

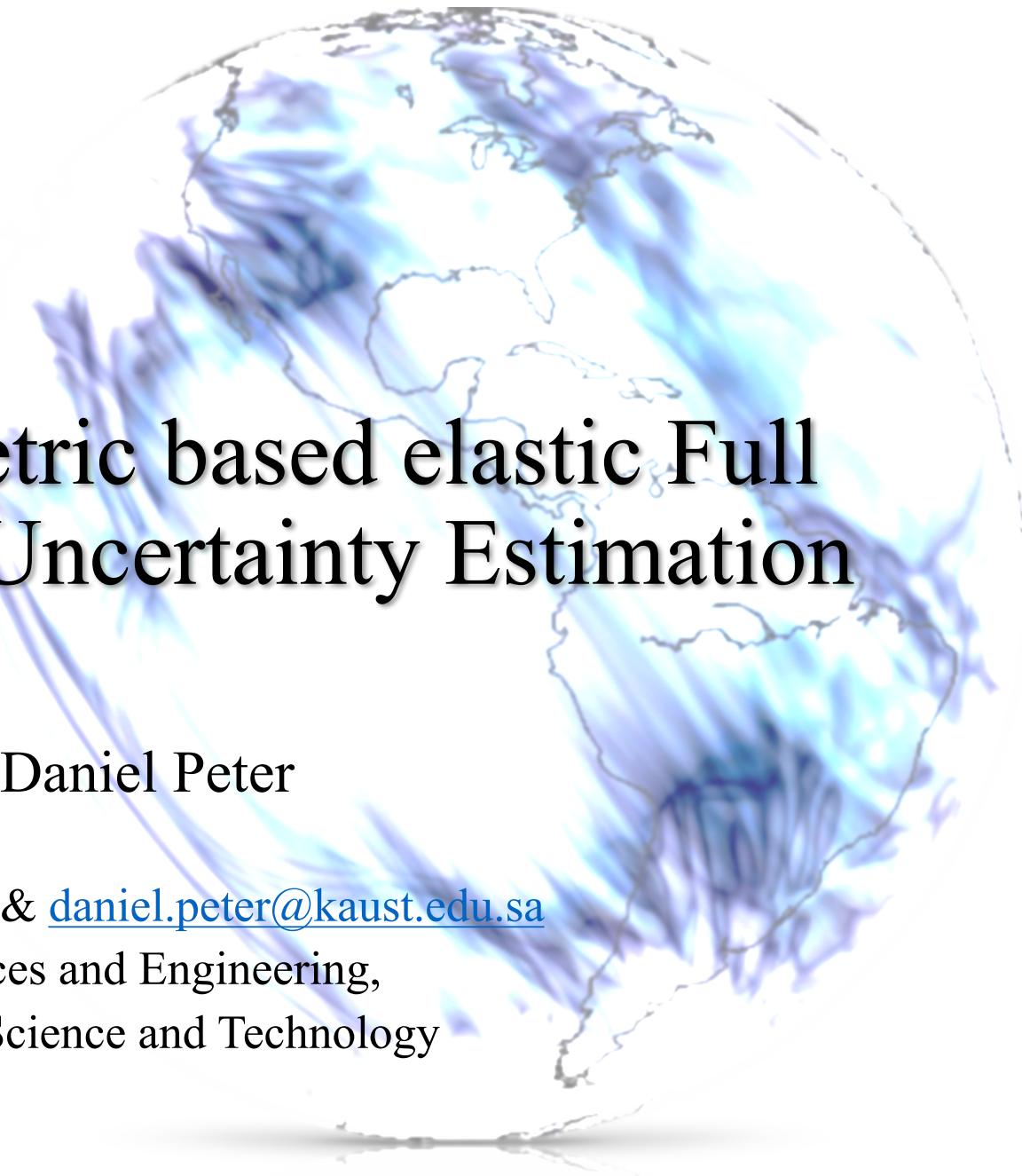


Square-Root Variable Metric based elastic Full Waveform Inversion and Uncertainty Estimation

Qiancheng Liu & Daniel Peter

Email: qiancheng.liu@kaust.edu.sa & daniel.peter@kaust.edu.sa

Division of Physical Sciences and Engineering,
King Abdullah University of Science and Technology



Motivation

- Full waveform inversion (FWI) has been widely studied.
- Its corresponding **Uncertainty Estimation** is still ignored.



Challenges & Solution

Challenges:

- Uncertainty Estimation is linked with (inverse) **Hessian** matrix
- Hessian matrix suffers from the “**Curse of Dimensionality**”

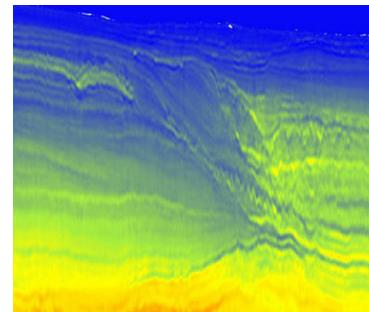
Our solution:

- Vector-Version Square-Root Variable Metric (**SRVM**) algorithm
- **Low-rank** approximation to the **inverse Hessian**

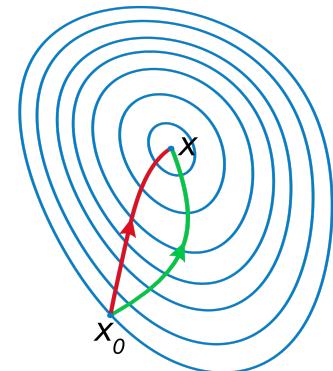


Outline

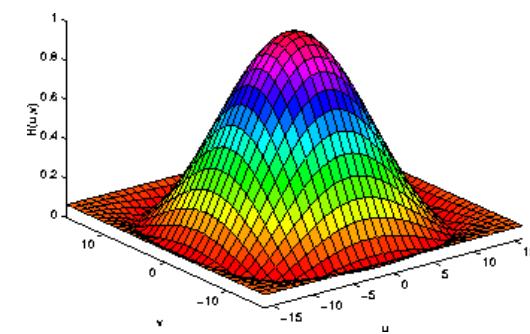
- Theory on Square-Root Variable Metric (SRVM)



- SRVM into FWI



- SRVM based Uncertainty Estimation

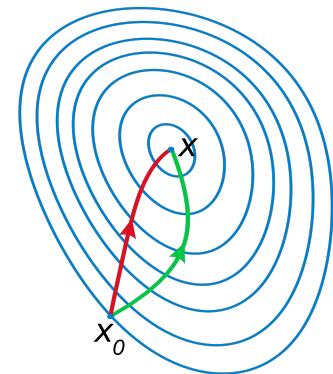


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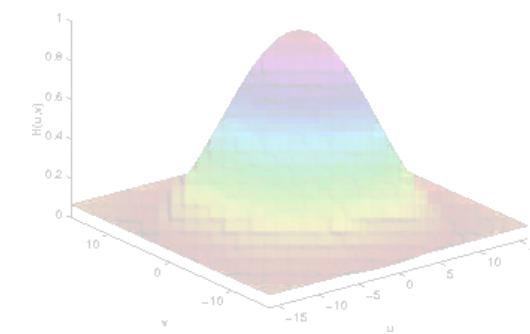
- Theory on Square-Root Variable Metric (SRVM)



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What's *SRVM* ?

- BFGS: $\mathbf{H}_{k+1} = \mathbf{H}_k - \frac{\mathbf{H}_k \Delta \mathbf{m}_k \Delta \mathbf{m}_k^T \mathbf{H}_k}{\Delta \mathbf{m}_k^T \mathbf{B}_k \Delta \mathbf{m}_k} + \frac{\Delta \mathbf{g}_k \Delta \mathbf{g}_k^T}{\Delta \mathbf{g}_k^T \Delta \mathbf{m}_k},$
- DFP: $\mathbf{B}_{k+1} = \mathbf{B}_k - \frac{\mathbf{B}_k \Delta \mathbf{g}_k \Delta \mathbf{g}_k^T \mathbf{B}_k}{\Delta \mathbf{g}_k^T \mathbf{B}_k \Delta \mathbf{g}_k} + \frac{\Delta \mathbf{m}_k \Delta \mathbf{m}_k^T}{\Delta \mathbf{g}_k^T \Delta \mathbf{m}_k}, \quad (\text{Dual of BFGS})$
- SRVM: $\mathbf{S}_{k+1} \mathbf{S}_{k+1}^T = \mathbf{S}_k \left(\mathbf{I} - (1/P_k) \mathbf{S}_k^T \mathbf{y}_k \mathbf{y}_k^T \mathbf{S}_k \right) \mathbf{S}_k^T, \quad (\text{Square-rooted DFP})$

with

$$\mathbf{B}_{k+1} = \mathbf{S}_{k+1} \mathbf{S}_{k+1}^T, \quad \mathbf{B}_k = \mathbf{S}_k \mathbf{S}_k^T, \quad \mathbf{y}_k = \mu_k \mathbf{g}_k + \Delta \mathbf{g}_k, \quad P_k = \mathbf{y}_k^T \mathbf{B}_k \Delta \mathbf{g}_k.$$



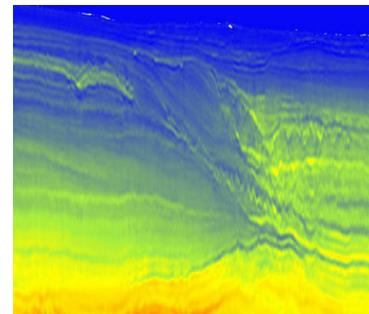
Vector-version SRVM

- SRVM algorithm in **vector version**
- The number of vectors = the number of iterations
- **Memory cost affordable even for large-scale** problems

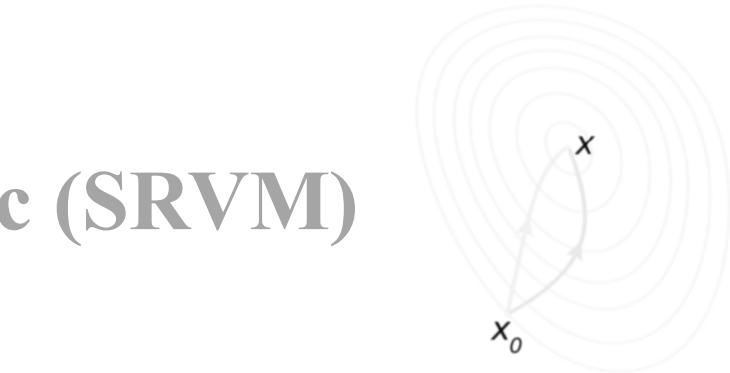


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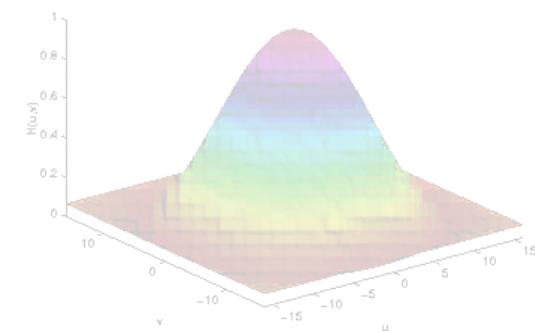
- Theory on Square-Root Variable Metric (SRVM)



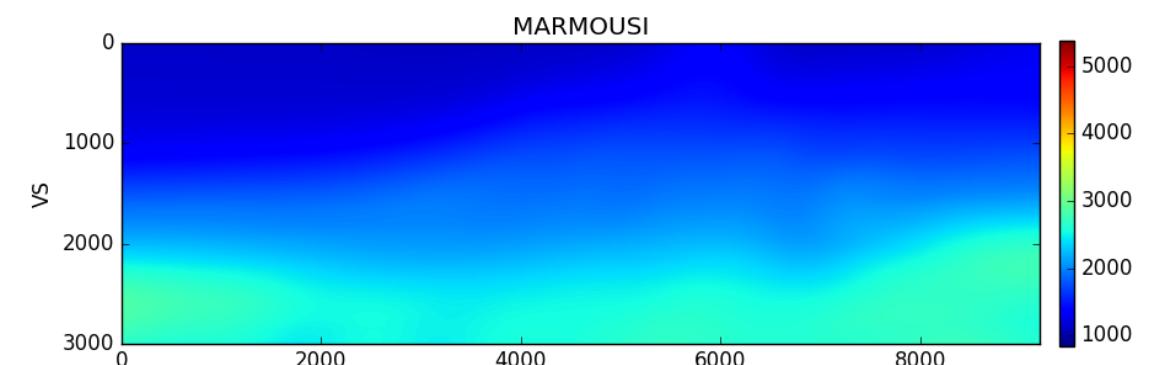
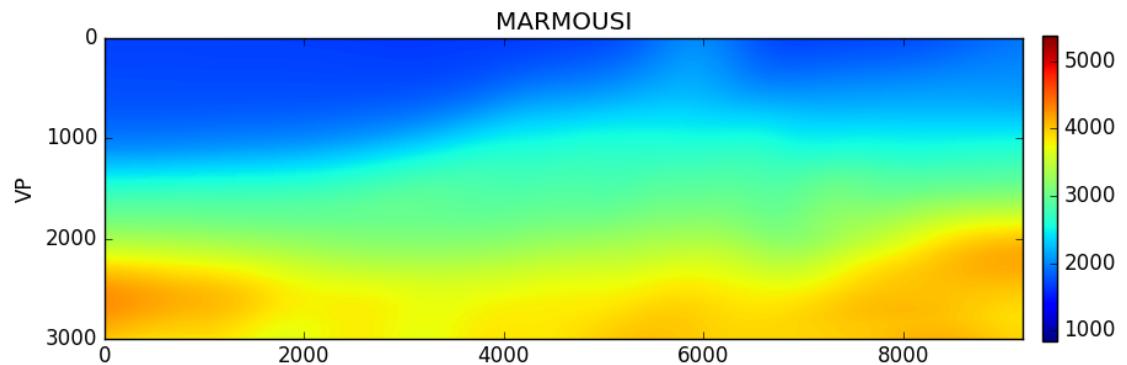
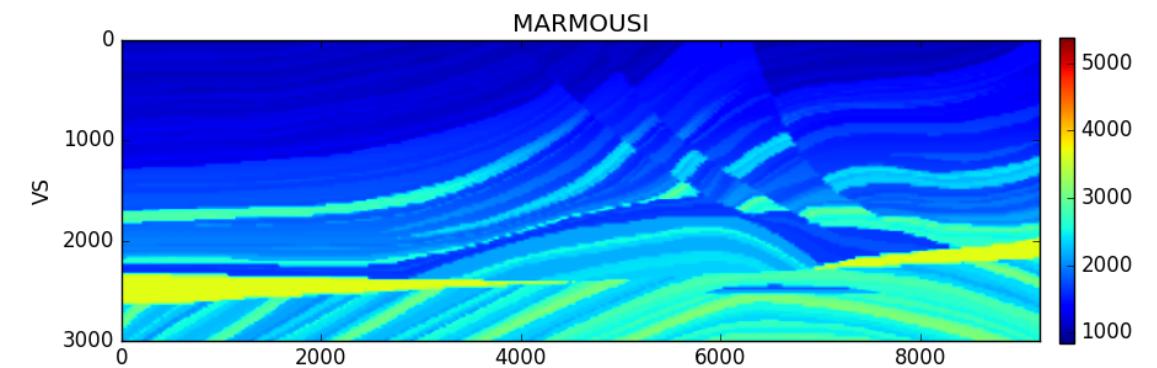
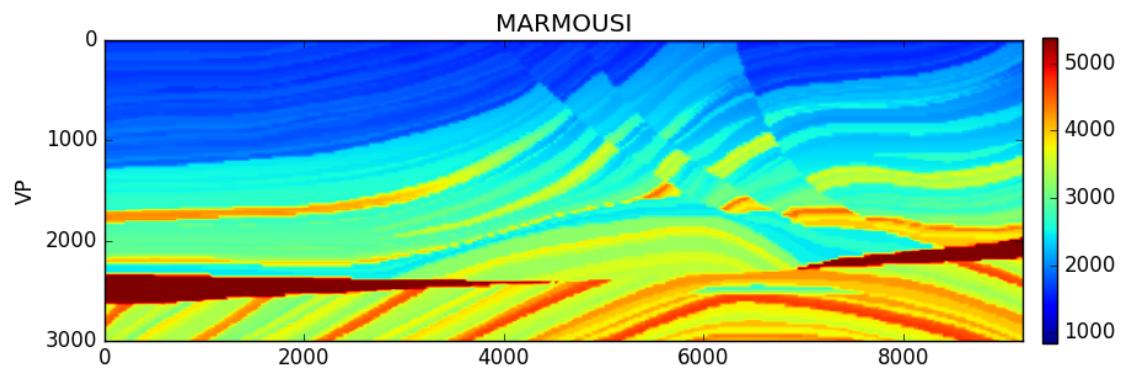
- SRVM into FWI



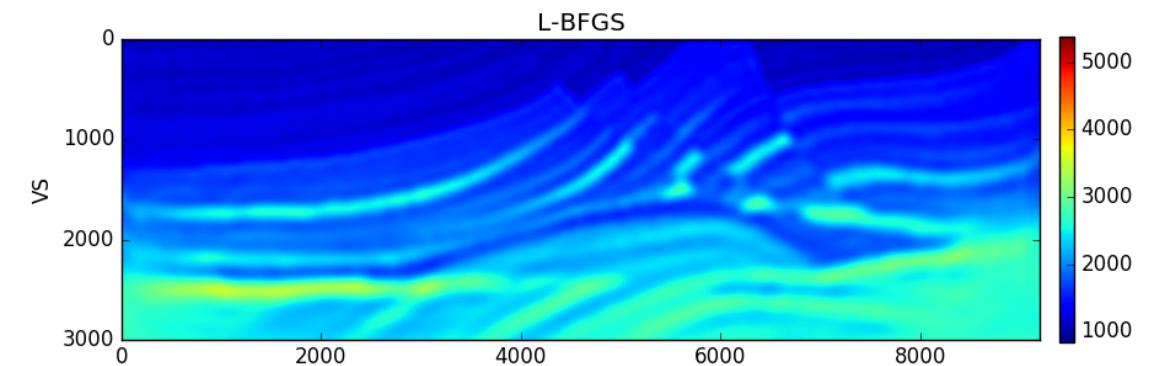
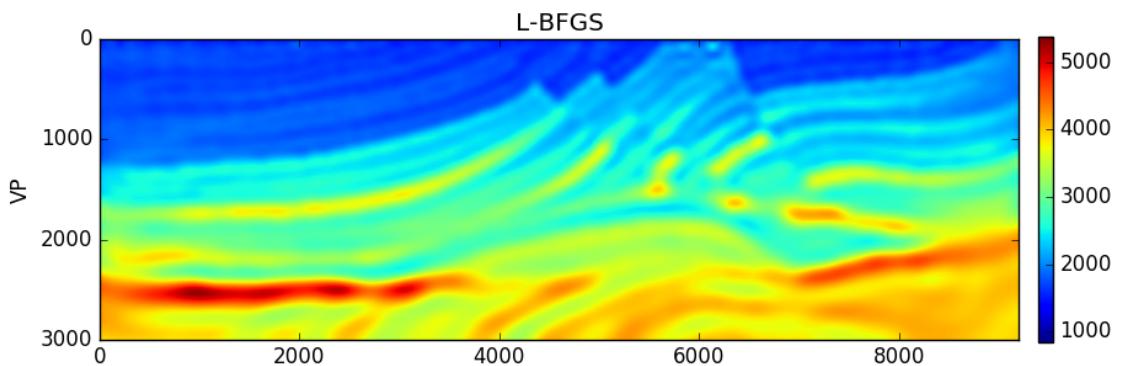
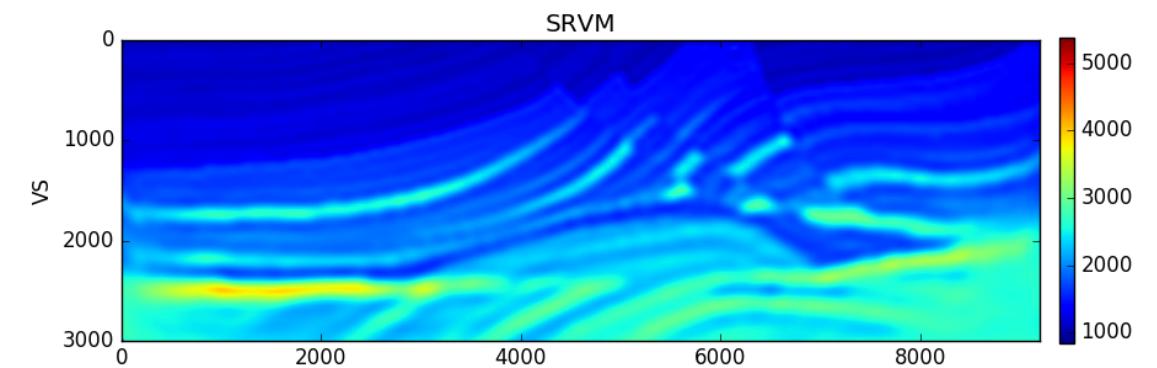
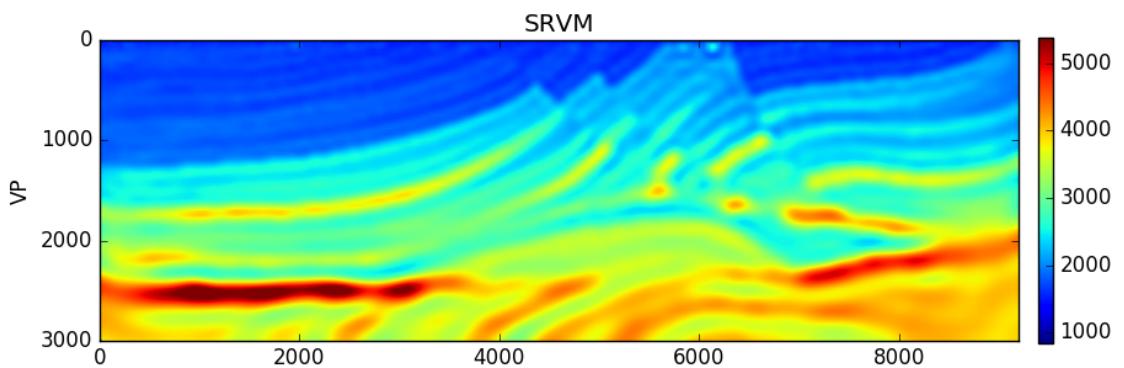
- SRVM based Uncertainty Estimation



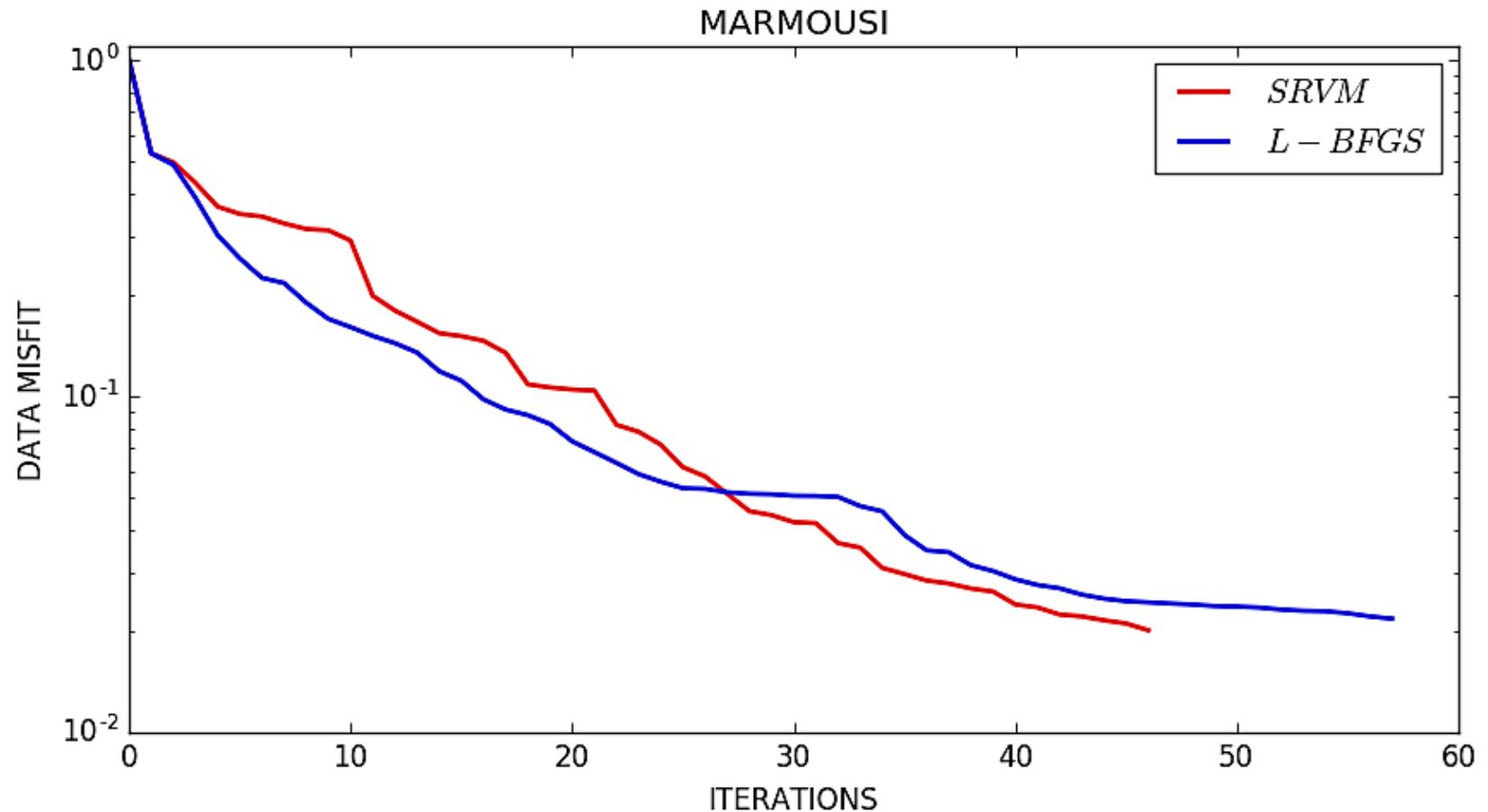
Marmousi Benchmark (*True* and *Init* models)



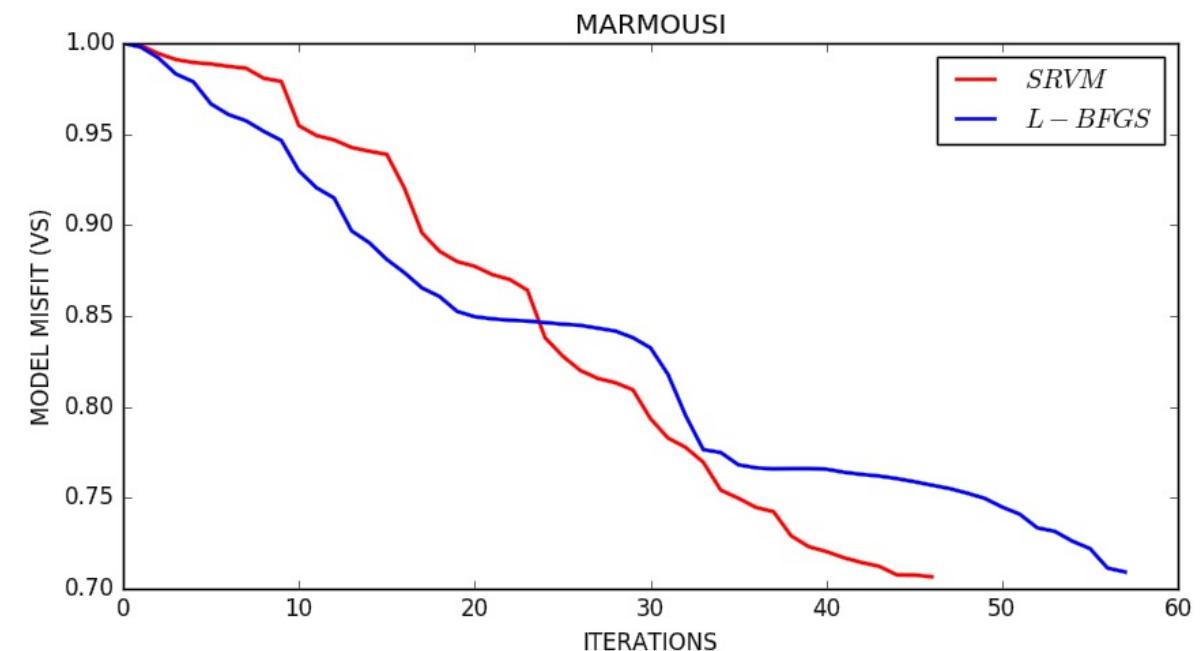
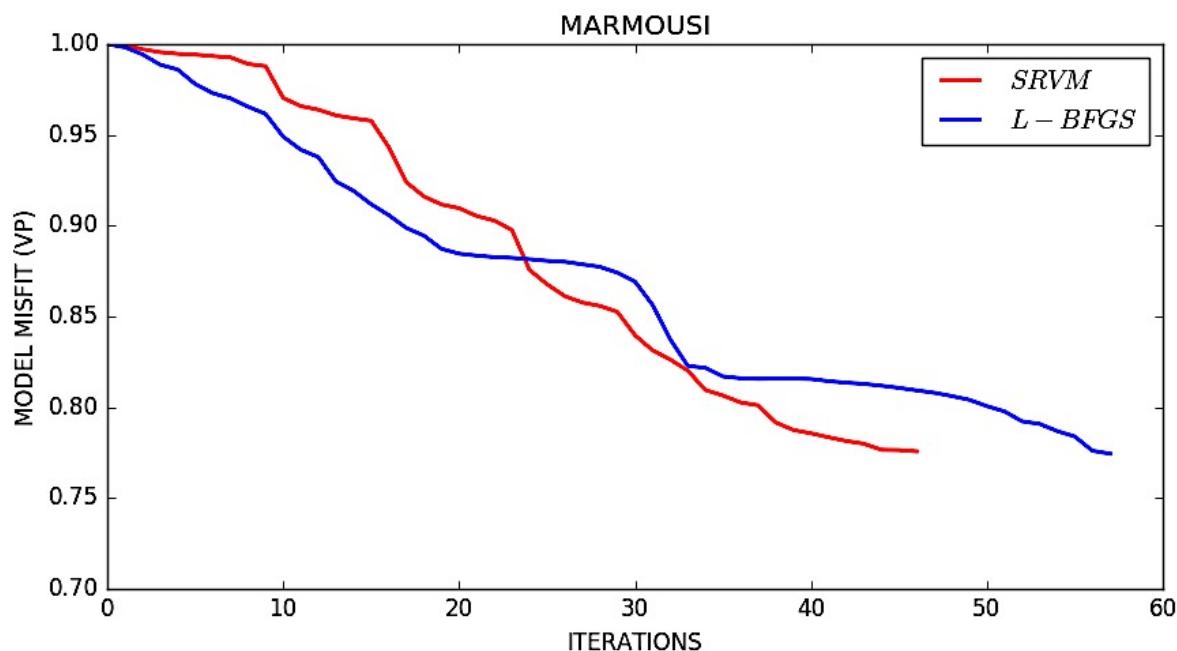
SRVM *v.s.* L-BFGS in FWI



SRVM v.s. L-BFGS: data-misfit curve

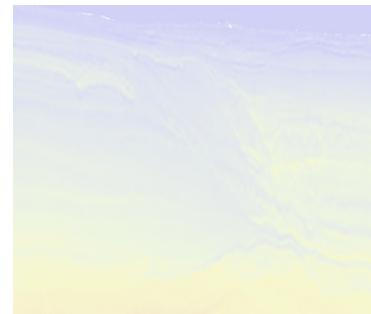


SRVM v.s. L-BFGS: Vp , Vs model-misfit curves

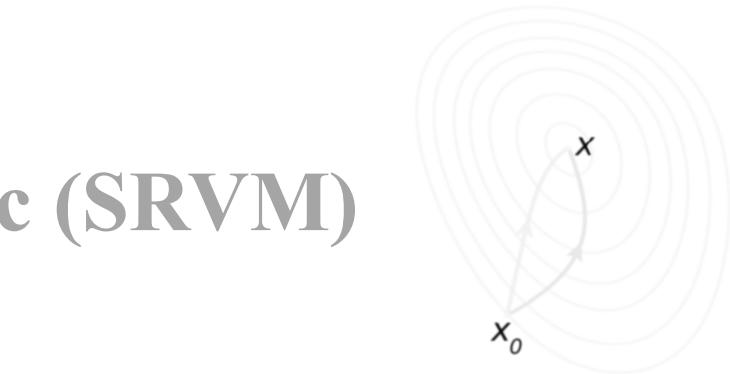


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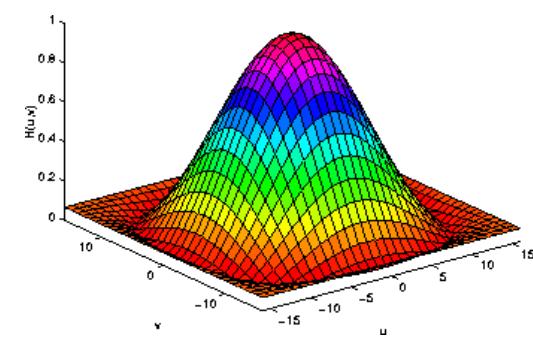
- Theory on Square-Root Variable Metric (SRVM)



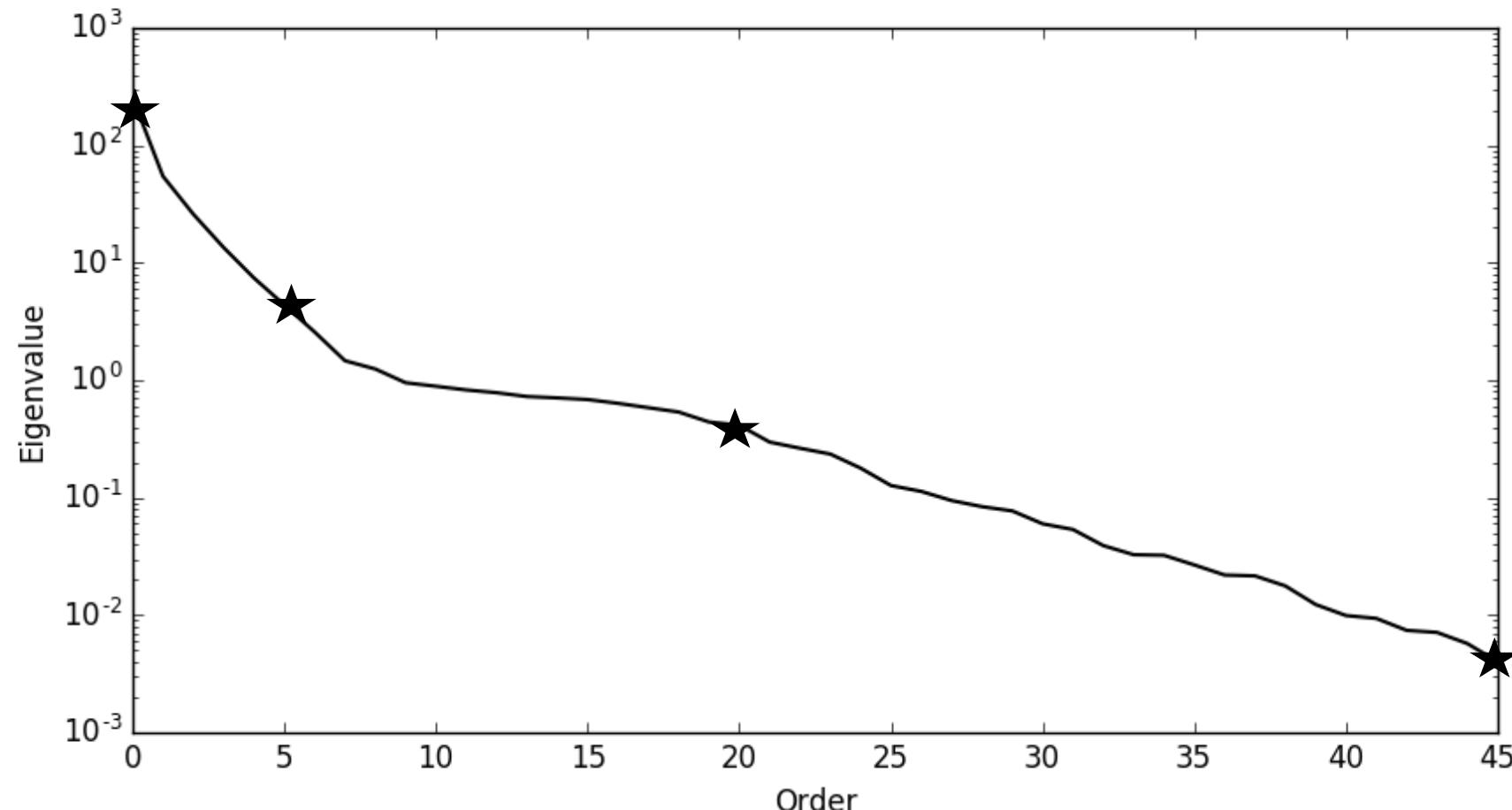
- SRVM into FWI



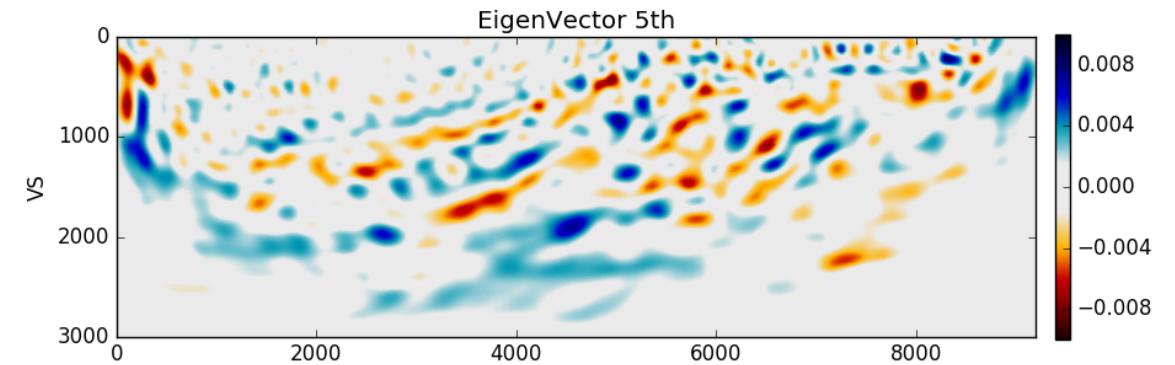
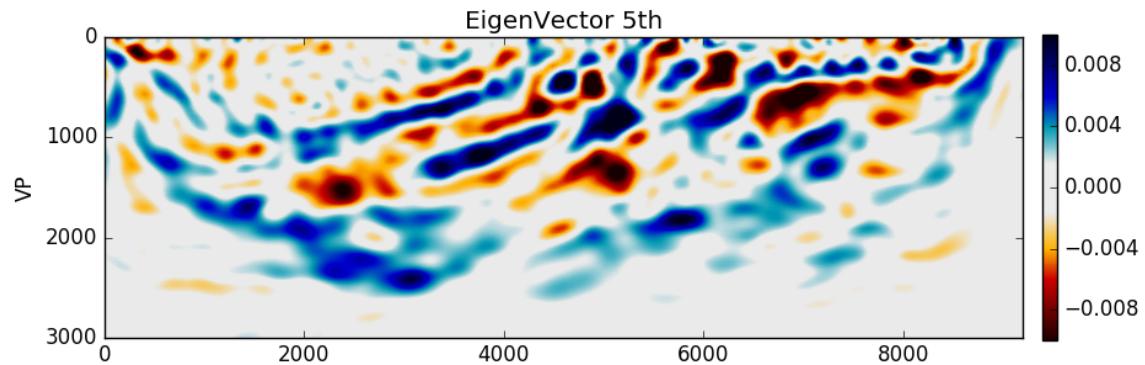
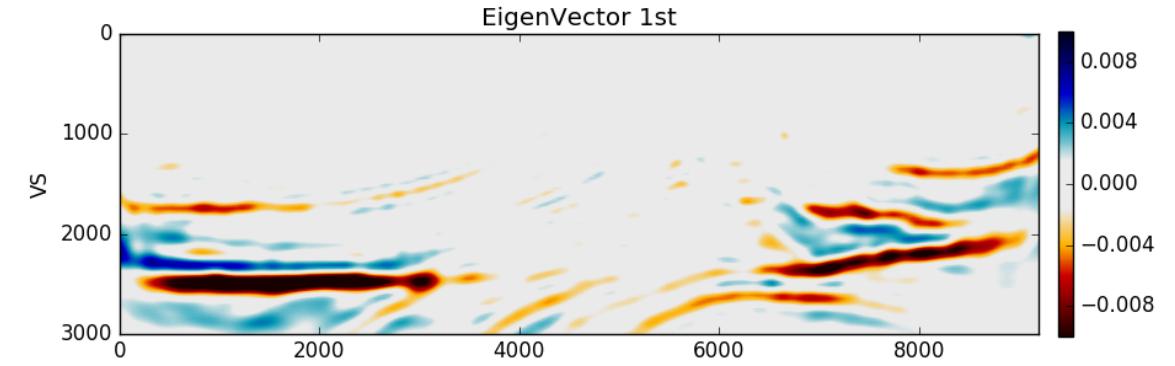
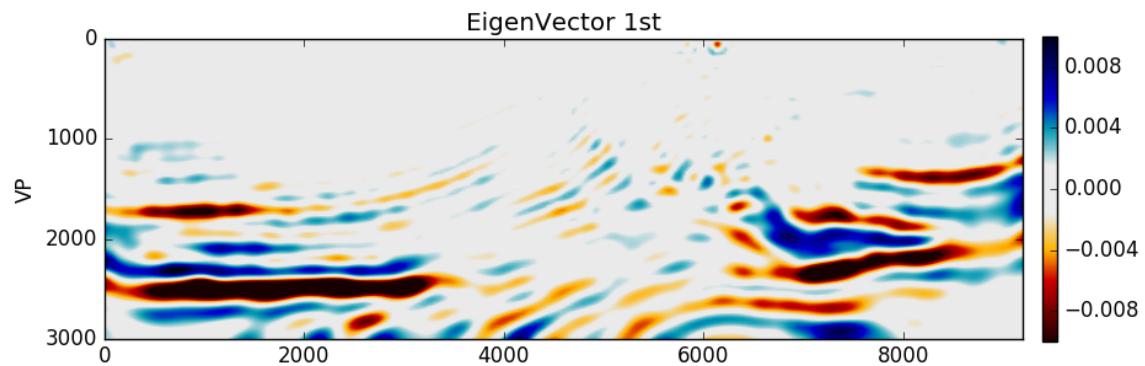
- SRVM based Uncertainty Estimation



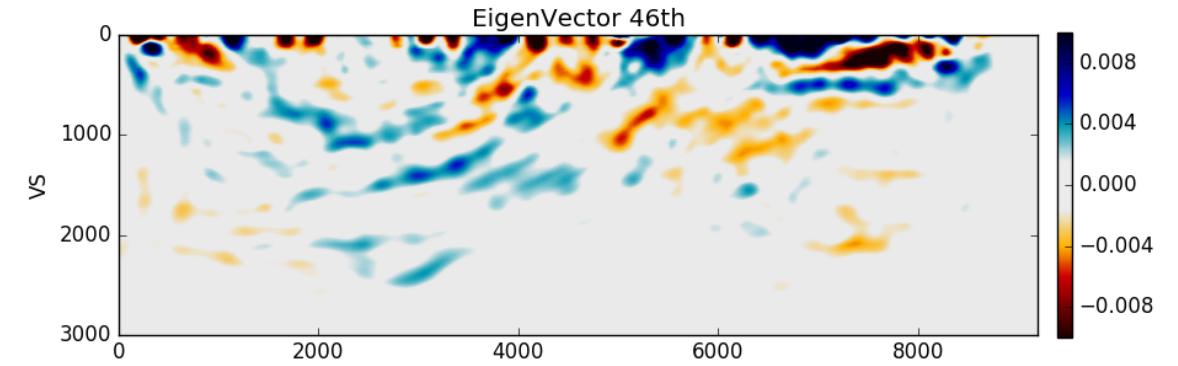
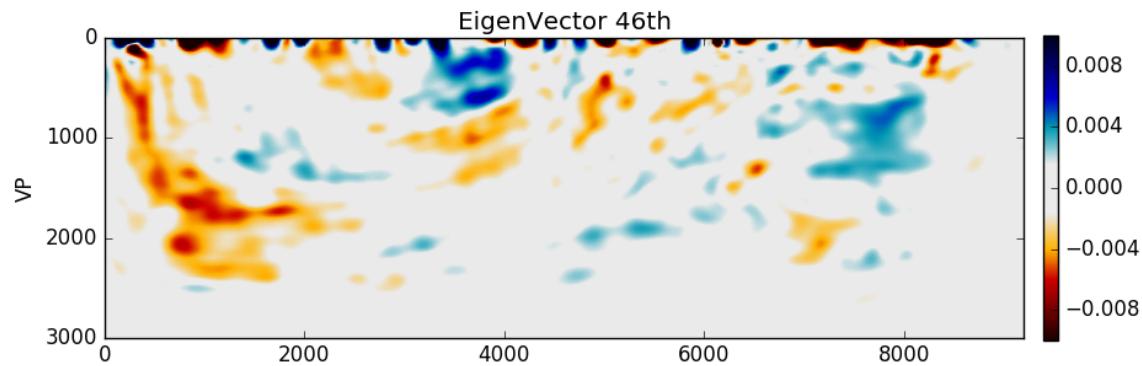
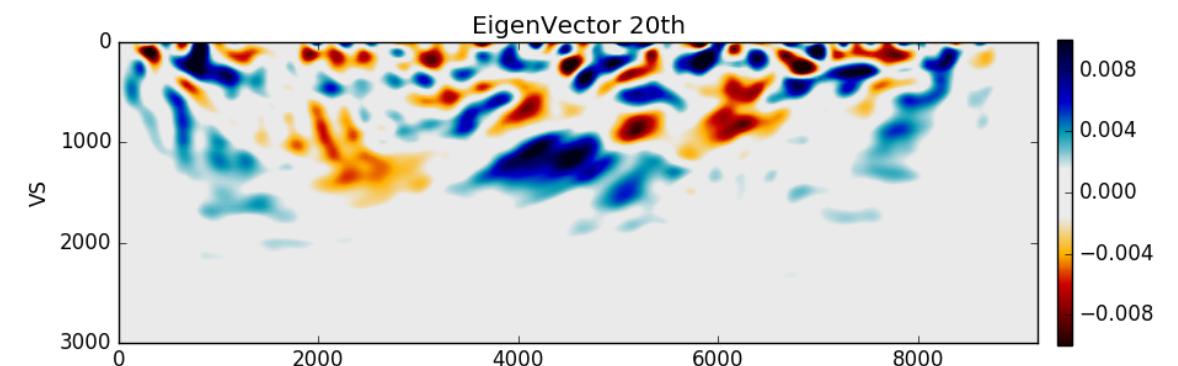
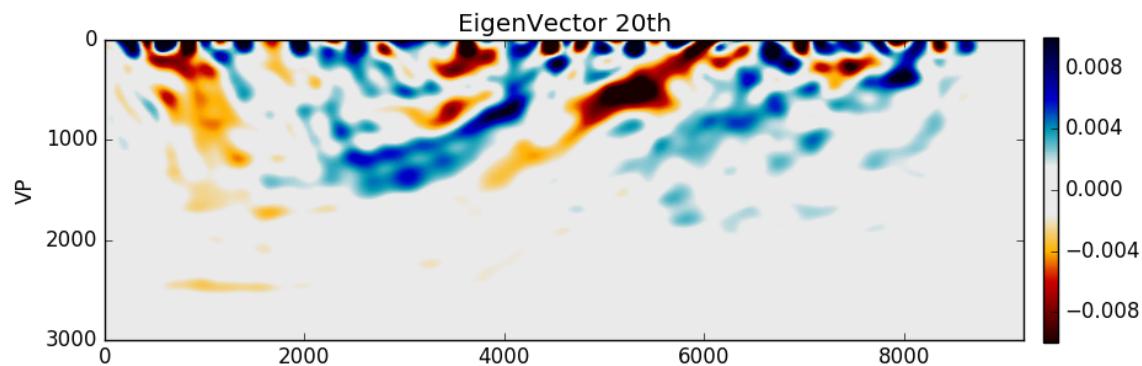
SRVM with Randomized SVD on inverse Hessian



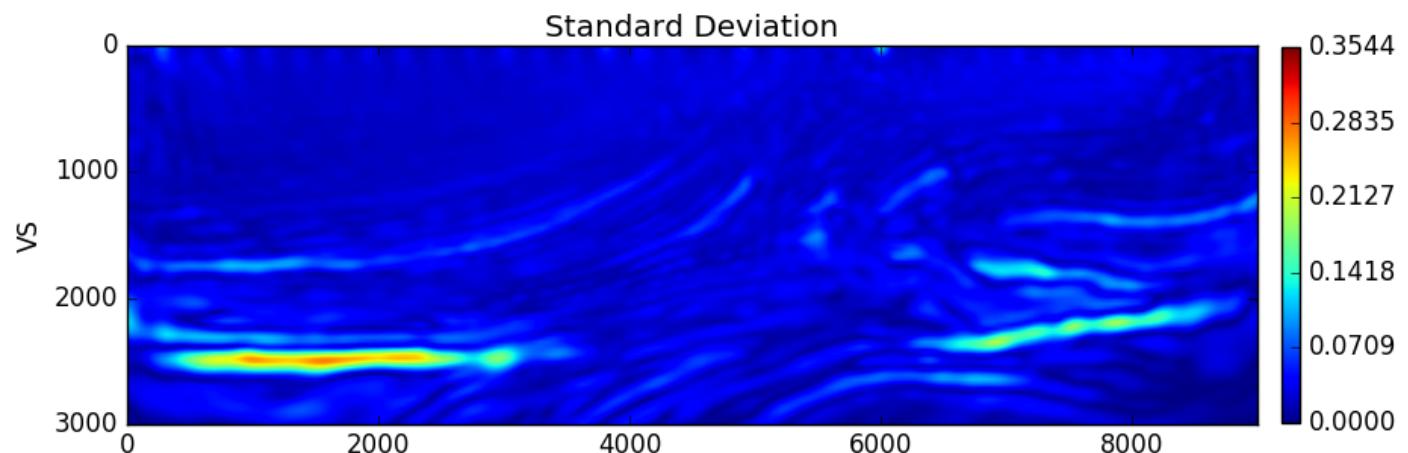
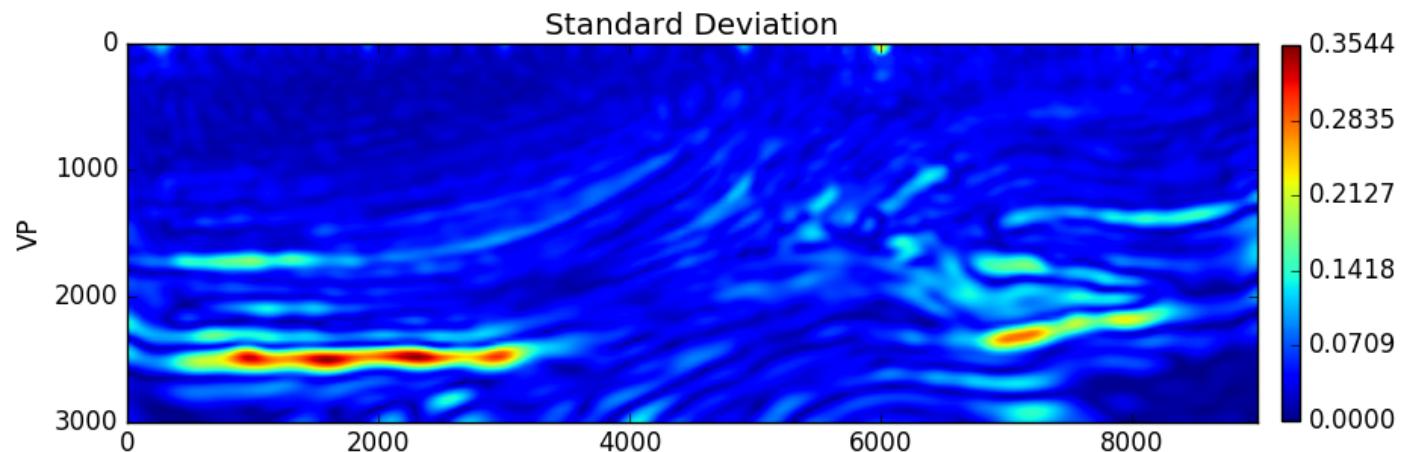
Eigenvectors of inverse Hessian (1st, 5th)



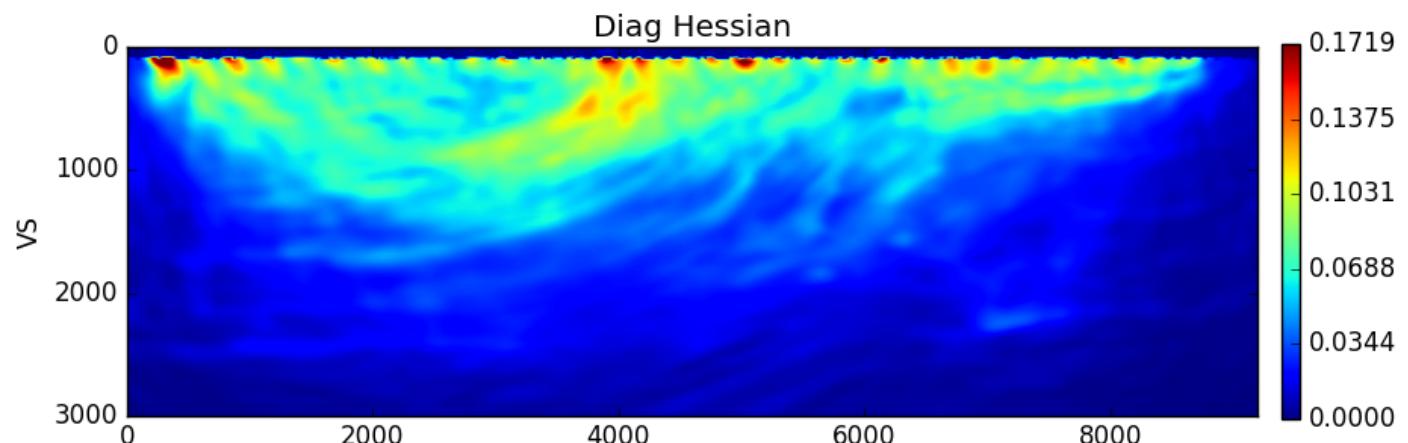
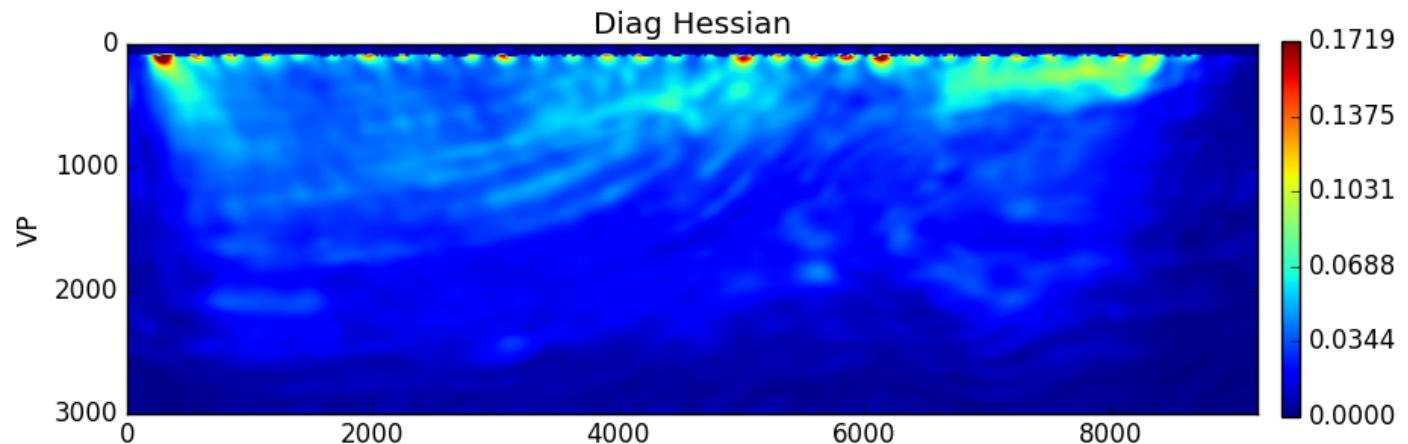
Eigenvectors of inverse Hessian (20th, 46th)



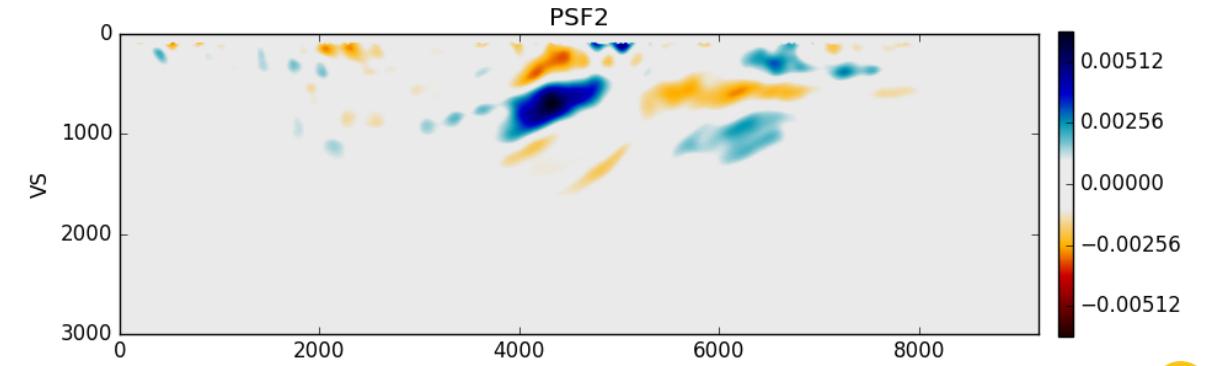
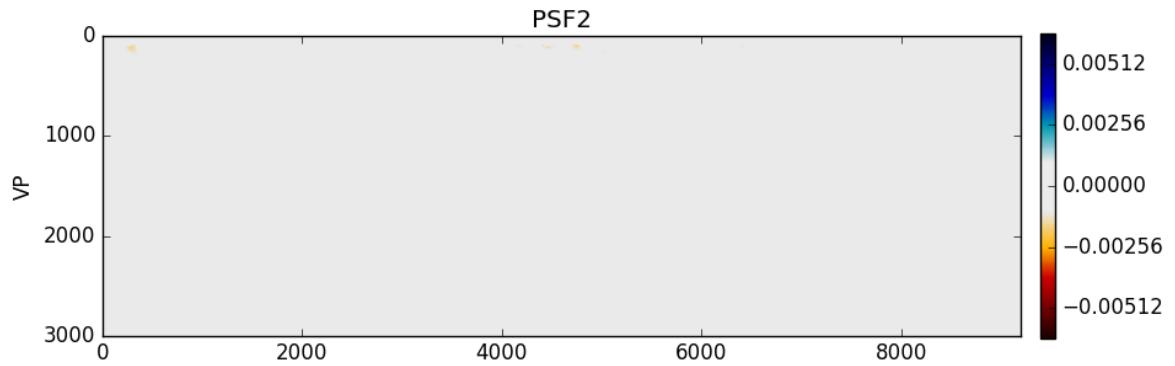
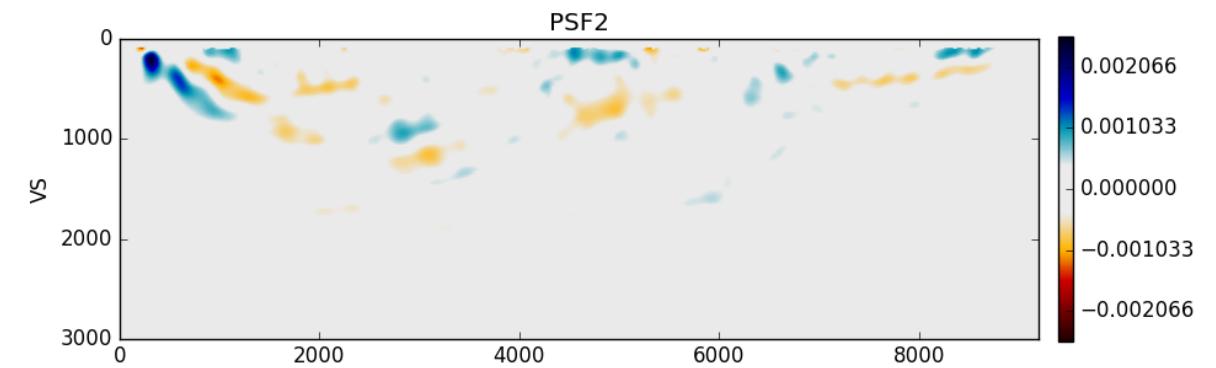
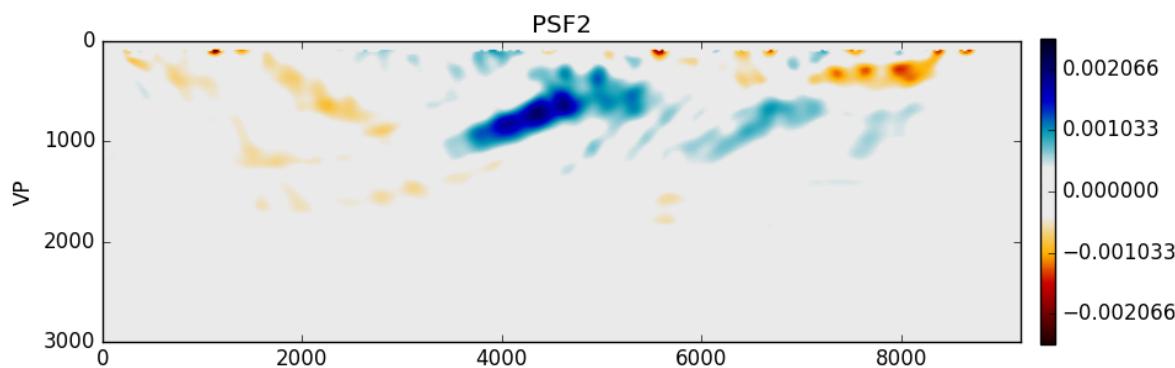
Uncertainty map: standard deviation (Vp , Vs)



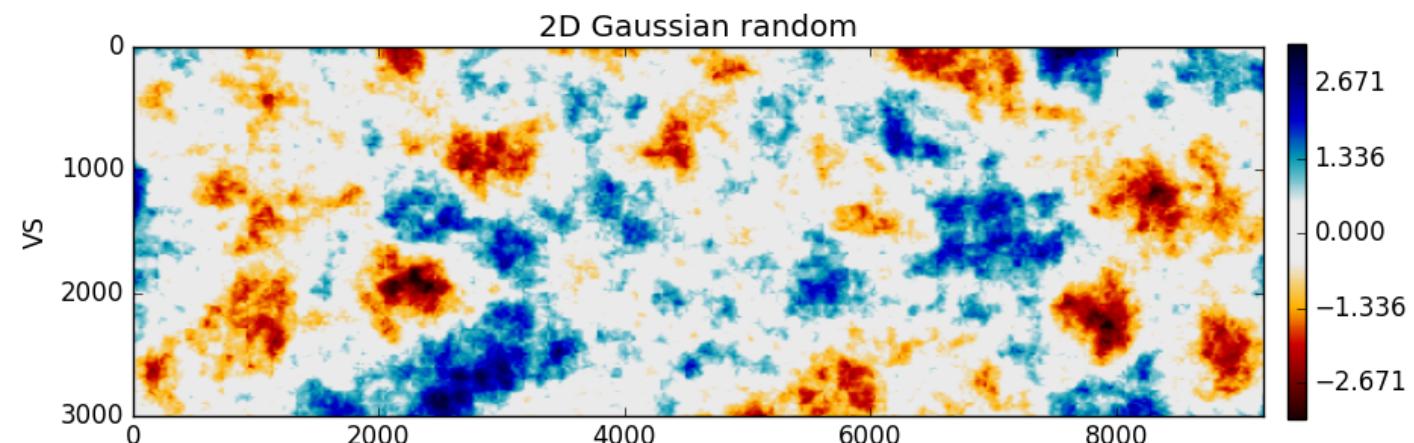
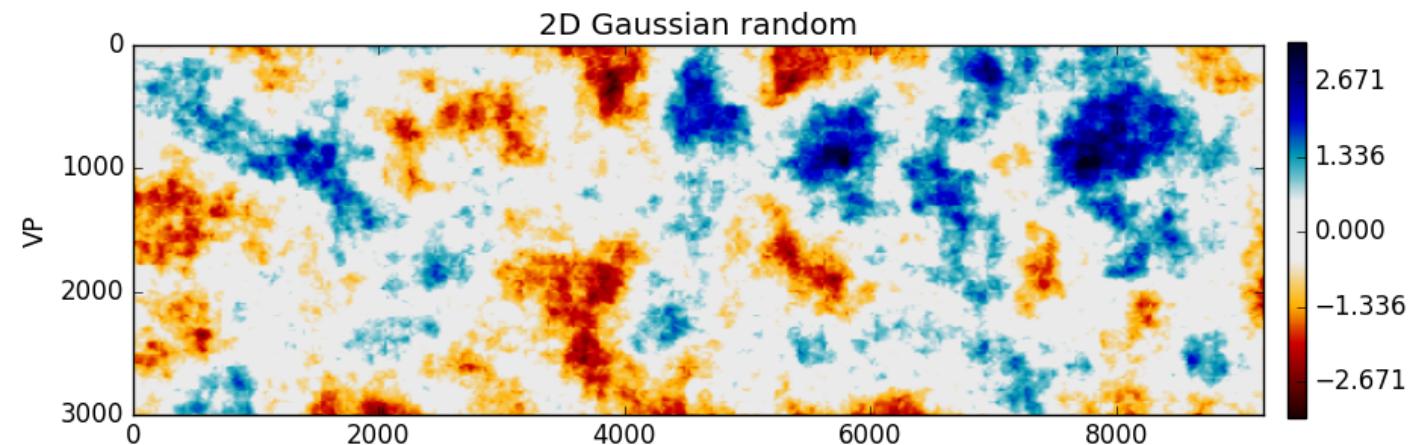
Diagonal Hessian: Vp , Vs



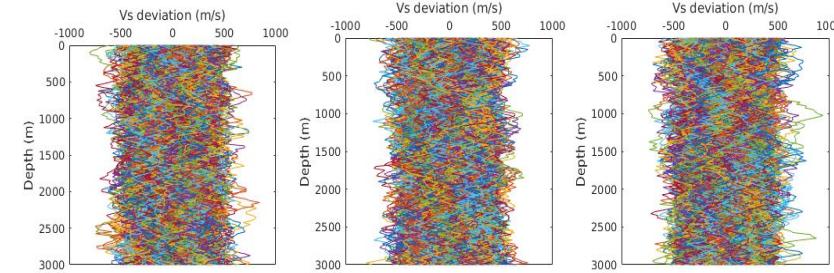
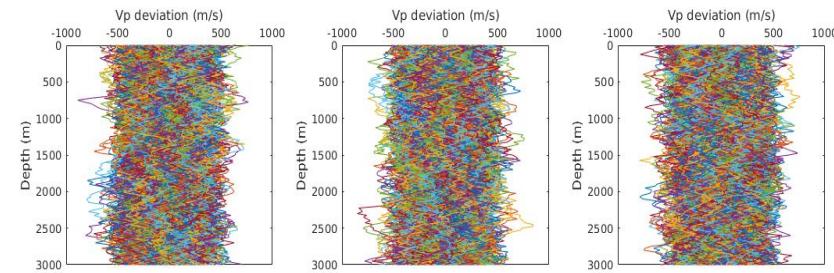
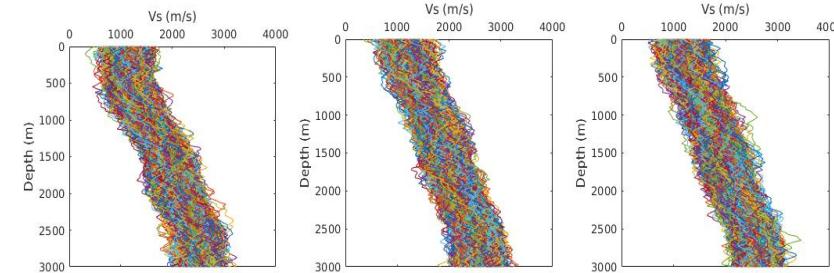
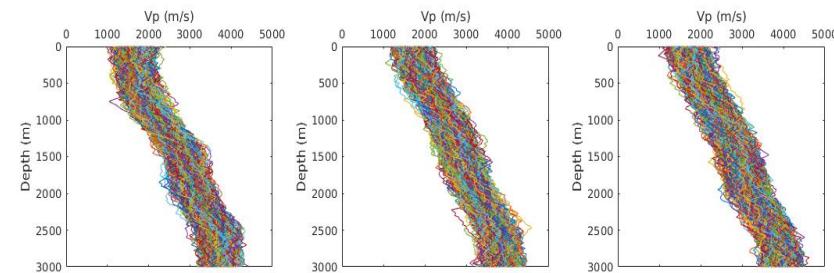
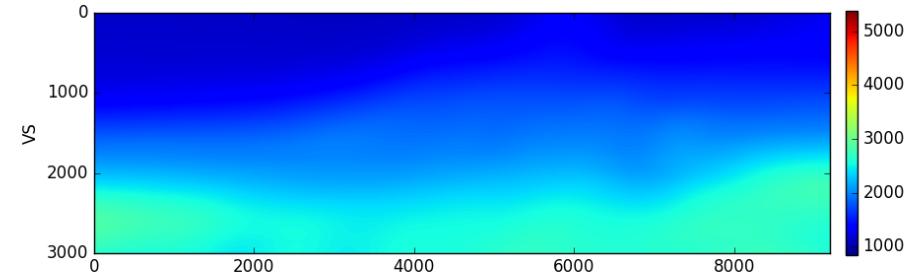
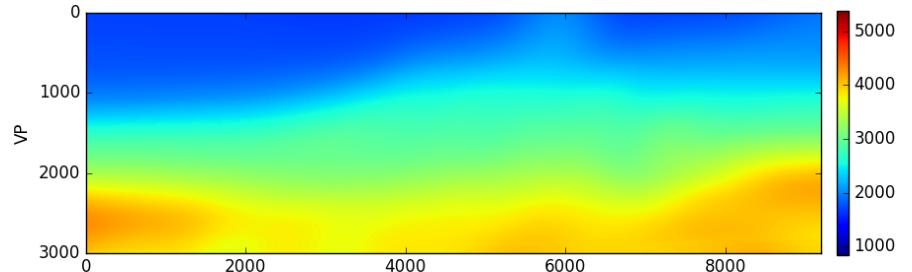
Point-spread function (PSF): Vp , Vs



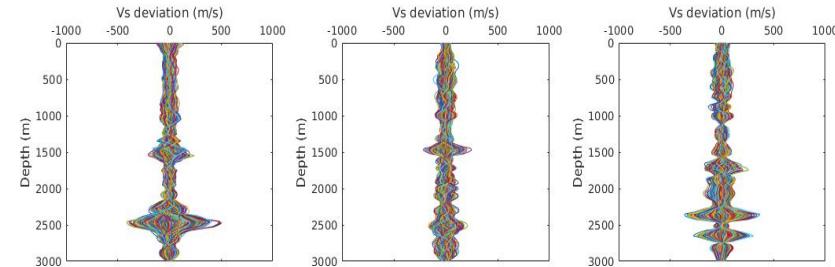
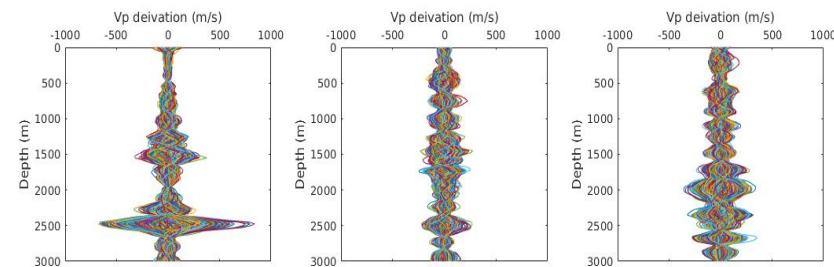
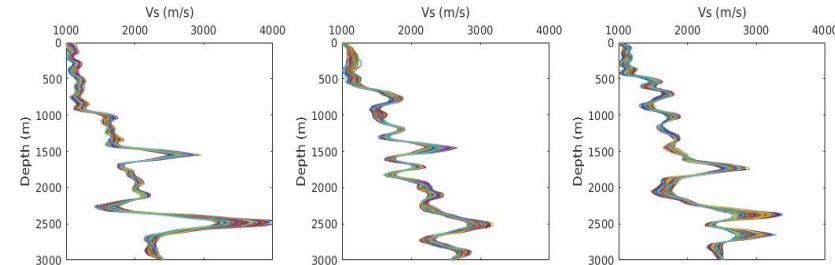
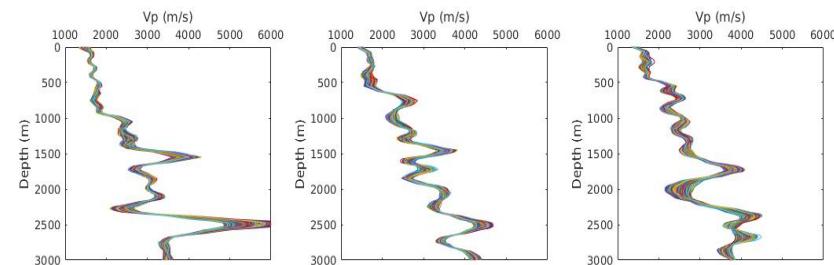
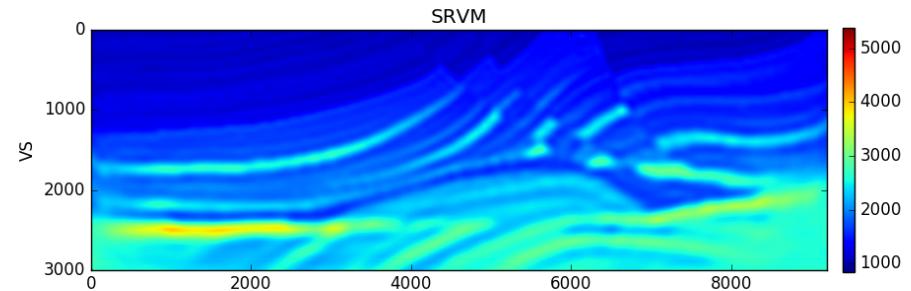
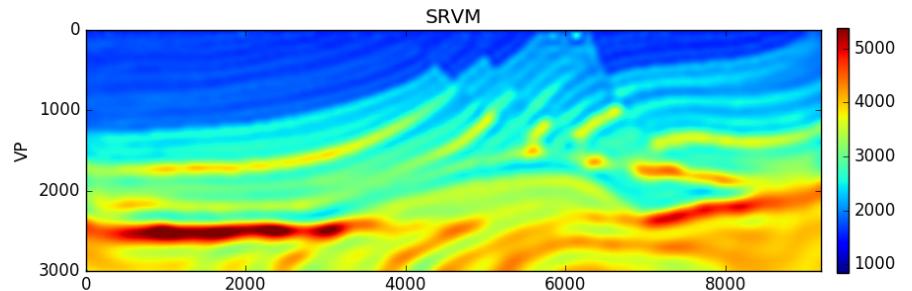
2D Gaussian randoms for prior/posterior samplings



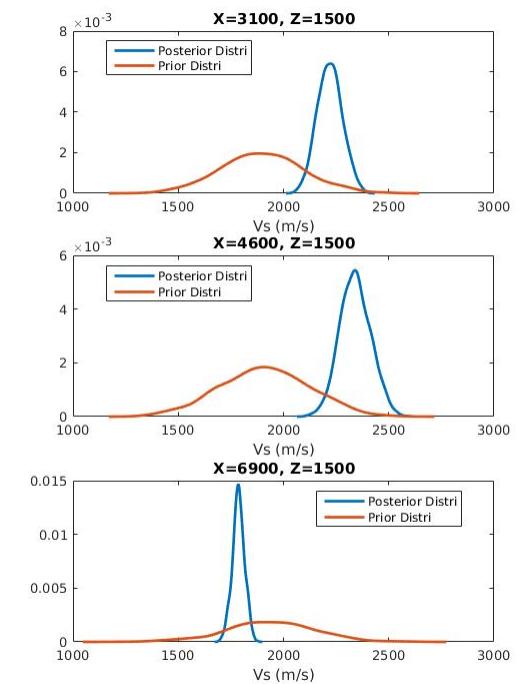
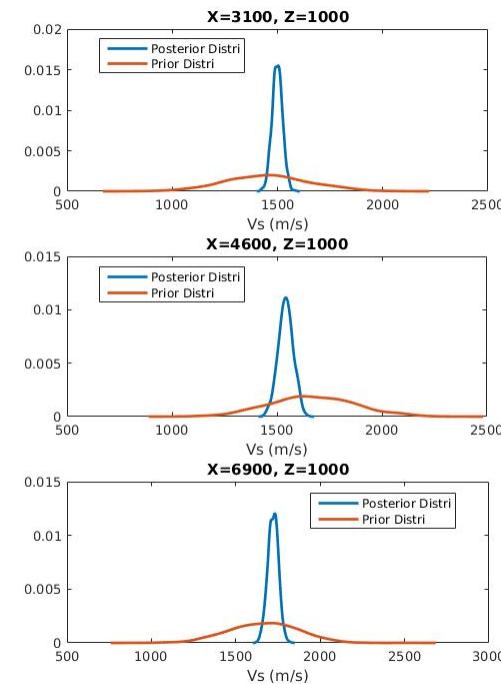
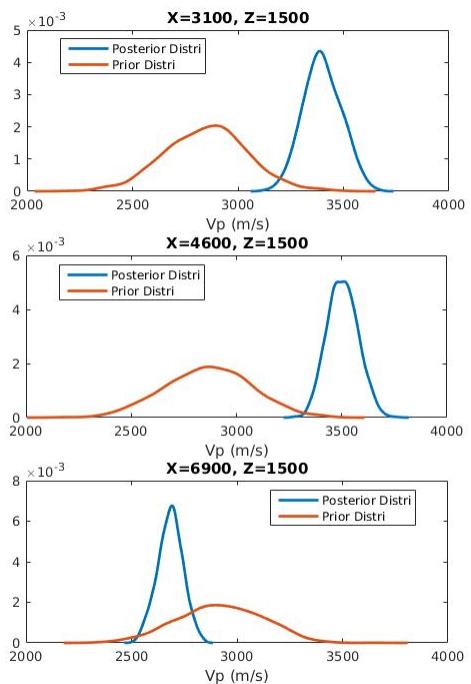
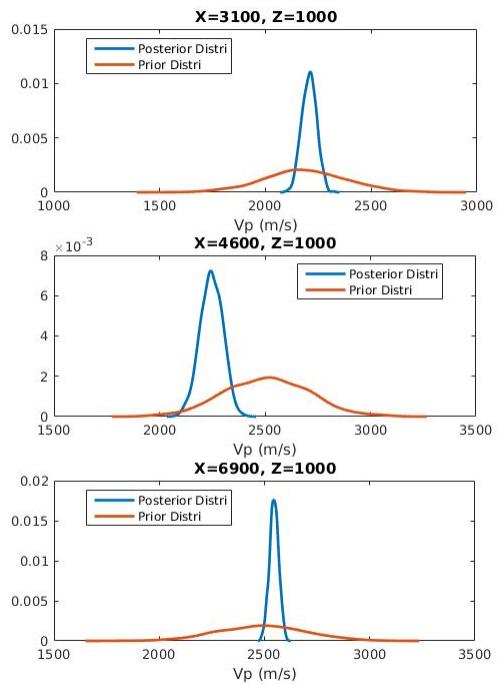
Prior distribution: Vp , Vs (*boreholes at X=3100m, 4600m, 6900m*)



Posterior distribution: Vp , Vs *(boreholes at X=3100m, 4600m, 6900m)*



Prior v.s. Posterior Probability density functions: Vp , Vs



Conclusions

- As a **quasi-Newton** method, **SRVM** performs as good as **L-BFGS** in our full-space Marmousi testing.
- After FWI is done, we can retrieve the information of inverse Hessian for **Uncertainty Estimation**.
- We employ randomized sampling to develop a **SRVM-RSVD** to facilitate the **Uncertainty Estimation** and **Posterior Sampling**.





Thanks !!!

by Qiancheng Liu & Daniel Peter

