

# A Spine for Teichmueller Space of Closed Hyperbolic Surfaces (Draft)

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*We claim a minimal dimension spine  $W$  of Teichmueller space  $\text{Teich}(S)$  consists of surfaces which are filled by their shortest essential nonseparating geodesics. [-J.H. Martel]*

## 1 Minimal Geodesic Subsurface Lemma

We assume  $(S, g)$  is a compact hyperbolic surface with constant Gauss curvature  $K = -1$ .

**Definition:** A collection  $C$  of curves is  $\pi_1$ -essential if the curves are homotopically nontrivial. The collection is nonseparating, or  $H_1$ -essential, if the curves are nonzero  $[\alpha] \neq 0$  in  $H_1(S, \mathbf{Z})$  for  $\alpha \in C$ .

**Definition:** Let  $C$  be a collection of homotopy essential geodesics, and let  $S_0$  be a geodesic subsurface of  $S$  containing  $C$ . The complexity of  $C$  is defined as the rank of the homological image of  $C$ , that is

$$\xi(C) := \dim \text{span}(H_1(C)).$$

We see  $\xi = \xi(C)$  is an integer taking every integer value between  $1 \leq \xi \leq 2g$  where  $g$  is the genus of the surface  $S$ .

**Lemma:** A collection of homotopy essential nonseparating geodesics  $C$  has  $\xi(C) = 2g$  if and only if  $C$  is filling, i.e. iff  $S - C$  is a disjoint union of topological disks.

**Remark:** If  $S_0$  is a proper nonempty geodesic subsurface of  $S$ , then  $S_0$  is a surface with geodesic boundary  $\partial S_0$ . In otherwords there are no topological embeddings of  $S_{p,0} \hookrightarrow S_{q,0}$  when  $p \leq q$ . Every proper geodesic subsurface has *some* boundary.

**Remark:** The definition of  $\xi$  extends to subsurfaces  $S_0 \hookrightarrow S$  with

$$\xi(S_0) := \dim \text{image}(H_1(S_0)).$$

We begin with a Lemma/Definition which constructs a canonical geodesic subsurface  $S_0$  containing  $C$ .

**Lemma 1** (Unique Minimal Complexity Geodesic Subsurfaces): Let  $C$  be a collection of essential nonseparating geodesic curves on  $(S, g)$ . There exists a unique geodesic subsurface  $S_0 = S_0(C)$  such that -  $S_0$  contains  $C$  in its interior; and - the boundary  $\partial S_0$  is homotopically essential in  $S$ ; and - the subsurface has minimal complexity  $\xi(S_0) = \xi(C)$ .

Equivalently  $C$  fills a unique essential geodesic subsurface  $S_0$  in  $S$ .

*Proof of Lemma 1:* If  $S_0$  is a geodesic subsurface containing  $C$  and satisfying  $\xi(S_0) = \xi(C)$ , then  $S_0$  strong deformation retracts onto  $C$ . Therefore if  $S_0, S_1$  are two such subsurfaces with  $\xi(S_0) = \xi(S_1) = \xi(C)$ , then  $S_0$  and  $S_1$  are homotopic relative to  $C$ . It follows that there exists a unique geodesic subsurface in the homotopy class  $\text{rel } C$  by energy minimizing argument [incomplete].

*Remark:* The geodesic subsurface  $S_0$  constructed in Lemma 1 is a degenerate subsurface when the curves of  $C$  are pairwise disjoint, i.e. the subsurface is basically the one-dimensional geodesic link  $C \subset S$ . The subsurface  $S_0$  is nondegenerate when there exists a nontrivial intersection amongst some elements of  $C$  in which case the genus of  $S_0$  is nonzero.

## 2 Belt Tightening Lemma

The purpose of constructing the canonical geodesic subsurface  $S_0$  in Lemma 1 is to contract the boundary  $\partial S_0$  and thereby deform the hyperbolic structure. The following Belt Tightening Lemma is our main observation:

**Belt Tightening Lemma:** Let  $S_0$  be a proper subsurface of  $S$  with geodesic boundary  $\partial S_0$ . Let  $C$  be a collection of essential nonseparating geodesics disjoint from  $\partial S_0$ . Suppose  $\xi(S_0) = \xi(C)$ .

There exists a one-parameter deformation  $\{g_t\}$  in  $\text{Teich}(S)$  such that:

- the metric  $g_t$  is hyperbolic for all  $t \geq 0$  and  $g_0 = g$ ;
- the boundary lengths  $\ell(\gamma, g_t)$  are decreasing for all  $t \geq 0$  and all  $\gamma \in \partial S_0$ ;
- the curve lengths  $\ell(\alpha, g_t)$  are simultaneously increasing for all  $t \geq 0$  and all  $\alpha \in C$ .

Proof: [Thurston, Minimal Stretch Maps preprint]

## 3 Well-Rounded Retract of Teichmueller Space

Here is our proposal for constructing well-rounded retracts of  $\text{Teich}(S)$ .

**Definition:** Let  $C = C(g)$  be the set of geodesic nonseparating  $\pi_1$ -essential curves on  $(S, g)$ .

**Definition:** The  $C$ -systole of  $(S, g)$  consists of the shortest curves in  $C$  relative to  $g$  length. We denote the  $C$ -systoles of a given metric  $g$  by  $C'(g)$ .

**Definition:** A collection of curves  $C_0$  fills the surface  $S$  if the complement  $S - C_0$  is a disjoint union of topological disks.

**Notation:** For metric  $g$ , let  $S_0 := S_0(C'(g))$  be the minimal geodesic subsurface constructed in Lemma 1 and containing the  $C$ -systoles.

**Remark:** Evidently  $\xi(S_0) \leq \xi(S)$  with equality if and only if  $C'(g)$  fills  $S$ . Otherwise if  $C'$  does not fill, then  $S_0(C')$  has nontrivial geodesic boundary which we can contract by Belt Tightening Lemma. Iterating this process defines the retract.

**Definition:** For every index  $1 \leq j \leq 2g$ , let  $W_j$  be the subvariety of  $\text{Teich}(S)$  consisting of hyperbolic metrics whose  $C$ -systoles satisfy  $\xi(C) \geq j$ .

**Theorem:** The Teichmueller space  $\text{Teich}$  continuously and equivariantly retracts onto  $W = W_{2g}$ . Moreover  $W$  has codimension  $2g - 1$  in  $\text{Teich}$  and therefore is a minimal dimension spine of  $\text{Teich}$ .

**Proof:** The retract  $Teich \rightarrow W$  is defined as a composition of retracts

$$W_1 \rightarrow W_2 \rightarrow \cdots \rightarrow W_{2g}.$$

The general retract  $W_j \rightarrow W_{j+1}$  is defined as follows:

Let  $(S, g)$  be a hyperbolic surface in  $W_j$  with  $\xi(C(g)) = j < 2g$ . Let  $\{g_t\}$  be the unique one-parameter deformation of hyperbolic metrics constructed in Belt Tightening Lemma which *contracts* the geodesic boundary  $\partial S_0(g)$  and simultaneously expands the lengths of  $C$  in  $S_0(g)$ .

*Claim:* There exists a minimal stopping time  $\tau = \tau(g)$  which depends continuously on  $g$  such that  $g_\tau \in W_{j+1}$ . Equivalently  $\tau$  is the unique minimal time such that a new *independant*  $C$ -systole appears and which *strictly increases the complexity*  $\xi$  of the supporting minimal subsurface  $S_0(g_\tau)$ . Analytically  $\tau$  is defined as the least time  $t$  such that

$$\xi(S_0(g_t)) > \xi(S_0(g)).$$

*Claim:* The one-parameter deformation defines a continuously well-posed global retraction  $g \mapsto g_\tau$  from  $W_j$  to  $W_{j+1}$ .

*Claim:* The subvariety  $W_{j+1}$  is a codimension one subvariety of  $W_j$ . Therefore  $W_{2g}$  is a codimension  $2g - 1$  subvariety of  $Teich$ . This is the minimal possible dimension according to Bieri-Eckmann homological duality. QED.

**Remark:** Geometric minimality requires a further homological duality argument a la [Souto-Pettet]. [Insert details]