

MATH466/MATH766

Math of machine learning

01/08 Lecture 1 introduction

References:

- Ch5 of Deep Learning by Ian Goodfellow, Yoshua Bengio and Aaron Courville
- Ch2 of The Elements of Statistical Learning by Trevor Hastie, Robert Tibshirani and Jerome Friedman

Todays contents:

- overview
- policies
- basic concepts in machine learning
- supervised learning overview

Important concepts:

- generalization gap
- overfitting and underfitting
- bias-variance decomposition

Recommend reading:

course policies: refer to syllabus for details

1. communication: canvas, email, in-person. questions, feedbacks and complains are valuable.
2. academic integrity, collaboration and AI tools.
3. grade: course evaluation (2%) + HW (38%) + 2 exams (30%) + course project (30%).
midterm: will provide practice questions before the exam
final: will provide practice questions before the exam or change the exam to a take-home open-book exam
HW: write solutions independently; feedback is very welcome
4. individual course project:
can be any topic related to machine learning
several checkpoints are setted
the learning process is the goal of the course project
refer to the specific file for details
5. late policy:
late day
penalty
where to ask for help
6. notes to graduate students:
an additional assignment
grade and withdraw

course overview:

brainstorm

This course will emphasize understanding machine learning methods through the mathematical derivation, computation and proof. Coding serves as a tool to help understanding.

Some basic concepts in machine learning

- The main components of machine learning are data/task, model/method and algorithm
 - data/task: what do you want the machine to learn
 - model/method: how do you formulate the learning procedure
 - algorithm: how do you solve the learning model
- Based on the data/tasks provided, machine learning are roughly divided into 3 categories: supervised learning, unsupervised learning and reinforcement learning
 - supervised learning: labeled data/learn the label. E.g. regression, classification
 - unsupervised learning: unlabeled data. E.g. clustering, dimension reduction, manifold learning, data generating
 - reinforcement learning: no data beforehand, environment provided, data are generated and learning happens while interacting with the environment.
- There are many other active research area in machine learning whose category is not very clear. We follow this categorization for teaching purpose, for example clearer structure, easier comparison and etc. Please feel free to explore more after class if you are interested and you are always welcome to email me/come to office hour when you have questions so that we can learn together

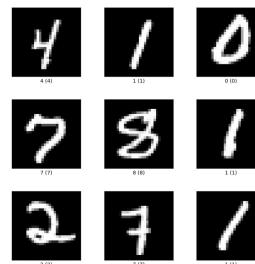
Supervised learning overview

1. Task

labeled data $\{(x_i, y_i)\}_{i=1}^n$,

$x_i \in \mathbb{R}^d$, inputs;

$y_i \in \mathbb{R}$, labels / responses



MNIST
a dataset of handwritten digits
 $x_i \in \mathbb{R}^{784}, y_i \in \{0, 1, \dots, 9\}$

Goal: predict y given x

e.g. by $f(x)$

• classification . disc labels

$y_i \in \{0, 1, 2, \dots, 9\}$.

• regression . cont labels

$y_i \in \mathbb{R}$

Variables Table

Variable Name	Role	Type	Demographic	Description	Units	UCI Real estate valuation a dataset used to study house unit area price in a district in China
No	ID	Integer				
X1 transaction date	Feature	Continuous		for example, 2013.250=2013 March, 2013.500=2013 June, etc.		
X2 house age	Feature	Continuous			year	
X3 distance to the nearest MRT station	Feature	Continuous			meter	
X4 number of convenience stores	Feature	Integer		number of convenience stores in the living circle on foot	integer	
X5 latitude	Feature	Continuous		geographic coordinate, latitude	degree	
X6 longitude	Feature	Continuous		geographic coordinate, longitude	degree	
Y house price of unit area	Target	Continuous		10000 New Taiwan Dollar/Ping, where Ping is a local unit, 1 Ping = 3.3 meter squared	10000 New Taiwan Dollar/Ping	

$$x_i \in \mathbb{R}^6, y_i \in \mathbb{R}$$

Q: How to measure the performance of a learned model f ?

2. Measurement : {training, testing, population} error
generalization gap

- loss function: $l: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}_{\geq 0}$

e.g. $l(\hat{y}, y) = \frac{1}{2} (\hat{y} - y)^2$, $l(\hat{y}, y) = \begin{cases} 1, & \hat{y} \neq y \\ 0, & \hat{y} = y \end{cases}$

$$l(\hat{y}, y) = |\hat{y} - y|$$

- error / empirical risk: if the learned model is $y = f(x)$

$$R(f) := \frac{1}{n} \sum_{i=1}^n l(f(x_i), y_i)$$

\uparrow prediction \uparrow data

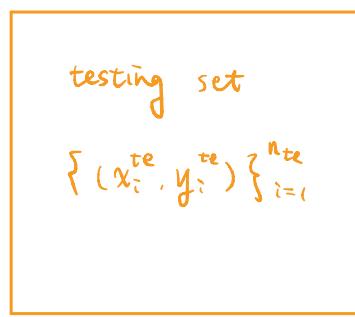
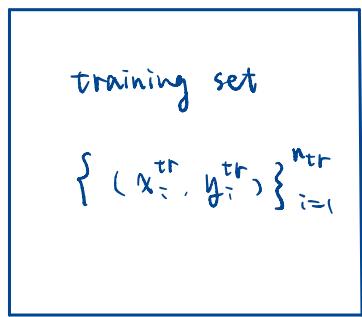
- training and testing :

assume training data and testing data

(x, y) follows the same distribution $P(x, y)$

use training set to find the model f

use testing set to measure if the model f is good.



model training never across
this line →

training error $R_{tr}(f) = \frac{1}{n_{tr}} \sum_{i=1}^{n_{tr}} l(f(x_i^{tr}), y_i^{tr})$

testing error $R_{te}(f) = \frac{1}{n_{te}} \sum_{i=1}^{n_{te}} l(f(x_i^{te}), y_i^{te})$

We want both error to be small

If testing data are i.i.d sampling from $P(x, y)$,
then as $n_{te} \rightarrow +\infty$, $R_{te}(f)$ is an approximation of
population error $R_p(f) = \int l(f(x), y) dP(x, y)$

- testing / population error are also called generalization error.
- generalization gap

$$R_p(f) - R_{tr}(f) \text{ or } R_{te}(f) - R_{tr}(f)$$

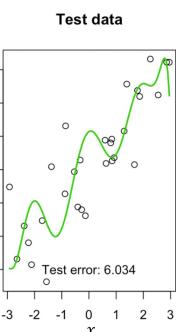
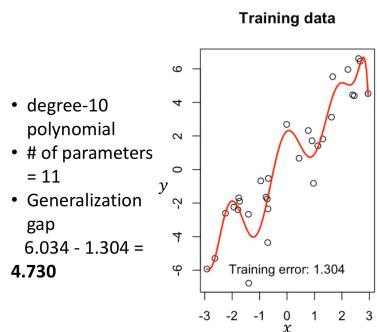
smaller generalization gap is better

3. common issues and the reason

3.1. overfitting and underfitting

overfitting

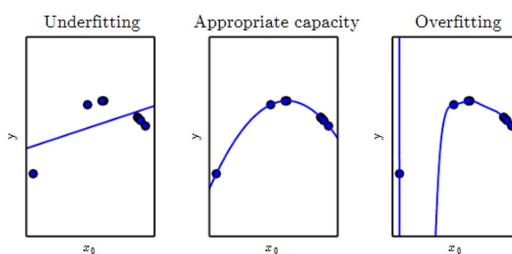
underfitting



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cr. Ch. 5 of Deep Learning by Ian Goodfellow and Yoshua Bengio and Aaron Courville

underfitting : poor performance on both training and testing data
← the model is too simple to capture data complexities

overfitting : large generalization gap
← the model overlearns the data
(noise, inaccurate data)

3.2. Model capacity and U-shape curve

Training : find a model f to fit the training data.

usually within a set of models \mathcal{F} , i.e. $f \in \mathcal{F}$

Model capacity : the ability of functions in \mathcal{F} to fit data

e.g. the set of constant functions has a low capacity

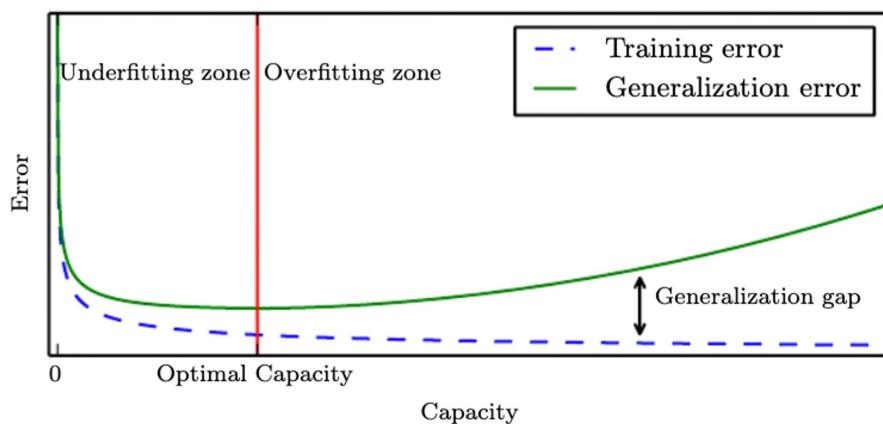
$$\mathcal{F} = \{ f : f(x) = a \mid a \in \mathbb{R} \}$$

e.g. the set of all well-defined functions has a high capacity

higher model capacity $\xrightarrow{\text{usually}}$ lower training error

BUT higher model capacity is not always better

U-shape curve



* 3.3 Bias - Variance Decomposition

learned model $f \leftarrow$ training data
 $\Rightarrow f$ is also random

assume training process is deterministic

the randomness of f all comes from the randomness of training data

\Rightarrow at a new input x with true response y

the squared error of prediction $(f(x) - y)^2$ is random

the randomness all comes from the randomness of training data

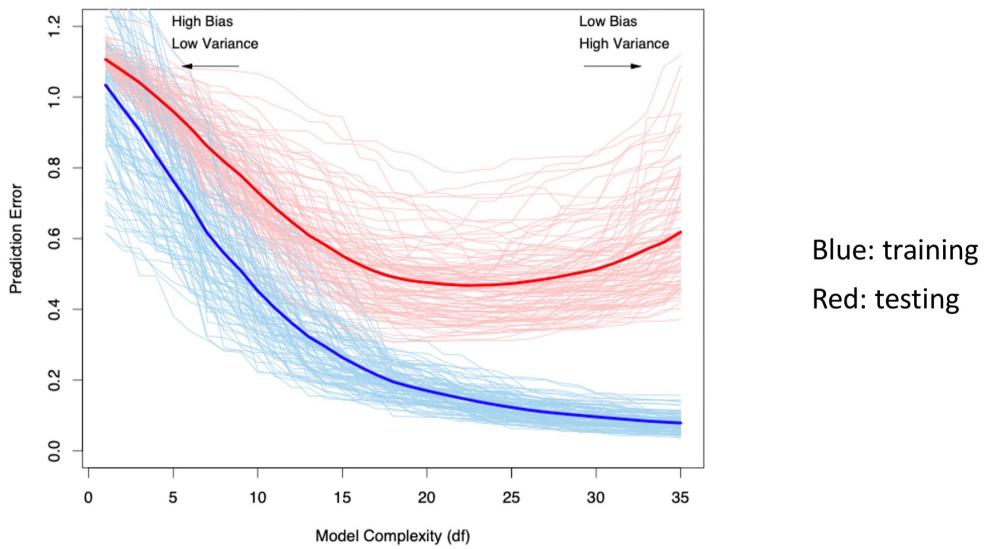
Consider the expectation of the squared error

$$E_{\text{tr}}[(f(x) - y)^2]$$

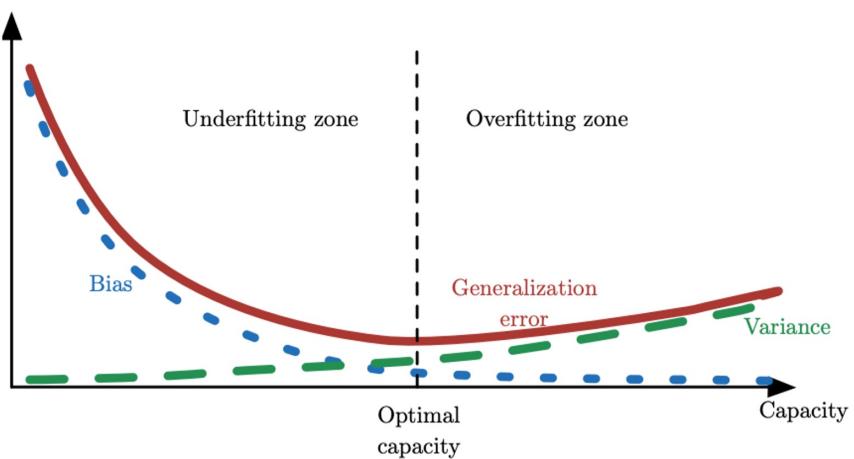
$$= \frac{E_{\text{tr}}[(f(x) - E_{\text{tr}}[f(x)])^2]}{\text{Variance}} + \frac{(E_{\text{tr}}[f(x)] - y)^2}{\text{Bias}^2}$$

low capacity \rightarrow high bias, low variance \rightarrow underfitting

high capacity \rightarrow high variance, low bias \rightarrow overfitting



cr. Ch. 7.2 of The Elements of Statistical Learning, 2(1), 2009, by Trevor Hastie, Robert Tibshirani, and Jerome Friedman



cr. Ch. 5 of Deep Learning by Ian Goodfellow and Yoshua Bengio and Aaron Courville

Q: How to find the optimal capacity?

4. Solve the issue: model selection and cross-validation

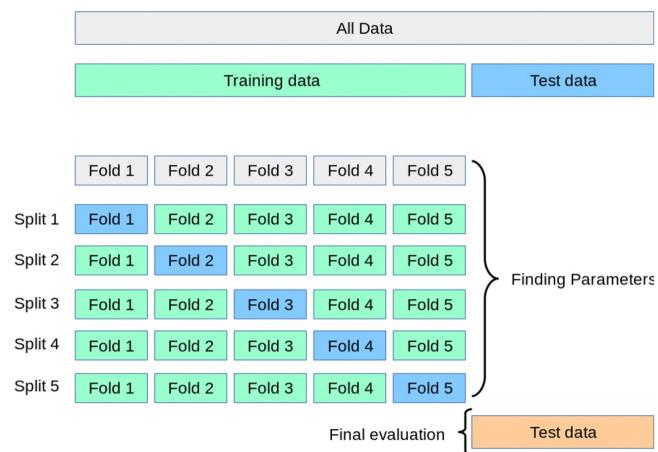
- Validation



Given training set, "sacrifice" a part of samples as a trial to test the model and the part of data are called validation set.

The trial testing error computed on the validation set can be used to indicate testing error.

- Cross Validation (5-fold)



cr. sklearn 3.1. cross-validation