My Project

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Contents

1 Namespace Index **1**

1.1 Namespace List 1

2 Hierarchical Index **3**

2.1 Class Hierarchy 3

3 Class Index **5**

3.1 Class List 5

4 Namespace Documentation **7**

4.1 simlib.action Namespace Reference 7

4.1.1 Detailed Description 7

4.2 simlib.archspec Namespace Reference 7

4.2.1 Detailed Description 8

4.3 simlib.simulated Namespace Reference 8

4.3.1 Detailed Description 8

5 Class Documentation **9**

5.1 simlib.action.Action Class Reference 9

5.1.1 Detailed Description 9

5.1.2 Member Function Documentation 9

5.1.2.1 get_args() 9

5.1.2.2 get_ctr() 10

5.1.2.3 get_fn() 10

5.2 simlib.simulated.ActionQueue Class Reference 10

5.2.1 Detailed Description . . . 10
5.2.2 Member Function Documentation . . . 10
5.2.2.1 popAction() . . . 11
5.2.2.2 test() . . . 11
5.2.2.3 update() . . . 11
5.3 simlib.anchor.Anchor Class Reference . . . 11
5.4 simlib.archspec.ArchSpec Class Reference . . . 11
5.4.1 Detailed Description . . . 12
5.5 simlib.FSM.Device Class Reference . . . 12
5.5.1 Detailed Description . . . 13
5.5.2 Member Function Documentation . . . 13
5.5.2.1 getState() . . . 13
5.6 simlib.FSM.DW1000 Class Reference . . . 13
5.7 simlib.hub.Hub Class Reference . . . 13
5.7.1 Member Function Documentation . . . 14
5.7.1.1 generateCompleteMap() . . . 14
5.7.1.2 resetMap() . . . 14
5.8 simlib.archspec.MySubclass Class Reference . . . 15
5.9 simlib.node.Node Class Reference . . . 15
5.9.1 Member Function Documentation . . . 15
5.9.1.1 listenForSignal() . . . 16
5.10 simlib.simulated.Simulated Class Reference . . . 16
5.10.1 Detailed Description . . . 16
5.11 simlib.simulationenvironment.SimulationEnvironment Class Reference . . . 17
5.12 simlib.FSM.State Class Reference . . . 17
5.12.1 Detailed Description . . . 17

Index **19**

Chapter 1

Namespace Index

1.1 Namespace List

Here is a list of all documented namespaces with brief descriptions:

simlib.action 7
simlib.archspec 7
simlib.simulated 8

Chapter 2

Hierarchical Index

2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

simlib.action.Action 9
simlib.simulated.ActionQueue 10
simlib.archspec.ArchSpec 11
simlib.simulationenvironment.SimulationEnvironment 17
simlib.FSM.State 17
ABC
- simlib.FSM.Device 12
  - simlib.anchor.Anchor 11
  - simlib.FSM.DW1000 13
  - simlib.node.Node 15
- simlib.simulated.Simulated 16
  - simlib.archspec.MySubclass 15
  - simlib.FSM.Device 12
  - simlib.hub.Hub 13

Chapter 3

Class Index

3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

simlib.action.Action
Classes ## 9
simlib.simulated.ActionQueue 10
simlib.anchor.Anchor 11
simlib.archspec.ArchSpec
Classes ## 11
simlib.FSM.Device 12
simlib.FSM.DW1000 13
simlib.hub.Hub 13
simlib.archspec.MySubclass 15
simlib.node.Node 15
simlib.simulated.Simulated
Classes ## 16
simlib.simulationenvironment.SimulationEnvironment 17
simlib.FSM.State 17

Chapter 4

Namespace Documentation

4.1 simlib.action Namespace Reference

Classes

- class Action

  Classes ##.

Functions

- def **fn** (n)
- def **fn2** (x, y)

Variables

- int **errors** = 0
- **test_obj** = None

4.1.1 Detailed Description

```
@package Action
This module defines the Action object, which is used, together with the ActionQueue class,
to implement delayed function calls.
```

4.2 simlib.archspec Namespace Reference

Classes

- class ArchSpec

  Classes ##.
- class MySubclass

Variables

- int **errors** = 0
- **archspec_obj** = ArchSpec(int , int , int)

4.2.1 Detailed Description

```
@package Architecture Specification
This module presents the simulation environment with the types of the hub, nodes, and
anchors.
```

4.3 simlib.simulated Namespace Reference

Classes

- class ActionQueue
- class Simulated

  Classes ##.

Variables

- bool **DEBUG** = True
- int **errors** = 0
- **aq** = ActionQueue( )
- **action1** = Action(aq.test, ["I was the first action added"])
- **action2** = Action(aq.test, ["then me (:"])
- **action3** = Action(aq.test, ["lastly me (;"])
- int **i** = 0

4.3.1 Detailed Description

```
@package Simulated
The simulated module contains the Simulated class that is an abstract class
that generalizes the notions fo a device, central hub, anchor and node. It
also contains the ActionQueue class that is resposuble for keeping track of
the current stated of the actions that are waiting to be executed (time until
execution).
```

Chapter 5

Class Documentation

5.1 simlib.action.Action Class Reference

Classes ##.

Public Member Functions

- def **__init__**
- def **decrement**
- def **set_fn**
- def **set_ctr**
- def get_fn (self)
- def get_args (self)
- def get_ctr (self)

5.1.1 Detailed Description

Classes ##.

```
Element of an action queue
```

5.1.2 Member Function Documentation

5.1.2.1 get_args()

```
def simlib.action.Action.get_args (
              self,
              list )
```

```
Returns the function args associated with this action.
```

5.1.2.2 get_ctr()

```
def simlib.action.Action.get_ctr (
              self,
              int )
```

Returns the counter value associated with this action.

5.1.2.3 get_fn()

```
def simlib.action.Action.get_fn (
              self,
              types,
              FunctionType )
```

Returns the function associated with this action.

The documentation for this class was generated from the following file:

- src/simlib/action.py

5.2 simlib.simulated.ActionQueue Class Reference

Public Member Functions

- def **__init__** (self)
- def **addToQueue**
- def popAction (self)
- def update (self)
- def test (self, test)

Public Attributes

- **queue**

5.2.1 Detailed Description

Creates instance of Action Queue

5.2.2 Member Function Documentation

5.2.2.1 popAction()

```
def simlib.simulated.ActionQueue.popAction (
              self )
```

removes the oldest Action from the list

5.2.2.2 test()

```
def simlib.simulated.ActionQueue.test (
              self,
              test )
```

Arbitrary function added for unit test.

5.2.2.3 update()

```
def simlib.simulated.ActionQueue.update (
              self )
```

Every time the update function is called, decrement the counter of the first action in the action queue. If the the counter is zero, pop the action off the action queue

The documentation for this class was generated from the following file:

- src/simlib/simulated.py

5.3 simlib.anchor.Anchor Class Reference

Inheritance diagram for simlib.anchor.Anchor:

5.4 simlib.archspec.ArchSpec Class Reference

Classes ##.

Public Member Functions

- def **__init__**
- def **get_hubclass** (self)
- def **get_anchorclass** (self)
- def **get_nodeclass** (self)
- def **set_hubclass**
- def **set_anchorclass**
- def **set_nodeclass**

5.4.1 Detailed Description

Classes ##.

```
Architecture specification
Defines what classes to use for hub, anchors, and nodes.


The default constructor
@param hubclass The type of the central hub
@param anchorclass The type of the anchor
@param nodeclass The type of the node
```

The documentation for this class was generated from the following file:

- src/simlib/archspec.py

5.5 simlib.FSM.Device Class Reference

Inheritance diagram for simlib.FSM.Device:

Collaboration diagram for simlib.FSM.Device:

Public Member Functions

- def **__init__**
- def getState (self)
- def **setNextState**
- def **getParam**

Public Attributes

- **available_states**
- **initial_state**
- **dev_state**
- **physical_data**
- **next_states**

5.5.1 Detailed Description

```
Creates an instance of a device dependent on the FSM,
physical data, and available states used to accurately
model the DW1000 or other like devices.
```

5.5.2 Member Function Documentation

5.5.2.1 getState()

```
def simlib.FSM.Device.getState (
              self,
              State )
```

```
Returns the current state of the device.
```

The documentation for this class was generated from the following file:

- src/simlib/FSM.py

5.6 simlib.FSM.DW1000 Class Reference

Inheritance diagram for simlib.FSM.DW1000:

Collaboration diagram for simlib.FSM.DW1000:

Public Member Functions

- def **__init__**
- def **mainloop**

Additional Inherited Members

The documentation for this class was generated from the following file:

- src/simlib/FSM.py

5.7 simlib.hub.Hub Class Reference

Inheritance diagram for simlib.hub.Hub:

Collaboration diagram for simlib.hub.Hub:

Public Member Functions

- def **__init__** (self, algorithm)
- def **setTime**
- def **containsAnchor**
- def **addAnchor**
- def **removeAnchor**
- def **containsNode**
- def **addNode**
- def **removeNode**
- def resetMap (self)
- def **mapDistance**
- def **getNodePosition**
- def **mapAnchorAndNode**
- def **triliterateNode**
- def generateCompleteMap (self)
- def **addAction**
- def **prependAction**
- def **mainloop** ()

Public Attributes

- **time**
- **anchors**
- **nodes**
- **map**
- **nodePositions**
- **algorithm**

5.7.1 Member Function Documentation

5.7.1.1 generateCompleteMap()

```
def simlib.hub.Hub.generateCompleteMap (
              self )
```

Generates a complete map of anchors and nodes

5.7.1.2 resetMap()

```
def simlib.hub.Hub.resetMap (
              self )
```

Resets the map to [][]

The documentation for this class was generated from the following file:

- src/simlib/hub.py

5.8 simlib.archspec.MySubclass Class Reference

Inheritance diagram for simlib.archspec.MySubclass:

Collaboration diagram for simlib.archspec.MySubclass:

Additional Inherited Members

The documentation for this class was generated from the following file:

- src/simlib/archspec.py

5.9 simlib.node.Node Class Reference

Inheritance diagram for simlib.node.Node:

Collaboration diagram for simlib.node.Node:

Public Member Functions

- def **__init__**
- def **setTime**
- def **getID** ()
- def listenForSignal ()
- def **addAction**
- def **prependAction**

Public Attributes

- **time**
- **ID**
- **xPos**
- **yPos**
- **zPos**
- **xVel**
- **yVel**
- **zVel**
- **signalList**

5.9.1 Member Function Documentation

5.9.1.1 listenForSignal()

```
def simlib.node.Node.listenForSignal (
              int )
```

```
Searches to see if it is the target of any signals. Returns the sending ID
if a signal is found or 0 if no signal is found.
```

The documentation for this class was generated from the following file:

- src/simlib/node.py

5.10 simlib.simulated.Simulated Class Reference

Classes ##.

Inheritance diagram for simlib.simulated.Simulated:

Collaboration diagram for simlib.simulated.Simulated:

Public Member Functions

- def **__init__** (self)
- def **mainloop**
- def **run_timestep**

Public Attributes

- **actionQueue**

5.10.1 Detailed Description

Classes ##.

The documentation for this class was generated from the following file:

- src/simlib/simulated.py

5.11 simlib.simulationenvironment.SimulationEnvironment Class Reference

Public Member Functions

- def **__init__** (self)
- def **createHub**
- def **createNode**
- def **getNodeByID**
- def **associateNode**
- def **dissassociateNode**
- def **deleteNode**
- def **createAnchor**
- def **getAnchorByID**
- def **associateAnchor**
- def **dissassociateAnchor**
- def **deleteAnchor**
- def **mainloop** ()

Public Attributes

- **time**
- **hubs**
- **anchors**
- **nodes**
- **nextID**
- **signalList**

The documentation for this class was generated from the following file:

- src/simlib/simulationenvironment.py

5.12 simlib.FSM.State Class Reference

Public Member Functions

- def **__init__**
- def **getParam**

Public Attributes

- **physical_data**

5.12.1 Detailed Description

```
Creates instance of a State for the device.
```

The documentation for this class was generated from the following file:

- src/simlib/FSM.py

Index

generateCompleteMap
    simlib::hub::Hub, 14
get_args
    simlib::action::Action, 9
get_ctr
    simlib::action::Action, 9
get_fn
    simlib::action::Action, 10
getState
    simlib::FSM::Device, 13

listenForSignal
    simlib::node::Node, 15

popAction
    simlib::simulated::ActionQueue, 10

resetMap
    simlib::hub::Hub, 14

simlib.action, 7
simlib.action.Action, 9
simlib.anchor.Anchor, 11
simlib.archspec, 7
simlib.archspec.ArchSpec, 11
simlib.archspec.MySubclass, 15
simlib.FSM.DW1000, 13
simlib.FSM.Device, 12
simlib.FSM.State, 17
simlib.hub.Hub, 13
simlib.node.Node, 15
simlib.simulated, 8
simlib.simulated.ActionQueue, 10
simlib.simulated.Simulated, 16
simlib.simulationenvironment.SimulationEnvironment, 17
simlib::FSM::Device
    getState, 13
simlib::action::Action
    get_args, 9
    get_ctr, 9
    get_fn, 10
simlib::hub::Hub
    generateCompleteMap, 14
    resetMap, 14
simlib::node::Node
    listenForSignal, 15
simlib::simulated::ActionQueue
    popAction, 10
    test, 11
    update, 11

test
    simlib::simulated::ActionQueue, 11

update
    simlib::simulated::ActionQueue, 11