

COMPUTACIÓN PARALELA

OPENMP – ENTREGA 1

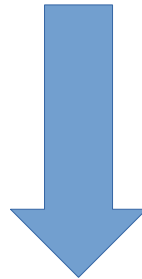
Grupo 01

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1. Comenta primero los problemas que tenía el código y cómo son las soluciones básicas necesarias.

```
/* Stop if searcher finds another trail */  
int check;  
check = accessMat( tainted, pos_row, pos_col );  
accessMat( tainted, pos_row, pos_col ) = 1;
```



```
/* Stop if searcher finds another trail */  
int check;  
#pragma omp atomic capture  
{  
    check = accessMat( trails, pos_row, pos_col );  
    accessMat( trails, pos_row, pos_col ) = search;  
}
```

```

if ( check != 0 ) {
    searchers[ search ].follows = accessMat( trails, pos_row, pos_col );
    search_flag = 1;
}
else {
    /* Annotate the trail */
    accessMat( trails, pos_row, pos_col ) = search;

    /* Compute the height */
    accessMat( heights, pos_row, pos_col ) = get_height( pos_row, pos_col, rows, columns, x_min, x_max, y_min, y_max );
}

```



```

if ( check != -1 ) {
    #pragma omp atomic write
    accessMat( trails, pos_row, pos_col ) = check;
    search_flag = 1;
}
else {
    float local_max;

    /* Compute the height */
    local_max=accessMat( heights, pos_row, pos_col ) = get_height( pos_row, pos_col, rows, columns, x_min, x_max, y_min, y_max );
}

```

```

/* 4. Compute searchers climbing trails */
#pragma omp for private(search)
for( search = 0; search < num_searchers; search++ ) {
    int search_flag = 0;
    while( ! search_flag ) {
        search_flag = climbing_step( rows, columns, searchers, search, heights, trails, x_min, x_max, y_min, y_max );
    }
}

#ifdef DEBUG
#define _OPENMP

This function is used only in sequential versions. Several threads exploring
the same time can derive in mixed lines and confusing output of no value.

t_trails( rows, columns, trails );
t_heights( rows, columns, heights );
if
if
    }

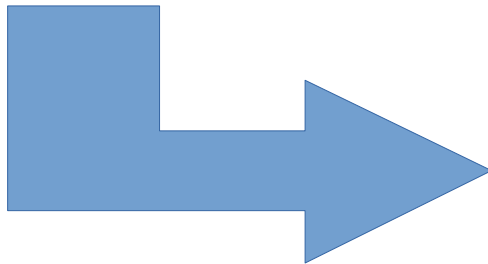
}
#pragma omp for private(search)
for( search = 0; search < num_searchers; search++ ) {
    searchers[ search ].follows = accessMat( trails, searchers[ search ].pos_row, searchers[ search ].pos_col );
}

```

2. Comenta las cosas extras que se han conseguido explicando ****por qué**** funcionan, o ****de dónde surgió**** la idea de probarlas.

- Eliminar la matriz tainted.

```
/* 3.2. Terrain initialization */
for( i=0; i<rows; i++ ) {
    for( j=0; j<columns; j++ ) {
        accessMat( heights, i, j ) = INT_MIN;
        accessMat( trails, i, j ) = -1;
        accessMat( tainted, i, j ) = 0;
    }
}
```



```
/* 3.2. Terrain initialization */
#pragma omp parallel for
for( i=0; i<rows*columns; i++ ) {
    heights[i] = INT_MIN;
    trails[i] = -1;
    //tainted[i] = 0;
}
```

- Inicialización del buscadores.

```
/* 3.3. Searchers initialization */  
int search;  
for( search = 0; search < num_searchers; search++ ) {  
    searchers[ search ].id = search;  
    searchers[ search ].pos_row = (int)( rows * erand48( random_seq ) );  
    searchers[ search ].pos_col = (int)( columns * erand48( random_seq ) );  
    searchers[ search ].steps = 0;  
    searchers[ search ].follows = -1;  
    total_steps[ search ] = 0;  
}
```

```
/* 3.3. Searchers initialization */
```

```
int search;
```

```
for( search = 0; search < num_searchers; search++ ) {  
    searchers[ search ].pos_row = (int)( rows * erand48( random_seq ) );  
    searchers[ search ].pos_col = (int)( columns * erand48( random_seq ) );  
}
```

```
#pragma omp parallel  
{
```

```
#pragma omp for
```

```
for( search = 0; search < num_searchers; search++ ) {  
    searchers[ search ].id = search;  
    searchers[ search ].steps = 0;  
    searchers[ search ].follows = -1;  
    total_steps[ search ] = 0;  
}
```

```

/* Compute the height */
local_max=accessMat( heights, pos_row, pos_col ) = get_height( pos_row, pos_col, rows, columns, x_min, x_max, y_min, y_max );

int climbing_direction = 0;
float altura;
if ( pos_row > 0 ) {
    /* Compute the height in the neighbor if needed */
    altura = accessMat( heights, pos_row-1, pos_col );
    if ( altura == INT_MIN )
        altura=accessMat( heights, pos_row-1, pos_col ) = get_height( pos_row-1, pos_col, rows, columns, x_min, x_max, y_min, y_max );

    /* Annotate the travelling direction if higher */
    if ( altura > local_max ) {
        climbing_direction = 1;
        local_max = altura;
    }
}
if ( pos_row < rows-1 ) {
    /* Compute the height in the neighbor if needed */
    altura=accessMat( heights, pos_row+1, pos_col );
    if ( altura == INT_MIN )
        altura=accessMat( heights, pos_row+1, pos_col ) = get_height( pos_row+1, pos_col, rows, columns, x_min, x_max, y_min, y_max );

    /* Annotate the travelling direction if higher */
    if ( altura > local_max ) {
        climbing_direction = 2;
        local_max = altura;
    }
}

```


PARALELIZACIÓN

```
/* 4. Compute searchers climbing trails */
#pragma omp for private(search)
for( search = 0; search < num_searchers; search++ ) {
    int search_flag = 0;
    while( ! search_flag ) {
        search_flag = climbing_step( rows, columns, searchers, search, heights, trails, x_min, x_max, y_min, y_max );
    }
}

#ifdef DEBUG
#define _OPENMP

This function is used only in sequential versions. Several threads exploring
the same time can derive in mixed lines and confusing output of no value.

t_trails( rows, columns, trails );
t_heights( rows, columns, heights );
if
if
    }

}
#pragma omp for private(search)
for( search = 0; search < num_searchers; search++ ) {
    searchers[ search ].follows = accessMat( trails, searchers[ search ].pos_row, searchers[ search ].pos_col );
}
```

```
/* 5. Compute the leading follower of each searcher */
#pragma omp for private(search)
for( search = 0; search < num_searchers; search++ ) {
    int search_flag = 0;
    int parent = search;
    int follows_to = searchers[ parent ].follows;

    while( ! search_flag ) {
        if ( follows_to == parent ) search_flag = 1;
        else {
            parent = follows_to;
            follows_to = searchers[ parent ].follows;
        }
    }
    searchers[ search ].follows = follows_to;
}
```

REDUCCIONES

```
/* 7. Compute statistical data */
#pragma omp for private(search) reduction(max:max_accum_steps,max_height) reduction(+:num_local_max)
for( search = 0; search < num_searchers; search++ ) {
    /* Maximum of accumulated trail steps to a local maximum */
    if ( max_accum_steps < total_steps[ search ] )
        max_accum_steps = total_steps[ search ];

    /* If this searcher found a maximum, check the maximum value */
    if ( searchers[ search ].follows == search ) {
        num_local_max++;
        int pos_row = searchers[ search ].pos_row;
        int pos_col = searchers[ search ].pos_col;
        int altura=accessMat( heights, pos_row, pos_col );
        if ( max_height < altura)
            max_height = altura;
    }
}

#pragma omp for reduction(+:total_tainted)
for( i=0; i<rows*columns; i++ ) {
    if ( trails[i] !=-1)
        total_tainted++;
}

} //Fin región paralela
```

3. Comenta otras cosas que se han probado y no han funcionado. Si tenéis alguna idea de por qué, explicadlo.

- Calcular las alturas fuera de la función *climbing_step*
- Utilizar *sections* para los diferentes if de la función *climbing_step*
- Cláusula *schedule*



4. Comenta como te has organizado con tu compañero para trabajar durante el concurso

5. Comenta fuentes, páginas web u otros recursos que has consultado durante el desarrollo de la práctica/concurso

- Apuntes de la asignatura
- <https://stackoverflow.com/>
- <https://bisqwit.iki.fi/story/howto/openmp/>
- <https://www.openmp.org/>