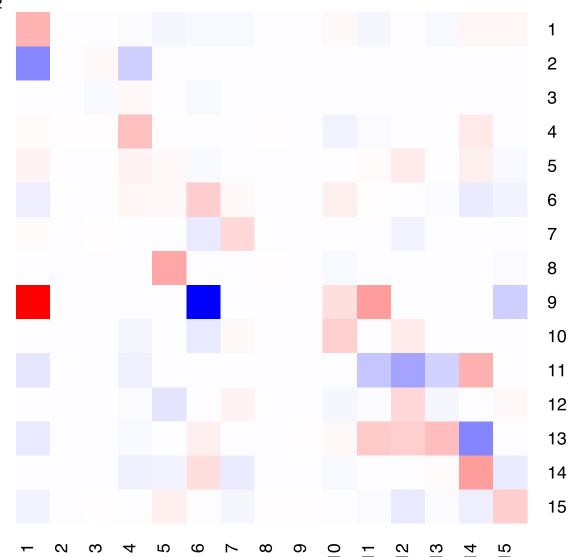


## Posterior mean, 0 ∉ HDI



 $\beta * x_{j,t-1} * N_{j,t-1}$  (driver, x)

 $N_{i,t}$  (response, y)