# Jiahao Xu

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#### EDUCATION

Virginia Tech VA, United States Doctor of Philosophy in Computer Science & Applications program 08/2023 - present • Advisor: Chris North **Tufts University** MA, United States Master of Science of Computer Science 01/2021 - 05/2023 • GPA: 3.80 University of California, Irvine CA, United States Exchange Student Program 04/2019 - 10/2019 • GPA: 3.62 (Spring Quarter), 3.543 (Summer Session) Chang'an University Xi'an, China 08/2016 - 06/2020 Bachelor of engineering • GPA: 3.29 • Major: Computer Science and Technology Research Experience Graduate Researcher Virginia Tech Advisor: Chris North 09/2022 - 05/2023• Explanations of Dimension Reduction Plots Tufts University Graduate Researcher 09/2022 - 05/2023Advisor: Remco Chang • Explore the possibility of implementing hypothesis-driven visual analysis Internship Research Internship Wuhan 10/2019 - 12/2019 Tencent Research and Development Center • Deep learning model test and refine Projects 01/2022 - 05/2022 $VAST2019-MC3 \mid JavaScript, D3$ • Develop an interactive visualization system for VAST2019 MC3 • The dataset contains messages from an APP before, during, and after an earthquake. • The program consists of a Timeline, a Map, and a Word Bubble whose size depends on the frequency of the word • This is a final project for CS178(Visual Analytics) at Tufts 09/2021 - 12/2021**Network Programming** | Python, Socket programming • Construct an encrypted P2P instant messager • Generates an RSA keypair and sends a message over a network, followed by its signature • Construct a Port Scanner • Construct a Port Scanner Detector 09/2021 - 12/2021Visulization of Convex Hull Construction  $\mid C++, LEDA$ • Implemented the Incremental Approach of Convex Hull construction • Visualize how the construction works step by step • This is a final project for CS163(Computational Geometry) at Tufts

#### Vehicle Queue Control | Python, Virtual Simulator

01/2020 - 06/2020

- Construct Carla simulator, which is an open-source autonomous driving simulator
- Display a vehicle queue control program
- This program uses a constant time-gap spacing strategy to change the acceleration of the vehicle dynamically

#### **3D Image Reconstruction** | Python, Meshlab

04/2019 - 06/2019

- Calibrated the camera by using the scans of a checkboard
- Triangulated to get the meshes of the object
- Reconstructed the 3D model of the object

## TECHNICAL SKILLS

Languages: C++, Python, JavaScript Framework: React, Flask, Django Libraries: D3, OpenCV, OpenGl, LEDA Applications: Wireshark, Unity, MeshLab