

Appendix S1. Linear regression models and non-linear population dynamics

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1 One species, logistic growth

Population growth over time in a single species is first modelled using a Beverton-Holt (discrete-time, logistic) model (Beverton and Holt (1957)), using an intra-specific competition coefficient for density-dependent growth (Hart and Marshall (2013)).

$$N_{i,t+1} = \frac{r_i N_{i,t}}{1 + \alpha_{ii} N_{i,t}}$$

Note that in this model, the system is at equilibrium when $N_{i,t+1} = N_{i,t}$, and therefore:

$$N^* = N^* \frac{r_i}{1 + \alpha_{ii} N^*}$$

$$1 = \frac{r_i}{1 + \alpha_{ii} N^*}$$

$$N^* = \frac{r_i - 1}{\alpha_{ii}}$$

1.1 Population dynamics simulation

In the metacommunity simulation in the main text, a species resides in a site with an initial population size $N_{i,0} \sim \text{Pois}(10)$, a growth rate r_i that depends on the local environmental value E_k and the species trait x_i , and a fixed intra-specific competition coefficient of $\alpha_{ii} = 0.00125$. We simulate population growth here:

```
set.seed(42)
# Simulate initial species population growth
N1.0 <- rpois(1, 10)
r1.0 <- 1.67
alpha.11 <- 0.00125
# model function
disc_log <- function(r, N0, alpha) {
  Nt1 <- (r * N0) / (1 + alpha * N0)
```

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```

    return(Nt1)
}
# Simulation of model for t time steps
t <- 30
N <- rep(NA, t)
N[1] <- N1.0
for (i in 2:t) {
  N[i] <- disc_log(r = r1.0, N0 = N[i - 1], alpha = alpha.11)
}

```

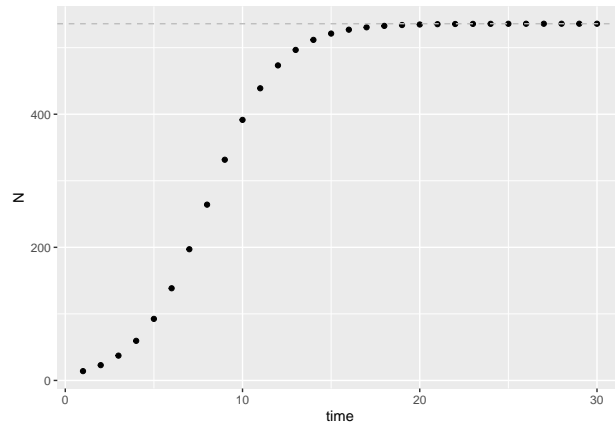


Figure 1: Population size N over time t for a discrete-time logistic growth model, with parameters $r_i = 1.67$, $N_{1,0} = 14$, and $\alpha_{11} = 0.00125$.

1.2 Linear statistical model

We fit the population time series data to a first-order auto-regressive model to predict N_{t+1} as a function of N_t , and compare that to a linear regression:

$$N_{t+1} = \beta_0 + \beta_1 N_t + \epsilon_t$$

```

# Fit the model
m.1.ar <- arima(x = log(N), order = c(1, 0, 0), include.mean = T, method = "CSS")
m.1.lm <- lm(log(dat$N[2:t]) ~ log(dat$N[1:(t - 1)]))
# plotting the series along with the fitted values
m.1.ar.fit <- log(N) - residuals(m.1.ar)
m.1.lm.fit <- log(dat$N[2:t]) - m.1.lm$resid
dat$ar1.fit <- m.1.ar.fit
dat$lm.fit <- NA
dat$lm.fit[2:t] <- m.1.lm.fit

```

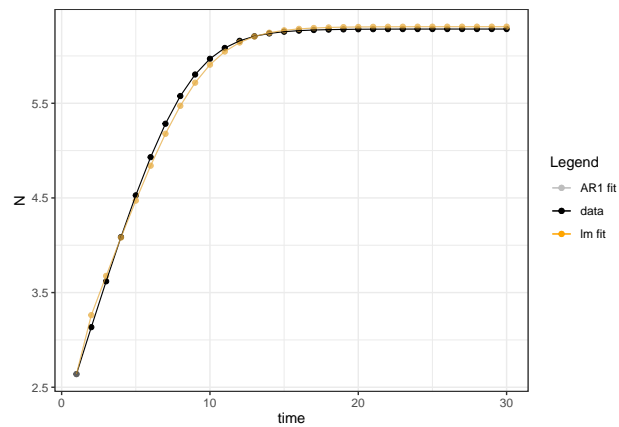


Figure 2: Population size over time (black line) with fitted values from a first-order autoregressive model (red dashed line).

- 17 The linear model is a good fit, and N_{t+1} and N_t are well-represented by a linear function:

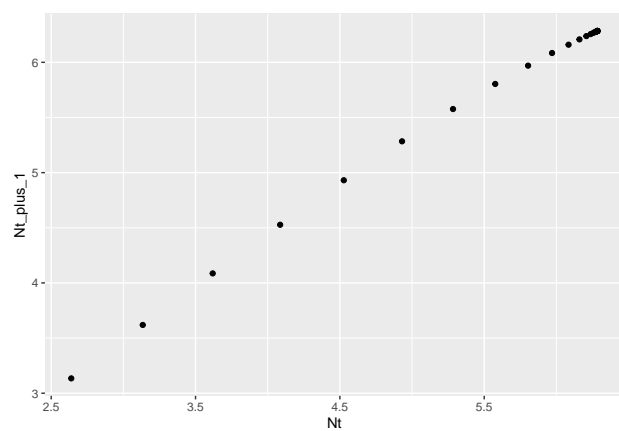


Figure 3: Population size (logarithm) at one time step N_{t+1} as a function of log-population size in the previous time step N_t .

- 18 We also examine density dependence by plotting $\Delta N = N_{t+1} - N_t$ vs. N_t :

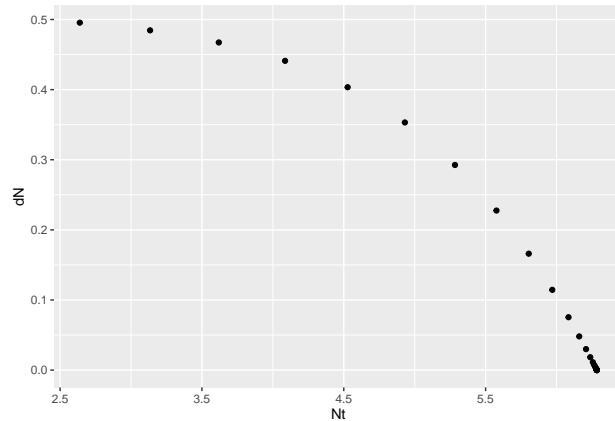


Figure 4: Change in population size from one time step to the next N_{t+1} as a function of N_t

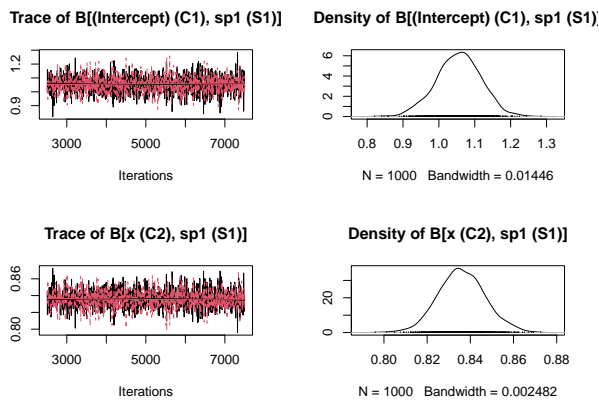
1.3 Bayesian linear statistical model: HMSC

We can estimate the same model parameters using HMSC:

```
# prepare data in HMSC format
Y <- as.matrix(log(dat$N[2:t]))
XData <- data.frame(x = log(dat$N[1:(t - 1)]))
m.1.hmsc <- Hmsc(Y = Y, XData = XData, XFormula = ~x)
# Bayesian model parameters
nChains <- 2
thin <- 5
samples <- 1000
transient <- 500 * thin
verbose <- 500 * thin
# sample MCMC
m.1.sample <- sampleMcmc(m.1.hmsc, thin = thin, sample = samples, transient = transient,
  nChains = nChains, verbose = verbose)
#> setting updater$GammaEta=FALSE due to absence of random effects included to the model
#> Computing chain 1
#> Chain 1, iteration 2500 of 7500 (transient)
#> Chain 1, iteration 5000 of 7500 (sampling)
#> Chain 1, iteration 7500 of 7500 (sampling)
#> Computing chain 2
#> Chain 2, iteration 2500 of 7500 (transient)
#> Chain 2, iteration 5000 of 7500 (sampling)
#> Chain 2, iteration 7500 of 7500 (sampling)

m.post.hmsc <- convertToCodaObject(m.1.sample)
summary(m.post.hmsc$Beta)
#>
#> Iterations = 2505:7500
#> Thinning interval = 5
#> Number of chains = 2
#> Sample size per chain = 1000
#>
#> 1. Empirical mean and standard deviation for each variable,
```

```
#>      plus standard error of the mean:
#>
#>               Mean      SD Naive SE Time-series SE
#> B[(Intercept) (C1), sp1 (S1)] 1.0550 0.06240 0.0013952      0.0013954
#> B[x (C2), sp1 (S1)]          0.8361 0.01083 0.0002422      0.0002415
#>
#> 2. Quantiles for each variable:
#>
#>           2.5%    25%    50%    75%    97.5%
#> B[(Intercept) (C1), sp1 (S1)] 0.9288 1.0132 1.0564 1.0974 1.1693
#> B[x (C2), sp1 (S1)]          0.8154 0.8287 0.8358 0.8431 0.8582
plot(m.post.hmsc$Beta)
```



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22 These estimates match well with those from the AR1 and linear model:

```
# AR1 coefficients (recall that the intercept is the term below multiplied by 1
# - phi1)
m.1.ar$coef
#>      ar1 intercept
#> 0.8359839 6.4371388
m.1.ar$coef[2] * (1 - m.1.ar$coef[1])
#> intercept
#> 1.055794
# linear model
summary(m.1.lm)$coefficients[1:2, 1:2]
#>               Estimate Std. Error
#> (Intercept)      1.0557944 0.054425861
#> log(dat$N[1:(t - 1)]) 0.8359839 0.009441702
# Bayesian estimates
summary(m.post.hmsc$Beta)$statistics[1:2, 1:2]
#>               Mean      SD
#> B[(Intercept) (C1), sp1 (S1)] 1.0549596 0.06239605
#> B[x (C2), sp1 (S1)]          0.8360545 0.01082936
```

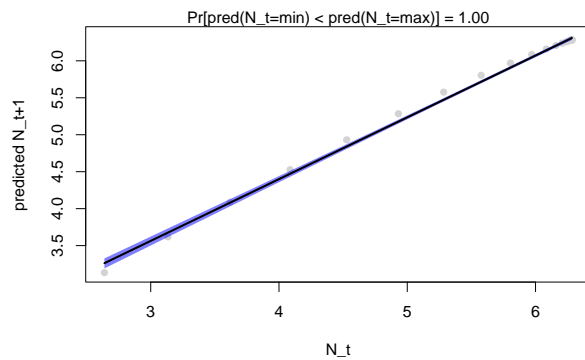


Figure 5: Observed (grey) and model-fit (blue) values for population size at time t (x-axis) and $t+1$ (y-axis).

1.4 Conclusions

In this example, a first-order auto-regressive model works well, bypassing the need to estimate logistic growth parameters r_i and α_{ii} . The density-dependence dynamics ($\Delta N \sim f(N_t)$) show an overall declining trend over time. The Bayesian estimation implemented in HMSC gives good parameter estimates.

```
knitr::knit_exit()
```

Beverton, R. J., and S. J. Holt. 1957. On the dynamics of exploited fish populations (Vol. 11). Springer Science & Business Media.

Hart, S. P., and D. J. Marshall. 2013. [Environmental stress, facilitation, competition, and coexistence](#). Ecology 94:2719–2731.