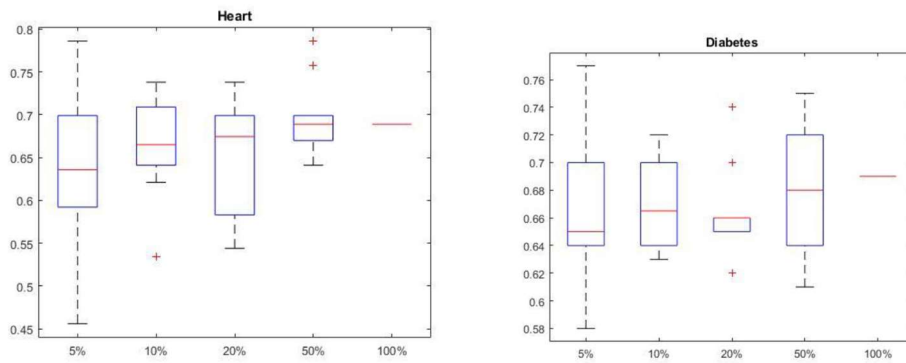
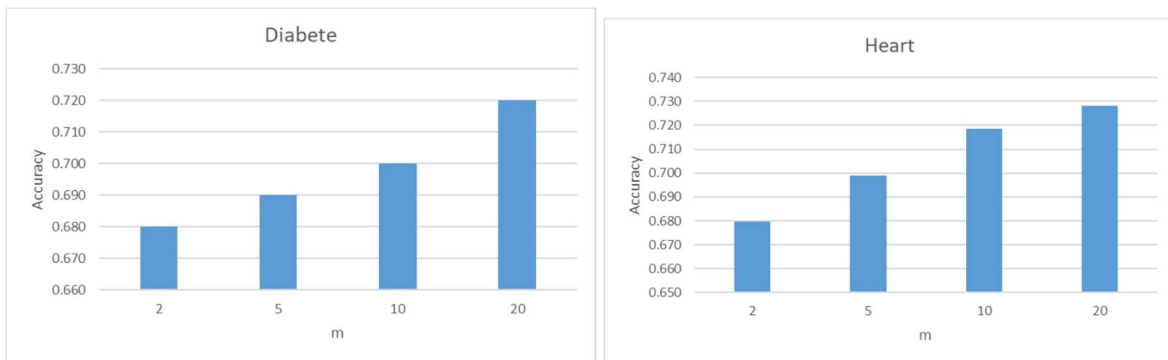


Part 2



Part 3



Part 4

1. Information Theory

(a) If $H(X|Y) = H(X)$ then X and Y are independent.

True:

$$I(X; Y) = H(X) - H(X|Y)$$

If $I(X; Y) = 0$ then $H(X) = H(X|Y)$. We can write:

$$I(X; Y) = D(P_{X,Y} \parallel P_X P_Y) = 0$$

$D(Q \parallel P) = 0$ iff $P(x) = Q(x) \forall x$, therefore $P_{X,Y}(x, y) = P_X(x)P_Y(y)$ for every x, y and as result $X \perp Y$.

2. Standardize the data set with four points in 2 dimension: $(7, 7), (3, 7), (3, 3), (7, 3)$;

$u_1 = 5, u_2 = 5, \sigma_1 = 2, \sigma_2 = 2$,

$(7, 7) \rightarrow (1, 1)$

$(3, 7) \rightarrow (-1, 1)$

(3, 3) \rightarrow (-1, -1)
(7, 3) \rightarrow (1, -1)

3. KNN

- (1) 1NN: x3 is the closest, then its label is 1.
- (2) 2NN: x2, x3, x4 are the closest, then its label is 1.
- (3) 3NN: We need to get the reciprocal value of the distance, then its label is 1.

4. Performance Measurements

- (1) Accuracy = $(TP+TN)/(TP+FP+FN+TN) = (76+82)/(76+18+24+82) = 0.79$
- (2) Error = $1 - \text{Accuracy} = 0.21$
- (3) True positive rate = $TP/\text{actual pos} = TP/(TP+FN) = 76/(76+24) = 0.76$
- (4) False positive rate = $FP/\text{actual neg} = FP/(TN+FP) = 18/(18+82) = 0.18$
- (5) Precision = $TP/\text{predicted pos} = TP/(TP+FP) = 76/(76+18) = 0.8085$
- (6) Recall = $TP/\text{actual pos} = TP/(TP+FN) = 76/(76+24) = 0.76$