## Lecture 1: Introduction

Xuming He SIST, ShanghaiTech Fall, 2019



### Outline

- Introduction
  - □ What & Why deep learning?
- Course logistics
  - Overall philosophy
  - Grading policy
  - □ Pre-requisite / Syllabus
- Background review



- Our goal: Build intelligent algorithms to make sense of data
  - □ Example: Recognizing objects in images





red panda (Ailurus fulgens)

Example: Predicting what would happen next



Vondrick et al. CVPR2016



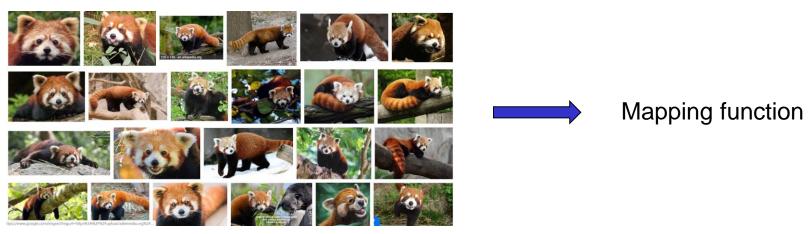
# Introduction

- A broad range of real-world applications
  - ☐ Speech recognition
    - Input: sound wave → Output: transcript
  - □ Language translation
    - Input: text in language A (Eng) → Output: text in language B (Chs)
  - □ Image classification
    - Input: images → Output: image category (cat, dog, car, house, etc.)
  - □ Autonomous driving
    - Input: sensory inputs → Output: actions (straight, left, right, stop, etc.)
- Main challenges: difficult to manually design the algorithms

## A data-driven approach

Each task as a mapping function (or a model)

- □ input data: images
- expected output: object or action names
- Building such mapping functions from data



red panda (Ailurus fulgens)

# A data-driven approach

Building a mapping function (model)

$$y = f(x; \theta)$$

- □ x: input data
- □ y: expected output
- $\square \theta$ : parameters to be estimated

Learning the model from data

- $\square$  Given a dataset  $\mathcal{D} = \{(x_n, y_n)\}_{n=1}^N$
- $\square$  Find the 'best' parameter  $\hat{\theta}$ , such that

$$y_n \simeq f(x_n; \hat{\theta}) \quad \forall n$$

And it can be generalized to unseen input data

# What is deep learning?

- Using deep neural networks as the mapping function
- Deep neural networks
  - A family of parametric models
  - Consisting of many 'simple' computational units
  - □ Constructing a multi-layer representation of input

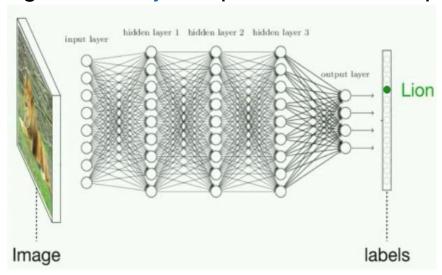
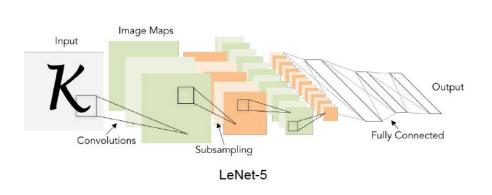


Image from Jeff Clune's Deep Learning Overview

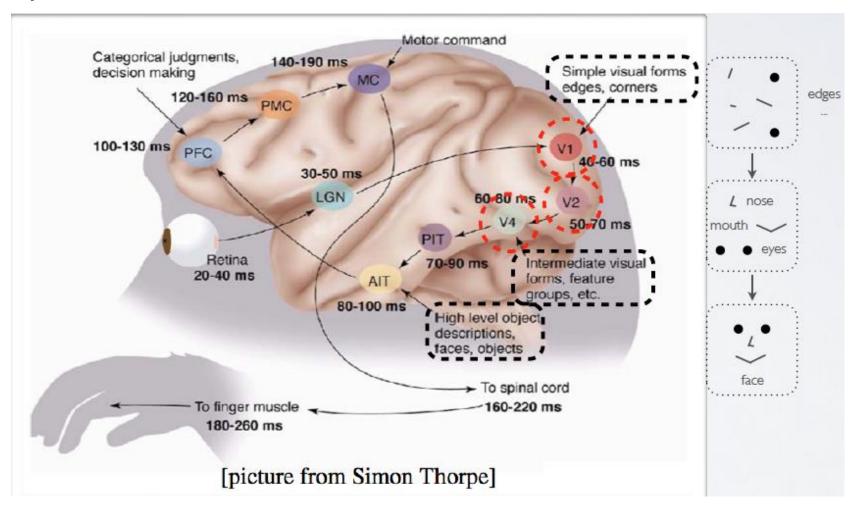
## What is deep learning?

- Using deep neural networks as the mapping function
- Parameter estimation from data
  - □ Parameters: connection weights between units
  - □ Formulated as an optimization problem
  - □ Efficient algorithms for handling large-scale models & datasets



## Why deep networks?

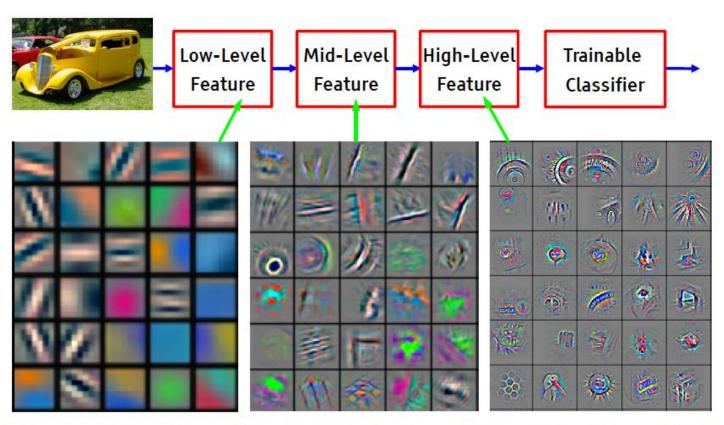
Inspiration from visual cortex



9/10/2019

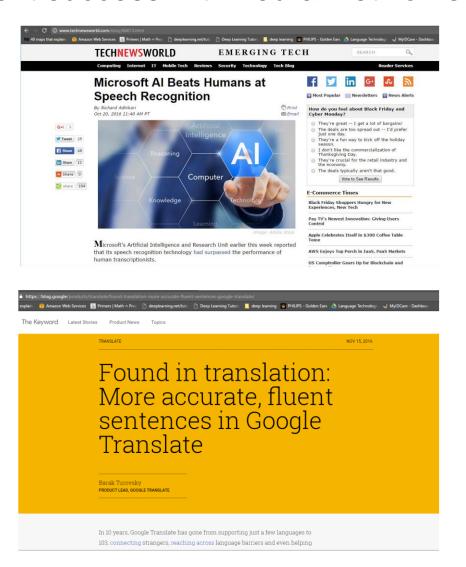
## Why deep networks?

- A deep architecture can represent certain functions (exponentially) more compactly
- Learning a rich representation of input data



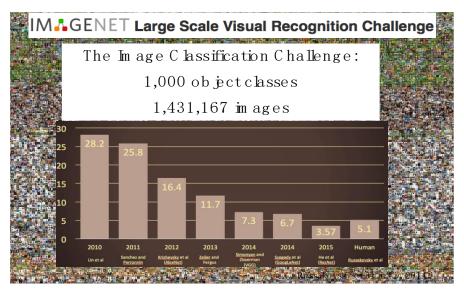
### Recent success with DL

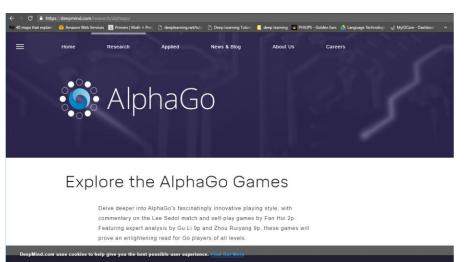
Some recent success with neural networks



### Recent success with DL

Some recent success with neural networks





# Summary: Why deep learning?

- One of the major thrust areas recently in various pattern recognition, prediction and data analysis
  - ☐ Efficient representation of data and computation
  - Other key factors: large datasets and hardware
- The state of the art in many problems
  - Often exceeding previous benchmarks by large margins
  - □ Achieve better performances than human for certain "complex" tasks.
- But also somewhat controversial ...
  - □ Lack of theoretical understanding
  - Sometimes difficult to make it work in practice

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## Is it alchemy?





## Questions behind the scene

- Return of neural networks
  - □ What is different this time?
  - □ How it works for specific problems?
  - □ Why get great performance?
- Future development
  - □ Its limitation and weakness?
  - ☐ The road to general-purpose Al?



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## Course objectives

- Learning to use deep networks
  - □ How to write from scratch, debug and train neural networks
  - Toolboxes commonly used in practice
- Understanding deep models
  - Key concepts and principles
- State of the art
  - Some new topics from research field
  - Focusing on vision-related problems



- Piazza:
  - □ piazza.com/shanghaitech.edu.cn/fall2019/cs280
  - ☐ The schedule for the latter half of the semester may vary a bit
- Part I: Basic neural networks (1~1.5 weeks)
  - Linear models
  - Multiple layer networks
  - Gradient descent and BP
- Part II: Convolutional neural networks
- Part III: Recurrent neural networks/Deep RL
- Part IV: Generative neural networks



- Piazza: <a href="https://piazza.com/shanghaitech.edu.cn/fall2017/cs280/home">https://piazza.com/shanghaitech.edu.cn/fall2017/cs280/home</a>
  - □ The schedule for the latter half of the semester may vary a bit
- Part I: Basic neural networks
- Part II: Convolutional neural networks (4 weeks)
  - CNN basics
  - Understanding CNN
  - CNN in Vision
- Part III: Recurrent neural networks/Deep RL
- Part IV: Generative neural networks



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  - □ The schedule for the latter half of the semester may vary a bit
- Part I: Basic neural networks
- Part II: Convolutional neural networks
- Part III: Recurrent neural networks/Deep RL (4 weeks)
  - □ LSTM, GRU
  - Attention modeling
  - □ RNN in Vision/NLP
  - Deep reinforcement learning
- Part IV: Generative neural networks

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- Piazza: <a href="https://piazza.com/shanghaitech.edu.cn/fall2017/cs280/home">https://piazza.com/shanghaitech.edu.cn/fall2017/cs280/home</a>
  - ☐ The schedule for the latter half of the semester may vary a bit
- Part I: Basic neural networks
- Part II: Convolutional neural networks
- Part III: Recurrent neural networks/Deep RL
- Part IV: Generative neural networks (2.5~3 weeks)
  - Variational Auto Encoder (VAE)
  - □ Generative deep nets (GAN)
  - Sequential generative models
- Note: no lectures in the following weeks
  - □ Oct 28 ~ Nov 1 (ICCV)
  - □ Nov 18 ~ Nov 22 (Tentative)

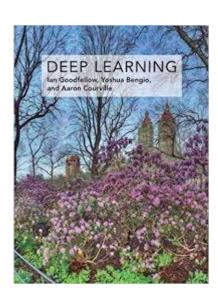


### Textbook and materials

- Deep learning:
  - □ <a href="http://www.deeplearningbook.org/">http://www.deeplearningbook.org/</a>
  - □ <a href="http://neuralnetworksanddeeplearning.com/">http://neuralnetworksanddeeplearning.com/</a>
- Online deep learning courses:
  - □ Stanford: CS230, CS231n
  - □ CMU: 11-785
  - MIT: 6.S191



Survey papers, tutorials, etc.





### Instructor and TAs

- Instructor: Me
  - hexm at shanghaitech
  - □ SIST 1A-304D
- TAs (tentative):
  - □ Rongjie Li
  - □ Shuailin Li
  - □ ... will be finalized next week
- Office hours: on Piazza
- We will use Piazza as the communication platform

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## Grading policy

- 3 Problem sets: 15% x 3 = 45%
  - □ Write-up problem sets + Programming tasks
- Final course project: 35%(+10%)
  - □ Proposal: 5%
  - ☐ Final report (CVPR format): 25%
  - □ Presentation: 5%
  - Bonus points for novel results: 10%
- 10 Quizzes (in class): 2% x 10 = 20%
- Late policy
  - 25% off per day late
  - Not accepted after 3 late days
  - Does not apply to Final course project/Quizzes
- Collaboration policy
  - □ Project team: at most 3 students
  - Grading according to each member's contribution



## Pre-requisite

- Proficiency in Python
  - All class assignments will be in Python (and use numpy)
  - □ A Python tutorial available on Piazza
- Calculus, Linear Algebra, Probability and Statistics
  - Undergrad course level
- Equivalent knowledge of Andrew Ng's CS229 (Machine Learning)
  - Formulating cost functions
  - Taking derivatives
  - Performing optimization with gradient descent
- Will be evaluated in next quiz (Thurday)



### **Outline**

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- Background review
  - ☐ Machine learning basics

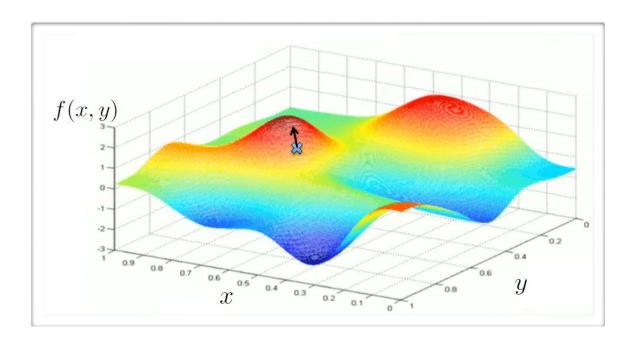
Acknowledgement: Hugo Larochelle's, Mehryar Mohri@NYU's & Yingyu Liang@Princeton's course notes



### Math review - Calculus

### Gradient

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = \left[ \frac{\partial}{\partial x_1} f(\mathbf{x}), \cdots, \frac{\partial}{\partial x_d} f(\mathbf{x}) \right]^{\mathsf{T}} = \begin{bmatrix} \frac{\partial}{\partial x_1} f(\mathbf{x}) \\ \vdots \\ \frac{\partial}{\partial x_d} f(\mathbf{x}) \end{bmatrix}$$



## Math review - Calculus

#### Hessian and Jacobian

• Hessian: 
$$\nabla_{\mathbf{x}}^{2} f(\mathbf{x}) = \begin{bmatrix} \frac{\partial^{2}}{\partial x_{1}^{2}} f(\mathbf{x}) & \dots & \frac{\partial^{2}}{\partial x_{1} \partial x_{d}} f(\mathbf{x}) \\ \vdots & \dots & \vdots \\ \frac{\partial^{2}}{\partial x_{d} \partial x_{1}} f(\mathbf{x}) & \dots & \frac{\partial^{2}}{\partial x_{d}^{2}} f(\mathbf{X}) \end{bmatrix}$$
• If  $\mathbf{f}(\mathbf{x}) = [f(\mathbf{x})_{1}, \dots, f(\mathbf{x})_{k}]^{\top}$  is a vector, the Jacobian is: 
$$\nabla_{\mathbf{x}} \mathbf{f}(\mathbf{x}) = \begin{bmatrix} \frac{\partial}{\partial x_{1}} f(\mathbf{x})_{1} & \dots & \frac{\partial}{\partial x_{d}} f(\mathbf{x})_{1} \\ \vdots & \dots & \vdots \\ \frac{\partial}{\partial x_{1}} f(\mathbf{x})_{k} & \dots & \frac{\partial}{\partial x_{d}} f(\mathbf{x})_{k} \end{bmatrix}$$



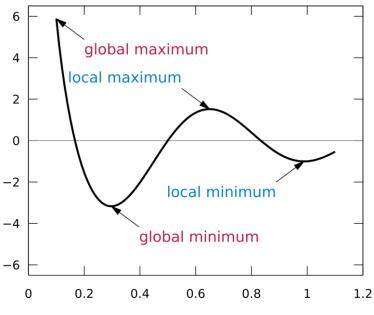
## Math review – Calculus

- Local and global minima
  - Necessary condition

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = 0$$

- Sufficient condition
  - Hessian is positive definite

$$f(\mathbf{x}) \approx f(\mathbf{x}^*) + (\mathbf{x} - \mathbf{x}^*)^{\mathsf{T}} \nabla_{\mathbf{x}} f(\mathbf{x}) + \frac{1}{2} (\mathbf{x} - \mathbf{x}^*)^{\mathsf{T}} \nabla_{\mathbf{x}}^2 f(\mathbf{x}) (\mathbf{x} - \mathbf{x}^*)$$





## Math review – Probability

#### Factorization

- Probability chain rule: p(s,o) = p(s|o)p(o) = p(o|s)p(s)
  - in general:

$$p(\mathbf{x}) = \prod_{i} p(x_i | x_1, \dots, x_{i-1})$$

• Bayes rule:

$$p(O = o|S = s) = \frac{p(S=s|O=o)p(O=o)}{\sum_{o'} p(S=s|O=o')p(O=o')}$$

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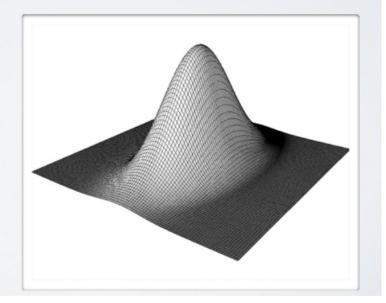
# Math review - Probability

### Common distributions

• Gaussian variable:  $\mathbf{X} \in \mathbb{R}^d$ 

$$p(\mathbf{x}) = \frac{1}{\sqrt{(2\pi)^d \det(\Sigma)}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^{\top} \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)$$

- $\mathbf{E}[\mathbf{X}] = \boldsymbol{\mu}$
- $\operatorname{Cov}[\mathbf{X}] = \Sigma$





### Math review – Statistics

#### Monte Carlo estimation

a method to approximate an expensive expectation

$$E[f(\mathbf{X})] = \sum_{\mathbf{x}} f(\mathbf{x}) p(\mathbf{x}) \approx \frac{1}{K} \sum_{k} f(\mathbf{x}^{(k)})$$

• the  $\mathbf{x}^{(k)}$  must be sampled from  $p(\mathbf{x})$ 

#### Maximum likelihood

$$\widehat{\theta} = \arg\max_{\theta} p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(T)})$$

Independent and identically distributed

$$p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(T)}) = \prod_{t} p(\mathbf{x}^{(t)})$$



### ML tasks

- Classification: assign a category to each item (e.g., document classification)
- Regression: predict a real value for each item (e.g., prediction of stock values, economic variables)
- Ranking: order items according to some criterion (e.g., relevant web pages returned by a search engine)
- Clustering: partition data into 'homogenous' regions (e.g., analysis of very large data sets)
- Dimensionality reduction: find lower-dimensional manifold preserving some properties of the data

## Example 1: image classification



Task: determine if the image is indoor or outdoor Performance measure: probability of misclassification

## Example2: clustering images



Task: partition the images into 2 groups Performance: similarities within groups

Data: a set of images

## Standard learning scenarios

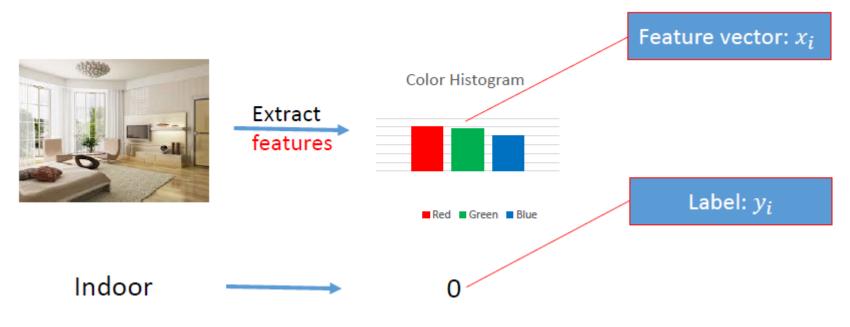
- Unsupervised learning: no labeled data
- Supervised learning: uses labeled data for prediction on unseen points
- Semi-supervised learning: uses labeled and unlabeled data for prediction on unseen points
- Reinforcement learning: uses reward to learn prediction on action policies.
- **...**

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## Supervised learning

#### Task formulation

- Learning example:  $(\mathbf{x}, y)$
- ullet Task to solve: predict target y from input  ${f x}$ 
  - classification: target is a class ID (from 0 to nb. of class 1)
  - regression: target is a real number





## Supervised learning

#### Task formulation

- Learning example:  $(\mathbf{x}, y)$
- ullet Task to solve: predict target y from input  ${f x}$ 
  - classification: target is a class ID (from 0 to nb. of class 1)
  - regression: target is a real number





#### Problem setup

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$
- Find y = f(x) using training data
- s.t. f correct on test data

What kind of functions?



#### Problem setup

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$
- Find  $y = f(x) \in \mathcal{H}$  using training data
- s.t. f correct on test data

Hypothesis class



#### Problem setup

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$
- Find  $y = f(x) \in \mathcal{H}$  using training data
- s.t. f correct on test data

Connection between training data and test data?



#### Problem setup

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $y = f(x) \in \mathcal{H}$  using training data
- s.t. f correct on test data i.i.d. from distribution D

They have the same distribution

i.i.d.: independently identically distributed



#### Problem setup

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $y = f(x) \in \mathcal{H}$  using training data
- s.t. f correct on test data i.i.d. from distribution D

What kind of performance measure?



#### Problem setup

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $y = f(x) \in \mathcal{H}$  using training data
- s.t. the expected loss is small

$$L(f) = \mathbb{E}_{(x,y) \sim D}[l(f,x,y)] -$$

Various loss functions



#### Problem setup

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $y = f(x) \in \mathcal{H}$  using training data
- s.t. the expected loss is small

$$L(f) = \mathbb{E}_{(x,y) \sim D}[l(f, x, y)]$$

- Examples of loss functions:
  - 0-1 loss:  $l(f, x, y) = \mathbb{I}[f(x) \neq y]$  and  $L(f) = \Pr[f(x) \neq y]$
  - $l_2$  loss:  $l(f, x, y) = [f(x) y]^2$  and  $L(f) = \mathbb{E}[f(x) y]^2$



#### Problem setup

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $y = f(x) \in \mathcal{H}$  using training data
- s.t. the expected loss is small

$$L(f) = \mathbb{E}_{(x,y) \sim D}[l(f,x,y)]$$

How to use?



#### Problem setup

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $y = f(x) \in \mathcal{H}$  that minimizes  $\hat{L}(f) = \frac{1}{n} \sum_{i=1}^{n} l(f, x_i, y_i)$
- s.t. the expected loss is small

$$L(f) = \mathbb{E}_{(x,y) \sim D}[l(f,x,y)]$$

**Empirical loss** 



### Supervised learning pipeline

#### Three steps

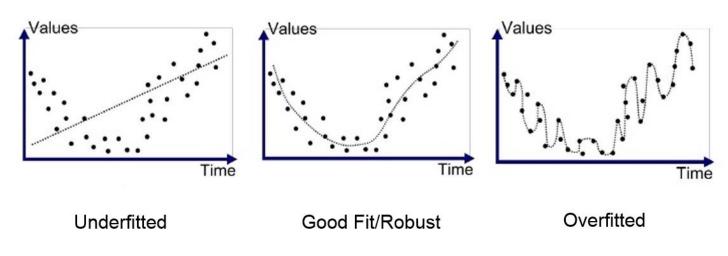
- Collect data and extract features
- Build model: choose hypothesis class  $m{\mathcal{H}}$  and loss function l
- Optimization: minimize the empirical loss

#### Datasets & hyper-parameters

- Hyper-parameter: a parameter of a model that is not trained (specified before training)
  - ullet Training set  $\mathcal{D}^{\mathrm{train}}$  serves to train a model
  - ullet Validation set  $\mathcal{D}^{\mathrm{valid}}$  serves to select hyper-parameters
  - Test set  $\mathcal{D}^{\mathrm{test}}$  serves to estimate the generalization performance (error)

## Generalization

- Model selection for better generalization
  - Capacity: flexibility of a model
  - Underfitting: state of model which could improve generalization with more training or capacity
  - Overfitting: state of model which could improve generalization with less training or capacity
  - Model Selection: process of choosing the best hyper-parameters on validation set



#### Generalization

#### Training/Validation curves





#### Questions

- Generalization
  - Interaction between training set size/capacity/training time and training error/generalization error
- If capacity increases:
  - □ Training error will ?
  - □ Generalization error will?
- If training time increases:
  - □ Training error will ?
  - □ Generalization error will ?
- If training set size increases:
  - □ Generalization error will?
  - Gap between the training and generalization error will ?



#### Formulation

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $f_{w}(x) = w^{T}x$  that minimizes  $\hat{L}(f_{w}) = \frac{1}{n}\sum_{i=1}^{n}(w^{T}x_{i} y_{i})^{2}$

l<sub>2</sub> loss; also called mean square error

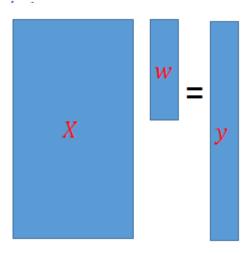
Hypothesis class  ${m {\mathcal H}}$ 



#### Optimization

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $f_w(x) = w^T x$  that minimizes  $\hat{L}(f_w) = \frac{1}{n} \sum_{i=1}^n (w^T x_i y_i)^2$
- Let X be a matrix whose i-th row is  $x_i^T$ , y be the vector  $(y_1, ..., y_n)^T$

$$\widehat{L}(f_w) = \frac{1}{n} \sum_{i=1}^{n} (w^T x_i - y_i)^2 = \frac{1}{n} ||Xw - y||_2^2$$





#### Optimization

Set the gradient to 0 to get the minimizer

$$\nabla_{w} \hat{L}(f_{w}) = \nabla_{w} \frac{1}{n} ||Xw - y||_{2}^{2} = 0$$

$$\nabla_{w} [(Xw - y)^{T} (Xw - y)] = 0$$

$$\nabla_{w} [w^{T} X^{T} X w - 2w^{T} X^{T} y + y^{T} y] = 0$$

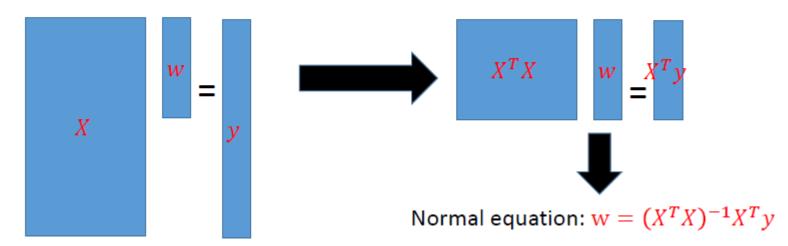
$$2X^{T} X w - 2X^{T} y = 0$$

$$w = (X^{T} X)^{-1} X^{T} y$$



#### Optimization

- Algebraic view of the minimizer
  - If X is invertible, just solve Xw = y and get  $w = X^{-1}y$
  - But typically X is a tall matrix



What if not invertible?



#### With bias term

Bias term

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $f_{w,b}(x) = w^T x + b$  to minimize the loss
- Reduce to the case without bias:
  - Let w' = [w; b], x' = [x; 1]
  - Then  $f_{w,b}(x) = w^T x + b = (w')^T (x')$



#### ■ Why l<sub>2</sub> loss?

- Why not choose another loss
  - $l_1$  loss, hinge loss, exponential loss, ...
- Empirical: easy to optimize
  - For linear case:  $\mathbf{w} = (X^T X)^{-1} X^T y$
- Theoretical: a way to encode prior knowledge

#### Questions:

- What kind of prior knowledge?
- Principal way to derive loss?



- Maximum likelihood estimation (MLE)
  - Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
  - Let  $\{P_{\theta}(x,y): \theta \in \Theta\}$  be a family of distributions indexed by  $\theta$
  - Would like to pick  $\theta$  so that  $P_{\theta}(x, y)$  fits the data well



- Maximum likelihood estimation (MLE)
  - Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
  - Let  $\{P_{\theta}(x,y): \theta \in \Theta\}$  be a family of distributions indexed by  $\theta$
  - "fitness" of  $\theta$  to one data point  $(x_i, y_i)$ likelihood $(\theta; x_i, y_i) := P_{\theta}(x_i, y_i)$



- Maximum likelihood estimation (MLE)
  - Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
  - Let  $\{P_{\theta}(x,y): \theta \in \Theta\}$  be a family of distributions indexed by  $\theta$
  - "fitness" of  $\theta$  to i.i.d. data points  $\{(x_i, y_i)\}$ likelihood $(\theta; \{x_i, y_i\}) := P_{\theta}(\{x_i, y_i\}) = \prod_i P_{\theta}(x_i, y_i)$



- Maximum likelihood estimation (MLE)
  - Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
  - Let  $\{P_{\theta}(x,y): \theta \in \Theta\}$  be a family of distributions indexed by  $\theta$
  - MLE: maximize "fitness" of  $\theta$  to i.i.d. data points  $\{(x_i, y_i)\}$  $\theta_{ML} = \operatorname{argmax}_{\theta \in \Theta} \prod_i P_{\theta}(x_i, y_i)$



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  - Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
  - Let  $\{P_{\theta}(x,y): \theta \in \Theta\}$  be a family of distributions indexed by  $\theta$
  - MLE: maximize "fitness" of  $\theta$  to i.i.d. data points  $\{(x_i, y_i)\}$

```
\theta_{ML} = \operatorname{argmax}_{\theta \in \Theta} \log[\prod_{i} P_{\theta}(x_i, y_i)]
```

 $\theta_{ML} = \operatorname{argmax}_{\theta \in \Theta} \sum_{i} \log[P_{\theta}(x_i, y_i)]$ 



- Maximum likelihood estimation (MLE)
  - Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
  - Let  $\{P_{\theta}(x,y): \theta \in \Theta\}$  be a family of distributions indexed by  $\theta$
  - MLE: negative log-likelihood loss

$$\theta_{ML} = \operatorname{argmax}_{\theta \in \Theta} \sum_{i} \log(P_{\theta}(x_{i}, y_{i}))$$
$$l(P_{\theta}, x_{i}, y_{i}) = -\log(P_{\theta}(x_{i}, y_{i}))$$
$$\hat{L}(P_{\theta}) = -\sum_{i} \log(P_{\theta}(x_{i}, y_{i}))$$



- MLE: conditional log-likelihood
  - Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
  - Let  $\{P_{\theta}(y|x): \theta \in \Theta\}$  be a family of distributions indexed by  $\theta$
  - MLE: negative conditional log-likelihood loss

$$\theta_{ML} = \operatorname{argmax}_{\theta \in \Theta} \sum_{i} \log(P_{\theta}(y_i|x_i))$$

$$l(P_{\theta}, x_i, y_i) = -\log(P_{\theta}(y_i|x_i))$$
  
$$\hat{L}(P_{\theta}) = -\sum_i \log(P_{\theta}(y_i|x_i))$$

Only care about predicting y from x; do not care about p(x)



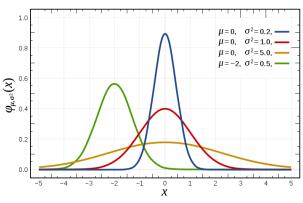
## MLE example: Regression

#### Regression with I2 Loss

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $f_{\theta}(x)$  that minimizes  $\hat{L}(f_{\theta}) = \frac{1}{n} \sum_{i=1}^{n} (f_{\theta}(x_i) y_i)^2$

 $l_2$  loss: Normal + MLE

- Define  $P_{\theta}(y|x) = \text{Normal}(y; f_{\theta}(x), \sigma^2)$
- $\log(P_{\theta}(y_i|x_i)) = \frac{-1}{2\sigma^2}(f_{\theta}(x_i) y_i)^2 \log(\sigma) \frac{1}{2}\log(2\pi)$
- $\theta_{ML} = \operatorname{argmin}_{\theta \in \Theta} \frac{1}{n} \sum_{i=1}^{n} (f_{\theta}(x_i) y_i)^2$

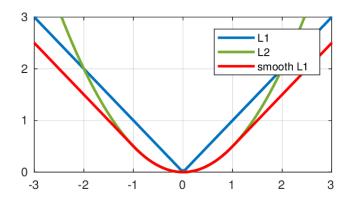




#### **Outliers**

- L2 loss = Gaussian distribution
- What if we have outliers?
  - □ Some data points lie far away from the linear structure
- Robust estimation
  - L1 loss: Laplace distribution

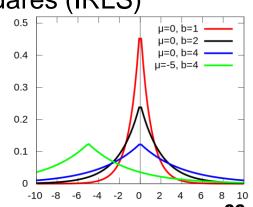
$$\hat{L}(f_w) = \frac{1}{n} \sum_{i=1}^{n} |w^{\mathsf{T}} x_i - y_i|$$



Optimization: iteratively reweighted least squares (IRLS)

$$\beta_i^{(0)} = 1, \quad \beta_i^{(t)} = \frac{1}{|w^{(t)}|^{\mathsf{T}} x_i - y_i|}$$

$$w^{(t+1)} = \arg\min_{w} \frac{1}{n} \sum_{i=1}^{n} \beta_i^{(t)} \|w^{\mathsf{T}} x_i - y_i\|^2$$





#### Generalization

- Overfitting or under-determined?
  - □ Ridge regression

$$\hat{L}(f_w) = \frac{1}{n} \sum_{i=1}^n \|w^{\mathsf{T}} x_i - y_i\|^2 + \lambda \sum_{j=1}^d w_j^2$$

- The optimal weights  $w^* = (X^\intercal X + \lambda I)^{-1} X^\intercal Y$
- □ Lasso regression

$$\hat{L}(f_w) = \frac{1}{n} \sum_{i=1}^n \|w^{\mathsf{T}} x_i - y_i\|^2 + \lambda \sum_{j=1}^d |w_j|$$

- Convex optimization: proximal gradient descent
- $\ \square$  The hyper-parameter  $\lambda$  controls the model complexity



## Summary

- Introduction to deep learning
- Course logistics
- Review of basic math & ML
- Next time
  - Basic neural networks
  - □ First Quiz on prerequisite