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q[{u_List, v_List}] := q[{u, v}] = N[Dot[u - v, u - v]^(-3/2)];
(*exponent -3 is choice. but can replace with -2 or -4,-5,...*)

proj1[w_List] := proj1[w] = {w[[1]] (1 - w[[3]])^(-1), w[[2]] (1 - w[[3]])^(-1), 0};
q1[w_List] := q1[w] = N[ ( q[{w, proj1[w]}] + (1/2) q[{w, {0, 0, 1.}}] )];
(* above cost c(w,z) to target z *)

proj2[w_List] := proj2[w] = {0, w[[2]] (1 - w[[1]])^(-1), w[[3]] (1 - w[[1]])^(-1)};
q2[w_List] := q2[w] = N[ ( q[{w, proj2[w]}] + (1/2) q[{w, {1., 0., 0.}}] )];
(* cost c(w,x) with target x *)

proj3[w_List] := proj3[w] = {w[[1]] (1 - w[[2]])^(-1), 0, w[[3]] (1 - w[[2]])^(-1)};
q3[w_List] := q3[w] = N[ ( q[{w, proj3[w]}] + (1/2) q[{w, {0., 1., 0.}}] )];
(* cost c(w,x) with target y *)

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prod[n_Integer] := prod[n] = ((Table[e^y[j], {j, 1, 3}] // Total)^n // Expand);
A = {{1, 0, 0}, {0, 1, 0}, {0, 0, 1}};
simp[m_Integer] := simp[m] = (Level[(
  (prod[m] //. Table[y[j] → pt[A[[j]]], {j, 1, 3}]) //.
  {n_Integer pt[z_List] → pt[Times[n, z]]}
) //. {pt[z_] + pt[z1_] → pt[z + z1], n_Integer e^z_ → e^z, 1}] //
  {e^pt[z_List] → v[Times[N[1/m], z]]];

B :=
  ((simp[21] // Total) /. {v[{z1_, z2_, z3_}] :> c[ q1[{z1, z2, z3}] ] v[{z1, z2, z3}]
  }); (*evaluating cost c(w,z) as sum q1+
  q2 over gates containing target z. *)

B1 := Coefficient[(B /. {c[z_Real] → f c[z]}), f];
B2 := B2 = (B1 /. {c[a_Real] v[{z1_, z2_, z3_}] → pt[{z1, z2, a}]});
B3 := (Level[B2, 1]) //. pt[z_List] → z;

F := ((simp[21] // Total) /. {v[{z1_, z2_, z3_}] :> c[ q2[{z1, z2, z3}] ] v[{z1, z2, z3}]
  }); (* evaluating cost c(w,x) *)
F1 := Coefficient[(F /. {c[z_Real] → f c[z]}), f];
F2 := F2 = (F1 /. {c[a_Real] v[{z1_, z2_, z3_}] → pt1[{z1, z2, a}]});
F3 := (Level[F2, 1]) //. pt1[z_List] → z;

G := ((simp[21] // Total) /. {v[{z1_, z2_, z3_}] :> c[ q3[{z1, z2, z3}] ] v[{z1, z2, z3}]
  }); (* evaluating cost c(w,y) *)
G1 := Coefficient[(G /. {c[z_Real] → f c[z]}), f];
G2 := G2 = (G1 /. {c[a_Real] v[{z1_, z2_, z3_}] → pt2[{z1, z2, a}]});
G3 := (Level[G2, 1]) //. pt2[z_List] → z;

Print[ListPointPlot3D[{B3, F3, G3},
  PlotRange → {0, 100}, PlotStyle -> PointSize[Large]]];

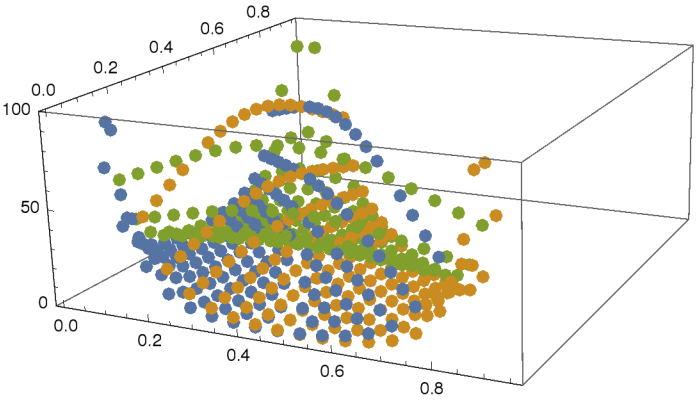
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Power::infy : Infinite expression $\frac{1}{0.^{3/2}}$ encountered. >>

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General::stop : Further output of Power::infy will be suppressed during this calculation. >>



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(*Print[ListPointPlot3D[B3,PlotRange->Automatic]];
Print[ListPointPlot3D[F3]];
G2*)

T := T = B2 + F2 + G2;
T1 :=
  T1 = (T /. {pt[{z1_Real, z2_Real, a_Real}] + pt1[{z1_Real, z2_Real, b_Real}] + pt2[
    {z1_Real, z2_Real, c_Real}] -> p[{z1, z2}] argval[z, 0.]
    argval[x, (b - a)] argval[y, (c - a)] max[Min[0., b - a, c - a]]});

T2 := T2 = (T1 /. {
  (argval[y_, l1_Real] max[m_Real] :> maxarg[y] max[m] /; l1 <= m),
  (argval[y_, l1_Real] max[m_Real] :> max[m] /; l1 > m)
});

sub[z] := sub[z] = (Coefficient[T2, maxarg[z]]) /. {maxarg[z_] :> 1};
sub[y] := sub[y] = (Coefficient[T2, maxarg[y]]) /. {maxarg[z_] :> 1};
sub[x] := sub[x] = (Coefficient[T2, maxarg[x]]) /. {maxarg[z_] :> 1};
postsub[y] :=
  postsub[y] = Level[sub[y], 1] /. {max[l_Real] p[{z1_Real, z2_Real}] -> {z1, z2, 1}};
postsub[x] := postsub[x] = Level[sub[x], 1] /.
  {max[l_Real] p[{z1_Real, z2_Real}] -> {z1, z2, 1}};
postsub[z] := postsub[z] = Level[sub[z], 1] /.
  {max[l_Real] p[{z1_Real, z2_Real}] -> {z1, z2, 1}};

ListPointPlot3D[{postsub[x], postsub[z], postsub[y]},
  PlotStyle -> PointSize[Large]]

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