Rollback - return to some safe state, restart process from that state

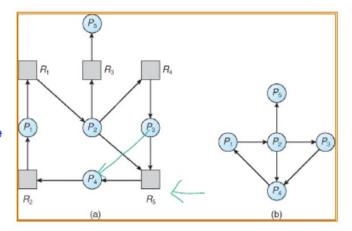
3-2>

When deadlock is detected, the system must recover either

by termination some of the deadlocked process (데드락 걸린 프로세스 종료)

- or by preempting resources from some of the deadlocked processes (데드락 걸린프로세스의 자원 선점해버림)
- <Deadlock Detection>
- i) Allow system to enter deadlock state
- ii) Detection algorithm
- iii) Recovery scheme
- <Single Instance of each Resource Type>
- How to detect deadlock using resource-allocation graph
- Maintain wait-for graph from resource-allocation graph
 - Nodes are processes
 - P_i → P_i if P_i is waiting for P_i
- Periodically invoke an algorithm that searches for a cycle in the graph
 - If a cycle exist → deadlock
- An algorithm to detect a cycle in a graph requires an order of n² operations,
 - where n is the number of vertices in the graph
- Corresponding Wait-for graph
- How to detect deadlock in a multiple instances of a resource type?
- Available: A vector of length m indicates the number of available resources of each type.
- Allocation: An n x m matrix defines the number of resources of each type currently allocated to each process.
- Request: An n x m matrix indicates the current request of each process.
 - If Request [i,j] = k, then process P_i is requesting k more instances of resource type R_i.

<Resource-Allocation Graph and Wait-for Graph>



Resource-Allocation Graph

Detection Algorithm (Cont.) - modified safety algorithm

1. Let Work and Finish be vectors of length m and n, respectively. Initialize: Work = Available

For i=0, 1, ..., n-1, if $Allocation_i \neq 0$, then Finish[[i] = false; Otherwise, Finish[i] = true.

- 2. Find an index | such that both:
 - (a) Finish [i] == false
 - (b) Request_i ≤ Work

If no such i exists, go to step 4.

- 3. Work = Work + Allocation Finish[i] = true go to step 2.
- 4. If Finish [i] == false, for some i, 0 ≤ i ≤ n-1, then the system is in

Moreover, if Finish[i] == false, then P_i is deadlocked.

Algorithm requires an order of O(m x n²⁾ operations to detect whether the system is in deadlocked state. >

- Five processes P₀ through P₄;
- · three resource types
 - A (7 instances), B (2 instances), and C (6 instances).
- Snapshot at time T₀:

_	Allocation	Request	Available
	ABC	ABC	ABC
P_0	010	000	000
P_1	200	202	
P_2	303	000	
P_3	211	100	
P_4	002	002	

Sequence <P₀, P₂, P₃, P₁, P₄> will result in Finish[i] = true for all i.

P₂ requests an additional instance of type C.

Request	
ABC	
P ₀ 000	
P ₁ 202	15 WWW
P ₂ 0 0 1	
P ₃ 100	
P ₄ 002	

- · State of system?
 - Can reclaim resources held by process P₀, but insufficient resources to fulfill other processes' requests.
 - Deadlock exists, consisting of processes P₁, P₂, P₃, and P₄.

<Detection-Algorithm Usage>

- When, and how often, to invoke depends on"
 - How often a deadlock is likely to occur?
 - How many processes will need to be rolled back? : one for each disjoint cycle
- If detection algorithm is invoked arbitrarily(독단적으로),
 - there may be many cycles in the resource graph
 - and so we would not be able to tell which of the many deadlocked processes "caused" the deadlock.
- <Recovery from Deadlock> : several alternatives
- 1. operator에게 데드락 일어났다고 알려서 manually 처리하게 하기
- 2. Process Termination : circular wait 깨게 하기 위해 종료시킴
- i) Abort all deadlocked processes.
- ii) Abort one process at a time until the deadlocked cycle is eliminated
- 3. Resource Preemption : deadlocked process으로부터 자원 선점(preempt) 하기

three issues in resource preemption

- 1) Selecting a victim minimize cost
- 2) Rollback return to some safe state, restart process from that state
- 3) Starvation same process may always be picked as victim.