Lecture 9: Interpreter runtime structures

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Today

- ► Scopes, environments, function calls
- ▶ Implementing functions and function calls
- Closures
- ► Memory management, garbage collection

Scopes, environments, and function calls

Scope, lifetime

- ► Scope: in what region(s) of the program is a particular variable visible?
- ▶ Lifetime: when in the execution of the program does a variable exist?
- ► These are related but distinct concepts

```
var a, b, c;
a = 1;
b = 2;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

var a, b, c;

```
a = 1;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

scope of global variable a

var a, b, c;

a = 1;

```
c = 3:
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b:
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

scope of global variable a

global variable a not visible here: shadowed by parameter a

```
var a, b, c;
a = 1;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
scope of global variable b
```

```
scope of global variable b
var a, b, c;
c = 3:
                           global variable b not visible
here: shadowed by local variable
function add1(a) {
  var b;
  b = 1:
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
var a, b, c;
a = 1;
b = 2:
c = 3:
function add1(a) {
 var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
```

```
global variable c's scope is

the entire program

not shadowed by any
identically-named parameters
or local variables
```

```
var a, b, c;
                           global variable c's scope is
b = 2:
                           the entire program
c = 3;
function add1(a) {
                              _ not shadowed by any
                               identically-named parameters
or local variables
 var b;
        Assignment to 1
glabal variable!
 a + b:
var d:
d = add1(c);
println(a);
println(b);
println(c);
```

```
var a, b, c;
a = 1;
b = 2;
c = 3;
                         scope of parameter a:
body of function
function add1(a) {
 var b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
var a, b, c;
a = 1;
b = 2;
c = 3;
                           scope of local variable b:
from point of definition to
end of function body
function add1(a) {
  var b
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
var a, b, c;
a = 1;
b = 2;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
                         scope of global variable d:
point of definition to end of module
var d
d = add1(c);
println(a);
println(b);
println(c);
d;
```

Variable lifetime

- Global variables exist for the duration of the execution of the program
- ▶ Parameters and local variables exist for the duration of a function call
 - ► Call stack: each call pushes an activation record
 - ▶ A calls B, B calls C, C calls D, etc. arbitrarily many calls can be in progress at any point
 - ▶ In practice, the call stack is usually limited in size
 - Recursion: A calls itself
 - Caller and callee always have distinct activation records

Environment

- ► We'll use the term *environment* for a data structure containing a collection of variables that have a common lifetime
- ► Global environment: has definitions of global variables
 - ► Global variables are visible throughout the program unless shadowed by a variable in an "inner" scope
- ► Function call environment: created dynamically (on the call stack) to represent parameters and local variables of a called function

Nesting of environments

- ► Nesting: an "inner" environment can reference variables in an "outer" environment
 - But not vice versa!
- ► In our interpreter, there are only two levels of nesting, the global environment and function call environments
- ▶ In a block-structured language, every "block" defines a new environment
 - ► C and C++ are block-structured languages

```
*denotes current
var a, b, c;
                   environment
a = 1;
b = 2;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b:
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
global environment
                Function
```

```
*denotes current
var a, b, c;
                   environment
a = 1;
b = 2;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
global environment
               Function
```

```
*denotes current
var a, b, c;
                   environment
a = 1;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
global environment
                Function
```

```
*denotes current
var a, b, c;
                   environment
a = 1;
b = 2;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

var a, b, c;

```
environment
a = 1;
b = 2;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c); create environment
println(a);
println(b);
println(c);
d;
```

*denotes current

```
global environment
               Function
```

```
*denotes current
                                           global environment
var a, b, c;
                  environment
a = 1;
b = 2;
c = 3;
                                                             Function
function add1(a) {
  var b;
                add call environment
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
* denotes current
                                            global environment
var a, b, c;
                   environment
a = 1;
b = 2:
c = 3;
                                                                Function
function add1(a) {
                 add call environment
  var b;
  b = 1:
  c = 4;
  a + b;
var d;
                              bind parameter(s)
to argument value(s)
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
*denotes current
                                           global environment
var a, b, c;
                  environment
a = 1;
b = 2:
c = 3;
                                                              Function
function add1(a) {
  var b;
                add call environment
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
*denotes current
                                           global environment
var a, b, c;
                  environment
a = 1;
b = 2;
c = 3;
                                                             Function
function add1(a) {
  var b;
                add call environment
  b = 1:
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
* denotes current
                                           global environment
var a, b, c;
                  environment
a = 1;
b = 2;
c = 3;
                                                              Function
function add1(a) {
  var b;
                add call environment
  b = 1;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

var a, b, c;

a = 1;

```
b = 2;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

* denotes current

environment

var a, b, c;

```
a = 1;
b = 2;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b:
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

*denotes current

environment

```
*denotes current
var a, b, c;
                   environment
a = 1;
b = 2;
c = 3;
function add1(a) {
 var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
*denotes current
var a, b, c;
                   environment
a = 1;
b = 2;
c = 3;
function add1(a) {
 var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c); Priv
d;
```

```
global environment
               Function
```

```
*denotes current
                                          global environment
var a, b, c;
                  environment
a = 1;
b = 2;
c = 3;
                                                            Function
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
                Program result:
```

Lexical addresses

In a language where every variable's scope is known statically, we can use *lexical addresses* to associate variable references with their definitions

Each variable has an integer position

Lexical address is pair (depth, position)

▶ depth: 0 if referenced variable is in current environment, 1 if in parent, 2 if in grandparent, etc.

Determining lexical addresses

Analyze source:

- ► Keep track of current (static) environment, initially the global environment
- ightharpoonup Enter a nested environment (with previous environment as its parent)
- ► Leave a nested scope → return to parent environment
- Keep track of names defined (variables, functions)
- ► As long as definitions precede uses, we can associate each reference to a name with an entry in a static environment
- ► Static (pre-execution) environments are also called *symbol tables*
 - Much more about these when we move on to compilers!



```
Initially: global env. w/ intrinsics defined
var a, b, c;
a = 1;
b = 2;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

global env. name position println O

```
var a, b, c; definitions of a, b, c
a = 1;
b = 2;
c = 3;
function add1(a) {
  var b;
  b = 1;
  c = 4;
  a + b;
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
global env.

name position

println

b

c

3
```

```
assign lexical addresses
 var a, b, c;
\frac{a}{b} = 1; (0,1)

\frac{a}{b} = 2; (0,2)

c = 3; (0,3)
 function add1(a) {
    var b;
    b = 1;
    c = 4;
    a + b:
 var d;
 d = add1(c);
 println(a);
 println(b);
 println(c);
 d;
```

```
global env.

name position

println

a
b
2
c
3
```

```
global env.
                      create nested
var a, b, c;
\frac{a}{b} = 1; (0,1)
\frac{a}{b} = 2; (0,1)
                                                               position
                     env. for function,
                                                       name
                      define add 1 in
                                                    println
c = 3; (0,3)
                      alobal env
                                      parent
function add1(a) {
                                       1 link
  var b;
                                                     add 1
  b = 1;
  c = 4;
                        ald I env.
  a + b:
                                   position
                           name
var d;
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
global env.
                        define parama,
var a, b, c;
\frac{a}{b} = 1; (0,1)
\frac{a}{b} = 2; (0,2)
                                                                 position
                                                         name
                                                     println
c = 3; (0,3)
                                        parent
function add1(a) {
                                        1 link
  var b;
                                                       add 1
  b = 1;
  c = 4;
                        ald I env.
  a + b;
                                    position
                            name
var d;
                              1
d = add1(c);
println(a);
println(b);
println(c);
d;
```

```
assign lexical addrs
for var refs
 var a, b, c;
\frac{a}{b} = 1; (0,1)
\frac{a}{b} = 2; (0,2)
                                                           println
 c = 3; (0,3)
                                            parent
 function add1(a) {
                                             link
   var b;
                                                             add 1
   \underline{b} = 1; (0,1)
   c = 4; (1,3)
                            ald I env.
  a + b;
(0,0) (0,1)
                                         position
                               name
 var d;
                                  1
 d = add1(c);
 println(a);
 println(b);
 println(c);
 d;
```

global env.

name position

println
b
2
c
add1
4

```
assign lexical addrs
for var refs
                                                       global env.
 var a, b, c;
\frac{a}{b} = 1; (0,1)
\frac{a}{b} = 2; (0,2)
                                                                   position
                                                          name
                                                       println
 c = 3; (0,3)
               reference to
function add (a) labor variable,
                                         parent
                                          1 link
                                                         add 1
  c = 4; (1,3)
(0,0) (0,1)
                                      position
                             name
 var d;
 d = add1(c);
 println(a);
 println(b);
 println(c);
 d;
```

```
var a, b, c;
                     define global var d
 \frac{a}{b} = 1; (0,1)
\frac{a}{b} = 2; (0,2)
 c = 3; (0,3)
 function add1(a) {
    var b;
   b = 1; (0,1)
   c = 4; (1,3)
  a + b;
(0,0) (0,1)
 var d;
 d = add1(c);
 println(a);
 println(b);
 println(c);
 d;
```

global env.

name position

println
b
2
c
add1
d
5

d;(0,5)

```
assign remaining
lexical addresses
       var a, b, c;
       \frac{a}{b} = 1; (0,1)
\frac{a}{b} = 2; (0,2)
       c = 3; (0,3)
       function add1(a) {
           var b;
          b = 1; (0,1)
          c = 4; (1,3)
        a + b;
      (0,0) (0,1)
       var d;
     d = add1(c);
(0,4) (0,3)
(0,0) println(a); (0,1)
(0,0) println(b); (0,2)
(0,0) println(c); (0,3)
```

global env. position name println

Function calls

Executing a function call

- ► As we've seen, executing a function call means:
 - Creating a new environment for it (with global environment as parent)
 - ► Evaluating argument expressions
 - ▶ Binding function parameters to argument values in the new function call environment
 - Evaluating the body of the function in the new function call environment
 - ▶ Result of evaluating body is result of function
 - ▶ Becomes value of function call expression at call site

Environment representation

How to represent an environment? One possibility:

```
struct Environment {
   std::map<std::string, struct Value> vars;
   struct Environment *parent;
};
```

Assumes that variables will be looked up by name

Another possibility

If lexical addresses are computed for variable/function references, then the *position* of the variable in the environment is the key to accessing it

▶ Names are only needed when assigning lexical addresses prior to execution

```
So:
```

```
struct Environment {
    // In both of these vectors, index=position
    std::vector<std::string> names; // not needed at runtime!
    std::vector<struct Value> vals; // only needed at runtime!
    struct Environment *parent;
}
```

Assumes that variables will be looked up (at runtime) by position

Function representation

Key information in function representation:

- ▶ Identifying information about all parameters and local variables
 - ► Enough information to create and initialize a function call environment at runtime
 - ► Maybe use Environment for this? Only needs info for local parameters and variables, can leave parent field null
- ► AST of function body

Possibility:

```
struct Function {
   struct Environment env_template;
   struct Node *body_ast;
};
```

Closures

Closures

Many languages support closures, a.k.a. anonymous functions, lambdas

Basic idea: the closure retains a pointer to its parent environment, i.e., the environment in which it was created at runtime

► This may imply that the lifetime of the parent environment is extended to be at least as long as the lifetime of the closure

Closure example

```
function make addn(n) {
  return function(x) { x + n; };
var add1, add2;
add1 = make addn(1);
add2 = make addn(2);
println(add1(1)); // prints 2
println(add2(1)); // prints 3
```

Implementing closures

A few possible implementation techniques:

- Dynamically-allocate function call environments
 - Closure values retain a pointer to parent environment
 - ► Could use reference counting to know when to delete dynamically-created environments
 - ► Environment is destroyed when there are no remaining references to it
- ► Closure retains a *copy* of its parent environment (and grandparent, etc.)
 - Or, copies of just the variables that are actually referenced by the body of the closure function

Memory management, garbage collection

Dynamically allocated values

- We noted last time that runtime values may require dynamically-allocated storage
 - ► Strings, vectors, list nodes, objects, etc.
- ► How to ensure that dynamically allocated memory gets reclaimed when no longer used?
- ► A couple standard approaches:
 - Reference counting
 - Garbage collection

Reference counting

- ► All dynamically allocated objects have a reference count field
 - ▶ Is just an integer indicating how many pointers are pointing to the object
- ► Language runtime must take care to increment and decrement references counts
 - ► C++ smart pointers can help a lot with this
- ▶ When reference count reaches 0, deallocate
- Problem: object graphs with cycles can't be reclaimed

Garbage collection

- ► Language runtime keeps track of references to dynamic objects
- ▶ Periodically, it determines which objects are reachable
 - ► Unreachable objects are reclaimed
- ► There are *many* ways to do this! (Tons of research, we could do an entire course on this topic)
 - ► We'll briefly discuss two

Root set

- ► The *root set* of references are the starting point for determining which objects are reachable
- ► It consists of:
 - Objects referenced by global variables
 - Objects referenced by the activation records (i.e., function call environments) of currently-executing functions (on the call stack)
- Objects not directly or indirectly reachable from the root set can be assumed to be garbage

Assumptions

- ▶ The garbage collector can find all of the dynamically allocated objects
- ► Given a pointer to an object, the garbage collector knows what pointers to other objects are stored in it

Mark and sweep

- ➤ Starting from the root set, do a graph traversal to find all reachable objects, and mark them as "live"
- ► Traverse all dynamically allocated objects, and reclaim the memory of those not marked as alive
 - ► Also, clear the "live" mark on objects that are still alive

Copying

- ► Heap is divided into *semispaces*
- New objects are allocated in the current semispace
- ► To collect garbage:
 - Starting from the root set, do a graph traversal of reachable objects
 - ► For each live object, copy it into the other semispace (keeping track of mapping from old location to new location)
 - Once all objects are copied, update all pointers in root set and live objects to reflect the updated object locations
 - Switch semispaces