

Linearity (선형성) : $f(x)$ — Ex —

- ① Super position (중첩) : $f(x_1 + x_2) = f(x_1) + f(x_2)$
- ② Homogeneity (동질성) : $f(ax) = a f(x)$ (Constant)

$f(a_1x_1 + a_2x_2)$
 $= a_1 f(x_1) + a_2 f(x_2)$

ex) $y = mx = f(x)$: 선형성 O

$$m(a_1x_1 + a_2x_2) = a_1mx_1 + a_2mx_2 = a_1f(x_1) + a_2f(x_2)$$

$y = mx + n$ ($n \neq 0$) : 선형성 X

$$m(a_1x_1 + a_2x_2) + n \neq a_1(mx_1 + n) + a_2(mx_2 + n)$$

operation (덧셈, 곱셈...) about $x_1(t), x_2(t)$..

$$\frac{d}{dt}(a_1x_1(t) + a_2x_2(t)) = a_1 \frac{d}{dt}x_1(t) + a_2 \frac{d}{dt}x_2(t)$$

$$\int \dots dt = a_1 \int x_1(t) dt + a_2 \int x_2(t) dt$$

Matrix $A \times (x_1, x_2)$

$$\begin{bmatrix} A \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} y \end{bmatrix}$$

$$: A(a_1x_1 + a_2x_2) = a_1Ax_1 + a_2Ax_2$$

Basic Notation of Matrix

Vector $V = (a, b, c)^T \rightarrow$ row vector

\downarrow
 $V = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \rightarrow$ Column vector.

Transpose (전치) : row \leftrightarrow Column

ex) $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^T \rightarrow \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$

Linear Combination (선형 결합)

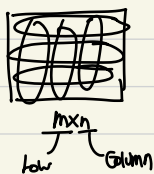
$$: V = \begin{bmatrix} a_1 \\ b_1 \\ c_1 \end{bmatrix}, W = \begin{bmatrix} a_2 \\ b_2 \\ c_2 \end{bmatrix} \Rightarrow \underline{\alpha V + \beta W} = \alpha \begin{bmatrix} a_1 \\ b_1 \\ c_1 \end{bmatrix} + \beta \begin{bmatrix} a_2 \\ b_2 \\ c_2 \end{bmatrix} = \begin{bmatrix} \alpha a_1 + \beta a_2 \\ \alpha b_1 + \beta b_2 \\ \alpha c_1 + \beta c_2 \end{bmatrix}$$

$$\begin{bmatrix} V & W \end{bmatrix} = \begin{bmatrix} a_1 & a_2 \\ b_1 & b_2 \\ c_1 & c_2 \end{bmatrix} \cdot \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \begin{bmatrix} \alpha a_1 + \beta a_2 \\ \alpha b_1 + \beta b_2 \\ \alpha c_1 + \beta c_2 \end{bmatrix} = \alpha \begin{bmatrix} a_1 \\ b_1 \\ c_1 \end{bmatrix} + \beta \begin{bmatrix} a_2 \\ b_2 \\ c_2 \end{bmatrix}$$

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 어떤 행벡터의 선형 결합

"
 선형 벡터들은 α, β 계수를 Linear Combination

Matrix



$$A \pm B$$

$$AB \neq BA$$

$$AI = IA = A$$

행렬은 단위행렬

$$I = E$$

$$= \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}$$

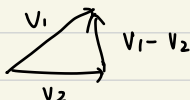
$$A A^T = A^T A = I$$

정사영

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Vector : $V = (a, b, c)^T = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$

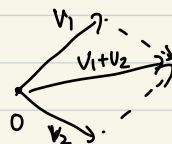
$$V_1 - V_2$$



(a, b, c)

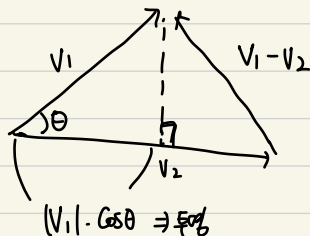
$$V_1 + V_2$$

$$= (a_1 + a_2, b_1 + b_2, c_1 + c_2)$$

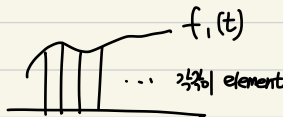


- Inner product (내적) $\hat{=}$ Projection (영)

$$V_1 \cdot V_2 = |V_1| |V_2| \cdot \cos \theta = (a_1 \cdot a_2 + b_1 \cdot b_2 + c_1 \cdot c_2)$$



함수의 내적 $(f_1(t), f_2(t))$



$$f_1(t) = (\dots, f_1(t_1), f_1(t_2), \dots)$$

$$f_2(t) = (\dots, f_2(t_1), f_2(t_2), \dots)$$

$$\sum_{k=-\infty}^{\infty} f_1(t_k) \cdot f_2(t_k) \rightarrow \int f_1(t) f_2(t) dt$$

Hilbert Space.

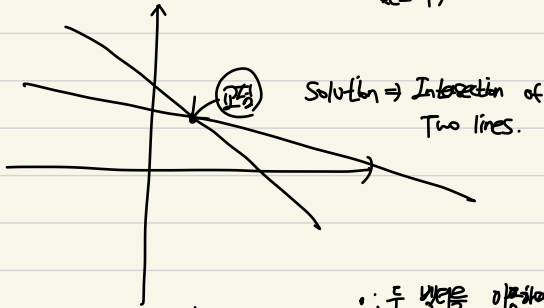
Chapter 1 : Gauss Elimination.

⇒ How to solve Linear system eqn.

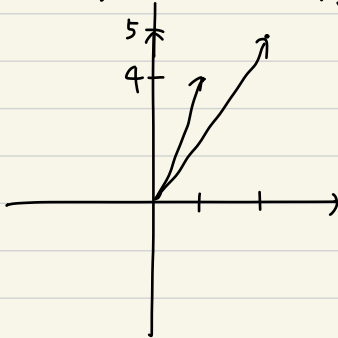
$$\begin{cases} x+2y=3 & -① \\ 4x+5y=6 & -② \end{cases} \quad 4 \times ① - ② \Rightarrow 3y=6$$

$$\begin{bmatrix} 1 & 2 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 6 \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 4 & 5 \end{bmatrix}^{-1} \begin{bmatrix} 3 \\ 6 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$



∴ 두 방정식을 이용하여 해를 구할 수 있다.



For 3-D vector.

$$\begin{cases} 2u+v+w=5 \\ 4u-v=-2 \\ -2u+7v+2w=9 \end{cases}$$

Row form ⇒ Intersection of 3 planes.

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -1 & 0 \\ -2 & 7 & 2 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 5 \\ -2 \\ 9 \end{bmatrix} \quad u \begin{bmatrix} 2 \\ 4 \\ -2 \end{bmatrix} + v \begin{bmatrix} 1 \\ -1 \\ 7 \end{bmatrix} + w \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$$

Column form ⇒ Linear Combination of Column Vectors.