

Constraint Satisfaction Problems

CZ3005: Artificial Intelligence

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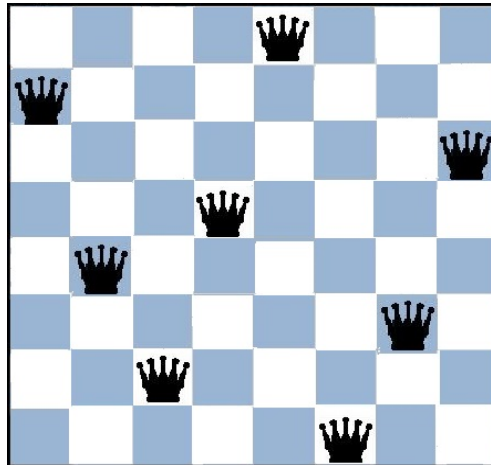
Outline

- ❑ What is the Constraint Satisfaction Problem?
- ❑ Backtracking search
- ❑ Forward checking and constraint propagation
- ❑ Most-constraining variable and least-constraining value heuristics
- ❑ Search using min-conflict heuristics

Constraint Satisfaction Problem (CSP)

Goal: discover some state that satisfies a given set of constraints

Example: 8-Queens Problem



Example: Cryptarithmic Puzzle

$$\begin{array}{r} \text{S E N D} \\ + \text{M O R E} \\ \hline \text{M O N E Y} \end{array}$$

Constraint Satisfaction Problem (CSP) cont.

Example: Sudoku

							1	3
			7					6
			5		9			
						9		
1		6						
						2		
7	4						5	
	8					4		
				1				

Example: Minesweeper



Examples: Real-world CSPs

- ❑ Assignment problems
 - ❑ e.g., who teaches what class
- ❑ Timetabling problems
 - ❑ e.g., which class is offered when and where?
- ❑ Hardware configuration
- ❑ Transportation scheduling
- ❑ Factory scheduling
- ❑ Floor-planning

CSP

State

- defined by **variables** V_i with **values** from domain D_i

Example: 8-queens

- Variables: locations of each of the eight queens
- Values: squares on the board

Goal test

- a set of **constraints** specifying allowable combinations of values for subsets of variables

Example: 8-queens

- Goal test: No two queens in the same row, column or diagonal

Example: Cryptarithmic Puzzle

$$\begin{array}{r} \text{S} \quad \text{E} \quad \text{N} \quad \text{D} \\ + \text{M} \quad \text{O} \quad \text{R} \quad \text{E} \\ \hline \text{M} \quad \text{O} \quad \text{N} \quad \text{E} \quad \text{Y} \end{array}$$

- Variables: D, E, M, N, O, R, S, Y
- Domains: {0, 1, 2, 3, 4, 5, 6, 7, 8, 9}
- Constraints
 - $Y = D + E$ or $Y = D + E - 10$, etc
 - $D \neq E$, $D \neq M$, $D \neq N$, etc.
 - $M \neq 0$, $S \neq 0$ (unary constraints: concern the value of a single variable)

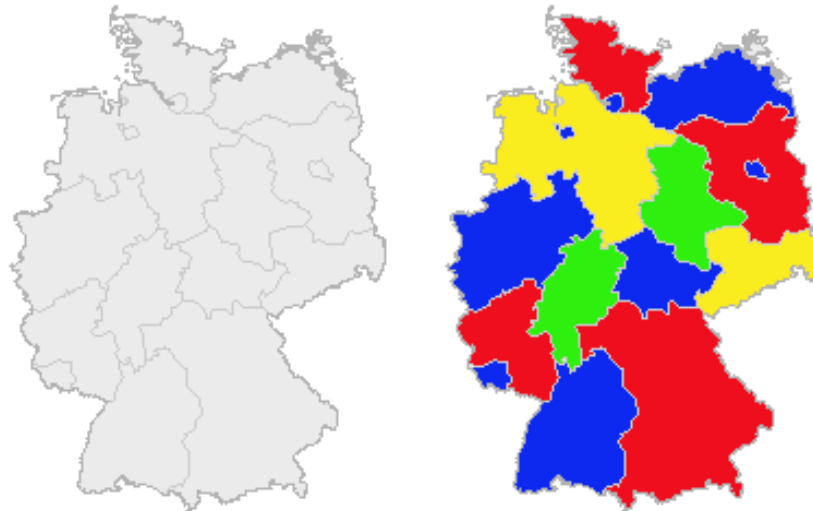
Example: Minesweeper

A	B	C
J	2	D
I	3	E
H	G	F

- ❑ Variables: The cells
- ❑ Domains: $\{0; 1\}$ representing {safe, mined}
- ❑ Constraints: Each cell has a number $m \in \{1, \dots, 8\}$ indicating the number of mines nearby, so m is equal to sum of value of neighbour cells

Example: Map Coloring

Color a map so that no adjacent parts have the same color



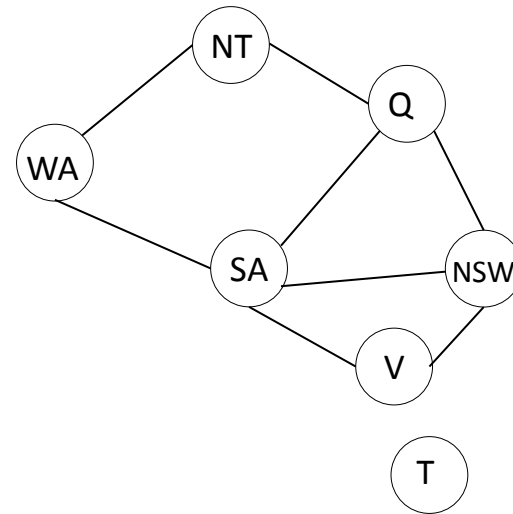
- ❑ Variables: Countries C_i
- ❑ Domains: $\{Red, Blue, Green\}$
- ❑ Constraints: $C1 \neq C2$, $C1 \neq C5$, etc
 - ❑ **binary** constraints

Some Definitions

- ❑ A state of the problem is defined by an **assignment** of values to some or all of the variables
- ❑ An assignment that does not violate any constraints is called a **consistent** or **legal** assignment
- ❑ A **solution** to a CSP is an assignment with every variable given a value (**complete**) and the assignment satisfies all the constraints

Visualize a CSP as a Constraint Graph

Example: Australia map coloring



Nodes: Variables; Arcs/Edges: Constraints.

Applying Standard Search

- **States**: defined by the values assigned so far
- **Initial state**: all variables unassigned
- **Actions**: assign a value to an unassigned variable
- **Goal test**: all variables assigned, no constraints violated

Question: How to represent constraints?

Answer: Explicitly (e.g., $D \neq E$)

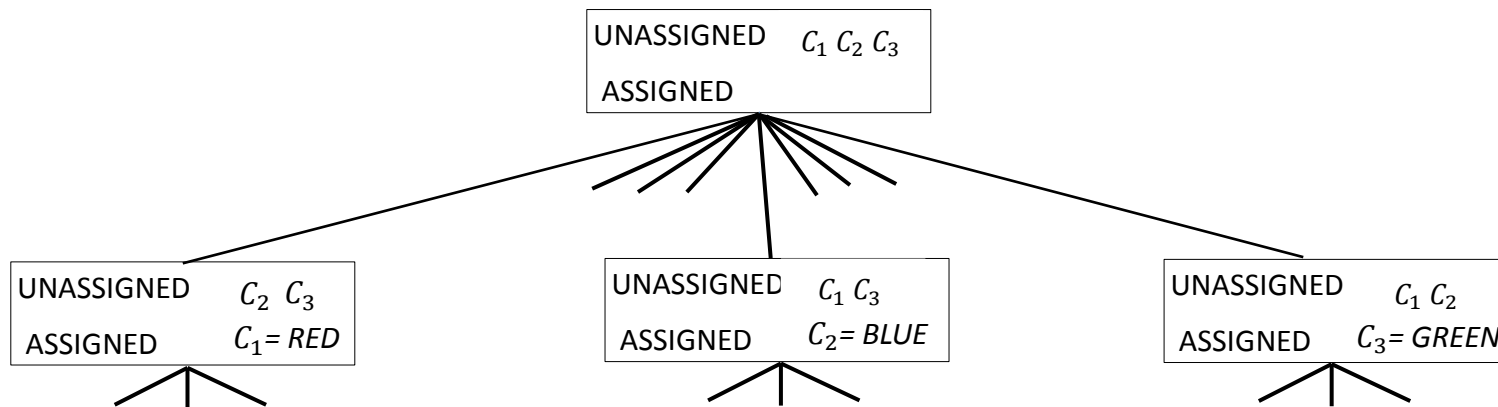
Example

- Row the 1st queen occupies: $V_1 \in \{1, 2, 3, 4, 5, 6, 7, 8\}$
(similarly, for V_2)
- No-attack constraint for V_1 and V_2 :
 $\{ \langle 1, 3 \rangle, \langle 1, 4 \rangle, \langle 1, 5 \rangle, \dots, \langle 2, 4 \rangle, \langle 2, 5 \rangle, \dots \}$

Implicitly: use a function to test for constraint satisfaction

Applying Standard Search...

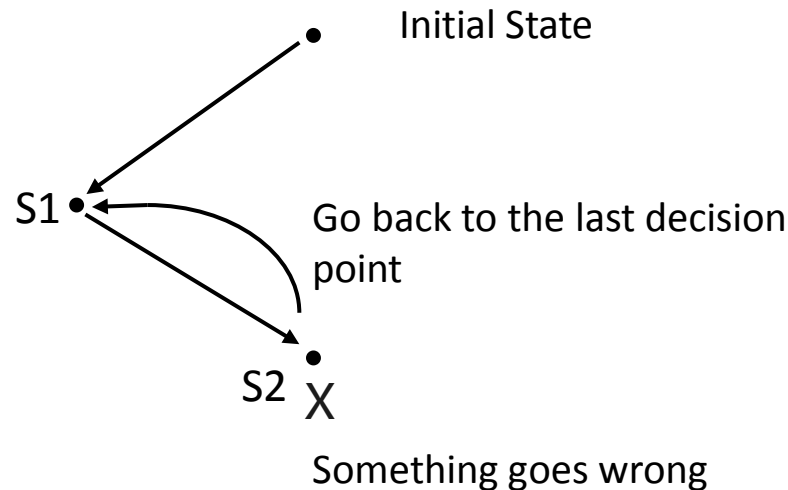
Example: map coloring



- ❑ Number of variables: n
- ❑ Max. depth of space: n
- ❑ Depth of solution state: n (all variables assigned)
- ❑ Search algorithm: depth-first search

Backtracking Search

Backtracking search: Do not waste time searching when constraints have already been violated



- ❑ Before generating successors, check for constraint violations
- ❑ If yes, backtrack to try something else

The diagram shows a search tree for a 4x4 grid game. The root node is a 4x4 grid. It branches into two nodes, which then branch into four nodes each. The tree continues to branch down to a leaf node, which is marked with a green checkmark, indicating it is the optimal path. Red 'X' marks are placed on several nodes, indicating they are not optimal.

Heuristics for CSPs

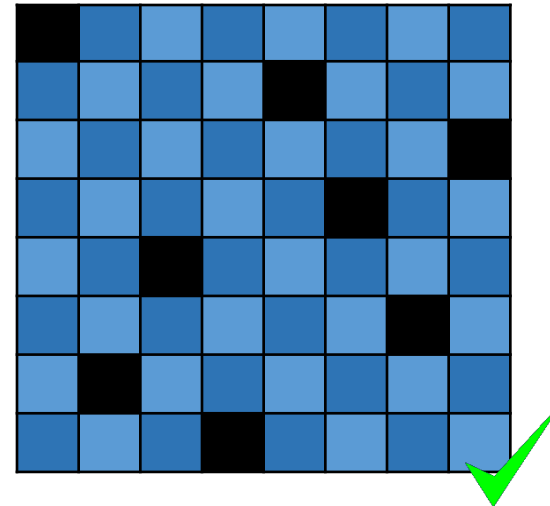
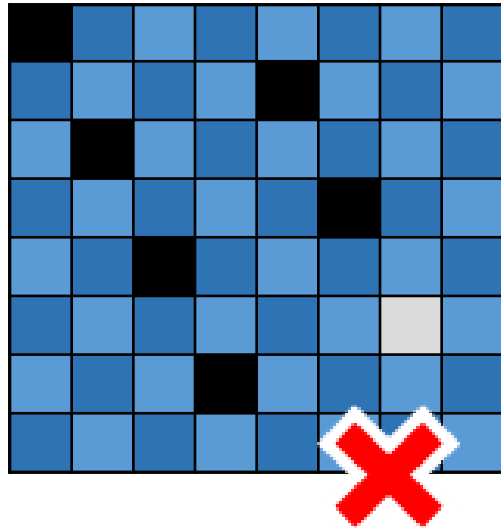
Plain backtracking is an uninformed algorithm!!

More intelligent search that takes into consideration

- ❑ Which variable to assign next
- ❑ What order of the values to try for each variable
- ❑ Implications of current variable assignments for the other unassigned variables
 - ❑ forward checking and **constraint propagation**

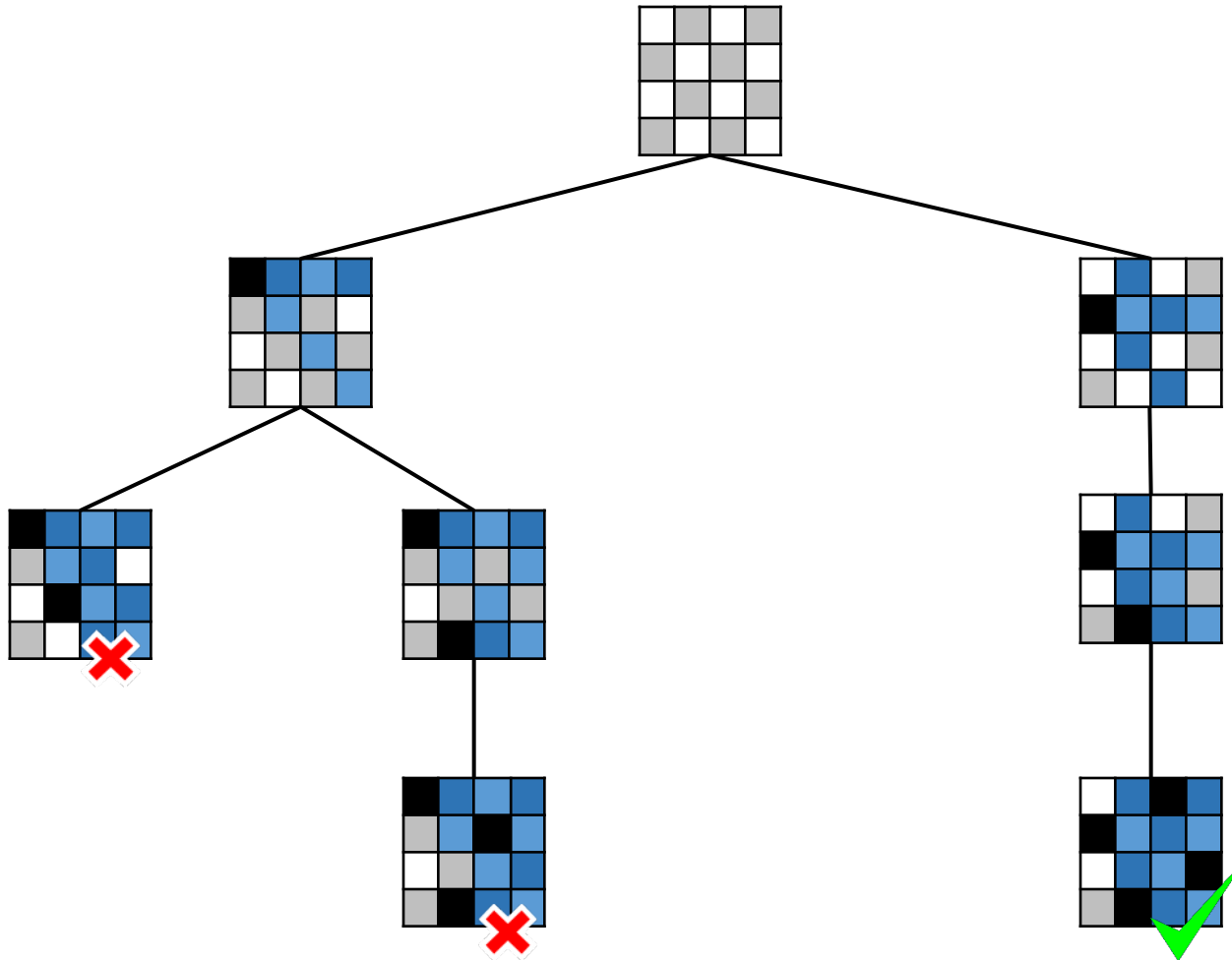
Constraint propagation: propagating the implications of a constraint on one variable onto other variables

Constraint Propagation for 8-Queens

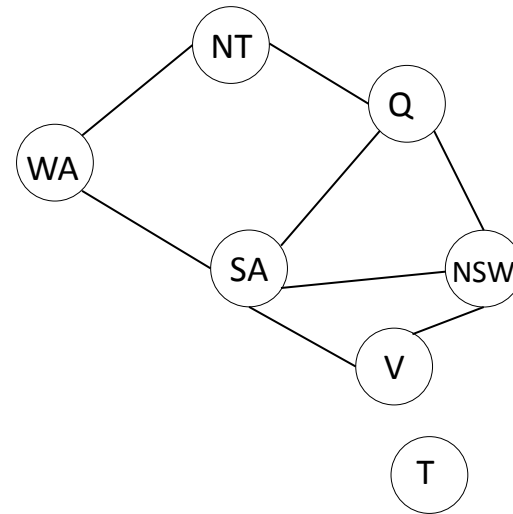


Solution for 8-Queens

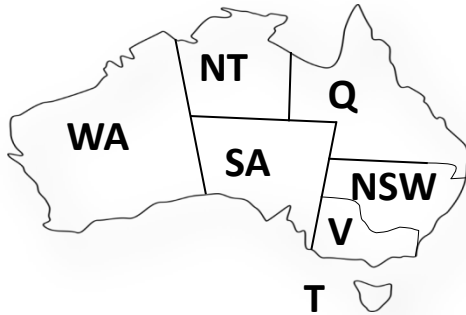
Search Tree of 4-Queens with Constraint Propagation



Example (Map Coloring)



Example (Map Coloring)...



WA

NT

Q

NSW

V

SA

T



WA

NT

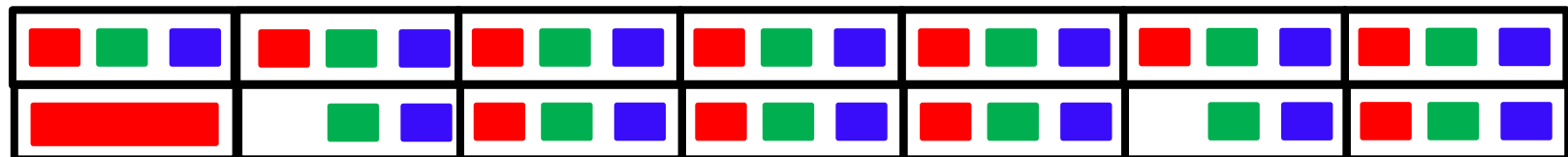
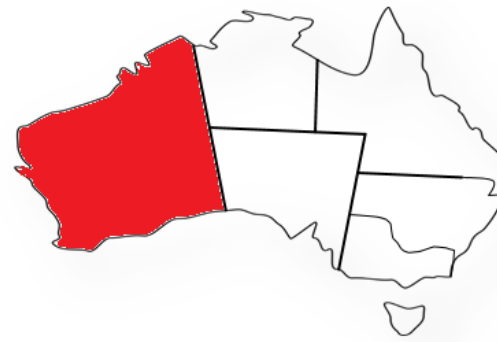
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Example (Map Coloring)...



WA

NT

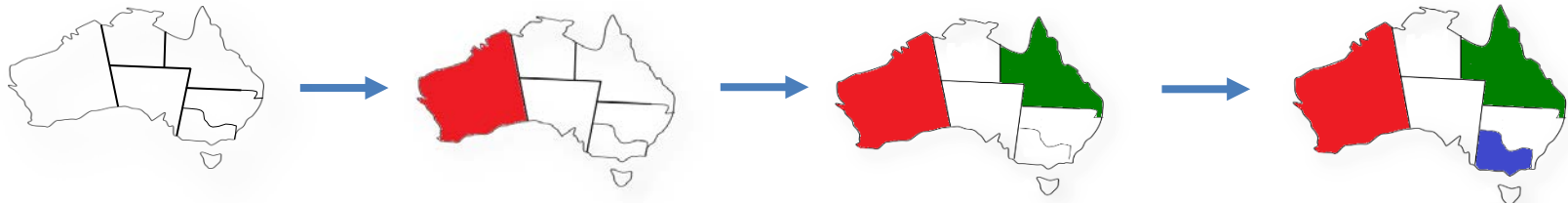
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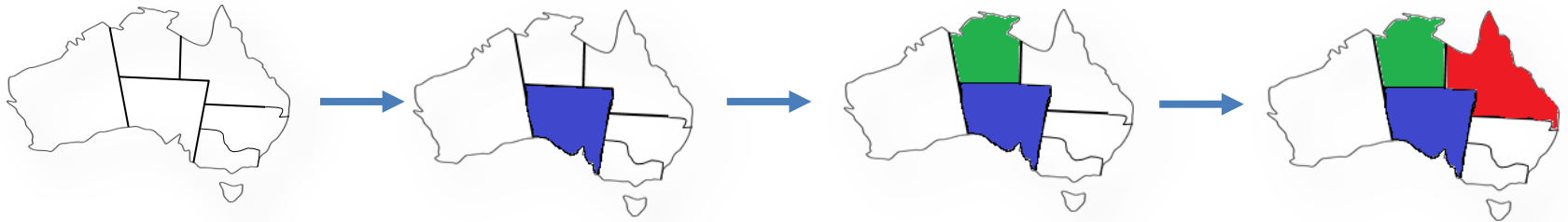
V

SA

T

Most Constrained Variable (or minimum remaining values (MRV) heuristic

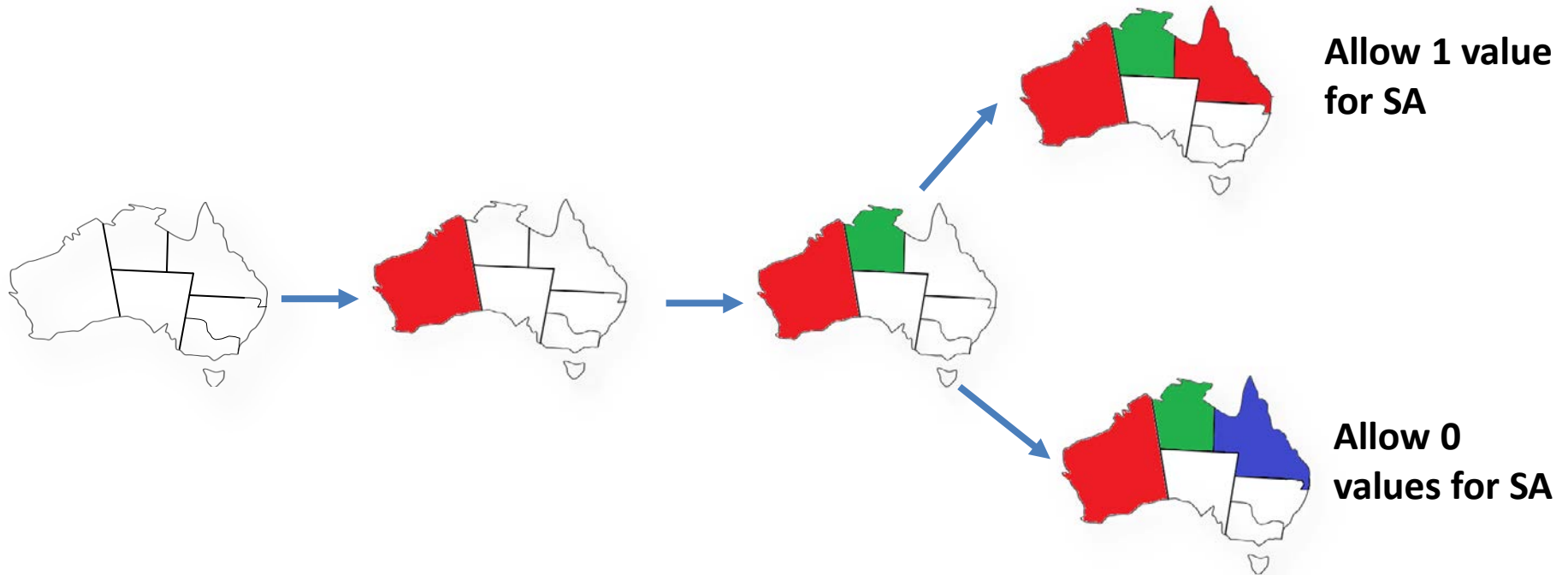
Example: map coloring



To reduce the branching factor on future choices by selecting the variable that is involved in the **largest number of constraints** on unassigned variables.

Not covered in any exam

Least Constraining Value

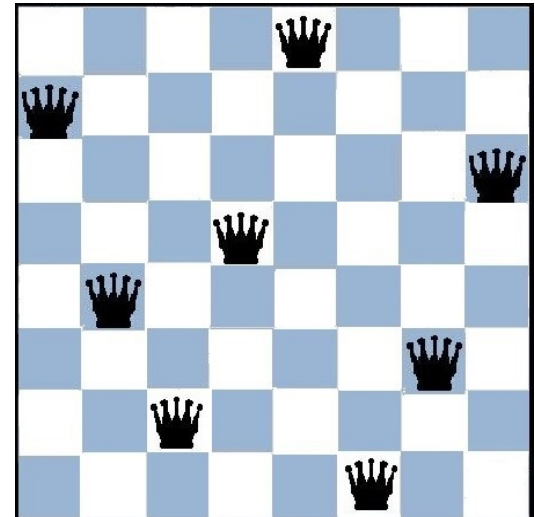
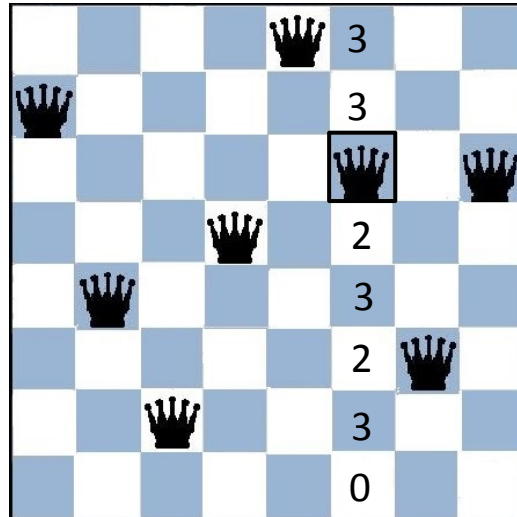
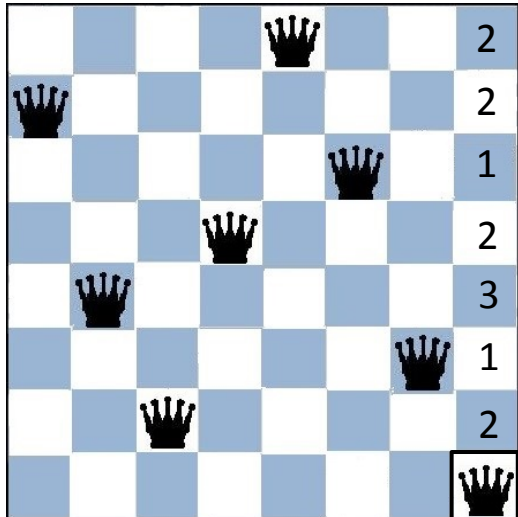


Choose the value that leaves maximum flexibility for subsequent variable assignments

Not covered in any exam

Min-Conflicts Heuristic (8-queens)

- A local heuristic search method for solving CSPs
- Given an initial assignment, selects a variable in the scope of a violated constraint and assigns it to the value that minimizes the number of violated constraints



Not covered in any exam