

Homework #3

1.) a) Let $u(t, x)$ be the true solution to $\partial_t u + a \partial_x u = 0$, $a > 0$.

$$T_j^{n+1} = u(t + \Delta t, x) - u_j^{n+1} \quad (\text{LTE}).$$

Taylor expanding, we see that

$$u(t, x - \Delta x) = u - \Delta x \partial_x u + \frac{\Delta x^2}{2} \partial_{xx} u - \frac{\Delta x^3}{6} \partial_{xxx} u + O(\Delta x^4)$$

$$u(t, x - 2\Delta x) = u - 2\Delta x \partial_x u + 2\Delta x^2 \partial_{xx} u - \frac{4\Delta x^3}{3} \partial_{xxx} u + O(\Delta x^4)$$

$$u(t + \Delta t, x) = u + \Delta t \partial_t u + \frac{\Delta t^2}{2} \partial_{tt} u + O(\Delta t^3)$$

Since $\partial_t u = -a \partial_x u$ and $\partial_{tt} u = a^2 \partial_{xx} u$, we see that

$$u(t + \Delta t, x) = u - a \Delta t \partial_x u + \frac{1}{2} a^2 \Delta t^2 \partial_{xx} u + O(\Delta t^3)$$

We see that if $u = u_j^n$, then

$$\begin{aligned} 3u_j^n - 4u_{j-1}^n + u_{j-2}^n &= 3u - 4u + 4\Delta x \partial_x u - 2\Delta x^2 \partial_{xx} u + \frac{2\Delta x^3}{3} \partial_{xxx} u + O(\Delta x^4) \\ &\quad + u - 2\Delta x \partial_x u + 2\Delta x^2 \partial_{xx} u - \frac{4}{3} \Delta x^3 \partial_{xxx} u + O(\Delta x^4) \\ &= 2\Delta x \partial_x u - \frac{2}{3} \Delta x^3 \partial_{xxx} u + O(\Delta x^4) \end{aligned}$$

$$\begin{aligned} u - 2u_{j-1}^n + u_{j-2}^n &= u - 2u + 2\Delta x \partial_x u - \Delta x^2 \partial_{xx} u + \frac{1}{3} \Delta x^3 \partial_{xxx} u + O(\Delta x^4) \\ &\quad + u + 2\Delta x \partial_x u + 2\Delta x^2 \partial_{xx} u - \frac{4}{3} \Delta x^3 \partial_{xxx} u + O(\Delta x^4) \\ &= \Delta x^2 \partial_{xx} u - \Delta x^3 \partial_{xxx} u + O(\Delta x^4) \end{aligned}$$

$$\begin{aligned} \Rightarrow u_j^{n+1} &= u - \frac{\Delta t}{2\Delta x} a \left[2\Delta x \partial_x u - \frac{2}{3} \Delta x^3 \partial_{xxx} u + O(\Delta x^4) \right] + \frac{\Delta t^2}{2\Delta x^2} a^2 \left[\Delta x^2 \partial_{xx} u - \Delta x^3 \partial_{xxx} u + O(\Delta x^4) \right] \\ &= u - a \Delta t \left[\partial_x u - \frac{1}{3} \Delta x^2 \partial_{xxx} u + O(\Delta x^3) \right] + a^2 \Delta t^2 \left[\frac{1}{2} \partial_{xx} u - \frac{1}{2} \Delta x \partial_{xxx} u + O(\Delta x^2) \right] \\ &= u - a \Delta t \partial_x u + \frac{1}{2} a^2 \Delta t^2 \partial_{xx} u + \frac{1}{3} a \Delta t \Delta x^2 \partial_{xxx} u - \frac{1}{2} a^2 \Delta t^2 \Delta x \partial_{xxx} u + O(\Delta x^2) \\ &= u - a \Delta t \partial_x u + \frac{1}{2} a^2 \Delta t^2 \partial_{xx} u - \frac{1}{2} a^2 \Delta t^2 \Delta x \partial_{xxx} u + O(\Delta x^2) \end{aligned}$$

$$\Rightarrow T_j^{n+1} = u(t + \Delta t, x) - u_j^{n+1}$$

1.) a) continued)

Plugging in $u(t+\Delta t, x)$ & u_j^{n+1} into the LTE formula gives

$$\begin{aligned} T_j^{n+1} &= (u - a\Delta t \partial_x u + \frac{1}{2}a^2\Delta t^2 \partial_{xx} u + \mathcal{O}(\Delta t^3)) \\ &\quad - (u - a\Delta t \partial_x u + \frac{1}{2}a^2\Delta t^2 \partial_{xx} u - \frac{1}{2}a^2\Delta t^2 \Delta x \partial_{xxx} u + \mathcal{O}(\Delta x^2)) \\ &= \frac{1}{2}a^2\Delta t^2 \Delta x \partial_{xxx} u + \mathcal{O}(\Delta t^3 + \Delta x^2) = \mathcal{O}(\Delta t^2 + \Delta x^2). \end{aligned}$$

Thus the LTE of this scheme is $\mathcal{O}(\Delta t^2 + \Delta x^2)$.

b) First, we will rewrite the scheme and let $v = \frac{\Delta t}{\Delta x} a$.

$$\begin{aligned} U_j^{n+1} &= U_j^n - \frac{1}{2}v(3U_j^n - 4U_{j-1}^n + U_{j-2}^n) + \frac{1}{2}v^2(U_j^n - 2U_{j-1}^n + U_{j-2}^n) \\ &= (1 - \frac{3}{2}v + \frac{1}{2}v^2)U_j^n + (2v - v^2)U_{j-1}^n + (-\frac{1}{2}v + \frac{1}{2}v^2)U_{j-2}^n \\ &= \frac{1}{2}(v-1)(v-2)U_j^n + v(2-v)U_{j-1}^n + \frac{1}{2}v(v-1)U_{j-2}^n \end{aligned}$$

Now let $U_j^n = g(\xi)^n e^{i\xi j \Delta x}$. Then

$$\begin{aligned} g(\xi) &= \frac{1}{2}(v-1)(v-2) + v(2-v)e^{-i\xi \Delta x} + \frac{1}{2}v(v-1)e^{-2i\xi \Delta x} \\ &= e^{-i\xi \Delta x} \left[\frac{1}{2}(v-1)(v-2)e^{i\xi \Delta x} + v(2-v) + \frac{1}{2}v(v-1)e^{-i\xi \Delta x} \right] \\ &= e^{-i\xi \Delta x} \left[\frac{1}{2}v(v-1)e^{i\xi \Delta x} - (v-1)e^{i\xi \Delta x} + v(2-v) + \frac{1}{2}v(v-1)e^{-i\xi \Delta x} \right] \\ &= e^{-i\xi \Delta x} \left[v(v-1)\cos \xi \Delta x + v(2-v) - (v-1)e^{i\xi \Delta x} \right] \\ &= e^{-i\xi \Delta x} \left[v(v-1)\cos \xi \Delta x + v(2-v) - (v-1)\cos \xi \Delta x - i(v-1)\sin \xi \Delta x \right] \\ &= e^{-i\xi \Delta x} \left[(v-1)^2 \cos \xi \Delta x + v(2-v) - i(v-1)\sin \xi \Delta x \right] \\ |g(\xi)|^2 &= |e^{-i\xi \Delta x} [(v-1)^2 \cos \xi \Delta x + v(2-v) - i(v-1)\sin \xi \Delta x]|^2 \\ &= |e^{-i\xi \Delta x}|^2 |(v-1)^2 \cos \xi \Delta x + v(2-v) - i(v-1)\sin \xi \Delta x|^2 \\ &= [(v-1)^2 \cos \xi \Delta x + v(2-v)]^2 + (v-1)^2 \sin^2 \xi \Delta x \\ &= (v-1)^4 \cos^2 \xi \Delta x + 2v(2-v)(v-1)^2 \cos \xi \Delta x + v^2(2-v)^2 + (v-1)^2 \sin^2 \xi \Delta x \end{aligned}$$

1.) b.) continued.)

$$\begin{aligned}|g(\xi)| &= (v-1)^2 [(v-1)^2 \cos^2 \xi \Delta x + \sin^2 \xi \Delta x] + 2v(2-v)(v-1)^2 \cos \xi \Delta x + v^2(2-v)^2 \\&= (v-1)^2 [v^2 \cos^2 \xi \Delta x - 2v \cos^2 \xi \Delta x + 1] + 2v(2-v)(v-1)^2 \cos \xi \Delta x + v^2(2-v)^2 \\&= (v-1)^2 [-v(2-v) \cos^2 \xi \Delta x + 1] + 2v(2-v)(v-1)^2 \cos \xi \Delta x + v^2(2-v)^2 \\&= (v-1)^2 + v^2(2-v)^2 + 2v(2-v)(v-1)^2 \cos \xi \Delta x - v(2-v) \cos^2 \xi \Delta x\end{aligned}$$

*Note that

$$\begin{aligned}(v-1)^2 + v^2(2-v)^2 &= v^2 - 2v + 1 + v^2(v^2 - 4v + 4) \\&= v^4 - 4v^3 + 5v^2 - 2v + 1 = 1 + v(v^3 - 4v^2 + 5v - 2)\end{aligned}$$

also we see that

$$(2-v)(v-1)^2 = (2-v)(v^2 - 2v + 1) = -v^3 + 4v^2 - 5v + 2 = -(v^3 - 4v^2 + 5v - 2)$$

This means we have

$$(v-1)^2 + v^2(2-v)^2 = 1 + v(v^3 - 4v^2 + 5v - 2) = 1 - v(2-v)(v-1)^2$$

$$\begin{aligned}\Rightarrow |g(\xi)| &= 1 - v(2-v)(v-1)^2 + 2v(2-v)(v-1)^2 \cos \xi \Delta x - v(2-v) \cos^2 \xi \Delta x \\&= 1 - v(2-v)(v-1)^2 (1 - 2 \cos \xi \Delta x + \cos^2 \xi \Delta x) \\&= 1 - v(2-v)(v-1)^2 (1 - \cos \xi \Delta x)^2\end{aligned}$$

We require $|g(\xi)| \leq 1$ for L^2 stability, so

$$1 - v(2-v)(v-1)^2 (1 - \cos \xi \Delta x)^2 \leq 1$$

$$\Rightarrow -v(2-v)(v-1)^2 (1 - \cos \xi \Delta x)^2 \leq 0$$

Since $v = a \frac{\Delta t}{\Delta x} \geq 0$, $(v-1)^2 \geq 0$, $(1 - \cos \xi \Delta x)^2 \geq 0$, this means we need $(2-v) \geq 0$ to satisfy this condition. Thus $v \leq 2$, so $a \frac{\Delta t}{\Delta x} \leq 2$ is the L^2 stability condition for this scheme.

2.) Let us replace U_j^n by a continuous function $v(t, x)$. Then

$$\frac{v(t+\Delta t, x) - v(t, x)}{\Delta t} + a \frac{v(t, x+\Delta x) - v(t, x-\Delta x)}{2\Delta x} = 0$$

Taylor expanding, we see that

$$\begin{aligned} v(t+\Delta t, x) &= v(t, x) + \Delta t \partial_t v(t, x) + \frac{\Delta t^2}{2} \partial_{tt} v(t, x) + O(\Delta t^3) \\ v(t, x+\Delta x) &= v(t, x) + \Delta x \partial_x v(t, x) + \frac{\Delta x^2}{2} \partial_{xx} v(t, x) + O(\Delta x^3) \\ v(t, x-\Delta x) &= v(t, x) - \Delta x \partial_x v(t, x) + \frac{\Delta x^2}{2} \partial_{xx} v(t, x) + O(\Delta x^3) \end{aligned}$$

Plugging into above and assuming $\frac{\Delta t}{\Delta x}$ is fixed gives

$$\partial_t v + \frac{\Delta t}{2} \partial_{tt} v + a \partial_x v + O(\Delta x^2) = 0 \quad O(\Delta x^2) = 0$$

$$\Rightarrow \partial_t v + a \partial_x v = -\frac{\Delta t}{2} \partial_{tt} v + O(\Delta x^2)$$

We see that we can differentiate w.r.t. t to get

$$\partial_{tt} v + a \partial_{tx} v = O(\Delta x)$$

$$\Rightarrow \partial_{tt} v = -a \partial_x (\partial_t v) + O(\Delta x)$$

$$\Rightarrow \partial_{tt} v = -a \partial_x (-a \partial_x v) + O(\Delta x) = a^2 \partial_{xx} v + O(\Delta x)$$

Plugging this in for $\partial_{tt} v$ gives

$$\begin{aligned} \partial_t v + a \partial_x v &= -\frac{\Delta t}{2} [a^2 \partial_{xx} v + O(\Delta x)] + O(\Delta x^2) \\ &= -\frac{\Delta t}{2} a^2 \partial_{xx} v + O(\Delta x^2) \end{aligned}$$

Since $-\frac{\Delta t}{2} a^2 < 0$ always, this diffusion term can never be positive. Negative diffusion produces instability, so this implies this scheme is always unstable for all $\frac{\Delta t}{\Delta x}$.



















