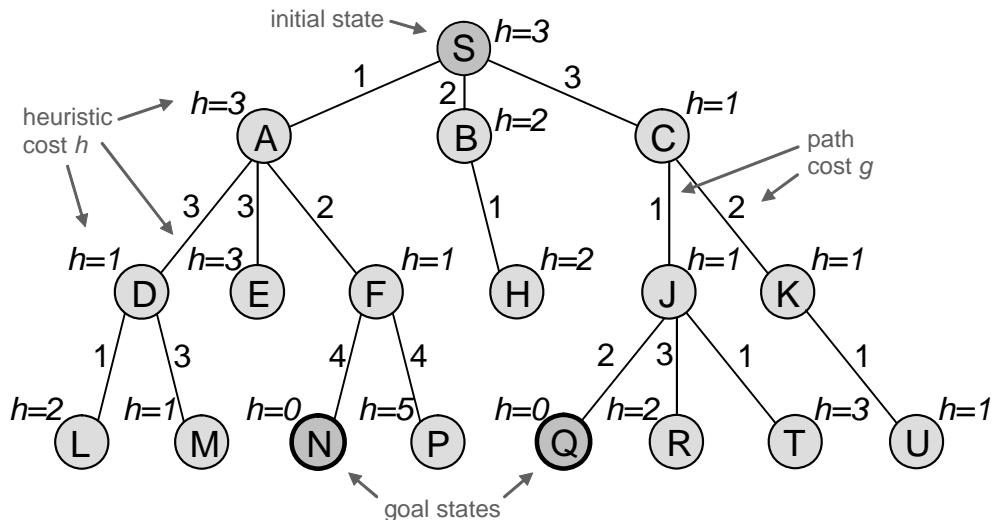


**3.1** Explain which search algorithm is most appropriate in the following situations:

- We have a very large search space with a large branching factor and with possibly infinite paths. We have no heuristic function. We want to find a path to the goal with minimum number of states.
- We have a state space with lots of cycles and links of varying costs. We have no heuristic function. We want to find the shortest path.
- Our search space is a tree of fixed depth and all the goals are at the bottom of the tree. We have a heuristic function and we want to find any goal as quickly as possible.

**3.2** Consider the search problem defined by the annotated search tree below.



- Apply the standard A\* search algorithm. Draw all generated nodes, write their  $f$ -costs, and number expanded nodes in order of expansion. Assume that the children of a node are processed in alphabetical order, and that nodes of equal priority are extracted from the search queue in FIFO order.
- State how many nodes were generated and how many were expanded. Comment on the solution obtained and the effectiveness of the search. What do you think of the heuristic function  $h$  employed?

**3.3** The  $w$ -A\* search algorithm is a weighted variant of A\* that places more emphasis on the heuristic function by using the  $f$ -cost  $f_w(n) = g(n) + w \times h(n)$ , for any  $w > 1$ .

- Similarly to question 3.2a, apply the  $w$ -A\* search algorithm for  $w = 2$ .
- Similarly to question 3.2b, comment on the performance and usefulness of the  $w$ -A\* search algorithm – in this case and in general.