

Operating systems (continued)



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- Interprocess communication (IPC): OS provides mechanisms so that processes can pass data.
- Two types of semantics:
- blocking: sending process waits for response;
- non -blocking : sending process continues.



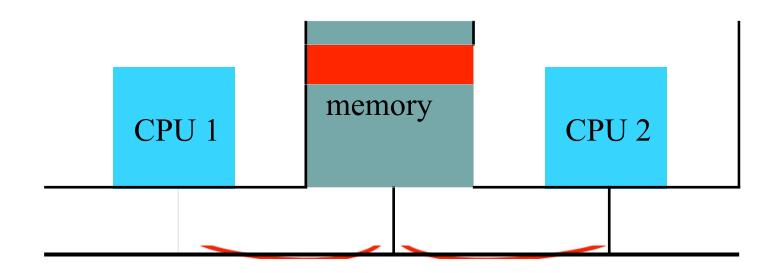


- Shared memory:
 - processes have some memory in common;
 - must cooperate to avoid destroying/missing messages.
- Message passing:
 - processes send messages along a communication channel ---no common address space.





• Shared memory on a bus:



Race condition in shared memory



- Problem when two CPUs try to write the same location:
- CPU 1 reads flag and sees 0.
- CPU 2 reads flag and sees 0.
- CPU 1 sets flag to one and writes location.
- CPU 2 sets flag to one and overwrites location.





- Problem can be solved with an atomic test and set:
 - single bus operation reads memory location, tests it, writes it.
- NIOS- II provides a hardware implementation of an atomic test and set instruction for mutual exclusion implementation in multi - processor system.
- ARM test and set provided by SWP indivisible swap instruction:

```
ADR r0, GATEKEEPER ; r0 gets memory address
LDR r1,#1 ; constant 1 in r1

GETFLAG: SWP r1,r1,[r0] ; r1 < -> GATEKEEPER mem
BNZ GETFLAG ; Zero flag set from memory. Branch Not Z
;If someone beat us (ie already 1), try again
; ie wait for zero to be written when other CPU leaves
; read or write to shared memory here .......

LDR r1, #0 ; finish access by
SWP r1, r1, [r0] ; writing 0 to GATEKEEPER so others allowed access
```





- Critical region : section of code that cannot be interrupted by another process.
- Examples:
- writing shared memory;
- accessing I/O device.
- Looking forward?
- Goto Mutex notes
- Example3_IncDecCS

Semaphores

- Semaphore: OS primitive for controlling access to critical regions and coordinating multiple processes.
- Protocol:
- Get access to semaphore with Wait() called OSSemPend() in uC/OS -II.
- Perform critical region operations.
- Release semaphore with Signal() called OSSemPost() in uC/OS -II.

Invented by Edsger Dijkstra in 1962 and in many references still called PV semaphores taken from the Dutch words for Wait and Signal





- A semaphore consists of its own:
- Counter (unsigned integer)
- Wait function eg OSSemPend()
- Signal function eg OSSemPost()
- Queue of blocked processes waiting for a signal to arrive from another process.





Waiting on a semaphore:

- If (counter > 0) decrements the counter.
- If (counter = 0) block and add caller to queue of blocked processes

Signalling a semaphore reverses a wait:

- If the queue is empty the counter increments.
- Otherwise the highest priority queued process is made ready to run – counter remains 0.





- Processes < > people
- Semaphore < -> meeting place (eg park bench) with a jar of tokens
- Counter < -> number of tokens in jar.
- Wait <-> a person picks up a token or waits in a queue at the bench for a token to arrive.
- Signal < -> person deposits a token and moves away.





Event signalling

Synchronising interprocess data transfer

 Mutual exclusion of processing in critical sections.

Process States with Semaphores



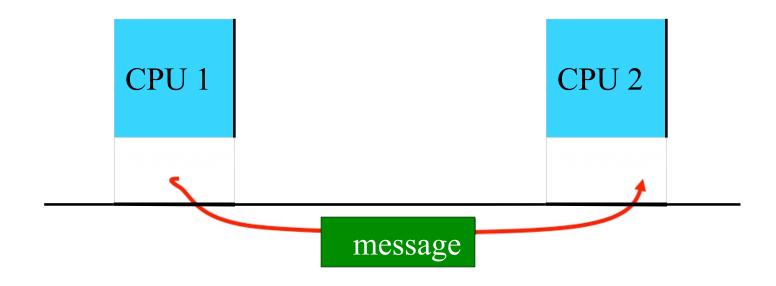
1 Sleep = OSTimeDly() 2 Timer ISR wakes task executing 3 Wait = OSSemPend() Scheduler on 0 semaphore Scheduler 4 Signal=OSSemPost() by a (different & blocked executing) task ready waiting

OSCreateTask()





Message passing on a network:

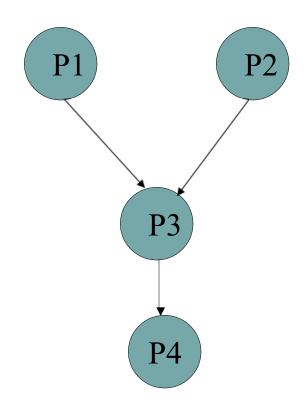


This material has been adapted from chapter 6 slides provided with the textbook by Wolf "Computers as Components: principles of embedded system design" Morgan Kaufmann © .





- One process may not be able to start until another finishes.
- Data dependencies
 defined in a task graph .
- All processes in one task run at the same rate.



Other operating system functions



- Date/time.
- File system.
- Networking.
- Security.