

# Machine Learning

## Clustering

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# Outline

Unsupervised learning

k-means clustering

Hierarchical clustering

DBSCAN

# Supervised learning

So far we have seen supervised learning, where,

- ▶ Pairs  $\{\mathbf{x}^{(n)}, y^{(n)}\}_{n=1}^N$  of input and output data.
- ▶ Goal: learn a model  $\hat{y}^{(n)} = f(\mathbf{x}^{(n)}; \Omega)$ .
- ▶ Such that  $\mathcal{L}(y^{(n)}, \hat{y}^{(n)}) \approx 0$ .

# Unsupervised learning

Let's see now a few models for unsupervised learning.

- ▶ No labels  $y^{(n)}$  for training, i.e., only  $\{\mathbf{x}^{(n)}\}_{n=1}^N$ .
- ▶ We do not learn a mapping function.
- ▶ Rather, we try to make sense of  $\{\mathbf{x}^{(n)}\}$ .
- ▶ Discover hidden structures on data.
- ▶ Examples: clustering, dimensionality reduction.

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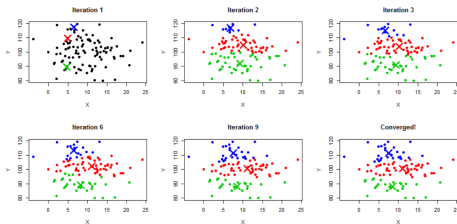
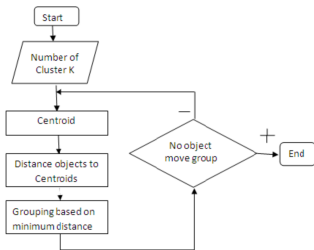
DBSCAN

# Intuition

- ▶ Find  $k$  groups (clusters) of similar objects
- ▶ Easy to understand and to implement.
- ▶ Prototype-based approach (each cluster is represented by a prototype sample, a.k.a., *centroid*).

# Method

1. Randomly pick  $k$  centroids.
2. Assign each point to its closest centroid.
3. Move the centroids to the center of each cluster.
4. Repeat 2., and 3., until convergence.



# Considerations

## Distance metric

Euclidean is the most used.

$$d(\mathbf{x}, \mathbf{y}) = \sum_{n=1}^N (x_n - y_n)^2.$$

## Variants

- ▶ k-medoids: Manhattan distance, median point as centroid.
- ▶ fuzzy C-means: soft assignment (probability distribution).

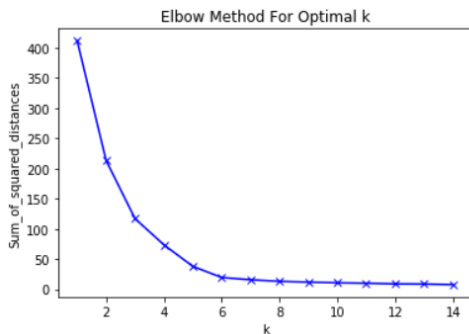


## Validate quality

Given that there is no ground truth label  $y$ , it is difficult to tell whether the clustering algorithm is doing well. Use inspection.

### Elbow curve

Try different values of  $k$ , then pick the one value where the *purity* of the clusters is no longer improved.



# Silhouette score

Gives an idea of how tightly grouped the clusters are.

Per each sample  $\mathbf{x}^{(i)}$ , compute,

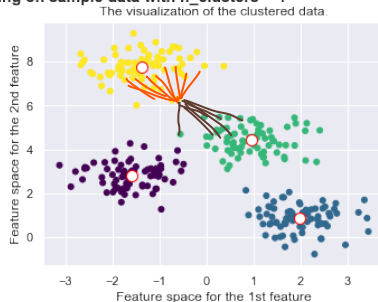
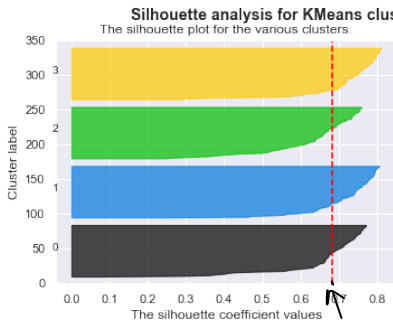
1. Cohesion  $a^{(i)}$ : average distance between the sample  $\mathbf{x}^{(i)}$  and all other points in the same cluster.
2. Separation  $b^{(i)}$ : average distance between the sample  $\mathbf{x}^{(i)}$  and all samples in the nearest cluster.
3. Silhouette  $s^{(i)}$ :

$$s^{(i)} = \frac{b^{(i)} - a^{(i)}}{\max\{b^{(i)}, a^{(i)}\}}.$$

$s$  can take values between  $[-1, 1]$ . The higher the better.

# Silhouette plot

Silhouette scores can be plotted for comparison.



**Note:** both elbow and silhouette, can be used for most clustering methods.

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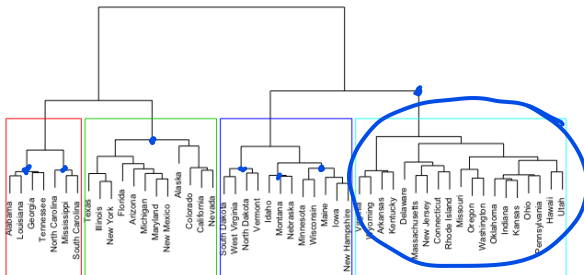
k-means clustering

Hierarchical clustering

DBSCAN

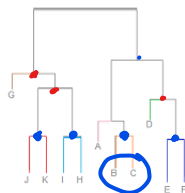
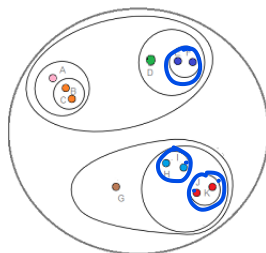
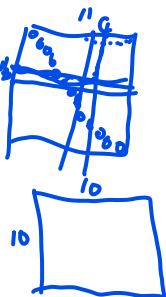
# Intuition

- ▶ Dendrogram (tree-like) visualization.
- ▶ No need to define the number of clusters a priori.
- ▶ We can selected by inspection.
- ▶ Can be agglomerative or divisive.



# Method

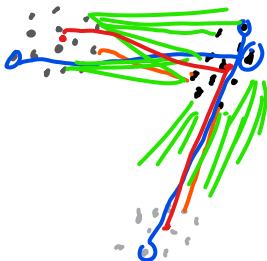
1. Compute distance matrix for all samples.
2. Represent each point as a singleton cluster.
3. Merge the two closest clusters, based on a linkage strategy.
4. Update distance matrix.
5. Repeat 2., 3., 4., until only one single cluster is left.



## Linkage strategies

Distance between clusters can be defined as,

- ▶ Single: the distance between their closest members.
- ▶ Complete: the distance between their farthest members.
- ▶ Average: the average distance between each pair of members.
- ▶ Ward: the distance between their centroids.



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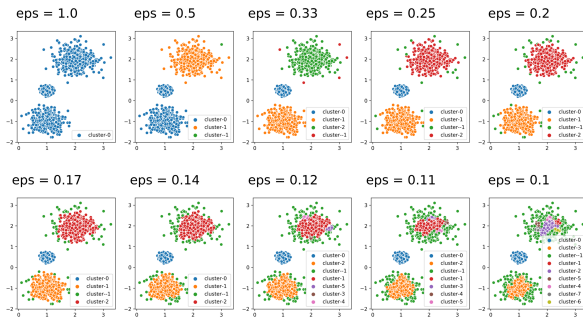
DBSCAN



# Intuition

Density-based Spatial Clustering of Applications with Noise (DBSCAN).

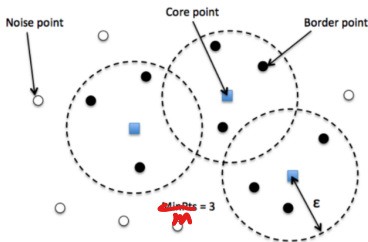
- ▶ Define how densely populated clusters must be.
- ▶ Density: number of points within a radius  $\epsilon$ .



# Method, I

Define,

1. **core points**: if at least  $m$  neighboring points fall within radius  $\epsilon$ .
2. **border points**: if it has fewer neighboring points than  $m$  within radius  $\epsilon$ , but lies within the radius of a core point.
3. **noise points**: all points that are neither core nor border points.



## Method, II

After initial definition, continue with,

1. Form a separate cluster for each core point, or a connected group of core points (core points are connected if they are no farther away than  $\epsilon$ ).
2. Assign each border point to the cluster of its corresponding core point.
3. All non-assigned points end up marked as outliers.



# Other methods

- ▶ Affinity propagation. ✓
- ▶ Spectral clustering. ✓
- ▶ Mean shift. ✓
- ▶ Fuzzy C-means. ✓

# Q&A

Thank you!

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