

PRES

ENTATION

- <https://www.youtube.com/watch?v=ApPPQpkoe-4>



CMPE322 A1: CONCEPTUAL ARCHITECTURE

Group 20:

Group Leader: Jordan Herzstein

*Christopher Seguin Bianchi, Laurie Yuzichuk, Cameron
Bennett*

Presenters:

Jasper Lim, Campbell Love



- Open-source, multiplatform flight simulator
- Used by NASA and the FAA for standards and in training modules
- Started in 1997
- Client-Server Architecture

FLIGHTGEAR



OVERVIEW |

System Functionality	Concurrency
System Evolution	Division of Responsibilities
Data Flow and Control	Lessons learned
Use Cases	Conclusion

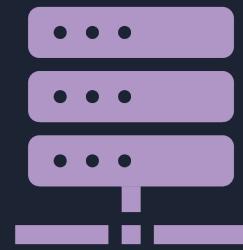


DERIVATION PROCESS

Consulted wiki, documentation, official website, general publications on flight simulators. Concluded FlightGear has an architecture that is a combination of:



Model-View-Controller
Architecture,



High-Level
Architecture,



and Client-Server
Architecture.



SYSTEM FUNCTIONALITY

Was redesigned to better use parallelism

Now features a Model-View-Controller Architecture

Split into 2 main components: the FDM Server, and the client

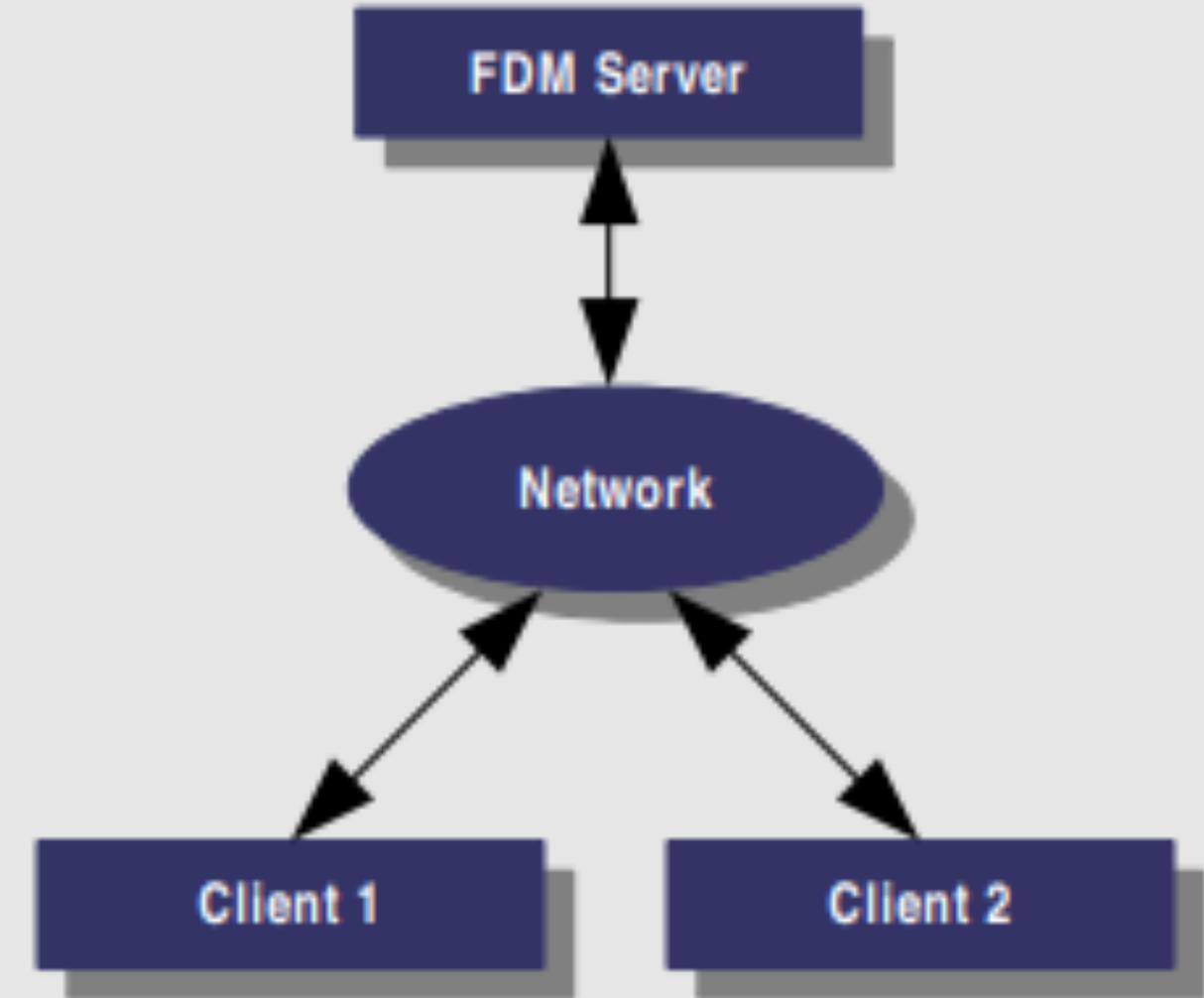


Figure 1-An example of a setup where multiple users can inhabit a single aircraft and operate its controls.



FDM SERVER

- Main calculations of the flight models and core simulation tasks, including the computation of flight dynamics and the management of environmental variables.
- Multiplayer settings as well as shared AI traffic data across sessions.



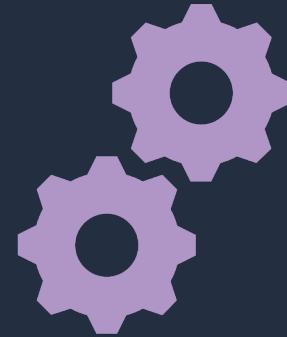
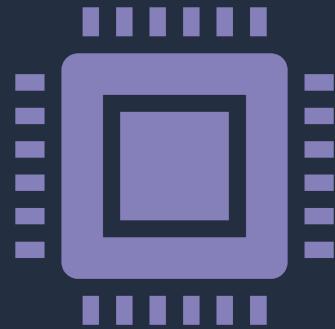
FDM CLIENT

- Interface between the user and the simulation by handling input/output operations as well as rendering the simulation's visual and audio components.
- It handles communications with the FDM server to reflect real-time changes in the simulation state, ensuring that user inputs directly influence the flight dynamics.



COM4		ARDU IMU			GPI Refresh Rate	
Connected/Disconnected		IMU ArduPilot 2.7 Beta 0			200	
Latitude	37.62471	MSG CUR:	0	0		
Longitude	-122.38629	MSG_NWFL	472616000	113560640		115000
Altitude	301.74	MSG_Rate in A	1500	E 1500	T 1100 R 1500	
Pitch	0.741	MSG_CUR:	0	0		
Roll	11.128	MSG_NWFL	472616000	113560640		115000
Heading	33.917	MSG_AUTO				
Attitude Output		msgRAW	113			
Roll	0.054	MSG_Status:	0			
Pitch	0.003	MSG_CUR:	0	0		
Yaw	0.911	MSG_NWFL	472616000	113560640		115000
Throttle	1.000	MSG_Checksum:				
Adjusted Status		Simulator Authority - For all planes			Save Settings	
WP Cur	1126	WP Cur:	1000			
Bearing Err	3.38	Roll Cur:	3000			
Altitude Err	293.94	Pitch Cur:	3000			
WP E	Mode: Auto	Roll Err:	3000			
Throttle		Pitch Err:	3000			
		Throttle Cur:	100			

SYSTEM EVOLUTION



There are two forms of developers, core developers and open or 'normal' developers.

System architecture is built upon a modular design. Modules include aircraft models, scenery databases, user interface components, etc.



DATA FLOW AND CONTROL

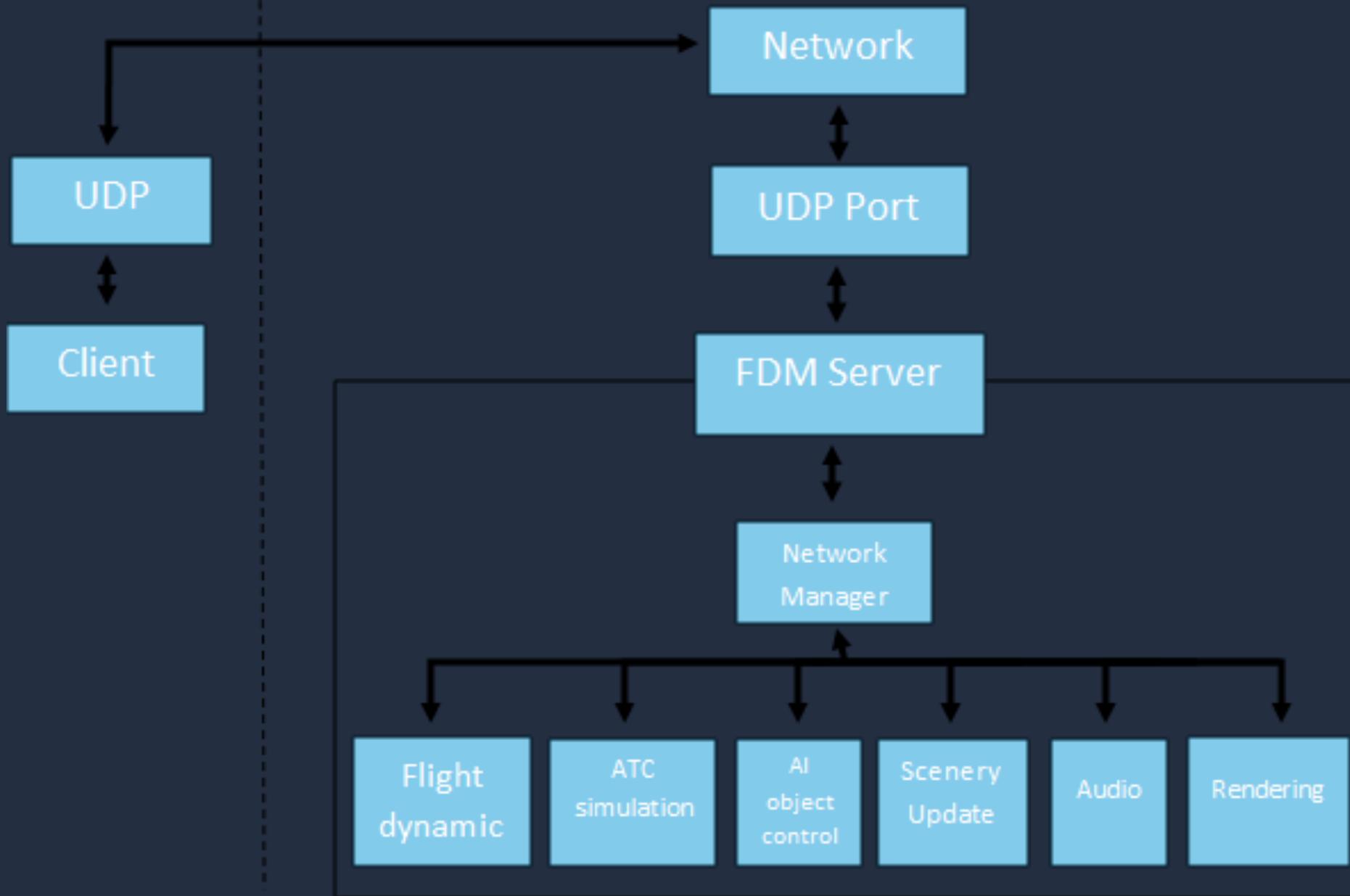
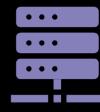


Figure 2: Diagram of FlightGear's Data Flow and Control Flow



DATA FLOW AND CONTROL



Through UDP Ports, the client/user and FDM server connect to a network. There, changes can be uploaded to and from one another and allow for either side to react accordingly.



DATA FLOW AND CONTROL

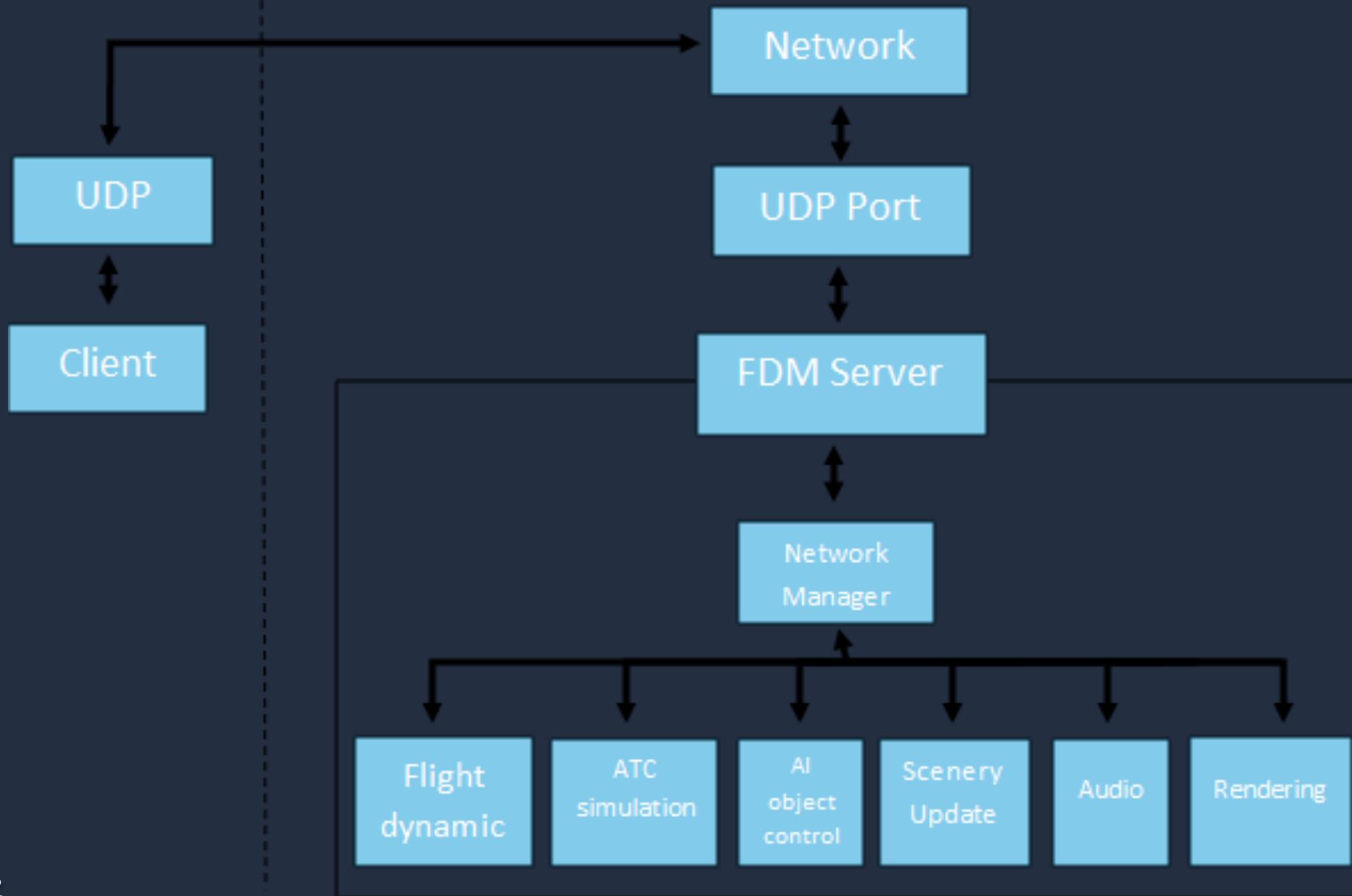
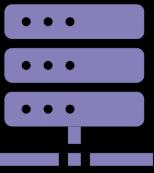


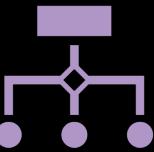
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DATA FLOW AND CONTROL

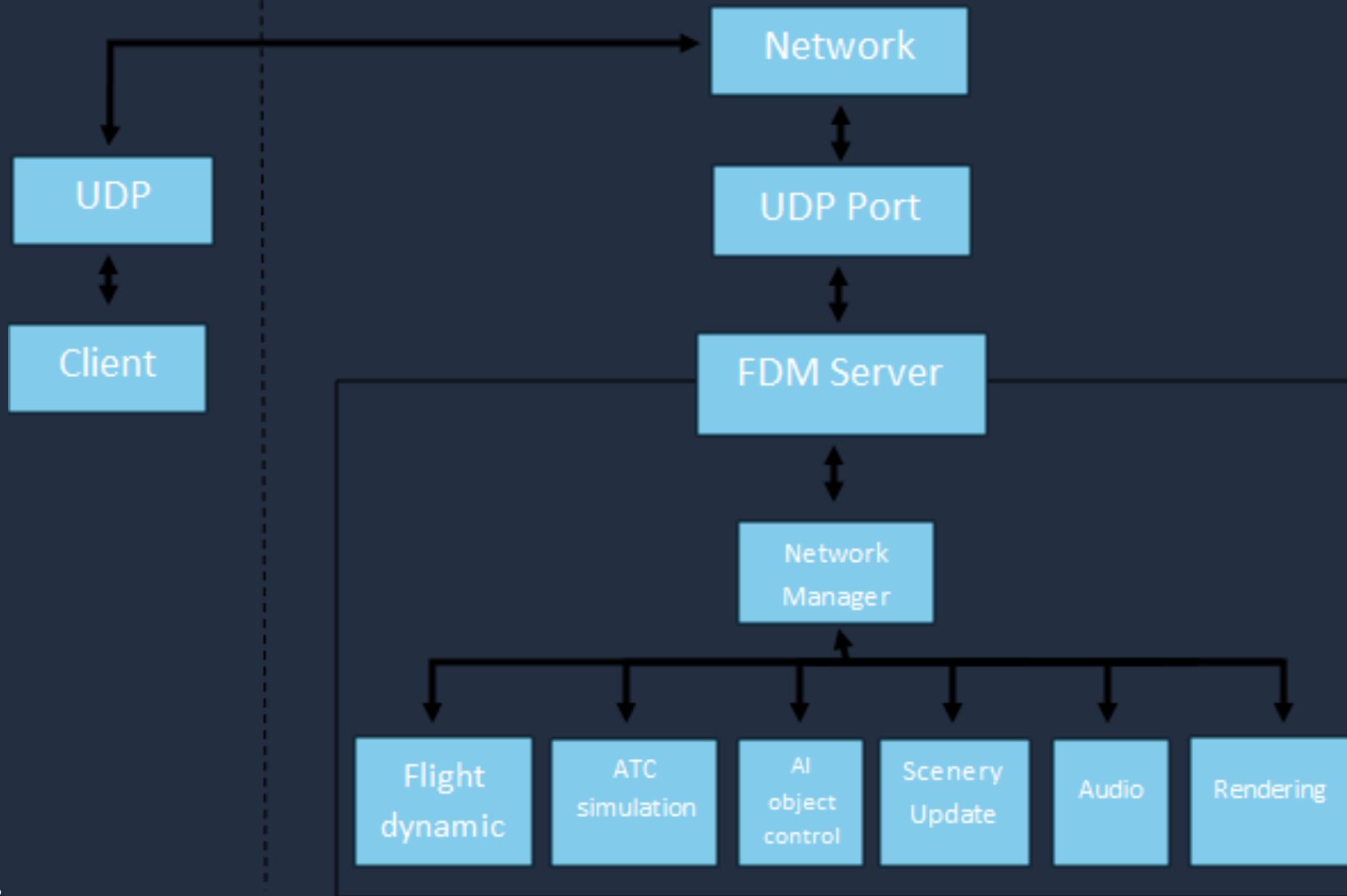
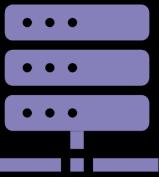


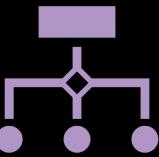
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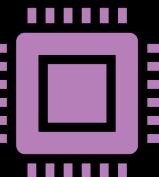
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Calculations will be made, and audio and visual rendering as well as updating the scenery outside the user's aircraft allow for the user to receive confirmation that their inputs have been registered by FlightGear's system. These updates will be output back to the network manager and from there, the FDM server will update the network and thus the client.

USE CASE #1

Sequence Diagram - Starting Aircraft

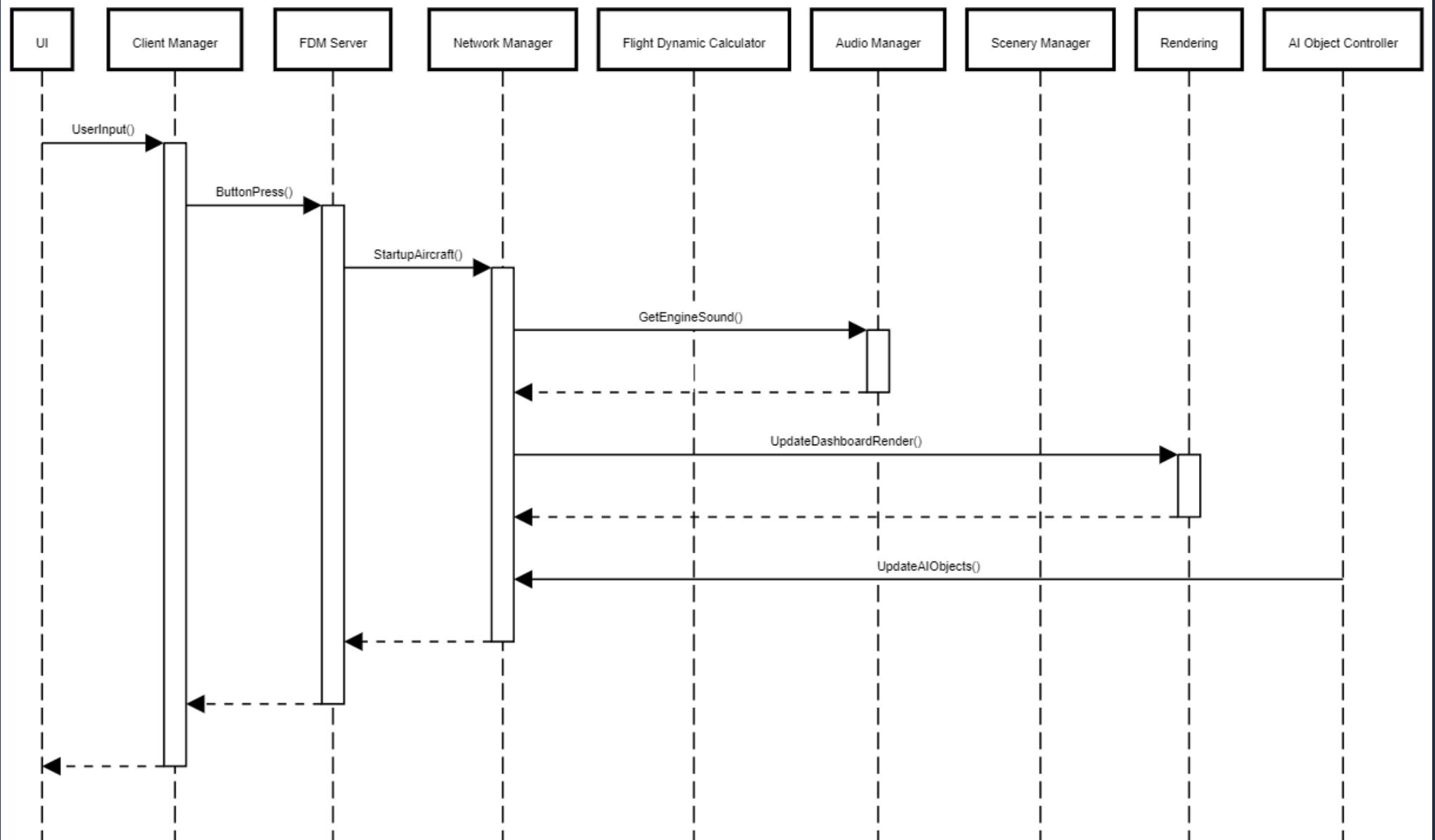


Figure 3: Sequence Diagram for Starting Aircraft



USE CASE #2

Sequence Diagram - In Air Flight

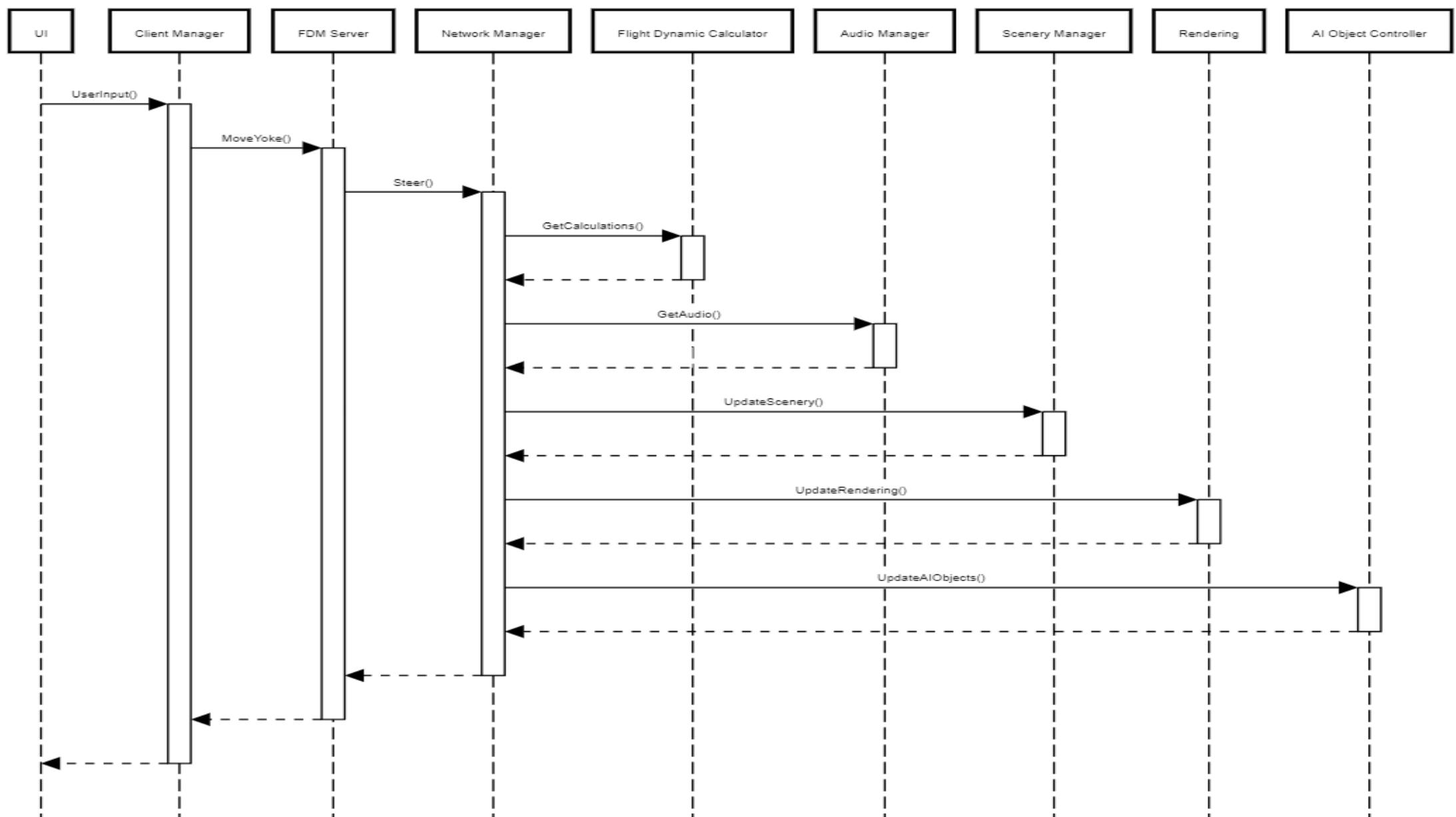
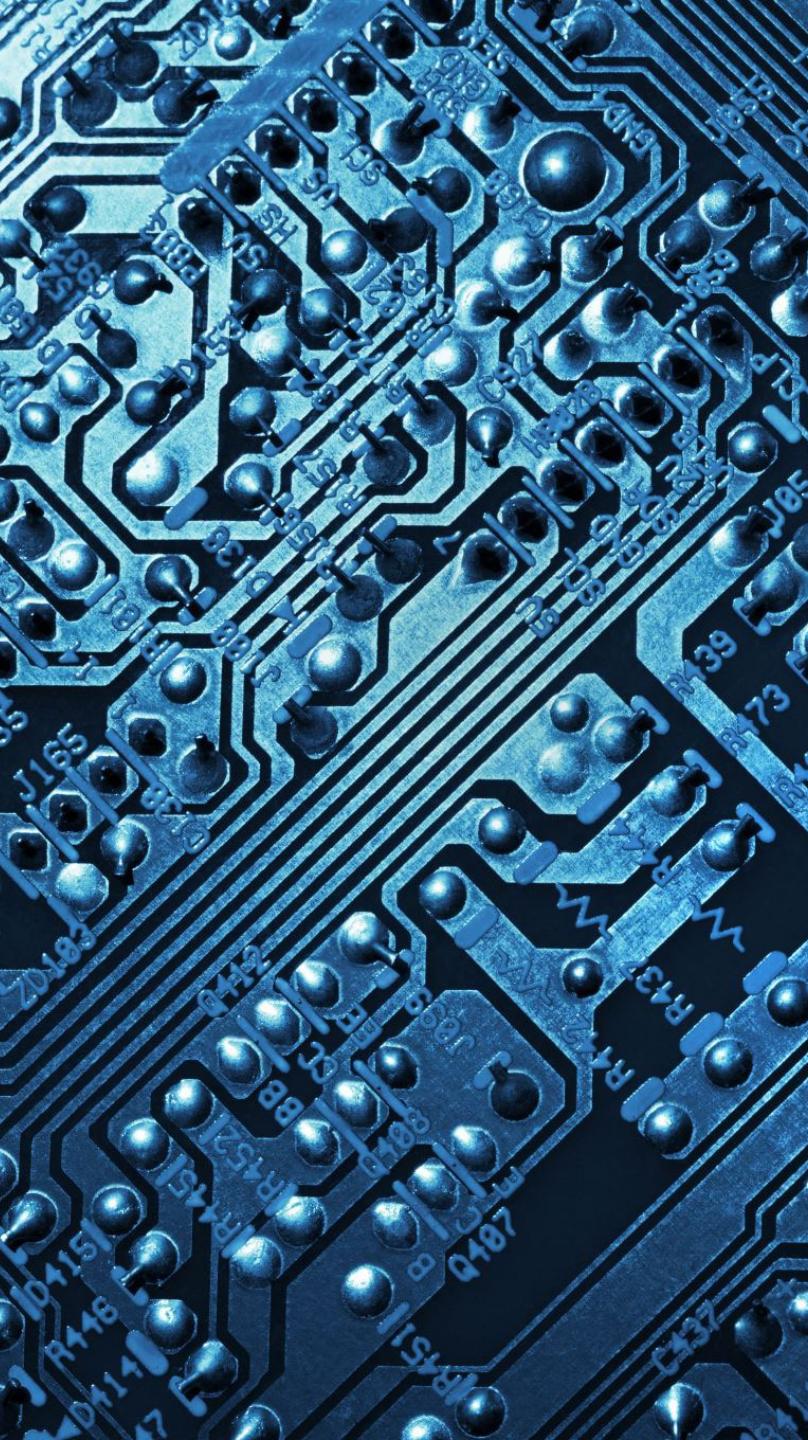


Figure 4: Sequence Diagram of When Flying Aircraft





CONCURRENCY

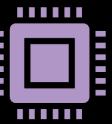
- Evolutions in technology including multi-core processors has improved parallel processing capabilities
- Distributed computing potentially improves processing speed as more computers used, however, this adds challenges
- Threads allow for parallel processing on one machine, semaphores used to sync threads



DIVISION OF RESPONSIBILITIES



Core developers make direct contributions to the source code.



Normal developers can make improvements to the source code, but they need to be reviewed.



Employs High-Level Architecture (HLA), which splits the simulation into different components



This allows anyone to create components in FlightGear that are language flexible.



LESSONS LEARNED

- Most research is from FlightGear Wiki
- Concurrency research from D. Allerton's "Flight Simulation Software", not specific to FlightGear
- Did not compare with other projects such as Microsoft Flight Simulator
- Learned about the benefits and drawbacks of HLA and other practices of FlightGear



CONCLUSION

- The purpose of the system is to accurately simulate aircraft flight in a way that is open, accessible, and easily modifiable for developers and non-developers alike
- It is in part able to accomplish this by creating an environment for threading resource intensive tasks. For example, it uses the FDM server for computing intensive core simulation tasks
- Uses a mixture of MVC, HLA, and Client-Server Architecture

