

```

# Import Dependencies
import numpy as np
import matplotlib.pyplot as plt
from sklearn.gaussian_process import GaussianProcessRegressor
from sklearn.gaussian_process.kernels import RBF, WhiteKernel,
ExpSineSquared, ConstantKernel
from sklearn.kernel_ridge import KernelRidge

```

## Midterm 1 Project, Problem 2-6

```

# Part 1: Generate noisy data as done previously
x = np.linspace(0, 50, 1000) # Generate 1000 evenly spaced x data
points
y_true = np.cos(x) # True function y = cos(x)

# Randomly select 40 points from the first 500 data points
np.random.seed(42) # Ensure reproducibility
indices = np.random.choice(np.arange(500), size=40, replace=False)

# Add i.i.d. random noise (mean 0, variance 0.16) to the 40 selected
points
noise = np.random.normal(0, np.sqrt(0.16), size=40)
x_train = x[indices].reshape(-1, 1) # Select 40 x points from the
first 500
y_train_noisy = y_true[indices] + noise # Add noise to the
corresponding y points

# Part 2: Fit a Gaussian Process (GP) model using a periodic kernel
# Define the kernel: periodic kernel (ExpSineSquared) + white noise
(WhiteKernel)
kernel_gp = ExpSineSquared(length_scale=1.0, periodicity=1.0) +
WhiteKernel(noise_level=1.0)

# Create the Gaussian Process Regressor with the specified kernel
gp = GaussianProcessRegressor(kernel=kernel_gp,
n_restarts_optimizer=10)

# Fit the GP to the noisy data
gp.fit(x_train, y_train_noisy)

# Predict using the GP on the full x range
x_pred = x.reshape(-1, 1)
y_pred_gp, y_std_gp = gp.predict(x_pred, return_std=True)

# Part 3: Use the same periodic kernel for KRR and set  $\lambda$  to 10
krr_kernel = ExpSineSquared(length_scale=1.0, periodicity=1.0)

# Set penalty coefficient  $\lambda$  to 10
penalty_coefficient = 10
print(f"Penalty Coefficient for KRR ( $\lambda$ ): {penalty_coefficient}")

```

```

# Fit the KRR model with  $\lambda = 10$ 
krr = KernelRidge(kernel=krr_kernel, alpha=penalty_coefficient)
krr.fit(x_train, y_train_noisy)

# Predict using the KRR model
y_pred_krr = krr.predict(x_pred)

# Plot the results with GP, KRR  $\lambda = 10$ , and the true function
plt.figure(figsize=(10, 6))

# Plot the true function  $y = \cos(x)$ 
plt.plot(x, y_true, label=r"$y = \cos(x)$", color='blue')

# Plot the noisy training data points
plt.scatter(x_train, y_train_noisy, label="Noisy Training Data",
            color='red', zorder=5)

# Plot the GP predictions with uncertainty bounds
plt.plot(x_pred, y_pred_gp, label="GP Prediction", color='green')
plt.fill_between(x_pred.flatten(), y_pred_gp - 1.96 * y_std_gp,
                 y_pred_gp + 1.96 * y_std_gp, alpha=0.2, color='green')

# Plot the KRR predictions with  $\lambda = 10$ 
plt.plot(x_pred, y_pred_krr, label="KRR Prediction with  $\lambda = 10$ ",
         color='orange')

# Set labels, title, and legend
plt.title("GP vs KRR ( $\lambda = 10$ ) Predictions")
plt.xlabel("x")
plt.ylabel("y")
plt.legend()
plt.grid(True)

# Show the plot
plt.show()

```

Penalty Coefficient for KRR ( $\lambda$ ): 10

GP vs KRR ( $\lambda = 10$ ) Predictions

