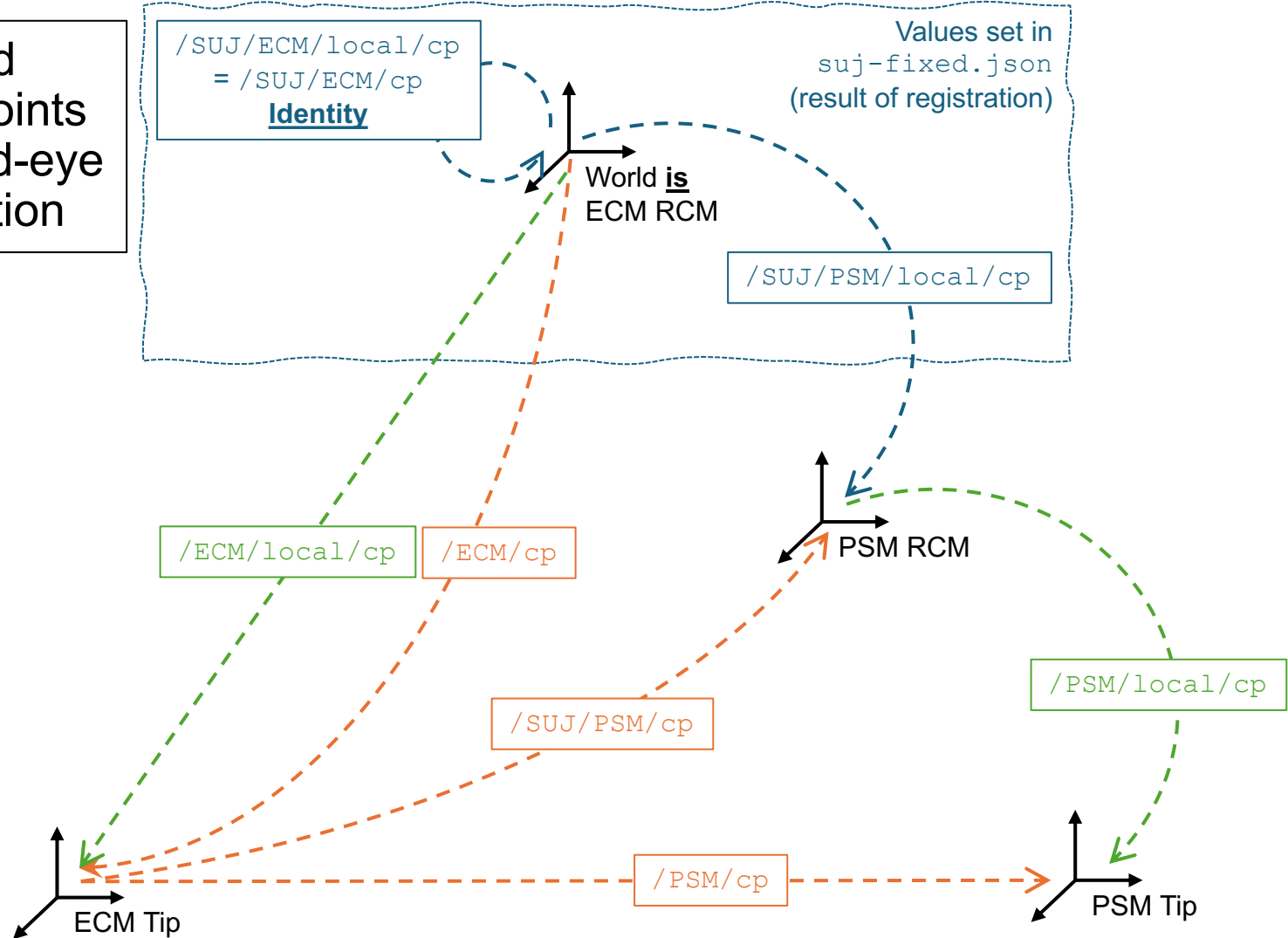


Fixed
Setup Joints
with hand-eye
calibration



--> From file or ROS topic --> Sensors and forward kinematics --> Composition