

Simulation Assignment #1
EECS 170LC
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1 Introduction

p- and n-channel transistors are characterized using Cadence Virtuoso. The I_D versus V_{GS} and I_D versus V_{DS} curves of the n-channel MOSFET are analyzed. Then the I_S versus V_{SG} and I_S versus V_{SD} curves of the p-channel MOSFET are analyzed. Other properties such as body leakage current are considered.

2 Simulation 1

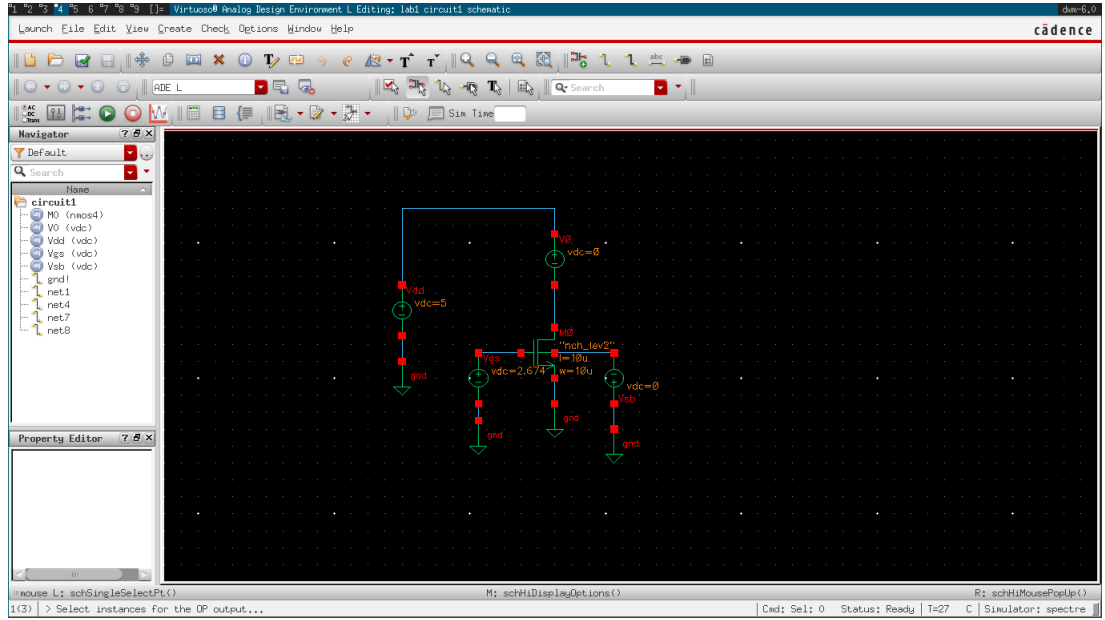


Figure 1: Circuit for Simulation 1

The value of V_{GS} for which $I_D = 500\mu A$ is listed in table (1). g_m is determined from a DC operating point analysis in Virtuoso as well as from the plot in figure (2).

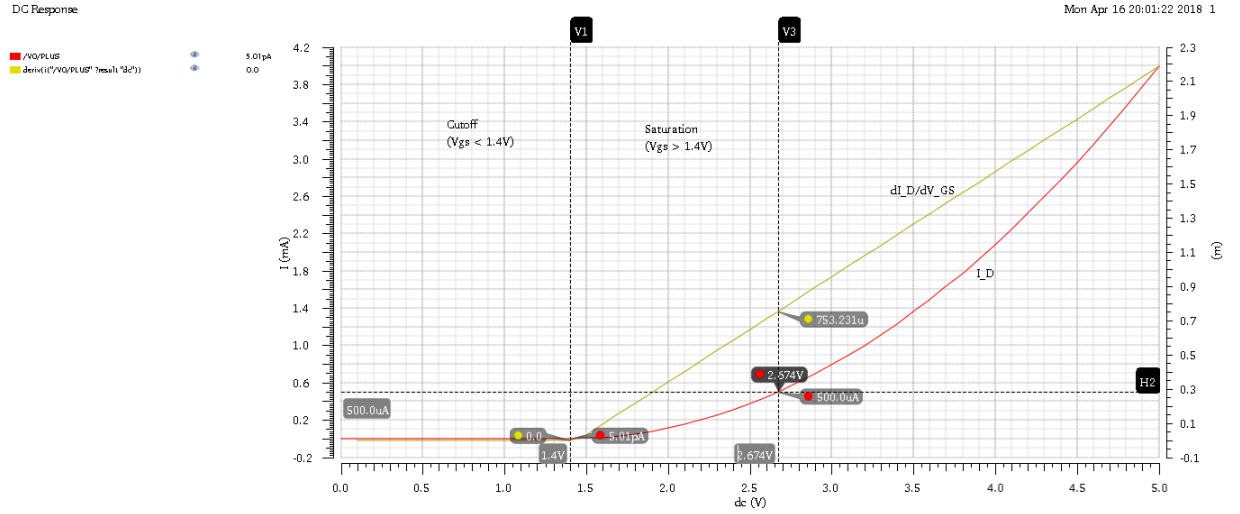


Figure 2: I_D and $\frac{\partial I_D}{\partial V_{GS}}$ versus V_{GS} for NMOS

It should be noted that the transistor is always in saturation when it is not in cutoff since $V_{DS} = 5V$ and $V_{GS} < 5V$, which implies $V_{GS} - V_t < V_{DS}$. By definition, $g_m = \frac{\partial I_D}{\partial V_{GS}}$. So, g_m can be determined from the graph at the point when $I_D = 500\mu A$.

Table 1: Simulation 1 Results

V_{GS} [V]	g_m from DC op point [$\mu A / V$]	g_m from Graph [$\mu A / V$]	Error
2.674	784	752.231	4.05%

3 Simulation 2

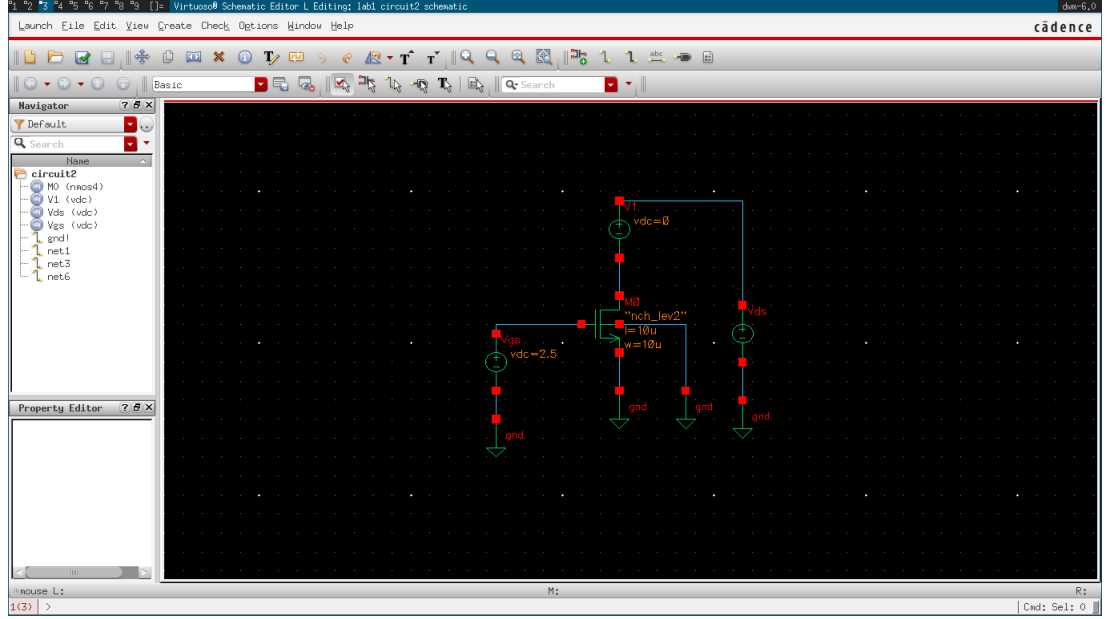
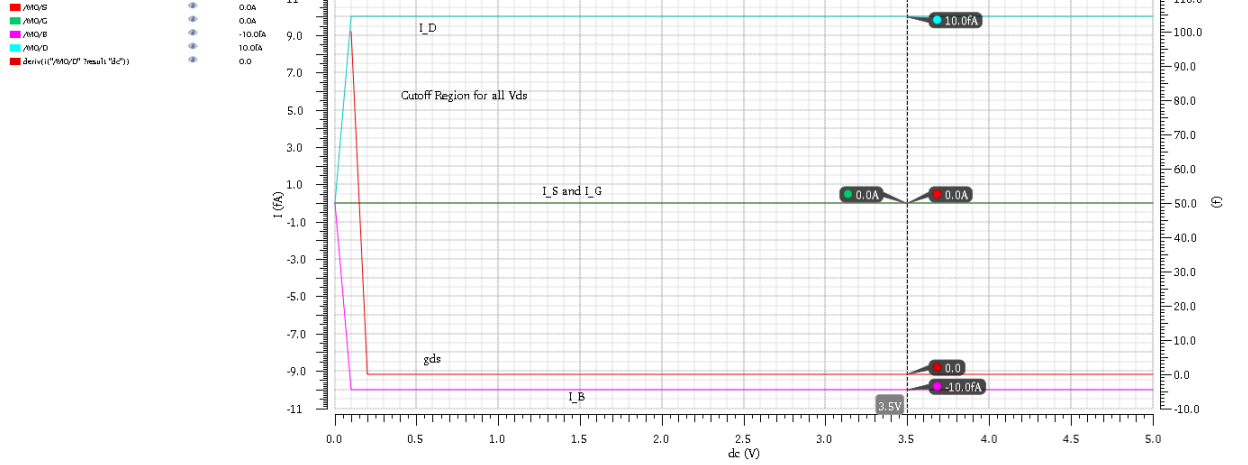


Figure 3: Circuit for Simulation 2

The I_D versus V_{DS} characteristics of the n-channel MOSFET are analyzed. For MOSFETs with channel-length modulation, $r_o = \frac{1}{\lambda I'_D}$ by definition, where $I'_D = \frac{k_n}{2} V_{ov}^2$ is the saturation current without channel-length modulation effects. Here, V_{ov} is the transistor's overdrive voltage, and k_n is the MOSFET's transconductance parameter. The small-signal drain-to-source conductance g_{ds} is to be defined as $g_{ds} = \frac{1}{r_o} = \lambda I'_D$. However, I'_D is difficult to acquire from realistic simulations.

To a first-order approximation, $I_D = \frac{k_n}{2} V_{ov}^2 (1 + \lambda V_{DS}) = I'_D (1 + \lambda V_{DS})$ in saturation mode. So, $\frac{\partial I_D}{\partial V_{DS}} = \lambda I'_D = g_{ds}$. Thus, by analyzing the derivative of I_D with respect to V_{DS} at a particular value of V_{DS} , g_{ds} can be determined from simulation.

First, a simulation is run with $V_{GS} = 0V$.

Figure 4: NMOS I_D versus V_{DS} when $V_{GS} = 0V$

Here, $I_S = 0$ and $I_D = -I_B \neq 0$. Because the transistor is in cutoff mode, no channel between the source and drain forms. However, the drain's doped n-region forms a pn-junction with the p-type body of the NMOS. Thermally-generated carriers in the depletion layer become accelerated by the potential difference of the junction's depletion layer. Thus, a "leakage" current occurs from the drain to the body. As the drain voltage increases, thermally-generated carriers become accelerated by a larger potential difference, thereby increasing the current. This relationship can be somewhat accurately modeled by the ideal (or Shockley) diode equation:

$$I_{DB} = I_S(e^{\frac{V_{DB}}{V_T}} - 1) \quad (1)$$

Here, I_{DB} is the current that flows from the drain to the body of the MOSFET. I_S is the reverse saturation current, which is approximately 10fA. V_{DB} is the voltage between the drain and the body. $V_T = \frac{k_B T}{q}$ is the diode's thermal voltage. For $V_{DB} \ll -V_T$, $I_{DB} \approx -I_S$, which explains why the curve is constant for large V_{DS} . Note that $V_{DS} = V_D - V_S = V_D - V_B = V_{DB}$.

The definition of g_{ds} requires that the transistor be in saturation. However, if a small signal is to be applied at the MOSFET's gate, one would expect $g_{ds} = 0$ since the channel cannot conduct any current. Plotting $\frac{\partial I_D}{\partial V_{DS}}$, labeled g_{ds} in figure (4), $g_{ds} = 0$ at $V_{DS} = 3.5V$, the particular voltage of interest, consistent with intuition.

V_{GS} is now increased to 2.5V. In the triode region, I_D depends on $-V_{DS}^2$ because $I_D = k_n(V_{ov} - 0.5V_{DS})V_{DS}$. So, $\frac{\partial I_D}{\partial V_{DS}}$ depends linearly on $-V_{DS}$. In

the saturation region, $\frac{\partial I_D}{\partial V_{DS}}$ is constant with V_{DS} . Therefore, the transition point between a linear curve and a constant curve marks the transition from saturation to triode, whose intervals are labeled in figure (5).

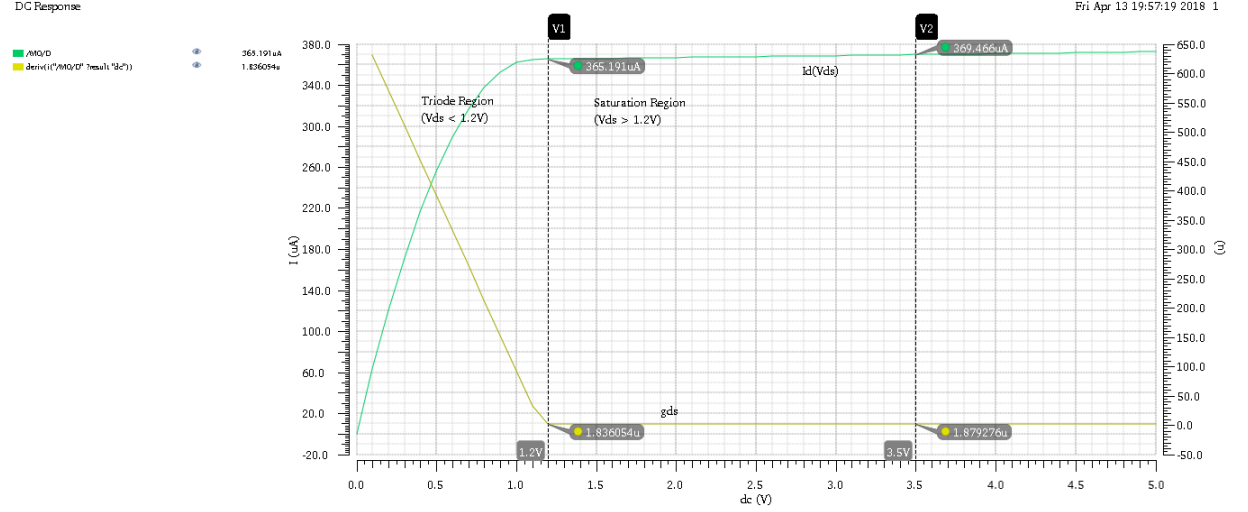


Figure 5: NMOS I_D versus V_{DS} when $V_{GS} = 2.5V$

Here, g_{ds} can be properly evaluated since the transistor is analyzed at $V_{DS} = 3.5V$, which occurs in the saturation region.

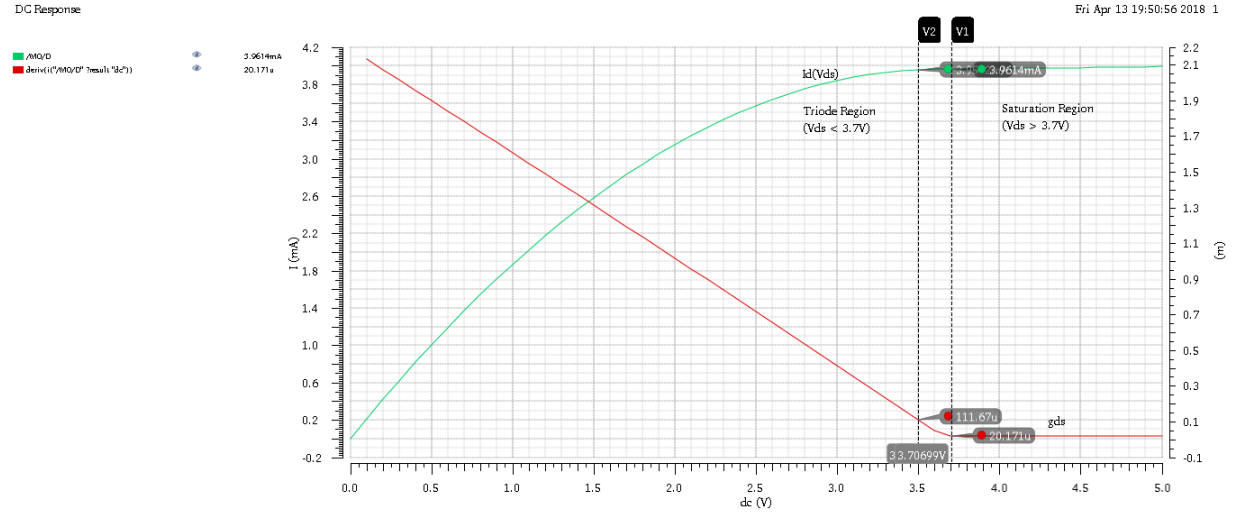


Figure 6: NMOS I_D versus V_{DS} when $V_{GS} = 5.0V$

The simulation results for $V_{GS} = 5.0V$ are shown in figure (6). The transistor

operates in the triode region at $V_{DS} = 3.5\text{V}$, but the same definition is applied nonetheless. The final results are tabulated in table (2).

Table 2: Simulation 2 Results

Vgs [V]	gds from Graph [uA / V]	gds from DC Op Point [mA / V]	Error
0	0	0	0.00%
2.5	1.88	1.88	0.00%
5.0	111.67	81.19	37.54%

4 Simulation 3

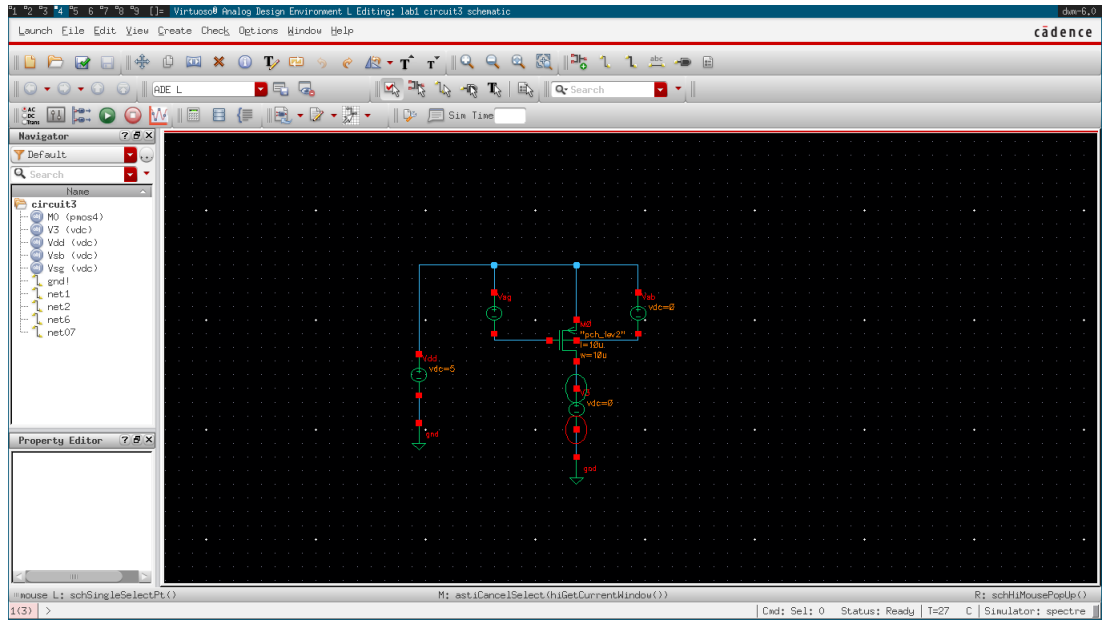


Figure 7: Circuit for Simulation 3

Simulation 3 is similar to Simulation 1 except that a PMOS is used instead of an NMOS.

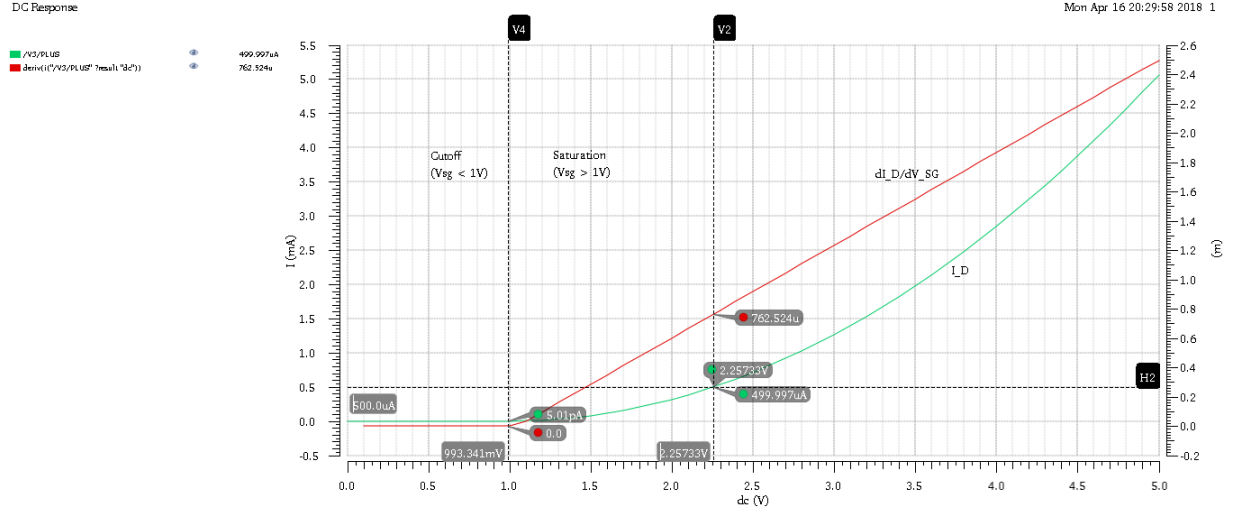


Figure 8: I_D and $\frac{\partial I_D}{\partial V_{SG}}$ versus V_{SG} for PMOS

Again, the transistor is in saturation when it exits cutoff because $V_{SD} = 5V$ and $V_{SG} < 5V$, meaning $V_{SG} - |V_t| < V_{SD}$. For the PMOS, the definition $g_m = \frac{\partial I_D}{\partial V_{SG}}$ shall be used.

Table 3: Simulation 3 Results

Vsg [V]	gm from DC op point [uA / V]	gm from Graph [uA / V]	Error
2.25733	794.1	762.52	4.1%

5 Simulation 4

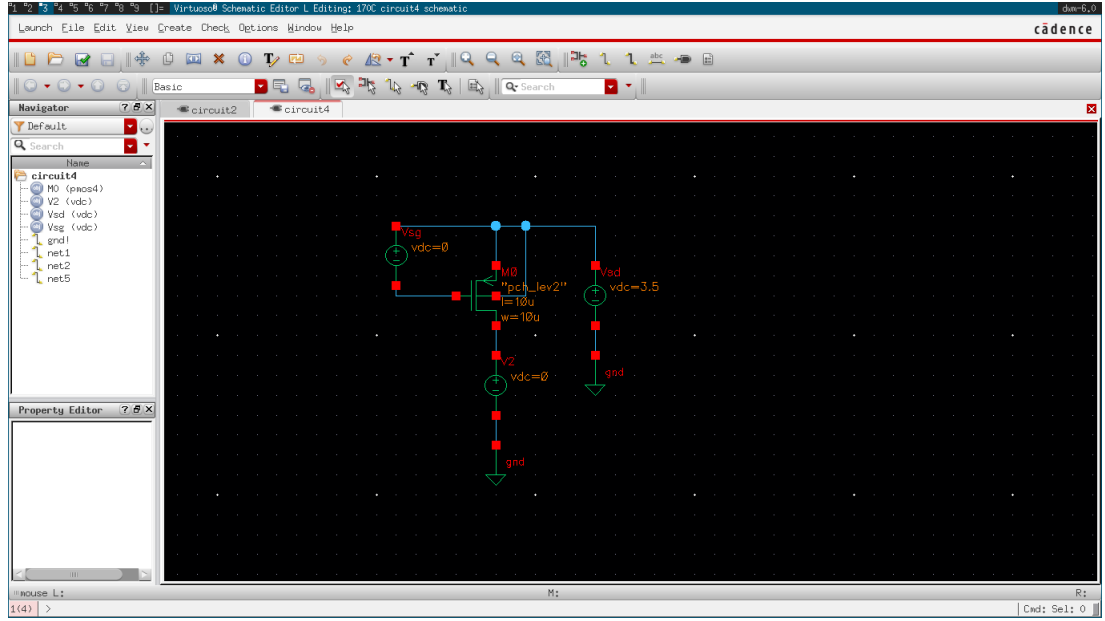


Figure 9: Circuit for Simulation 4

The results for Simulation 4 are similar to Simulation 2, except a PMOS is used instead of an NMOS. The definition $g_{sd} = \frac{\partial I_D}{\partial V_{SD}}$ is used instead.

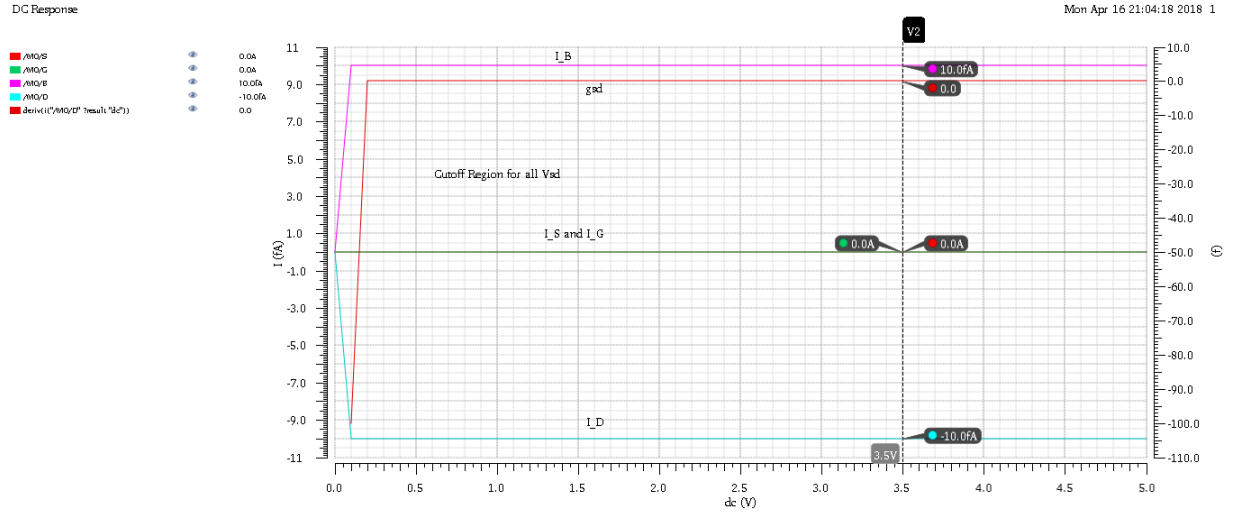


Figure 10: PMOS I_D versus V_{SD} when $V_{SG} = 0V$

Table 4: Simulation 4 Results

Vsg [V]	gsd from Graph [uA / V]	gsd from DC Op Point [mA / V]	Error
0	0	0	0%
2.5	7.24	7.249	0.12%
5.0	392.3	361.6	8.5%

λ for the NMOS and PMOS can be calculated from the given data. Two samples are already taken for each transistor: the current at the edge of saturation and triode I_{D1} and the current at $V_{DS} = 3.5V$ (or V_{SD} in the case of a PMOS). Consider the transistor at $V_{GS} = 2.5V$ (or V_{SG} in the case of a PMOS). It operates in saturation at this V_{DS} (or V_{SD} value). Therefore, its current is given by $I_D = I'_D(1 + \lambda V_{DS})$ (or V_{SD} in the case of a PMOS). So, λ can be determined from a system of equations. The equations are written for the NMOS, but extrapolating to the PMOS is trivial by simply replacing V_{DS} with V_{SD} :

$$I_{D1} = I'_D(1 + \lambda V_{DS1}) \quad (2)$$

$$I_{D2} = I'_D(1 + \lambda V_{DS2}) \quad (3)$$

Solving equations (2) and (3) for λ yields:

$$\lambda = \frac{I_{D2} - I_{D1}}{I_{D1}V_{DS2} - I_{D2}V_{DS1}} \quad (4)$$

λ for each transistor is presented in table(5). The results are compared with the simulation models.

Table 5: Lambda Calculations for Transistors

	Calculated Lambda	Model-Specified Lambda	Percentage Error
NMOS	0.00512	0.00500	2.41860%
PMOS	0.01054	0.01000	5.37199%

A simpler approach can also be taken to determine λ . For processes with relatively long transistors, λ should not be very large. Because $\lambda = \frac{1}{V_A}$, where V_A is the Early voltage, this implies that V_A is quite large. So, long as V_{DS} (or V_{SD} in the case of a PMOS) is not very large relative to V_A ($V_{DS} \ll V_A$), the following approximation can be made:

$$I_D = I'_D(1 + \lambda V_{DS}) = I'_D(1 + \frac{V_{DS}}{V_A}) \approx I'_D \quad (5)$$

Therefore, $g_{ds} = \lambda I'_D \approx \lambda I_D$ for $V_A \gg V_{DS}$ (or $V_A \gg V_{SD}$ for a PMOS). So, λ can also be approximated using $\lambda \approx \frac{g_{ds}}{I_D}$ (or g_{sd} in the case of a PMOS) provided that these assumptions about the transistor hold.

6 Conclusion

The g_m values for all of the simulations are quite close (within 5%) of the value provided by Virtuoso's DC operating point analysis. g_{ds} is generally quite accurate as well. However, for the NMOS at $V_{GS} = 5V$, the simulation result from the graph is off from the DC operating point analysis by over 30%. The reasons for this are not quite clear, though it may be that Virtuoso's definition of g_{ds} in the triode region differs from $\frac{\partial I_D}{\partial V_{DS}}$. A deeper investigation is required to understand this discrepancy. Furthermore, the simulation model captures the leakage current through the body of the MOSFET and can thus be considered quite accurate compared to real transistors. Lastly, the calculated λ values are close to, but not exactly equal to, the λ value in the simulation model. The equations used for channel-length modulation are likely a first-order approximation, and Virtuoso may be using a higher-order model that considers V_{DS}^2 or even V_{DS}^3 terms.