

# **CS450: Numerical Analysis**

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#### **Approximation Errors**

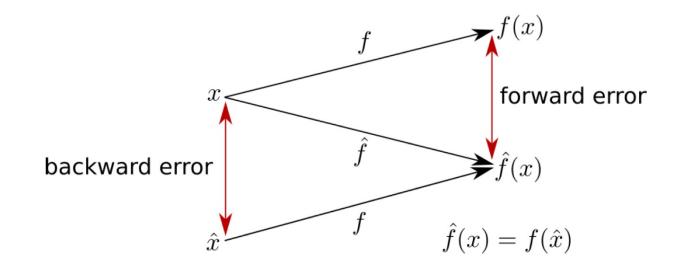


- Last lecture: we want to evaluate  $\sin(\frac{\pi}{8})$ , but the requirement is without using a computer/calculator
  - We have to opt for approximations
  - Using  $\sin\left(\frac{\pi}{8}\right) \approx \frac{\pi}{8} \approx \frac{3.14}{8} = 0.3927$ , we have an approximated solution
  - Two types of errors:
    - $\circ$  Truncation error, caused by approximating  $\sin(x)$  by x
    - $\circ$  Rounding error, caused by approximating  $\pi$  by 3.14
  - There could be other errors, making things complicated... we want something more unified...

#### **Approximation and Errors**



- Forward and backward error
  - Suppose we want to compute y = f(x), where  $f: R \to R$ , but obtain approximate value  $\hat{y}$
  - Forward error:  $\Delta y = \hat{y} y$
  - Backward error:  $\Delta x = \hat{x} x$ , where  $f(\hat{x}) = \hat{y}$



#### **Approximation and Errors**



- Forward and backward error
  - Suppose we want to compute  $\sin(\frac{\pi}{8})$ , and the system produces  $\sin(\frac{\pi}{8}) \approx \frac{\pi}{8} \approx \frac{3.14}{8} = 0.3927$
  - What is the forward error?:  $\Delta y = \hat{y} y =$
  - What is the backward error?:  $\Delta x = \hat{x} x =$ 
    - o Is backward error unique?
    - o Why we need backward error?

#### **Approximation and Errors**



- Forward and backward error
  - What is forward error?
    - The computational error of an algorithm
    - Essentially, this is what we really want for an algorithm, but usually hard to obtain...
  - What is backward error?
    - Backward error enables us to measure computational error with respect to data propagation error



- Absolute condition number
  - The absolute condition number is a property of the problem, measuring its sensitivity to perturbations in input
  - How much a small change in the input leads to changes in the output
  - Formally, defined by the ratio of absolute errors at output and input

$$\kappa_{abs}(f) = \lim_{\delta \to 0} \max_{\|\Delta x\| < \delta} \frac{\|\Delta f\|}{\|\Delta x\|}$$



- Exercise
  - Absolute condition number, defined by the ratio of absolute errors at output and input

$$\kappa_{abs}(f) = \lim_{\delta \to 0} \max_{\|\Delta x\| < \delta} \frac{\|\Delta f\|}{\|\Delta x\|}$$

Calculate the absolute condition number of

$$\circ f(x) = |x| \text{ at } x = 0$$

$$\circ f(x) = e^x \text{ at } x = 1$$

What do we observe?



- Exercise
  - Absolute condition number, defined by the ratio of absolute errors at output and input

$$\kappa_{abs}(f) = \lim_{\delta \to 0} \max_{\|\Delta x\| < \delta} \frac{\|\Delta f\|}{\|\Delta x\|}$$

• If f is differentiable at x, the absolute condition number is essentially the derivative at that point

$$\kappa_{abs}(f) = \lim_{\delta \to 0} \max_{\|\Delta x\| < \delta} \frac{\|\Delta f\|}{\|\Delta x\|} = \frac{df}{dx}$$



- Relative condition number
  - Formally, defined by the ratio of relative errors at output and input

$$\kappa_{rel}(f) = \lim_{\delta \to 0} \max_{\|\Delta x\| < \delta} \frac{\|\Delta f/f(x)\|}{\|\Delta x/x\|} = \lim_{\delta \to 0} \max_{\|\Delta x\| < \delta} \frac{\|\frac{f(x + \Delta x) - f(x)}{f(x)}\|}{\|\frac{\Delta x}{x}\|}$$

$$= \lim_{\delta \to 0} \max_{\|\Delta x\| < \delta} \frac{\|f(x + \Delta x) - f(x)\|}{\|\Delta x\|} \frac{\|x\|}{\|f(x)\|} = \frac{|x \cdot f'(x)|}{|f(x)|} = \frac{|x| \cdot \kappa_{abs}(f)}{|f(x)|}$$



- Exercise
  - Relative condition number, defined by the ratio of relative errors at output and input

$$\kappa_{rel}(f) = \frac{|x \cdot f'(x)|}{|f(x)|}$$

Calculate the absolute condition number of

$$\circ f(x) = \sqrt{x} \text{ at } x = 2$$

$$\circ f(x) = e^x \text{ at } x = 1$$



- Interpretation
  - (Relative) condition number

$$\kappa(f) = \frac{|x \cdot f'(x)|}{|f(x)|}$$

- Condition number indicates how much the system will be amplifying the errors in the input: suppose we are to evaluate  $f(x) = \tan(x)$  for x near  $\frac{\pi}{2}$
- Suppose  $x_1 = \frac{\pi}{2} 0.001$  and  $x_2 = \frac{\pi}{2} 0.002$ ,  $|x_1 x_2| = 0.001$  but  $|f(x_1) f(x_2)| = 500$
- What is the condition number?



- Interpretation
  - (Relative) condition number

$$\kappa(f) = \frac{|x \cdot f'(x)|}{|f(x)|}$$

Linking the forward and backward error

forward\_error = 
$$\kappa(f) \times \text{backward\_error}$$

- Condition number indicates how much the system will be amplifying the errors in the input
- Forward error may not be easy to obtain, but condition number and backward errors are accessible



- Example
  - Evaluate the value of  $\sqrt{2}$
  - Algorithm: make guess on t such that  $t^2 \le 2$  until reaching some desire precision
  - Equivalently, it means evaluating  $f(x) = \sqrt{x}$  at x = 2
  - To start with, we approximate  $\sqrt{2}$  by t = 1.4
    - Forward error:  $\sqrt{2} 1.4 = ?$
    - o Backward error:  $2 (1.4)^2 = ?$
    - o Condition number:  $\kappa(f) = \frac{|x \cdot f'(x)|}{|f(x)|} = ?$



- Example
  - Evaluate the value of  $\sqrt{2}$
  - Algorithm: make guess on t such that  $t^2 \le 2$  until reaching some desire precision
  - Equivalently, it means evaluating  $f(x) = \sqrt{x}$  at x = 2
  - Next, we approximate  $\sqrt{2}$  by t = 1.41
    - Forward error:  $\sqrt{2} 1.41 = ?$
    - Backward error:  $2 (1.41)^2 = ?$
    - o Condition number:  $\kappa(f) = \frac{|x \cdot f'(x)|}{|f(x)|} = ?$



- Remark
  - (Relative) condition number

$$\kappa(f) = \frac{|x \cdot f'(x)|}{|f(x)|}$$

- Depends on the function f itself, not on anything else
- By applying an algorithm, we evaluate f(x) by  $\hat{f}(x) = \hat{y}$
- Using backward error analysis, we assume  $\hat{f}(x) = f(\hat{x})$  for some  $\hat{x}$  that is close to x, i.e., our approximated solution to the original problem is the exact solution to a "nearby" point



- Remark
  - Condition number provides a sense about errors due to round-off, which might result in useless/unreliable results
  - If condition number is 1, then 1% input error → 1% output error
  - If condition number is 1000, then 0.1% input error  $\rightarrow$  100 amplification in output
- Conditioning tells only half the story...
  - Even if a problem is well conditioned, does it mean that we are bound to evaluate it well?



- Example
  - To evaluate  $a_n = 2^{-n}$ , use the following recursion

$$a_0 = 1$$
,  $a_1 = 1/2$ 

$$a_{n+1} = \frac{5}{2}a_n - a_{n-1}$$

- This algorithm works on the paper
- What if there is a very small perturbation in  $a_0$ ? Say  $a_0 = 1 + 2 \times 10^{-16}$



- Example
  - To evaluate  $a_n = 2^{-n}$ , use the following recursion

$$a_0 = 1 + 2 \times 10^{-16}, a_1 = 1/2$$

$$\circ \ a_{n+1} = \frac{5}{2}a_n - a_{n-1}$$

A piece of code in Matlab

```
delta = 2e-16;

A(1) = 1+delta;
A(2) = 1/2;

N = 100;

for i = 2:N
        A(i+1) = 5/2*A(i) - A(i-1);
end
```

51	52	53	54	55	56	57	58	59	60	61	62	63	64
-0.0833	-0.1667	-0.3333	-0.6667	-1.3333	-2.6667	-5.3333	-10.6667	-21.3333	-42.6667	-85.3333	-170.6667	-341.3333	-682.6667



- Characterization
  - Algorithm is stable if result produced is relatively insensitive to perturbations during computation
  - Stability of algorithms is analogous to conditioning of problems: Small changes in the initial data produce correspondingly small changes in the final results
  - Accuracy: closedness of computed solution to true solution of the problem
  - Applying stable algorithm to well-conditioned problem yields accurate solution



- Characterizing stability
  - Suppose that  $E_0 > 0$  denotes an error introduced at some stage in the calculation and  $E_n$  represents the magnitude of the error after n subsequent operations
    - o If  $E_n \approx CnE_0$ , where C is a constant independent of n, then the growth of error is linear;
    - o If  $E_n \approx C^n E_0$ , for some C > 1, then the growth of error is called exponential
  - Linear growth of error is usually unavoidable, and when  $E_0$  and C are small, the results are generally acceptable
  - Exponential growth of error should be avoided because the terms  $\mathcal{C}^n$  becomes large for even relatively small values of n



- Example
  - To evaluate  $a_n = 2^{-n}$ , use the following recursion

$$a_0 = 1$$
,  $a_1 = 1/2$ 

$$a_{n+1} = \frac{5}{2}a_n - a_{n-1}$$

- What would be the growth of error?
- Step 1: check that for any constants  $c_1$  and  $c_2$ ,  $a_n = c_1 \cdot \left(\frac{1}{2}\right)^n + c_2 \cdot 2^n$  is a solution to the above recursion



- Example
  - To evaluate  $a_n = 2^{-n}$ , use the following recursion

$$a_0 = 1$$
,  $a_1 = 1/2$ 

$$a_{n+1} = \frac{5}{2}a_n - a_{n-1}$$

■ Step 2: check that for any constants  $c_1$  and  $c_2$ ,  $a_n = c_1 \cdot \left(\frac{1}{2}\right)^n + c_2 \cdot 2^n$  is a solution to the above recursion; and if  $a_0 = 1$ ,  $a_1 = 1/2$ , then  $c_1 = 1$  and  $c_2 = 0$ 



- Example
  - To evaluate  $a_n = 2^{-n}$ , use the following recursion

$$a_0 = 1$$
,  $a_1 = 1/2$ 

$$a_{n+1} = \frac{5}{2}a_n - a_{n-1}$$

• Step 3: check that for any constants  $c_1$  and  $c_2$ ,  $a_n = c_1 \cdot \left(\frac{1}{2}\right)^n + c_2 \cdot 2^n$  is a solution to the above recursion; and if  $a_0 = 1 + \delta$ ,  $a_1 = 1/2$ , then  $c_1 = ?$  and  $c_2 = ?$ 



- Example
  - To evaluate  $a_n = 2^{-n}$ , use the following recursion

$$a_0 = 1$$
,  $a_1 = 1/2$ 

$$a_{n+1} = \frac{5}{2}a_n - a_{n-1}$$

• Step 4: if  $a_0 = 1 + \delta$ ,  $a_1 = 1/2$ , then  $c_1 = ?$  and  $c_2 = ?$ ; what is the growth of error?

# **Learning Objectives**



- Forward error and backward error
- Conditioning number of a problem
- Algorithm stability