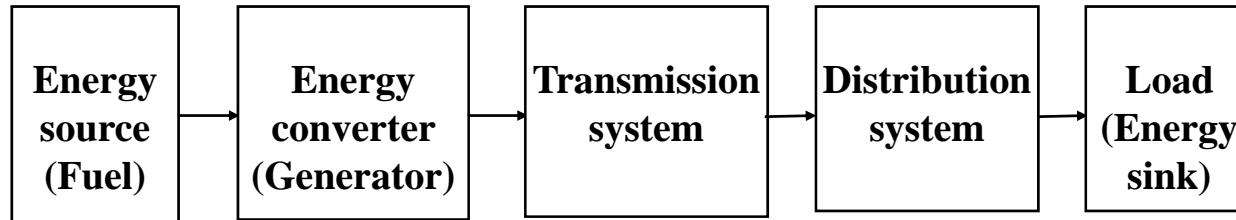


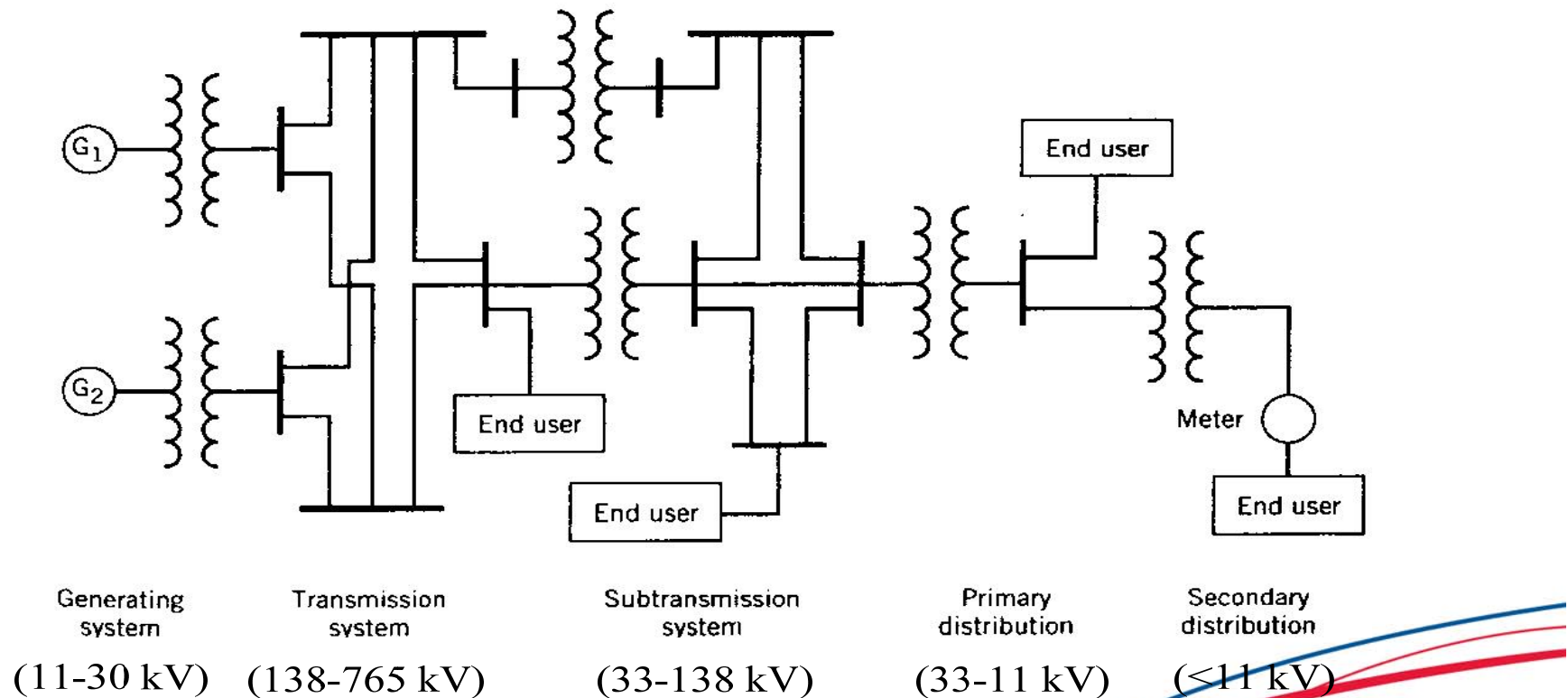
1. INTRODUCTION TO POWER SYSTEMS

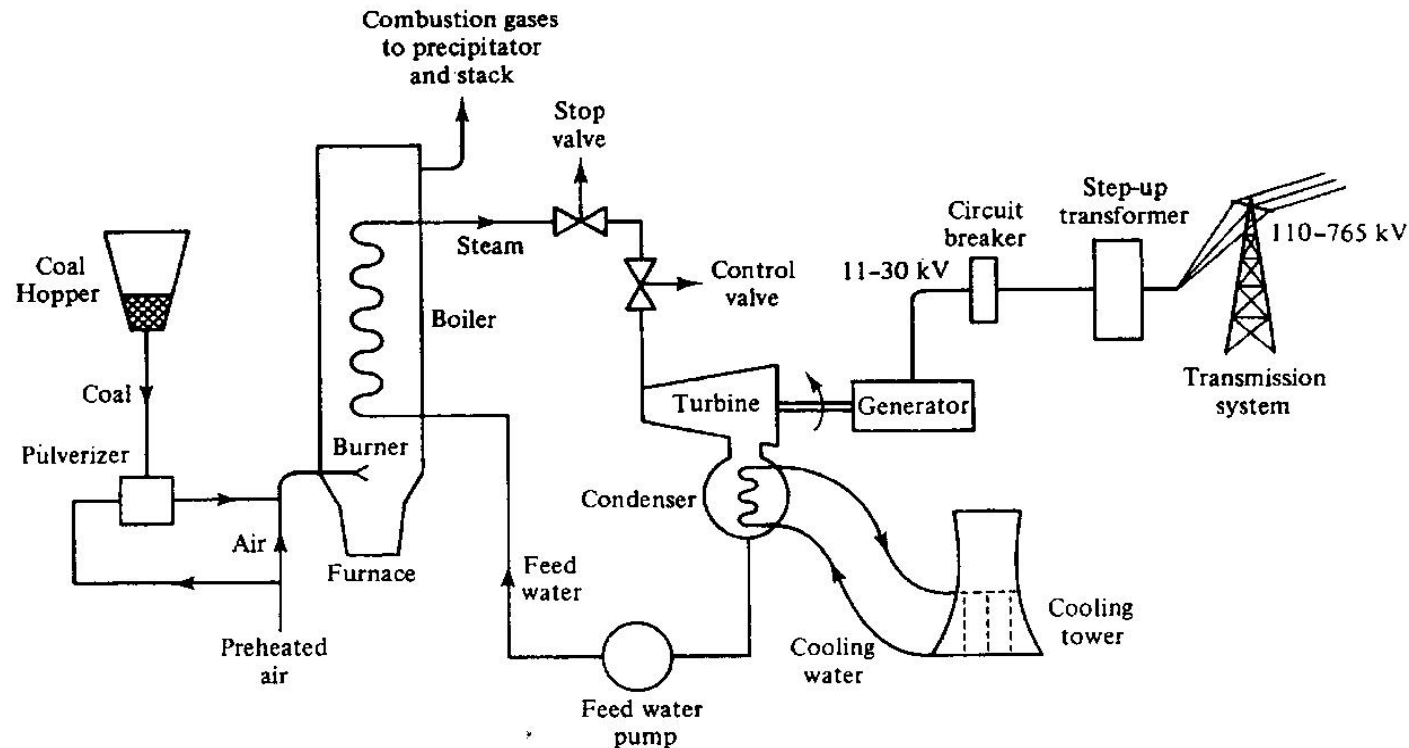
The structure of the electric power or energy system is very large & complex. Nevertheless, it can be divided into five basic stages/components/subsystems.



- Energy source may be
 - coal, gas or oil (fossil fuel)
 - fissionable material (nuclear)
 - water in a dam (hydro)
 - renewable sources e.g. solar, wind, tidal, biofuels, geothermal
- Generator that transforms non-electrical energy to electrical energy; usually rotating-machinery type; power output from few kilowatts to few thousand MW; voltage levels 440 V to 25 kV.
- Transmission system transports generated energy from generating stations to major load centres; voltage levels 115 kV to 765 kV (less than 138 kV usually referred to as sub-transmission system); overhead lines & underground cables.

- Transformers used to change voltage levels (to high over transmission system & low over distribution system, etc)
- Distribution system transports transmitted energy from transmission system to users; voltage levels typically 1 kV to 33 kV.
- Loads : industrial, commercial, residential, farm, etc.





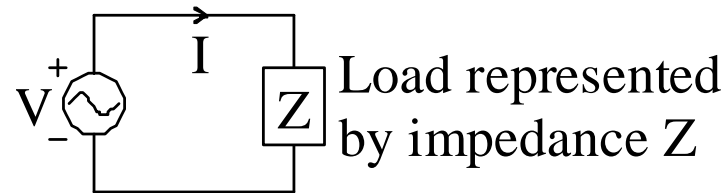
Schematic of a Coal-fired Generating Station

2. REVIEW OF SINGLE-PHASE & THREE-PHASE CIRCUITS

Before we embark on a detailed study of the generators & lines, it would help to quickly review the basic concepts of :

- 3-phase systems (as most power systems operate as 3- ϕ systems)
- Single-phase equivalent of 3- ϕ systems (since for balanced 3- ϕ systems, we can use one phase of the star(Y)-equivalent)
- Per unit (p.u.) systems

- ⇒ Recall that all the above have been covered elsewhere (EE2005/EE3010), but since we will be using them extensively, it is worth taking a look back in time!
- ⇒ First, a review of the one-phase system.



Let $V = |V| \angle 0^\circ$ (reference) & $Z = |Z| \angle \theta$, where θ is power factor angle.
 $\therefore Z = R + jX$ (assuming inductive load)

$$\Rightarrow R = |Z| \cos \theta \text{ \& } X = |Z| \sin \theta$$

$$\Rightarrow I = \frac{V}{Z} = \frac{|V| \angle 0^\circ}{|Z| \angle \theta} = \frac{|V|}{|Z|} \angle -\theta = |I| \angle -\theta$$

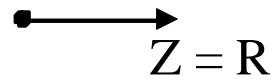
Apparent power S (VA, kVA, MVA and $|S| = |V| |I|$)

$$\begin{aligned} \Rightarrow S &= VI^* = (|V| \angle 0^\circ)(|I| \angle \theta) = |V| |I| \angle \theta = |S| \angle \theta \\ &= |V| |I| \cos \theta + j |V| |I| \sin \theta \\ &= P + jQ \end{aligned}$$

where P : Real (active) power (W, kW, MW)

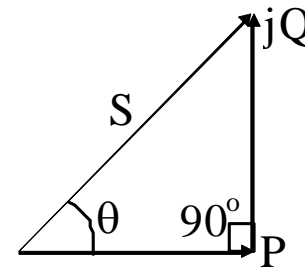
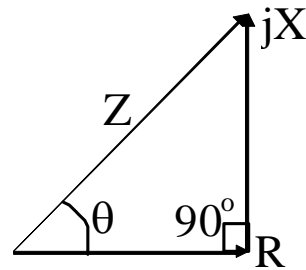
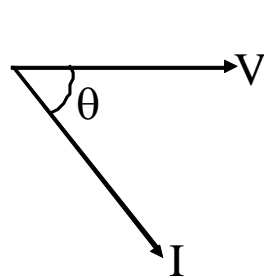
Q : Imaginary (reactive) power (var, kvar, Mvar)

⇒ **For $\theta = 0^\circ$ (unity power factor load)**

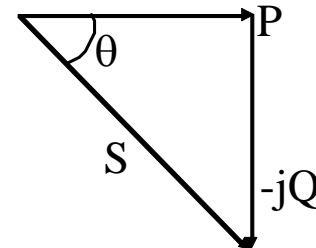
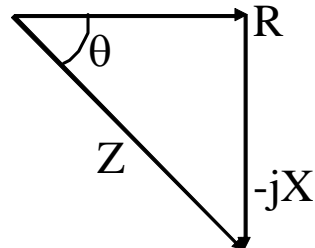
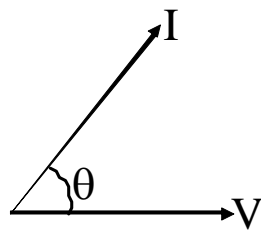


$$S = P \\ = |V| |I|$$

⇒ **For lagging P.F. loads,**



⇒ **For leading P.F. loads,**



What are Real & Reactive Powers?

By convention,

- Lagging vars \Rightarrow Inductive load $\Rightarrow Q$ (+VE)
- Leading vars \Rightarrow Capacitive load $\Rightarrow Q$ (-VE)

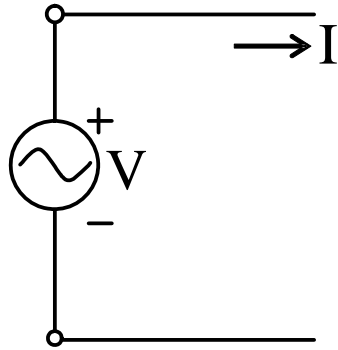
$$\begin{aligned} P &= \text{Real or active power, consumed/dissipated in resistance } R \\ &= |V| |I| \cos \theta = (|I| |Z|) |I| \cos \theta = |I|^2 |Z| \cos \theta \\ &= |I|^2 R \end{aligned}$$

$$\begin{aligned} Q &= \text{Reactive power absorbed by inductive reactance } X \text{ (or generated by} \\ &\text{capacitive reactance)} \\ &= |V| |I| \sin \theta = |I| |Z| |I| \sin \theta = |I|^2 |Z| \sin \theta \\ &= |I|^2 X \end{aligned}$$

Represents the energy exchange between source & reactor/capacitor i.e. represents stored energy.

Convention for Real & Reactive Powers

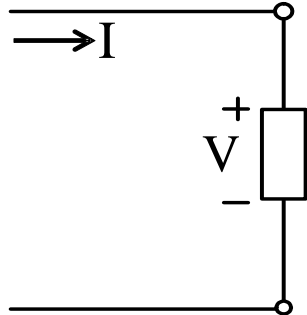
1) Generators



$$S = VI^* = P + jQ$$

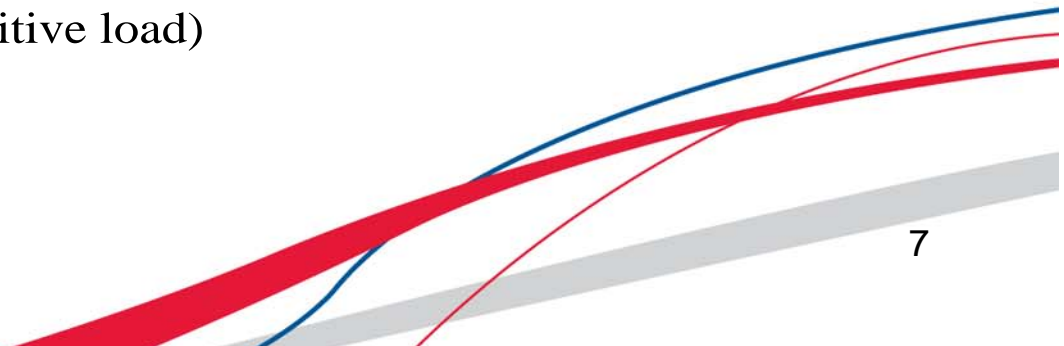
- If P is positive, real power is delivered/supplied
- If P is negative, real power is absorbed by source
- If Q is positive, reactive power is supplied/delivered
- If Q is negative, reactive power is absorbed by source

2) Loads



$$S = VI^* = P + jQ$$

- If P is positive, real power is absorbed by the load
- If P is negative, real power is supplied by the load
- If Q is positive, reactive power is absorbed by the load (lagging PF load \Rightarrow inductive load)
- If Q is negative, reactive power is supplied by the load (leading PF load \Rightarrow capacitive load)

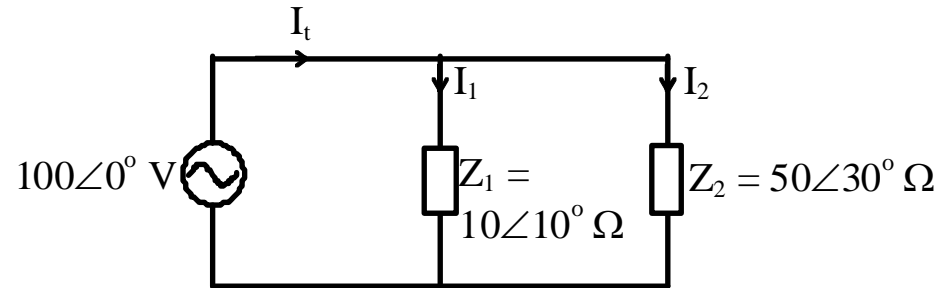


⇒ Inductive load absorbs reactive power.

⇒ Capacitive load generates reactive power, or absorbs negative reactive power.

Review Exercises (1 & 2)

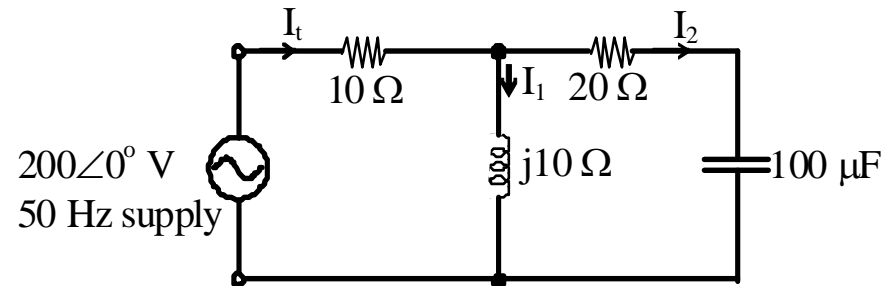
(1)



Find the

- a) Real power P (1158.014 W)
- b) Reactive power Q (273.657 VAr lag)
- c) Apparent power S (1189.91 VA)
- d) Power factor of the Network (0.973 lag)

(2)



Find the Network

- a) Power factor (0.7 lag)
- b) Real power (1601.16 W)
- c) Reactive power (1628.2 VAr)
- d) Apparent power (2283.6 VA)

Review of Balanced 3-phase Systems

- Mesh or Delta (Δ) connection
- Star or Wye (Y) connection

Usually (By default if not specified), 3- ϕ systems specified in terms of

- total 3- ϕ S, P, Q
- line-to-line voltages
- line currents

Remember : $\cos \theta = \text{power factor}$

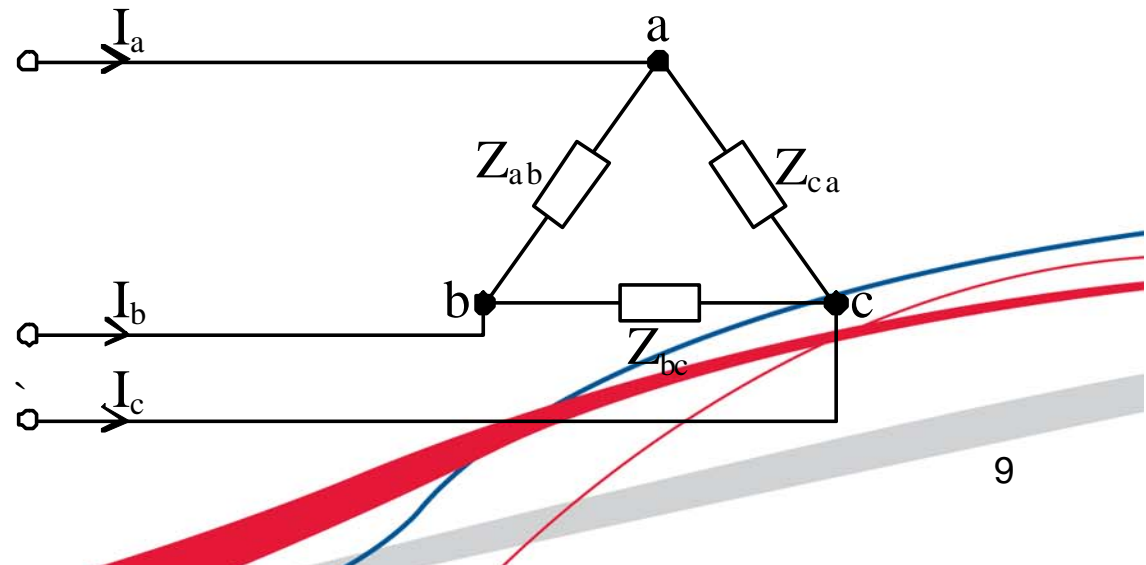
$\theta =$ power factor angle, where θ is always between phase voltage & phase current of the same phase.

Delta Connection

$$Z_{ab} = Z_{ca} = Z_{bc} = |Z| \angle \theta$$

$$I_{ab} = \frac{V_{ab}}{Z_{ab}}, \quad I_{bc} = \frac{V_{bc}}{Z_{bc}} \quad \&$$

$$I_{ca} = \frac{V_{ca}}{Z_{ca}}$$



If $V_{ab} = \text{Reference} = |V_{ab}| \angle 0^\circ \text{ V}$

Then $V_{bc} = |V_{ab}| \angle -120^\circ \text{ V}$

& $V_{ca} = |V_{ab}| \angle 120^\circ \text{ V}$

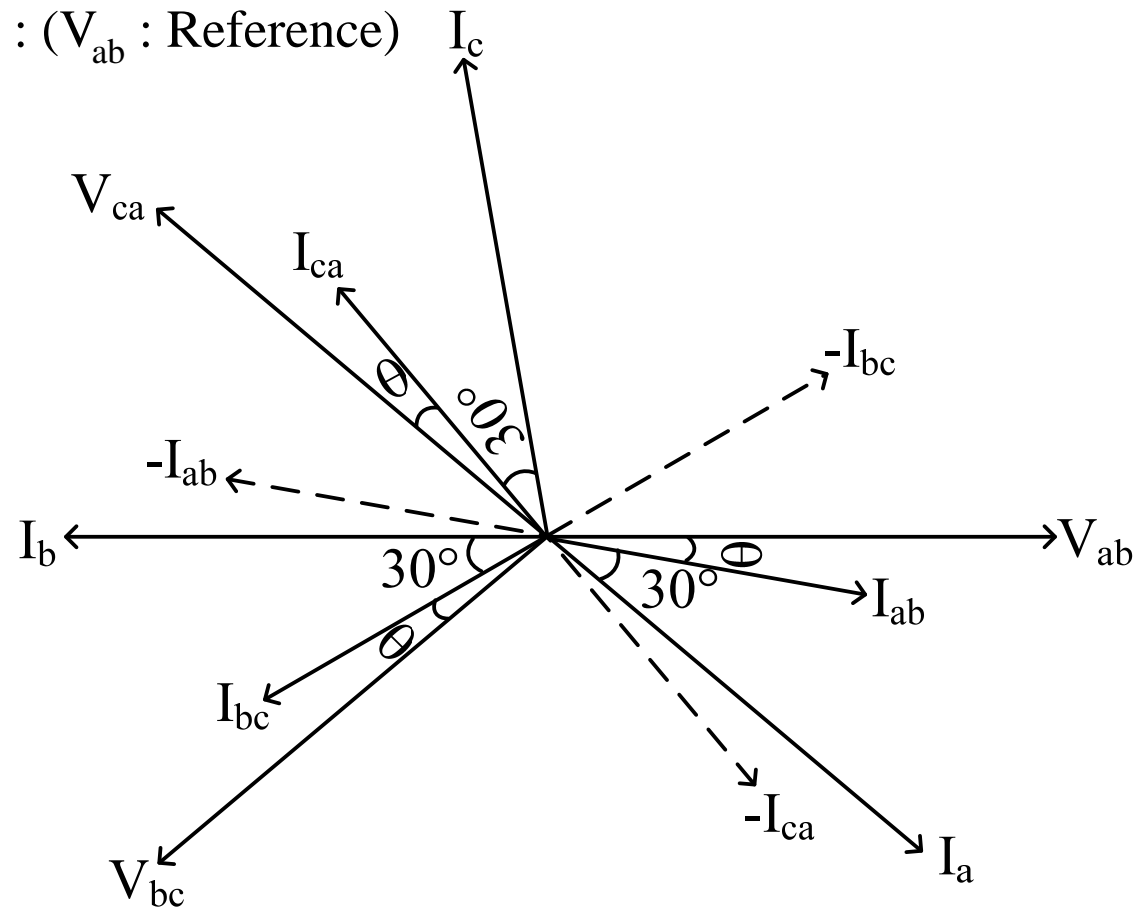
Line currents $I_a = I_{ab} - I_{ca}$
 $I_b = I_{bc} - I_{ab}$ & $I_c = I_{ca} - I_{bc}$

$$\Rightarrow \begin{aligned} I_a &= \sqrt{3} |I_{ab}| \angle -\theta - 30^\circ \\ I_b &= \sqrt{3} |I_{bc}| \angle -120^\circ - \theta - 30^\circ \\ I_c &= \sqrt{3} |I_{ca}| \angle 120^\circ - \theta - 30^\circ \end{aligned} \quad \begin{aligned} |I_{\text{LINE}}| &= \sqrt{3} |I_{\text{PHASE}}| \\ |V_{\text{LINE}}| &= |V_{\text{PHASE}}| \end{aligned}$$

$$\begin{aligned} \text{Apparent power } S &= 3 V_{\text{PHASE}} I_{\text{PHASE}}^* \\ &= 3 |V_{\text{PHASE}}| |I_{\text{PHASE}}| \angle \theta \\ &= 3 |V_{\text{LINE}}| \frac{1}{\sqrt{3}} |I_{\text{LINE}}| \angle \theta \\ &= \sqrt{3} |V_{\text{LINE}}| |I_{\text{LINE}}| \angle \theta \text{ VA} \end{aligned}$$

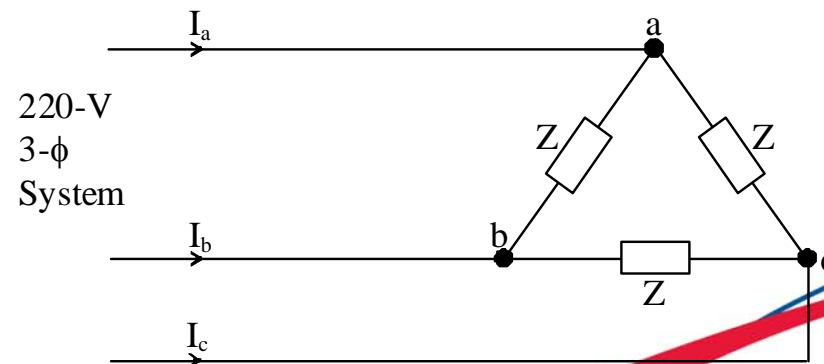
$$\begin{aligned} \Rightarrow S &= \sqrt{3} |V_{\text{LINE}}| |I_{\text{LINE}}| \cos \theta + j \sqrt{3} |V_{\text{LINE}}| |I_{\text{LINE}}| \sin \theta \\ &= P + jQ \end{aligned}$$

Phasor Diagram : (V_{ab} : Reference)



Review Exercise (3)

(3)



$$Z = 30 \angle -15^\circ \Omega$$

Find phase & line currents. Sketch phasor diagram.

$$(I_a = 12.7 \angle -15^\circ \text{ A})$$

Y-connection

$$I_a = I_{an} = \frac{V_{an}}{Z}$$

$$= \frac{|V_{an}|}{|Z|} \angle -\theta$$

$$\text{Reference } V_{an} = |V_{an}| \angle 0$$

$$V_{ab} = V_{an} + V_{nb}$$

$$V_{bc} = V_{bn} + V_{nc}$$

$$V_{ca} = V_{cn} + V_{na}$$

$$\text{Here } |I_{\text{LINE}}| = |I_{\text{PHASE}}|$$

$$\& |V_{\text{LINE}}| = \sqrt{3} |V_{\text{PHASE}}|$$

$$S = 3 V_{\text{PHASE}} I_{\text{PHASE}}^*$$

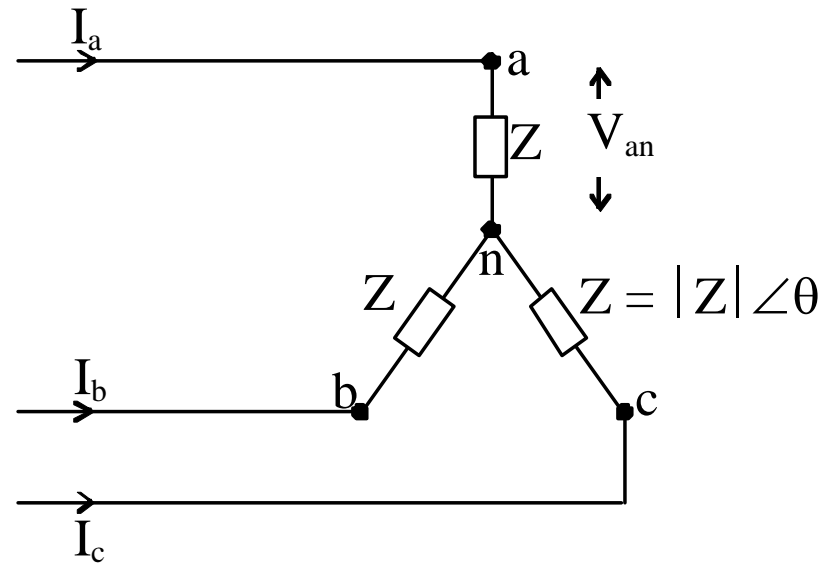
$$= 3 |V_{\text{PHASE}}| \angle 0^\circ [|I_{\text{PHASE}}| \angle \theta]$$

$$= 3 \frac{1}{\sqrt{3}} |V_{\text{LINE}}| |I_{\text{LINE}}| \angle \theta$$

$$= \sqrt{3} |V_{\text{LINE}}| |I_{\text{LINE}}| \angle \theta$$

$$= \sqrt{3} |V_{\text{LINE}}| |I_{\text{LINE}}| \cos \theta + j \sqrt{3} |V_{\text{LINE}}| |I_{\text{LINE}}| \sin \theta$$

$$= P + jQ$$



Review Exercise (4)

(4) $V_{AB} = 208 \angle 30^\circ \text{ V}$

Load $Z = (4 + j3) \Omega$ in each phase.

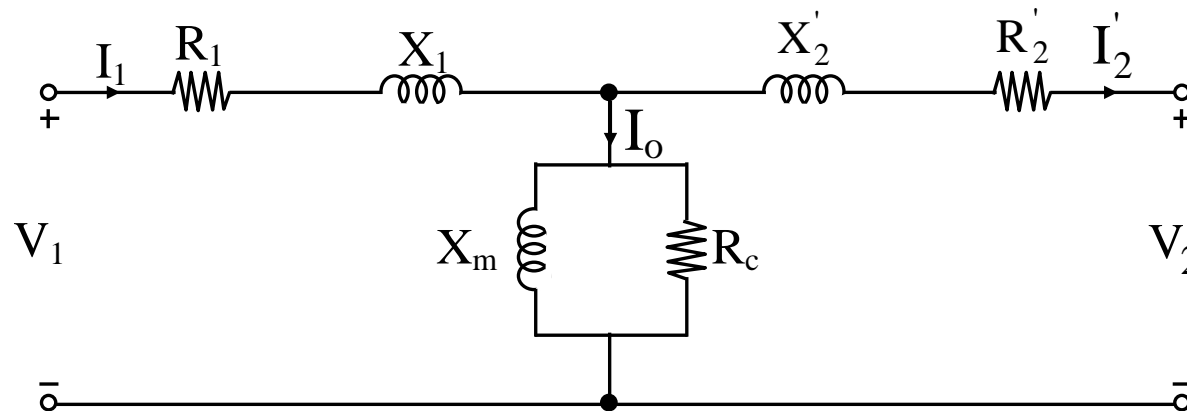
- Find the line currents & power dissipated in the loads (total power).
- Also find Q & S.

[Y-connected system, phase seq. A-B-C]

$I_a = 24.02 \angle -36.87^\circ \text{ A}$, $P = 6923 \text{ W}$, $Q = 5192.17 \text{ VAr lag}$, $S = 8653.7 \text{ VA}$

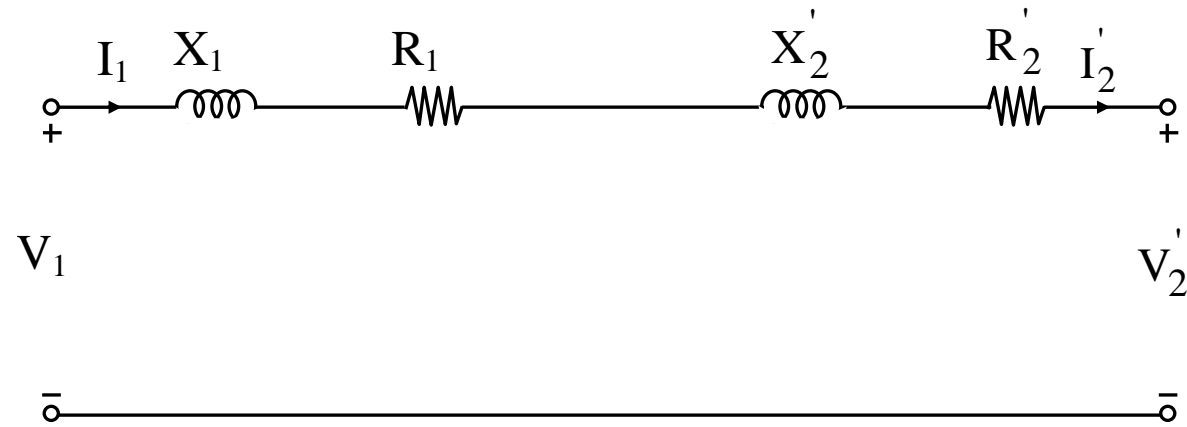
Review of Transformer's Equivalent CKT.

\Rightarrow Equivalent circuit (per phase)

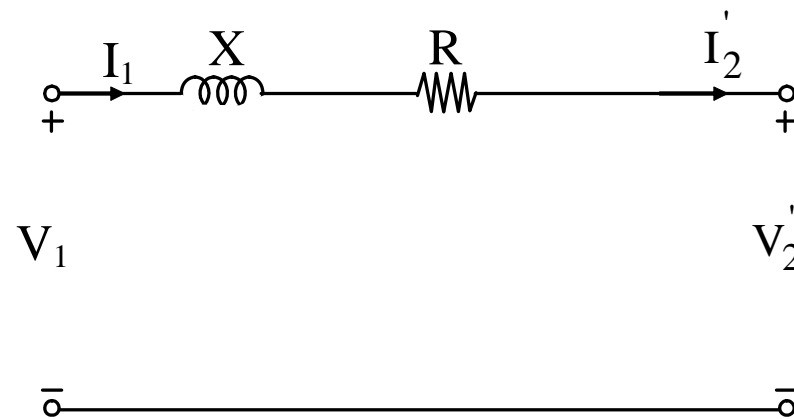


(All quantities referred to the primary)

\Rightarrow Approximate equivalent circuit (neglecting magnetizing current)

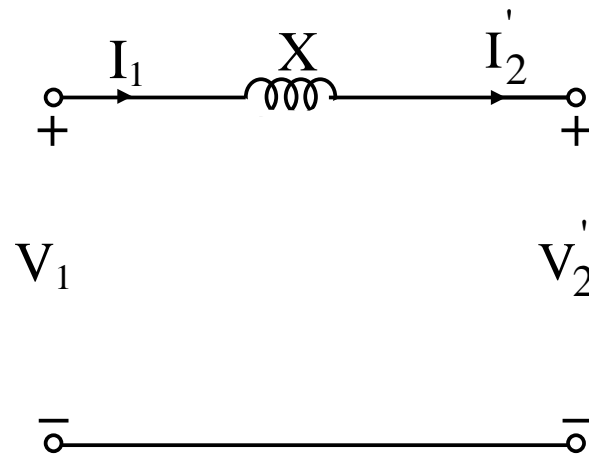


which reduces to



where $R = R_1 + R_2' = \text{total equivalent resistance}$ & $X = X_1 + X_2' = \text{total equivalent reactance}$.

\Rightarrow Frequently R is neglected, in which case



In other words, the transformer can be replaced by an equivalent impedance, or just an equivalent reactance.

3. PER-UNIT (P.U.) SYSTEM

- Power transmission lines are operated at very high voltage levels (kilovolts). Due to the large amount of power transmitted, megawatts & megavoltamps are commonly-used terms!
- It therefore would be more meaningful to scale down all physical values of Ω , A, kV, MVA, MW using scaling factors called based values. For example, if a base voltage of 100 kV is selected, then physical system voltages of 80 kV, 110 kV & 100 kV become $\frac{80}{100}$, $\frac{110}{100}$ & $\frac{100}{100}$ per unit respectively!

- The per-unit value of any quantity is defined as the ratio of the actual quantity to an “arbitrarily” chosen value (base or reference) of the same dimensions.

$$\therefore \text{Quantity in per unit} = \frac{\text{physical quantity}}{\text{base value}}$$

$$\& \text{Quantity in percent} = \frac{\text{physical quantity}}{\text{base value}} \times 100$$

- Percent system should be used with caution (due to mult. factor of 100)
- Per-unit system is preferred in power system calculations as it offers the following advantages :

Advantages of Per-unit System

- Analysis is greatly simplified, e.g. all impedances of a given equivalent CKT can be directly added without considering system voltages.
- Use of “ $\sqrt{3}$ ” is eliminated! The base values account for these easily.
- Manufacturers of electrical equipment usually specify the impedance in per unit or percent of nameplate ratings.

- Electrical machines & transformers have widely varying internal impedances with size & rating. However, it turns out that in the p.u. system, these impedances fall within a fairly narrow range. Hence, if the actual impedance of a machine is not known, its per unit value can be easily assigned!
- Circuit analyst is relieved of the worry of referring quantities to one side or other side of transformer, especially in large networks containing many transformers of different turns ratios.

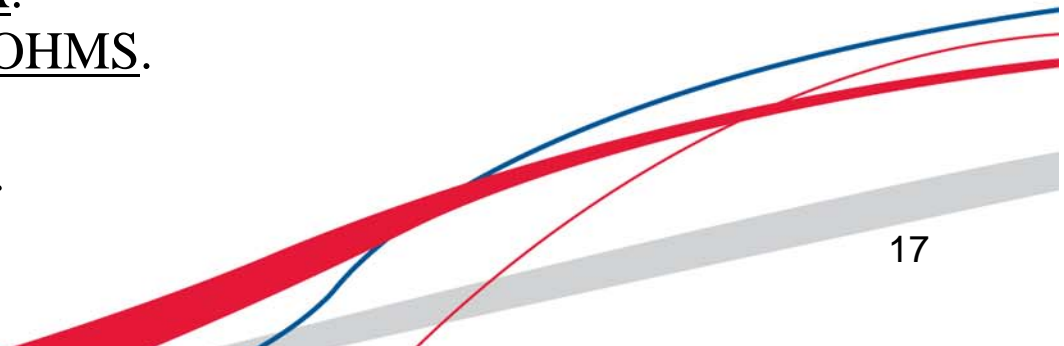
⇒ Eliminates the possible cause of making serious calculation mistakes!

- P.U. values are more convenient in simulating machine systems on digital computers.

Significant advantage : Per unit impedance of transformer is the same on both sides of the transformer!

Per Unit (p.u.) Quantities in 3-phase Power System

- There are 4 base values
 1. Power base S_b , usually in MVA.
 2. Impedance base Z_b , usually in OHMS.
 3. Current base I_b , usually in A.
 4. Voltage base V_b , usually in kV.



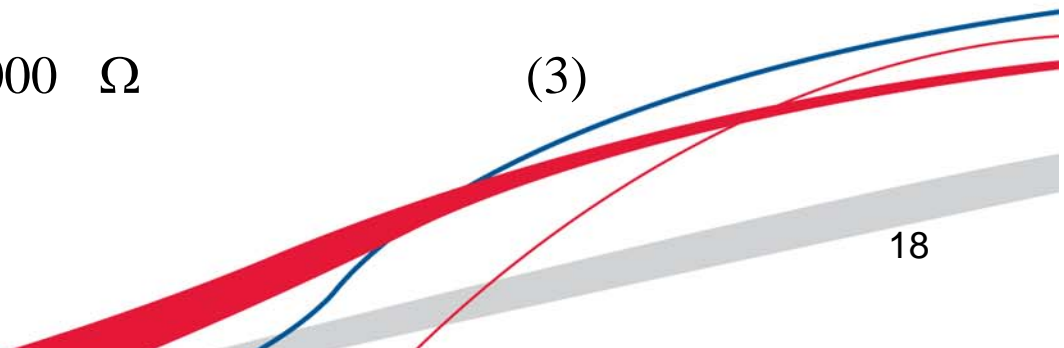
- In 3-phase systems, usually
 - S, P, Q are three-phase powers in MVA, MW & MVA_r respectively
 - Voltages considered are line-to-line values
 - Currents considered are line values
 - Impedances considered are phase values of equivalent star (Y) configuration
(This means that all impedances in Ω must be converted to equivalent Y value in Ω , before converting to its p.u. value)
- The 4 base values (S_b , Z_b , I_b & V_b) are related as follows :

$$S_b = \sqrt{3} \frac{V_b I_b}{1000} \text{ MVA} \quad (1)$$

where V_b is line-to-line base voltage in kV & I_b is the line current in AMPS.

$$\Rightarrow I_b = \frac{S_b \times 1000}{\sqrt{3} \times V_b} \quad (2)$$

$$\text{Next, } Z_b = \frac{(V_b / \sqrt{3})}{I_b} \times 1000 \quad \Omega \quad (3)$$



Note : $\frac{V_b}{\sqrt{3}}$ is the phase voltage of the equivalent Y system.

Substituting (2) in (3), we get :

$$Z_b = \frac{(V_b / \sqrt{3})}{\left(\frac{S_b \times 1000}{\sqrt{3} \times V_b} \right)} \times 1000$$

$$\Rightarrow Z_b = \frac{V_b^2}{S_b} \Omega \quad (4)$$

- From the above, it is clear that we need to select only 2 base values, instead of all 4. For example, if S_b & V_b are selected, then I_b & Z_b can be calculated using equations (2) & (4) respectively!
- V_b (and consequently Z_b & I_b too) changes from transformer primary to secondary as follows :

$$\begin{aligned} \frac{V_b \text{ (primary)}}{V_b \text{ (secondary)}} &= \frac{\text{No. of turns (primary)}}{\text{No. of turns (secondary)}} \\ &= \frac{N_1}{N_2} \text{ (line – to – line turns ratio, } a \text{)} \end{aligned}$$

- Per unit values of Z, R, X & I are the same on either side of the transformer, but the actual values are not!

⇒ Per unit quantities can now be evaluated as :

$$Z_{p.u.} = \frac{Z(\Omega)}{Z_b(\Omega)}; I_{p.u.} = \frac{I(\text{AMPS})}{I_b(\text{AMPS})};$$

$$V_{p.u.} = \frac{V(\text{kV})}{V_b(\text{kV})}; P_{p.u.} = \frac{P(\text{MW})}{S_b(\text{MVA})}$$

⇒ If necessary, actual voltages/currents/ohms etc. can also be obtained as :

Actual value = Base value \times p.u. value

General Guidelines for Obtaining P.U. Values

Objective : To reduce the number of computations by selecting suitable values for V_b & S_b .

- Base MVA (S_b) is the same for all parts of the system. Normally S_b in MVA is used.
- Base kV (V_b) is selected in one part of the system; for other parts base kV is obtained according to the line-to-line voltage ratios of transformers.

- Base impedances will be different in different parts of the system.
- In general, the p.u. (or %) impedances of electrical equipment are specified in terms of their own MVA & kV ratings. These values need to be converted to the system bases selected in (1) & (2) above. This conversion is done using the following formula :

$$Z_{\text{p.u. NEW}} = \frac{Z_{\text{ACTUAL}}}{Z_{\text{b NEW}}}$$

$$Z_{\text{p.u. OLD}} = \frac{Z_{\text{ACTUAL}}}{Z_{\text{b OLD}}}$$



Manufacturer's base (Equipment base)

where : $Z_{\text{b NEW}}$ = Base impedance selected in that part of the system where this component is placed

$$= \frac{(V_{\text{b NEW}})^2}{S_{\text{b NEW}}} \Leftarrow \text{these are base values in that section}$$

$$\& Z_{\text{b OLD}} = \frac{(V_{\text{b OLD}})^2}{S_{\text{b OLD}}} \Leftarrow \text{these are component bases/ratings}$$

$$\therefore \frac{Z_{p.u. \text{ NEW}}}{Z_{p.u. \text{ OLD}}} = \frac{Z_{b \text{ OLD}}}{Z_{b \text{ NEW}}} = \frac{(V_{b \text{ OLD}})^2 / S_{b \text{ OLD}}}{(V_{b \text{ NEW}})^2 / S_{b \text{ NEW}}}$$

$$\Rightarrow Z_{p.u. \text{ NEW}} = Z_{p.u. \text{ OLD}} \times \left[\frac{V_{b \text{ OLD}}}{V_{b \text{ NEW}}} \right]^2 \times \left[\frac{S_{b \text{ NEW}}}{S_{b \text{ OLD}}} \right] \quad (*)$$

Example 1 : A component rated for 13.2 kV, 30 MVA & with $Z = 0.2$ p.u. (on its own ratings) is placed in a power system portion where $V_b = 13.8$ kV & $S_b = 50$ MVA. What is the new p.u. Z of the component?

Here,

$S_{b \text{ NEW}} = 50$	$S_{b \text{ OLD}} = 30$
$V_{b \text{ NEW}} = 13.8$	$V_{b \text{ OLD}} = 13.2$
$Z_{p.u. \text{ OLD}} = 0.2$	$Z_{p.u. \text{ NEW}} = ?$

$$\therefore Z_{p.u. \text{ NEW}} = 0.2 \times \left[\frac{13.2}{13.8} \right]^2 \times \left[\frac{50}{30} \right] = 0.306 \text{ p.u.}$$

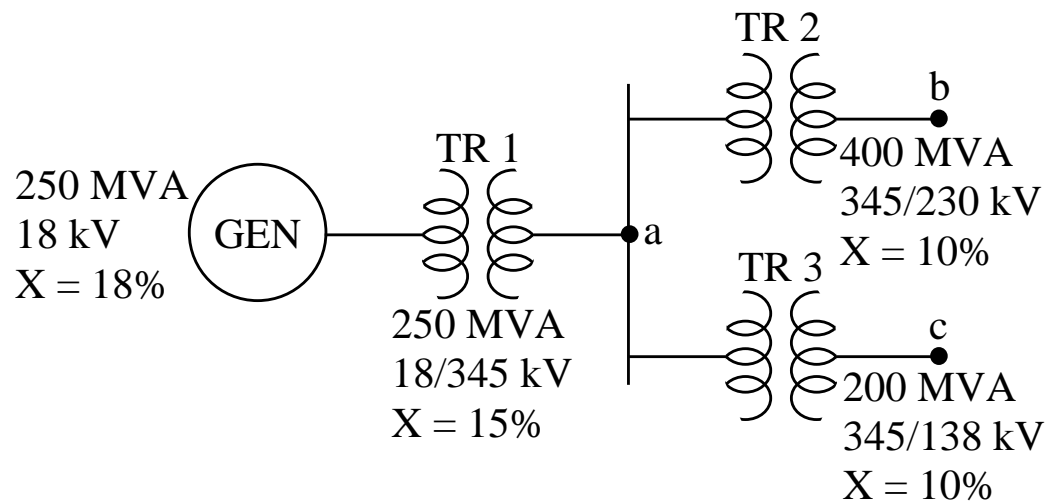
- If a transformer impedance is given in p.u., then this value is based on the MVA rating of the transformer.

\Rightarrow Use equation in (*) above to convert this given p.u. to the new p.u. on the system base kVA, S_b .

- If the S_b (base MVA) is not specified (and that is usually the case), the system component that has the largest MVA rating is chosen to give us the base MVA. Occasionally, a nice round number such as 100 MVA is selected as the base MVA!

Example 2 : For the power system shown below,

- Find appropriate voltage bases by selecting $V_b = 18$ kV at the generator terminals.
- Find all impedances in p.u. Use $S_b = 100$ MVA.



Solution : Given $V_{b, \text{GEN}} = 18$ kV (generator circuit)

Base voltage at point a = $V_{b, a}$

$$V_{b, \text{GEN}} \times \frac{345}{18} = 345 \text{ kV}$$

$$\text{Base voltage at point b} = V_{b,b} = V_{b,a} \times \frac{230}{345} = 230 \text{ kV}$$

$$\text{Finally, base voltage at point c} = V_{b,c} = V_{b,a} \times \frac{138}{345} = 138 \text{ kV}$$

Next, assuming a power base of $S_b = 100 \text{ MVA}$, let us find all the impedances in p.u.

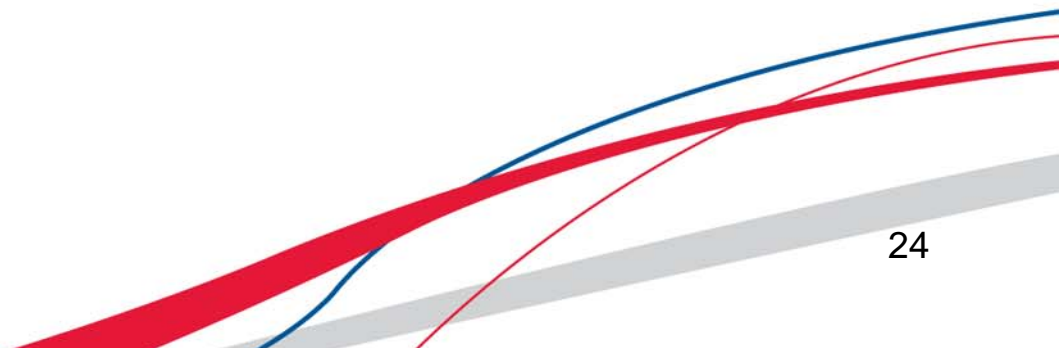
$$\begin{aligned} Z_{\text{GEN,NEW p.u.}} &= Z_{\text{GEN,OLD p.u.}} \times \left[\frac{V_{b \text{ OLD,GEN}}}{V_{b, \text{GEN}}} \right]^2 \times \frac{S_{b \text{ NEW}}}{S_{b \text{ OLD,GI}}} \\ &= 0.18 \times \left(\frac{18}{18} \right)^2 \times \left(\frac{100}{250} \right) = 0.072 \text{ p.u.} \end{aligned}$$

$$Z_{\text{TR1,NEW p.u.}} = Z_{\text{TR1,OLD p.u.}} \times \left[\frac{V_{b \text{ OLD,TR1}}}{V_{b, \text{GEN}}} \right]^2 \times \left[\frac{S_{b \text{ NEW}}}{S_{b \text{ OLD,TR1}}} \right]$$

↑

Calculated on the primary side

$$\begin{aligned} &= 0.15 \times \left[\frac{18}{18} \right]^2 \times \left[\frac{100}{250} \right] \\ &= 0.06 \text{ p.u.} \end{aligned}$$



$$Z_{\text{TR2,NEW p.u.}} = Z_{\text{TR2,OLD p.u.}} \times \left[\frac{V_{\text{b OLD,TR2}}}{V_{\text{b,a}}} \right]^2 \times \left[\frac{S_{\text{b NEW}}}{S_{\text{b OLD,TR2}}} \right]$$

↑

Calculated on the primary side

$$= 0.10 \times \left[\frac{345}{345} \right]^2 \times \left[\frac{100}{400} \right]$$

$$= 0.025 \text{ p.u.}$$

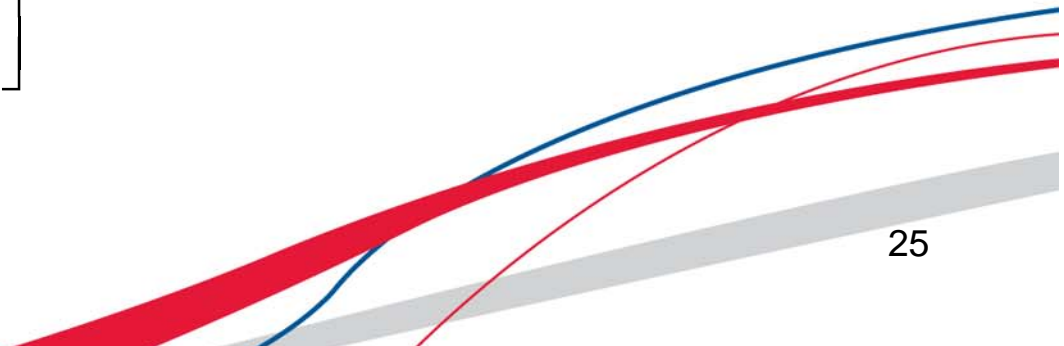
$$Z_{\text{TR3,NEW p.u.}} = Z_{\text{TR3,OLD p.u.}} \times \left[\frac{V_{\text{b OLD,TR3}}}{V_{\text{b,a}}} \right]^2 \times \left[\frac{100}{200} \right]$$

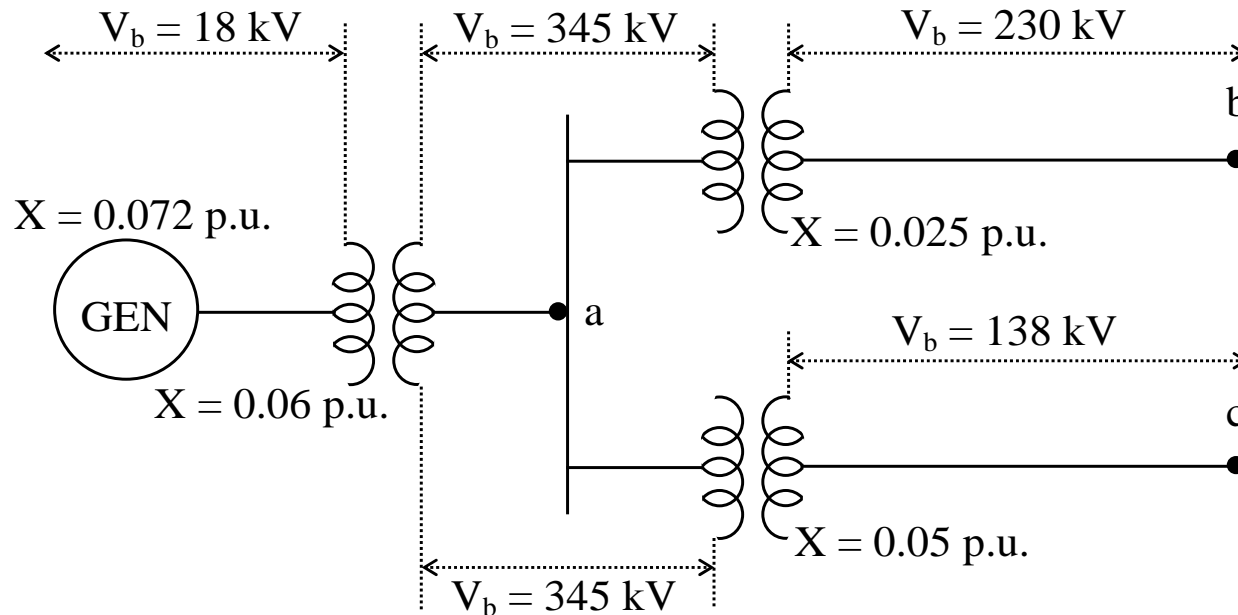
↑

Calculated on the primary side

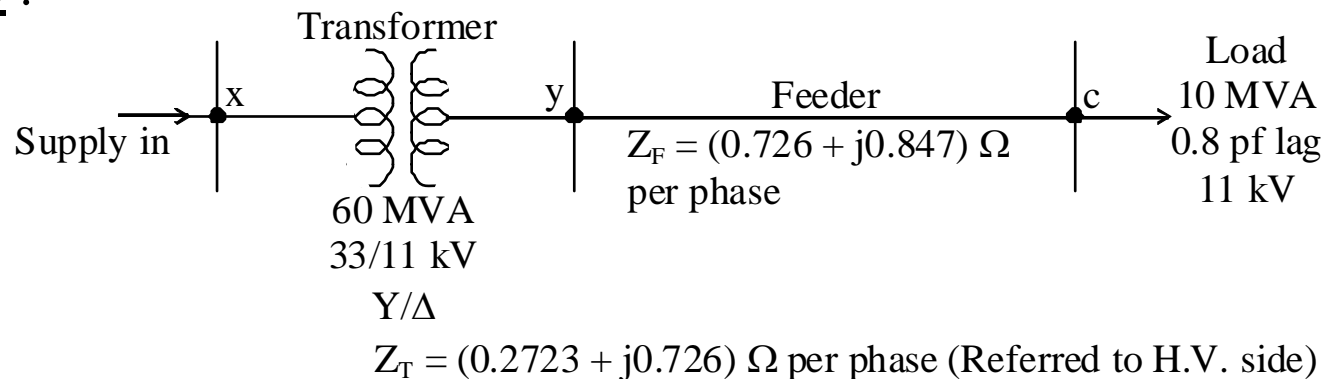
$$= 0.10 \times \left[\frac{345}{345} \right]^2 \times \left[\frac{1}{2} \right]$$

$$= 0.05 \text{ p.u.}$$





Example 3 :



Calculate the input & output line voltages of the 3- ϕ transformer i.e. voltages at x and y.

Solution : Let base MVA = $S_b = 60$ MVA (constant throughout the system)

Transformer H.V. side

Base kV, $V_{b\ x} = 33\text{ kV}$ (assumed)

$$Z_{b\ \text{primary of trans.}} = Z_{b\ x} = \frac{V_{b\ x}^2}{S_b} = \frac{33^2}{60} = 18.15\ \Omega = Z_{b\ \text{pri}}$$

$$\therefore Z_{T\ \text{p.u.}} = \frac{Z_{T\ \text{actual pri}}}{Z_{b\ \text{pri}}} = \frac{0.2723 + j0.726}{18.15} = 0.015 + j0.04 = 0.0427 \angle 69.44^\circ\ \text{p.u.}$$

Transformer L.V. side

Base kV = $V_{b\ y} = V_{b\ x} \frac{11}{33} = 11\text{ kV}$

$$\therefore Z_{b\ y} = \frac{(V_{b\ y})^2}{S_b} = \frac{11^2}{60} = 2.017\ \Omega$$

$$\therefore Z_{F\ \text{p.u.}} = \frac{Z_F(\Omega)}{Z_{b\ y}} = \frac{0.726 + j0.847}{2.017} = 0.36 + j0.42 = 0.5532 \angle 49.4^\circ\ \text{p.u.}$$

\therefore Total impedance

$$Z_{\text{TOT p.u.}} = Z_{T\ \text{p.u.}} + Z_{F\ \text{p.u.}} = 0.5935 \angle 50.81^\circ\ \text{p.u.}$$

$$S_{\text{Load}} = 10\text{ MVA}, 0.8\text{ pf lag} = 10 \angle 36.87^\circ\text{ MVA}$$

$$\therefore S_{\text{Load p.u.}} = \frac{S_{\text{Load}}}{S_b} = \frac{10 \angle 36.87^\circ}{60} = 0.1667 \angle 36.87^\circ \text{ p.u.}$$

$$V_{\text{Load}} = 11 \text{ kV} \Rightarrow V_{\text{Load p.u.}} = \frac{V_{\text{Load}}}{V_{b c}} = \frac{11}{11} = 1.0 \angle 0^\circ \text{ p.u.}$$

\Rightarrow Load current

$$I_{\text{Load p.u.}}^* = \frac{S_{\text{Load p.u.}}}{V_{\text{Load p.u.}}} = \frac{0.1667 \angle 36.87^\circ}{1 \angle 0^\circ} = 0.1667 \angle 36.87^\circ \text{ p.u.}$$

$$\Rightarrow I_{\text{Load p.u.}} = 0.1667 \angle -36.87^\circ \text{ p.u.}$$

\therefore Voltage at the L.V. side of transformer

$$\begin{aligned} V_{y \text{ p.u.}} &= (I_{\text{Load p.u.}})(Z_F \text{ p.u.}) + V_{\text{Load p.u.}} \\ &= (0.1667 \angle -36.87^\circ)(0.5532 \angle 49.4^\circ) + 1 \angle 0^\circ = 1.09 \angle 1.05^\circ \text{ p.u.} \end{aligned}$$

Actual voltage $|V_y| = V_{y \text{ p.u.}} \times \text{Base voltage at } y = 1.09 \times 11 \text{ kV} \simeq \underline{\underline{12 \text{ kV}}}$

Finally, voltage at H.V. side of transformer

$$\begin{aligned} V_{x \text{ p.u.}} &= (Z_T \text{ p.u.})(I_{\text{Load p.u.}}) + V_{y \text{ p.u.}} \\ &= (0.0427 \angle 69.44^\circ)(0.1667 \angle -36.87^\circ) + 1.09 \angle 1.05^\circ = 1.0963 \angle 1.24^\circ \text{ p.u.} \end{aligned}$$

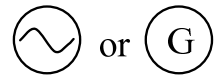
Actual voltage, $|V_x| = V_{x \text{ p.u.}} \times \text{Base voltage at } x$
 $= 1.0963 \times 33 = \underline{\underline{36.18 \text{ kV}}}$

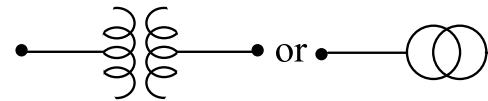
Single-line Diagram (SLD) & Impedance (Reactance) Diagram

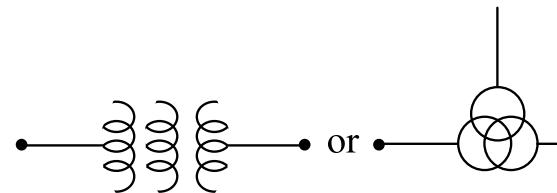
- You have already learnt the circuit models for transformers. Very soon, you will learn circuit models for synchronous machines & transmission lines & loads.
- Our present interest is in “how to portray the assemblage of these components to model a power system in its entirety”.
- Since a balanced 3- ϕ system is always solved as a single-phase equivalent circuit composed of one of the three lines & the neutral return, it is seldom necessary to show more than 1-phase & neutral return when drawing a diagram of the system.
- Often the diagram is simplified further by omitting the completed CKT thru the neutral, and by indicating the components by standard symbols rather than by equiv. CKTs.

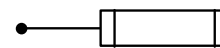
⇒ Such a simplified diagram is called one-line diagram or single-line diagram.

Standard Symbols Used in SLD

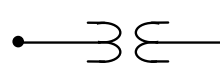
 Rotating machine/generator

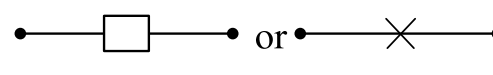
 2-winding power transformer

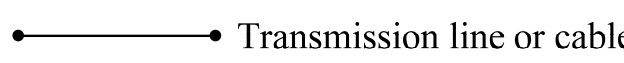
 3-winding power transformer

 Fuse

 Current transformer

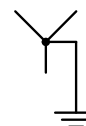
 Potential transformer

 Circuit breaker

 Transmission line or cable

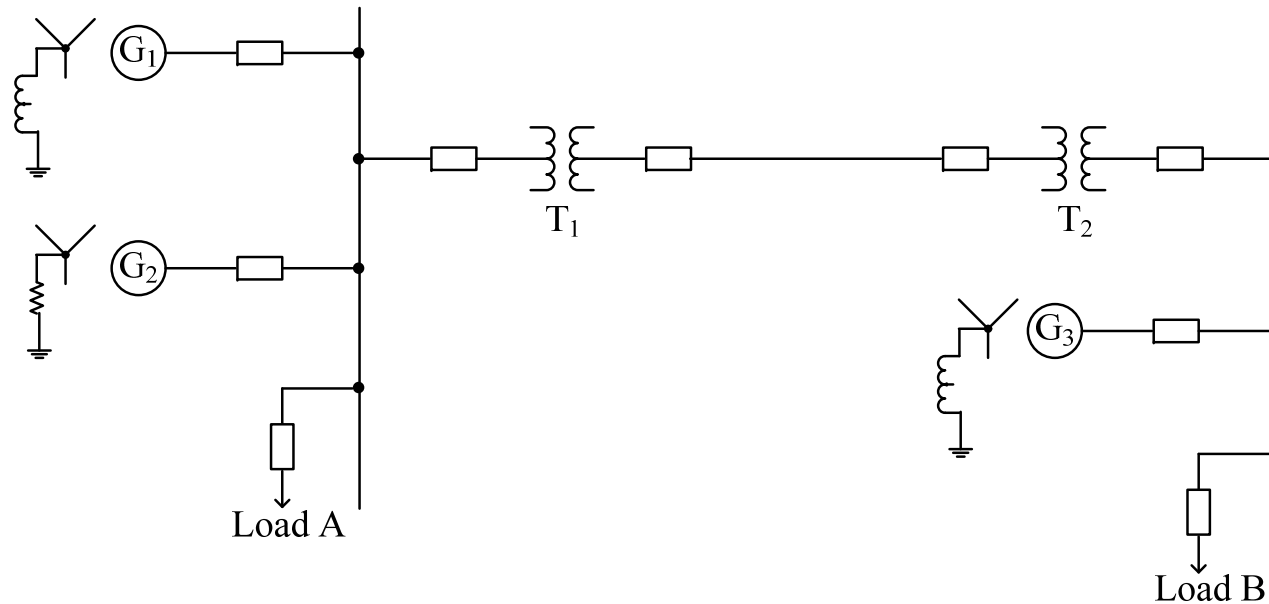
 3-φ, 3-wire Delta connection

 3-φ wye, Neutral ungrounded

 3-φ wye, Neutral grounded

- ⇒ Most transformer neutrals in transmission systems are solidly grounded.
- ⇒ Generator neutrals are usually grounded thru fairly high R or L to limit the flow of current to ground during a fault (abnormal condition).

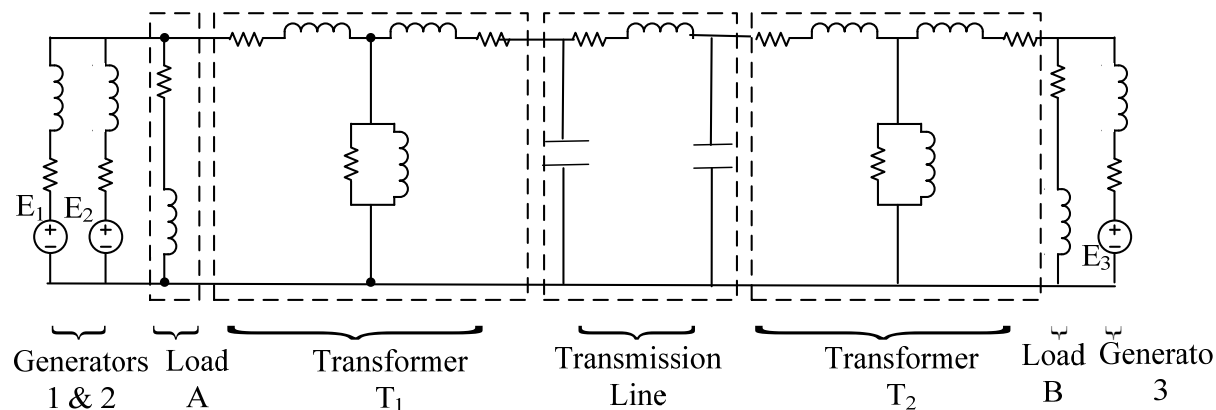
Example of SLD :



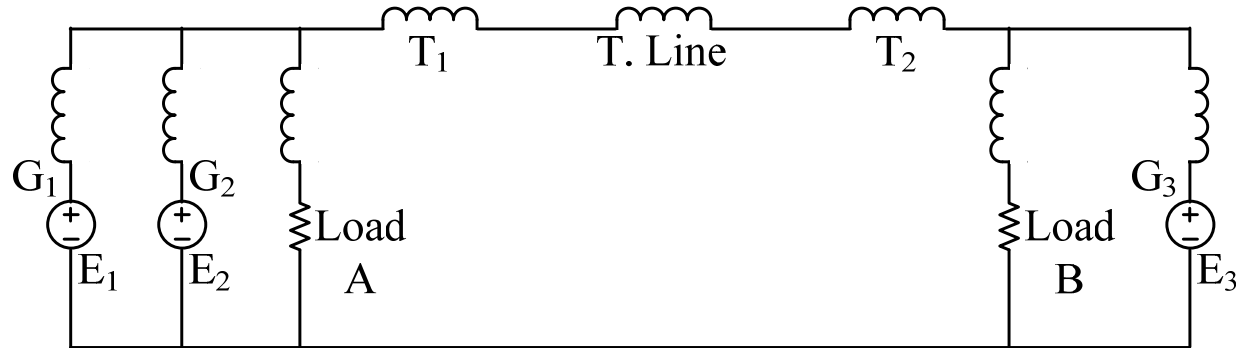
- ⇒ The amount of information presented on the SLD depends on the purpose for which the diagram is intended.
- ⇒ As stated earlier, p.u. system is used to solve for the unknowns.

Impedance & Reactance Diagrams

- When the individual components of a SLD are represented by their equivalent circuits, then the resultant drawing is called the per-phase impedance diagram.
- The impedance diagram of the system shown on the previous page is as follows :

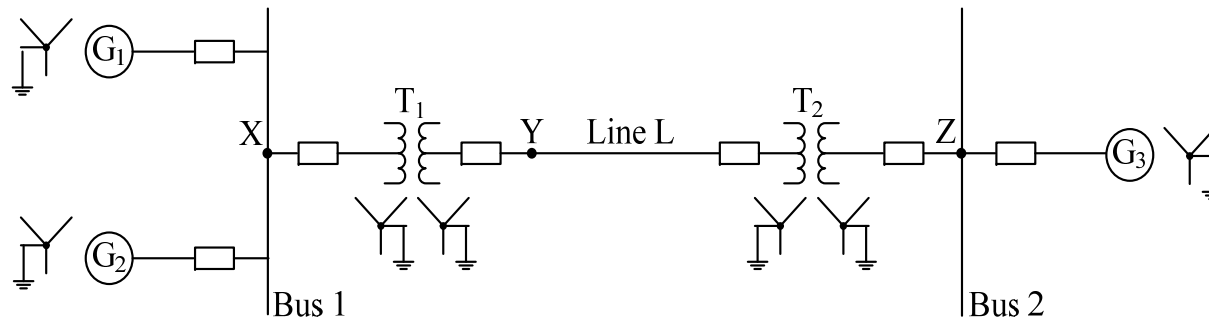


- Since the shunt current of a transformer is usually insignificant compared with the full-load current, the shunt admittance is usually omitted from the equiv. CKT of transformer.
 - Resistance is often omitted since $X \gg R$.
 - Transmission-line capacitances may also be omitted.
- ⇒ Resultant diagram is called reactance diagram.



Note : Consistent base kVs must be specified in different sections of the system to analyze using the p.u. system.

Example 4 : Consider the power system shown :



G_1 : 20 MVA, 6.6 kV, $X = 0.655 \Omega$

G_2 : 10 MVA, 6.6 kV, $X = 1.31 \Omega$

G_3 : 30 MVA, 3.81 kV, $X = 0.1452 \Omega$

T_1 : 10 MVA, 6.7/38 kV, $X = 14.52 \Omega$ per phase (on 38 kV side)

T_2 : 12 MVA, 38/3.8 kV, $X = 14.52 \Omega$ per phase (on 38 kV side)

$X_L = 17.4 \Omega$ per phase

Using a 30 MVA base & a 6.6 kV base in G_1 circuit, obtain the p.u. impedance diagram.

Solution : Base MVA = 30 for all sections.

Base kV in G_1 & G_2 CKT = 6.6 kV = V_{bX}

$$Z_{bX} = Z_{BaseX} = \frac{(V_{bX})^2}{S_b} = \frac{6.6^2}{30} = 1.452 \Omega$$

$$\therefore X_{G_1 \text{ p.u.}} = \frac{X_{G_1}(\Omega)}{Z_{bX}} = \frac{0.655}{1.452} = 0.451 \text{ p.u.}$$

$$X_{G_2 \text{ p.u.}} = \frac{X_{G_2}(\Omega)}{Z_{bX}} = \frac{1.31}{1.452} = 0.9022 \text{ p.u.}$$

Base kV in T_1 Secondary (38 kV side) + Line

$$= V_{bY} = V_{bX} \times \frac{38}{6.7} = 6.6 \times \frac{38}{6.7} = 37.4328 \text{ kV}$$

$$\therefore Z_{bY} = \frac{(V_{bY})^2}{S_b} = \frac{(37.4328)^2}{30} = 46.707 \Omega$$

$$\therefore X_{T_1 \text{ p.u.}} = \frac{X_{T_1Y}(\Omega)}{Z_{bY}} = \frac{14.52}{46.707} = 0.3109 \text{ p.u.}$$

$$X_{L \text{ p.u.}} = \frac{X_L (\Omega)}{Z_{b Y}} = \frac{17.4}{46.707} = 0.3725 \text{ p.u.}$$

$$\text{Now, } X_{T_2 \text{ p.u.}} = \frac{X_{T_2 Y} (\Omega)}{Z_{b Y}} = \frac{14.52}{46.707} = 0.3109 \text{ p.u.}$$

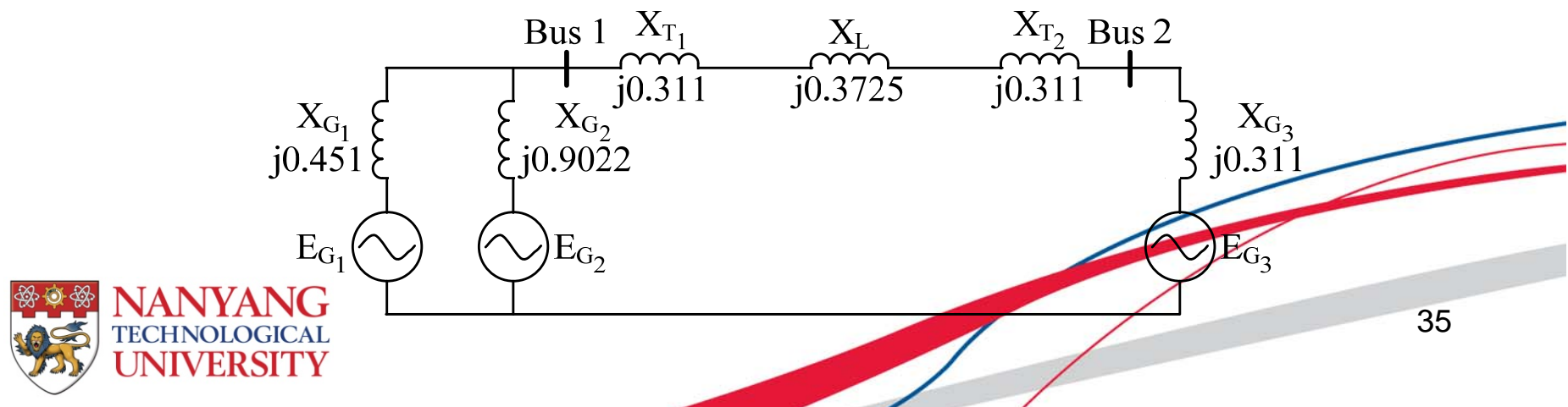
Base kV on Secondary (3.8 kV) side of T_2

$$= V_{b Z} = V_{b Y} \times \frac{3.8}{38} = 37.4328 \times \frac{3.8}{38} = 3.7433 \text{ kV}$$

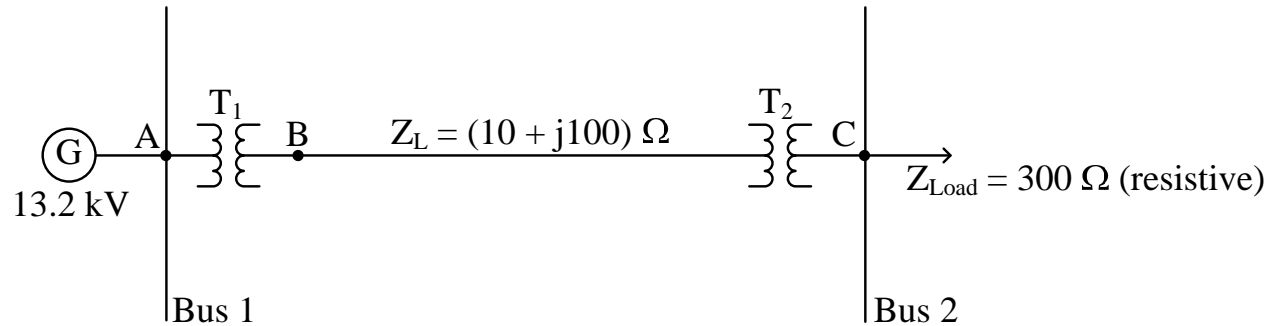
$$\Rightarrow Z_{b Z} = \frac{(V_{b Z})^2}{S_b} = \frac{3.7433^2}{30} = 0.4671 \Omega$$

$$\therefore X_{G_3 \text{ p.u.}} = \frac{X_{G_3} (\Omega)}{Z_{b Z}} = \frac{0.1452}{0.4671} = 0.3109 \text{ p.u.}$$

P.U. Impedance (Reactance) Diagram



Example 5 : (Last example on p.u./reactance diagram)



T_1 : 5 MVA, 13.2 Δ /132 Y kV, $X = 10\%$

T_2 : 10 MVA, 138 Y/69 Δ kV, $X = 8\%$

Assume that generator terminal voltage magnitude is 13.2 kV (L-L). (Ignore the generator reactance).

Find actual values of : Generator current, line current, load current, load voltage & MVA.

Solution : Assume $S_b = \text{Base MVA} = 10 \text{ MVA}$ & $V_{bA} = 13.2 \text{ kV}$

$$\therefore X_{T_1 \text{ p.u. NEW}} = X_{T_1 \text{ p.u. OLD}} \times \left[\frac{V_{b \text{ OLD } T_1}}{V_{bA}} \right]^2 \times \left[\frac{S_{b \text{ NEW}}}{S_{b T_1}} \right] = 0.10 \times \left[\frac{13.2}{13.2} \right]^2 \times \left[\frac{10}{5} \right] = 0.20 \text{ p.u.}$$

↑

(Calculated on the primary side)

$$\underline{\text{Base kV in Section B}} = V_{b\ B} = V_{b\ A} \times \frac{132}{13.2} = 132 \text{ kV}$$

$$\therefore Z_{b\ B} = \frac{132^2}{10} = 1742.4 \ \Omega$$

$$\therefore Z_{L\ \text{p.u.}} = \frac{Z_L (\Omega)}{Z_{b\ B}} = \frac{10 + j100}{1742.4} = 0.00574 + j0.0574 = 0.0577 \angle 84.29^\circ \text{ p.u.}$$

Now,

$$X_{T_2\ \text{p.u. NEW}} = X_{T_2\ \text{p.u. OLD}} \times \left[\frac{V_{b\ \text{OLD } T_2}}{V_{b\ B}} \right]^2 \times \left[\frac{S_{b\ \text{NEW}}}{S_{b\ T_2}} \right]$$

↑

(Calculated on primary side)

$$= 0.08 \times \left[\frac{138}{132} \right]^2 \times \left[\frac{10}{10} \right] = 0.087438 \text{ p.u.}$$

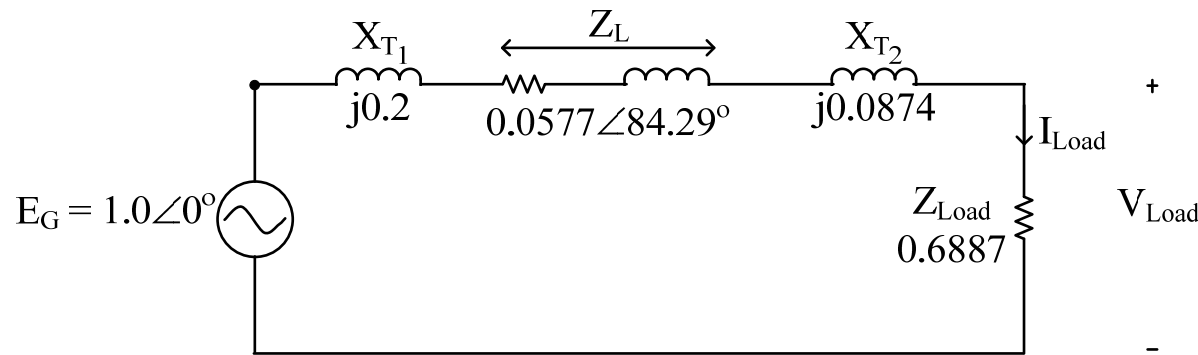
Next, base kV in section C

$$= V_{b\ C} = V_{b\ B} \times \frac{69}{138} = 132 \times \frac{69}{138} = 66 \text{ kV}$$

$$\therefore Z_{b\ C} = \frac{(V_{b\ C})^2}{S_b} = \frac{66^2}{10} = 435.6\ \Omega$$

$$\therefore Z_{\text{Load p.u.}} = \frac{Z_{\text{load}}(\Omega)}{Z_{b\ C}} = \frac{300}{435.6} = 0.6887\ \text{p.u.}$$

4. IMPEDANCE DIAGRAM (P.U.)



$$I_{\text{Load p.u.}} = \frac{1\angle 0^\circ}{j0.2 + (0.00574 + j0.0574) + j0.0874 + 0.6887}$$

$$= \frac{1\angle 0^\circ}{0.694445 + j0.3448} = \frac{1\angle 0^\circ}{0.7753\angle 26.404^\circ} = 1.2898\angle -26.4^\circ\ \text{p.u.}$$

Note : $I_{\text{Load p.u.}}$ represents different actual currents in sections A, B & C.

Now,

$$V_{\text{Load p.u.}} = I_{\text{Load p.u.}} \times 0.6887 \angle 0^\circ = 0.88826 \angle -26.4^\circ \text{ p.u.}$$

$$S_{\text{Load p.u.}} = (V_{\text{Load p.u.}})(I_{\text{Load p.u.}})^* = 1.1457 \angle 0^\circ$$

$$\Rightarrow \text{Load power (actual)} = S_{\text{Load p.u.}} \times S_b = 11.458 \text{ MVA} \Leftarrow$$

$$|V_{\text{Load}}|_{\text{Actual}} = |V_{\text{Load p.u.}}| \times \text{base kV in section C} = 0.88826 \times 66 = \underline{58.625 \text{ kV}} \Leftarrow$$

Last step : Find base currents in all sections.

$$I_{bA} = \frac{S_b}{\sqrt{3} V_{bA}} = \frac{10 \times 10^3}{\sqrt{3} \times 13.2} = 437.386 \text{ Amps}$$

$$\Rightarrow I_{\text{Gen}} = I_{bA} \times I_{\text{Load p.u.}} = 437.386 \times 1.2898 = \underline{564.14 \text{ Amps}}$$

$$I_{bB} = \frac{S_b}{\sqrt{3} V_{bB}} = \frac{10 \times 10^3}{\sqrt{3} \times 132} = 43.7387 \text{ Amps}$$

$$\Rightarrow I_{\text{Line}} = I_{\text{b B}} \times I_{\text{Load p.u.}}$$

$$= 43.7387 \times 1.2898 = \underline{56.414 \text{ Amps}}$$

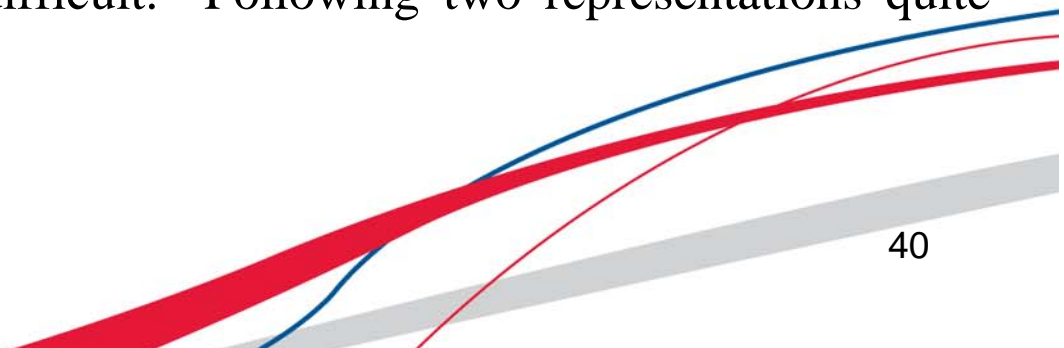
$$I_{\text{b C}} = \frac{S_{\text{b}}}{\sqrt{3} V_{\text{b C}}} = \frac{10 \times 10^3}{\sqrt{3} \times 66} = 87.4773 \text{ Amps}$$

$$\Rightarrow I_{\text{Load}} = I_{\text{b C}} \times I_{\text{Load p.u.}}$$

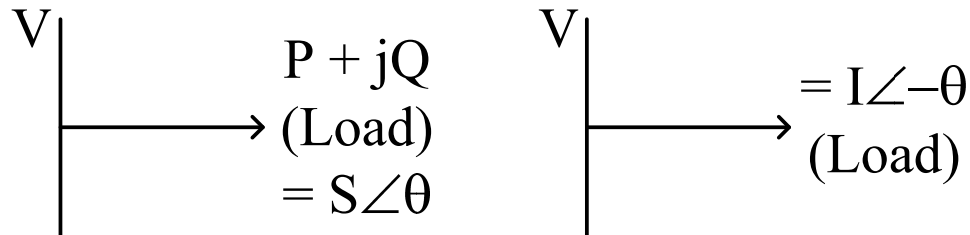
$$= 87.4773 \times 1.2898 = \underline{112.828 \text{ Amps}}$$

Load Representations

- Actual P & Q demands of load depend on system frequency & voltage.
- Residential loads behave differently than (say) commercial or industrial loads. They are less affected by frequency and are usually resistive – kW demand sensitive to voltage of supply.
- Industrial loads e.g. induction motor loads draw reactive power which is sensitive to voltage level (real power demand, kW, does not vary significantly).
- Accurate estimate of load very difficult. Following two representations quite reasonable/satisfactory :



1) Constant Power Model (e.g. Air-conditioning loads)

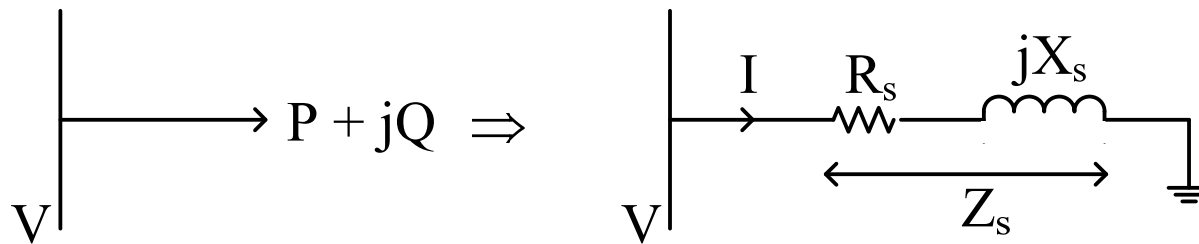


$$S = VI^* \Rightarrow I^* = \frac{S \angle \theta}{V \angle 0^\circ} \Rightarrow I = \frac{S}{V} \angle -\theta = \frac{\sqrt{P^2 + Q^2}}{V} \angle -\theta$$

where θ is load power factor angle (assumed lagging)

\Rightarrow Here load power (S) remains constant, although load voltage (V) & current (I) will change; e.g. air-conditioning loads.

2) Constant-impedance Model (e.g. Water heaters & light bulbs)



$$Z_s = \frac{V}{I} = \frac{V}{\left(\frac{S}{V} \angle -\theta\right)} = \left|\frac{V^2}{S}\right| \angle \theta$$

$$P = I^2 R_s \Rightarrow R_s = \frac{P}{I^2} = \frac{P}{\left(\frac{P^2 + Q^2}{V^2} \right)}$$

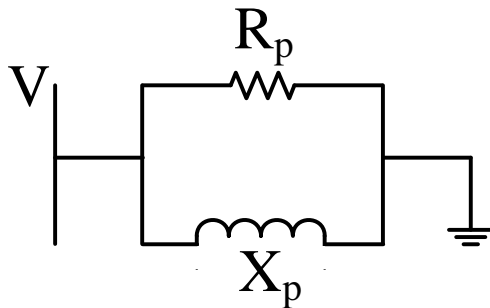
$$\Rightarrow R_s = \frac{P V^2}{P^2 + Q^2} \Omega$$

$$Q = I^2 X_s \Rightarrow X_s = \frac{Q}{I^2} = \frac{Q}{\left(\frac{P^2 + Q^2}{V^2} \right)} = \frac{Q V^2}{P^2 + Q^2} \Omega$$

In p.u. system : $Z_{S \text{ p.u.}} = R_{S \text{ p.u.}} + jX_{S \text{ p.u.}}$

\Rightarrow For a constant-impedance load, the load impedance is kept constant but the current & power drawn at various voltages will be different.

Note : Constant-impedance load may also be represented by R & X in parallel.



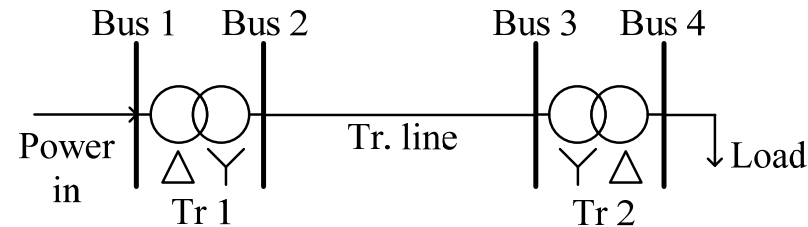
$$\Rightarrow Z_p = \frac{(R_p)(jX_p)}{R_p + jX_p} \Omega$$

$$\text{where } R_p = \frac{V^2}{P} \Omega$$

$$\& X_p = \frac{V^2}{Q} \Omega$$

REVIEW EXERCISES (5)

- (5) Draw the impedance diagram for the 3-phase system shown in the following figure indicating the pu values of impedances.



$$\text{Tr line : } Z = 12.8 + j64 \, \Omega$$

Tr 1 : 1 × 3-phase 120 MVA Transformer, Δ/Y , 34.5 kV/345 kV, $Z = (1 + j8)\%$

Tr 2 : 3 × 1-phase 30 MVA Transformer, 200 kV/20 kV, $Z = (1 + j7)\%$

Take the base values at bus 2 as 100 MVA and 345 kV.

(Hint : List the base values for all buses and then convert parameters to the common base)

$$\underline{\text{Tr 1 : } (0.0083 + j0.0667) \text{ pu, Tr. line : } (0.0108 + j0.0538) \text{ pu, Tr 2 : } (0.0112 + j0.0784) \text{ pu}}$$

- (6) The system in problem (5) delivers a load of 60 MW at bus 4 at the rated voltage of 20 kV. Indicate the load terminal conditions in pu and calculate : (a) the voltage at bus 1, (b) phase angle of voltage at bus 1, for the following cases :
- (i) 0.8 (lag), and (ii) 0.8 (lead)

$$\begin{aligned} \text{(i)} \quad & \underline{V_L = 1.004 \angle 0^\circ \text{ pu, } I_L = 0.7469 \angle -36.87^\circ \text{ pu, 38.51 kV, } 5.41^\circ} \\ \text{(ii)} \quad & \underline{V_L = 1.004 \angle 0^\circ \text{ pu, } I_L = 0.7469 \angle 36.87^\circ \text{ pu, 32.51 kV, } 8.08^\circ} \end{aligned}$$

REVIEW EXERCISES (7 & 8)

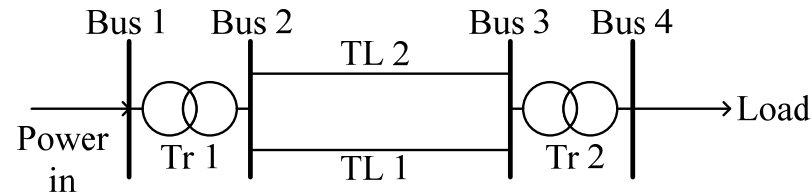
- (7)(a) Draw the impedance diagram for the system shown in the figure indicating the p.u. values of impedance, for the following system data.

Tr. Lines : TL1 and TL2 : $R = 16 \Omega$, $X = 120 \Omega$.

Load : $(12 + j9)$ MVA at 13.2 kV.

Tr 1 : 20 MVA, 11/120 kV, $Z = (2 + j10)\%$

Tr 2 : 20 MVA, 120/13.8 kV, $Z = (1 + j8)\%$



Represent the load by a constant series impedance and take the base values for the transmission line as 60 MVA, and 120 kV.

- (b) If the voltage at Bus 1 is maintained at rated value (11 kV), calculate the load terminal voltage.

(a) TL1 & TL2 : $0.067 + j0.50$ p.u.; Load impedance : $2.928 + j2.196$ p.u.;

Tr 1 : $0.06 + j0.3$ p.u.; Tr 2 : $0.03 + j0.24$ p.u.

(b) $V_L = 11.83$ kV

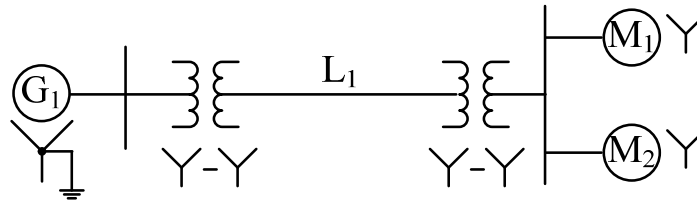
Note : Load voltage for (b) will NOT be 13.2 kV as in (a). The load is fixed but the load voltage can vary!

- (8) Consider the power system shown below.

- Draw the per unit reactance diagram using a 30 MVA, 13.8 kV base in the generator circuit.
- If motor loads M_1 and M_2 draw 16 MW and 8 MW respectively at unity power factors and 12.5 kV, find the internally generated generator voltage (i.e., voltage before the generator reactance itself).

(i) $X_{G1} = j0.15$; $X_{T1} = j0.078$; $X_{Line} = j0.166$; $X_{T2} = j0.0915$; $X_{M1} = j0.2744$; $X_{M2} = j0.549$

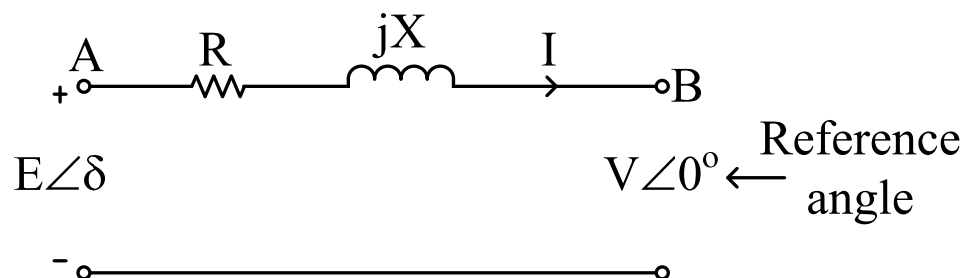
(ii) 1.0391 p.u. (14.339 kV)



- G_1 : 30 MVA, 13.8 kV, 3- ϕ generator, $X_{G1} = 15\%$
 M_1 : 20 MVA, 12.5 kV, 3- ϕ motor load, $X_{M1} = 20\%$ (synchronous motor)
 M_2 : 10 MVA, 12.5 kV, 3- ϕ motor load, $X_{M2} = 20\%$ (synchronous motor)
 T_1 : 35 MVA, 13.2/115 kV, Transformer, $X_{T1} = 10\%$
 T_2 : 30 MVA, 12.5/115 kV, Transformer, $X_{T2} = 10\%$
 L_1 : Line $X_L = 80 \Omega$

Basic Equations for Real/Reactive Powers (Please see Appendix A for details)

- Consider transfer of power from point “A” in a power system to point “B”, thru an impedance $Z = R + jX = |Z| \angle \alpha$



- Voltage at “A” = $E \angle \delta$
- Voltage at “B” = $V \angle 0^\circ$

$$I = \frac{E \angle \delta - V \angle 0}{R + jX} = \frac{E}{Z} \angle (\delta - \alpha) - \frac{V}{Z} \angle -\alpha$$

- Complex power delivered at “B”

$$S = VI^* \text{ (in per unit)}$$

$$= (V \angle 0^\circ) \left[\frac{E}{Z} \angle (\alpha - \delta) - \frac{V}{Z} \angle \alpha \right] = \frac{VE}{Z} \angle (\alpha - \delta) - \frac{V^2}{Z} \angle \alpha$$

$$\Rightarrow \text{Real power } P = \frac{VE}{Z} \cos(\alpha - \delta) - \frac{V^2}{Z} \cos \alpha$$

$$\text{Reactive power } Q = \frac{VE}{Z} \sin(\alpha - \delta) - \frac{V^2}{Z} \sin \alpha$$

Special case : $R \simeq 0 \Rightarrow Z = 0 + jX = X \angle 90^\circ$

$$\therefore S = \frac{VE}{X} \angle (90^\circ - \delta) - \frac{V^2}{X} \angle 90^\circ$$

$$\Rightarrow P = \frac{VE}{X} \sin \delta \text{ \& } Q = \frac{VE}{X} \cos \delta - \frac{V^2}{X}$$

- Point “A” is usually
 - (1) Internally-generated voltage E for a synchronous generator or
 - (2) Sending-end voltage for a transmission line
- Point “B” is usually
 - (1) Load voltage V for a generator connected to a load or
 - (2) Receiving-end voltage for a transmission line

- Impedance $Z = R + jX$ (or $Z \simeq jX$) is usually
 - (1) Synchronous impedance of a synchronous generator or
 - (2) Series impedance of a trans. line
- Note [for $R \simeq 0$]
 - \Rightarrow P flows from “A” to “B” for angle δ taking positive values; else “B” to “A”; if $\delta = 0$, $P = 0$ (no real power).
P depends largely on relative angle difference of voltages at “A” & “B”.
 - \Rightarrow For small δ : Q flows from “A” to “B” if $|E| > |V|$; else “B” to “A”; if $|E| \simeq |V|$, then $Q \simeq 0$ (no reactive power).
Q depends largely on voltage magnitudes at “A” or “B”.

