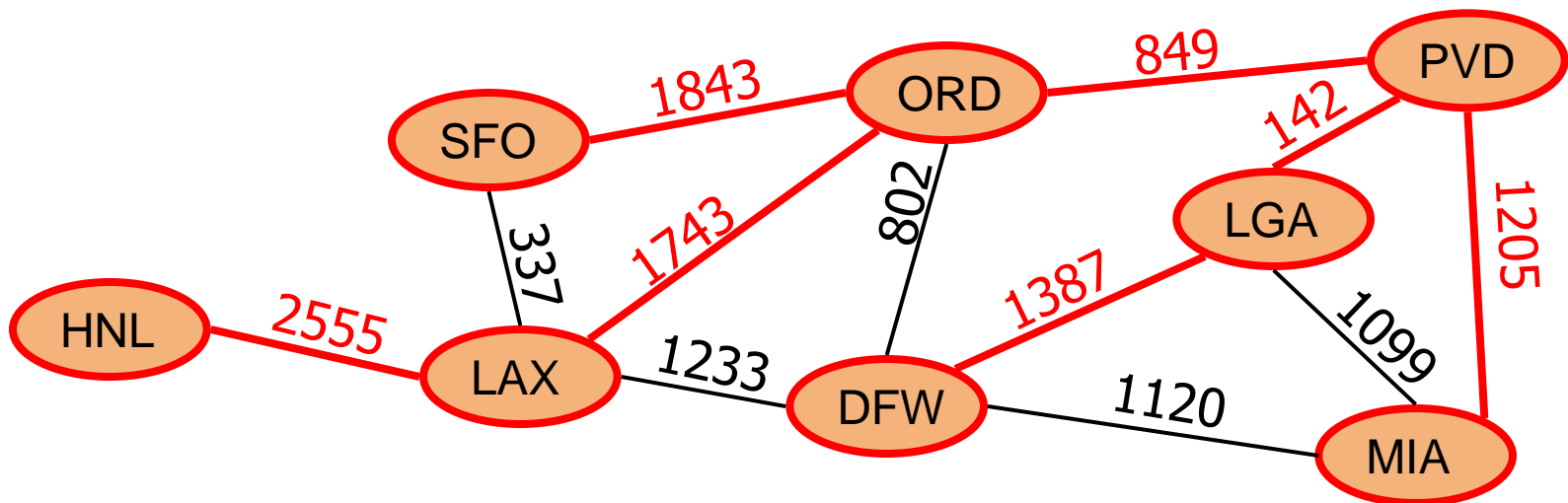
A **subpath** of a shortest path is itself a **shortest path**

Property 2:

There is a **tree of shortest paths** from a start vertex to all the other vertices

Example:

Tree of shortest paths from Providence (PVD)

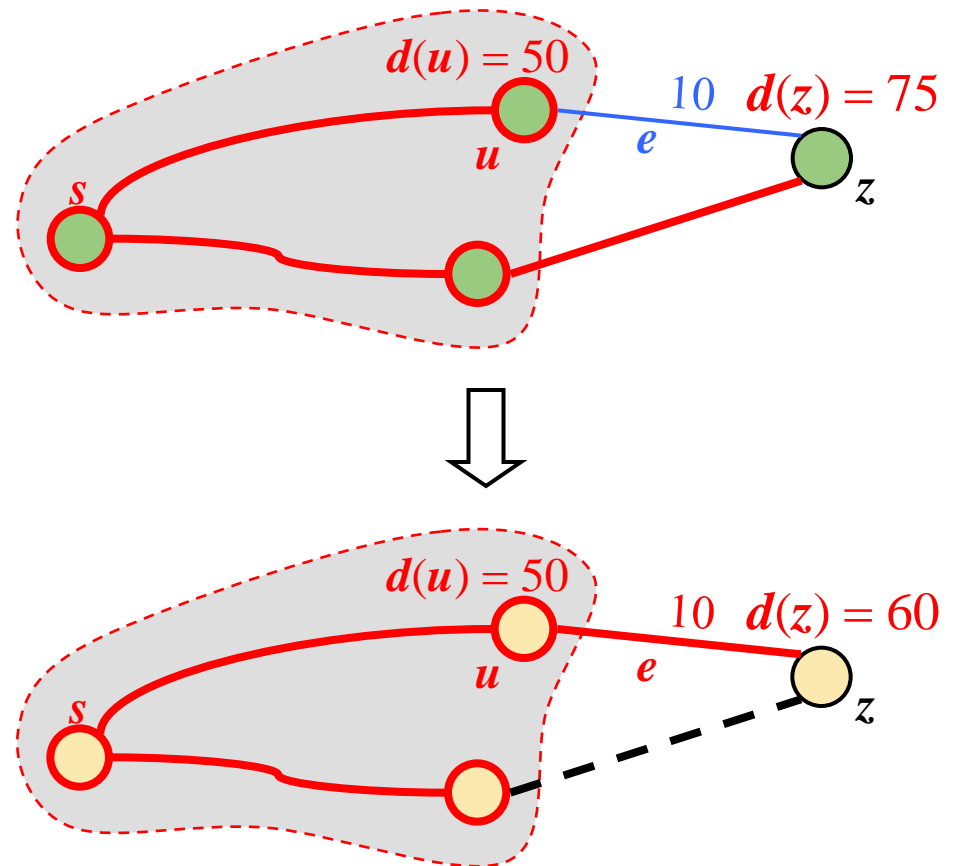


Dijkstra's Algorithm

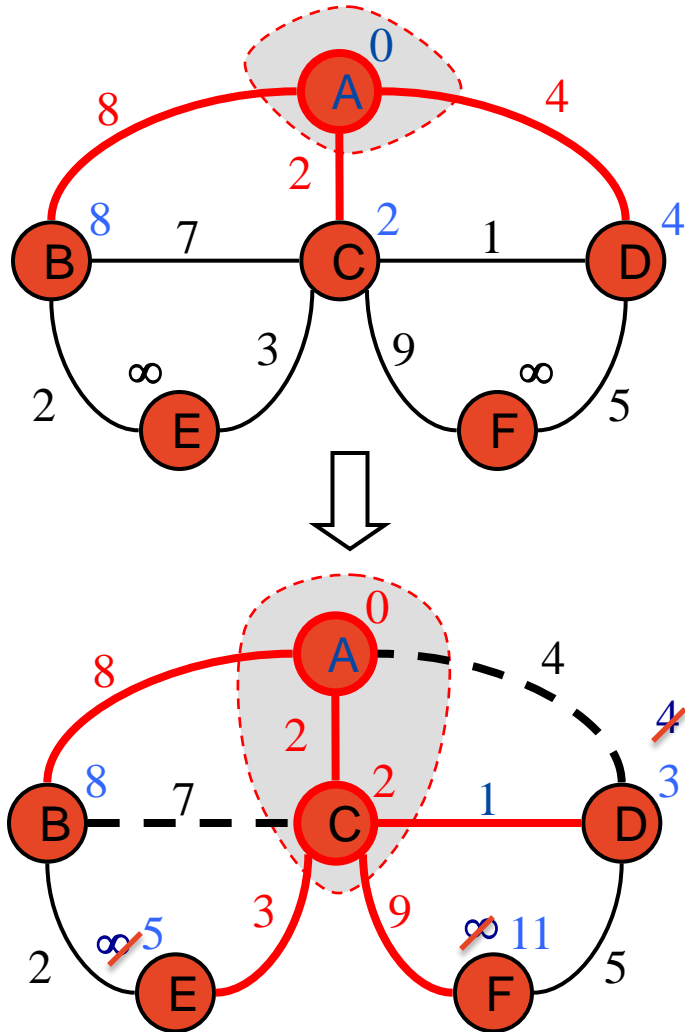
- The distance of a vertex v from a vertex s is the length of a shortest path between s and v
- Dijkstra's algorithm computes the distances of all the vertices from a given **start vertex s**
(single source shortest path)
- Assumptions:
 - the graph is **connected**
 - the edges are **undirected**
 - the edge weights are **nonnegative**
- We grow a “cloud” C of vertices, beginning with s and eventually covering all the vertices
- We store with each vertex v a **label $d(v)$** representing the distance of v from s in the subgraph consisting of the cloud and its adjacent vertices
- At each step
 - We add to the cloud the vertex u outside the cloud with the **smallest distance label, $d(u)$**
 - We update the labels of the vertices adjacent to u
- ***Greedy method:*** optimise cost function

Edge Relaxation

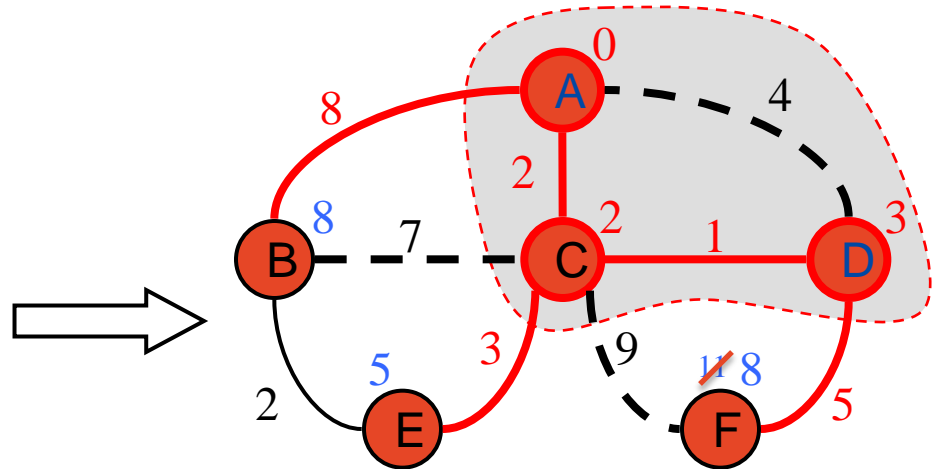
- Consider an edge $e = (u, z)$ such that
 - u is the vertex most recently added to the cloud
 - z is not in the cloud
- The **relaxation** of edge e updates distance $d(z)$ as follows:
 $d(z) \leftarrow \min\{d(z), d(u) + \text{weight}(e)\}$



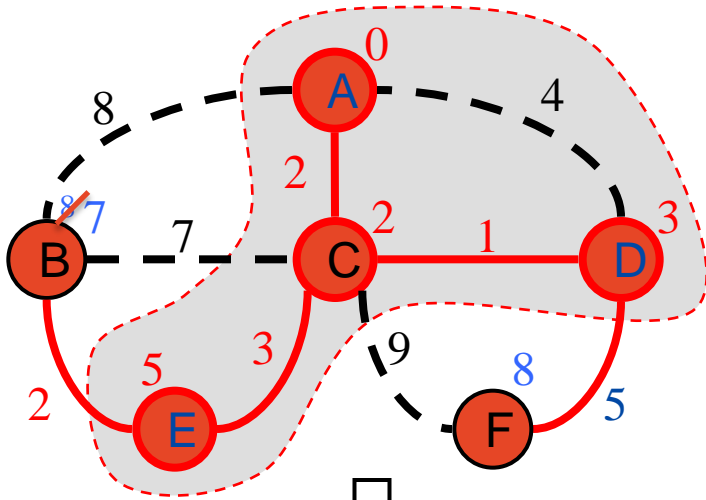
Example



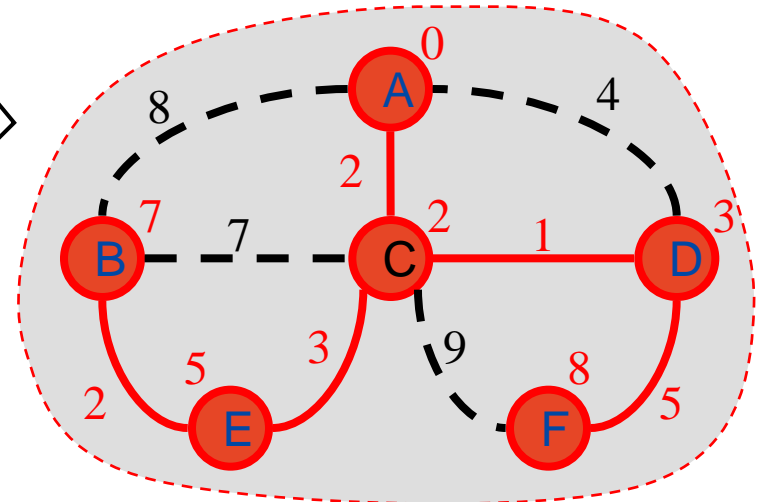
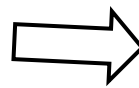
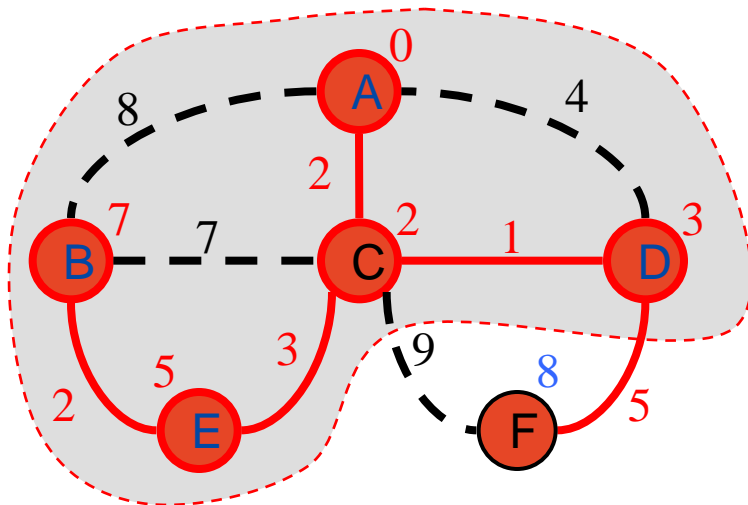
Node	Distance from A	Predecessor node
A	0	--
B	∞ 8	A
C	∞ 2	A
D	∞ 4 3	A C
E	∞ 5	C
F	∞ 11 8	C D



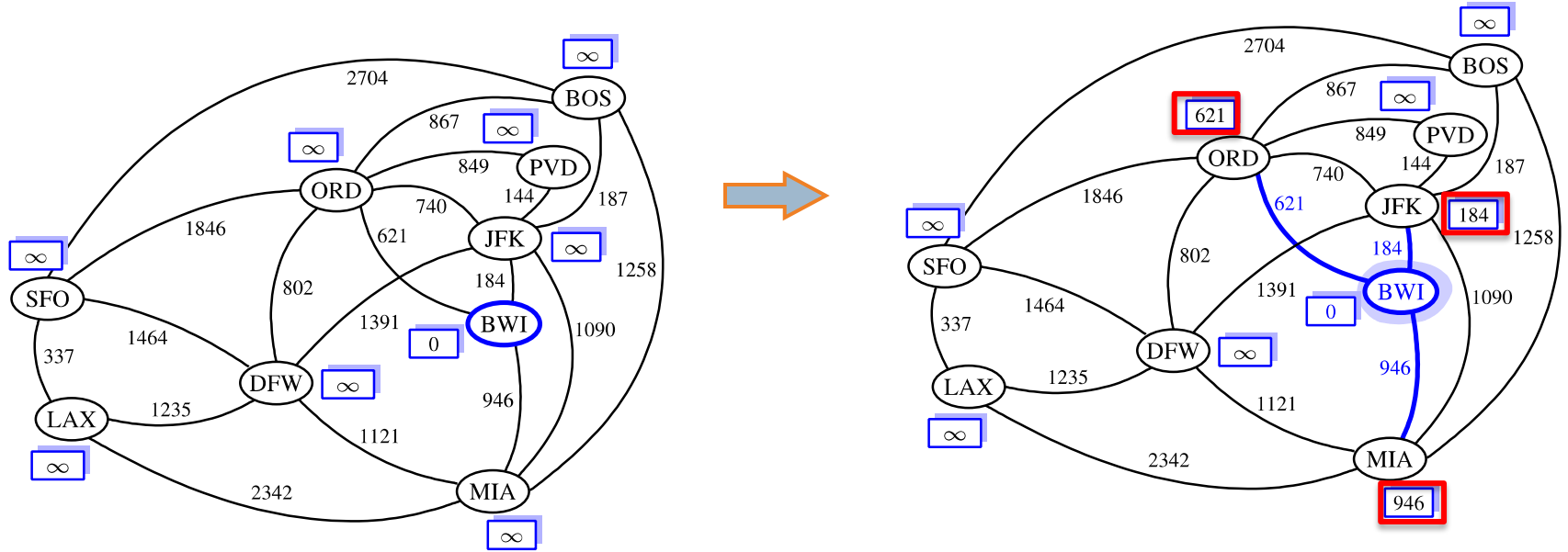
Example



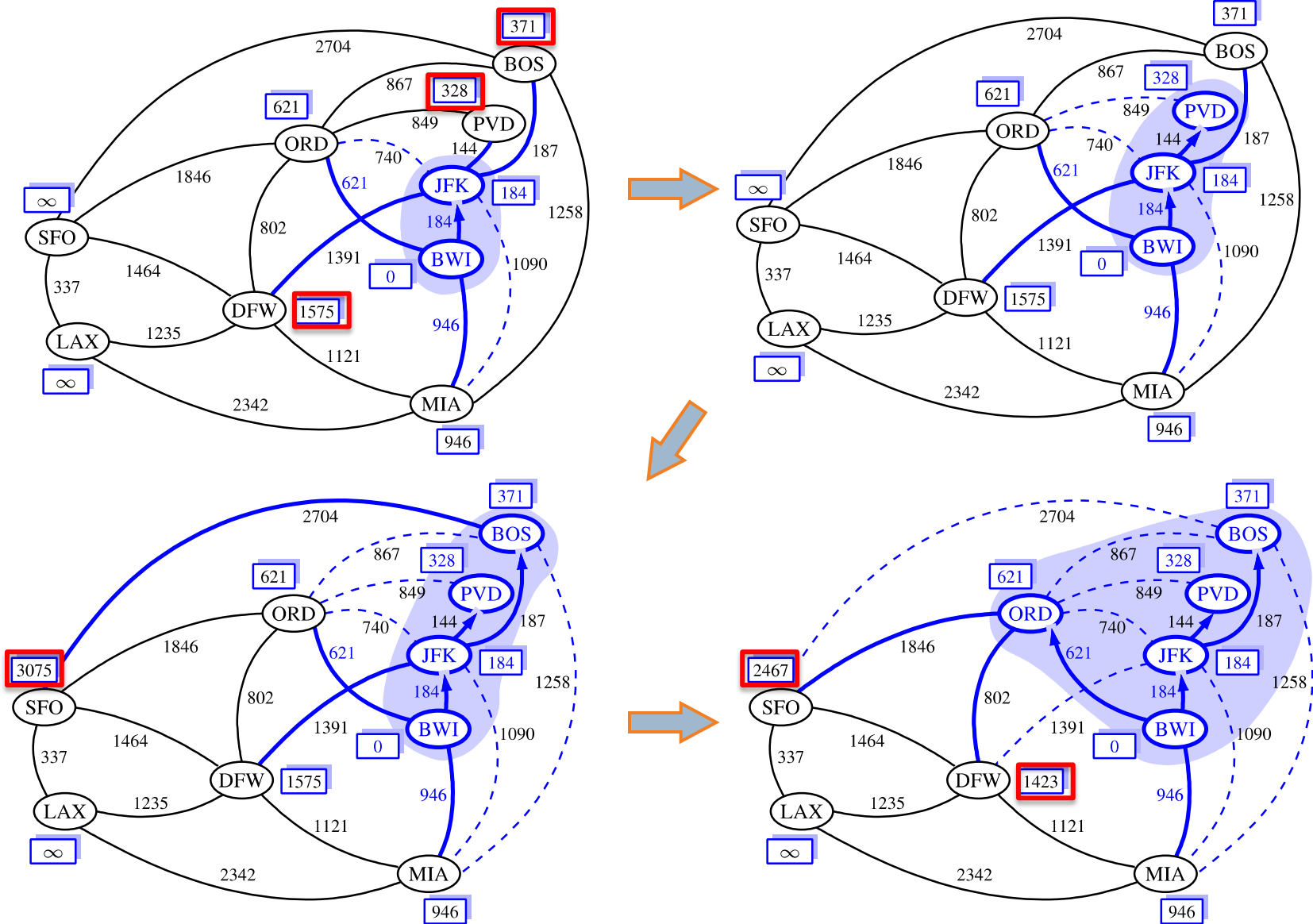
Node	Distance from A	Predecessor node
A	0	--
B	∞ 8 7	A E
C	∞ 2	A
D	∞ 4 3	A C
E	∞ 5	C
F	∞ 11 8	C D



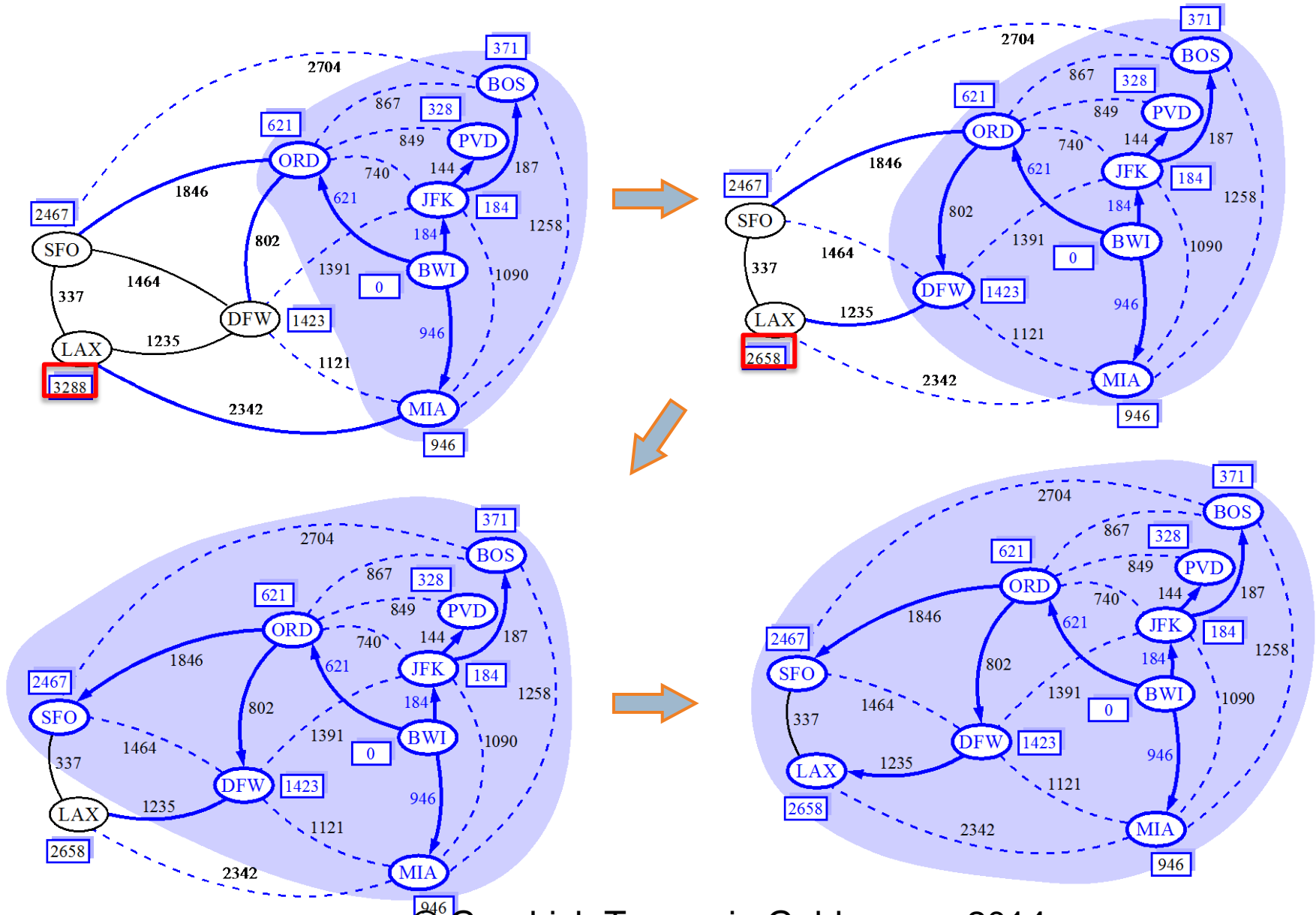
Dijkstra: Example 2



Dijkstra: Example 2 (cont)



Dijkstra: Example 2 (cont)



Dijkstra's Algorithm

Algorithm ShortestPath(G, s):

Input: A weighted graph G with nonnegative edge weights, and a distinguished vertex s of G .

Output: The length of a shortest path from s to v for each vertex v of G .

Initialize $D[s] = 0$ and $D[v] = \infty$ for each vertex $v \neq s$.

Let a priority queue Q contain all the vertices of G using the D labels as keys.

while Q is not empty **do**

 {pull a new vertex u into the cloud}

$u =$ value returned by $Q.\text{remove_min}()$

for each vertex v adjacent to u such that v is in Q **do**

 {perform the *relaxation* procedure on edge (u, v) }

if $D[u] + w(u, v) < D[v]$ **then**

$D[v] = D[u] + w(u, v)$

 Change to $D[v]$ the key of vertex v in Q .

return the label $D[v]$ of each vertex v

Analysis of Dijkstra's Algorithm

- Graph operations
 - Method **incidentEdges** is called once for each vertex
- Label operations
 - We set/get the distance and locator labels of vertex z $O(\deg(z))$ times
 - Setting/getting a label takes $O(1)$ time
- **Priority queue** operations: [adaptable priority queue](#) (sec. 9.5)
 - Each vertex is inserted once into and removed once from the priority queue, where each insertion or removal takes $O(\log n)$ time
 - The key of a vertex in the priority queue is modified at most $\deg(w)$ times, where each key change takes $O(\log n)$ time
- Dijkstra's algorithm runs in $O((n + m) \log n)$ time provided the graph is represented by the **adjacency list/map structure**
 - Recall that $\sum_v \deg(v) = 2m$
- The running time can also be expressed as [O\(m log n\)](#) since the graph is connected (good when m is small, [sparse](#) graph)
- Alternative PQ Implementation
 - Unsorted sequence: [O\(n^2\)](#) ($O(n)$ FindMin, $O(1)$ key update), m is large ([dense](#))
 - [Fibonacci Heap: O\(m+nlogn\)](#)

Java Implementation

```
1  /** Computes shortest-path distances from src vertex to all reachable vertices of g. */
2  public static <V> Map<Vertex<V>, Integer>
3  shortestPathLengths(Graph<V,Integer> g, Vertex<V> src) {
4      // d.get(v) is upper bound on distance from src to v
5      Map<Vertex<V>, Integer> d = new ProbeHashMap<>();
6      // map reachable v to its d value
7      Map<Vertex<V>, Integer> cloud = new ProbeHashMap<>();
8      // pq will have vertices as elements, with d.get(v) as key
9      AdaptablePriorityQueue<Integer, Vertex<V>> pq;
10     pq = new HeapAdaptablePriorityQueue<>();
11     // maps from vertex to its pq locator
12     Map<Vertex<V>, Entry<Integer,Vertex<V>>> pqTokens;
13     pqTokens = new ProbeHashMap<>();
14
15     // for each vertex v of the graph, add an entry to the priority queue, with
16     // the source having distance 0 and all others having infinite distance
17     for (Vertex<V> v : g.vertices()) {
18         if (v == src)
19             d.put(v,0);
20         else
21             d.put(v, Integer.MAX_VALUE);
22         pqTokens.put(v, pq.insert(d.get(v), v));           // save entry for future updates
23     }
```

Java Implementation (continued)

```
24 // now begin adding reachable vertices to the cloud
25 while (!pq.isEmpty()) {
26     Entry<Integer, Vertex<V>> entry = pq.removeMin();
27     int key = entry.getKey();
28     Vertex<V> u = entry.getValue();
29     cloud.put(u, key); // this is actual distance to u
30     pqTokens.remove(u); // u is no longer in pq
31     for (Edge<Integer> e : g.outgoingEdges(u)) {
32         Vertex<V> v = g.opposite(u,e);
33         if (cloud.get(v) == null) {
34             // perform relaxation step on edge (u,v)
35             int wgt = e.getElement();
36             if (d.get(u) + wgt < d.get(v)) { // better path to v?
37                 d.put(v, d.get(u) + wgt); // update the distance
38                 pq.replaceKey(pqTokens.get(v), d.get(v)); // update the pq entry
39             }
40         }
41     }
42 }
43 return cloud; // this only includes reachable vertices
44 }
```

Shortest Paths Tree

- Using the template method pattern, we can extend Dijkstra's algorithm to return a **tree of shortest paths** from the start vertex to all other vertices
- We store with each vertex a third label:
 - **parent edge** in the shortest path tree
- In the edge **relaxation** step, we update the parent label
- Textbook: reconstruction of the tree
 - Similar to DFS/BFS: **parent u**
 - Check all incoming edges of each vertex v
 - $O(n+m)$ time

Algorithm *DijkstraShortestPathsTree*(G, s)

...

for all $v \in G.vertices()$

...

setParent(v, \emptyset)

...

for all $e \in G.incidentEdges(u)$

{ relax edge e }

$z \leftarrow G.opposite(u, e)$

$r \leftarrow getDistance(u) + weight(e)$

if $r < getDistance(z)$

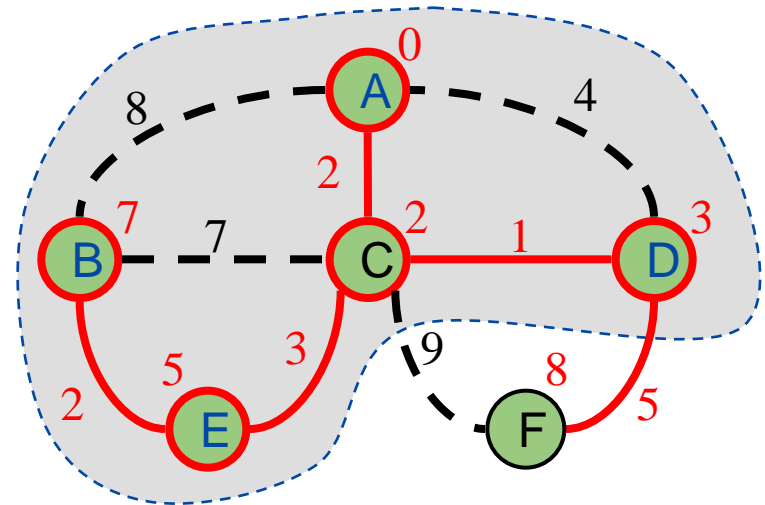
setDistance(z, r)

setParent(z, e)

Q.replaceKey(*getEntry*(z), r)

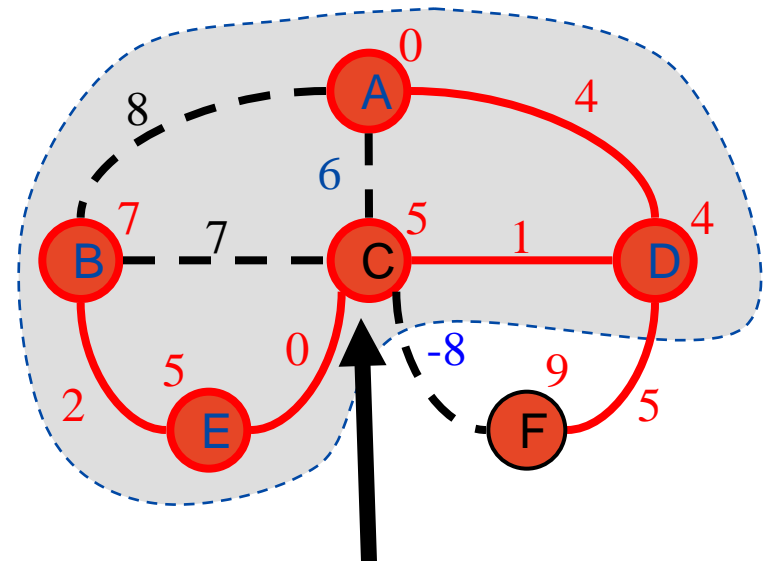
Why Dijkstra's Algorithm Works (correctness)

- Dijkstra's algorithm is based on the **greedy method**.
- It adds vertices by increasing distance.
- When v is added to C , $d(v)=d(s,v)$: length of the shortest path
- Suppose it didn't find all shortest distances. Let **F** be the first wrong vertex the algorithm processed.
- When the previous node, **D**, on the true shortest path was considered, its distance was correct.
- But the edge (D,F) was **relaxed** at that time!
- Thus, so long as $d(F) \geq d(D)$, F 's distance cannot be wrong (**no negative edges**).
- That is, there is no wrong vertex. Contradiction.



Why It Doesn't Work for Negative-Weight Edges

- Dijkstra's algorithm is a “greedy” method.
 - It adds vertices by increasing distance.
- If a node with a **negative** incident edge were to be added late to the cloud, it could mess up distances for vertices already in the cloud.
(no negative cycle)



C's true distance is 1, but it is already in the cloud with $d(C)=5$!

Summary

- Directed graphs
 - Directed DFS (section 14.3)
 - Strong connectivity (section 14.3)
 - Transitive closure (Floyd-Warshall algorithm) (section 14.4)
 - Topological ordering (section 14.5)
- Weighted graphs (Section 14.6)
 - Shortest paths (Dijkstra's algorithm)