

ECE3073

Looking at example executions

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Two approaches

- Run some uCOS II code under windows and observe the text output from the task executions.
- Use a scheduling simulator to observe the expected execution as a timeline.

Example executions

- Example 1:
- Two timed tasks with specified priorities

Task I

```
//*****  
// TASK:  
//      TaskI  
// DESCRIPTION:  
//      Prints a message with elapsed timer ticks and goes to sleep for 500 msec  
//*****  
void TaskI (void *p_arg){  
    p_arg = p_arg;  
    while (1){  
        OS_Printf("Task I:\t\t Ticks=%d,\t delaying 500 msec\n", OSTimeGet());  
        /* your code here. Create more tasks, etc. */  
        OSTimeDlyHMSM(0, 0, 0, 500);  
    }  
} //TaskI
```

What does the “Task I” do?

- Runs an infinite loop with a time delay and print.

```
//************************************************************************
```

```
// TASK:
```

```
//          StartTask
```

```
// DESCRIPTION:
```

```
//          First task created in app.c.
```

```
//          Creates another task with error checking and then enters an infinite loop. Each loop iteration has a blocking call to OS.
```

```
//          In this case it is OSTimeDlyHMSM.
```

```
//          Prints a message with elapsed timer ticks and goes to sleep for 1 sec
```

```
//************************************************************************
```

```
void StartTask (void *p_arg)
```

```
{
```

```
    INT8U err;
```

```
    p_arg = p_arg; // removes compiler warning of unused p_arg
```

```
#if OS_TASK_STAT_EN > 0
```

```
    OSStatInit();                /* Determine CPU capacity */
```

```
#endif
```

```
    OS_Printf("StartTask:\t %s VERSION %d\n", __FILENAME__, VERSION);
```

```
    OS_Printf("StartTask:\t Creating Task1 with priority %d\n", TASK1_PRIO);
```

```
    err = OSTaskCreateExt(Task1,
```

```
        (void *)0,
```

```
        (OS_STK *)&Task1Stk[TASK_STK_SIZE-1],
```

```
        TASK1_PRIO,
```

```
        TASK1_PRIO,
```

```
        (OS_STK *)&Task1Stk[0],
```

```
        TASK_STK_SIZE,
```

```
        (void *)0,
```

```
        OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR);
```

```
    Perror(err,"ERROR - OSTaskCreate(Task1 ..) failed");// checks err and exits if an error printing message - see app.c
```

```
#endif
```

```
    while (1)                /* Task body, always written as an infinite loop. */
```

```
    {
```

```
        OS_Printf("StartTask:\t Ticks=%d,\t delaying 1 second\n", OSTimeGet());
```

```
        OSTimeDlyHMSM(0, 0, 1, 0);
```

```
    }
```

```
} //StartTask
```

What does the “Start Task” do?

- Creates Task 1 then
- Runs an infinite loop with a time delay and print.

What makes them distinct?

- The time delays and the priorities allocated
- Task 1500msecs
- StartTask1sec
- for version 1same priority!!
- for version 2Task 1 a higher number
- for version 3Task 2 a lower number

Priorities in uCOS II

- The lowest number represents the highest priority
- 0 is the highest and 64 the lowest.
- What priority should we give to the “Idle Task”
- **Always check when looking at a new system!!!**
- The simulator has the highest number as the highest priority.



Predictions for Version 1??

main: Creating StartTask with priority 5
StartTask: example1_tasks.c VERSION 1
StartTask: Creating Task1 with priority 5
Task1: Ticks=?, delaying 500 msec
StartTask: Ticks=?, delaying 1 second

Run it and determine the problem!



Predictions for Version 2?

main: Creating StartTask with priority 5
StartTask: example1_tasks.c VERSION 2
StartTask: Creating Task1 with priority 6
Task1: Ticks=?, delaying 500 msec
StartTask: Ticks=?, delaying 1 second
Task1: Ticks=?, delaying 500 msec
StartTask: Ticks=?, delaying 1 second

The Result for eg1v2

```
Z:\Desktop\Ex1OS\SoftwareForStudents\RealTimeExamplesPDFsEXEs>eg1v2.exe
```

```
main:      Creating StartTask with priority 5
StartTask: example1_tasks.c VERSION 2
StartTask:  Creating Task1 with priority 6
StartTask:  Ticks=1,      delaying 1 second
Task1:      Ticks=1,      delaying 500 msec
Task1:      Ticks=51,     delaying 500 msec
StartTask:  Ticks=101,    delaying 1 second
Task1:      Ticks=101,    delaying 500 msec
Task1:      Ticks=151,    delaying 500 msec
StartTask:  Ticks=201,    delaying 1 second
Task1:      Ticks=201,    delaying 500 msec
Task1:      Ticks=251,    delaying 500 msec
StartTask:  Ticks=301,    delaying 1 second
Task1:      Ticks=301,    delaying 500 msec
Task1:      Ticks=351,    delaying 500 msec
StartTask:  Ticks=401,    delaying 1 second
Task1:      Ticks=401,    delaying 500 msec
```

```
^C
```

SimSo

- Two versions of SimSo
- Download and execute
- Web based
- We will set up the example to mimic what we have just done.

The configuration

Two tasks with StartTask having the higher priority

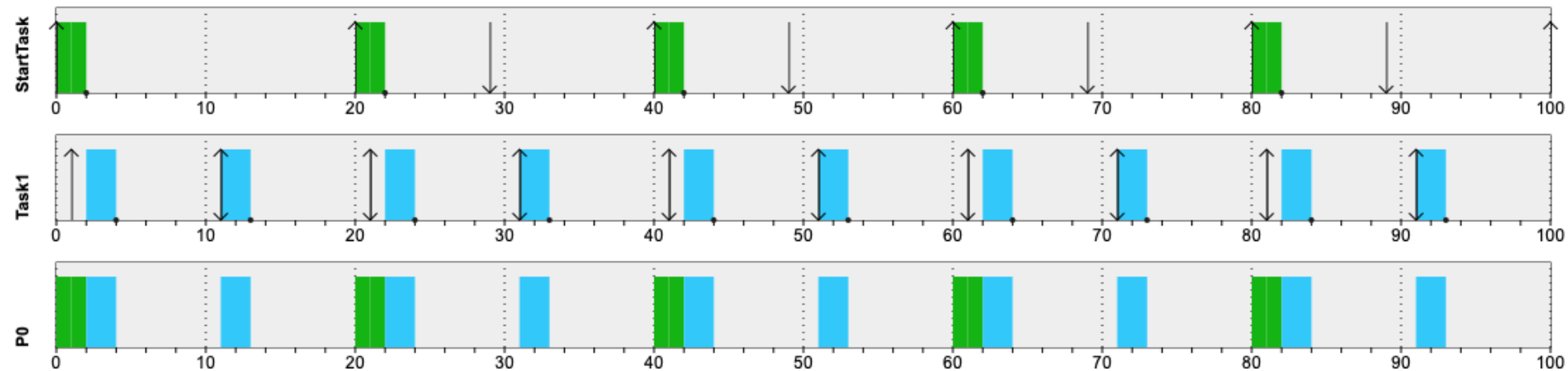
Task I is activated within StartTask so is slightly later to start.

StartTask has twice the delay of Task I

I Processor and fixed priority.

Deadlines same as period

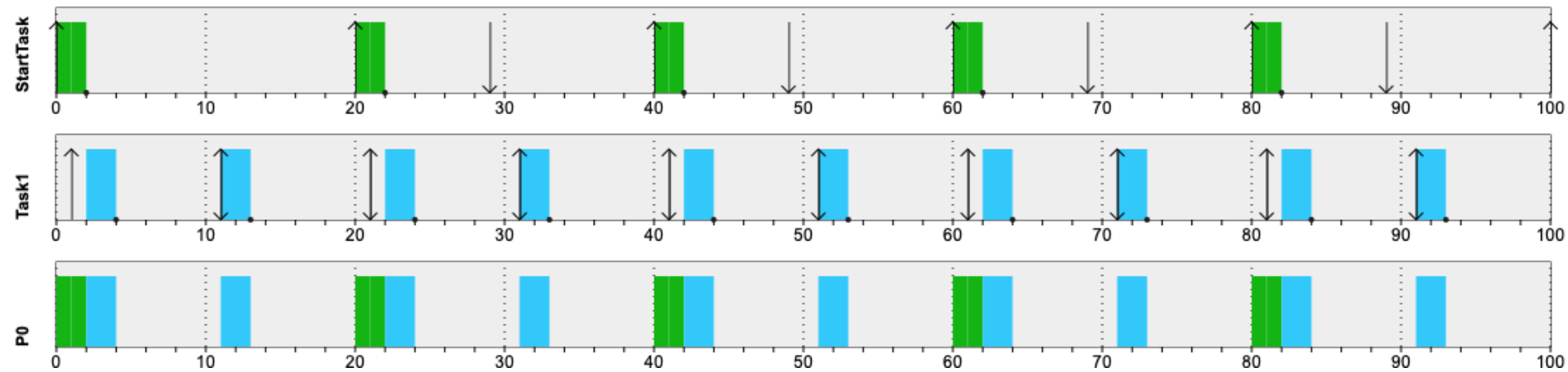
The output from Simso



Are we happy?

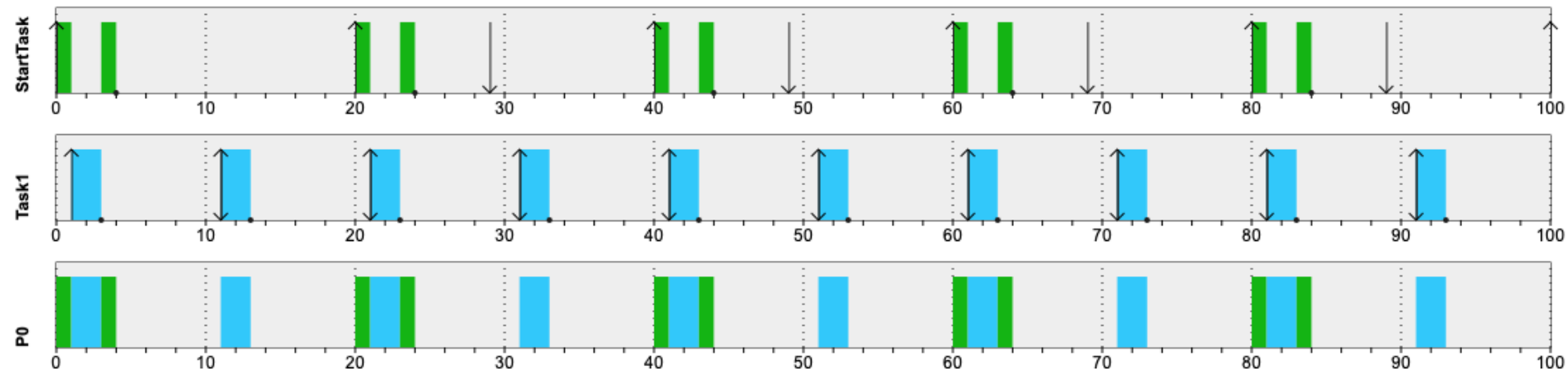
Where did we include our priority settings?

Adding StartTask priority 10 and Task1 priority 5



No change!!

What if we swapped priorities?





Predictions for Version 3?

main: Creating StartTask with priority 5
StartTask: example1_tasks.c VERSION 3
StartTask: Creating Task1 with priority 4
Task1: Ticks=?, delaying 500 msec
StartTask: Ticks=?, delaying 1 second
Task1: Ticks=?, delaying 500 msec
StartTask: Ticks=?, delaying 1 second
Task1: Ticks=?, delaying 500 second

Alternate Predictions for Version3



main: Creating StartTask with priority 5
StartTask: example1_tasks.c VERSION 3
StartTask: Creating Task1 with priority 4
Task1: Ticks=?, delaying 500 msec
StartTask: Ticks=?, delaying 1 second
Task1: Ticks=?, delaying 500 msec
Task1: Ticks=?, delaying 500 msec
StartTask: Ticks=?, delaying 1 second

Where do we go from here?

- SimSo is good for scheduling simulation.
So we will use it for this.
- It does not handle inter task communications.
- BUT that comes a little later.

Example executions

- Example 2:
- Two timed tasks with parameter passing



Predictions ex 2

main: Creating StartTask with priority 5

StartTask: example2_parameterpassing.c VERSION 1

StartTask: Creating Task with priority 6 and parameter 0

StartTask: Creating Task with priority 7 and parameter 1

TaskStart: Ticks=?, still here!

Task0: Ticks=?, still here

Task1: Ticks=?, still here

Task0: Ticks=?, still here

Task1: Ticks=?, still here



Predictions ex 2

main: Creating StartTask with priority 5

StartTask: example2_parameterpassing.c VERSION 2

StartTask: Creating Task with priority 6 and parameter 0

StartTask: Creating Task with priority 7 and parameter 1

TaskStart: Ticks=?, still here!

Task0: Ticks=?, still here

Task1: Ticks=?, still here

Task0: Ticks=?, still here

Task1: Ticks=?, still here



Predictions ex 2

main: Creating StartTask with priority 5

StartTask: example2_parameterpassing.c VERSION 3

StartTask: Creating Task with priority 4 and parameter 0

StartTask: Creating Task with priority 7 and parameter 1

TaskStart: Ticks=?, still here!

Task0: Ticks=?, still here

Task1: Ticks=?, still here

Task0: Ticks=?, still here

Task1: Ticks=?, still here



Predictions ex 2

main: Creating StartTask with priority 5

StartTask: example2_parameterpassing.c VERSION 4

StartTask: Creating Task0 with priority 6 and parameter 0

Task0: Ticks=?, still here

StartTask: Creating Task1 with priority 7 and parameter 1

Task1: Ticks=?, still here

StartTask: Creating Task2 with priority 8 and parameter 2

Task2: Ticks=?, still here

TaskStart: Ticks=?, still here!

Task0: Ticks=?, still here

Task1: Ticks=?, still here

Task2: Ticks=?, still here