Helices of RNAs

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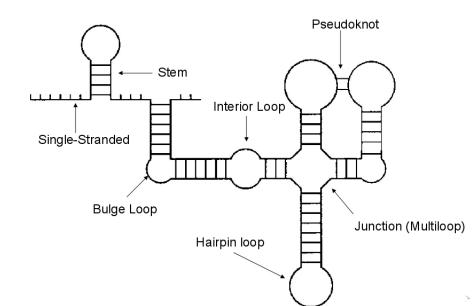
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Outline

- RNA secondary structure components and classical algorithms
- Introducing concept of abstract shapes
- Development of a new structure abstraction
- Outlook

Secondary structure components of RNA



Classical secondary structure algorithms (Zuker 1981)

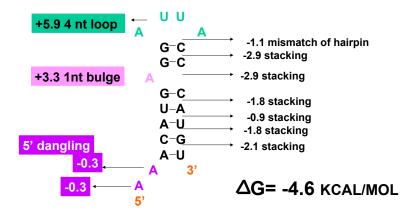
Simplifying Assumptions for Structure Prediction

- RNA folds into one minimum free-energy structure.
- There are no knots (base pairs never cross).

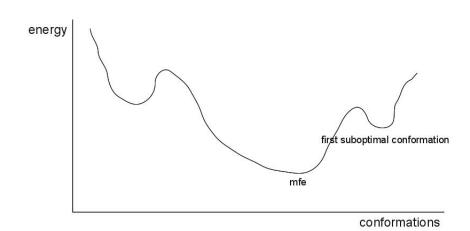
RNA has different structural domains

- single-stranded regions (first described by Zuker and Stiegler in 1981)
- RNA folding are stabilized by the stacking or by dangling end
- destabilized by hairpin, internal and bulge loops
- the runtime is $O(n^3)$

Free energy computation example



energy landscape



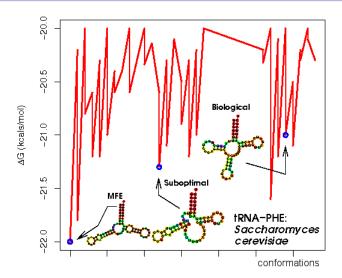
Suboptimal structures

But the "true" structure is not always the one with the lowest predicted free energy. So what to do?

- Enumerate suboptimal structures within a given energy range R.
- Hope to find a structure fulfilling your expectation or coming close to experimental results.

But the number of suboptimal structures grows exponentially with the energy range considered.

energy landscape

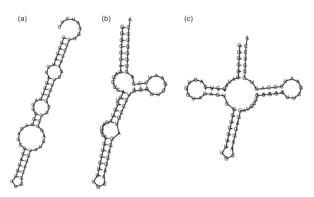


Introducing abstract shapes

Solution: Use abstract shapes to describe a set of structures.

- developed by Giegerich and Voss
- An abstract shape represents a class of similar structures sharing a common pattern of helix nesting and adjacency.
- "Abstract" since we do not care about all details of the structures.
- Each shape class has a representative structure called shrep (with minimum folding energy).

Abstract shape, energy range: 5 kcal/mol



Drawback of abstract shape

 The major drawback of abstract shape analysis is the position independence of the abstraction

Drawback example 1 of abstract shape

AACUAAAACAAUUUUUGAAGAACAGUUUCUGUACUUCAUUGGUAUGUAGAGACUUC

Drawback example 2 of abstract shape

develop a new structure abstraction

The straightforward idea to overcome the position independence of the current available shape abstractions is

the position of which secondary structure domains will be tracked

- helical regions of hairpin loop
- helical regions of multiloops
- helical regions of stacked pairs, bulge and internal loops

which positions of the vordefined structure domain will be tracked

- i
- j
- (i,j)
- i+j/2

helices positions example

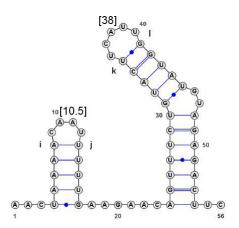
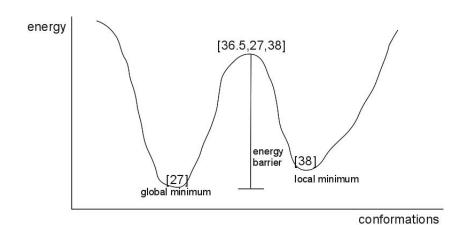


Figure: The structure is composed of two helices which are closed by hairpin loops (i,j) and (k,l), respectively. The positions are: i=8, j=13, k=35 and l=41. Thus, this structure would be abstracted to [10.5,38]

Output from the first trial version of helices shape

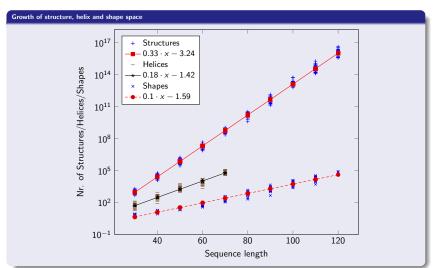
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Helices shape, Energy range: 5 kcal/mol
-6.7 ..((..((....))..))...((((((((((....)))))..))))).. [11.5.38]
 .(((((.....((((((((...)))))))))))).((...))... [27,49.5]
 -4.2 .(((((.....(((((...))))))))))))...((...)).. [27,51]
[9.5,27,22.5]
-3.3 .(((((.....(((((((...)))).)))))))),...((...)), [27.51.5]
-3.3 ..((((....))....))...((((((((((....)))))..))))).. [9,38]
 .(((((.....((((((((...)))).))))))))....((...)). [27.52]
 -2.3 .....((((,,(((,,,)))((((,,,,)))),...,)))) [36.5.27.38] *
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energy barrier



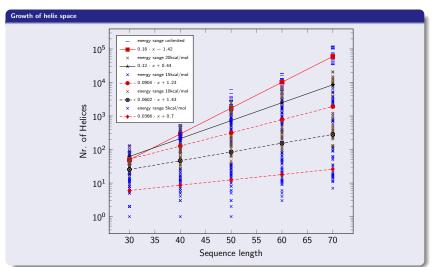
Possible problem

Although the helices space grows considerably slower than structure space, but it is still exponential



Solution of possible problem

One of the solution: we limit the helices space by setting an energy range on it



Outlook: Designing RNA class predictors

- Development of a new structure abstraction (helices index)
- Implementation of an algorithm based on the structure abstraction
- Evaluating the algorithm
- Designing RNA class predictors.

End

- Thanks a lot for your attention !
- Questions ?