UM-SJTU JOINT INSTITUTE PHYSICS LABORATORY (VP141)

LABORATORY REPORT

Exercise 4
Measurement of the Speed of Sound

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Contents

1	Introduction	1
2	Experimental Setup	1
3	Measurement Procedure3.1 Resonance Method3.2 Phase-comparison Method3.3 Time-difference Method in Liquid	3
4	Results 4.1 Resonance Method	
5	Conclusions and Discussion	6
6	Reference	8
A	Uncertainty Analysis A.1 Uncertainty of Resonance Method	9
В	Data Sheet	9

1 Introduction

The objective of this exercise to study and perform several methods of measuring the speed of sound, including the resonance method, the phase comparison method and the time difference method. How to use a function generator and an oscilloscope will also be explored.

Sound is a mechanical wave. Its phase speed v, frequency f and wavelength λ are related by the formula

$$v = \lambda f. \tag{1}$$

Hence, if the frequency f and wavelength λ of a wave of sound are known, its speed can be calculated.

In this experiment an ultrasonic wave is chosen as the signal source, because its wavelength is short enough to measure the speed of sound precisely. The frequency can be read off from the device directly. Two methods can be utilized to find the wavelength. One is the resonance method. When the distance between two transducers L satisfies

$$L = n\frac{\lambda}{2},\tag{2}$$

where n = 1, 2, ..., the maximum output voltage will be observed. By measuring L we can then obtain the wavelength. The other method is the phase-comparison method. When the distance between two points on the wave is a multiple of the wavelength, *i.e.*

$$L = n\lambda, \tag{3}$$

where n = 1, 2, ..., the two points are of the same phase and the Lissajous figure of them will become a straight line. Hence, if the L where the Lissajous figure shows as a straight line is recorded, the wavelength can be derived.

Alternatively, we know that for motion with constant speed v along a straight line, we have

$$v = \frac{L}{t},\tag{4}$$

where L is the distance travelled over time t. Therefore, by measuring the distance a wavefront travels and the time spent, the speed of the sound wave can also be figured out.

2 Experimental Setup

The main experimental equipment includes a signal source, two piezoelectric transducers S_1 and S_2 , and oscilloscope Figure 1. The frequency of the sound wave is displayed directly in the screen of the oscilloscope. The distance between the two signal sources can be adjusted by the knob on the right and can be measured by the caliper on the device. Basic information about the measurement instruments are summarized in Table 1.

Instrument	Measured quantities	Type-B uncertainties
Oscilloscope	Frequency	$0.001\mathrm{kHz}$
	Time	$0.4\mu\mathrm{s}$
Caliper	Distance	$0.001\mathrm{mm}$
Thermometer	Temperature	1°C

Table 1: Information of measurement instruments.

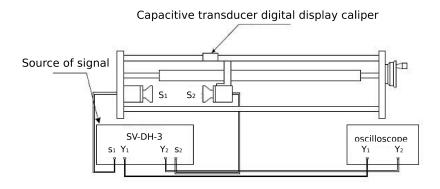


Figure 1: Experimental setup.

3 Measurement Procedure

Caution

- 1. Make sure that S_2 moves in only one direction during each part of the experiment to avoid the backslash error.
- 2. When using the time-difference method, the initial distance between S_1 and S_2 should be greater than 10 cm.
- 3. Prevent metal devices and callipers from contact with water when measuring the speed of sound in water.
- 4. Make sure that the distance between S_1 and S_2 is always greater than 1 cm.

3.1 Resonance Method

In this part, you will adjust the distance between the two sources of signal and record the distance when the output voltage curves displayed on the screen reaches its maximum.

- 1. Set the initial distance between S_1 and S_2 at about 1 cm.
- 2. Turn on the signal source and the oscilloscope. Then set the following options on the panel of the signal source
 - (1) Choose Continuous wave for Method.
 - (2) Adjust Signal Strength until a 10 V peak voltage is observed on the oscilloscope.
 - (3) Adjust Signal Frequency between 34.5 and 40 kHz until the peak-to-peak voltage reaches its maximum. Record the frequency.
- 3. Increase L gradually by moving S_2 , and observe the output voltage of S_2 on the oscilloscope. Record the position of S_2 as L_2 when the output voltage reaches an maximum.
- 4. Repeat step 3 to record 12 values of L_2 and find v by performing a linear fit to the data.

3.2 Phase-comparison Method

In this part, you need to adjust the distance between the two sources of signal and record the distance when the Lissajous figures shown on the screen becomes a straight line.

- 1. Use Lissajous figures to observe the phase difference between the transmitted and the received signals. Move S_2 and record the position when the Lissajous figure becomes a straight line with the same slope.
- 2. Repeat step 1 to collect 12 sets of data and perform a linear fit to find v.

3.3 Time-difference Method in Liquid

In this part, you will set the distance between the two source of signals and then measure the time spent to cover the distance by operating on the panel of the oscilloscope.

- 1. Change the medium to water.
- 2. Adjust the frequency to 100 Hz and the width to 500 μ s.
- 3. Use the cursor function of the oscilloscope to measure the time and the distance between the the starting points of neighboring periods. Record 12 pairs of data and perform a linear fit to $v_{\rm water}$.

4 Results

The measured frequency of the sound wave $f=38.957\,[\mathrm{kHz}]\pm0.001\,[\mathrm{kHz}]$. The measured temperature $T=23\,[^{\circ}\mathrm{C}]\pm1\,[^{\circ}\mathrm{C}]$.

4.1 Resonance Method

The measurement data of the resonance method is presented in Table 2.

L [mn	$n \pm 0.001 [mm]$
1	12.340
2	16.886
3	21.365
4	25.927
5	30.360
6	34.940
7	39.390
8	43.984
9	48.413
10	52.986
11	57.430
12	61.991

Table 2: Measurement data for the resonance method.

Plot L vs. n and apply linear fit using Origin, as is shown in Figure 2. The slope of the fit is $\alpha_1 = 4.511 \, [\text{mm}] = 4.511 \times 10^{-3} \, [\text{m}]$ with uncertainty $u_{\alpha_1} = 0.006 \, [\text{mm}] = 6 \times 10^{-6} \, [\text{m}]$. According to Eq.2, we obtain

$$\lambda = 2\alpha_1$$
.

Combining this result with Eq.1, the speed of sound can be then calculated as

$$v = \lambda f = 2\alpha_1 f = 2 \times 4.511 \times 10^{-3} \times 38.957 \times 10^3 = 351.5 \,[\text{m/s}] \pm 0.5 \,[\text{m/s}].$$
 (5)

with the relative uncertainty 0.13%.

Theoretically, at 20 °C, the speed of sound in air is 344 [m/s]^[2]. The relative difference is then

 $\frac{|351.5 - 344|}{344} \times 100\% = 2.2\,\%.$

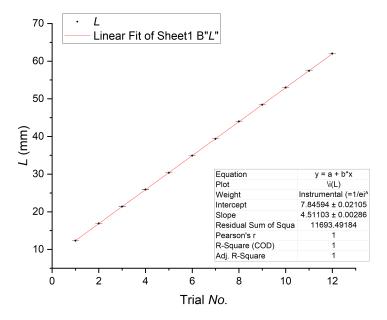


Figure 2: L vs. n for resonance method.

4.2 Phase-comparison Method

The measurement data of the resonance method is presented in Table 3.

Plot L vs. n and apply linear fit using Origin, as is shown in Figure 3. The slope of the fit is $\alpha_2 = 8.981 \, [\mathrm{mm}] = 8.981 \times 10^{-3} \, [\mathrm{m}]$ with uncertainty $u_{\alpha_2} = 0.006 \, [\mathrm{mm}] = 6 \times 10^{-6} \, [\mathrm{m}]$. According to Eq.3, we have

$$\lambda = \alpha_2$$
.

Combining this result with Eq.1, the speed of sound can be then calculated as

$$v = \lambda f = \alpha_2 f = 8.981 \times 10^{-3} \times 38.957 \times 10^3 = 349.9 \,[\text{m/s}] \pm 0.2 \,[\text{m/s}].$$
 (6)

with the relative uncertainty 0.07%.

Theoretically, at $20\,^{\circ}\text{C}$, the speed of sound in air is $344~[\text{m/s}]^{[2]}$. The relative difference is then

$$\frac{|349.9 - 344|}{344} \times 100\% = 1.7\%.$$

L [mm]	$[m] \pm 0.001 $
1	21.330
2	30.321
3	39.323
4	48.350
5	57.318
6	66.321
7	75.298
8	84.236
9	93.229
10	102.210
11	111.133
12	120.139

Table 3: Measurement data for the phase-comparison method.

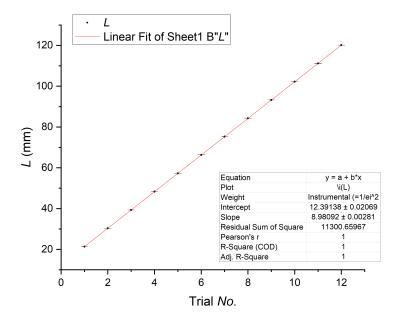


Figure 3: L vs. n for phase-comparison method.

4.3 Time-difference Method

The measurement data of the resonance method is shown in Table 4.

	$L \left[\text{mm} \right] \pm 0.001 \left[\text{mm} \right]$	$t \left[\mu \mathrm{s} \right] \pm 0.4 \left[\mu \mathrm{s} \right]$
1	110.000	81.6
2	120.000	87.6
3	130.000	94.4
4	140.000	100.8
5	150.000	108.0
6	160.000	114.4
7	170.000	121.2
8	180.000	128.0
9	190.000	134.8
10	200.000	141.2
11	210.000	148.0
12	220.000	154.8

Table 4: Measurement data for the time-difference method.

Plot t vs. L and apply linear fit using Origin, as is shown in Figure 4. The slope of the fit is $\alpha_3 = 0.669 \, [\mu \text{s/mm}] = 6.669 \times 10^{-4} \, [\text{s/m}]$ with uncertainty $u_{\alpha_3} = 0.004 \, [\mu \text{s/mm}] = 4 \times 10^{-6} \, [\text{s/m}]$. According to Eq.4, we have

$$v = \frac{1}{\alpha_3} = \frac{1}{6.669 \times 10^{-4}} = 1499 \,[\text{m/s}] \pm 9 \,[\text{m/s}].$$
 (7)

with the relative uncertainty 0.60%.

Theoretically, at 20 °C, the speed of sound in water is 1482 [m/s]^[2]. The relative difference is then

$$\frac{|1499 - 1482|}{1499} \times 100\% = 1.13\,\%.$$

5 Conclusions and Discussion

The results of the above analysis are summarized in Table 5.

	$v[\mathrm{m/s}]$	$u_{v,r}$	$v_{\mathrm{theory}} [\mathrm{m/s}]^{[2]}$	relative error
Resonance(air)	351.5 ± 0.5	0.13%	344	2.2%
Phase-comparison(air)	349.9 ± 0.2	0.07%	344	1.7%
Time-difference (liquid)	1499 ± 9	0.60%	1482	1.13%

Table 5: Experimental and theoretical results.

From Table 5 it can be seen that the results conform to the theoretical and the errors are acceptable. Besides, as can be seen from Figure $2\sim4$, the R-square value r is close enough to 1 to show that the linear fit is rather fitting to the original data points.

Still, some possible reasons of errors are listed in the following:

1. The knob for adjusting the distance is loose, which may rotate after we have adjusted the distance and thus cause error.

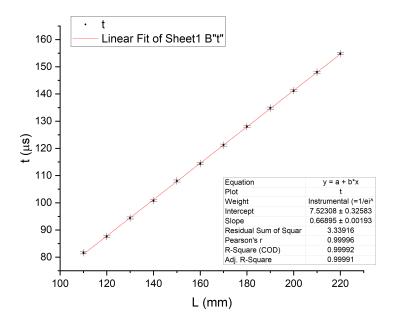


Figure 4: L vs. t.

- 2. The theoretical speed of sound shown in Table 5 is at the temperature of 20° C. In our experiment, however, the temperature is measured to be $23\,[^{\circ}\text{C}] \pm 1\,[^{\circ}\text{C}]$, which is higher than 20° C. The temperature can result in the difference between theoretical values and the experimental results (This is also the reason why we need to measure temperature in our experiment).
- 3. Also, the theoretical speed of sound in water shown is in the conditions of pure water. The water used in our experiment is not pure, which can lead to inaccuracy.
- 4. In the phase-comparison method, we can't make sure that the Lissajous figures become exactly straight lines every time. However, we have already optimize this method by choosing the "straight line" Lissajous figures as reference. It is much easier and can cause less error to judge that the figure forms a straight line than to judge that the figure becomes an ellipse of the same shape and size (and that is the reason why we use the "straight line" Lissajous figures as reference).
- 5. Similarly, in the resonance method, we need to arrive at the maximum of the output voltage showed on the screen, but we can't make sure that we make it exactly at the maximum point. (This is related to the reason why we use the resonance frequency. At resonance frequency, the output voltage will be greater and "steeper", which will thus make it more easier and cause less error to judge whether the output voltage has reached its maximum. Otherwise, the error may become larger.)

Note that there are other operations specified in our experiment which can help reduce the error. For example, in the time-difference method, the L is set to be greater than $100 \, [\mathrm{mm}]$, which ensures that a certain time interval is needed to cover L so that the time interval measured is

not too small and thus the relative error of the measurement of the time interval is relatively small.

We can also see from Table 5 that the resonance method gives the result of medium uncertainty and largest relative error; the phase-comparison method gives the result of least uncertainty and medium relative error; the time-difference method gives the result of greatest uncertainty but with least relative error. With the above analysis of the factors that contribute to error and uncertainty, we can somehow interpret such a comparison of the three methods. The relatively greater uncertainty of time measurement results in the greatest uncertainty of the time-difference method; the maximum output voltage is harder to be judged, which leads to the greatest relative error of the resonance method.

In my opinion, the ideas below may help improve the experiment:

- 1. Wash the container of water. Clean and purify the water in it.
- 2. Keep the room temperature constant at 20° .
- 3. Use devices of higher resolution and sensitivity to make it easier for us to judge whether the output voltage reaches its maximum and whether the Lissajous figures forms a straight line and thus reduce the corresponding error.

6 Reference

- [1] Qin Tian, et al. editor. "VP141 Exercise 4: Measurement of the Speed of Sound".
- [2] Young and Freedman. University Physics with Modern Physics. pp. 516, Table 16.1.

A Uncertainty Analysis

A.1 Uncertainty of Resonance Method

Apply the uncertainty propagation formula to Eq.5,

$$u_v = \sqrt{\left(\frac{\partial v}{\partial \alpha_1}\right)^2 u_{\alpha_1}^2 + \left(\frac{\partial v}{\partial f}\right)^2 u_f^2} = \sqrt{4f^2 u_{\alpha_1}^2 + 4\alpha_1^2 u_f^2} = 0.4676 = 0.5 \,[\text{m/s}],$$

and the relative uncertainty is

$$u_{r,v} = \frac{u_v}{v} \times 100\% = \frac{0.4676}{351.5} \times 100\% = 0.13\%.$$

A.2 Uncertainty of Phase-comparison Method

Apply the uncertainty propagation formula to Eq.6,

$$u_{v} = \sqrt{\left(\frac{\partial v}{\partial \alpha_{2}}\right)^{2} u_{\alpha_{2}}^{2} + \left(\frac{\partial v}{\partial f}\right)^{2} u_{f}^{2}} = \sqrt{f^{2} u_{\alpha_{2}}^{2} + \alpha_{2}^{2} u_{f}^{2}} = 0.2339 = 0.2 \,[\text{m/s}],$$

and the relative uncertainty is

$$u_{r_v} = \frac{u_v}{v} \times 100\% = \frac{0.2339}{349.9} \times 100\% = 0.07\%.$$

A.3 Uncertainty of Time-difference Method

Apply the uncertainty propagation formula to Eq.7,

$$u_v = \sqrt{\left(-\frac{1}{\alpha_3^2}\right)^2 u_{\alpha_3}^2} = \frac{u_{\alpha_3}}{\alpha_3^2} = 8.994 = 9 \,[\text{m/s}],$$

and the relative uncertainty is

$$u_{r_v} = \frac{u_v}{v} \times 100\% = \frac{8.994}{1499} \times 100\% = 0.60\%.$$

B Data Sheet

See the last two pages.

UM-SJTU JOINT INSTITUTE Physics Laboratory Data Sheet (Exercise 4)

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Date: Jun 28, 2019

NOTICE. Please remember to show the data sheet to your instructor before leaving the laboratory. The data sheet will not be accepted if the data are recorded with a pencil or modified with a correction fluid/tape. If a mistake is made in recording a datum item, cancel the wrong value by drawing a fine line through it, record the correct value legibly, and ask your instructor to confirm the correction. Please remember to take a record of the precision of the instruments used. You are required to hand in the original data with your lab report, so please keep the data sheet properly.

Frequency of the sound wave f = 38.95 [FHz] \pm 0.00 [FHz] Temperature T = 23 [$^{\prime}$] \pm 1 [$^{\prime}$ C]

$L_i [\underline{mm} \pm \underline{0.00}] [\underline{m}$	$L_i \left[\underline{mm} \pm \underline{aoo} \right] \left[\underline{mm} \right]$
1 12,340	7 39,390
2 16.886	8 43,984
3 21.365	9 48, 413
4 25,9>7	10 52,986
5 30,360	11 57, 430
6 34,940	12 61.391

Table 1. Data table for the resonance method.

L_i	[mm] ± 0,00 [mm]	L_i	[mm] ± 0,001 [mm]
1	21,330	7	75,298
2	30,321	8	84,236
3	39,323	9	93,229
4	48,350	10	102,210
5	57.318	11	111,133
6	66,321	12	120,139

Table 2. Data table for the phase comparison method.

レースナー	uncertainty	propagation
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	t_i [us] \pm 0.4 [us]	$L_i \left[\underline{mm} \right] \pm \underline{o}_i \underline{o} \underline{o} \left[\underline{mm} \right]$
1	81.bR	110,000
2	87.6a	120,000
3	94,40	130.000
4	100,8	140,000
5	108.0	10,000
6	114.4	160,000
7	121,2	170,000
8	128.0	180,000
9	134.8	190,000
10	141.2	200,000
11	148.0	210,000
12	15-4.8	220,000

Table 3. Data table for the time difference method (liquid).

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