

150 HW 6

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6.1 Conditional independence

Consider the hidden Markov model (HMM) shown below, with hidden states S_t and observations O_t for times $t \in \{1, 2, \dots, T\}$. Indicate whether the following statements are true or false.

F
T
F
F
T
F
T
T
T
F
F
T

$$P(S_t|S_{t-1}) = P(S_t|S_{t-1}, O_t)$$

$$P(S_t|S_{t-1}) = P(S_t|S_{t-1}, O_{t-1})$$

$$P(S_t|S_{t-1}) = P(S_t|S_{t-1}, S_{t+1})$$

$$P(S_t|O_{t-1}) = P(S_t|O_1, O_2, \dots, O_{t-1})$$

$$P(O_t|S_{t-1}) = P(O_t|S_{t-1}, O_{t-1})$$

$$P(O_t|O_{t-1}) = P(O_t|O_1, O_2, \dots, O_{t-1})$$

$$P(O_1, O_2, \dots, O_T) = \prod_{t=1}^T P(O_t|O_1, \dots, O_{t-1})$$

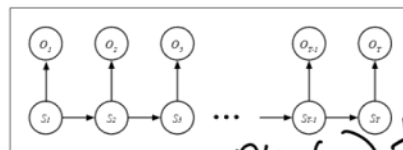
$$P(S_2, S_3, \dots, S_T|S_1) = \prod_{t=2}^T P(S_t|S_{t-1})$$

$$P(S_1, S_2, \dots, S_{T-1}|S_T) = \prod_{t=1}^{T-1} P(S_t|S_{t+1})$$

$$P(S_1, S_2, \dots, S_T|O_1, O_2, \dots, O_T) = \prod_{t=1}^T P(S_t|O_t)$$

$$P(S_1, S_2, \dots, S_T, O_1, O_2, \dots, O_T) = \prod_{t=1}^T P(S_t, O_t)$$

$$P(O_1, O_2, \dots, O_T|S_1, S_2, \dots, S_T) = \prod_{t=1}^T P(O_t|S_t)$$



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$$P(O_1, S_1) \neq P(O_2, S_2|S_1, O_1) \neq P(O_T, S_T|S_1, O_1, \dots, O_{T-1}, S_{T-1})$$

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6.2 More conditional independence

Indicate the **smallest** subset of evidence nodes that must be considered to compute each conditional probability shown below. The first two problems are done as examples. (You may assume everywhere that $2 < t < T - 1$: i.e., do not worry about special boundary cases.)

$$P(S_t | S_1, S_2, \dots, S_{t-1}) = P(S_t | S_{t-1})$$

$$P(O_t | S_1, S_2, \dots, S_T) = P(O_t | S_t)$$

$$P(S_t | S_{t+1}, S_{t+2}, \dots, S_T) = \frac{P(S_t | S_{t+1})}{P(S_{t+1})}$$

$$P(S_t | O_t, O_{t-1}, O_{t+1}) = \frac{P(S_t | O_t, O_{t-1}, O_{t+1})}{P(O_t, O_{t-1}, O_{t+1})}$$

$$P(S_t | O_t, O_{t-1}, O_{t+1}, S_{t-1}, S_{t+1}) = \frac{P(S_t | S_{t-1}, S_{t+1}, O_t)}{P(S_{t-1}, S_{t+1}, O_t)}$$

$$P(S_t | S_1, S_T, O_1, O_t, O_T) = \frac{P(S_t | S_1, S_T, O_t)}{P(S_1, S_T, O_t)}$$

$$P(S_t | O_t, O_{t+1}, \dots, O_T) = \frac{P(S_t | O_t, O_{t+1}, \dots, O_T)}{P(O_t, O_{t+1}, \dots, O_T)}$$

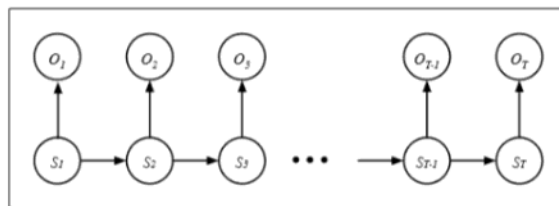
$$P(O_t | O_1, O_2, \dots, O_{t-1}) = \frac{P(O_t | O_1, O_2, \dots, O_{t-1})}{P(O_1, O_2, \dots, O_{t-1})}$$

$$P(O_t | O_1, O_2, \dots, O_{t-1}, S_{t-1}) = \frac{P(O_t | S_{t-1})}{P(S_{t-1})}$$

$$P(O_t | O_1, O_2, \dots, O_{t-1}, S_{t-2}) = \frac{P(O_t | S_{t-2}, O_{t-1})}{P(S_{t-2}, O_{t-1})}$$

$$P(O_t | S_{t-2}, S_{t-1}, S_{t+1}, S_{t+2}) = \frac{P(O_t | S_{t-1}, S_{t+1})}{P(S_{t-1}, S_{t+1})}$$

$$P(O_t | O_{t-1}, O_{t+1}, S_1, S_T) = \frac{P(O_t | O_{t-1}, O_{t+1}, S_1, S_T)}{P(O_{t-1}, O_{t+1}, S_1, S_T)}$$



#3

#4

$$\begin{aligned}
 (a) \quad P(Y_1 | X_1) &= \sum_{x_0} P(X_1, X_0 = x_0 | X_1) \quad (\text{margin.}) \\
 &= \sum_{x_0} P(X_0 = x_0 | X_1) P(Y_1 | X_0 = x_0, X_1) \quad (\text{P.R.}) \\
 &= \sum_{x_0} P(X_0 = x_0) P(Y_1 | X_0 = x_0, X_1) \quad (\text{C.I. by d-sep. \#3})
 \end{aligned}$$

$$\begin{aligned}
 (b) \quad P(Y_1) &= \sum_{x_1} P(X_1 = x_1, Y_1) \quad (\text{margin.}) \\
 &= \underbrace{\sum_{x_1} P(X_1 = x_1)}_{\text{from CPT}_s} \underbrace{P(Y_1 | X_1 = x_1)}_{\text{from (a)}} \quad (\text{P.R.})
 \end{aligned}$$

(c) $P(X_t | Y_1, Y_2, \dots, Y_{t-1}) = P(X_t)$ since X_t is C.I. with Y_1, Y_2, \dots, Y_{t-1} when Y_t is not given by d-sep. #3 on node Y_t .

$$\begin{aligned}
 (d) \quad P(Y_t | X_t, Y_1, Y_2, \dots, Y_{t-1}) \\
 &= \sum_{x_{t-1}} P(Y_t, X_{t-1} = x_{t-1} | X_t, Y_1, Y_2, \dots, Y_{t-1}) \quad (\text{margin.}) \\
 &= \sum_{x_{t-1}} P(X_{t-1} = x_{t-1} | X_t, Y_1, Y_2, \dots, Y_{t-1}) P(Y_t | X_{t-1} = x_{t-1}, X_t, \\
 &\quad Y_1, Y_2, \dots, Y_{t-1}) \quad (\text{P.R.})
 \end{aligned}$$

$$= \underbrace{\sum_{x_{t-1}} P(X_{t-1}=x_{t-1} | Y_1, Y_2, \dots, Y_{t-1})}_{\text{given by prev. step of recur.}} \underbrace{P(Y_t | X_{t-1}=x_{t-1}, X_t)}_{\substack{\text{CPT} \\ (\text{by d-sep. \# 2 \& 3})}}$$

$$\begin{aligned} (e) \quad P(Y_t | Y_1, Y_2, \dots, Y_{t-1}) &= \sum_{x_t} P(Y_t, X_t=x_t | Y_1, Y_2, \dots, Y_{t-1}) \\ &= \sum_{x_t} \underbrace{P(X_t=x_t | Y_1, Y_2, \dots, Y_{t-1})}_{\text{from (a)}} \underbrace{P(Y_t | X_t=x_t, Y_1, Y_2, \dots, Y_{t-1})}_{\substack{\text{from (b)} \\ (\text{P.R.})}} \end{aligned}$$

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6.5 Inference in HMMs

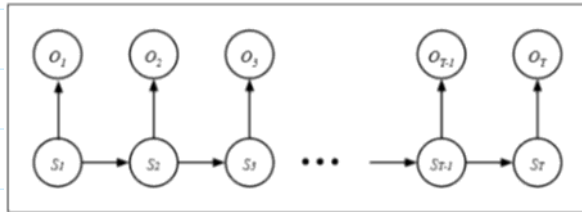
Consider a discrete HMM with hidden states S_t , observations O_t , transition matrix $a_{ij} = P(S_{t+1}=j | S_t=i)$ and emission matrix $b_{ik} = P(O_t=k | S_t=i)$. In class, we defined the forward-backward probabilities:

$$\begin{aligned} \alpha_{it} &= P(o_1, o_2, \dots, o_t, S_t=i), \\ \beta_{it} &= P(o_{t+1}, o_{t+2}, \dots, o_T | S_t=i), \end{aligned}$$

for a particular observation sequence $\{o_1, o_2, \dots, o_T\}$ of length T . In terms of these probabilities, which you may assume to be given, as well as the transition and emission matrices of the HMM, show how to (efficiently) compute the following quantities:

- (a) $P(S_{t+1}=j | S_t=i, o_1, o_2, \dots, o_T)$
- (b) $P(S_t=i | S_{t+1}=j, o_1, o_2, \dots, o_T)$
- (c) $P(S_{t-1}=i, S_t=j, S_{t+1}=k | o_1, o_2, \dots, o_T)$
- (d) $\hat{s}_t = \operatorname{argmax}_i [P(S_t=i | o_1, o_2, \dots, o_T)]$

In all these problems, you may assume that $t > 1$ and $t < T$; in particular, you are *not* asked to consider the boundary cases.



$$\begin{aligned} (a) \quad & P(S_{t+1}=j | S_t=i, o_1, o_2, \dots, o_T) \\ &= P(S_{t+1}=j | S_t=i, o_{t+1}, \dots, o_T) \quad \left(\begin{array}{l} o_1, \dots, o_t \text{ are C.I. with} \\ S_{t+1} \text{ by d-sep \# 1} \end{array} \right) \\ &= \frac{P(o_{t+1}, \dots, o_T | S_t=i, S_{t+1}=j) P(S_{t+1}=j | S_t=i)}{P(o_{t+1}, \dots, o_T | S_t=i)} \quad (\text{Baye's Rule}) \\ &= \frac{P(o_{t+1} | S_t=i, S_{t+1}=j) P(o_{t+2}, \dots, o_T | S_t=i, S_{t+1}=j) \cdot a_{ij}}{\beta_{it}} \quad \begin{array}{l} (\text{P.R.}) \\ (\text{substitution}) \end{array} \\ &= P(o_{t+1} | S_{t+1}=j) P(o_{t+2}, \dots, o_T | S_{t+1}=j) \cdot \frac{a_{ij}}{\beta_{it}} \quad (\text{C.I.}) \end{aligned}$$

$$= \frac{b_{j(t+1)} \cdot \beta_{j(t+1)} \cdot a_{ij}}{\beta_{it}}$$

$$(b) \quad P(S_t = i | S_{t+1} = j, o_1, o_2, \dots, o_T)$$

$$= \frac{P(S_{t+1} = j | S_t = i, o_1, o_2, \dots, o_T) P(S_t = i | o_1, o_2, \dots, o_T)}{P(S_{t+1} = j | o_1, o_2, \dots, o_T)}$$

1st term in numerator is from (a), 2nd term is

$$P(S_t = i | O_1, O_2, \dots, O_T) = \frac{P(S_t = i, O_1, O_2, \dots, O_T)}{P(O_1, O_2, \dots, O_T)}$$

$$= \frac{P(S_t = i, O_1, O_2, \dots, O_t) P(O_{t+1}, O_{t+2}, \dots, O_T | S_t = i)}{\sum_{k=1}^N P(S_T = k, O_1, O_2, \dots, O_T)}$$

(P.R., C.I., margln.)

$$= \frac{\alpha_{it} \cdot \beta_{it}}{\sum_{k=1}^n \alpha_{KT}}$$

Similarly, denominator $P(S_{t+1}=j \mid o_1, o_2, \dots, o_T)$

$$= \frac{\alpha_{j(t+1)} \cdot \beta_{j(t+1)}}{\sum_{k=1}^n \alpha_{kT}}$$

So $P(S_t = i | S_{t+1} = j, O_1, O_2, \dots, O_T)$

$$b_{i(t+1)} \cdot \cancel{B_{i(t+1)}} \cdot a_{it} \propto_{it} \cdot \cancel{B_{it}} \quad a_{it} \cdot b_{i(t+1)} \propto_{it}$$

$$= \frac{b_{j(o_{t+1})} \cdot \cancel{\beta_{j(t+1)}} \cdot a_{ij}}{\cancel{\beta_{it}}} \cdot \frac{\alpha_{it} \cdot \cancel{\beta_{it}}}{\alpha_{j(t+1)} \cdot \cancel{\beta_{j(t+1)}}} = \frac{a_{ij} \cdot b_{j(o_{t+1})} \alpha_{it}}{\alpha_{j(t+1)}}$$

$$(c) \quad P(S_{t-1}=i, S_t=j, S_{t+1}=k | O_1, O_2, \dots, O_T)$$

$$= P(S_t=j | O_1, \dots, O_T) P(S_{t-1}=i | S_t=j, O_1, \dots, O_T) P(S_{t+1}=k | S_t=j, \underbrace{S_{t-1}=i}_{\text{P.R., C.I.}}, O_1, \dots, O_T)$$

$$= \frac{\alpha_{jt} \cdot \beta_{jt}}{\sum_{k=1}^n \alpha_{kT}} \cdot \frac{a_{ij} \cdot b_{j(o_t)} \alpha_{i(t-1)}}{\alpha_{jt}} \cdot \frac{b_{k(o_{t+1})} \cdot \beta_{k(t+1)} \cdot a_{jk}}{\beta_{jt}}$$

$$= \frac{a_{ij} \cdot b_{j(o_t)} \cdot \alpha_{i(t-1)} \cdot b_{k(o_{t+1})} \cdot \beta_{k(t+1)} \cdot a_{jk}}{\sum_{k=1}^n \alpha_{kT}}$$

$$(d) \quad \hat{S}_t = \underset{i}{\operatorname{argmax}} \quad P(S_t=i | O_1, O_2, \dots, O_T)$$

$$= \underset{i}{\operatorname{argmax}} \left(\frac{\alpha_{it} \cdot \beta_{it}}{\sum_{k=1}^n \alpha_{kT}} \right) \quad (\text{from prev. step})$$

6.6

(a) No. $\{S_1^*, \dots, S_T^*\}$ is the sequence that

makes $P(S_1, S_2, \dots, S_T | O_1, O_2, \dots, O_T)$ largest.

so $P(\hat{S}_1, \hat{S}_2, \dots, \hat{S}_T | O_1, O_2, \dots, O_T)$ can only be smaller or equal to $P(S_1^*, \dots, S_T^* | O_1, \dots, O_T)$

since $\hat{s}_1, \dots, \hat{s}_T$ are obtained individually.

(b) Yes. As mentioned in (a), it's possible that $\hat{s}_t = \tilde{s}_t^*$ for all t .

(c) No. In most cases, they will not be equal.

(d) Yes. $P(\hat{s}_1, \hat{s}_2, \dots, \hat{s}_T) = \frac{1}{n^T}$ where n is the number of possible values s_t can take, so it always > 0 .