Parametrized Complexity Part 2

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Correction

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DEFINITION

Let A and B be parameterized problems. A **parameterized reduction** of A onto B maps an instance (x, k) of A to an instance (x', k') of B such that

- 1. x' depends only on x.
- 2. k' depends only on k.
- 3. The function that maps x to x' can be computed in $f(k) \cdot poly(|x|)$ time.
- 4. k' is bounded by a computable function of k.
- 5. $(x, k) \in A$ if and only if $(x', k') \in B$.

Introduction

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 As with polynomial-time-reduction, parameterized reduction also yields its own hierarchical complexity class structure, which will be the main topic of today's lecture.

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- It is believed, though not as strong as $P \neq NP$, that $NTMA_k \notin FPT$.
- We can now define a new complexity class under the assumption that NTMA_k \notin FPT.

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Polynomial Time Reduction	Parameterized Reduction
Problem A is NP	Problem A is $W[1]$
if A is reducible to SAT	if A is reducible to $NTMA_k$

Parameterized Reduction
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Problem A is W[1]-hard
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Problem A is NP-hard	Problem A is W[1]-hard
if SAT is reducible to A	if $NTMA_k$ is reducible to A
Problem A is NP-complete	Problem A is $W[1]$ -complete
if A is NP and NP-hard	if A is W[1] and W[1]-hard
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- As any independent set of size k can be found, if any, within path length of $O(k^2)$, we conclude that Independent-Set_k \in W[1].

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- The vertices of the graph will be grouped into k^2 cells labelled $\{1, 2, \dots, k\} \times \{1, 2, \dots, k\}$, where vertices in each cell form a clique.
- By adding some more edges, we want this graph to have an independent set of size $k \times k$ if and only if the machine has an accepting path of length k.

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 - 1. For all $1 \le i \le k$ and $1 \le j_1 < j_2 \le k$, add edges between every vertices from $\Sigma \times Q$ in the cell (i, j_1) and in the cell (i, j_2) .

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 - 2. For all $1 \le i < k$ and j and $(p, a) \in \Sigma \times Q$, put edges between (p, a) at cell (i, j) and every vertices at the row i + 1 which is incompatible with (p, a) according to the transition function of the machine.

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- Clearly, this graph has a clique of size k^2 if and only if the initial machine has an accepting path of length k. Therefore, Independent-Set_k is W[1]-complete.

COROLLARY

Clique_k is W[1]-complete.

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 $\mathsf{Regular}\text{-}\mathsf{Clique}_k \text{ is } \mathsf{W[1]}\text{-}\mathsf{complete}.$

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- Create Δ copies of $G: G_1, \dots, G_{\Delta}$, and let v_i be the vertex corresponding to v in G_i .
- For each vertex v of G, create $\Delta \deg(v)$ new vertices $v_1', \dots, v_{\Delta \deg(v)}'$, and connect each v_i and v_i' .

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- For each vertex v of G, create $\Delta \deg(v)$ new vertices $v'_1, \dots, v'_{\Delta \deg(v)}$, and connect each v_i and v'_i .
- Since for each $l \ge 3$, all clique of size l of the resulting graph is contained in one of G_i s, it has a clique of size k if and only if the original graph has a clique of size k.

COROLLARY

Regular-Independent-Set $_k$ is W[1]-complete.

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- We'll later define the class W[2], where Dominating-Set_k has been proven to be complete on.

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- As there's no edge between x_i and y_i , every dominating set of size k in the resulting graph must contain exactly one vertex from each V_i .
- Now it is clear from the construction that the original graph has an independent set of size k if and only if the resulting graph has a dominating set of size k.

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Question: Is there a valid assignment of the input where exactly k variables are set to True?

THEOREM

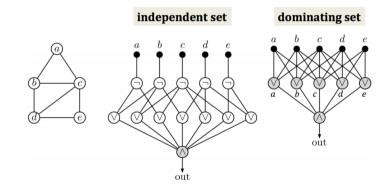
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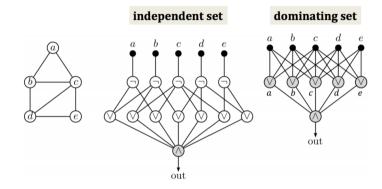
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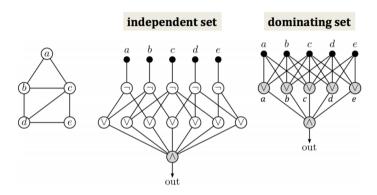
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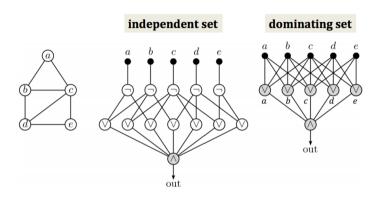
As we've noted earlier, locality of $Clique_k$ / $Independent-Set_k$ plays a part in the distinguishment of these two groups.

We formalize this concept to define other classes in W-Hierarchy.





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- 2. In the Dominating-Set_k circuit, all the input-output path pass through two gates that has large number of inputs.

DEFINITION

1. A large gate is a gate that has more than some fixed constant number. We let the constant be 2 for now.

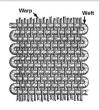
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DEFINITION

- 1. $A_k \in W[t]$ if there's a computable function f such that there's a reduction from A_k to a problem in $C[t,d]_k$.
- 2. A_k is W[t]-hard if, for all d, every problem in C[t,d]_k is reducible to A_k .
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- 5. $A_k \in W[P]$ if A_k is reducible to Circuit-SAT_k.
- 6. $A_k \in XP$ if there exists computable functions f and g such that A_k can be solved in time $f(k) \cdot n^{g(k)}$.

The followings are known:

 $\bullet \ \mathsf{FPT} = \mathsf{W}[\mathsf{0}] \subseteq \mathsf{W}[\mathsf{1}] \subseteq \mathsf{W}[\mathsf{2}] \subseteq \cdots \subseteq \mathsf{W}[\mathsf{SAT}] \subseteq \mathsf{W}[\mathsf{p}] \subseteq \mathsf{XP}$

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- $FPT \neq XP$

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- If Vertex-Cover_k could be solved in $2^{o(k)} \cdot n^c$ time, since $k \leq n$, this would yield a $2^{o(n)} \cdot n^c$ algorithm for Vertex-Cover, violating the ETH.
- As Vertex-Cover has been shown to be solvable in time $O(k \cdot n + 1.28^k)$ by Chen et al., this bound is tight.

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• Similarly to the previous theorem, Dominating-Set_k, Clique_k, and Hamiltonian-Cycle_k can all be shown to require $2^{\Omega(k)} \cdot n^c$ time to solve for all integer c > 0.

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- We give a reduction from 3COL to Clique_k.

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- 5. G' = (V', E') is the final graph.

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- Set k to be the maximum value such that $f(k) \le n$ and $k^{k/s(k)} \le n$, and let g be the minimum value between the inverse of the two functions above.
- Now the runtime of our 3-coloring algorithm is $f(k) \cdot ((k \cdot 3^{n/k})^{k/s(k)}) \le n \cdot k^{k/s(k)} \cdot 3^{n/s(k)} \le n^2 \cdot 3^{n/s(g(n))} \le 2^{o(n)}$ which violates the ETH.

The End