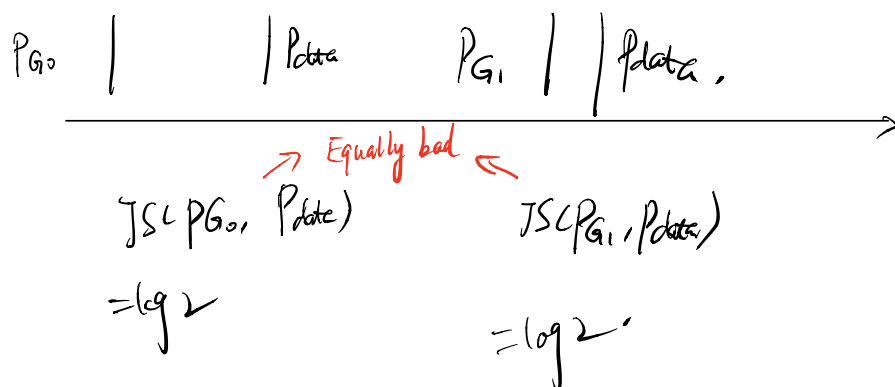


JSD 的问题, 往往 P_G 和 P_{data} 没有重合

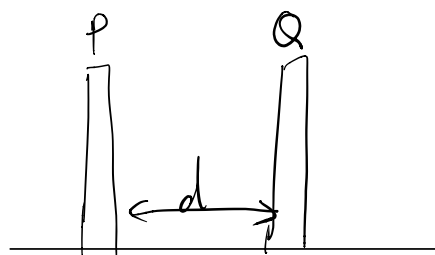
JSD is $\log 2$ if two distributions do not overlap



\Rightarrow Same objective value is obtained 不容易得到 G' !

WGAN.

把 JSD 换成 Earth Mover's Distance



$$W(P, Q) = d$$

$P_{G_0} \parallel \parallel P_{data}$

$$W(P_{G_0}, P_{data}) \\ = d_0$$

$P_{G_{50}} \parallel \parallel P_{data}$

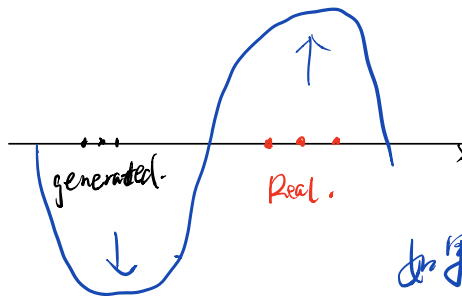
$$W(P_{G_{50}}, P_{data}) \\ = d_{50}$$

如何修改 discriminator ?

$$V(G, D) = \max_{D \in \text{Lipschitz}} \{ \overset{\uparrow}{\mathbb{E}_{P_{data}} [D(x)]} - \overset{\downarrow}{\mathbb{E}_{P_G} [D(x)]} \}$$

D has to be smooth enough

(对于 JSD, D 距离是有 \log 的)



如果不加限制, 会趋于无穷大

Lip schitz - Function: $\|f(x_1) - f(x_2)\| \leq k \|x_1 - x_2\|$

$k=1$ for 1-Lipschitz

实际中快速 D weight clipping

if $w > c, w = c$

if $w < -c, w = -c$

② WGAN-GP

$D \in \text{Lipschitz} \Leftrightarrow \|\nabla_x D(x)\| \leq 1$ for all x

$$V(G, D) = \max_D [E_{x \sim p_{data}} [D(x)] - E_{x \sim p_g} [D(x)]]$$

$$- \lambda \int_{\mathcal{X}} \max(0, \|\nabla_x D(x)\| - 1) dx$$

↓

$$E_{x \sim p_{data}} [\max(0, \|\nabla_x D(x)\| - 1)]^2$$

↓

$$(\|\nabla_x D(x)\| - 1)^2$$

Algorithm of Original GAN

• In each training iteration:

- Sample m examples $\{x^1, x^2, \dots, x^m\}$ from data distribution $p_{data}(x)$
- Sample m noise samples $\{z^1, z^2, \dots, z^m\}$ from the prior $p_{prior}(z)$
- Learning D
 - Obtaining generated data $\{\tilde{x}^1, \tilde{x}^2, \dots, \tilde{x}^m\}, \tilde{x}^i = G(z^i)$
 - Update discriminator parameters θ_d to maximize
 - $\tilde{V} = \frac{1}{m} \sum_{i=1}^m \log D(x^i) + \frac{1}{m} \sum_{i=1}^m \log (1 - D(\tilde{x}^i))$
 - $\theta_d \leftarrow \theta_d + \eta \nabla \tilde{V}(\theta_d)$
- Repeat k times
- Learning G
 - Sample another m noise samples $\{z^1, z^2, \dots, z^m\}$ from the prior $p_{prior}(z)$
 - Update generator parameters θ_g to minimize
 - $\tilde{V} = \frac{1}{m} \sum_{i=1}^m \log D(x^i) + \frac{1}{m} \sum_{i=1}^m \log (1 - D(G(z^i)))$
 - $\theta_g \leftarrow \theta_g - \eta \nabla \tilde{V}(\theta_g)$

Algorithm of WGAN

- In each training iteration: **No sigmoid for the output of D**
 - Sample m examples $\{x^1, x^2, \dots, x^m\}$ from data distribution $P_{data}(x)$
 - Sample m noise samples $\{z^1, z^2, \dots, z^m\}$ from the prior $P_{prior}(z)$
 - Obtaining generated data $\{\tilde{x}^1, \tilde{x}^2, \dots, \tilde{x}^m\}$, $\tilde{x}^i = G(z^i)$
 - Update discriminator parameters θ_d to maximize
 - $\tilde{V} = \frac{1}{m} \sum_{i=1}^m D(x^i) - \frac{1}{m} \sum_{i=1}^m D(\tilde{x}^i)$
 - $\theta_d \leftarrow \theta_d + \eta \nabla \tilde{V}(\theta_d)$ **Weight clipping / Gradient Penalty ...**
 - Sample another m noise samples $\{z^1, z^2, \dots, z^m\}$ from the prior $P_{prior}(z)$
 - Update generator parameters θ_g to minimize
 - ~~$\tilde{V} = \frac{1}{m} \sum_{i=1}^m \log D(x^i) - \frac{1}{m} \sum_{i=1}^m \log D(G(z^i))$~~ **$\tilde{V} = \frac{1}{m} \sum_{i=1}^m D(x^i) - \frac{1}{m} \sum_{i=1}^m D(G(z^i))$**
 - $\theta_g \leftarrow \theta_g - \eta \nabla \tilde{V}(\theta_g)$

Learning
D

Repeat
k times

Learning
G

Only
Once

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