

$$\{\mathbf{q}_i(t), \mathbf{m}_i(t)\}_i$$



Patch
Initialization

$$\mathbf{S}(t_0)$$

Patch
Tracking

$$\mathbf{S}(t-1), \mathbf{S}(t)$$

Visibility
Estimation

$$\mathbf{V}(t)$$