

Panfeng Jiang

✉ jiangpf2022@berkeley.edu

✉ jiangpf2022@shanghaitech.edu.cn

Research Interests: Computer Vision, SLAM, Machine Learning, Artificial Intelligence

Education

- 2024.8 – 2025.6
- University of California, Berkeley (GPA:3.957/4.0)
 - Concurrent International in GLOBE program. Major: Computer Science.
- 2022 – present
- ShanghaiTech University (GPA:3.77/4.0)
 - Matriculated Undergraduate. Major: Computer Science. Minor: Mathematics and Applied Mathematic (**Ranking 8%-15%** in SIST College in the comprehensive evaluation)

Research Publications

- 1 S. Hang, L. Tao, **Panfeng. Jiang**, G. Ling, and K. Laurent, “Led matrix-based simultaneous localization and data transmission with an event camera,” (*Still Modifying*), 2023.
- Develop the detection part and new modules for event-based localization, spatiotemporal tracking, and real-time decoding.
 - Participated in the process of encoding-decoding, tracking algorithm designing and experimental testing.
 - Our efforts highlighted the practical advantages of our solution by using event-based camera, particularly in achieving 64 Kbps of bandwidth and centimeter-level positioning accuracy, beyond the capabilities of CMOS cameras.

Research Experiences

- 2023.4 – present
- Mobile Perception Lab
 - Research Advisor: Prof.Laurent Kneip, ShanghaiTech University


Relevant Course Projects

- Computer Vision
- Disentangling Object Motion for Self-supervised Depth Estimation(Self-supervised depth estimation heavily suffers from the mismatch of the photometric consistency caused by moving objects. And we trying to mitigate the negative impact caused by this.)
- SLAM
- Instance-level Object Pose Estimation with an Event Camera(Event camera is able to track fast object motion, and based on this advantage, I am going to track the 6DoF object motion given the object CAD model by using convex-hull detected and ICP algorithm based methods.)
 - Toy realization of Ordinary& Scale-aware & Jump-aware Pose Graph Optimization,Visual Odometry, Particle Filter and Five-point Minimal Solver for Event Camera Relative Motion Estimation.
- Machine Learning
- Use multiple models for quality prediction (discuss the advantages and disadvantages of logistic regression, random forest, XGBoost models, and combine principal component analysis and Huber Loss for model performance optimization)





Working Experiences and Social Participation

- 2024.11
- Served as a **staff, referee** in Rubik’s Cube competitions(Bay Area Speedcubin’ 65 - Berkeley 2024, Berkeley Fall 2024, Berkeley October Weekday Tricubealon 2024, Cool Down Berkeley 2024.)
- 2023.12
- Served as a **referee** in Changsha Rubik’s Cube Open 2023
- 2023.8-11
- Served as a **volunteer** in the summer camp of ShanghaiTech University , Shanghai Planetarium , Shanghai Library and the 27.5km mark of the 2023 Shanghai Marathon

Working Experiences and Social Participation (continued)


2023.7 – 2023.8  Served as a **teaching assistant** in the New Oriental TOEFL course, responsible for course quality supervision and feedback, after-class homework assignments and corrections, and course answering for classmates


Skills

Languages	 English(Fluent), Mandarin Chinese(First language).
Coding	 Python,C/C++
Experimental skills	 Usage of ROS (Robot Operating System) , event-based camera, motion capture system.
Knowledge	 Algorithms and Data Structure, Machine Learning, Visual SLAM, Event-based Vision, Deep Learning, Abstract Algebra.


Miscellaneous Experience


Awards and Achievements


2024.11  **Provincial Third Prize in the China Undergraduate Mathematical Contest in Modeling (CUMCM),**


2023.12  **Department Prize for Outstanding Student Performance,** ShanghaiTech University.


Certification

 CET-6 573




















2023.9  TOFEL iBT 91

2023.3  **Certified as RHCE (Red Hat® Certified Engineer).** Awarded by Red Hat,Inc.

 **Certified as RHCSA (Red Hat® Certified System Administrator).** Awarded by Red Hat,Inc.

2022.12  CET-4 642

GPA in Major Courses

Overall GPA	 3.77/4.0(Ranking in all Computer Science students:16/169,Ranking in all SIST students:27/243).
2025 Spring(Undertaking)	 Deep Nerual Networks
	 Elementary Algebraic Geometry
	 Introduction to Computer Graphics
	 Abstract Linear Algebra
	 Optimization Modols in Enginerring
2024 Fall(in UC Berkeley)	 Introduction to Abstract Algebra(A+)
	 Introduction to Artificial Intelligence(A)
	 Efficient Algorithms and Intractable Problems(A)
2024 Spring	 Computer Architecture I and Lab(A)
	 Simultaneous Localization and Mapping(A)
	 Introduction to Machine Learning(A+)
2023 Fall	 Algorithm and Data Structure(A+)
	 Computer Vision I(A)
2023 Spring	 Discrete Mathematics(A)
	 Mathematical Analysis II(A)
2022 Fall	 Introduction to Information Science and Technology(A-)
	 Mathematical Analysis I(A)
	 Linear Algebra I(A-)