

# Intermediate Programming

## Day 16

# Outline

- Exercise 15
- Midterm project

# Exercise 15

Determine the endianness of the hardware, using the fact that:  
**950238851 = 0x38A37E83**

⇒ Little endian

```
>> gcc endian.c ... -g
>> gdb ./a.out
...
(gdb) b main
...
(gdb) r
...
(gdb) n
...
(gdb) n
...
21         printf("%u\n", *p);
(gdb) print/x ((unsigned char *)p)[0]
$1 = 0x83
(gdb) print/x ((unsigned char *)p)[1]
$2 = 0x7e
(gdb) print/x ((unsigned char *)p)[2]
$3 = 0xa3
(gdb) print/x ((unsigned char *)p)[3]
$4 = 0x38

>>
```

# Exercise 15

Implement **magnitude** without using signed integers.

*interp.c*

```
...
unsigned int magnitude( unsigned int value )
{
    if( value & (1<<31) ) return ~value+1;
    else return value;
}
...
```

# Exercise 15

Implement `set_seed`.

*random.c*

```
...  
void set_seed( int seed )  
{  
    srand( seed );  
}  
...
```

# Exercise 15

Implement `gen_uniform`.

*random.c*

```
...  
void set_seed( int seed )  
{  
    srand( seed );  
}  
  
int gen_uniform( int max_num )  
{  
    return rand() % max_num;  
}  
...
```

# Exercise 15

Generate 500 uniformly distributed random numbers and increment the associated elements of the **hist** array.

*random.c*

```
...  
int main( void )  
{  
    ...  
    for( unsigned int i=0 ; i<500 ; i++ ) hist[ gen_uniform(max_range) ]++;  
    ...  
}  
...
```

# Exercise 15

Implement `normal_rand`.

*random.c*

```
...
void set_seed( int seed )
{
    srand( seed );
}

int gen_uniform( int max_num )
{
    return rand() % max_num;
}

int normal_rand( int max_num )
{
    const unsigned int N = 20;
    int sum = 0;
    for( unsigned int n=0 ; n<N ; n++ ) sum += gen_uniform( max_num );
    return sum / N;
}
```



# Exercise 15

Generate 500 normally distributed random numbers and increment the associated elements of the **hist** array.

*random.c*

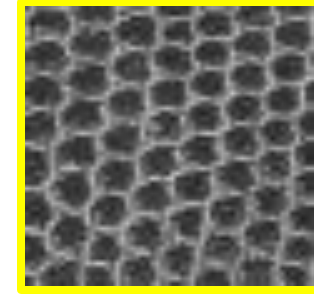
```
...  
int main( void )  
{  
    ...  
    for( unsigned int i=0 ; i<500 ; i++ ) hist[ normal_rand(max_range) ]++;  
    ...  
}  
...
```

# Outline

- Exercise 15
- Midterm project

# Midterm project

*exemplar*



## Goal:

Implement Efros and Leung's seminal work  
"Texture Synthesis by Non-parametric Sampling".

Given an exemplar texture image...

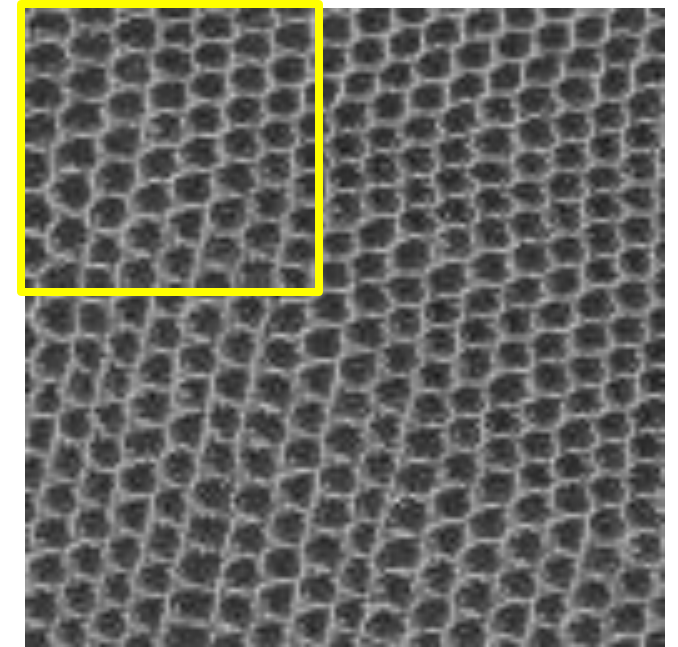
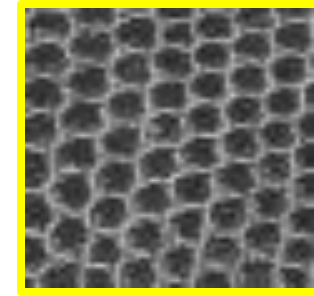
# Midterm project

## Goal:

Implement Efros and Leung's seminal work  
"Texture Synthesis by Non-parametric Sampling".

Given an exemplar texture image...  
synthesize a larger image by growing the texture.

*exemplar*



*synthesized\**

\*Recall that the pixel at (0,0) is the top left corner.

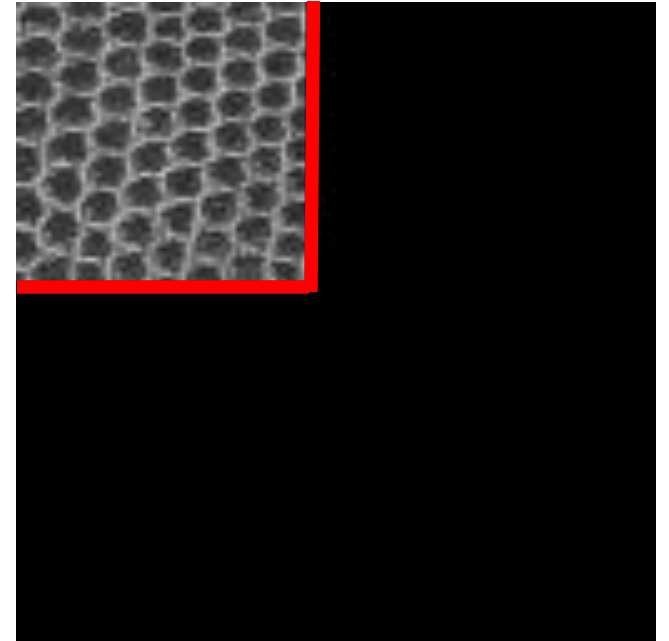
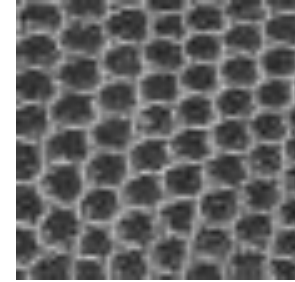
# Midterm project

## Approach:

To expand the exemplar, identify all boundary pixels – pixels whose values have not been synthesized yet but whose neighbors have.

Assign those to-be-set pixels (TBS pixels) a color by copying good color values from the exemplar.

*exemplar*



*synthesized*

# Midterm project

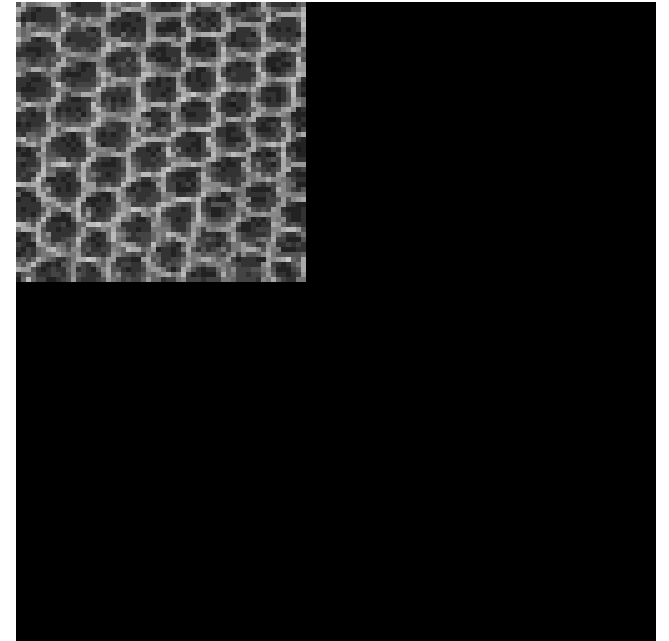
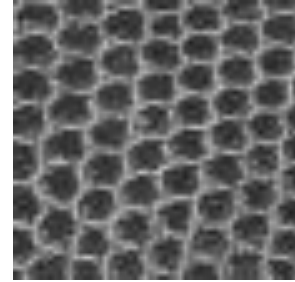
## Approach:

To expand the exemplar, identify all boundary pixels – pixels whose values have not been synthesized yet but whose neighbors have.

Assign those to-be-set pixels (TBS pixels) a color by copying good color values from the exemplar.

Repeat.

*exemplar*



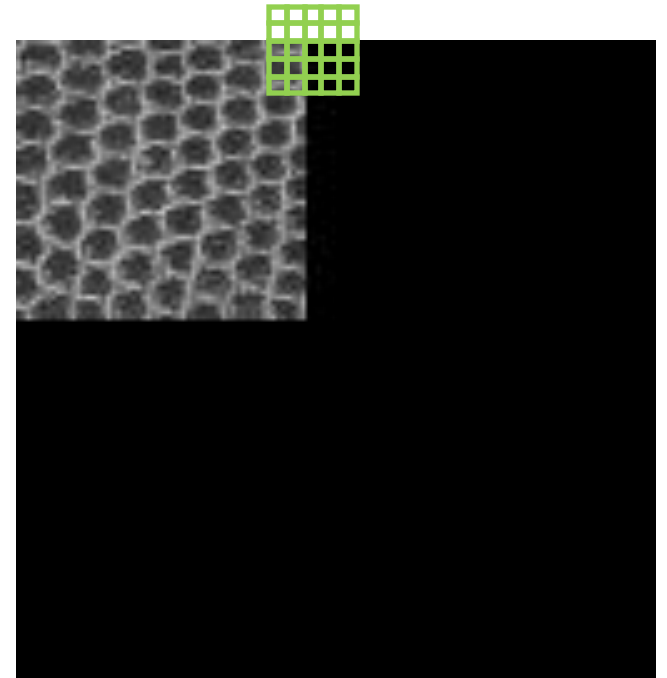
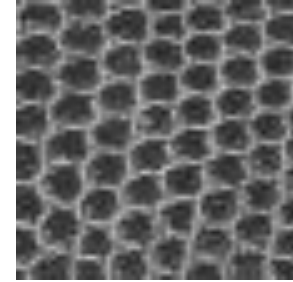
*synthesized*

# Midterm project

## Implementation (per TBS pixel):

- Center a  $(2r + 1) \times (2r + 1)$  window about the TBS pixel.
- For each exemplar pixel:
  - Measure how well the window about the exemplar pixel matches the window about the TBS pixel.

*exemplar*

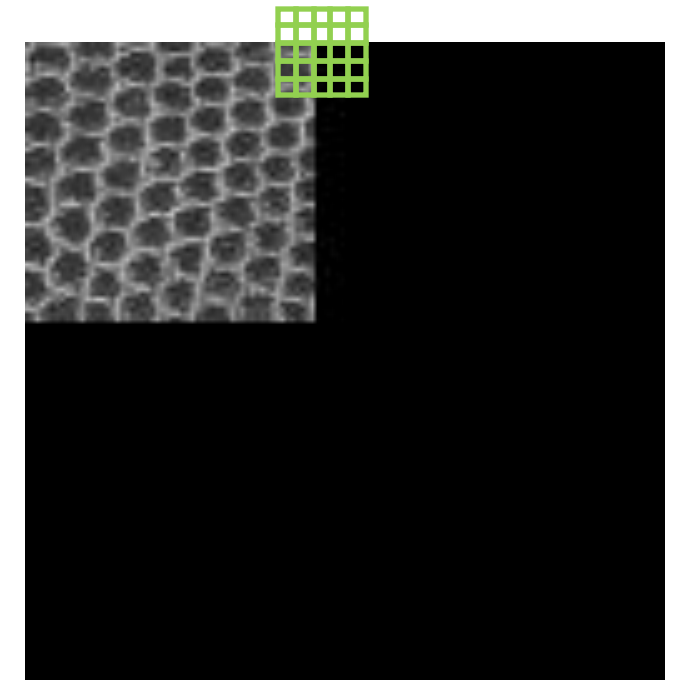
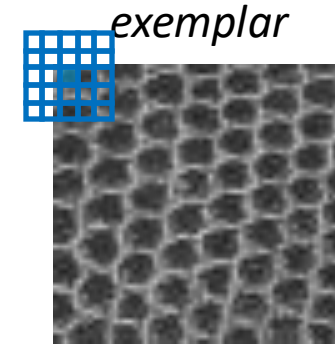


*synthesized*

# Midterm project

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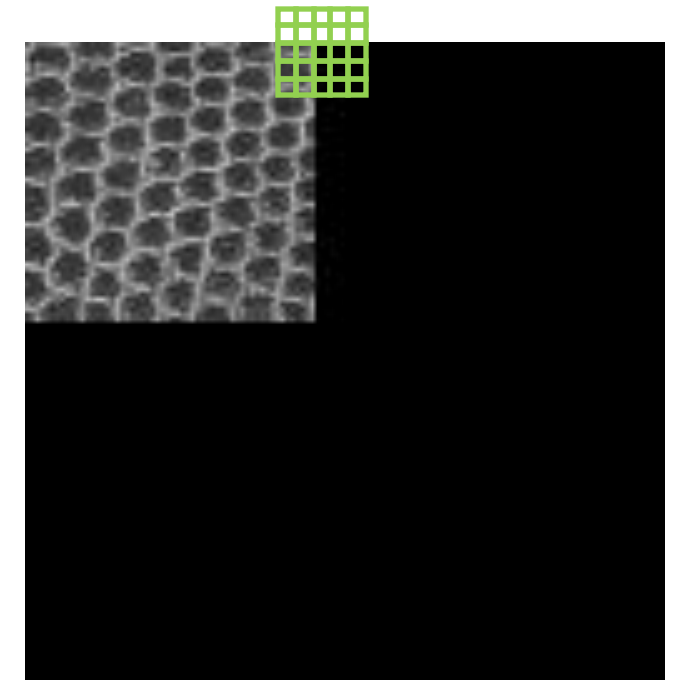
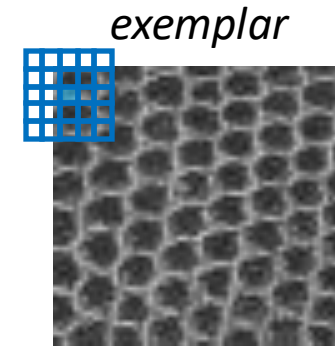




# Midterm project

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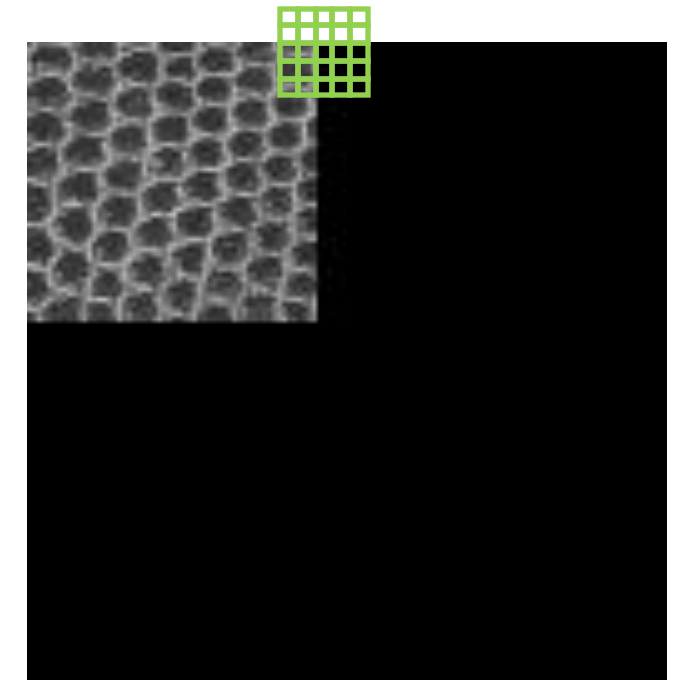
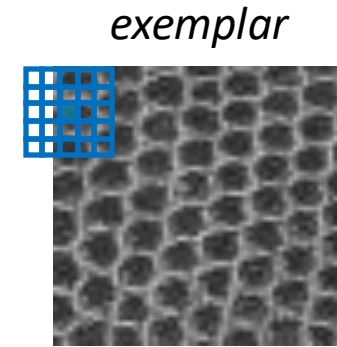


*synthesized*

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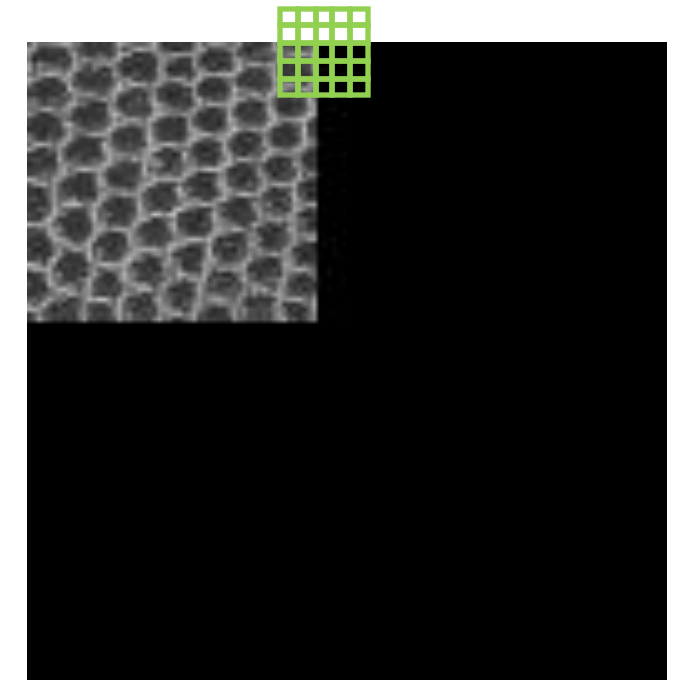
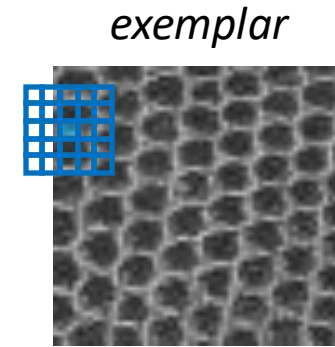


*synthesized*

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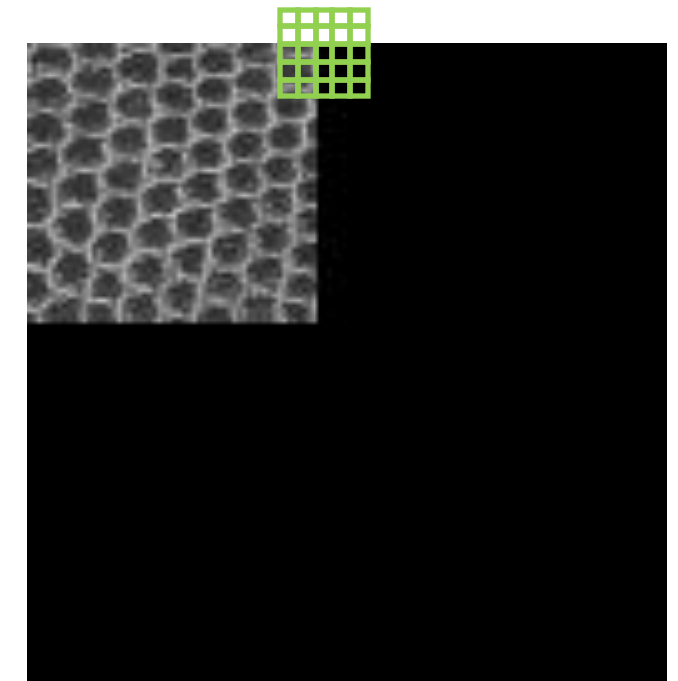
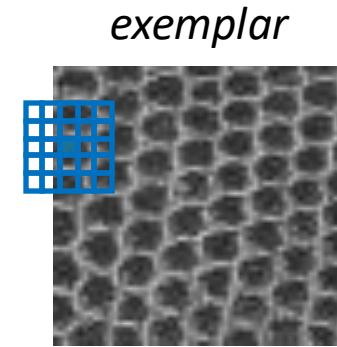


*synthesized*

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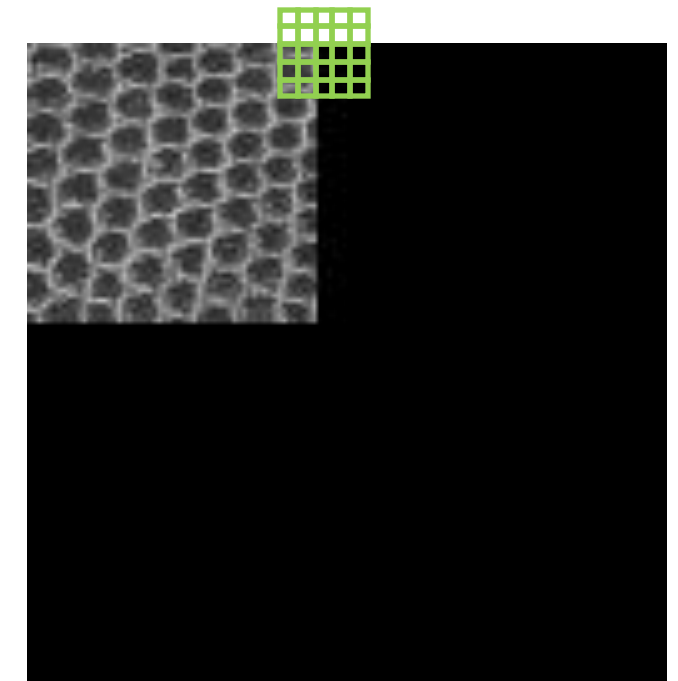
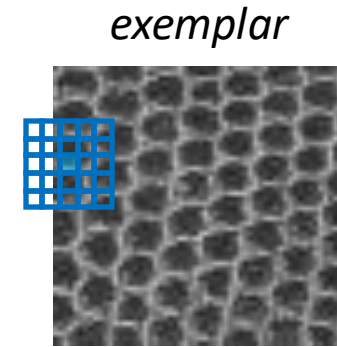


*synthesized*

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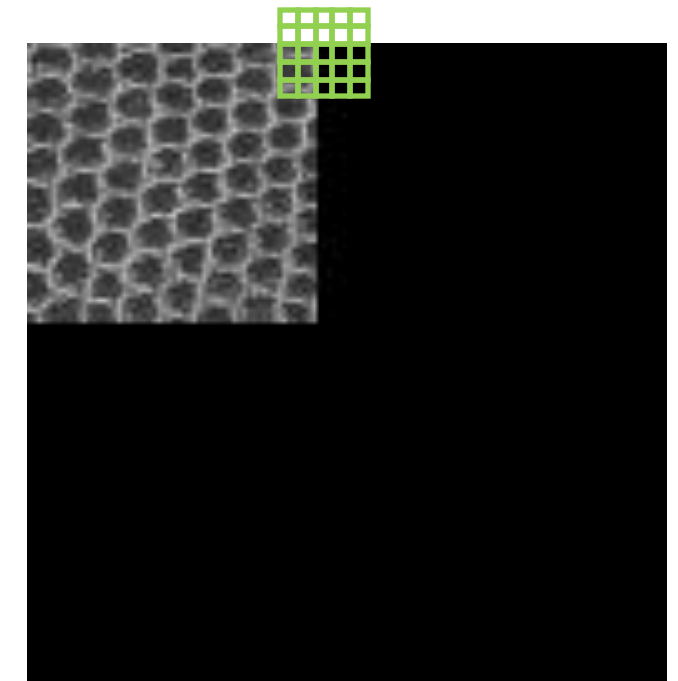
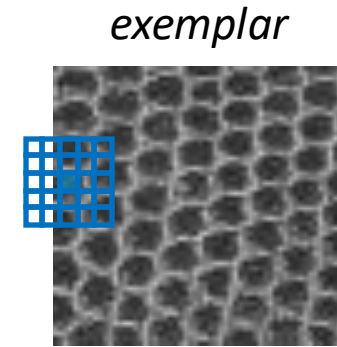


*synthesized*

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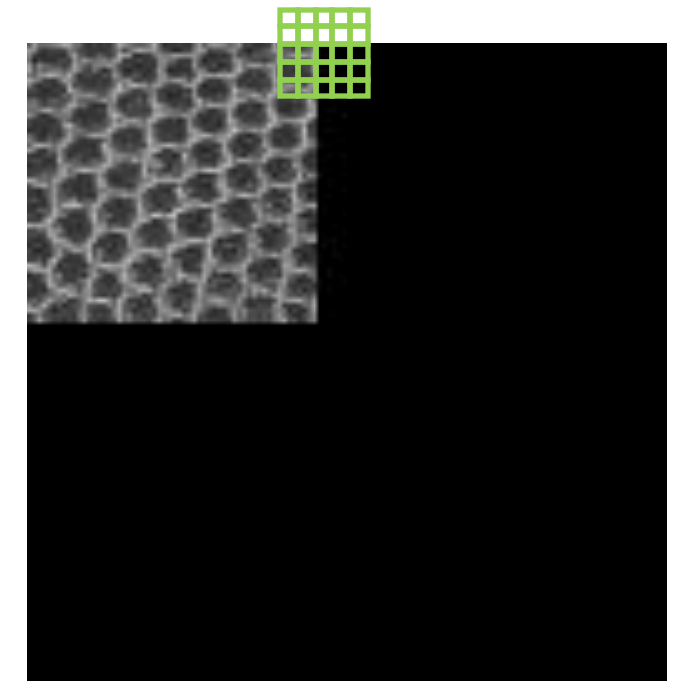
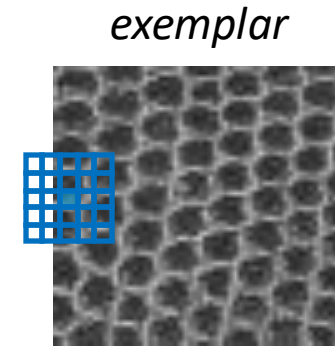


*synthesized*

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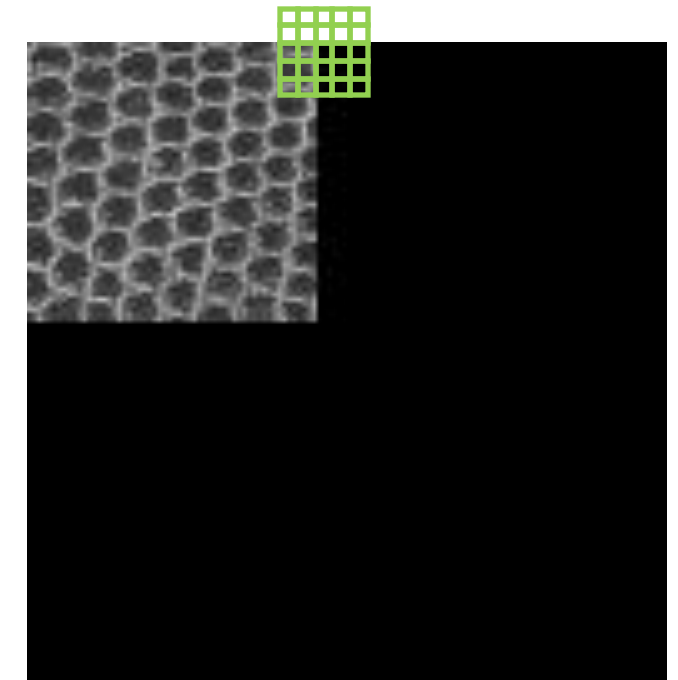
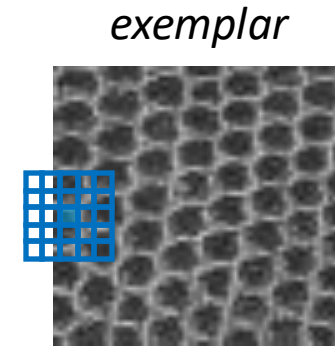


*synthesized*

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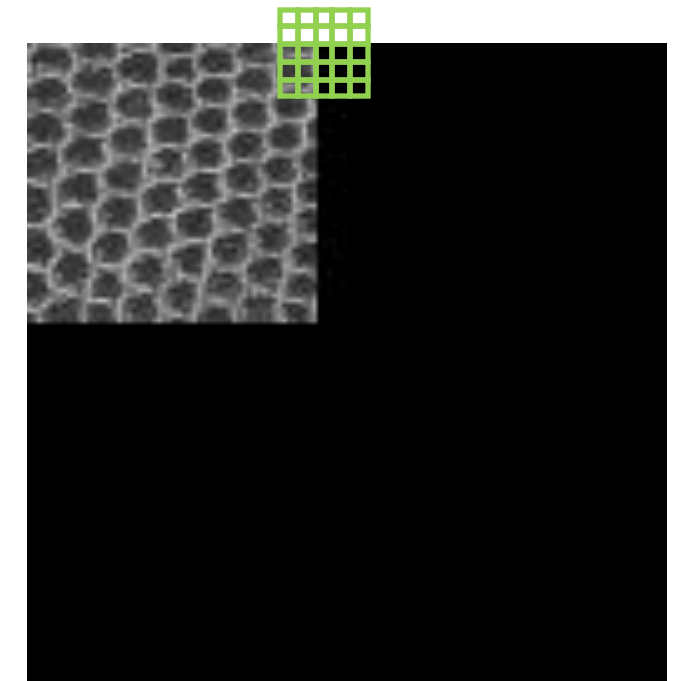
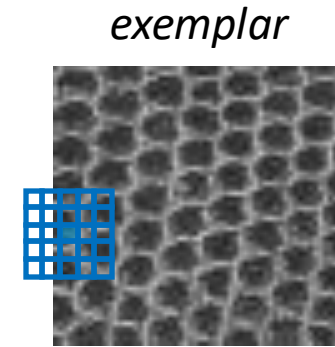
*synthesized*



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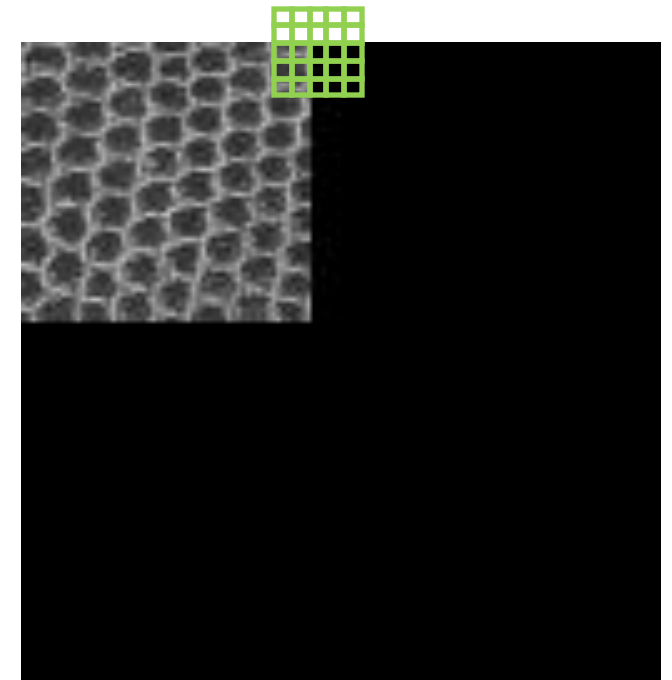
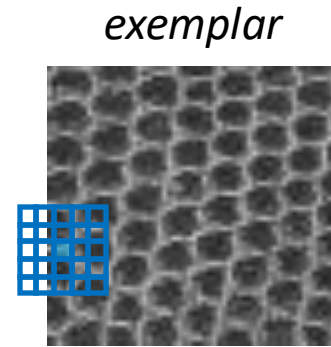


*synthesized*

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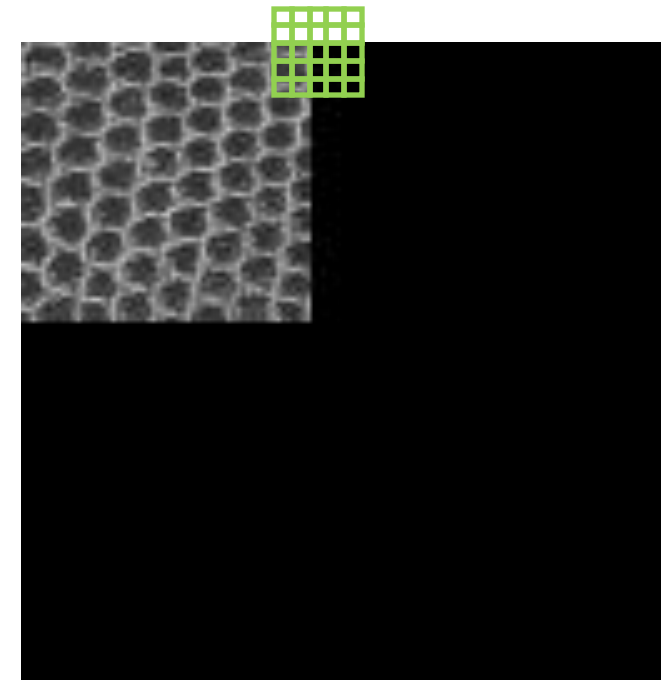
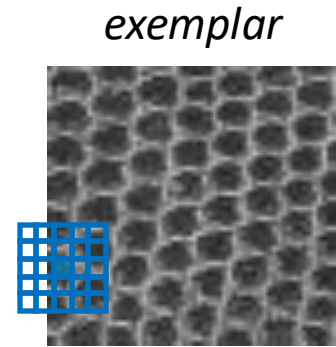


*synthesized*

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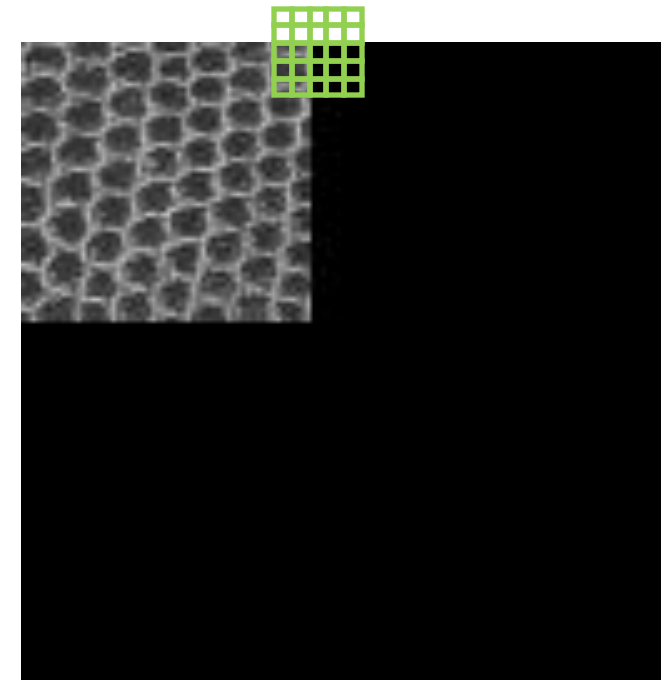
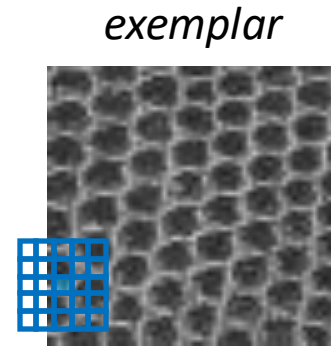


*synthesized*

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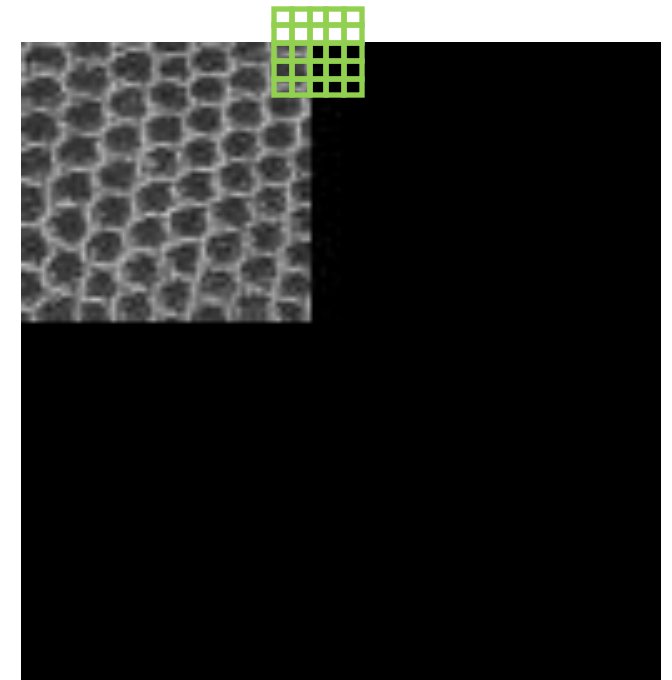
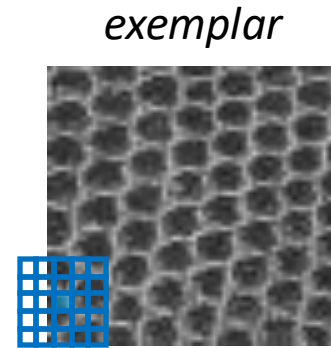


*synthesized*

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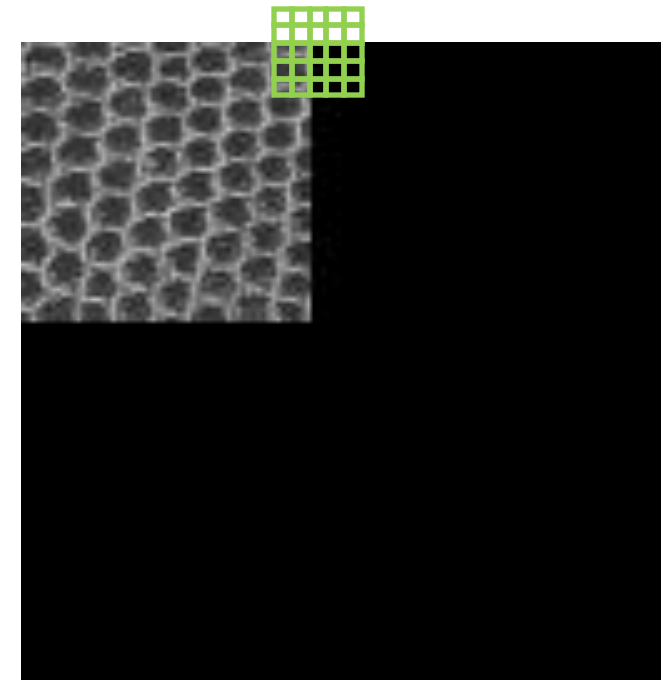
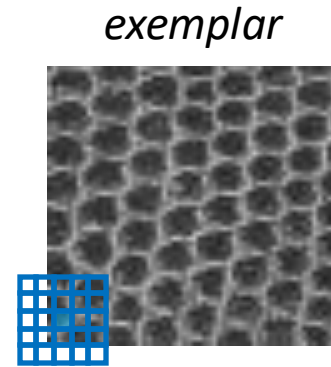


*synthesized*

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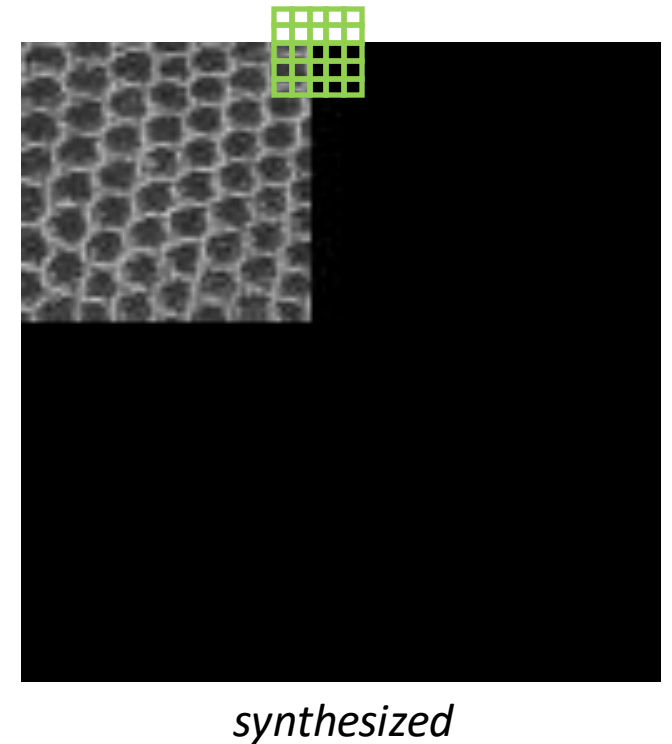
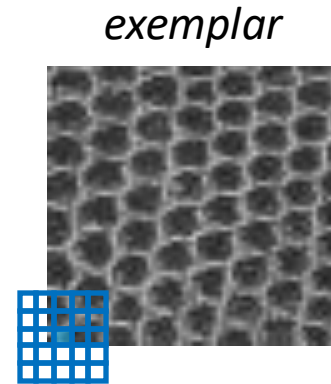


*synthesized*

# Midterm project

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# Midterm project

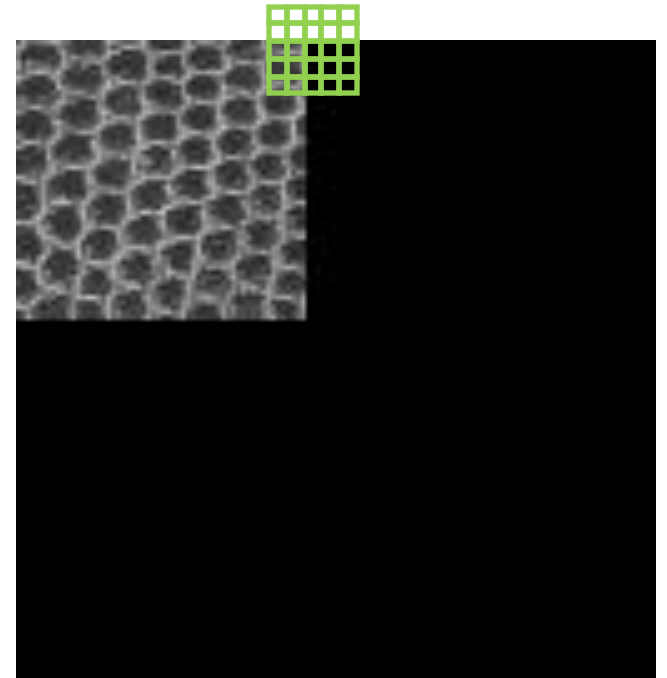
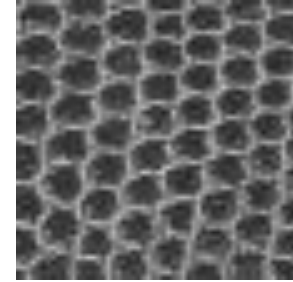
## Implementation (per TBS pixel):

- Center a  $(2r + 1) \times (2r + 1)$  window about the TBS pixel.
- For each exemplar pixel:
  - Measure how well the window about the exemplar pixel matches the window about the TBS pixel.
- Find the set of best matching exemplar pixels and select one at random from within the set.

This is done for **every** TBS pixel.

Once you've processed the current set of TBS pixels, you need to generate the next set.

*exemplar*



*synthesized*

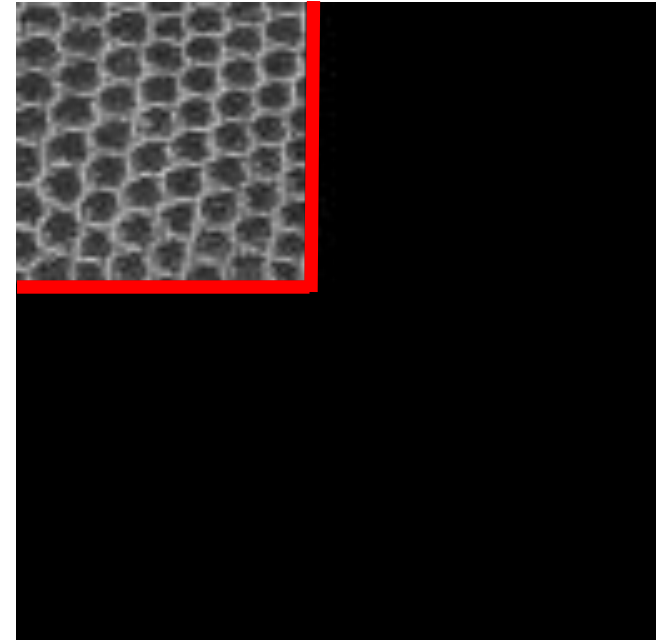
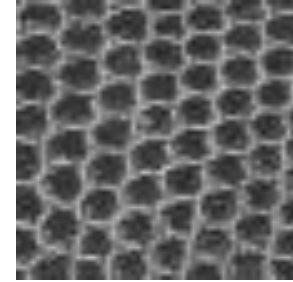


# Implementation details

## Processing the TBS pixels:

- You only want to process those pixels in the synthesized image that have not been *set* but have at least one (immediate) neighbor that has been *set*.
  - When setting values of the current set of TBS pixels you want to set the values of those TBS pixels with more *set* neighbors first.
- ⇒ You will need to sort the array of current TBS pixels.  
The function `SortTBSPixels` (in `image.[h/c]`) will help you with that.

*exemplar*



*synthesized*

# Aside

## Sorting:

Because of the importance of sorting, C defines (`stdlib.h` declares) a function for sorting an array values from smallest to largest:

```
void qsort( void *ptr , size_t count , size_t size , int (*cmp)(const void *, const void *) );
```

# Aside

## Sorting:

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- `ptr`: a pointer to the first element in the array

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- **ptr**: a pointer to the first element in the array
- **count**: the number of elements in the array

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- `ptr`: a pointer to the first element in the array
- `count`: the number of elements in the array
- `size`: the size of an element

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```
void qsort( void *ptr , size_t count , size_t size , int (*cmp)(const void *, const void *) );
```

- **ptr**: a pointer to the first element in the array
- **count**: the number of elements in the array
- **size**: the size of an element
- **cmp**: a pointer to a function taking two (**void**) pointers and returning an **int**
  - It returns a negative value if the first object pointed to is smaller than the second.
  - It returns a positive value if the first object pointed to is larger than the second.
  - It returns zero if they are the “same”.

# Aside

## Sorting:

Because of the importance of function for sorting an array

`void qsort( void *ptr , size_t count ,`

- **ptr**: a pointer to the first element
- **count**: the number of elements
- **size**: the size of an element
- **cmp**: a pointer to a function

- It returns a negative value if the first object pointed to is smaller than the second.
- It returns a positive value if the first object pointed to is larger than the second.
- It returns zero if they are the “same”.

*sort\_ints.c*

```
#include <stdio.h>
#include <stdlib.h>
```

```
int cmp_ints( const void *v1 , const void *v2 ){ return *(int *)v2-*(int *)v1; }
```

```
int main( void )
{
```

```
    int a[5];
```

```
    for( unsigned int i=0 ; i<5 ; i++ ) a[i] = rand();
```

```
    printf( "Unsorted:\n" );
```

```
    for( unsigned int i=0 ; i<sz ; i++ ) printf( "\t %d] %d\n" , i , a[i] );
```

```
    qsort( a , 5 , sizeof(int) , cmp_ints );
```

```
    printf( "Sorted:\n" );
```

```
    for( unsigned int i=0 ; i<sz ; i++ ) printf( "\t %d] %d\n" , i , a[i] );
```

```
    return 0;
```

```
}
```

# Aside

## Sorting:

Because of the importance of function for sorting an array

`void qsort( void *ptr , size_t count ,`

- **ptr**: a pointer to the first element
- **count**: the number of elements
- **size**: the size of an element
- **cmp**: a pointer to a function taking two (void) pointers and returning an int
  - It returns a negative value if the first object pointed to is smaller than the second
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```
#include <stdio.h>
#include <stdlib.h>
```

```
int cmp_ints( const void *v1 , const void *v2 ){ return *(int *)v2-*(int *)v1; }
```

```
int main( void )
{
```

```
    int a[5];
    for( unsigned int i=0 ; i<5 ; i++ ) a[i] = rand();
```

```
    printf( "Unsorted:\n" );
```

```
    for( unsigned int i=0 ; i<sz ; i++ ) printf( "%d\t", a[i] );
```

```
    qsort( a , 5 , sizeof(int) , cmp_ints );
```

```
    printf( "Sorted:\n" );
```

```
    for( unsigned int i=0 ; i<sz ; i++ ) printf( "%d\t", a[i] );
```

```
    return 0;
}
```

*sort\_ints.c*

```
>> ./a.out
```

Unsorted:

```
0] 1804289383
1] 846930886
2] 1681692777
3] 1714636915
4] 1957747793
```

Sorted:

```
0] 1957747793
1] 1804289383
2] 1714636915
3] 1681692777
4] 846930886
```

```
>>
```



# Aside

## Sorting:

Because of the importance of function for sorting an array

`void qsort( void *ptr , size_t count ,`

- **ptr**: a pointer to the first element
- **count**: the number of elements
- **size**: the size of an element
- **cmp**: a pointer to a function

### Note:

The sorted list is decreasing because **cmp\_ints** returns the value of the second minus the value of the first.

```
#include <stdio.h>
#include <stdlib.h>
```

```
int cmp_ints( const void *v1 , const void *v2 ){ return *(int *)v2-*(int *)v1; }
```

```
int main( void )
{
```

```
    int a[5];
    for( unsigned int i=0 ; i<5 ; i++ ) a[i] = rand();
```

```
    printf( "Unsorted:\n" );
```

```
    for( unsigned int i=0 ; i<sz ; i++ ) printf( "%d ", a[i] );
```

```
    qsort( a , 5 , sizeof(int) , cmp_ints );
```

```
    printf( "Sorted:\n" );
```

```
    for( unsigned int i=0 ; i<sz ; i++ ) printf( "%d ", a[i] );
```

```
    return 0;
}
```

*sort\_ints.c*

```
>> ./a.out
```

Unsorted:

0] 1804289383

1] 846930886

2] 1681692777

3] 1714636915

4] 1957747793

Sorted:

0] 1957747793

1] 1804289383

2] 1714636915

3] 1681692777

4] 846930886

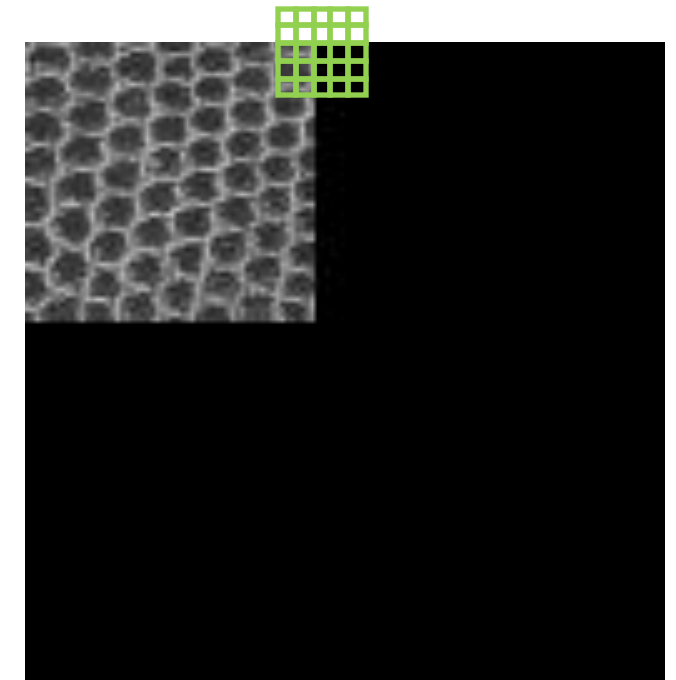
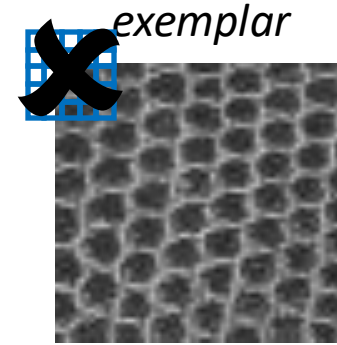
```
>>
```

# Implementation details

## Comparing TBS and exemplar windows:

- You should only consider an exemplar pixel as a candidate match for a TBS pixel if:

For every *set* neighbor within the TBS window, the corresponding pixel about the exemplar pixel is within the exemplar image.



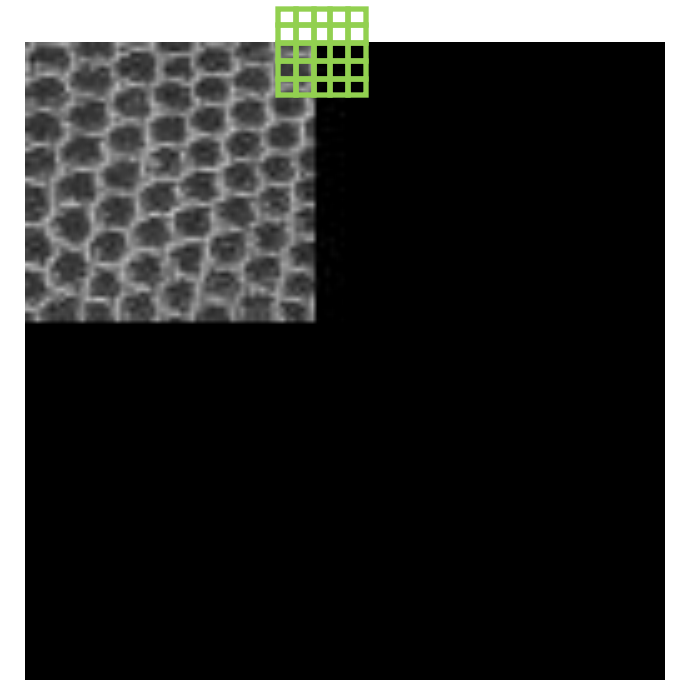
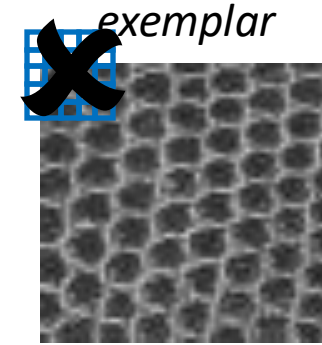
*synthesized*

# Implementation details

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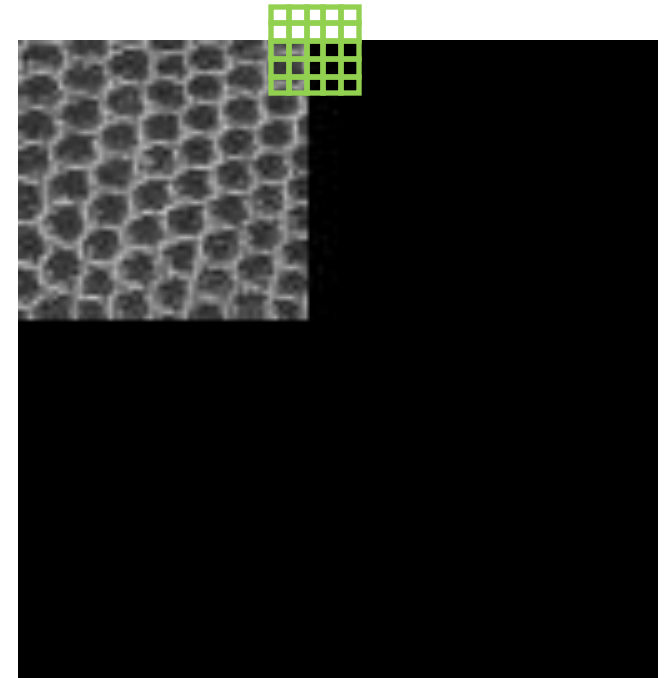
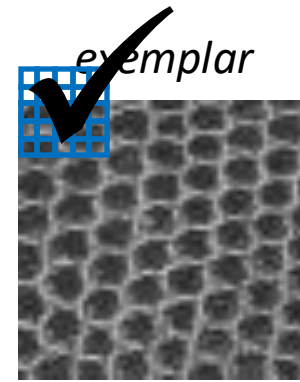
*synthesized*

# Implementation details

## Comparing TBS and exemplar windows:

- You should only consider an exemplar pixel as a candidate match for a TBS pixel if:

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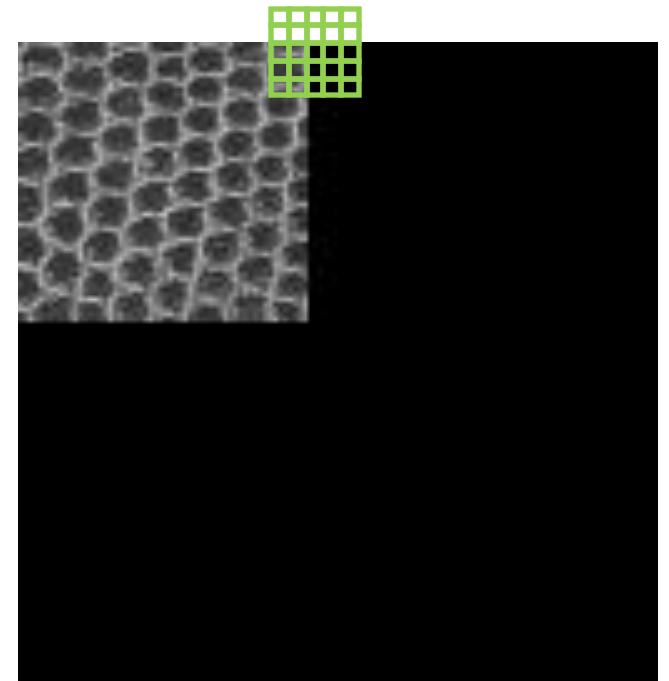
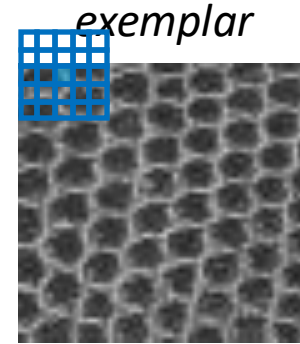


*synthesized*

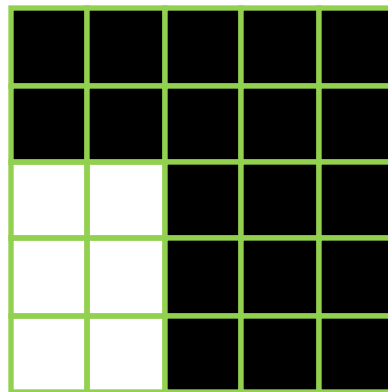
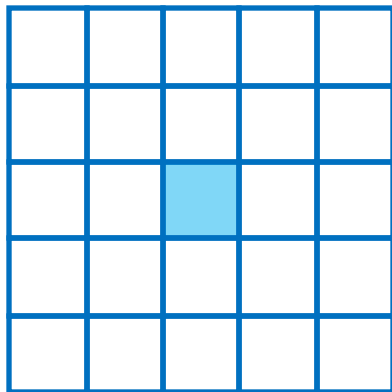
# Implementation details

## Comparing TBS and exemplar windows:

- For each pixel about the TBS pixel that is *set*
  - Sum the *weighted* squared differences of the red, green, and blue values of corresponding pixels.



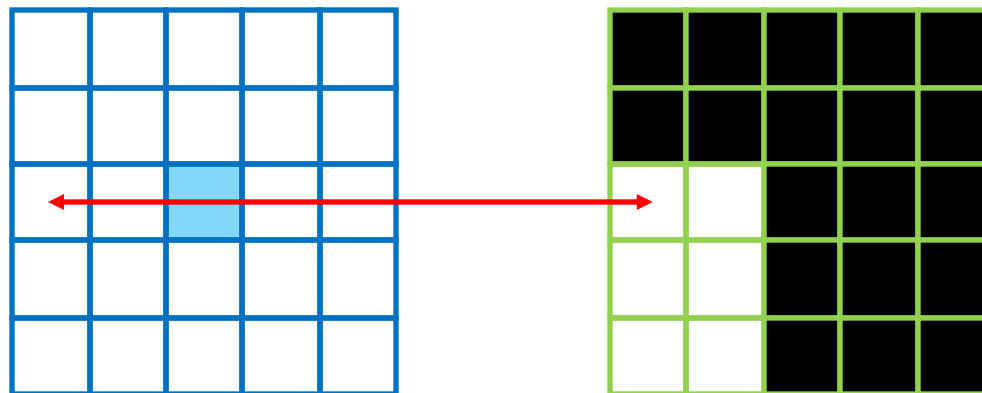
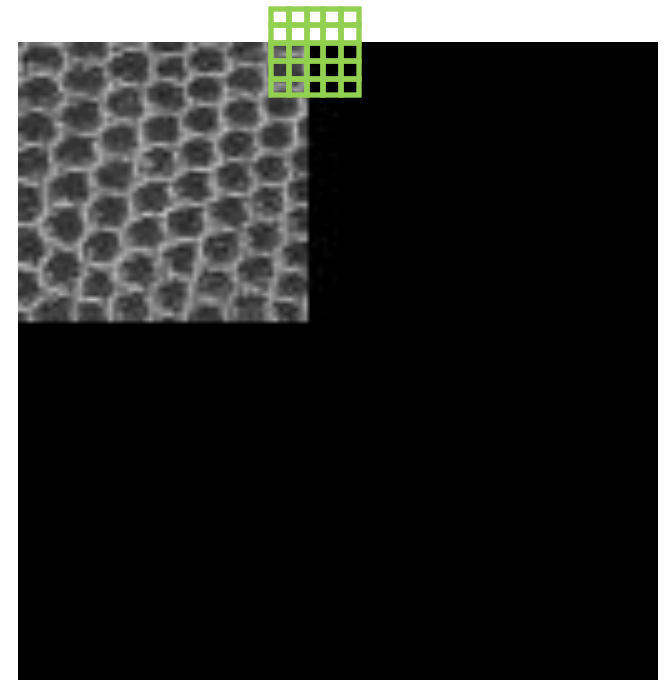
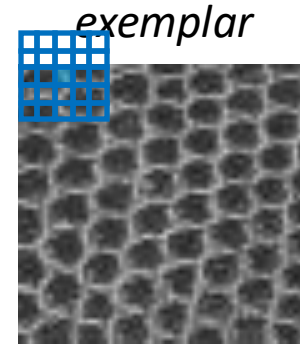
*synthesized*



# Implementation details

## Comparing TBS and exemplar windows:

- For each pixel about the TBS pixel that is *set*
  - Sum the *weighted* squared differences of the red, green, and blue values of corresponding pixels.

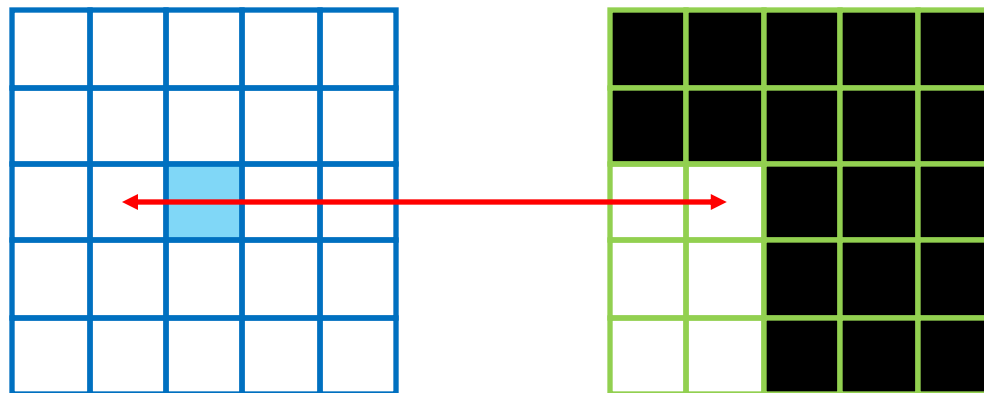
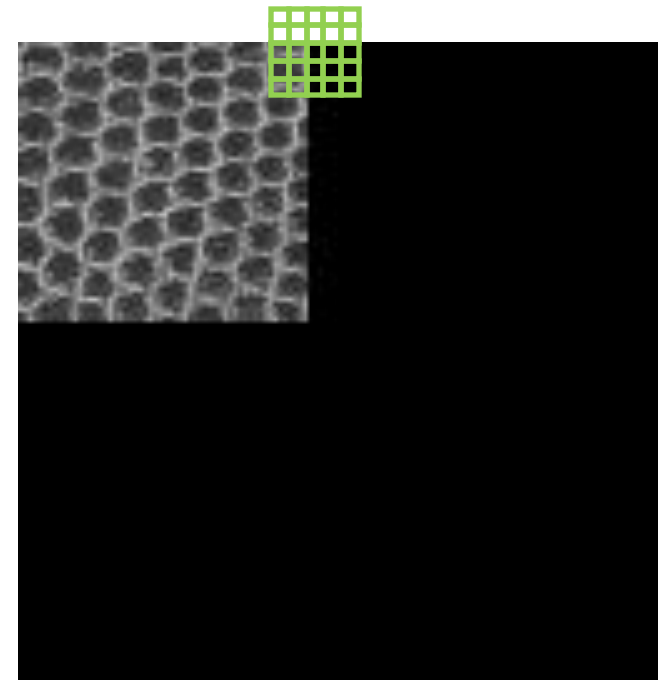
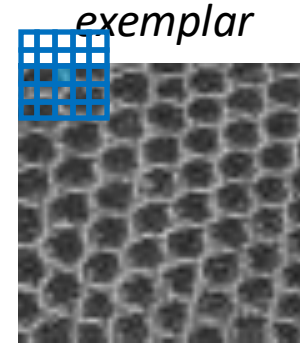


Visualization for  $r = 2$ .

# Implementation details

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- For each pixel about the TBS pixel that is *set*
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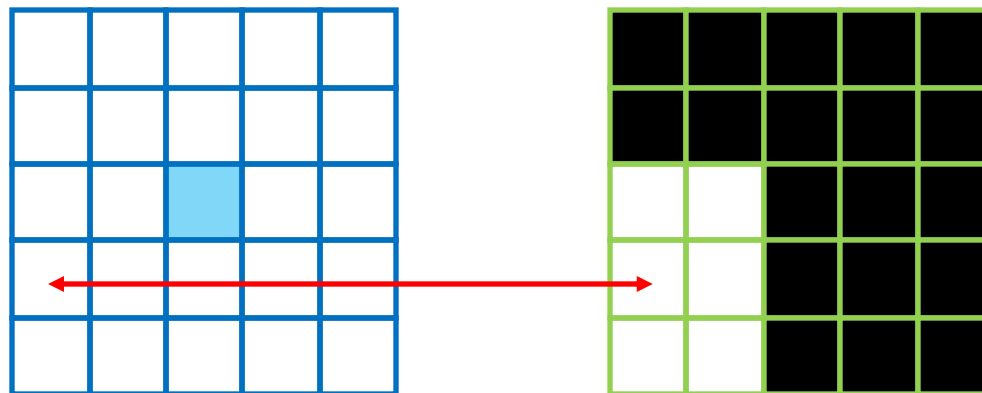
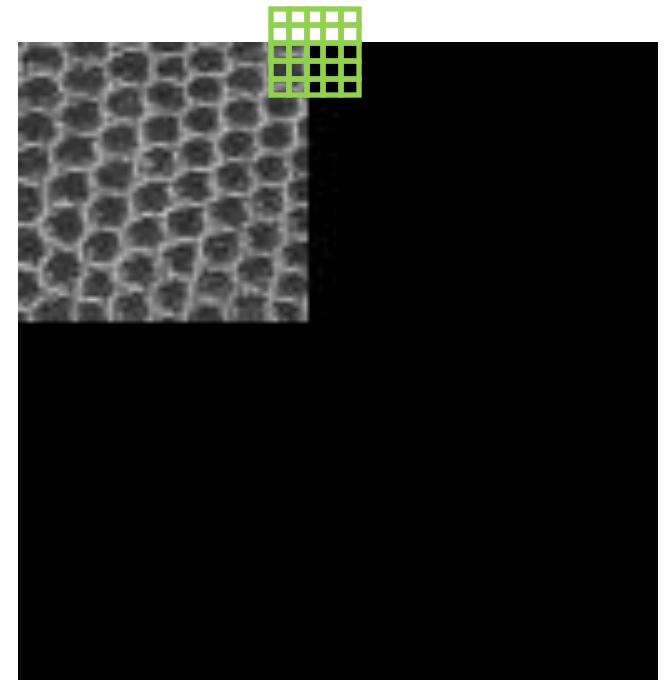
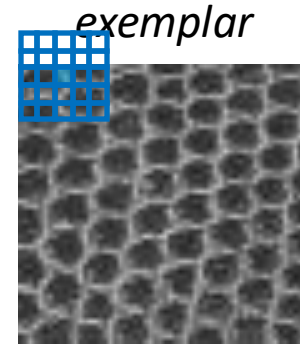


Visualization for  $r = 2$ .

# Implementation details

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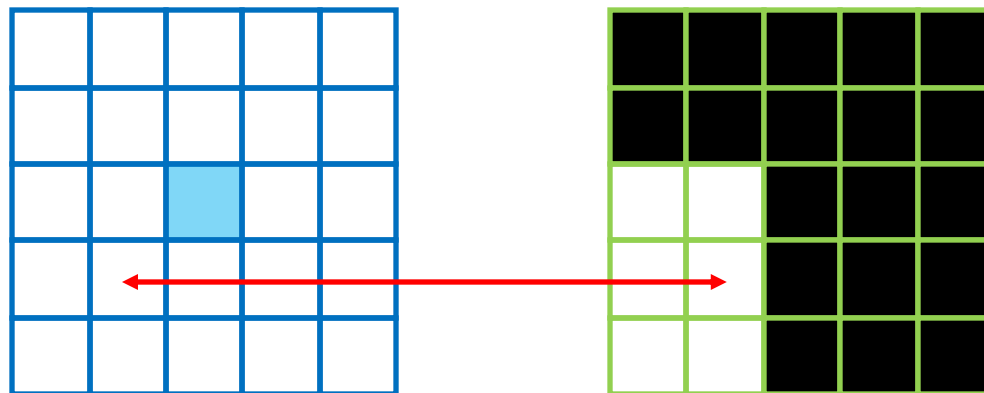
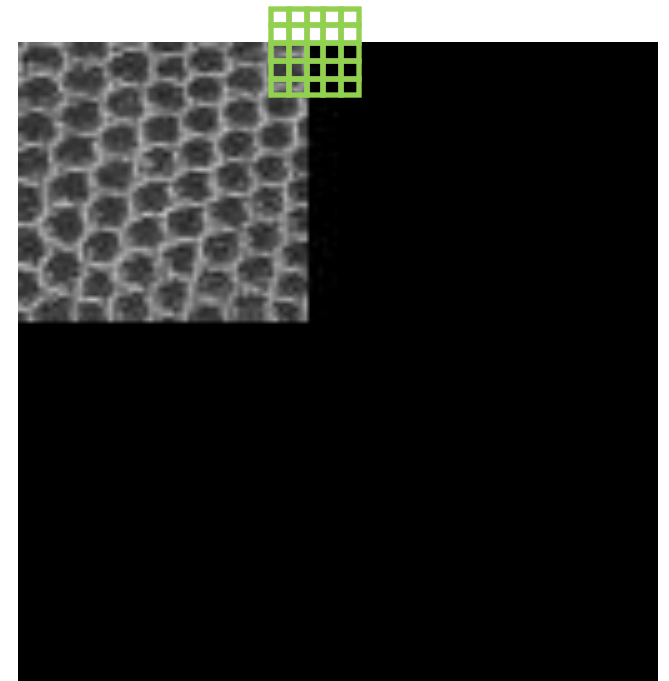
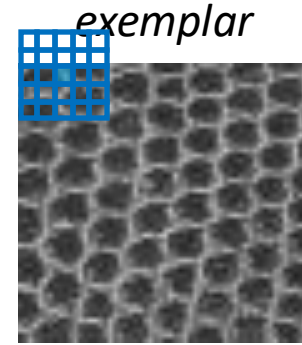
Visualization for  $r = 2$ .



# Implementation details

## Comparing TBS and exemplar windows:

- For each pixel about the TBS pixel that is *set*
  - Sum the *weighted* squared differences of the red, green, and blue values of corresponding pixels.

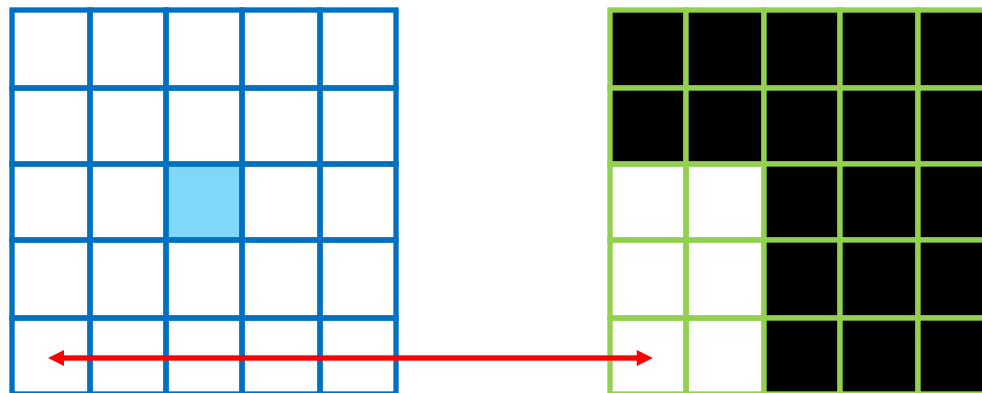
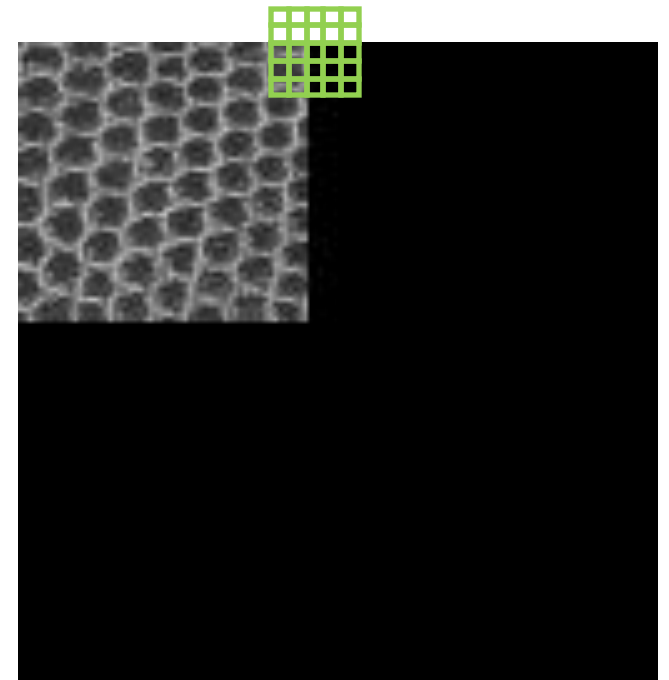
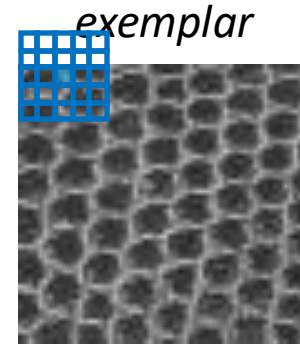


Visualization for  $r = 2$ .

# Implementation details

## Comparing TBS and exemplar windows:

- For each pixel about the TBS pixel that is *set*
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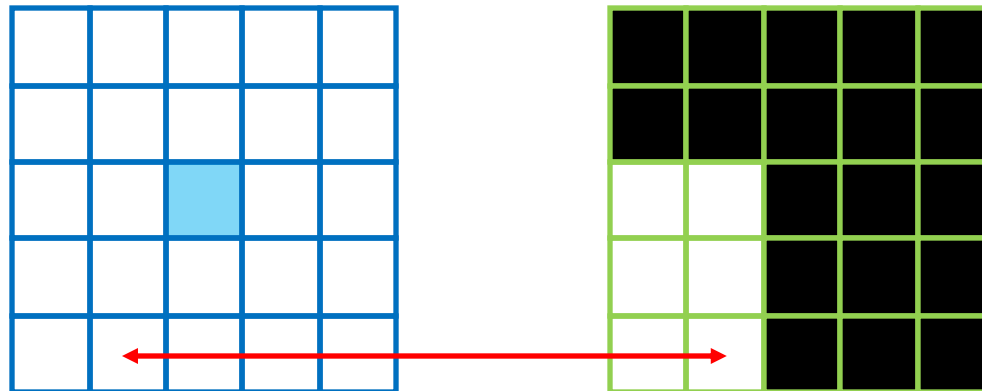
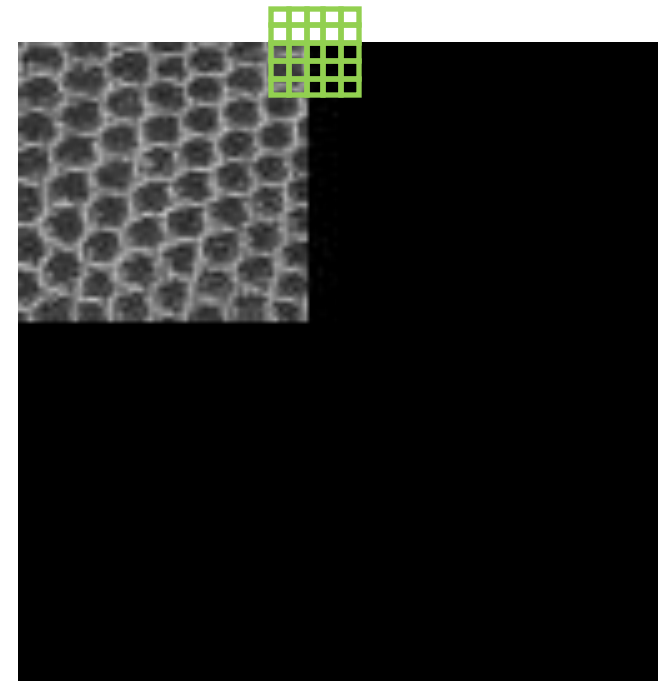
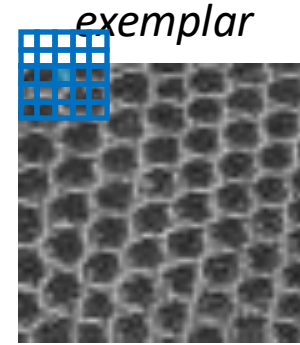


Visualization for  $r = 2$ .

# Implementation details

## Comparing TBS and exemplar windows:

- For each pixel about the TBS pixel that is *set*
  - Sum the *weighted* squared differences of the red, green, and blue values of corresponding pixels.



Visualization for  $r = 2$ .

# Implementation details

## Comparing TBS and exemplar windows:

- For each pixel about the TBS pixel that is *set*
  - Sum the *weighted* squared differences of the red green, and blue values of corresponding pixels.
  - The weight assigned to a pixel difference is given by a Gaussian with standard deviation  $\sigma = \frac{2r+1}{6.4}$

$$w_{ij} = \exp\left(-\frac{i^2 + j^2}{2\sigma^2}\right)$$

where  $i$  and  $j$  are the horizontal and vertical coordinates of the pixel in the window relative to the center.

(-2,-2)	(-1,-2)	(0,-2)	(1,-2)	(2,-2)
(-2,-1)	(-1,-1)	(0,-1)	(1,-1)	(2,-1)
(-2,0)	(-1,0)	(0,0)	(1,0)	(2,0)
(-2,1)	(-1,1)	(0,1)	(1,1)	(2,1)
(-2,2)	(-1,2)	(0,2)	(1,2)	(2,2)

*window indexing (i,j)*

# Implementation details

## Finding the set of best-matching exemplar pixels:

1. Identify the exemplar pixel minimizing the weighted sum of squared differences to the TBS pixel.
2. Let  $d_{min}$  be the weighted sum of squared difference for that exemplar pixel.
3. Define the set of best matching exemplar pixels to be those pixels whose weighted sum of squared differences to the TBS pixel is no larger than 1.1 times  $d_{min}$ .