

**CompSci131**

# **Parallel and Distributed Systems**

**Prof. A. Veidenbaum**

# Today's topics

- Berkeley sockets
- MPI
- Reading assignment:
  - Today: 4.3 *and* lecture notes
  - Next lecture: L10, MPI lecture notes
    - » Complete the assignment before next class

# Last Lecture Covered

- **Communication**
- **RPC**

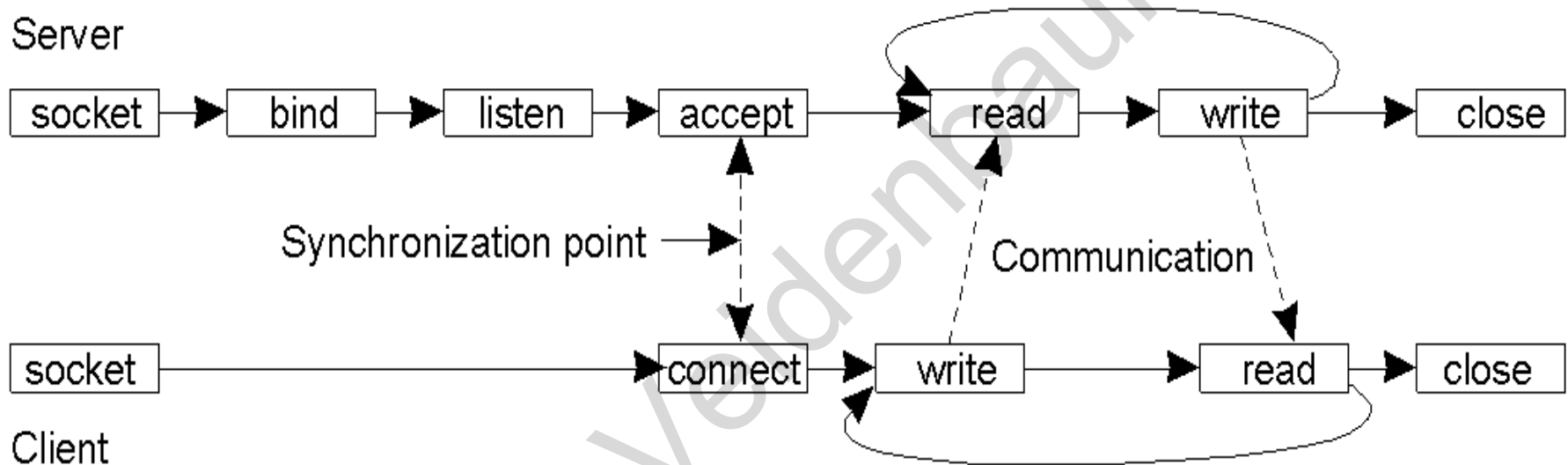
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# Message-Oriented Transient Communication Protocols

- **Berkeley Socket** primitives for TCP/IP
  - Read/write data and it will appear on the other end

Primitive	Meaning
<b>Socket</b>	<b>Create a new communication endpoint</b>
<b>Bind</b>	<b>Attach a local address (IP+port) to a socket</b>
<b>Listen</b>	<b>Announce willingness to accept connections</b>
<b>Accept</b>	<b>Block caller until a connection request arrives</b>
<b>Connect</b>	<b>Actively attempt to establish a connection</b>
<b>Send</b>	<b>Send some data over the connection</b>
<b>Receive</b>	<b>Receive some data over the connection</b>
<b>Close</b>	<b>Release the connection</b>

# Berkeley Sockets (2)



- **Server:**
  - Create local address for a socket (**bind**), reserve buffer (**listen**)
  - Wait for requests (**accept**), block until the next one arrives
- **Client:**
  - request **connection** to server, block until connection is set up

# Berkeley Sockets (3)

- How does a server handle multiple connections?
- *listen* specifies maximum number of connections
  - Allows the OS to reserve enough buffer space
- *accept* “wakes up” on every connection request
  - Allows the OS to fork off a new process to handle the new connection
  - Server goes back and listens for new *connect*
- Client uses transport-level address to connect
  - *connect* blocks until the connection is established

# The Message Passing Interface (MPI)

- Used to program a single application
  - on a multi-computer
- Uses the Single-Program Multiple-Data model
  - SPMD
  - All nodes run the same program on different local data
- Has a number of communication modes, primitives
  - Assumes reliable communication and thus uses transient mode
- Has data distribution primitives

# What exactly is MPI?

- **A Message Passing Interface**
  - Not a new language!
  - A standard for communication between processors
    - » The MPI-1 standard was defined in Spring of 1994
    - » MPI-2, -3, and 4 have also been defined
      - Major additions: parallel I/O, dynamic process management
- **The standard specifies**
  - names, calling sequences, and results of its functions
  - The functions can be called from Fortran and C/C++
  - All implementations of MPI must conform to the standard
    - » ensuring portability



# How to write MPI programs?

- Use standard C programming + parallelism, communication

```
#include <mpi.h>
void main (int argc, char *argv[]) {
int err;
err = MPI_Init(&argc, &argv);  /* join the Collective */
... /*compute smth*/
err = MPI_Finalize();          /* exit */
```

# How to write MPI programs?

- After MPI\_Init each process becomes part of the MPI *world*
  - Is ready to execute and communicate with others
  - Each participating process starts **the same program** on its node
    - » Can find out its own id (rank), total number of nodes

# What does MPI provide?

- **Point-to-point communication**
  - Send, Recv primitives
  - Communicates variables of the MPI types
    - » including aggregated types
- **Collective communication**
  - One-to-many and many-to-one
    - » Broadcast and “reduce” (with different operators)
      - Reductions:  $X = \text{SUM}(A[I]), 0 < I < N$
    - » Same syntax on all processors

- **Synchronization**

- **Barrier**

- » *Every* node has to reach this point in a program before *all* continue
    - » What about other types of synchronization?

- **Static process creation (in MPI-1)**

- » Can be dynamic in MPI-2 and later

# Point-to-point communication

- **Explicit `Send()` and `Recv()` primitives**
  - **Parameters:**
    - » **user buffer, data type, count (address, type, length)**
      - Data type can be user defined
  - **Can hide type conversion (different byte ordering, floats)**
- **Basic `Send/Recv` are Blocking**
  - **The `Send` function only returns when data is received by the remote task**
  - **The `Recv` blocks until it gets data**
    - » **This is synchronous communication**
- **Now can describe a simple MPI subset**
  - **sufficient to start programming...**

# A 6-function MPI

- **MPI\_Init(&argc, &argv)** - start MPI
- **MPI\_Finalize()** - end MPI
- **MPI\_COMM\_SIZE** - number of nodes
- **MPI\_COMM\_RANK** - my id (rank)
- **MPI\_SEND**
  - Parameters: (start, count, datatype, **dest**, tag, **comm**)
- **MPI\_RECV**
  - Parameters: (start, count, datatype, **source**, tag, **comm**, status)

- **6-function MPI uses**
  - **Blocking send/receive**
  - **Synchronization explicit in send/receive**
    - » **Deadlock possible**

# Other types of MPI primitives

- Has a number of communication modes, primitives

Primitive	Meaning
<b>MPI_bsend</b>	<b>Buffered send - append outgoing message to a local send buffer</b>
<b>MPI_send</b>	<b>Send a message and wait until copied to local or remote buffer</b>
<b>MPI_ssend</b>	<b>Synchronous send a message and wait until receipt starts</b>
<b>MPI_sendrecv</b>	<b>Send a message and wait for reply</b>
<b>MPI_isead</b>	<b>Pass reference to outgoing message, and continue</b>
<b>MPI_issend</b>	<b>Pass reference to outgoing message, and wait until receipt starts</b>
<b>MPI_recv</b>	<b>Receive a message; block if there are none</b>
<b>MPI_irecv</b>	<b>Check if there is an incoming message, but do not block</b>



- **MPI\_Irecv(&buf, count, datatype, source, tag, comm, &request)**
- **MPI\_Wait(&request, &status)**
  - Now block until Irecv is finished
- **MPI\_Test(&request, &flag, &status)**
  - Flag=1 when finished, else 0. status={src,tag}
- **MPI\_Get\_count(&status, datatype, &count)**
  - Returns the count of elements received

# Buffering

- Where is the message buffered?
- A critical issue for good performance
- There are three data exchange mechanisms
  - Eager (MPICH default)
    - » data is sent to the destination immediately
  - Rendezvous
    - » When a receive is posted
      - *Control is always sent*
  - Get
    - » Receiver reads data directly
      - Best on PGAS systems

# Sending Modes

- **Synchronous mode ( MPI\_Ssend):**
  - the send does not complete until a matching receive has begun
- **Buffered mode ( MPI\_Bsend)**
  - the user supplies the buffer to system for its use
- **Ready mode ( MPI\_Rsend)**
  - user guarantees that matching receive has been posted.
    - » *undefined behavior if the matching receive is not posted*
- **Non-blocking versions**
  - MPI\_Issend, MPI\_Irsend, MPI\_Ibsend
- ***Note that an MPI\_Recv may receive messages sent with any send mode.***