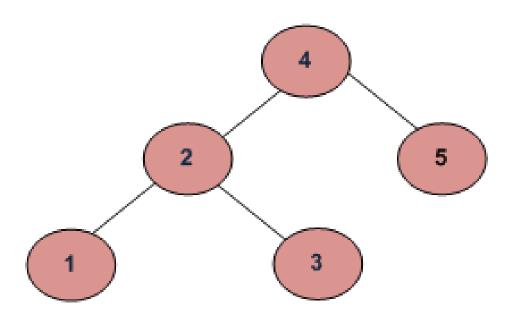
Binary Search Tree - Applications

SWE2016-44



Properties of BST

- 1) The left subtree of a node contains nodes with keys less than the node's key and the right subtree with keys greater than node's key.
- 2) The left and right subtree each must also be a binary search tree and there must be no duplicate nodes.

Method 1: Simple but Wrong

For each node, check if the left node of it is smaller than the node and right node of it is greater than the node.

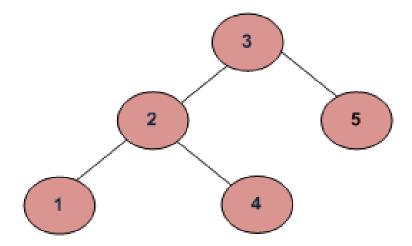
Method 1: Simple but Wrong

```
int isBST(struct node* node)
  if (node == NULL)
    return 1;
  if (node->left != NULL && node->left->data > node->data)
    return 0;
  if (node->right != NULL && node->right->data < node->data)
    return 0;
  if (!isBST(node->left) || !isBST(node->right))
    return 0;
  return 1;
```

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 if (!isBST(node->left) || !isBST(node->right))
    return 0;
  return 1;
```

→This approach is wrong as this will return true for below binary tree



Method 2: Correct but not efficient

For each node, check if max value in left subtree is smaller than the node and min value in right subtree greater than the node.

Method 2: Correct but not efficient

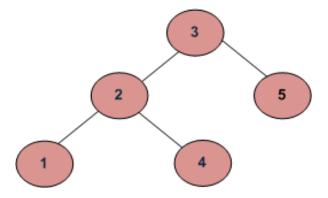
```
int isBST(struct node* node)
  if (node == NULL)
    return(true);
  if (node->left!=NULL && maxValue(node->left) > node->data)
    return(false);
  if (node->right!=NULL && minValue(node->right) < node->data)
    return(false);
  if (!isBST(node->left) || !isBST(node->right))
    return(false);
  return(true);
```

 It is assumed that you have helper functions minValue() and maxValue() that return the min or max int value from a nonempty tree

Method 2: Correct but not efficient

```
int isBST(struct node* node)
  if (node == NULL)
    return(true);
  if (node->left!=NULL && maxValue(node->left) > node->data)
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    return(false);
  if (!isBST(node->left) || !isBST(node->right))
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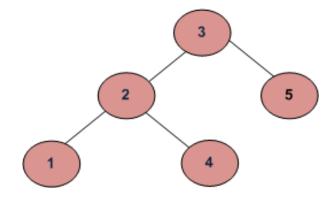
→ Avoid the following:



Method 2: Correct but not efficient

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int isBST(struct node* node)
  if (node == NULL)
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  return(true);
```

→ Avoid the following:



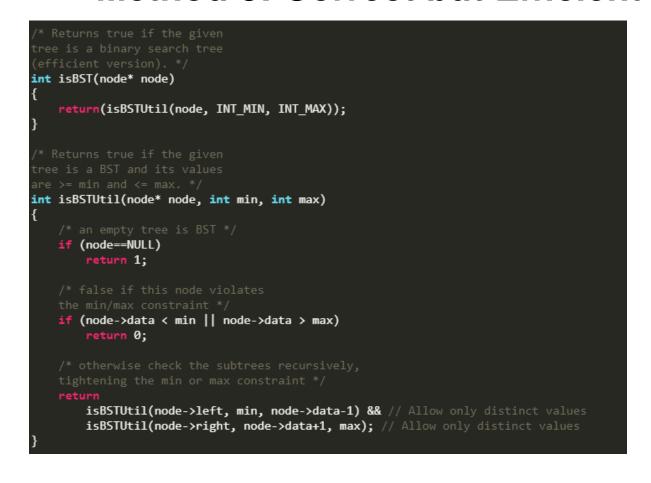
- → It traverses over some parts of the tree many times
- → Time Complexity: O(n*n)

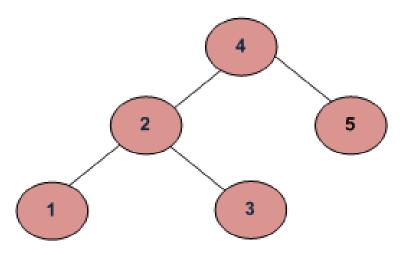
Method 3: Correct but Efficient

Write a utility helper function is BSTUtil(struct node* node, int min, int max) that traverses down the tree keeping track of the narrowing min and max allowed values as it goes, looking at each node only once.

The initial values for min and max should be INT_MIN and INT_MAX — they narrow from there.

Method 3: Correct but Efficient





Method 3: Correct but Efficient

```
int isBST(node* node)
   return(isBSTUtil(node, INT MIN, INT MAX));
int isBSTUtil(node* node, int min, int max)
    if (node==NULL)
       return 1;
   if (node->data < min || node->data > max)
       return 0;
       isBSTUtil(node->left, min, node->data-1) && // Allow only distinct values
       isBSTUtil(node->right, node->data+1, max); // Allow only distinct values
```

- Time Complexity: O(n)
- Auxiliary Space : O(1) if Function
 Call Stack size is not considered,
 otherwise O(n)

Method 4: Using Inorder Traversal

- 1) Do In-Order Traversal of the given tree and store the result in a temp array.
- 2) Check if the temp array is sorted in ascending order, if it is, then the tree is BST.

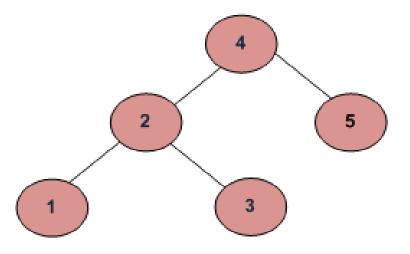
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- 1) Do In-Order Traversal of the given tree and store the result in a temp array.
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→ We can avoid the use of Auxiliary Array. While doing In-Order traversal, we can keep track of previously visited node. If the value of the currently visited node is less than the previous value, then tree is not BST.

Method 4: Using Inorder Traversal

```
bool isBST(node* root)
    static node *prev = NULL;
    if (root)
        if (!isBST(root->left))
        return false;
        if (prev != NULL &&
            root->data <= prev->data)
        return false;
        prev = root;
        return isBST(root->right);
    return true;
```



Method 4: Using Inorder Traversal

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- Time Complexity: O(n)
- Auxiliary Space : O(1)

Method	Correctness	Time Complexity
Method 1	Incorrect	O(n)
Method 2	Correct but inefficient	O(n*n)
Method 3	Correct and efficient	O(n)
Method 4 (using in-order Traversal)	Correct and efficient	O(n)

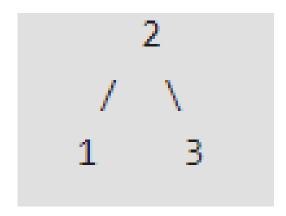
Given a sorted array. Write a function that creates a Balanced Binary Search Tree using array elements.

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Example 1:

Input array: {1, 2, 3}

Output Balanced BST

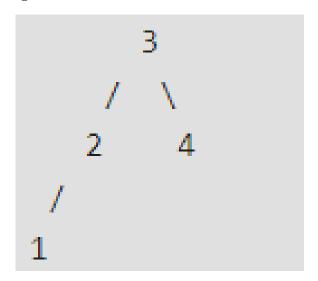


Given a sorted array. Write a function that creates a Balanced Binary Search Tree using array elements.

Example 2:

Input array: {1, 2, 3, 4}

Output Balanced BST



Given a sorted array. Write a function that creates a Balanced Binary Search Tree using array elements.

Solution:

1. Get the middle of the array and make it root

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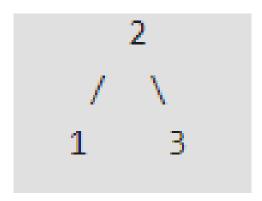
Solution:

- 1. Get the middle of the array and make it root
- 2. Recursively do the same for left and right halves
 - Get the middle of left half and make it left child of the root created in step 1
 - Get the middle of right half and make it right child of the root created in step 1

Given a sorted array. Write a function that creates a Balanced Binary Search Tree using array elements.

Consider Example 1:

Input array: {1, 2, 3}



Here, the middle element of the sorted array is 2 This is made the root of the required BST

```
/* A function that constructs Balanced
Binary Search Tree from a sorted array */
TNode* sortedArrayToBST(int arr[],
                        int start, int end)
   /* Base Case */
    if (start > end)
    return NULL;
   /* Get the middle element and make it root */
    int mid = (start + end)/2;
    TNode *root = newNode(arr[mid]);
    /* Recursively construct the left subtree
    and make it left child of root */
   root->left = sortedArrayToBST(arr, start,
                                    mid - 1);
    /* Recursively construct the right subtree
   and make it right child of root */
    root->right = sortedArrayToBST(arr, mid + 1, end);
    return root;
```

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Following is the recurrence relation for the function:

$$T(n) = 2T(n/2) + C$$

- T(n): Time taken for an array of size n
- C: Constant (Finding middle of array and linking root to left and right subtrees take constant time)

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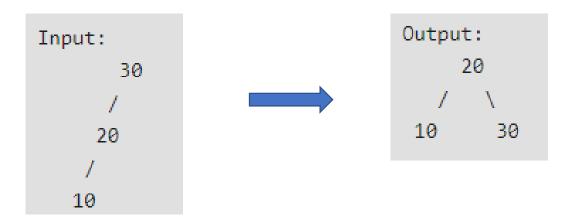
- T(n): Time taken for an array of size n
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Solving it using Master's theorem, we get the time complexity as O(n).

Given a BST (Binary Search Tree) that may be unbalanced, convert it into a balanced BST that has minimum possible height.

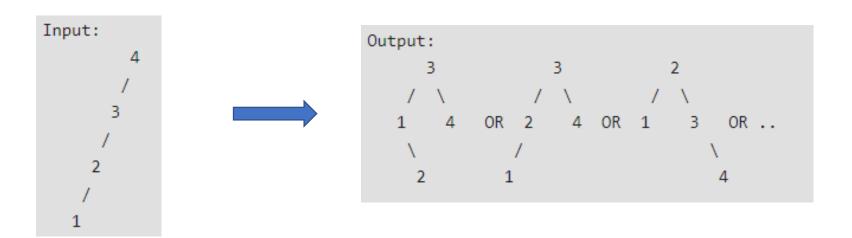
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- An Efficient Solution can construct balanced BST in O(n) time with minimum possible height. Below are steps.
 - 1. Traverse given BST in inorder and store result in an array. This step takes O(n) time. This array would be sorted as inorder traversal of BST always produces sorted sequence.
 - 2. Build a balanced BST from the above created sorted array using the recursive approach. This step also takes O(n) time as we traverse every element exactly once and processing an element takes O(1) time.

Merge Two Balanced Binary Search Trees

You are given two balanced binary search trees. Write a function that merges the two given balanced BSTs into a balanced binary search tree. Let there be m elements in first tree and n elements in the other tree. Your merge function should take O(m+n) time.

Method 1: Insert elements of first tree to second

Take all elements of first BST one by one, and insert them into the second BST

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- → The value of this expression will be between mLog(n) and mLog(m+n-1)

We can pick the smaller tree as first tree.

Method 2: Merge Inorder Traversals

1) Do inorder traversal of first tree and store the traversal in one temp array arr1[]. This step takes O(m) time.

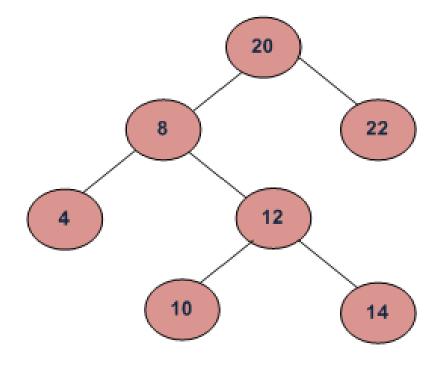
- 1) Do inorder traversal of first tree and store the traversal in one temp array arr1[]. This step takes O(m) time.
- 2) Do inorder traversal of second tree and store the traversal in another temp array arr2[]. This step takes O(n) time.

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- Do inorder traversal of second tree and store the traversal in another temp array arr2[]. This step takes O(n) time.
- 3) The arrays created in step 1 and 2 are sorted arrays. Merge the two sorted arrays into one array of size m + n. This step takes O(m+n) time.

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- 2) Do inorder traversal of second tree and store the traversal in another temp array arr2[]. This step takes O(n) time.
- 3) The arrays created in step 1 and 2 are sorted arrays. Merge the two sorted arrays into one array of size m + n. This step takes O(m+n) time.
- 4) Construct a balanced tree from the merged array using the technique discussed in this post. This step takes O(m+n) time.

Given root of binary search tree and K as input, find K-th smallest element in BST.

For example, in the following BST, if k = 3, then output should be 10, and if k = 5, then output should be 14.



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Inorder traversal of BST retrieves elements of tree in the sorted order.

Time complexity: O(n) where n is total nodes in tree

Given root of binary search tree and K as input, find K-th smallest element in BST.

Method 2: Augmented Tree Data Structure

Given root of binary search tree and K as input, find K-th smallest element in BST.

Method 2: Augmented Tree Data Structure

The idea is to maintain rank of each node. We can keep track of elements in a subtree of any node while building the tree. Since we need K-th smallest element, we can maintain number of elements of left subtree in every node.

Given root of binary search tree and K as input, find K-th smallest element in BST.

Method 2: Augmented Tree Data Structure

Assume that the root is having N nodes in its left subtree.

- If K = N + 1, root is K-th node.

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Assume that the root is having N nodes in its left subtree.

- If K = N + 1, root is K-th node.
- If K < N, we will continue our search (recursion) for the Kth smallest element in the left subtree of root.

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- If K = N + 1, root is K-th node.
- If K < N, we will continue our search (recursion) for the Kth smallest element in the left subtree of root.
- If K > N + 1, we continue our search in the right subtree for the (K − N − 1)-th smallest element.

Given root of binary search tree and K as input, find K-th smallest element in BST.

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- If K = N + 1, root is K-th node.
- If K < N, we will continue our search (recursion) for the Kth smallest element in the left subtree of root.
- If K > N + 1, we continue our search in the right subtree for the (K − N − 1)-th smallest element.
- Note that we need the count of elements in left subtree only.

Given root of binary search tree and K as input, find K-th smallest element in BST.

Method 2: Augmented Tree Data Structure

```
start:
if K = root.leftElement + 1
    root node is the K th node.
    goto stop
else if K > root.leftElements
    K = K - (root.leftElements + 1)
    root = root.right
    goto start
else
    root = root.left
    goto start
stop:
```

Given root of binary search tree and K as input, find K-th smallest element in BST.

Method 2: Augmented Tree Data Structure

Time complexity: O(h) where h is height of tree.

Reference

• https://www.geeksforgeeks.org