

Problem 1: (50 points) Solve the linear system $\mathbf{Ax} = \mathbf{b}$ with \mathbf{A} the Hilbert matrix with elements

$$a_{ij} = \frac{1}{(i+j-1)}, \quad i, j = 1, \dots, n.$$

\mathbf{b} is chosen in such a way that the exact solution is $\mathbf{x} = (1, 1, \dots, 1)^T$.

For $n = 5, 9, 20, 100$:

- (1) Find the **condition number of \mathbf{A}** . (10 points)
- (2) Solve it with the **direct method** (using the MATLAB builtin function `\`, or Python builtin function `numpy.linalg.solve`). (10 points)
- (3) Solve it with two iterative methods (**1: Gauss-Seidel or PG; 2: PCG**). For PCG, you can choose the preconditioner as the diagonal matrix made of the diagonal entries of the Hilbert matrix. (20 points)
- (4) Compare **the error for all three methods** (direct + two iterative) and number of iterations for two iterative methods. (10 points)

Show your results like in the following table:

n	$K(\mathbf{A}_n)$	\ PG			PCG	
		Error	Error	Iter	Error	Iter
4	1.55e+04	7.72e-13	8.72e-03	995	1.12e-02	3
6	1.50e+07	7.61e-10	3.60e-03	1813	3.88e-03	4
8	1.53e+10	6.38e-07	6.30e-03	1089	7.53e-03	4
10	1.60e+13	5.24e-04	7.98e-03	875	2.21e-03	5
12	1.70e+16	6.27e-01	5.09e-03	1355	3.26e-03	5
14	6.06e+17	4.12e+01	3.91e-03	1379	4.32e-03	5

Problem 2: (50 points) Numerically solve the following 1D heat equation:

$$u_t(x, t) - u_{xx}(x, t) = -\sin(x) \sin(t) + \sin(x) \cos(t), \quad x \in (0, \pi/2), t > 0.$$

subject to Dirichlet BCs:

$$u(0, t) = 0 \quad \text{and} \quad u(\pi/2, t) = \cos(t) \quad \text{for } t > 0,$$

and the initial condition:

$$u(x, 0) = \sin(x) \quad \text{for } x \in [0, \pi/2].$$

Use **one explicit** and **one implicit schemes** for **solving the resulting IVP** until **$T = \pi$** .

- (1) (30 points) Use some plots to demonstrate that your numerical solutions are accurate. The exact solution of this 1D heat equation is $u(x, t) = \sin(x) \cos(t)$.
- (2) (20 points) Choose two different Δ_x and two different Δt , discuss how they affect the accuracy of your numerical solutions. To assist your discussion, you can evaluate the error as $\frac{\|\mathbf{u}(T) - \mathbf{u}^n\|^2}{\|\mathbf{u}(T)\|^2}$, and then compare the errors obtained with different Δ_x and Δt , where $\mathbf{u}(T)$ denotes the exact solution at $T = \pi$; \mathbf{u}^n denotes your numerical solution at the last time step; $\|\cdot\|^2$ is square of the vector magnitude.