

MSc AI Dissertation Project Proposal Form

Student number	201602374	Date	13/02/2025	
Student name	Joshua Hellewell			
Supervisor name	Chandrasekhar Kambhampati			
Project title:	Enabling Sample Efficient Design Space Exploration through Machine Learning			
Project description – background, aims, objectives, research question(s), brief reflection on novelty/originality				

♥® ★ **%** UNIVERSITY OF HULL

Engineering is propelled by effective design space exploration and optimisation. As is common, numerical tools are used to substitute expensive physical testing; for example, computational fluid dynamics can, by solving physical numerical equations, provide engineers with flow field information such as surface pressure fields and velocity fields. Such simulations are often computationally expensive and not optimised for fast, iterative design exploration, which can be partly attributed to the input geometries (unstructured mesh files, point clouds, etc.) not lending themselves to simple parameterisation that would enable an interpretable representation of complex features and geometries. In the absence of such a concise description of how shapes are related, design space exploration and optimisation is constrained to a high-dimensional landscape, inheriting computational challenges and falling victim to the curse of dimensionality, which suppresses efficient design exploration. Complex shapes, such as those found in typical aerodynamic applications, can be composed of millions of elements described by vertices, edges, and faces, and therefore exploring all combinations is computationally infeasible. Having a lowdimensional representation of complex shapes that concisely represents the defining features and nuances enables optimisation methods such as grid search, Monte-Carlo methods, or gradientbased optimisation to be performed more efficiently. This research aims to investigate, compare and assess different approaches to addressing this high-dimensional challenge.

Despite many industry problems residing in the 3D space, the computational burden and data availability introduce unnecessary challenges that detract from the underlying concepts to be investigated in this research, and for that reason, this research will focus on 2D geometries and a simplified optimisation problem. Though the underlying principles are agnostic of the specific problem statement.

Objectives:

- Investigate techniques and approaches for representing geometry in a low dimensional form to enable sample efficient design space optimisation and carry out a comprehensive literature review of existing methods, to both the representation problem, and optimisation approaches.
- Develop approaches for representing a 2D geometries in in a lower dimensional space that
 can be used directly as part of a geometric shape optimisation problem and investigate the
 structure and smoothness of the learned geometry representations and their suitability for
 use in different optimisation approaches.
- The research will assess which approaches to geometry representation provide the most interpretable and controllable representation that can be harnessed to conduct targeted design modification and optimisation for the selected optimisation problem.

In addition to investigating methods for compressing the high-dimensional complexity of geometries, we will deploy the learned representations to a simple 2D optimisation problem, area to perimeter ratio — which may be perceived as the 2D equivalent of surface area to volume ratio, which is often used as a parameter to indicate heat losses; however, this approach could be extended to other industry problems, such as optimising the lift to drag ratio for an airfoil. The quantify of interest to be optimised will be labelled as compactness, and described by:

$$Compactness = \frac{Perimeter}{Area}$$

For example, for a circle, this is trivial as a circle can be described by a single parameter r – therefore the 'design space' is a single variable over parameterised by r . The below equation for



compactness of a circle allows us to make statements such as 'if we increase radius, r, the compactness will decrease' as the single parameter r is inversely proportional to the compactness. This allows a targeted modification of the design by adjusting just r (assuming we constrain ourselves to circles).

$$Compactness = \frac{2 \pi r}{\pi r^2} = 2 \frac{\pi}{r}$$

In contrast, some arbitrarily complex shape with a combination of smooth edges and straight sides with no constraint on being a specific shape group (quadrilateral, triangle etc) is not easily parameterised by a small number of variables and without significant constraints, the design space is highly complex. For this reason, the above 'compactness' cannot be easily interpreted in the same way as the circle statement. The motivation of this research is to enable a concise descriptor of the way in which arbitrary 2D shapes relate to each other by realisation of an intermediatory, low-dimensional representation learned from data that provides latent variables, i.e., tuneable variables, that describe a smooth transition between different shapes. In doing so, we provide a means to reduce the high-dimensional design space which better lends itself to optimisation approaches.

Methodology – rationale, data selection and collection, recruitment of participants, analytical process

The project will be conducted by firstly identifying a comprehensive dataset of 2D shapes that will be used to represent the geometry space, albeit simplified into the 2D domain to avoid computational limitations associated with data formats such as voxel grids, point clouds and mesh grids. Optionally, the UIUC 2D aerofoil dataset may be used, however, this dataset is smaller and spans a more similar library of geometries (i.e., all aerofoils). For 2D shapes, the representation of original data can be structured as pixels like in images – the sparse connectivity of such data makes the project appropriately tractable vs. computationally intensive structures such as point clouds, mesh and voxels.

All data will be stored locally and processed using Python. Specifically, for working with ML models the data will be stored as .h5 files for efficient storage and access. Any neural network models will be built using Metas' PyTorch architecture, and training using the CUDA implementation for efficient, parallelised model training. The 2D shape data will be represented as images to enable a structured representation of the shapes. These will be stored as numpy arrays, or tensors depending on selected models.

A literature review will be carried out that investigates techniques for representing high dimensionality data a low dimensional form in addition to methods for design exploration and optimisation methods that can be used for engineering design.

Theoretical framework and intended tools/technologies



Generative models may include Auto-encoders, Variational Auto-encoders, Denoising Auto-encoders, Sparse Auto-encoders, Contractive Auto-encoders. Generative Adversarial Networks. Implicit Neural Representations, Diffusion models.

Design space exploration may investigate methods such as: grid search, monte Carlo methods, Markov chain monte Carlo with optimisation techniques such as gradient-based optimisation and genetic algorithms (Gupta et al, 2007).

Python, PyTorch, Cuda, JAX, NVIDIA GPU, Viper HPC

Key literature identified for literature review (include references)

♥® ★ ***** UNIVERSITY OF HULL

Park, J. J., Florence, P., Straub, J., Newcombe, R., & Lovegrove, S. (2019). Deepsdf: Learning continuous signed distance functions for shape representation. *Proceedings of the IEEE Computer Society Conference on Computer Vision and Pattern Recognition*, 2019-June. https://doi.org/10.1109/CVPR.2019.00025

Zhu, Z., Wang, X., Bai, S., Yao, C., & Bai, X. (2016). Deep Learning Representation using Autoencoder for 3D Shape Retrieval. *Neurocomputing*, *204*. https://doi.org/10.1016/j.neucom.2015.08.127

Li, P., Pei, Y., & Li, J. (2023). A comprehensive survey on design and application of autoencoder in deep learning. In *Applied Soft Computing* (Vol. 138). https://doi.org/10.1016/j.asoc.2023.110176

Sun, JM., Wu, T. & Gao, L. Recent advances in implicit representation-based 3D shape generation. Vis. Intell. 2, 9 (2024). https://doi.org/10.1007/s44267-024-00042-

Sharp, N., Attaiki, S., Crane, K., & Ovsjanikov, M. (2022). DiffusionNet: Discretization Agnostic Learning on Surfaces. *ACM Transactions on Graphics*, *41*(3). https://doi.org/10.1145/3507905

Wu, Z., Song, S., Khosla, A., Yu, F., Zhang, L., Tang, X., & Xiao, J. (2015). 3D ShapeNets: A deep representation for volumetric shapes. *Proceedings of the IEEE Computer Society Conference on Computer Vision and Pattern Recognition*, 07-12-June-2015, 1912–1920. https://doi.org/10.1109/CVPR.2015.7298801

Qi, C. R., Su, H., Mo, K., & Guibas, L. J. (2017). PointNet: Deep learning on point sets for 3D classification and segmentation. *Proceedings - 30th IEEE Conference on Computer Vision and Pattern Recognition, CVPR 2017, 2017-January,* 77–85. https://doi.org/10.1109/CVPR.2017.16

Tripp, A., Daxberger, E., & Hernández-Lobato, J. M. (2020). Sample-efficient optimization in the latent space of deep generative models via weighted retraining. *Advances in Neural Information Processing Systems*, 2020-December.

Zhen Wei, Edouard R. Dufour, Colin Pelletier, Pascal Fua and Michaël Bauerheim (2024). Diffairfoil: An efficient novel airfoil sampler based on latent space diffusion model for aerodynamic shape optimization. *AIAA AVIATION FORUM AND ASCEND 2024*, July 2024.

Zheng, L., Karapiperis, K., Kumar, S., & Kochmann, D. M. (2023). Unifying the design space and optimizing linear and nonlinear truss metamaterials by generative modeling. *Nature Communications*, *14*(1). https://doi.org/10.1038/s41467-023-42068-x

Long, L., Cartis, C., & Shustin, P. F. (2024). Dimensionality Reduction Techniques for Global Bayesian Optimisation. arXiv preprint arXiv:2412.09183.

Wu, J., Zhang, C., Xue, T., Freeman, W. T., & Tenenbaum, J. B. (2016). Learning a probabilistic latent space of object shapes via 3D generative-adversarial modeling. *Advances in Neural Information Processing Systems*.

Siivola, E., Paleyes, A., González, J., & Vehtari, A. (2021). Good practices for Bayesian optimization of high dimensional structured spaces. In *Applied AI Letters* (Vol. 2, Issue 2). https://doi.org/10.1002/ail2.24

Danhaive, R., & Mueller, C. T. (2021). Design subspace learning: Structural design space exploration using performance-conditioned generative modeling. *Automation in Construction*, 127. https://doi.org/10.1016/j.autcon.2021.103664

♥® ★ **%** UNIVERSITY OF HULL

Gupta, S., Tiwari, R., & Nair, S. B. (2007). Multi-objective design optimisation of rolling bearings using genetic algorithms. *Mechanism and Machine Theory*, *42*(10). https://doi.org/10.1016/j.mechmachtheory.2006.10.002

Sun, J., Frazer, J. H., & Mingxi, T. (2007). Shape optimisation using evolutionary techniques in product design. *Computers and Industrial Engineering*, *53*(2). https://doi.org/10.1016/j.cie.2007.06.010

Demo, N., Ortali, G., Gustin, G., Rozza, G., & Lavini, G. (2021). An efficient computational framework for naval shape design and optimization problems by means of data-driven reduced order modeling techniques. *Bolletino Dell Unione Matematica Italiana*, *14*(1). https://doi.org/10.1007/s40574-020-00263-4

Laurenceau, J., Meaux, M., Montagnac, M., & Sagaut, P. (2010). Comparison of gradient-based and gradient-enhanced response-surface-based optimizers. *AIAA Journal*, *48*(5). https://doi.org/10.2514/1.45331

Catalani, G., Agarwal, S., Bertrand, X. *et al.* Neural fields for rapid aircraft aerodynamics simulations. *Sci Rep* **14**, 25496 (2024). https://doi.org/10.1038/s41598-024-76983-w

Kang, E., Jackson, E., & Schulte, W. (2011). An approach for effective design space exploration. *Lecture Notes in Computer Science (Including Subseries Lecture Notes in Artificial Intelligence and Lecture Notes in Bioinformatics)*, 6662 LNCS. https://doi.org/10.1007/978-3-642-21292-5 3

Selig, Michael S. (1996). UIUC airfoil data site. Urbana, Ill.: Department of Aeronautical and Astronautical Engineering University of Illinois at Urbana-Champaign,

UIUC. 2025. UIUC Applied Aerodynamic Group – UIUC Airfoil Coordinates Database. Retrieved March 4, 2025 from https://m-selig.ae.illinois.edu/ads/coord_database.html

Industrial partner (if appropriate)

Rolls-Royce,

Mark Hobbs — Mark.Hobbs@Rolls-Royce.com | Technical Specialist Future Methods

Project management

♥® ★ ***** UNIVERSITY OF HULL

Table: Project timeline and key outputs (expand table as needed)

Week	Activity	
Week 1 – w/c 10.03.25	Submit Proposal	
Week 1	Ethics approval form	
Week 2-4	Review literature on geometry representation	
Week 4-6	Review literature for shape optimisation in low-dimensional space.	
Week 2-6	Identify main gaps and establish problem statement(s)	
Week 5	Milestone: Produced literature matrix.	
Week 5	Create MSc thesis report structure.	
Week 5	Define methodology and research approach.	
Week 4-7	Write literature review	
Week 6-7	Write up metholodogy	
Week 7	Milestone: Literature review draft completed.	
Week 2-3	Collect or generate 2D shape dataset.	
Week 3-4	Pre-process data (resizing, augmentation, normalisation).	
Week 4-5	Define evaluation metric for low-dimensional representation.	
Week 5	Milestone: 2D shape dataset & processed.	
Week 6	Create GitHub project structure for model comparison.	
Week 6-9	Create geometry representation models/methods in Python.	
Week 8-10	Train & Validate techniques to obtain low-dimensional geometry	
	embeddings.	
Week 8-10	Assess smoothness, interpretability and effectiveness of	
	representations.	
Week 10	Milestone: Geometry Representation techniques tested.	
Week 9-11	Create optimisation technique scripts.	
Week 11-13	Integrate learned representations into compactness optimisation	
	framework.	
Week 13-14	Evaluate effectiveness of different representations for optimisation	
	task.	
Week 14	Milestone: Integrated geometry representation and design	
	exploration.	
Week 14-18	Draft final dissertation, including results & discussion.	
Week 19-21	Review & edit final report.	
Week 21 – w/c	Milestone: Dissertation submitted.	
11.08.25		

^{***}See table on page 9 for full project plan.

Resources and Research Data Management Plan (Describe the resources required and the data you expect to acquire or generate during this research project, how you will manage, describe, analyse, and store the data and what mechanisms you will use to share and preserve your data.)



Project will be managed in a GitHub repository:

https://github.com/jhell1717/MScProject2025/tree/Planning

All models will be updated and shared via this repository with the final selected model for geometry encoding being packaged into a Python package that a user can deploy on their own local machine through a pip install from the GitHub repo.

Many industry-relevant problems exhibit complex failure behaviour influenced by multiple factors that may not be apparent or comprehensible. Consequently, to avoid distracting from the underlying principles, the data will be simplified to two-dimensional geometric shapes. Adding additional complexity cannot be reasonably justified in accordance with the objectives of this research and risks obscuring the predictive accuracy and performance of selected models in isolation of challenge-problem induced error sources.

Planned outputs/publications/research datasets/impact/dissemination

The output from this research will be a comprehensive study of methods that sample efficient design space exploration.

Proceeding a comparison of different methods for reducing high-dimensional challenges to low dimensional sample space, deployment to a simple optimisation will be performed. This is likely to be compactness of a 2D shape, as a pseudo metric for heat losses in physical components.

A literature review of existing approaches will be performed, along with a substantial research paper documenting methodologies, results, discussions, limitations, conclusions and recommendations for methods that should be extended to industry specific use-cases.

The best performing model will be selected and produced as a tool that a practitioner could install locally to aid their design space exploration and optimisation.

