

MATH466/MATH766

Math of machine learning

03/24 Lecture 17 Laplacian Eigenmap and Spectral Convergence

References:

- Mikhail Belkin, Partha Niyogi, Laplacian eigenmaps for dimensionality reduction and data representation, Neural Computation, (2003)
- Mikhail Belkin, Partha Niyogi, Laplacian eigenmaps and spectral techniques for embedding and clustering, Neurips, 2001
- A. Singer, From graph to manifold Laplacian: the convergence rate, Applied and computational harmonic analysis, 2006
- Yaiza Canzani, Notes for Analysis on Manifolds via the Laplacian

Todays contents:

- Laplacian eigenmap
- spectral convergence

Important concepts:

- manifold hypothesis
- intrinsic

Recommend reading:

- ch1 of Yaiza Canzani, Notes for Analysis on Manifolds via the Laplacian

Review Graph G

affinity / adjacency matrix W ($W_{ij} = W_{ji}, W_{ii} = 0$)

degree matrix D , $D_{ii} = d_i = \sum_j W_{ij}$, $D_{ij} = 0$ if $i \neq j$

graph Laplacian $L = D - W$

$$L_{rw} = I - D^{-1}W$$

$$L_{sym} = I - D^{-\frac{1}{2}}W D^{-\frac{1}{2}}$$

Spectral Clustering : EVD of L : $0 = \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$

$y_i = \begin{bmatrix} \psi_{1i} \\ \psi_{2i} \\ \vdots \\ \psi_{di} \end{bmatrix} \in \mathbb{R}^d$, apply clustering algorithm, e.g. k-means to $\{y_i\}_{i=1}^n$

Laplacian Eigenmap

Laplacian Eigenmap

Lrw eigenval $0 = \lambda_1 \leq \lambda_2 \leq \lambda_3 \leq \dots \leq \lambda_n$

eigvec $\begin{matrix} \psi_1 & \psi_2 & \psi_3 & \dots & \psi_n \\ \parallel & & & & \\ 1_n & & & & \end{matrix}$

$$y_i = \begin{bmatrix} \psi_{1i} \\ \psi_{2i} \\ \vdots \\ \psi_{di} \end{bmatrix} \in \mathbb{R}^d$$

Laplacian Eigenmap

Understanding LE (P.O.V. 1)

Consider mapping $G = (V, E), (V = \{x_1, \dots, x_n\})$ to a line
and keep connected points stay close together.

i.e. find $f: V \rightarrow \mathbb{R}, x_i \mapsto y_i$

s.t. $\sum_{i,j} w_{ij} (y_i - y_j)^2$ is small

Denote $f = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$, then $\sum_{i,j} w_{ij} (y_i - y_j)^2 = \frac{1}{2} f^T L f$

need restrictions on $f: f^T D f = 1$

- removes the arbitrary scaling factor in the embedding
- vertex with larger degree is more important.

$$\rightarrow \min_{f^T D f = 1} f^T L f$$

By optimization thm, optimality condition $L f = \lambda D f$

$$\Rightarrow \text{optimal value } \lambda_{\min}(L) = 1 - \lambda_0 (P) = 0$$

$$\text{optimizer } f = 1_n = \psi_0$$

$f = \frac{1}{\sqrt{n}} 1_n$ is a trivial solution

$$\rightarrow \begin{array}{ll} \min_{\substack{f^T D f = 1}} f^T L f & \text{optimal value } (1 - \lambda_1) \\ \text{f}^T D 1_n = 0 & \text{optimizer } f = \psi_1 \end{array}$$

If we want to map x_i to $y_i \in \mathbb{R}^m$

and keep $\sum_{i,j} \|y_i - y_j\|^2 w_{ij}$ small

we can work with

$$\min_f \sum_{k=1}^m [(y_1)_k \ (y_2)_k \ \dots \ (y_n)_k] L \begin{bmatrix} (y_1)_k \\ (y_2)_k \\ \vdots \\ (y_n)_k \end{bmatrix} =: f_k$$

$$\text{s.t. } f_k^T D f_k = 1,$$

$$f_k^T D 1_n = 0,$$

$$f_k^T D f_{k'} = 0, \ k \neq k'$$

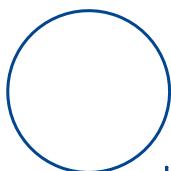
Understanding LE (p. 0, v. 2)

- Manifold $M \in \mathbb{R}^D$

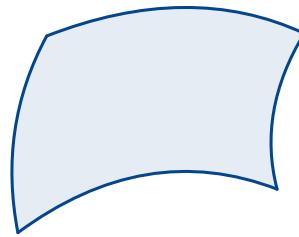
"every point has a nbhd homeomorphic to an open subset of \mathbb{R}^d "

homeomorphism: a cts, invertible func with cts inversion

e.g.



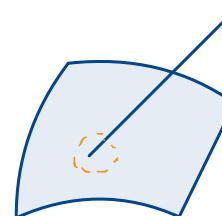
1d manifold in 2d space



2d manifold in 3d space



not a manifold



not a manifold

- Manifold hypothesis:

many high-dim data sets that occurs in the real world

actually lie along low-dim latent manifolds inside that high-dim space

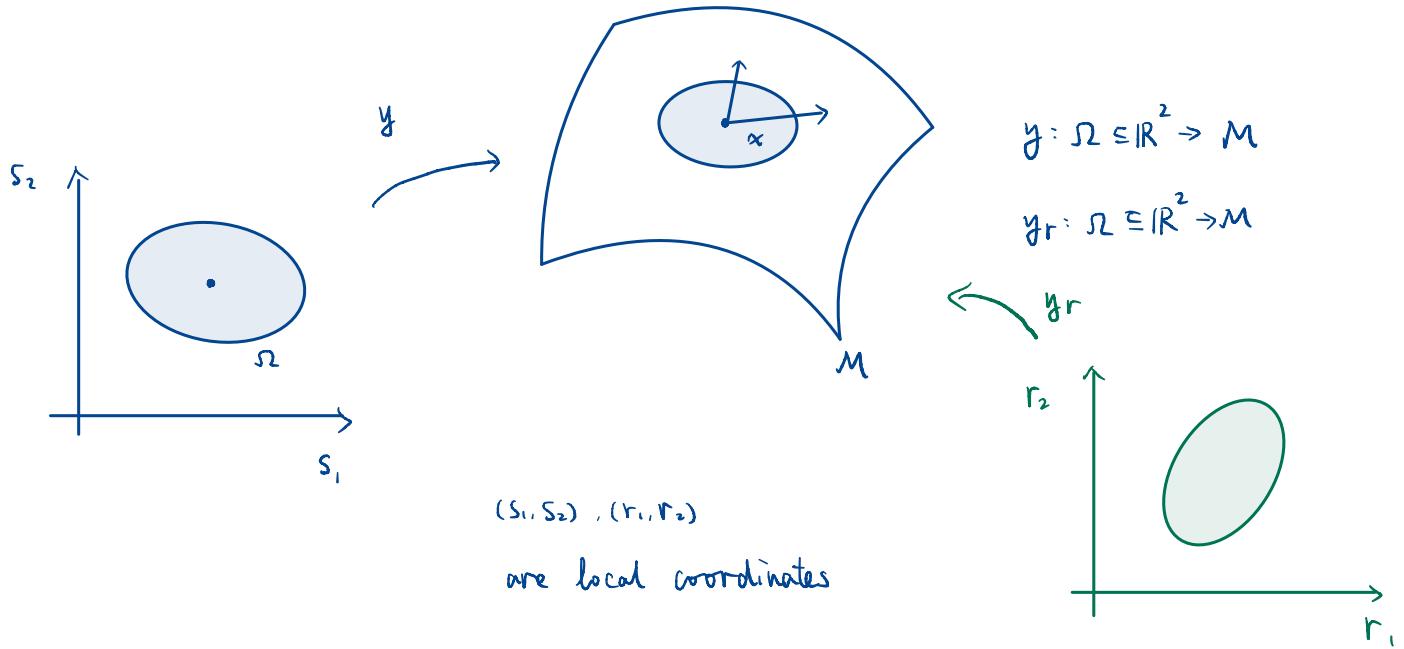
- differential operators on manifold

"intrinsic" v.s. "extrinsic"

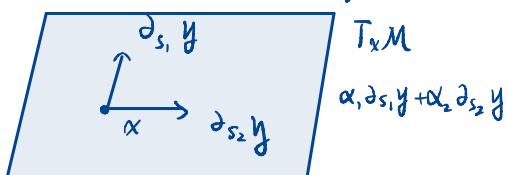
Similar to Euclidean space,

we can define Laplacian operator Δ_M on a manifold M

Δ_M is intrinsic



Tangent space



① metric is intrinsic to the manifold geometry

② differential operators on
a manifold depends on metric

③ If s are local normal coordinates

$$\text{i.e. } \partial s_i^\top \partial s_j = \delta_{ij} = \begin{cases} 1, & i=j \\ 0, & i \neq j \end{cases}$$

$$\text{then } \Delta_M f(x) = - \sum_{i=1}^d \frac{\partial^2}{\partial s_i^2} f(y(s)) \Big|_{y=x} = - \operatorname{div}_M \nabla_M f(x)$$

metric $g_x: T_x M \times T_x M \rightarrow \mathbb{R}$

$$(\alpha_1 \partial_{s_1} + \alpha_2 \partial_{s_2}, \beta_1 \partial_{s_1} + \beta_2 \partial_{s_2})$$

$$\mapsto (\alpha_1, \alpha_2) \begin{pmatrix} \partial_{s_1}^\top \\ \partial_{s_2}^\top \end{pmatrix} (\partial_{s_1}, \partial_{s_2}) \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix}$$

$$M \quad \xrightleftharpoons[?]{} \quad \Delta_M$$

eigen-problem : $\Delta\varphi = \lambda\varphi$ "can you hear the shape of a drum"

① full sequence of eigenvalues of Δ



area, perimeter and # of holes in Δ

dim, volume and total scalar curvature

② Sturm-Liouville's decomposition

(M, g) compact Riemannian manifold

w/. o.n. basis $\varphi_1, \varphi_2, \dots, \varphi_j$

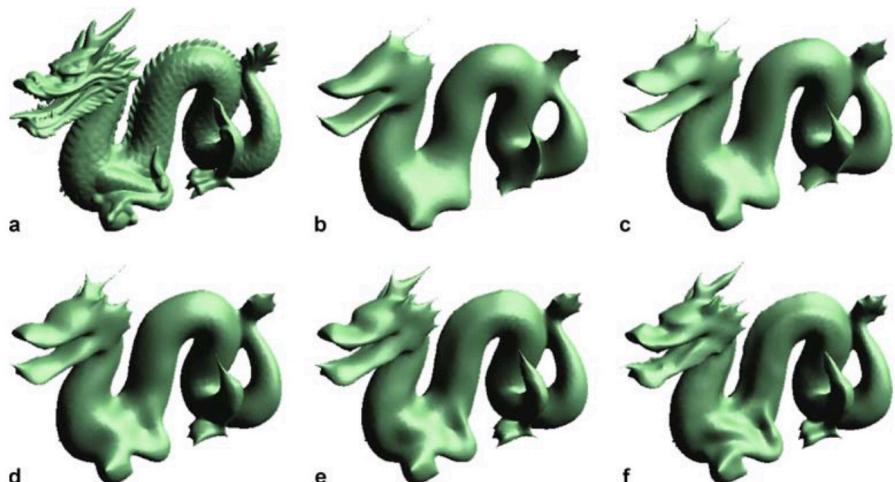
(eig-funcs of Δ_g)

Any function $f \in L^2(M)$ can be written as

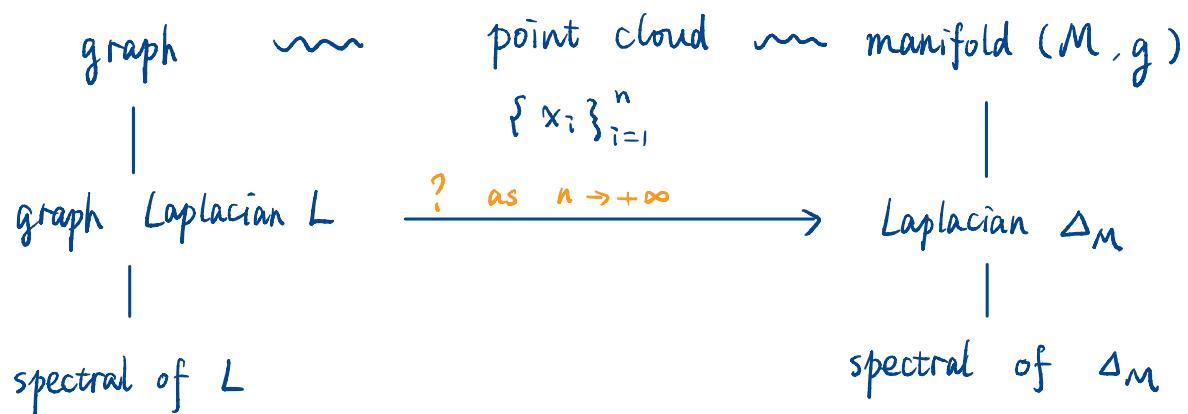
a convergent series in $L^2(M)$

$$f = \sum_{j=1}^{\infty} a_j \varphi_j \quad \text{for some } a_j \in \mathbb{R}$$

e.g. Euclidean space, Fourier sequence



a. M = Dragon. b-f. reconstructed manifold using $N = 100, 200, 300, 500$ and 900 eigenfunctions respectively. Picture from paper *Spectral mesh deformation*.



- Convergence [Singer 06]

$$W_{ij} = k \left(\frac{\|x_i - x_j\|^2}{2\varepsilon} \right) . k \text{ p.s.d. e.g. } k(x) = e^{-x}$$

$$L = I - D^{-1}W, \quad x_i \sim i.i.d U(M), \quad i=1, \dots, n$$

$$\begin{aligned} \text{then } \frac{1}{\varepsilon} \sum_{j=1}^n L_{ij} f(x_j) &= \frac{1}{2} \Delta_M f(x_i) + O\left(\frac{1}{n^{1/2} \varepsilon^{1/2+d/4}}, \varepsilon\right) \\ &\leq C_1 \frac{1}{n^{1/2} \varepsilon^{1/2+d/4}} + C_2 \varepsilon, \quad N \rightarrow +\infty, \varepsilon \rightarrow 0 \end{aligned}$$

- Demo