# Graph Algorithm Applications

SWE2016-44

- 1. Shortest Path in a graph
- 2. Social Network
- 3. Cycle Detection in undirected graph
- 4. To test if a graph is bipartite
- 5. Broadcasting in a network
- 6. Path Finding

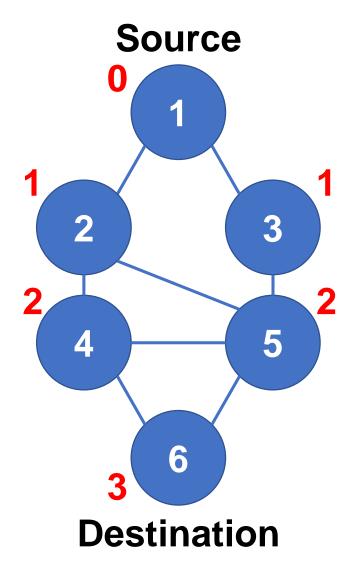
1. Shortest Path in an unweighted graph

#### **Initialize:**

Dist\_Shortest(F)  $\begin{cases} 0 \text{ if source=destination} \\ \infty \text{ otherwise} \end{cases}$ 

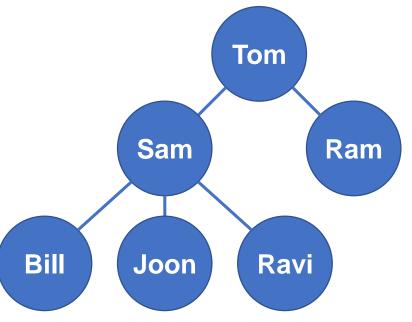
For each edge E={v, w}:

If w is unvisited,Dist\_Shortest(w) = Dist\_Shortest(v)+1



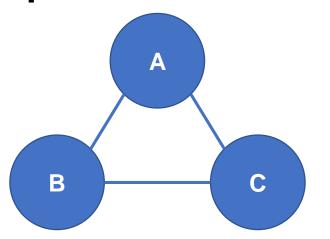
#### 2. Social Network

In social networks, we can find people within a given distance 'k' from a person BFS until 'k' levels.



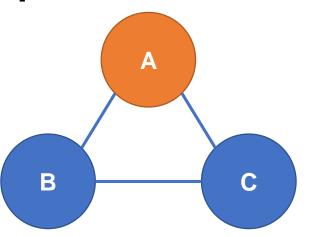
#### 3. Detecting cycle in undirected graph

For every visited vertex 'v', if there is an adjacent 'u' such that u is already visited and u is not parent of v, then there is a cycle in graph

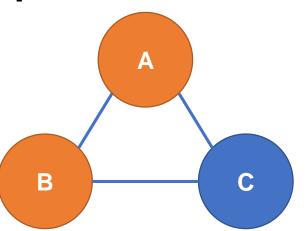


**BFS + Visited** 

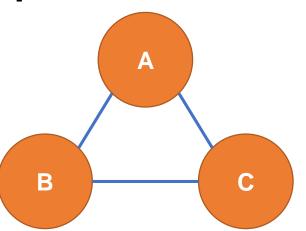
#### 3. Detecting cycle in undirected graph



#### 3. Detecting cycle in undirected graph



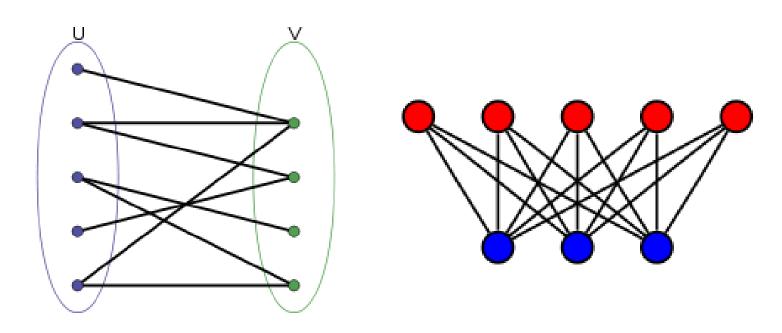
#### 3. Detecting cycle in undirected graph



4. Check if graph is bipartite or not: Bipartite Graph is a graph whose vertices can be divided into two disjoint and independent sets, U and V such that every edge (u, v) either connects a vertex from U to V or a vertex from V to U. In other words, for every edge (u, v), either u belongs to U and v to V, or u belongs to V and v to U. We can also say that there is no edge that connects vertices of same set.

#### 4. Check if graph is bipartite or not

**Bipartite Graph** 

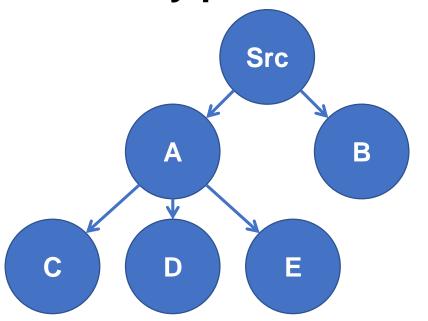


#### 4. Check if graph is bipartite or not

Use the vertex coloring algorithm:

- 1) Start with a vertex and give it a color (RED).
- 2) Run BFS from this vertex. For each new vertex, color it opposite its parents. (p:RED → v:BLUE, p:BLUE → v:RED)
- 3) Check for edges that it doesn't link two vertices of the same color.
- 4) Repeat steps 2 and 3 until all the vertices are colored RED or BLUE.

5. <u>Broadcasting in a Network</u>: Transferring data to all recipients simultaneously. BFS ensures that each node maintain shortest route to the source. Thus, reduces transmission delay and saves battery power.



6. Path Finding: find a path between two given vertices u and v

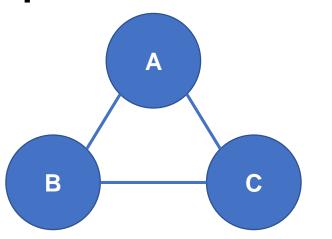
#### **Algorithm:**

- 1) Call BFS(G, u) with u as the start vertex.
- 2) Do BFS using a queue Q.
- 3) As soon as destination vertex v is encountered, return the path as the contents of the stack.

- 1. Detecting cycle in a graph
- 2. Path Finding
- 3. To test if a graph is bipartite
- 4. Topological Sort
- 5. Strongly Connected Components

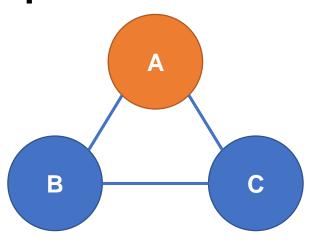
#### 1. Detecting cycle in a graph

For every visited vertex 'v', if there is an adjacent 'u' such that u is already visited and u is not parent of v, then there is a cycle in graph

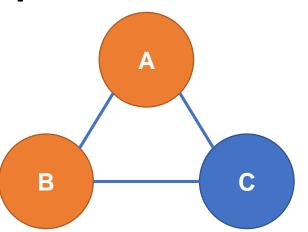


**DFS + Visited** 

#### 1. Detecting cycle in a graph

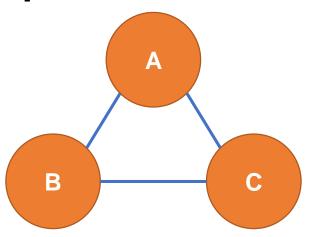


#### 1. Detecting cycle in a graph



#### 1. Detecting cycle in a graph

For every visited vertex 'v', if there is an adjacent 'u' such that u is already visited and u is not parent of v, then there is a cycle in graph



Only DFS for directed graph

2. Path Finding: find a path between two given vertices u and v

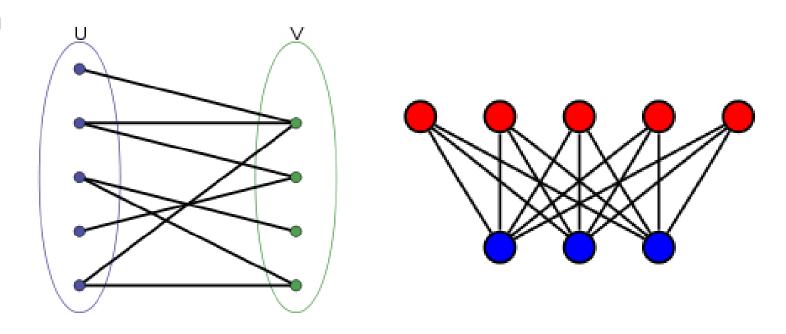
#### **Algorithm:**

- 1) Call DFS(G, u) with u as the start vertex.
- 2) Use a stack S to keep track of the path between the start vertex and the current vertex.
- 3) As soon as destination vertex v is encountered, return the path as the contents of the stack.

3. Check if graph is bipartite or not: Bipartite Graph is a graph whose vertices can be divided into two disjoint and independent sets, U and V such that every edge (u, v) either connects a vertex from U to V or a vertex from V to U. In other words, for every edge (u, v), either u belongs to U and v to V, or u belongs to V and v to U. We can also say that there is no edge that connects vertices of same set.

#### 3. Check if graph is bipartite or not

**Bipartite Graph** 



#### 3. Check if graph is bipartite or not

Use the vertex coloring algorithm:

- 1) Start with a vertex and give it a color (RED).
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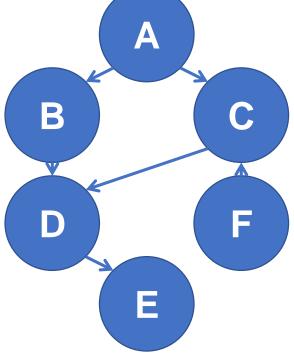
4. <u>Topological Sort</u>: for a DAG (Directed Acyclic Graph) G=(V, E) is a linear ordering of all its vertices such that if G contains an edge (u, v) then u appears before v in ordering.

**Topological Sort:** 

FABCDE

FACBDE

ABFCDE

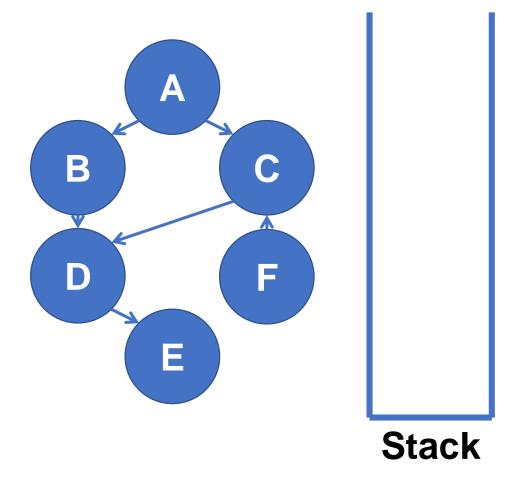


#### 4. Topological Sort

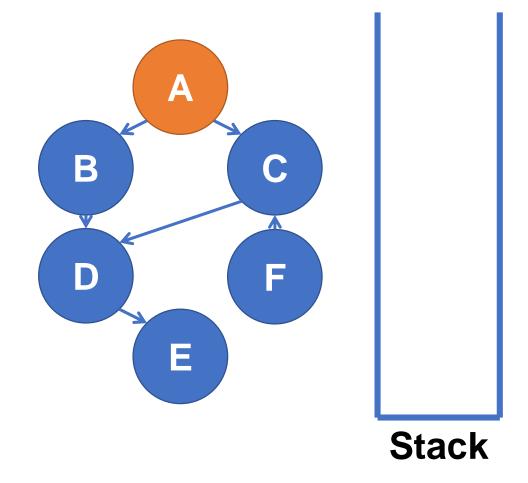
#### **Applications:**

- Build Systems
- Advanced-Packaging Tool
- Task Scheduling
- Pre-requisite problems

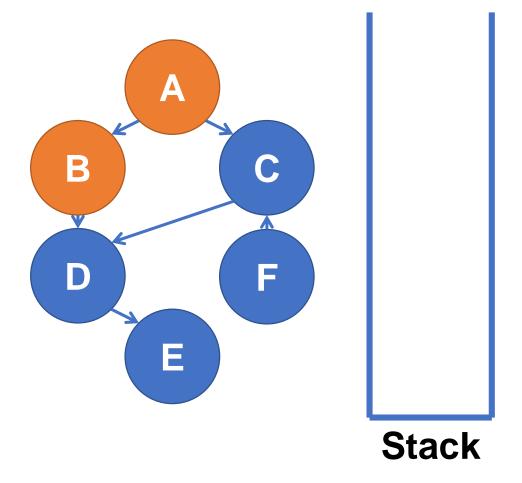
**Topological Sort:** 



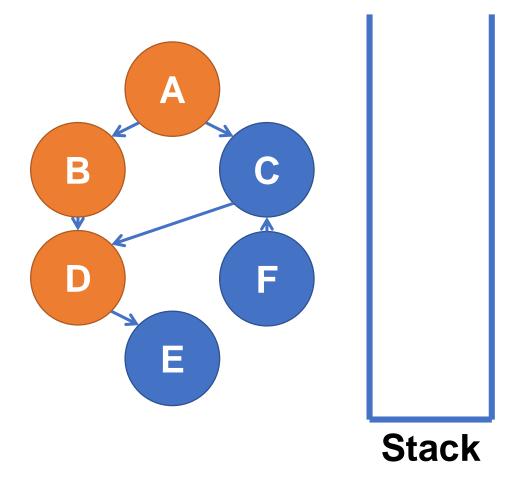
**Topological Sort:** 



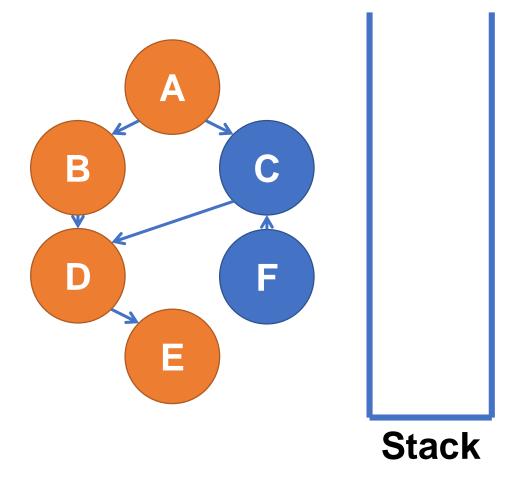
**Topological Sort:** 



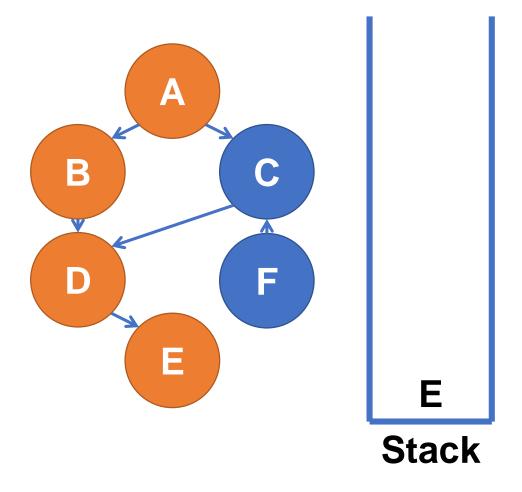
**Topological Sort:** 



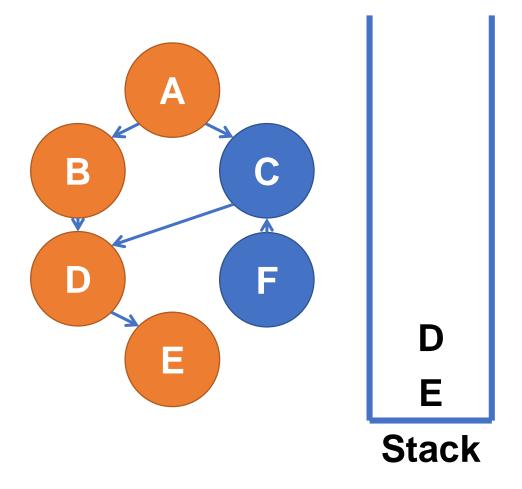
**Topological Sort:** 



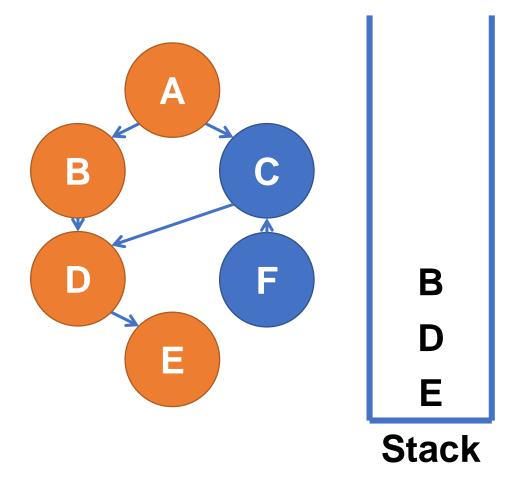
**Topological Sort:** 



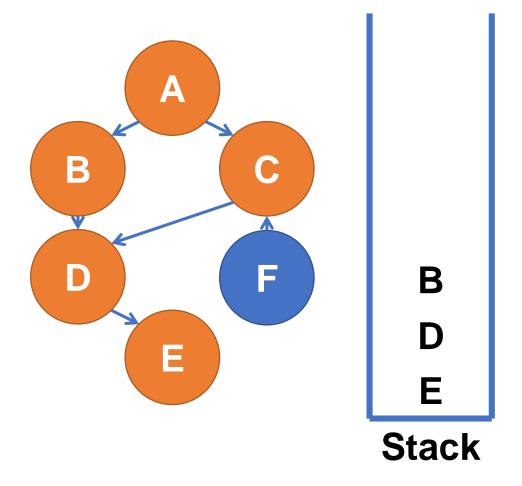
**Topological Sort:** 



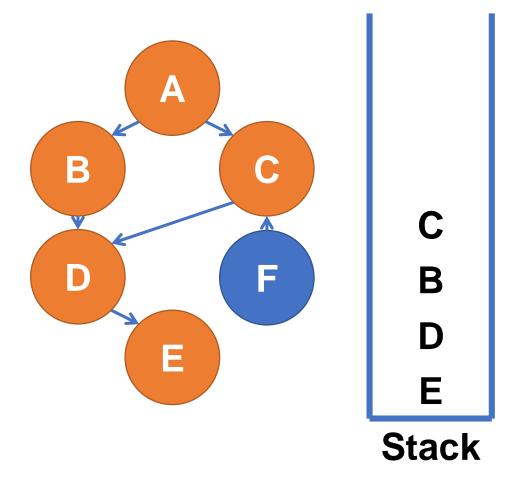
**Topological Sort:** 



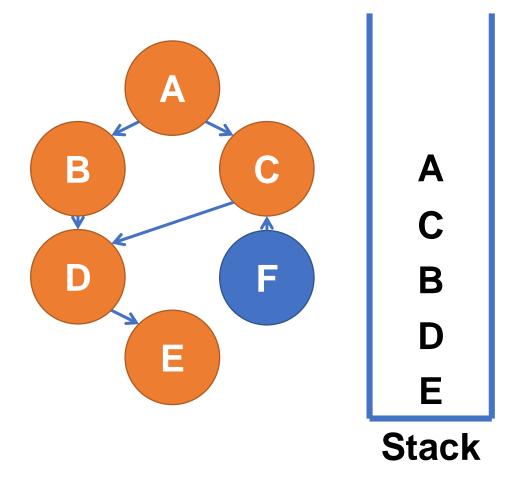
**Topological Sort:** 



**Topological Sort:** 

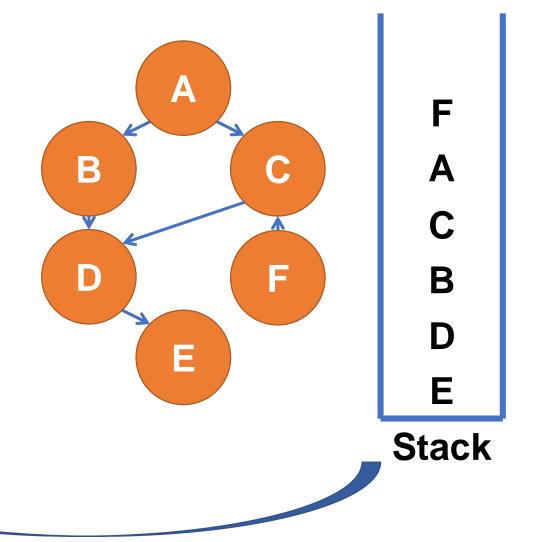


**Topological Sort:** 



**Topological Sort:** 

Use Depth First Search using a temporary stack



FACBDE

#### **Topological Sort**

```
void Graph::topologicalSort()
    stack<int> Stack;
   // Mark all the vertices as not visited
    bool *visited = new bool[V];
   for (int i = 0; i < V; i++)
        visited[i] = false;
   // Call the recursive helper function to store Topological
   // Sort starting from all vertices one by one
   for (int i = 0; i < V; i++)
      if (visited[i] == false)
        topologicalSortUtil(i, visited, Stack);
   // Print contents of stack
   while (Stack.empty() == false)
        cout << Stack.top() << " ";
        Stack.pop();
```

**Topological Sort** 

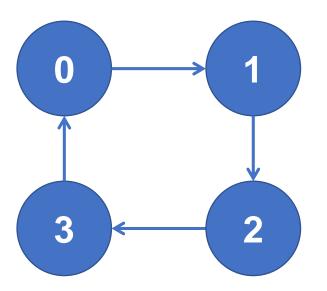
**Time Complexity:** O(V+E)

**V: Vertices** 

E: Edges

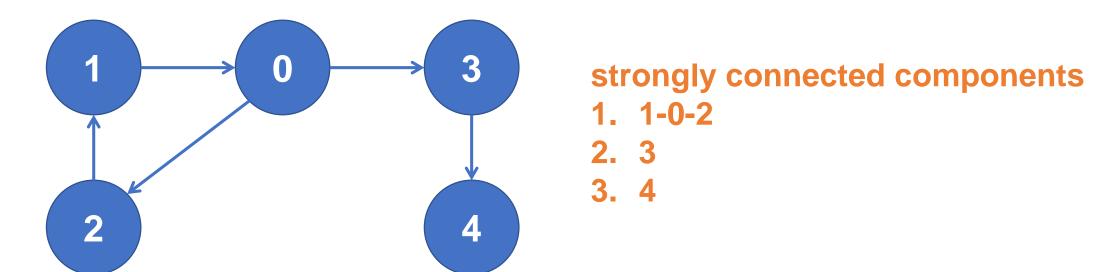
#### 5. Strongly Connected Components (SCC)

A directed graph is strongly connected if there is a path between all pairs of vertices.



#### 5. Strongly Connected Components (SCC)

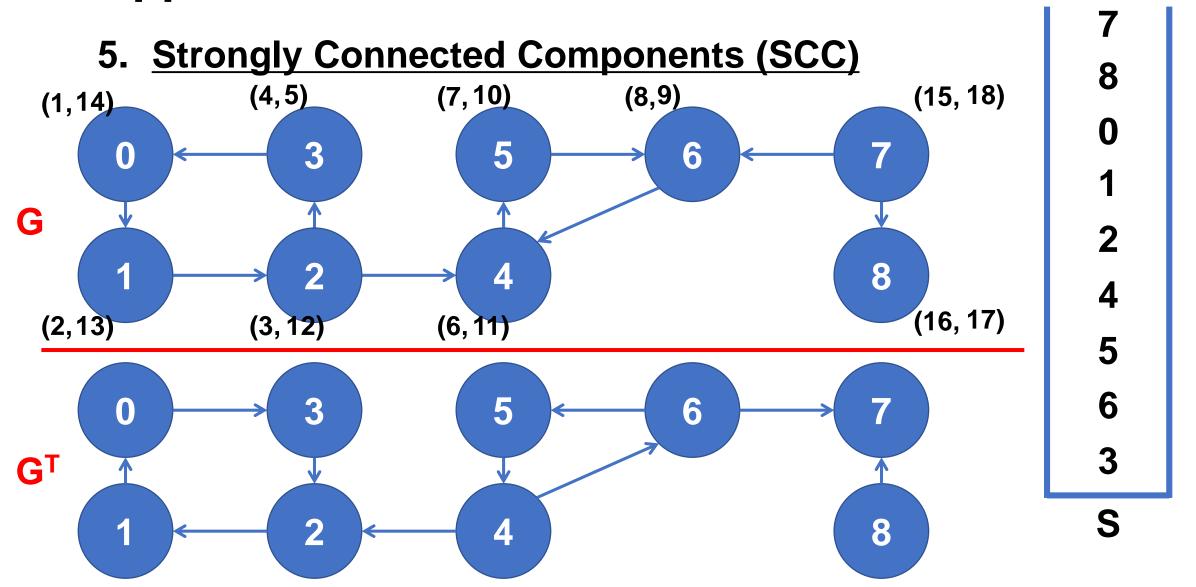
A strongly connected components (SCC) of a directed graph is a maximal strongly connected subgraph.



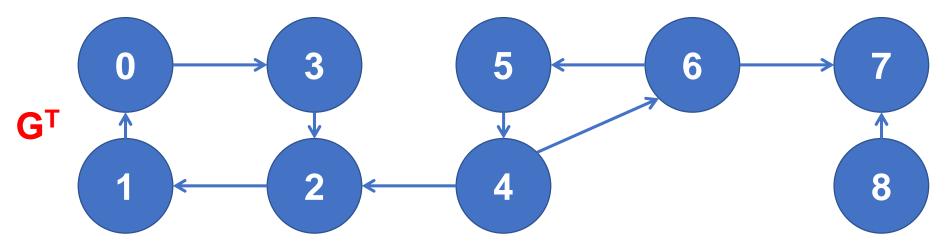
#### 5. Strongly Connected Components (SCC)

#### Kosaraju's algorithm:

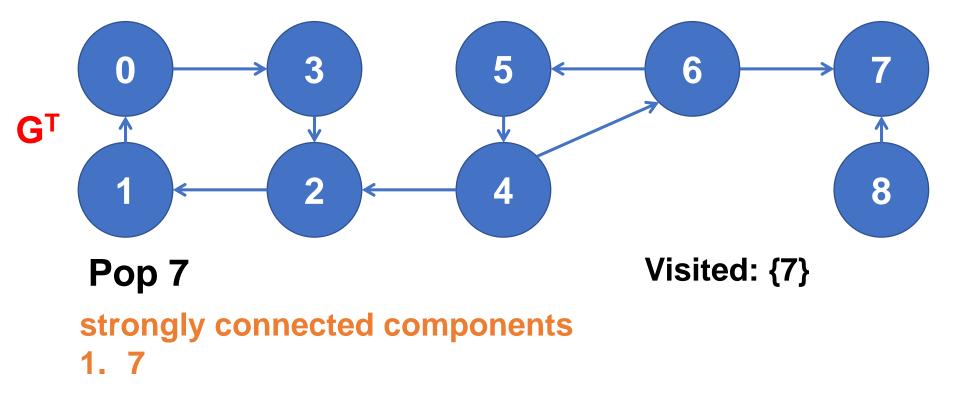
- 1) Create an empty stack S.
- 2) Do DFS of a graph. In DFS, after calling recursive DFS for adjacent vertices of a vertex, push the vertex to stack.
- 3) Reverse directions of all arcs to obtain the transpose graph.
- 4) One by one pop a vertex from S while S is not empty. Let the popped vertex be 'v'. Take v as source and do DFS call on v. The DFS starting from v prints strongly connected component of v.



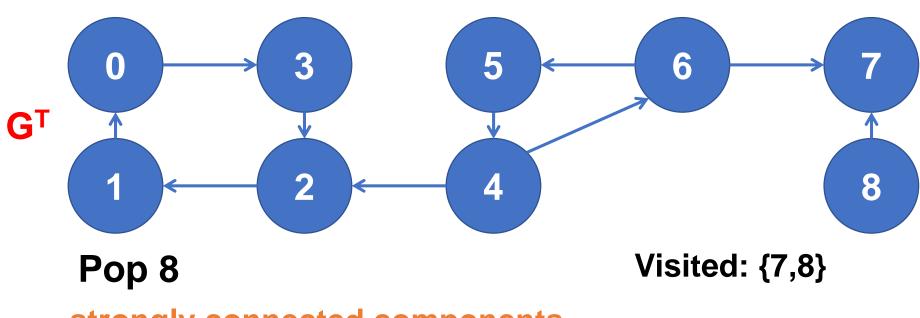
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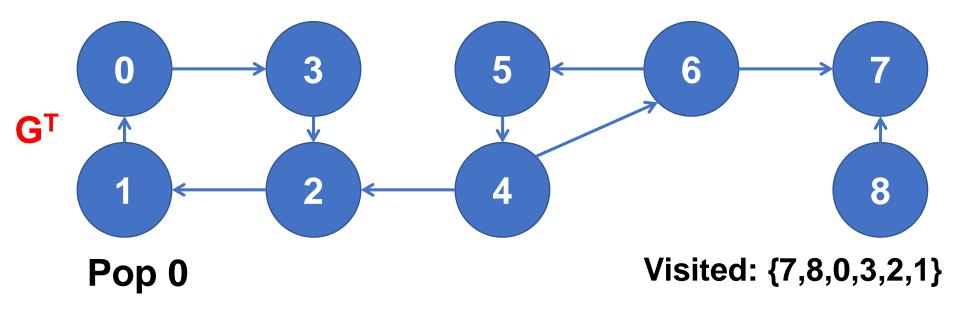


5. Strongly Connected Components (SCC)



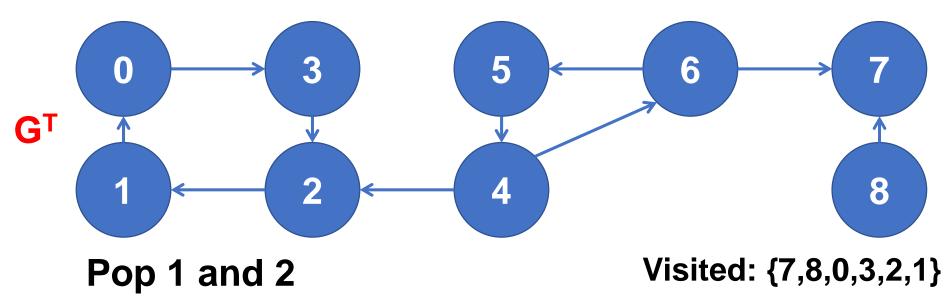
- 1. 7
- 2. 8

5. Strongly Connected Components (SCC)



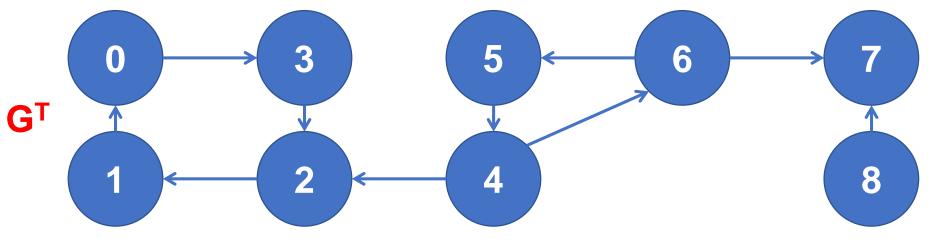
- 1. 7
- 2. 8
- 3. 0-3-2-1

5. Strongly Connected Components (SCC)



- 1. 7
- 2. 8
- 3. 0-3-2-1

5. Strongly Connected Components (SCC)



Pop 4 Visited: {7,8,0,3,2,1,4,6,5}

strongly connected components

- 1. 7
- 2. 8
- 3. 0-3-2-1
- 4. 4-6-5

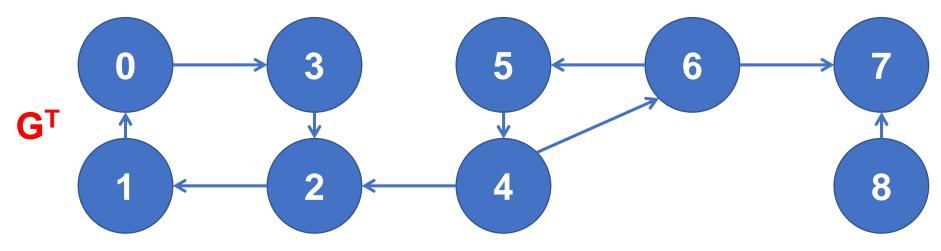
5

6

3

S

#### 5. Strongly Connected Components (SCC)



Pop 5, 6 and 3

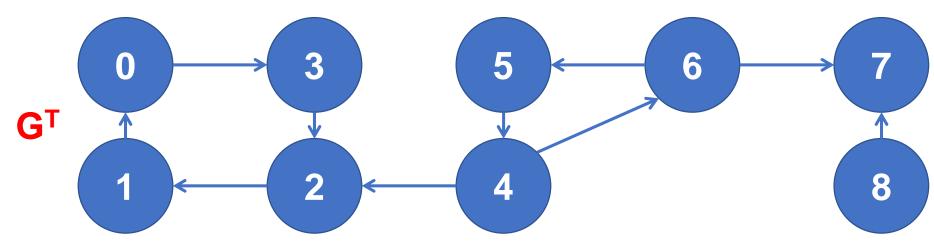
Visited: {7,8,0,3,2,1,4,6,5}

#### strongly connected components

- 1. 7
- 2. 8
- 3. 0-3-2-1
- 4. 4-6-5

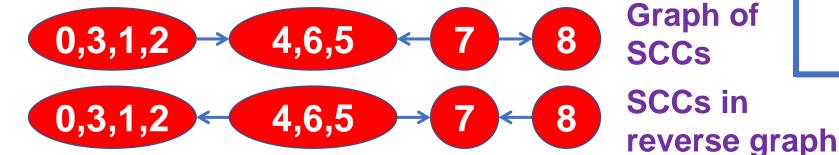
S

#### 5. Strongly Connected Components (SCC)



#### Stack is empty → Terminate

- 0-3-2-1



# **Strongly Connected Components**

```
void Graph::fillOrder(int v, bool visited[], stack<int> &Stack)
{
    // Mark the current node as visited and print it
    visited[v] = true;

    // Recur for all the vertices adjacent to this vertex
    list<int>::iterator i;
    for(i = adj[v].begin(); i != adj[v].end(); ++i)
        if(!visited[*i])
            fillOrder(*i, visited, Stack);

    // All vertices reachable from v are processed by now, push v
    Stack.push(v);
}
```

```
void Graph::printSCCs()
    stack<int> Stack;
   // Mark all the vertices as not visited (For first DFS)
   bool *visited = new bool[V];
   for(int i = 0; i < V; i++)
       visited[i] = false;
   // Fill vertices in stack according to their finishing times
   for(int i = 0; i < V; i++)
       if(visited[i] == false)
           fillOrder(i, visited, Stack);
   // Create a reversed graph
   Graph gr = getTranspose();
   // Mark all the vertices as not visited (For second DFS)
   for(int i = 0; i < V; i++)</pre>
       visited[i] = false;
   // Now process all vertices in order defined by Stack
   while (Stack.empty() == false)
       // Pop a vertex from stack
       int v = Stack.top();
       Stack.pop();
       // Print Strongly connected component of the popped vertex
       if (visited[v] == false)
            gr.DFSUtil(v, visited);
           cout << endl;
```

#### Reference

• Charles Leiserson and Piotr Indyk, "Introduction to Algorithms", September 29, 2004

https://www.geeksforgeeks.org