

# MUSIC APPLICATION OF MACHINE LEARNING

## Tutorial Session

Seungheon Doh

# Pytorch

## PyTorch

`torch.tensor([[1, 2], [3, 4]])`  
`torch.zeros()`  
`torch.ones()`  
`torch.size()`  
`torch.view()`  
`torch.transpose()`  
`torch.cat()`  
`torch.sum()`  
`torch.load()`

## Numpy

`np.array([[1, 2], [3, 4]])`  
`np.zeros()`  
`np.ones()`  
`np.shape[]`  
`np.reshape()`  
`np.transpose()`  
`np.concatenate()`  
`np.sum()`  
`np.load()`

# Pytorch

```
for epoch in num_epoch:
```

```
    total_loss = 0
```

```
    for x, y in train_loader:
```

```
        optimizer.zero_grad()
```

```
        prediction = model(x)
```

```
        loss = criterion(prediction, y)
```

```
        loss.backward()
```

```
        optimizer.step()
```

```
    total_loss += loss.item()
```

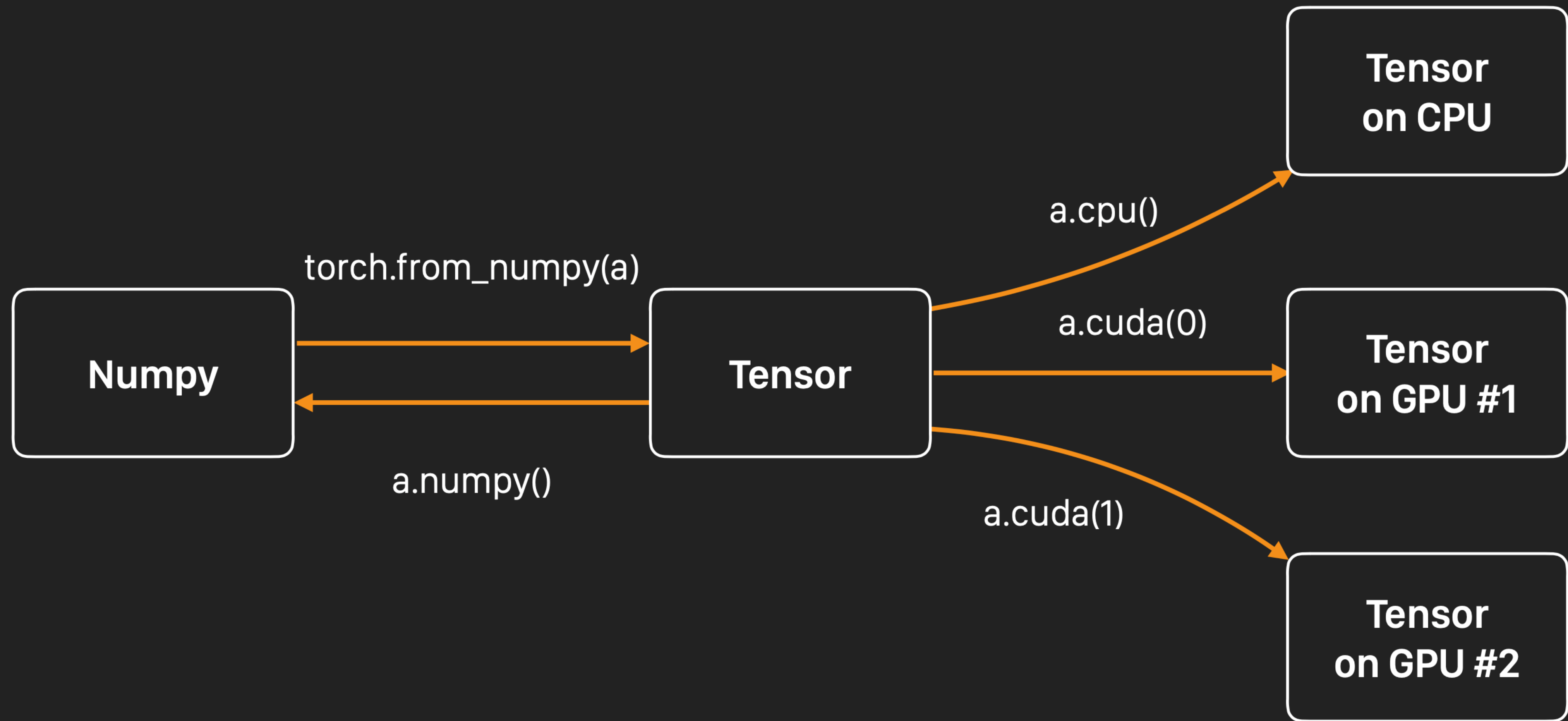
Set gradient to zero

Run model

Get loss

Run back-propagation

# Pytorch



# Pytorch

## AUTOGRAD

- Automatic differentiation for all operations
- Automatic back-propagation

```
x = torch.ones(2, 2, requires_grad=True)
y = x + 2
print(y)
```

```
x.detach()
```

```
loss.backward()
```

```
tensor([[3., 3.], [3., 3.]],
        grad_fn=<AddBackward0>)
```

Stopping tensor history tracking

Equivalent to `loss.backward(torch.tensor(1.0))`  
Calculating back-propagation

# Pytorch

## BUILDING A NETWORK

- Building a neural network based on nn.Module
- Automatically defined backward function using autograd

```
import torch.nn as nn
import torch.nn.functional as F

class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        self.conv1 = nn.Conv2d(3, 6, 5)
        self.conv2 = nn.Conv2d(6, 16, 5)
        self.pool = nn.MaxPool2d(2, 2)
        self.fc1 = nn.Linear(16*5*5, 120)
        self.fc2 = nn.Linear(120, 10)

    def forward(self, x):
        x = self.pool(F.relu(self.conv1(x)))
        x = self.pool(F.relu(self.conv2(x)))
        x = x.view(-1, 16*5*5)
        x = F.relu(self.fc1(x))
        x = self.fc2(x)
        return x
```

# Pytorch

## DATASET & DATALOADER

- Dataset - Class for loading data

init() - initial process like reading index file

getitem() - return data at an index

len() - return the size of entire data

- Dataloader - Wrapping up to batch

```
class GTZANDataset(Dataset):  
    def __init__(self, x, y):  
        self.x = x  
        self.y = y  
  
    def __getitem__(self, index):  
        return self.x[index], self.y[index]  
  
    def __len__(self):  
        return self.x.shape[0]
```

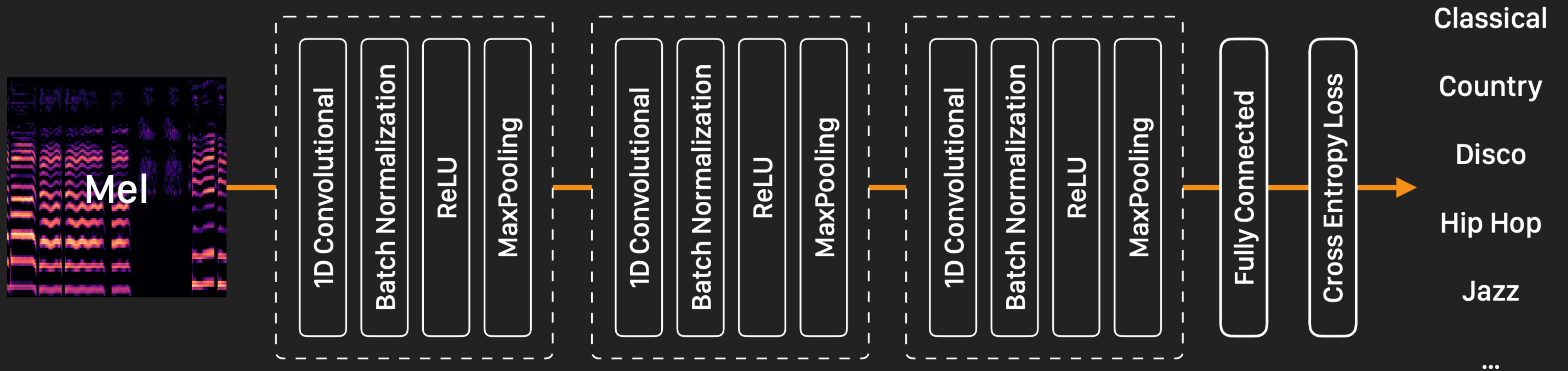
```
train_loader = DataLoader(dataset=train_set,  
                           batch_size=32,  
                           shuffle=True,  
                           drop_last=False)
```

# HomeWork!

- AutoTagging
- Metric Learning



# [Q1,2] Automatic Music Tagging

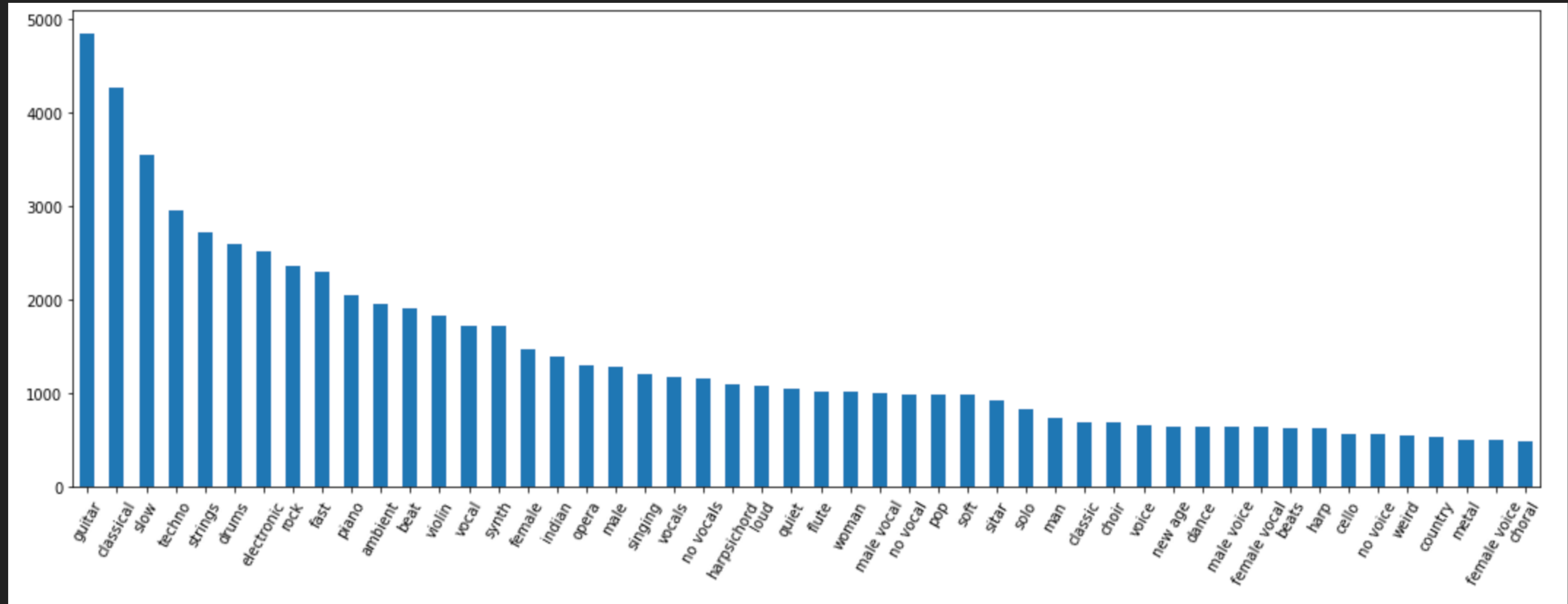


**Baseline ROCAUC 0.61**

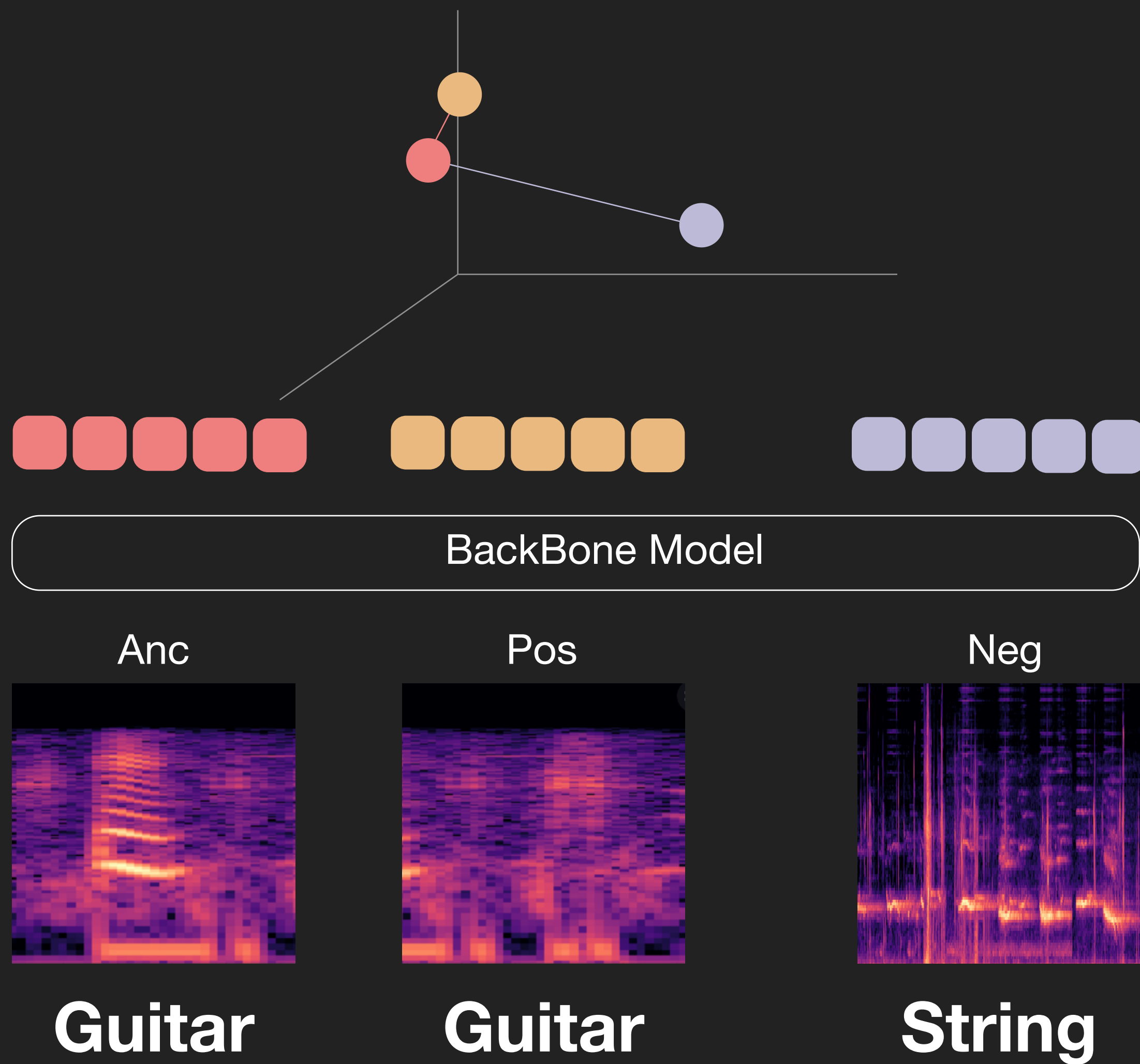
# [Q1,2] Automatic Music Tagging

## Dataset

- We use subset of magnatagatune dataset (9074 samples x 8 sec) with 50 Tags
- We use a relatively small and imbalanced dataset.



# [Q3,4] Metric Learning

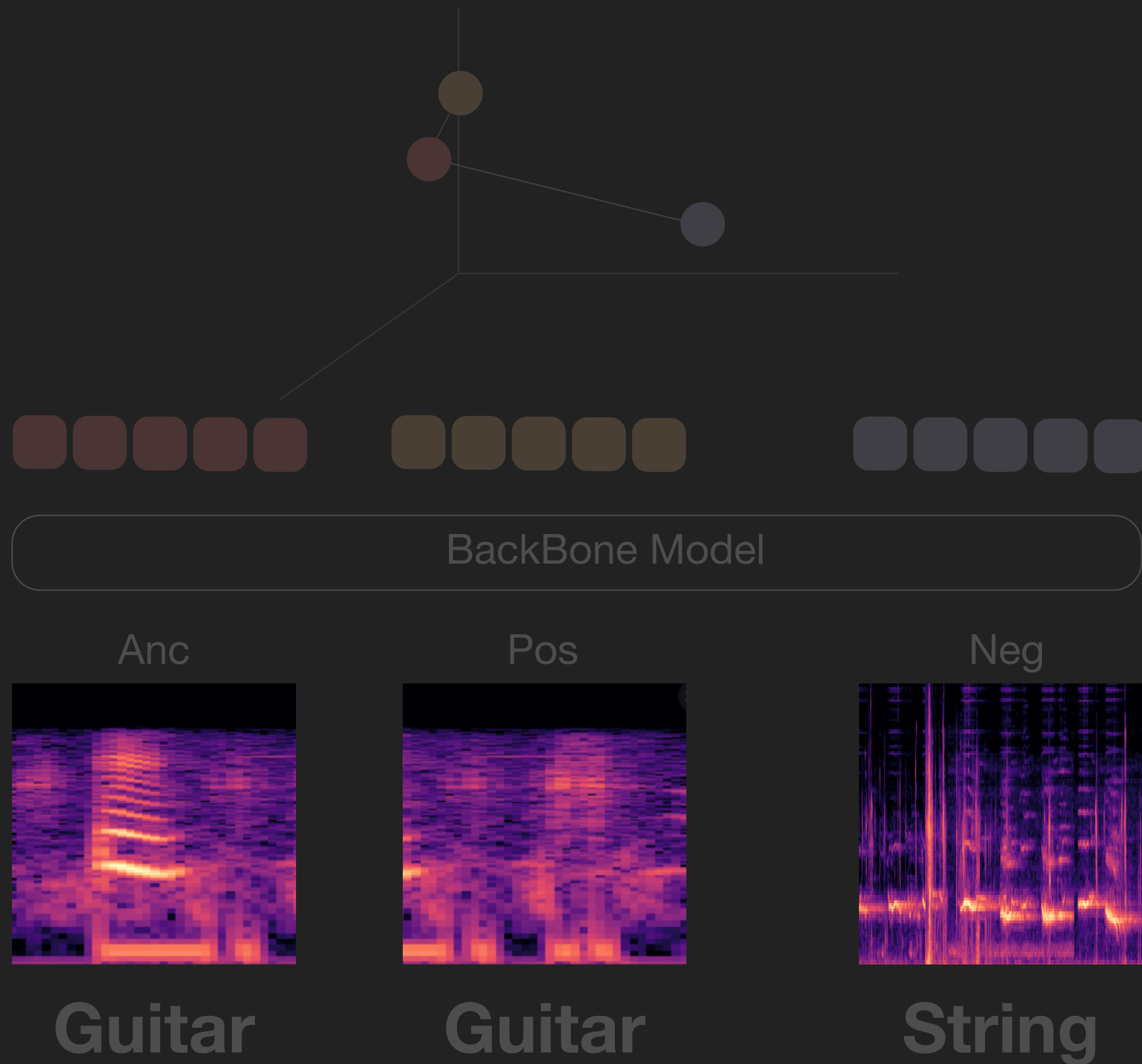


## Triplet Loss

$$L = [D(E_a, E_p) - D(E_a, E_n) + \delta]_+,$$

E : Embedding from backbone model

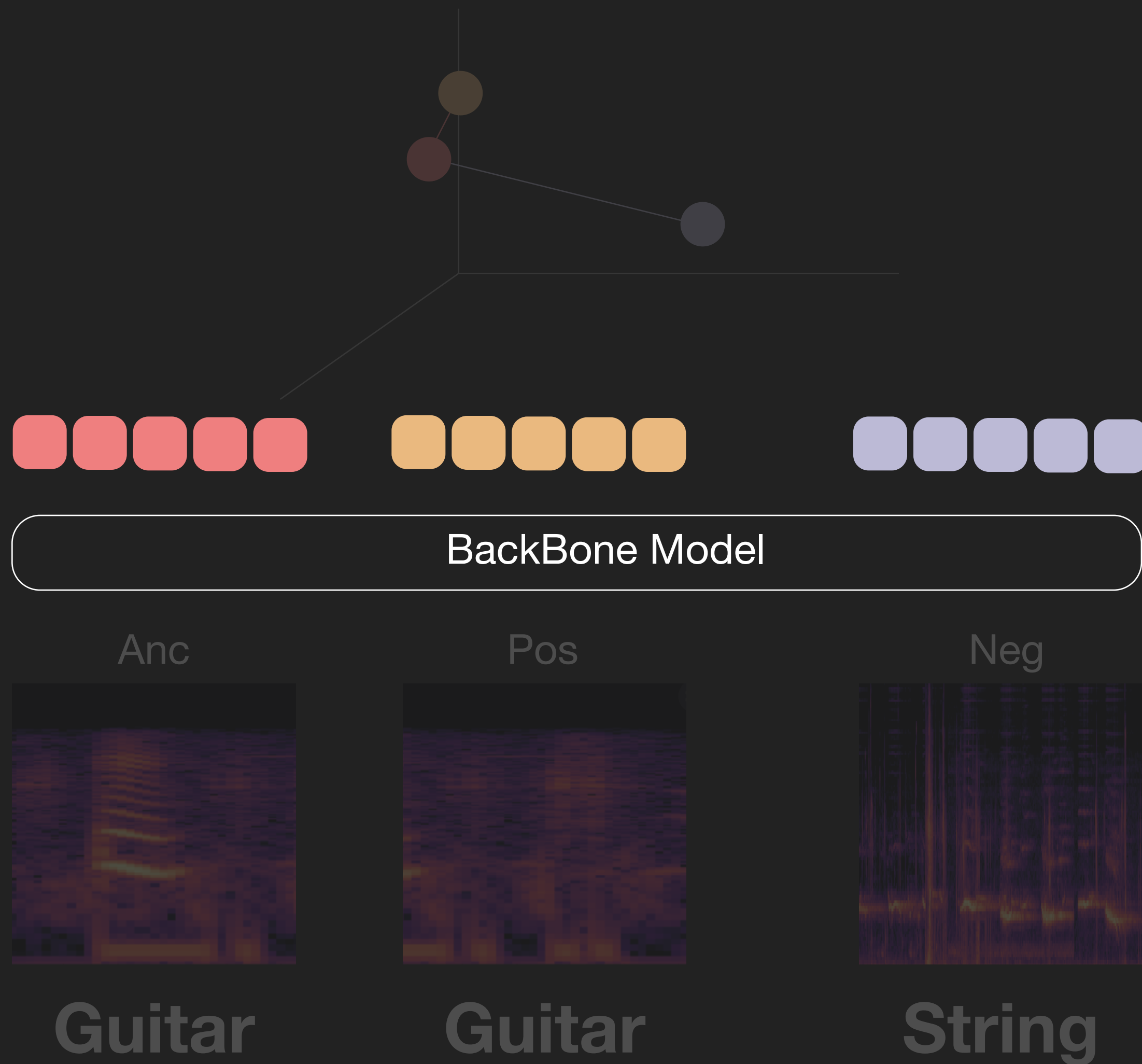
# [Q1,2.3,4] Improvement



## Audio Representation

- Change FFT Size & Mel Bin
- Change Input Sequence
- MFCC
- CQT
- Time domain Representation

# [Q1,2.3,4] Improvement



## Backbone Model

### - model parameters

Filter size

Pooling size

Stride size

Number of filters

Model depth

Regularization: L2/L1 and Dropout

### - hyperparameters

Learning rate

Model depth

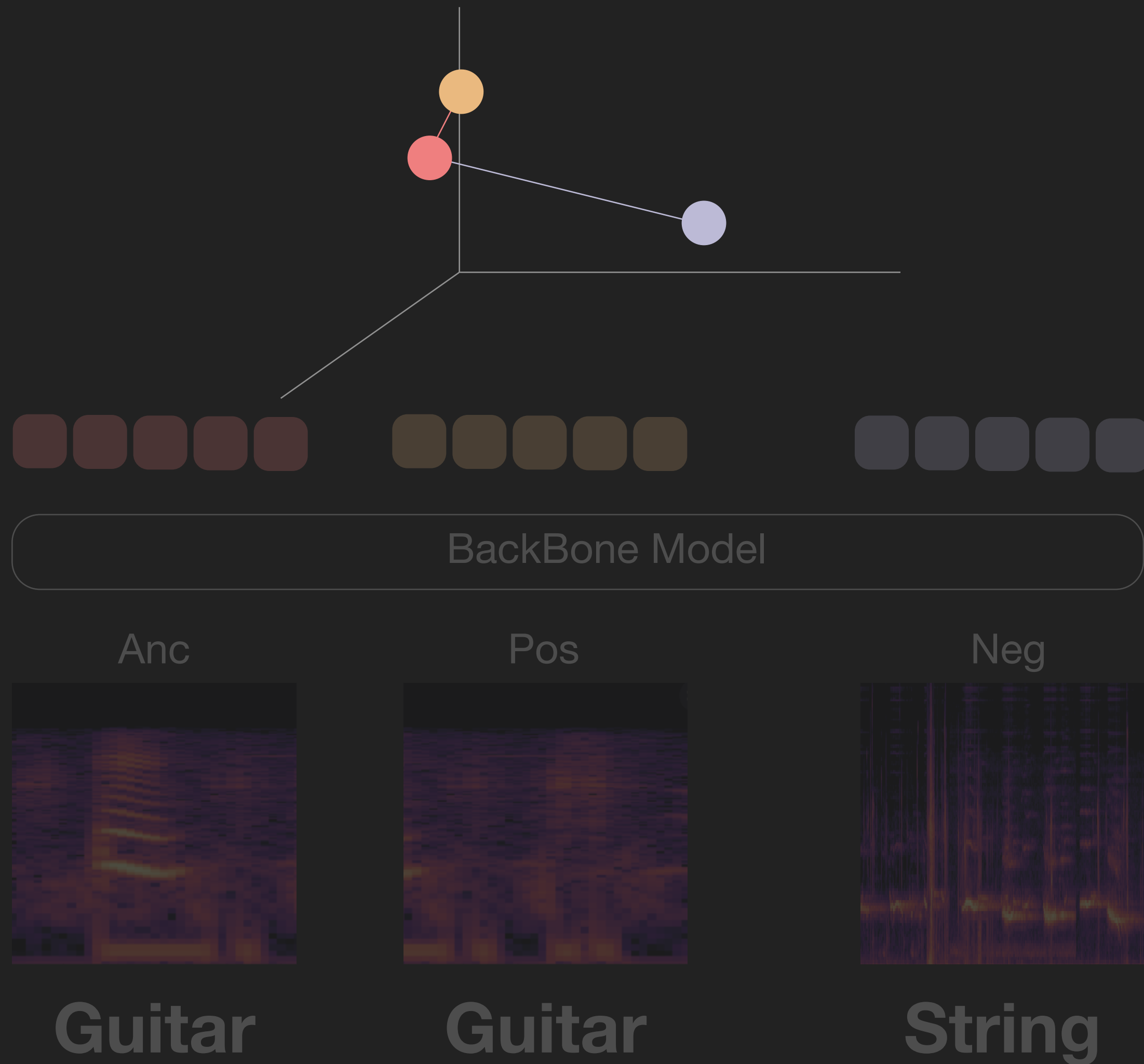
Optimizers: SGD (with Nesterov momentum),  
Adam, RMSProp, ...

### - use pretrained model (openl3, vggish)

# [Q3,4] Improvement

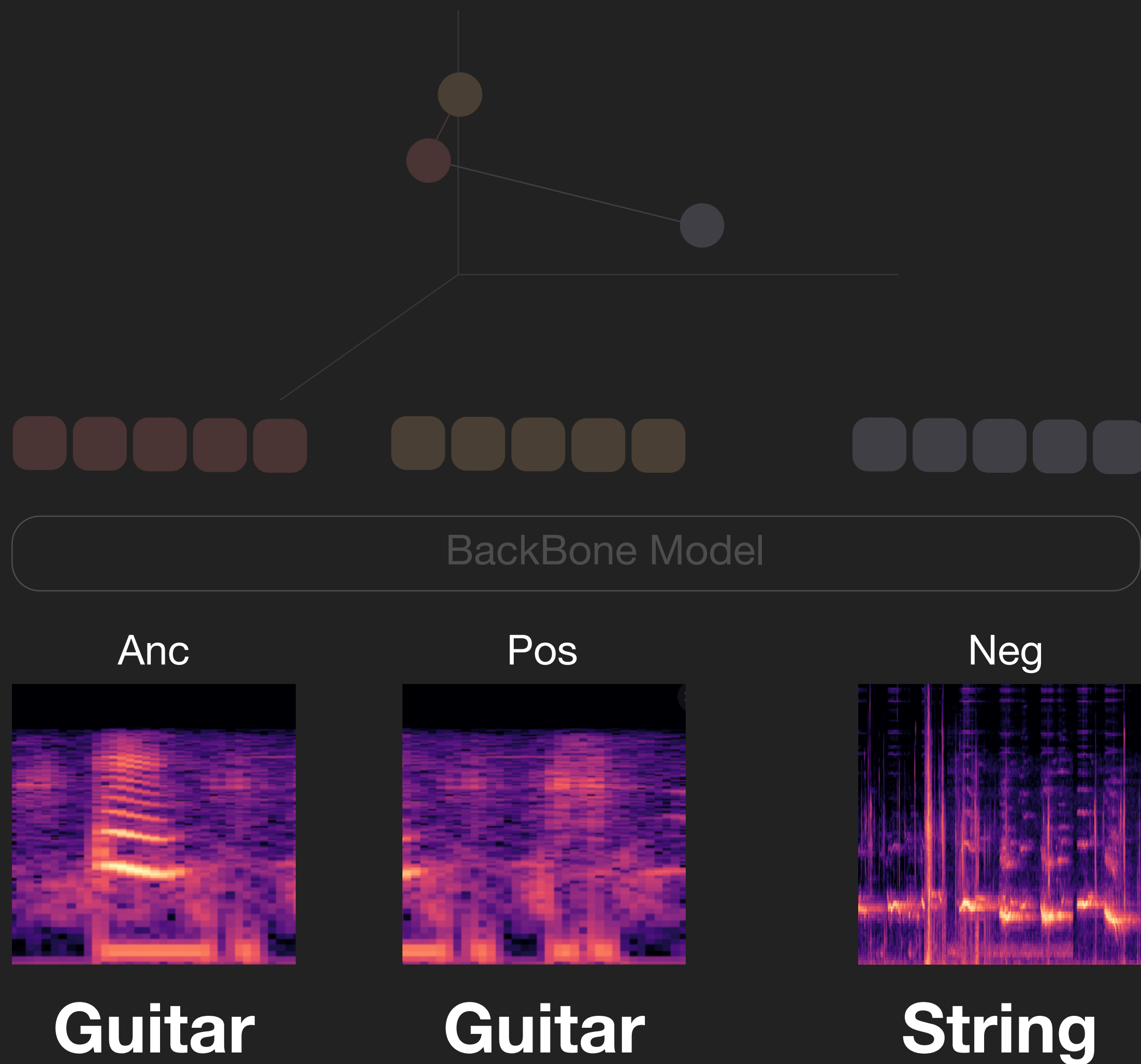
## Change Distance Measure

- Euclidean Space
- Cosine Space
- Hyperbolic Space





# [Q3,4] Improvement



## Sampling

- Tag based sampling
- Timbre, Beat based sampling
- Latent Space based sampling  
(Distance in SVD or Tag's Word Embedding)
- Instance based sampling (Self-Supervised)