

Introduction to TDVP

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References:

Haegeman et al arXiv:1103.0936
Haegeman et al arXiv:1408.5056 (follow here)
Vanderstraeten et al arXiv:1810.07006
Paeckel et al arXiv:1901.05824

goal: evolution with Schrödinger equation $i\hbar \partial_t |\psi\rangle = H |\psi\rangle$

issue: solution is not a (finite-bond dimension) MPS

Time dependent variational principle (TDVP):

parametrize $|\psi(\vec{M}(t))\rangle$ and derive equations for $\frac{d}{dt} \vec{M}^i \equiv \dot{\vec{M}}^i$

minimize

$$\| \underbrace{\dot{\vec{M}}^i(t) | \partial_i \psi(\vec{M}^i) \rangle}_{\text{in tangent space}} - \underbrace{\left(-\frac{i}{\hbar}\right) H |\psi(\vec{M}^i(t))\rangle}_{|\varphi\rangle \text{ not in tangent space}} \|$$

\rightarrow

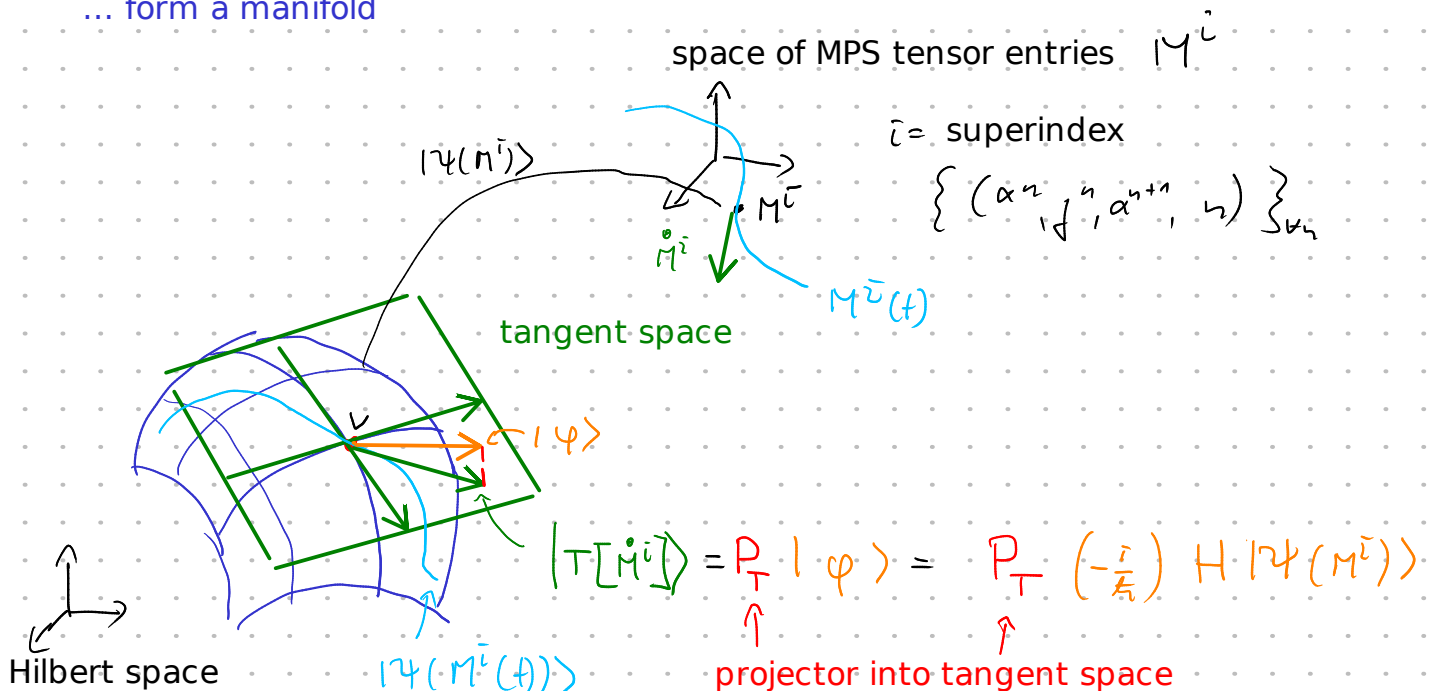
$$\frac{d}{dt} |\psi(\vec{M}^i(t))\rangle = \left(-\frac{i}{\hbar}\right) P_T H |\psi(\vec{M}^i(t))\rangle$$

MPS manifold

MPS with fixed bond dimension (and non-zero singular values)...

$$|\psi(\vec{M}^i)\rangle = \begin{array}{c} \textcircled{M^1} - \textcircled{M^2} - \textcircled{M^3} - \textcircled{M^4} - \textcircled{M^N} \end{array} = \begin{array}{c} \textcircled{A^1} - \textcircled{A^2} - \textcircled{\theta^N} - \textcircled{B^{N+1}} - \textcircled{B^N} \end{array}$$

... form a manifold



Tangent vector of general MPS

$$X^i |\partial_{M^i} \psi(M^i)\rangle = \sum_{n=1}^N \sum_{\{j^n\}} M^1 \cdots M^{n-1} \overset{\text{red } X^n}{\cancel{M^n}} M^{n+1} \cdots M^N |j^1 \cdots j^N\rangle$$

partial derivative = leave tensor out

$$\partial_{M^{ab}} \text{ (tensor diagram with } M \text{ on } a, b \text{)} = \sum_{abc} \frac{\partial M^{ab}}{\partial M^{ab}} N^{bc} O^{ca} = \text{ (tensor diagram with } \tilde{a}, \tilde{b} \text{)}$$

Tangent vector in mixed canonical form

$$|T[X^i]\rangle = \sum_{n=1}^N \sum_{\{j^n\}} \underbrace{A^1 \cdots A^{n-1}}_{\langle \alpha^n |_L} \overset{\text{red } X^n}{\cancel{X^n}} \underbrace{B^{n+1} \cdots B^N}_{|\alpha^{n+1}\rangle_R} |j^1 \cdots j^N\rangle$$

overcomplete: $\text{---}(X^n)\text{---} \rightarrow \text{---}(X^n)\text{---} + \text{---}(Y^n)\text{---}(B^n)\text{---} - \text{---}(A^n)\text{---}(Y^{n+1})\text{---}$
 (for some tensors Y describes same tangent vector)
 ($Y^1 = Y^{N+1} = 0$)

→ demand left gauge fixing
 (convention)

$$\begin{array}{c} X^n \\ | \\ A^n \end{array} = 0 \quad \text{for all } n < N$$

→ simplifies overlaps of tangent vectors:

$$\langle T[X^i] | T[Z^i] \rangle = \sum_n \text{ (tensor diagram with } X^n \text{ and } Z^n \text{)}$$

Tangent space projector P_T

given $|\psi\rangle$ we need to find $\min_{X^i} \| |T[X^i]\rangle - |\psi\rangle \|^2 =$

$$= \min \left| \sum_n \left(\text{ (tensor diagram with } X^i \text{ and } X^i \text{)} - \text{ (tensor diagram with } F^i \text{ and } X^i \text{)} - \text{ (tensor diagram with } X^i \text{ and } F^i \text{)} + \langle \psi | \psi \rangle \right) \right|$$

with

$$\text{---}(F^i)\text{---} = \text{---} \underbrace{A^1 \cdots A^{n-1}}_{\langle \alpha^n |_L} \text{---} \underbrace{B^{n+1} \cdots B^N}_{|\alpha^{n+1}\rangle_R} \text{---}$$

under the constraint

$$\begin{array}{c} \textcircled{X^n} \\ \downarrow \\ \textcircled{A^n} \end{array} = 0 \quad \text{for } n < N$$

minimal for

$$n < N: \quad \textcircled{X^n} = \left(\mathbb{1} - \underbrace{|A^n\rangle\langle A^n|}_{\begin{array}{c} \textcircled{A^n} \\ \downarrow \\ \textcircled{A^n} \end{array}} \right) \textcircled{F^n} = \textcircled{F^n} - \begin{array}{c} \textcircled{F^n} \\ \downarrow \\ \textcircled{A^n} \\ \downarrow \\ \textcircled{A^n} \end{array}$$

$$n = N: \quad \textcircled{X^N} = \textcircled{F^N}$$

Plug this into $|T[X^n]\rangle$:

$$|T[X^n]\rangle = P_T |\psi\rangle = \sum_{n=1}^N \begin{array}{c} \textcircled{\alpha^n} \textcircled{A^1} \textcircled{A^{n-1}} \\ \downarrow \quad \downarrow \\ \textcircled{\alpha^n} \textcircled{A^1} \textcircled{A^{n-1}} \end{array} \quad \left| \begin{array}{c} \textcircled{\beta^{n+1}} \textcircled{\beta^n} \langle \alpha^{n+1}|_R \\ \textcircled{\beta^{n+1}} \textcircled{\beta^n} |\alpha^{n+1}\rangle_R \end{array} \right.$$

$$- \sum_{n=1}^{N-1} \begin{array}{c} \textcircled{A^1} \textcircled{A^{n-1}} \textcircled{A^n} \quad \textcircled{\beta^{n+1}} \textcircled{\beta^n} \\ \textcircled{A^1} \textcircled{A^{n-1}} \textcircled{A^n} \quad \textcircled{\beta^{n+1}} \textcircled{\beta^n} \end{array}$$

$$P_T = \sum_{n=1}^N |\alpha^n\rangle_L \langle \alpha^n|_L \otimes \mathbb{1}_n \otimes |\alpha^{n+1}\rangle_R \langle \alpha^{n+1}|_R \\ - \sum_{n=1}^{N-1} |\alpha^{n+1}\rangle_L \langle \alpha^{n+1}|_L \otimes |\alpha^{n+1}\rangle_R \langle \alpha^{n+1}|_R$$

Plugging this into the TDVP equation yields

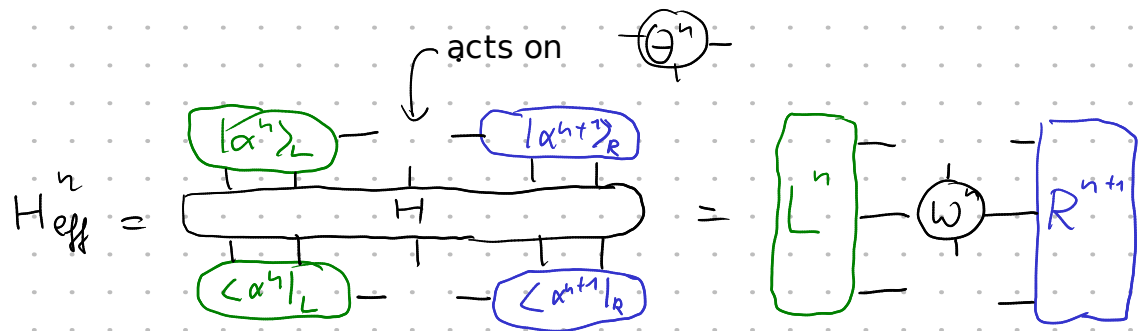
$$\sum_{n=1}^N \begin{array}{c} \textcircled{|\alpha^n\rangle_L} \\ \downarrow \end{array} \textcircled{\Theta^i} \begin{array}{c} \textcircled{|\alpha^{n+1}\rangle_R} \\ \downarrow \end{array} = |T[\Theta^i]\rangle = \left(-\frac{i}{\hbar}\right) P_T H |\psi\rangle =$$

$$= \left(-\frac{i}{\hbar}\right) \left[\sum_{n=1}^N \begin{array}{c} \textcircled{|\alpha^n\rangle_L} \textcircled{\Theta^i} \textcircled{|\alpha^{n+1}\rangle_R} \\ \hline \textcircled{\alpha^n|_L} \textcircled{\alpha^{n+1}|_R} \\ \textcircled{\alpha^n|_L} \textcircled{\alpha^{n+1}|_R} \end{array} - \sum_{n=1}^{N-1} \begin{array}{c} \textcircled{|\alpha^n\rangle_L} \textcircled{\Theta^i} \textcircled{|\alpha^{n+1}\rangle_R} \\ \hline \textcircled{\alpha^n|_L} \textcircled{A^n} \textcircled{\alpha^{n+1}|_R} \\ \textcircled{\alpha^n|_L} \textcircled{A^n} \textcircled{\alpha^{n+1}|_R} \end{array} \right]$$

We don't know how to integrate all terms at once,
but we can integrate each term individually!

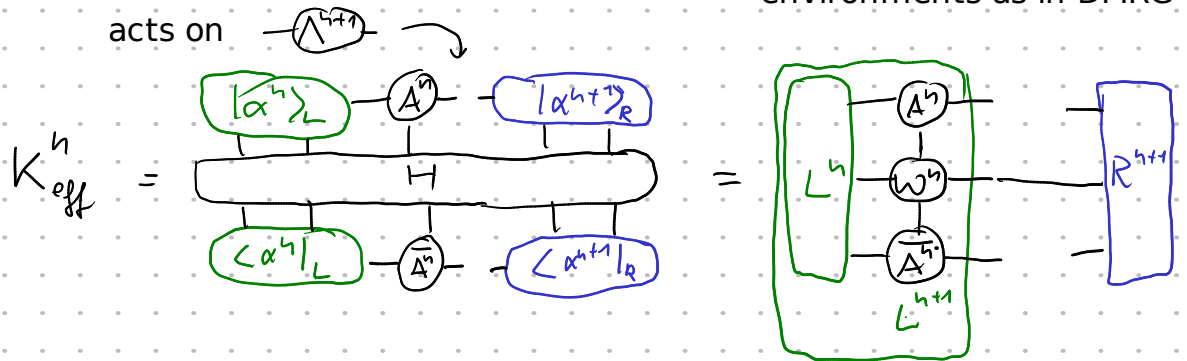
Doing so yields the TDVP algorithm on the next page.

Define one-site



environments as in DMRG

zero-site

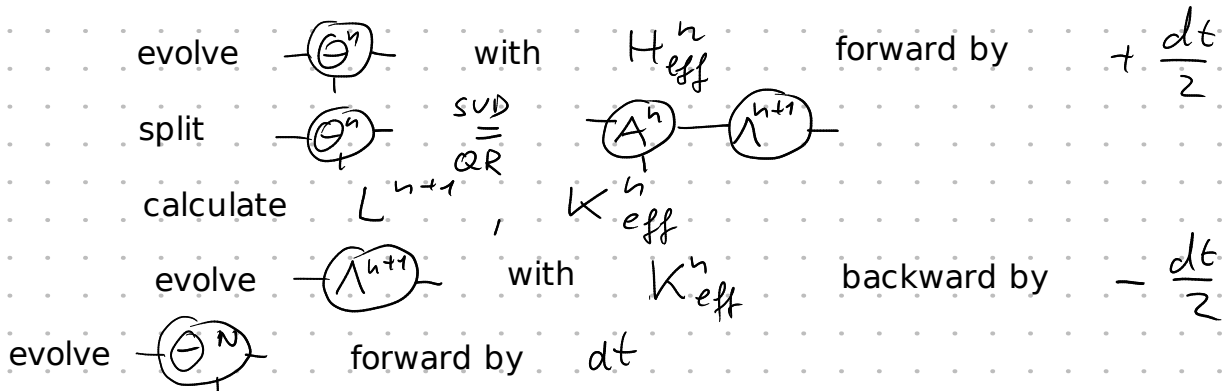


TDVP algorithm for MPS

Start with MPS in right canonical form

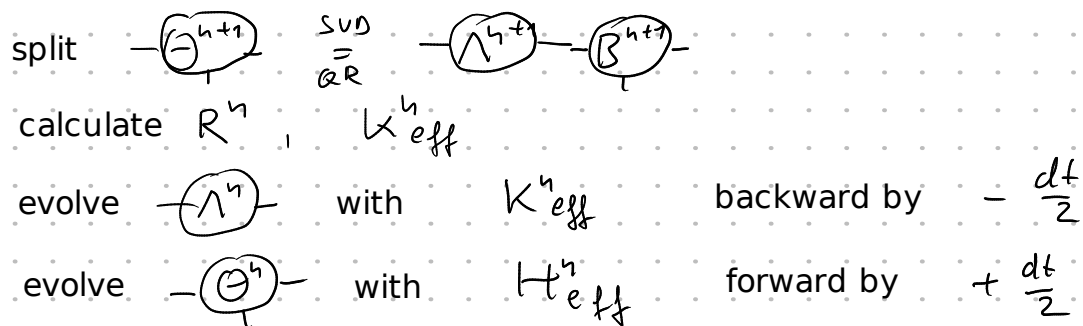
for n in $\{1, 2, \dots, N-1\}$:

sweep left to right



for n in $\{N-1, \dots, 2, 1\}$

sweep right to left



Properties:

very similar to DMRG:

recover (finite) DMRG for imaginary evolution with $dt \rightarrow \infty$

symmetric under inverse evolution,
hence correct to second order in dt

no truncation necessary,

always stay in manifold of MPS with fixed bond dimension

-> can use two-site scheme to expand the bond dimension

symplectic, preserves the energy